

Special Issue

Bio-Inspired Soft Robotics

Message from the Guest Editor

This Special Issue on "Bio-Inspired Soft Robotics" aims to present new findings and ideas in the field of bio-inspired soft robotics. Manuscripts from the field of soft robotics which try to take into account biological patterns in nature will be primarily beneficial. Contributions can deal with the possibilities of locomotion and the change in a structure's shape or behavior in response to external stimuli. To this end, we encourage the submission of papers with new advances in theoretical, experimental, and computational approaches to applications of bionic robots with various variable structures, shapes, and control capabilities.

- bioinspired soft mechanisms
- bio-inspired actuators
- biorobotics
- bio-inspired soft robotics
- biomimetic soft robots
- soft robot control
- locomotion of bio-inspired soft robots

Guest Editor

Dr. Erik Prada

Department of Industrial Automation and Mechatronics, Faculty of Mechanical Engineering, Technical University of Košice, 04200 Košice, Slovakia

Deadline for manuscript submissions

closed (30 November 2025)



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Actuators
Editorial Office
MDPI, Grosspeteranlage 5
4052 Basel, Switzerland
Tel: +41 61 683 77 34
actuators@mdpi.com

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About the Journal

Message from the Editorial Board

We are just entering the Next Wave of Technology (NWT) where actuators will play the same role as the computer chip did for computers/social media approximately four decades ago. Just in the U.S., production of \$1 trillion year of electromechanical systems (vehicles, orthotics, manufacturing cells, freight trains, aircraft, etc.) will be impacted by the NWT, all driven by actuators. Five key trends can be found for the future perspectives: “Performance to Reliability”, “Hard to Soft”, “Macro to Nano”, “Homo to Hetero” and “Single to Multi functional”. We invite papers that primarily impact these economic sectors; those illustrating basic scientific principles are also welcome.

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Prof. Dr. Kenji Uchino

Electrical Engineering, Emeritus Academy Institute, Pennsylvania State University, University Park, PA 16802, USA

Prof. Dr. Norman M. Wereley

Department of Aerospace Engineering, University of Maryland, 3179J Martin Hall, College Park, MD 20742, USA

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