Additionally, scripts from the following digital repositories/sources were employed:

- For `ros_controllers` package [44]
- For `schunk_modular_robotics` package [33]
- For `schunk_robots` package [34]
- For `scitos_common` package [45]
- For `scitos_driver` package [46]
- For Recursive Newton Euler Inverse Dynamics Solver [41]
- For The STRANDS Project: Long-Term Autonomy in Everyday Environments [47]
- For Navigation control [48]