



Control Systems in Biped Robots

Guest Editor:

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Message from the Guest Editor

Dear Colleagues,

This Special Issue is a collection of high-quality research papers in the areas of the control systems in biped robots. The topic includes but is not limited to control systems, kinematics and dynamics, design and modelling, walking gait generation, computer vision, and artificial intelligence. The papers should be full research papers or review papers that address the latest challenges and advances in this field with original ideas, novel solutions, sound methodologies, and convincing validations.

Dr. Chao Chen

Guest Editor

