

Mechanism of Electropulsing Treatment Technology for Flow Stress of Metal Material: A Review

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Abstract: Residual stress is caused by non-uniform deformation caused by non-uniform force, heat and composition, which is of great significance in engineering applications. It is assumed that the residual stress is always the upper limit of the elastic limit, so the reduction of the flow stress will reduce the residual elastic stress. It is particularly important to control the flow stress in metal materials. Compared with traditional methods, the use of electropulsing treatment (EPT) technology stands out due to its energy-efficient, highly effective, straightforward and pollution-free characteristics. However, there are different opinions about the mechanism of reducing flow stress through EPT due to the conflation of the effects from pulsed currents. Herein, a clear correlation is identified between induced stress levels and the application of pulsed electrical current. It was found that the decrease in flow stress is positively correlated with the current density and the duration of electrical contact and current action time. We first systematically and comprehensively summarize the influence mechanisms of EPT on dislocations, phase, textures and recrystallization. An analysis of Joule heating, electron wind effect, and thermal-induced stress within metal frameworks under the influence of pulsed currents was conducted. And the distribution of electric, thermal and stress fields under EPT are discussed in detail based on a finite element simulation (FES). Finally, some new insights into the issues and challenges of flow stress drops caused by EPT are proposed, which is critically important for advancing related mechanism research and the revision of theories and models.

Keywords: electropulsing treatment technology; flow stress; numerical analysis; microstructural analysis

1. Introduction

Residual stress represents the elastic tension maintained within a material, resulting from uneven stress and temperature distributions, as well as irregular structural deformation during manufacturing and processing stages. This phenomenon is a primary factor in the occurrence of brittleness and corrosive cracking in metals [1-3]. Based on the range of stresses, there are four types of flow stresses: (i) the first is the stress that exists throughout the material, (ii) the second is the stress within the composition, which is created by the tension and compression of the composition, (iii) the third kind of stress is the non-uniform stress existing in each grain, which is equivalent to the action stress between the actual grains and different phases in the structure, and (iv) the fourth is the more microscopic stress caused by dislocations and various intracrystalline defects [4–9]. Seeger et al. [10] considered that the first kind of stress is a constant in the macroscopic range, and the second kind of stress is also a constant in the microscopic domain, which tends to change periodically in the macroscopic range as well as the third kind of stress in the microscopic domain. Given the preparation and treatment of metallic materials, such as drawing [11], extrusion [12], rolling [13], corroding [14], cutting [15], grinding [16], surface rolling [17], shot peening [18], hammering [19], casting [20], quenching heat treatment [21], welding [22], etc., these four types of residual stresses are inevitable.



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In the processing of metal materials, the generation of residual stress is unavoidable, and concurrently, such stress can impair the operational efficiency of the material [23,24]. Therefore, it is of utmost significance to manage the residual stress within metal materials [25]. The origins of residual stress encompass three primary factors. (i) Residual stress arises from disparate plastic deformation resulting from applied forces. (ii) Thermal effects produce residual stress; non–uniform temperature changes cause non–uniform thermal expansion. (iii) Residual stress is caused by chemical action; this residual stress is the stress generated by the chemical change or physical change transmitted from the surface to the interior [26–31]. In summary, residual stress is caused by non–uniform deformation caused by non–uniform force, heat and composition. It is assumed that the residual stress is always the upper limit of the elastic limit, so a reduction in the flow stress will reduce the residual elastic stress. Therefore, it is particularly important to control the flow stress in metal materials.

The reduction process of flow stress is essentially various inelastic deformations that occur inside the material, and the initiation and development of the deformation process requires energy consumption. Various existing methods of eliminating flow stress have the characteristics of delivering energy to the material to induce the release of flow stress. At present, the main methods for reducing the flow stress are natural aging [32], thermal aging [33], vibration [34], the mechanical stretching method [35], the hammering method [36], etc. Compared with traditional methods, the use of electropulsing treatment (EPT) technology stands out due to its energy–efficient, highly effective, straightforward and pollution–free characteristics.

In recent years, EPT has been a new metal material processing technology [37], which mainly uses high–density energy input and a high–intensity electric field effect to promote the microstructure evolution inside metal materials, thereby improving the performances of the materials [38]. The use of pulsed current to process metal materials has achieved many excellent results that are different from those of traditional processing methods, and it has been widely researched and applied as a potential innovative technology that can break through the bottleneck of traditional processing technology. The current mechanism of flow stress drop under EPT has been accepted due to the fact that the pulse current facilitates the movement of the dislocation, reduces the concentration of stress and reduces the flow stress. In fact, the pulse current can reduce flow stress resulting from the movement of dislocations, the distribution of phases and plastic deformation.

Here, we systematically summarized the mechanisms of flow stress drop under EPT and explored the influences of thermal and non-thermal effects on dislocations, phases, textures and recrystallization. We attempted to construct the mapping relationship between pulse current and stress and used numerical analysis and FES to verify the consistent relationship. Finally, we believe that analyzing the situation of multi-field coupling from a multi-scale perspective is beneficial for promoting mechanism studies on flow stress drop under EPT. This work has important implications for improving mechanical properties under EPT.

2. The Mapping Relationship between Pulse Current and Stress

Numerous studies have established that EPT is capable of diminishing the flow stress of metal materials [39]. The research group of Conrad diligently examined the decline in flow stress experienced by metals such as Al, Cu, Ti, Ni, Fe, W and Nb when exposed to electrical pulse stresses during linear tensile strain at a consistent rate [40–45]. Their findings indicate a significant reduction in flow stress when metals are subjected to an electrical current pulse with an amperage of 10^3 – 10^4 A/mm² for 60 µs. Evidently, this induces a relaxation in stress as the current traverses through the metallic framework [46–50]. Up to now, the inherent ability of EPT to reduce flow stress has been reported from different aspects. The flow stress drop mechanism of EPT in terms of the organizational structure and the field variation in FES is illustrated in Figure 1.



Figure 1. Schematic of reduction in flow stress from the perspectives of organizational evolution and FES under EPT.

Figure 2A illustrates Li et al.'s [51] methodology, where a pulsed current is injected into the prolonged stress relaxation of nanocrystalline nickel foils, enhancing the relaxation rate. The findings demonstrate that this rate escalates with the introduction of pulsed currents. Additionally, as the magnitude of the pulse current density escalates, so too does the enhancement of the relaxation effect. Zhan et al. [52] devised a constitutive model inspired by aged relaxation in light of pulse current effects during the creep aging deformation process. It has been observed that as temperature elevates, the rate of stress relaxation correspondingly increases, implying that the thermal activation of dislocations is a factor during stress relaxation (refer to Figure 2B). Yang et al. [53]. integrated various effects (magneto-plasticity, Joule heating, electron wind, etc.) to construct a crystal plasticity model, decoupling the non-thermal effects and thermal effects on dislocation activity and quantifying their influence on flow stress. As shown in Figure 2C(a), the difference in stress between the control sample and the sample subjected to applied current at a strain of 0.26% was observed. The stress drop induced by pulsed current is significantly higher than that induced by Joule heating or continuous current, despite the overall temperature being the same. The additional stress drop is attributed to the non-thermal effects induced by pulsed

current. Figure 2C(b) demonstrates that, at lower root mean square current densities, the reduction in stress due to Joule heating is smaller than the non–thermal effects of pulsed current. As the root mean square current density increases, the temperature further rises, and the non–thermal effects initially increase and then decrease. This implies the existence of an optimal root mean square current, leading to the most significant stress drop under density and steady–state temperature with prominent magneto–plastic effects.



Figure 2. (**A**) Graph detailing the curvature radius of samples under varied current densities and relaxation periods [51]. (**B**) Diagram depicting stress relaxation trends at different temperatures post EPT [52]. (**C**) (**a**) The total stress drop; (**b**) the relationship between the stress drop caused by non-thermal effects and the root mean square current density of steady-state temperature, pulsed current and continuous current. The stress drop during Joule heating is provided for comparison (CC: continuous current) [53].

Concisely, an upsurge in pulse current duration, alongside temperature and current density within prescribed limits, correlates with a reduction in residual stress because of flow stress drop [54]. Nonetheless, the precise dynamics and microstructural mechanisms underpinning the pulse current's impact on flow stress drop remain obscure, casting doubt on its industrial viability. Next, we try to summarize the research results of pulse current affecting flow stress in metal materials and discuss the influence law and mechanism of pulse current on flow stress in metal materials from the perspectives of dislocations, phases and grains.

3. Effects of EPT on Dislocations

The composition of flow stress, identified as $\Delta \sigma_i$ is attributed to both thermal and non–thermal influences induced by the pulse current [55,56]. The correlation between flow stress σ_i and the density of dislocations ρ adheres to the Kock-Mecking framework [56,57]:

$$\sigma_i = \sigma_0 + \overline{M} \, \alpha G b \sqrt{\rho} \tag{1}$$

where σ_0 represents the baseline stress constant, \overline{M} represents the effective orientation factor of Taylor, α is a defined constant, b denotes the Burgers vector, and G signifies the modulus of shear elasticity. The magnitude of flow stress is linked to the dislocation's magnitude squared, and a decline in dislocation density within the crystal matrix contributes to flow stress drop. The formulation for current–assisted dislocation ascension is delineated as follows [58]:

$$\nu = 4\pi a c^0 D_V \frac{f V_a}{l K_0 T} \tag{2}$$

where v is the dislocation climbing rate, a denotes the atomic transition interval, c^0 is the density of vacancy sites in an ideal crystal structure, D_V is the coefficient of vacancy volume diffusion, K_0 is a constant, T denotes temperature, f/l is the climbing force, and Va is the atomic volume. Joule heat can increase D_V and T, and electronic wind can increase D_V and f/l, both of which can promote dislocation climbing and reduce dislocation density.

XRD peak widening as a result of strain serves as a method used to gauge dislocation density [59]. For homogeneous materials, the Williamson–Hall [60] formula is used to infer dislocation density based on X-ray peak expansion:

$$\Delta K \approx \frac{\alpha_s}{D} + N\sqrt{\rho}K \tag{3}$$

where ΔK is the peak width, *N* stands for a constant, α_s stands for the shape factor, *D* is for the crystallite dimension, and *K* is for the diffraction vector's intensity. Considering the effect of strain anisotropy, an improved Williamson-Hall formula [61,62] was developed as follows:

$$\Delta K \approx \frac{\alpha_s}{D} + bM \sqrt{\frac{\pi}{2}\rho} \left(K\overline{C}^{1/2} \right) \tag{4}$$

In this model, the dislocation contrast factor \overline{C} relates to the Miller indices, M remains a non–dimensional constant, and b denotes the Burgers vector. In conclusion, one can ascertain dislocation density empirically from the XRD data of the sample (Figure 3A) [63]. Generally speaking, the dislocation density of metal tends to decrease after EPT, and its dislocation evolution is shown in Figure 3B [64].



Figure 3. Cont.



Figure 3. (**A**) (**a**) XRD patterns of AA2195 alloy under creep aging test (CCA) and electric–assisted creep aging (ECA) conditions; (**b**) impact of electrical pulsing on dislocation density within AA2195 alloy [63]. (**B**) Depiction of the dislocation development mechanism in ECA–treated samples (green lines, dislocations, green spheres, electrons; orange panels, T1 precursor; I, II, III and IV all represent dislocation lines during evolution) [64].

3.1. Joule Heat Effect

The process of pulse current input will produce flow around effects in various highstress areas such as grain boundaries, dislocations, second-phase particles, vacancies, cracks, etc., providing Joule heat to the defect area due to higher resistivity [65]. Joule heat accelerates the movements of dislocations and their climbing and annihilation on grain boundaries, which is beneficial to the homogenization of the organization, thereby resulting in a decrease in flow stress [66].

Contemporary findings indicate that the Joule heating phenomenon can lower the barrier to dislocation motion and enhance the process of dislocation cancellation, consequently decreasing dislocation concentration [67–70]. Typically, the grid resistance, known as the Peierls–Nabarro force due to the periodically distributed Peierls energy of activation, is the barrier that must be overcome for the dislocation to slip [71–73]. Influenced by the kink–pair mechanism, the rate of a moving dislocation over distance *L* is given by

$$V_{\rm g} = \nu_D \frac{bL}{x_c^2} \exp\left(-\frac{U_g(\tau)}{kT}\right) \tag{5}$$

where $U_g(\tau)$ symbolizes the stress-dependent activation energy, *b* denotes the Burgers vector, $v_D b/x_c$ defines the oscillation frequency of the dislocation over wavelength x_c , *k* denotes the Boltzmann constant, and *T* stands for temperature. The equation suggests that within the domains of stress and temperature, the kink-pair mechanism benefits from thermal activation, indicating an advantage of increased temperatures for dislocation movement [74].

Zhang and his team [75] uncovered a stress–softening occurrence through their investigation on the influence of electric–assisted deformation on nickel–based superalloys' a-phase, as depicted in Figure 4A. Their conclusion was that the localized Joule heat effect was responsible for this, as it encouraged both dislocation slip and dislocation recovery. Moreover, the quick rate of dislocation recovery resulted in the swift alleviation of dislocations surrounding the δ phase, which they identified as the primary cause for the formation of dislocation–free loops around said δ phase (Figure 4A(c,d)). In a separate study, Zhang and colleagues [76] theorized that dislocations running perpendicular to the current direction could hinder electron movement due to the dislocation region's high scattering coefficient. The localized Joule heat effect caused temperatures in these areas to rise, and the resulting local high temperature prompted dislocation annihilation (Figure 4B). In Figure 4C, the highest strains can be seen at the top and bottom of the dislocation core, with less strain on the left and right sides. If the electron motion is not aligned with the dislocation, electrons move to either side of the dislocation core and are heavily scattered by the core, as the red curve illustrates. The electron detour results in a high concentration of electrons on either side of the dislocation, scattering caused by the strain field is minimal, as demonstrated by the black curve [77]. Zhang et al. [78] suggested that the softening impact of Joule heating lessens the dislocation density (Figure 4D). Briefly, Joule heating promotes the motion of dislocations, causing them to annihilate, thereby reducing dislocation density and flow stress.



Figure 4. (**A**) Illustration depicting how dislocation varies due to local Joule heat effects near the δ phase throughout the EPT [75]. (**B**) Local Joule heat effect map of dislocations in different directions (A represents a dislocation in the current direction, and B and C represent a dislocation in the vertical current direction) [76]. (**C**) Schematic of electrons orbiting edge dislocations in various orientations, in which the colored parabolic areas represent the strain fields surrounding these dislocations (The red curve indicates that when the direction of electron movement is not parallel to the dislocation, the electron will move to the left or right of the dislocation core, and then be strongly scattered by the dislocation core. The black curve indicates that when the electrons move parallel to the dislocation arrangements via TEM: (**a**,**c**) display the dislocation patterns for samples T1 and T2, respectively, in the absence of electrical pulses, while (**b**,**d**) present the configurations for samples T1-EP, T2-EP and T3, with EP indicating the application of electrical pulses [78].

3.2. Electronic Wind Effect

During EPT, migratory electrons can produce an electronic wind that influences the dislocations, resulting in an acceleration of dislocation movement due to the electronic wind's momentum [79]. As the dislocations in the alloy are generally secured by the secondary– phase particles, the unbound ends of the dislocations twist around the secondary–phase particles due to the electric wind force until the dislocation lines align with the flow of current; concurrently, the electronic wind force reaches its minimum impact [80,81]. This phenomenon is a primary factor in the alignment and flattening of dislocations within the alloy's grains when subjected to pulse current, reflecting the most evident non–thermal consequence of the pulse current.

In 1963, Troitskii and Lichtman first revealed the electron wind effect in metal crystals, that is, the interaction between moving electrons and dislocations [82]. For electronic wind, three models are mainly assumed at present:

Kravchenko's [83]:

$$\frac{f_{ed}}{l} = \left[\frac{b}{4}\left(\frac{3n}{2E_F}\right)\frac{\Delta^2}{v_F}\right](\nu_e - \nu_d) = \frac{3b}{8}\frac{\Delta^2}{eE_Fv_F}J\tag{6}$$

Klimov et al.'s [84,85]:

$$\frac{f_{ed}}{l} = \frac{1}{3} nm^* bv_F (v_e - v_d) = \frac{m^* bv_F}{3} J$$
(7)

Roschupkin et al.'s [86]:

$$\frac{f_{ed}}{l} = \frac{2h}{\pi}n(\nu_e - \nu_d) = \frac{2h}{\pi}nJ$$
(8)

where $\frac{f_{ed}}{l}$ stands for the force of drift electrons acting on dislocations per unit length, v_e stands for the electron directional drift rate, v_d stands for the dislocation rate, b denotes the Burgers vector mode, e stands for the electron charge, n stands for the electron density, m^* stands for the effective electron mass, E_F stands for the Fermi energy, v_F stands for the Fermi rate, h stands for Planck's constant, J stands for current density, and Δ stands for the energy gap. According to the above model, it is clear that the electronic wind force is proportional to the current density, that is to say, the greater the current density, the more obvious the electronic wind effect. Therefore, the expression for the electronic wind force can be mainly assumed as follows [87]:

$$\frac{f_{ed}}{l} = K_{ed}J \tag{9}$$

In this formula, K_{ed} is called the electronic wind coefficient. However, according to Formulas (6)–(8), the calculated *Ked* values are 10^{-17} , 10^{-16} and 10^{-15} Nm/A, respectively. According to the experimental results, *Ked* is in the order of 10^{-12} Nm/A.

Furthermore, the current progress of the electronic wind model still relies on a series of publications by Conrad and his colleagues, providing a systematic framework for simulating the electronic wind effect with different models under various assumptions. For instance, in assuming electrostatic equilibrium, under an externally applied current, electrons move continuously without reaching equilibrium. The stress reduction caused by the electronic wind force can be represented by the following equation [88]:

$$\sigma_{ep} = \frac{Bv_d}{b} \tag{10}$$

In this formula, σ_{ep} represents the decreasing stress, v_d denotes the average dislocation velocity, *B* stands for the resistance coefficient, and *b* denotes the Burgers vector. Furthermore, models describing the decrease in flow stress often involve the combined expression of multiple effect mechanisms [53,89], with the individual electron wind effect still exhibiting the aforementioned issues.

Extensive research indicates that migratory electrons assume a distinctive function in electrical pulse treatment as an ancillary force that advances dislocations [90]. These dislocations ultimately accumulate at the grain boundaries and establish linear configurations [91,92]. As illustrated in Figure 5, the activities of vacancies and dislocations receive an upsurge through the influence of migratory electrons, which promotes the rapid resolution of dislocations. Additionally, with the effect of electronic wind, the Frank–Read [93] source is unable to generate a significant number of dislocations, effectively diminishing the frequency of dislocation propagation. In the end, there are reductions in dislocation concentration and the realignment of dislocation structures in accordance with the trajectory of the migrating electrons. It is noteworthy that this decrease in dislocation density significantly reduces the extent of the flow stress drop [94].



Figure 5. The green and orange arrows represent the direction of drift electron motion and dislocation structure, respectively. (**a**–**f**) The stress before and after EPT at the current densities of (**a**,**e**,**f**) 4482 A/mm² and (**b**–**d**) 5184 A/mm², respectively. (**a**) 355 MPa and 270 MPa; (**b**) 345 MPa and 172 MPa, respectively; (**c**,**d**) 396 MPa and 197 MPa, respectively; (**e**,**f**) 456 MPa and 197 MPa, respectively (A and B represent the two ends of the dislocation line respectively; The red arrow indicates the direction parallel to the dislocation the direction of the electron wind force; c,d,e with circle indicate where the actual dislocation structure is located) [94].

As shown in Figure 6, Zhou et al. [95] designed the non–isothermal creep–age forming (NICF) samples as controls at the same temperature to identify the non–thermal effect of

pulsed current. The main climbing force of F_c is the vacancy concentration gradient, which will generate the thermodynamic driving force F_{osm} . The F_c can drive the edge component to climb along the direction from the normal line to Burgers vectors b, resulting in the gradual expansion of the spiral turn in Figure 6a. The synergistic effect of the electronic wind force F_{ew} and the climbing force F_c cause the spiral dislocation to evolve into a conical spiral dislocation and finally into a straight line in assisted creep–age forming (ECF) samples (Figure 6b). A schematic of the dislocation configuration during NICF and ECF sample evolution is shown in Figure 6c.



Figure 6. Illustration of the dynamics of helical dislocations in NICF and ECF specimens, depicted in parts (**a**,**b**), respectively, with the climbing plane PN oriented perpendicular to vector b. (**c**) presents a visual representation of the dislocation arrangements observed during the progression of the NICF and ECF specimens [95].

Zhang and colleagues [96] explored how electric pulse treatment (EPT) influences the static recrystallization (SRX) texture in nickel–based superalloys subjected to cold deformation. Their research revealed that the electron wind's role in generating parallel dislocation arrays can indirectly facilitate the SRX mechanism, as shown in Figure 7A(a–d). Conversely, Zhao and their team [97] proposed that the alignment of dislocations in parallel formations, driven by the electron wind under high–energy pulse currents, plays a pivotal role in dislocation mobility, which is significantly influenced by the electron beam's total flux, as depicted in Figure 7A(e,f). In a different study, Han and colleagues [69] delved into the impacts of electric currents on the mechanical properties and microstructure transformation of Al–Mg–Li alloys through electric pulse–assisted uniaxial tensile (EAUT) tests. They observed that, unlike the random and entangled dislocations seen in traditional samples, dislocations within the EAUT–treated samples' matrix exhibited a tendency for near–parallel alignment due to the electron wind's influence, as illustrated in Figure 7B.



Figure 7. (**A**) (**a**–**d**) TEM images of EPT samples treated at different temperatures for 20 min [96]: (**a**,**b**) at 700 °C; (**c**,**d**) at 800 °C; (**e**) compressed without electropulsing; (**f**) compressed with electropulsing [97]. (**B**) TEM images showing <011>Al electron diffraction patterns and brightfield images of samples under different test conditions: (**a**–**c**) EAUT; (**d**–**f**) conventional high–temperature tensile test [69].

In fact, the electron wind also induces the regeneration of dislocations [98,99]. In general, when the slip direction is [uvw], the shear stress τ and Burgers vector b are as follows:

$$\tau \propto G \cdot b = G \cdot a / n \left(u^2 + v^2 + w^2 \right)^{1/2} \tag{11}$$

where *G* is indicative of the shear modulus, *a* symbolizes the lattice constant, and *n* refers to the kind of dislocation (which can be full or partial dislocations, and for partial dislocations, *n* exceeds that of full dislocations). In accordance with Equation (11), the shear stress τ has an inverse relationship with *n*, implying that, when circumstances are the same, the critically resolved shear stress of partial dislocations falls below that of complete dislocations. Hence, when conditions are equivalent, partial dislocations have a higher propensity to regenerate under the effect of electron force [100].

As shown in Figure 8A, Zhang and colleagues [101] documented the elimination and reformation of dislocations in superalloys under the influence of electron force, utilizing

electro-in situ transmission electron microscopy. It has been demonstrated that different slip systems experience different electronic forces, dislocation regeneration will be driven by the action of continuous current, the electron force will not disappear, the continuous multiplication of dislocations occurs in region 2, and the phenomenon of dislocations are first annihilated and then regenerated in region 1. In Figure 8B, Xia et al. [102] proposed that the electronic wind facilitates the conversion of forest dislocations into active ones, activating more slip systems and shortening the pinning duration of movable dislocations. As shown in Figure 8C, Daudi et al. [103] argued that in samples subjected to high electron wind, defects like micro/nano cracks and micropores evolve into dislocations from near defects toward the free surface, where some dislocations are extinguished, thus reducing the flow stress. Importantly, while the electronic wind encourages dislocation multiplication, it leads to a more even strain distribution. A uniform plastic deformation of the sample correlates with a reduction in flow stress [104].



Figure 8. (A) (a) illustrates the interaction between the electron flow direction and various crystal planes; (b) demonstrates the Schmid factor for each slip system when subjected to this specific direction of electron force; (c) depicts the behavior of dislocations on the (110) plane over time [101]. (B) offers a graphical representation of how electron wind influences a screw dislocation, considering different Burgers vectors [102]. (C) (a) displays a Ti–6Al–4V alloy before the application of electrical current and (b) shows the same alloy after being subjected to a current density of 5×10^5 A/cm², with arrows and ellipses highlighting areas of dislocation build–up, clustering and elimination, and arrows and ellipses showing dislocation accumulation, aggregation and annihilation [103].

A conceptual model was introduced that describes how high–energy pulsed currents impact the relaxation and duration of elastic forces. This model is rooted in the theory that the plastic flow of materials is primarily governed by the thermally driven movement of dislocations [105]:

$$S = \frac{e_p}{e_0} = \frac{Ge_p}{\tau_0} = \left[1 - \exp\left(-\frac{G\tau_p}{\mu}\right)\right] \cdot \left[\left(1 - \frac{\tau_s}{\tau_0}\right) + \left(\frac{\alpha I^2}{\tau_0}\right)\right]$$
(12)

where *S* is the flow stress drop rate, e_p signifies the extent of plastic deformation, e_0 denotes the initial elastic strain, *G* stands for the shear modulus, τ_0 symbolizes the initial shear stress, τ_p refers to the time span of the electric pulse, μ denotes the lattice viscosity coefficient, τ_s is lattice resistance, α is a parameter related to lattice vibration energy, and *I* is current. It is evident that the alleviation of stress is attributed to the synergistic effects of Joule heating and the electron wind phenomenon.

In summary, Joule heat and electron wind can promote the migration of dislocations and carry out the rearrangement of dislocations. The stress can be eliminated from two aspects: (1) Joule heat reduces dislocation density and (2) electron wind induces dislocation increment to promote the uniform deformation of the samples.

4. Effects of EPT on Phase and Void

The existing literature suggests that EPT–elicited solid–phase transitions are key in the development of ultrafine grain (UFG) structures and potential nanostructures [106,107]. EPT, as a process away from equilibrium, allows the unstable solid phase in high–temperature samples to be maintained after quickly cooling to room temperature (RT) [107,108]. The electrical pulse not only facilitates the progression from the metastable state to the equilibrium state, but also strengthens the stability of the metastable state [109].

4.1. Joule Heating and Electron Wind Effects

The influence of pulse current on atomic mobility can be represented by this equation:

$$V_{ie} = \frac{D_0 Z^* j_e \rho}{KT} |e| \cdot exp\left(-\frac{Q}{KT}\right)$$
(13)

where V_{ie} is the atomic mobility, D_0 signifies the self–diffusion coefficient, Z^* represents the effective charge, j_e indicates the current density, ρ indicates the density, e stands for the electron charge, K stands for the Boltzmann constant, T stands for temperature, and Q is the activation energy. In Joule heating theory, for a given electrical parameter, the electrical energy is simply calculated as follows:

$$E_{Joule} = J^2 \rho V \Delta t \tag{14}$$

$$\Delta T = \frac{J^2}{mc} \rho V \Delta t \tag{15}$$

$$\rho = \frac{2m^*\overline{\upsilon}}{n_{ef}e^2}\frac{1}{\overline{l}} = \frac{2m^*\overline{\upsilon}}{n_{ef}e^2}\mu$$
(16)

where in Equation (14), J signifies the current density, ρ denotes the resistivity, V stands for the volume of the conductive portion, and Δt stands for the current action time. In Equation (15), m stands for the mass of the conductive portion, and c stands for the specific heat capacity. In Equation (16), m^* stands for the effective mass of the electron, n_{ef} stands for the number of free electrons per unit volume, e is the electron charge, \bar{v} stands for mean velocity of motion, \bar{l} stands for the free path of the electron, and μ stands for the scattering coefficient. Studies have shown that the resistivity of defects is approximately six to eight times greater than that of defect–free lattices [110,111]. As current passes through the metal, the localized Joule heat effect generates a temporary localized high temperature at the crystal defect, leading to an increase in the diffusion coefficient [112]. Furthermore, the intense scattering of drift electrons can supply extra energy to decrease the activation energy of atomic diffusion.

4.2. Thermal Compressive Stress Effect

The rate at which the sample's temperature increases is extremely rapid when it is subjected to a high–density pulse current [40,113]. During this procedure, the expansion of the sample does not occur in sync with its temperature increase, indicating that the expansion trails behind the warming. As a result, even in the absence of external constraints, thermal compressive stress develops within the sample. The thermal compressive stress produced through thermal expansion hysteresis and temperature rise is given by the formula below [114]:

$$\sigma(t) = E\alpha\Delta T_{\max[\Theta(t)]} - l(t) \tag{17}$$

where $\Theta(t)$ is the dimensionless temperature rise at any moment ($\Theta(t) = \frac{\Delta T}{\Delta T_{max}}$), ΔT is the instantaneous temperature change, ΔT_{max} is the maximum temperature change, l(t)is the dimensionless expansion length ($l(t) = \frac{\Delta L}{\Delta L_{max}}$), where the ΔL is the instantaneous length change, ΔL_{max} is the maximum length change, E stands for the elastic modulus; and α stands for the expansion coefficient. The maximum thermal compressive stress might be $\sigma_{max} = E\alpha\Delta T_{max}$, as the current density becomes higher, the ΔT_{max} and thermal compressive stress becomes larger. Hence, it can be simply inferred that the thermal compressive stress is in direct proportion to the current density. Thermal compressive stress along with Joule heat can speed up the atomic migration, which is capable of crack repair, thereby reducing flow stress.

As depicted in Figure 9A, Bao and colleagues [115] hypothesized that during Electro-Assisted Micro–Compression (EAMC), the current initiates the $\alpha \rightarrow \beta \rightarrow \alpha'$ phase transition in Ti-6Al-4V alloys, where the "hot spot" effect of localized Joule heating serves as the primary driver for the nucleation of new β -phase. Zhu et al. [116] suggested that when vacancies migrate and accumulate in areas such as dislocations and grain boundaries, they turn into nucleation sites for precipitates. The kinetic energy exchange between drifting electrons and solute atoms (Ni and Si) enhances the diffusivity of the solute atoms and lowers the energy barrier that the solute atoms have to overcome during the precipitation process, thereby speeding up the formation of precipitates (Figure 9B). The application of an electrical pulse speeds up the diffusion of atoms and the movement of dislocations toward the crack, assisting in its healing. This healing phenomenon can be attributed to Joule heating and the thermal compressive stress caused by the pulsed current bypassing the crack tip (Figure 9C) [117]. In Figure 9D, the micropore collapse is caused by the local softening of the micropore edges due to Joule heating and thermocompression stress. Furthermore, EPT promotes the migration of atoms to locally recrystallize near the healing zone [118]. As shown in Figure 9E(c1,d1), Guo et al. [119] lattice distortion near the interface might be a result of atomic migration under pulse current. In Figure 9E(e1,f1), an increased presence of atomic vacancies and lattice distortions near the interface might be linked to the precipitation of the α phase in β grains and the atomic migration at the α tip during the phase transition.



Figure 9. (**A**) Conceptual sketch of the $\alpha \rightarrow \beta \rightarrow \alpha'$ phase transformation pattern in Ti–6Al–4V under EAMC [115]. (**B**) Conceptual sketch of the Cu–Ni–Si alloy undergoing EPT to create precipitates [116].

(C) Conceptual visualization of the mechanism for crack healing, the stages of crack healing are shown in (**a**–**c**) [117]. (**D**) (**a**) The generation of micropores due to plastic deformation; (**b**) the rerouting effect of the current in the defect zone; (**c**) Joule heating and thermal compressive stress surrounding the micropores; (**d**) the collapse and recrystallization of the micropores [118]. (**E**) High–resolution TEM (HRTEM) images of the α/β interface in EST3: (**a**,**b**) chosen areas of the α and β interfaces; (**c**,**c1**) the coherent α/β interface of the three–point grain boundary; (**d**,**d1**) distorted α/β interface and imperfections; (**e**,**e1**) imperfections at the edge and inside of the interface; (**f**,**f1**) distortion of three–point grain boundaries and imperfections along the interface [119].

To sum up, throughout the EPT procedure, the generation of Joule heating and the movement of electrons contribute to the acceleration of atom and vacancy diffusion because of increased resistivity [120,121], thereby realizing the phase transition (development to equilibrium). Furthermore, the hot–compression stress can further promote the migration of atoms around the pores and achieve the healing of the pores.

5. Effects of EPT on Texture and Recrystallization

The dissipation of residual stress through flow stress drop via pulsed current is crucial as it allows for the release of elastic forces within the material through either macroscopic or microscopic plastic deformation, driven by dislocation movement [122]. The interaction between the electroplastic effect and both thermal and non-thermal effects leads to a reduction in the material's flow stress; this means that dislocations will reorganize, creating high–density, low–angle boundaries to mitigate stress concentrations [123–125]. Additionally, as the frequency of the electric pulse increases, the extent of recrystallization also rises [126], leading to the formation of a recrystallized microstructure characterized by fine, equiaxed grains, which contributes to a reduction in the strength of the material's texture [127,128].

5.1. Electroplastic Effect

Upon the application of pulse current to the deformed alloy, there is a notable decrease in the alloy's resistance to deformation, and its plasticity is greatly enhanced [68]. As Conrad and colleagues [44,83] have suggested, the plastic deformation, which is governed by the thermally activated movement of dislocations, along with the plastic strain $\dot{\varepsilon}_p$ experienced during the pulse, is

$$\dot{\varepsilon}_p = \dot{\varepsilon}_1 \left\{ -\frac{\Delta H(\sigma^*)}{kT} \right\}$$
(18)

where ε_1 is the coefficient closely associated with the density of moveable dislocations, the vibration frequency of individual dislocations, the extent of area influenced by thermal oscillations and the activation entropy. ΔH denotes the energy of activation for enthalpy, σ^* is the effective stress applied, *k* represents the Boltzmann constant, and *T* stands for the temperature. Conrad [45] believes that the effects produced by the pulse current, both thermal and non-thermal, primarily influence the pre-exponential factor and the activation enthalpy associated with dislocation motion. When the current passing through the conductor does not alter the thermal activation properties of dislocation movement, the rate of plastic deformation ε under the influence of the current is [129]

$$\dot{\varepsilon} = \dot{\varepsilon}_1 exp\left(-\frac{U_0}{kT}\left[1 - \left(\frac{kTm}{U_0}\right)\ln\left(\frac{\sigma^*Gb}{l_c}\right)\right]\right)$$
(19)

where U_0 represents the activation energy, $\frac{Gb}{l_c}$ indicates the threshold stress for the dislocation to surpass the barrier, and *m* is an exponent not reliant on the effective stress, l_c is the barrier spacing. Force effects (electron wind, thermal compressive stress, magnetic force, etc.) can have an effect on the l_c , which may promote dislocations from local pinning and thus affect

the plastic behavior of materials [130]. Ma et al. [131] deduced the creep model under the coupled action of force, electricity and heat:

$$\dot{\varepsilon}_{ec} = \dot{\varepsilon}_1 exp\left(-\frac{Q-\Delta Q_e}{kT}\right) \left[\sinh\left(\xi\frac{\sigma}{s}\right)\right]^{1/m'} \tag{20}$$

where $\dot{\epsilon}_{ec}$ denotes the rate of inelastic strain, Q represents the energy required for activation, ξ stands for the stress multiplier, σ stands for the stress, s stands for the internal variable of the average isotropic resistance to plastic flow, m' stands for the strain rate sensitivity, and $\Delta Q_e = \beta j^2$ is activation energy change caused by the current. It is observed that (i) the thermal component of the electroplastic can lessen the resistance against dislocation motion due to lattice friction and boost the frequency of dislocation oscillations, thereby reducing the energy barrier for dislocation slip; and (ii) the non-thermal dimension of the electroplastic effect is capable of modifying the local energy landscape of the dislocation core, altering how dislocations navigate obstacles and decreasing the thermal activation barriers they encounter. The synergistic influence of these elements facilitates the material's plastic deformation, essential for flow stress drop within the sample.

5.2. Thermal and Non–Thermal Effects on Grain Boundary Migration

Annealing recrystallization nucleation can be characterized by the migration of lowangle boundaries (LABM) and the motion of high–angle boundaries (HABM) [132]. The noticeable increases in the migration rates of both low– and high–angle boundaries are due to the enhanced exchange of vacancies and individual atoms during the EPT process. Typically, the speeds at which these boundaries move (*v*) are described through the equation below [133,134]:

$$v = MP, \ M = M_0 exp\left(-\frac{Q}{RT}\right)$$
(21)

where *P* denotes driving pressure, *M* indicates the mobility of the boundary, M_0 stands for a material constant, *T* stands for the absolute temperature, *Q* represents the energy required for boundary migration, and *R* stands for the gas constant. In EPT, the total driving pressure is [135]

$$P = P_V + P_R + P_{th} + P_{ath} \tag{22}$$

where P_V signifies the volume energy, P_R stands for the energy associated with grain boundaries, P_{th} is predominantly linked to the thermal compressive stress resulting from Joule heat, and P_{ath} mainly refers to the electronic wind force. As the current density and frequency increase, M, P_{th} and P_{ath} exhibit pronounced rises, leading to elevated stored energy levels and accelerated boundary migration. Consequently, this phenomenon promotes the initiation of twin recrystallization at comparatively reduced temperatures.

During plastic deformation, alterations in the shape and alignment of grains lead to a non–uniform grain orientation. Recrystallization initiates at points where different twinning systems intersect or through the reorganization of lattice dislocations within the twinned regions, which can produce small, recrystallized grains inducing random misorientation and another deviation along the rolling direction (RD) [136]. The Kernel Average Misorientation (KAM) serves as an indicator of the homogeneity of plastic deformation. Gao and co–authors [137] demonstrated a relationship between the density of geometrically necessary dislocations (GNDs) and the KAM value, as indicated by the subsequent equation:

$$\rho^{GND} = \frac{2\theta}{\mu b} \tag{23}$$

where θ , μ , and *b* correspond to the average KAM measured in radians, the scanning step size and the Burgers vector, respectively. Typically, the extent of plastic deformation increases as the value of KAM increases, and the value of KAM increases as the texture strength becomes lower.

5.3. Effects on Texture

According to Troitskii's [138,139] study, when electrons move perpendicularly to the slip system, that is, when their path is orthogonal to dislocations on the slip plane, the plasticity of the crystal is substantially diminished. This effect is akin to the way precipitates can pin dislocations when the direction of electron flow is perpendicular to the plane defined by the dislocation and its Burgers vector, thereby impeding dislocation movement [140,141].

Figure 10A shows that the maximum texture strength of the cold–rolled samples after EPT decreased from 4.500 to 3.586, and the increase in the KAM value eliminated part of the stress [142]. In Figure 10B, the texture that developed post–compression at RT is solely a deformation texture due to crystal slip, with a texture strength of 7.255. This figure is significantly higher than that resulting from pulse current deformation (4.449 and 4.345). During the Electrically Assisted Microforming (EAM) compression process, the recrystallization texture prompted by the pulsed current and the deformation texture caused by crystal slip counteract each other. This interaction leads to a decrease in overall texture strength and an increase in the orientation dispersion within the grains [143].



Figure 10. (**A**) The IPF and $\phi^2 = 45^{\circ}$ ODF maps of 0° direction specimens (**a**) without treatment and (**b**) with EST2 treatment [142]. (**B**) Pole figure of samples under different conditions: (**a**) uncompressed;

(b) compressed at 0 A/mm^2 ; (c) compressed at 57.16 A/mm²; (d) compressed at 70.23 A/mm² [143]. (C): KAM distributions of (a) A0 sample; (b) A4 sample; and (c) A6 sample and (d) KAM numerical statistics [144]. (D) Inverse pole figures (IPFs) of the α^{-1} -Fe phase in the samples: (a) initial; (b) CQ + CT, (c1) EQ + ET, (c2) IPFs of γ -Fe phase in EQ + ET sample; note: ND denotes the normal direction [145]. (E) Characteristics of the external load and electron wind stress and the rotation law of the crystal grains under the coupled stress field: (a) stress state in different regions during simple compression; (b) relationship between the stress state and grain rotation at A3 in sample A during simple compression; (d) stress state and grain rotation angle at A3 in sample A during simple compression; (e) stress state and grain rotation angle at A2 in sample A during simple compression; (g) coupled stress field and grain rotation at B3 in sample B during electroplastic compression; (g) coupled stress field and grain rotation at B2 in sample B during electroplastic compression; [146].

In Figure 10C, Ang et al. [144] believed that dislocations annihilate, grains rotate, and subgrain boundaries increase under the action of induced current. In Figure 11B(a), a pronounced <111> texture of α' -Fe appeared in TD, whereas it was weakened after tempering and conventional quenching (CT + CQ), as shown in Figure 10D(b). Nonetheless, this <111> texture nearly vanishes after tempering and electropulse quenching (ET + EQ), with the emergence of a new <110> texture (α' -Fe) aligned with the direction of the current, as depicted in Figure 10D(c1). In addition, the <111> orientation in the majority of the γ -Fe phase in the ET + EQ specimen is also aligned parallel to the current direction (Figure 10D(c2)). This underscores the critical influence of the current on the evolution of texture, while also facilitating the rapid release of micro–residual stress without a marked decrease in dislocation density [145]. Ultimately, the texture of the slip system is enhanced through the promotion of dislocation slip, and the electric current assists in achieving a more uniform texture across the sample (Figure 10E) [146].

5.4. Effects on Recrystallization

When subjected to pulse current, the material's structure evolves toward a state of reduced free energy, meaning the current lowers the material's resistivity and consequently decreases its electrical energy's free energy [147–150]. Furthermore, Qin et al. [151–154] proposed that the decrease in electrical free energy serves as the catalyst for the material's structural transformation. Qin et al. [155,156] studied the mechanism of recrystallization of wrought metals under electric pulses and showed that the Gibbs free energy changes in wrought metals during pulse–treated recrystallization can be expressed as follows:

$$\Delta G = \Delta G^d + \Delta G^o + \Delta G^a \tag{24}$$

where ΔG denotes the total alteration in Gibbs free energy, ΔG^d represents the stored energy inside the deformed metal, and ΔG^o and ΔG^a represent the additional free energy introduced by the non-thermal and thermal influences of the pulse current, respectively. In line with established nucleation theory, the rate at which recrystallization nuclei form, denoted by I_e , in the context of electric pulse treatment, can be articulated as follows:

$$I_e = I_0 \cdot \left(\frac{D}{\lambda^2}\right) \cdot exp\left(-\frac{\Delta G^d + \Delta G^o + \Delta G^a}{RT}\right)$$
(25)

where I_0 is a constant, λ represents the transition distance of the atom, *T* represents the absolute temperature, *R* represents the Boltzmann constant, and *D* represents the diffusion coefficient. With the application of pulsed current, the expansion rate of the recrystallized core is described as follows:

$$G = \frac{G_0}{E_0} \sqrt{E_0^2 - C\lambda b^2 J [K_{ew} \Omega(d_t - d_0)] + w N_b \rho e Z_b^* \ln(d_t / d_0)}$$
(26)

where E_0 is the initial storage energy, G_0 stands for the initial rate of crystal nucleus growth, λ indicates the grain boundary diffusion coefficient, K_{ew} is the electron wind correlation coefficient, C represents the positive coefficient, J is current density, Ω indicates the atomic volume, N_b is the atomic density at the grain boundary, w is the width of the grain boundary, ρ is the ideal crystal resistance, eZ_b^* is the effective charge of the metal ion at the grain boundary, and d_t and d_0 are the grown grain diameter and the original grain diameter, respectively. It can be seen that in the process of EPT, the non-thermal and thermal effects of pulsed current can increase the nucleation rate of recrystallization, but the grain growth is inhibited. The non-thermal and thermal effects can be simply understood as the Joule heat effect and electronic wind effect.

As shown in Figure 11A, Wang et al. [157] illustrated that with the prolongation of the high–density multiple pulse treatment (HMPT) time, the high–density dislocation cells and some entanglements disappeared, and the subcrystals preferentially merged through dislocation climbing in the localized regions with a high dislocation density. The majority of equiaxed recrystallized structures exhibit a flattened grain boundary morphology, as depicted in Figure 11A(e). New recrystallized nuclei are observed at the tri–angular intersection of grain boundaries at 120°, suggesting simultaneous nucleation and grain growth during the recrystallization process. Zhu et al. [158] confirmed that EPT has the capability to lower the activation energy for recrystallization and enhance the nucleation rate, thus facilitating the acceleration of new strain–free equiaxed grains via recrystallization, as illustrated in Figure 11B. The peak of the intragranular deflection angle decreases from ~1° to ~0.5° with increasing Joule temperature. It indicates that the subgrain merges or the subgrain boundary migrates, forming a low–angle grain boundary (2~10°).



Figure 11. (**A**) TEM images at various stages of the HMPT process: (**a**) initial state; (**b**–**f**) after HMPT 0.58 s, 1.16 s, 1.74 s, 2.32 s and 2.90 s, respectively [157]. (**B**) EBSD grain diagrams and recrystallization

fractions of cold–rolled AZ31 magnesium alloy strip at 250 °C before and after electrical pulse and annealing treatments at different times: (**a**) as received; (**b**) electrical–pulsed for 1800 s; (**c**) annealed for 19,200 s [158]. (**C**) (**a–c**) Images showing grain misorientation along selected lines (L1–L3) in samples subjected to EHT at temperatures of 805, 855 and 905 °C for 5 min each; (**d**–**f**) local misorientation maps in the black spots treated with different EHT temperature at 805, 855 and 905 °C for 5 min, respectively [159]. (**D**) Diffusion and recrystallization mechanism of interface elements of TA1/304 composite plate under EPT [160].

The presence of a small orientation deviation peak of 1° within the black spot represents the characteristic microstructure of recrystallized grains. Consequently, the electroplating effect accelerates the recrystallization process of abnormal beta grains when compared to traditional furnace heating methods. In Figure 11C(a–c), electron wind and localized Joule heating contribute to the formation of dislocation loops or low–angle boundaries, thereby expediting phase transformation and recrystallization within the abnormal beta grain region. Notably, these defects, which induce lattice stress in the black dot region, result from dislocation interactions as depicted in Figure 11C(d–f) [159]. Ren et al. [160] proposed that, under the influence of EPT, a new undistorted grain core is generated in highly distorted regions, subsequently absorbing the surrounding deformed matrix for growth. The presence of dislocations and solute atoms at grain boundaries impedes the growth of equiaxed grains, leading to their alignment in strips and forming monolayer grains as shown in Figure 11D.

In conclusion, compared with the conventional treatment, the coupling of non-thermal and thermal effects of pulse current leads to an increase in nucleation rate. Furthermore, the increases in atomic diffusivity, dislocation arrangement and grain boundary migration promote the formation of recrystallization and texture modification. Flow stress can be reduced through plastic deformation caused by recrystallization and texture modification.

6. Finite Element Applications

The finite element model was constructed upon a set of governing equations, which encompass the dynamic coupling of principles such as the conservation of charge, Fourier's law and equations of kinetic mechanics [161–163]. Pulsed current processing entails considerations of electromagnetism, electrodynamics, plastic dynamics and heat transfer [164,165]. Within the EPT process, Finite Element Simulation (FES) is predominantly employed to investigate the effects of different materials and control parameters on thermal, electrical and stress distributions within the system [166–168].

In the EPT process, significant features include the (i) transient stress drop during current density application, (ii) recovery of hardening behavior during current removal and (iii) long–range thermal softening [169–171]. A robust model must accurately capture the respective features in either mode currently applied. With the understanding of the electroplastic mechanism, the FES modeling has been realized from Joule heat to Joule heat coupled with electron wind to Joule heat coupled with electron wind based on dislocation density [172–175]. Table 1 presents the classification of constitutive models for electroplasticity. Importantly, none of the current constitutive models can accurately describe the specific process of flow stress drop using pulsed current, indicating the need for further modification.

Figure 12A illustrates the matrix as a high–conductivity cube, with the untreated sample's dislocation entanglement reduced to three mutually perpendicular, connected rods of low conductivity. Thermal compressive stress peaks at the entanglement's pinning point, leading to its gradual disappearance and leaving only dislocations parallel to the current direction during EPT [176]. As shown in Figure 12B, Qin et al. [177] used MATLAB and the finite difference method to solve the topologically close–pack (TCP) phase model. The results reveal that the current density peaks at the tip of the TCP phase, with stronger electron winds accelerating atomic diffusion. Additionally, a reduction in size correlates with a decrease in electrical free energy. Figure 12C presents simulation and experimental

results of three sets of tested recrystallized grains. Colored grains represent recrystallized grains, while white grains represent the matrix. The standard errors for all three sets of results are $\pm 4.56\%$, suggesting that the recrystallization nucleation mechanism of the Al–Zn–Mg–Cu alloy is dynamic recrystallization [178]. Figure 12D showcases the simulation conducted by Tiwari et al. [169] on the changes in material mechanical behavior solely due to Joule heating, employing finite elements within a coupled electro–thermal–mechanical model. The results indicate that Joule heating can effectively reduce stress.



Figure 12. (**A**) FEM simulation illustrating the impact of electropulsing on dislocation entanglement in the untreated AA6061 alloy: (**a**) model representation; (**b**) meshing configuration; (**c**–**e**) and (**f**–**h**) illustrations of current density and thermal distribution across the XY, ZY and ZX planes; (**i**) depiction of thermal compressive stress affecting dislocations aligned with the electric current (along the Y– axis) [176]. (**B**) (**a**–**e**) Current distribution around needle TCP phases of different sizes ((**a**): **a** = 0.5 µm, **b** = 0.5 µm; (**b**): **a** = 1.0 µm, **b** = 1.0 µm; (**c**): **a** = 1.0 µm, **b** = 2.0 µm; (**d**): **a** = 1.0 µm, **b** = 4.0 µm; (**e**): **a** = 1.0 µm, **b** = 6.0 µm); (**f**) graph illustrating the variation of electrical free energy corresponding to size diminution [177]. (**C**) Simulated outcomes for (**a**) Group A; (**b**) Group B; (**c**) Group C, alongside experimental findings for (**d**) Group A; (**e**) Group B; (**f**) Group C [178]. (**D**) (**a**) Dislocation density metrics; (**b**) room–temperature strain–hardening rate juxtaposed with constant–amplitude DC–enhanced (EA) deformation across true plastic strain; (**c**) FES data showcasing the Joule heating effect during electrically assisted compression testing, presented on true stress–true plastic strain graphs along with EA and RT deformation readings [169].

Models	Constitutive Equation	Authors
Empirical models	$\sigma = K\varepsilon^{n} + A(1 - exp(B\varepsilon)), A = f(J^{2})$ $\sigma = [(A + B\varepsilon^{n}) + 1 - exp(D_{1}\varepsilon_{2}^{D})T_{1}\varepsilon_{1}^{T}], T_{1}, T_{2} = f(J^{2})$	Roh et al. [179] Kim et al. [180]
Joule heating-based models	$\begin{split} \sigma &= f(T) \\ \dot{\varepsilon}_T &= \dot{\varepsilon}_E + \dot{\varepsilon}_{th} + \dot{\varepsilon}_{p,} \dot{\varepsilon}_p = f(\sigma, \varepsilon, T) \\ \sigma &= A\varepsilon^n - B(\zeta VI), \zeta = f(T) \\ \sigma &= K\varepsilon^n \varepsilon^s, K, \ n, \ s &= f(T) \\ \sigma &= K(T)\varepsilon^n \\ \sigma &= K(T)\varepsilon^n \\ T &\propto J^2, k_{EA} = Cf_T(f_J(gb))\sigma_{gb} - f_J(g)\sigma_g, \ f_T, f_J(g, gb) = f(T) \\ R &= Cf(T) \end{split}$	Kronenberger et al. [181] Gallo et al. [182] Salandro et al. [183] Jones [184] Magargee et al. [185] Zheng et al. [186] Wang et al. [111] Wang et al. [187]
Viscoplastic equation- based models	$\sigma = \sigma(\varepsilon, \varepsilon, T) + M/bK_{ew}J$ $\sigma_{exp} = \Delta\sigma_T + \Delta\sigma_{VE} + \Delta\sigma_{EP}$ $\sigma_{exp} = \Delta\sigma_T + \Delta\sigma_{EP}$ $\sigma_{EA}(\varepsilon, \varepsilon, T, J) = C(\varepsilon, \varepsilon, T) + \sigma_{ew}(J)$	Conrad [44] Lee et al. [188] Hariharan et al. [189] Wang et al. [190]
Physically based-models		Lahiri et al. [191] Dimitrov et al. [192] Kim et al. [193] Liu et al. [194] Hariharan et al. [172]

Table 1. The constitutive models of the mechanical behaviors of materials under the current application.

7. Conclusion and Perspective

Controlling flow stress in metal materials through pulse current has emerged as a rapidly advancing research field, garnering increasing attention and notable progress. Reducing flow stress using EPT is a nascent area of research, fraught with numerous challenges and uncertainties, especially when compared to traditional methods like natural aging, thermal aging, vibration aging, explosion and hammering methods. This progress report presents a comprehensive overview of recent advancements in understanding the microscopic mechanisms of EPT for mitigating flow stress. Additionally, we offer an indepth analysis covering various scales, including dislocation behavior, atomic structure, phase transitions, texture development and recrystallization processes. Through this discourse, we enhance our comprehension of how EPT relieves flow stress by examining it from the perspective of organizational structure evolution at the microscopic level. Then, we tried to isolate the various effects caused by the pulse current, and systematically illustrated each effect on the evolution of organizational structure.

Despite being in its infancy, research on flow stress drop through EPT remains highly appealing. Presently, there is a lack of comprehensive theories and models applicable to EPT, and the observation and mechanism description of the specific microscopic process of reducing flow stress under pulsed current are still unclear. The research prospect of EPT is broad, and the regular research results need to be further explored. It is important to note that future investigations into flow stress drop under EPT will need to carefully address several challenges and issues. From our perspective, the most significant of these issues are summarized as follows:

- 1. As for the microscopic mechanism of flow stress drop under EPT, it is generally believed that the Joule thermal effect, electronic wind effect and electroplastic effect have the main influence on the flow stress drop compared with skin effect, magnetostriction effect and pinch effect. Although the electroplastic effect has been widely recognized, the underlying mechanism related to the electric wind force has been controversial, and most studies have difficulty in separating these effects.
- 2. Currently, several mechanisms have been proposed to explain the drop of flow stress through EPT: (i) Joule heat and electron wind can promote the migration of dislocations and carry out the rearrangement of dislocations. During the climbing, dislocation annihilation dominates, thereby reducing the dislocation density and flow stress. (ii) The electroplastic and Joule thermal effects decrease the frictional resistance within the dislocation lattice, thereby lowering the flow stress of the material. Once the

flow stress drops below the initial residual stress level, the material undergoes plastic deformation, leading to residual stress reduction. (iii) The coupling of non-thermal and thermal effects induced by pulse current promotes atomic diffusion, dislocation rearrangement and grain boundary migration, leading to plastic deformation and flow stress drop.

- 3. The electronic wind coefficient Ked calculated according to Equations (6)–(8) yields values on the order of 10⁻¹⁷, 10⁻¹⁶ and 10⁻¹⁵ Nm/A, respectively. In contrast, experimental results yield Ked values on the order of 10⁻¹² Nm/A [44,45,195]. This huge discrepancy between theoretical and experimental results is something that electronic wind models have failed to address for years. The model of electronic wind power needs further revision.
- 4. We believe that multiscale computation is the future direction of the microscopic mechanism of flow stress drop under EPT. First-principle calculations reveal that charge imbalances near defects weaken atomic bonding under electric current [196]. Machine learning can further be used to calculate the macroscopic dislocation density. Multi-scale calculation combined with numerical analysis and finite element simulation can better describe the specific microscopic process of material flow stress drop under electric current.

In summary, in this burgeoning field of research, the exemplary instances provided for the various effects on the evolution of organizational structures in this progress report may be constrained by their brevity. It is conceivable that the drop of flow stress under EPT needs to be modified and improved in theory and model. In future work, we should consider how to further clarify the relationship between the material structure, performance parameters and the flow stress drop under EPT. Additionally, the influences of the pulse current waveform, frequency and other parameters also need to be further explored and analyzed. We posit that this progress report holds significant implications for the reduction of flow stress through EPT and the enhancement of mechanical properties in metal materials.

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