



# Proceeding Paper Discretized Finsler Structure: An Approach to Quantizing the First Fundamental Form <sup>+</sup>

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+ Presented at the 2nd Electronic Conference on Universe, 16 February–2 March 2023; Available online: https://ecu2023.sciforum.net/.

Abstract: Whether an algebraic or a geometric or a phenomenological prescription is applied, the first fundamental form is unambiguously related to the modeling of the curved spacetime. Accordingly, we assume that the possible quantization of the first fundamental form could be proposed. For precise accurate measurement of the first fundamental form  $ds^2 = g_{\mu\nu}dx^{\mu}dx^{\nu}$ , the author derived a quantum-induced revision of the fundamental tensor. To this end, the four-dimensional Riemann manifold is extended to the eight-dimensional Finsler manifold, in which the quadratic restriction on the length measure is relaxed, especially in the relativistic regime; the minimum measurable length could be imposed ad hoc on the Finsler structure. The present script introduces an approach to quantize the fundamental tensor and first fundamental form. Based on gravitized quantum mechanics, the resulting relativistic generalized uncertainty principle (RGUP) is directly imposed on the Finsler structure,  $F(\hat{x}_0^{\mu}, \hat{p}_0^{\nu})$ , which is obviously homogeneous to one degree in  $\hat{p}_0^{\mu}$ . The momentum of a test particle with mass  $\bar{m} = m/m_p$  with  $m_p$  is the Planck mass. This unambiguously results in the quantized first fundamental form  $d\tilde{s}^2 = [1 + (1 + 2\beta \hat{p}_0^{\rho} \hat{p}_{0\rho}) \bar{m}^2 (|\ddot{x}|/\mathcal{A})^2] g_{\mu\nu} d\hat{x}^{\mu} d\hat{x}^{\nu}$ , where  $\ddot{x}$  is the proper spacelike four-acceleration, A is the maximal proper acceleration, and  $\beta$  is the RGUP parameter. We conclude that an additional source of curvature associated with the mass *m*, whose test particle is accelerated at  $|\ddot{x}|$ , apparently emerges. Thereby, quantizations of the fundamental tensor and first fundamental form are feasible.

**Keywords:** modified theories of gravity; noncommutative geometry; curved spacetime; relativity and gravitation

## 1. Introduction

Following the assumption that the additional curvatures related to relativistic eightdimensional spacetime tangent bundle  $TM = M_4 \otimes M_4$  would be utilized to mimic the possible quantization on the four-dimensional spacetime  $M_4$ , the pseudo-Riemann manifold [1–4], this paper aims to introduce various possibilities for quantizing the first fundamental form, the line element, of curved spacetime in the relativistic regime. To this end, we suggest the Finslerian manifold, which is a smooth *n*-dimensional differentiable manifold  $M_4$  equipped with a continuous non-negative Finsler norm  $F : TM \rightarrow [0, +\infty)$ defined on the tangent bundle. For each point *x* on  $M_4$ , whose coordinates are  $x^{\mu} = (ct, x^i)$ , so that  $(x^{\mu}, \dot{x}^{\nu}) \mapsto F(x^{\mu}, \dot{x}^{\nu})$ , where  $\mu, \nu = 0, 1, 2, 3$  and  $\dot{x}^{\nu} = \partial x^{\nu} / \partial s$  are tangent vectors and  $\dot{x}^{\mu} \in T_x M$ , with the tangent bundle  $T_x M$  at *x* and  $TM := U_{x \in M} T_x M$  is the tangent bundle on M, it is conjectured that  $F(x^{\mu}, \dot{x}^{\nu})$  satisfies three properties, namely

- Positive definiteness, i.e., *F* is smooth on the complement of the zero section on *TM*,
- Positive homogeneity, i.e., *F* is positively 1-homogeneous in  $\dot{x}^{\mu}$ , the relativistic fourvelocity, i.e.,  $F(x^{\mu}, \lambda \dot{x}^{\mu}) = \lambda F(x^{\mu}, \dot{x}^{\nu}), \forall \lambda \in \mathbb{R}^+$ , and
- Subadditivity, i.e., for vectors  $\vec{v}$  and  $\vec{w}$  tangent to  $M_4$  at the point x, F fulfills (pointwise) the triangle inequality  $F(x^{\mu}, \vec{v} + \vec{w}) \leq F(x^{\mu}, \vec{v}) + F(x^{\mu}, \vec{w})$ .



Citation: Tawfik, A.N. Discretized Finsler Structure: An Approach to Quantizing the First Fundamental Form. *Phys. Sci. Forum* **2023**, *7*, 36. https://doi.org/10.3390/ ECU2023-14066

Academic Editor: Lorenzo Iorio

Published: 18 February 2023



**Copyright:** © 2023 by the author. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). The Hessian of  $F^2(x^{\alpha}, \dot{x}^{\beta})$  determines the Finsler metric,

$$g_{AB} = \frac{1}{2} \frac{\partial^2}{\partial \dot{x}^{\alpha} \partial \dot{x}^{\beta}} F^2(x^{\alpha}, \dot{x}^{\beta}), \tag{1}$$

with  $A, B = 0, 1, 2, \dots, 7$ , while  $\alpha, \beta = 0, 1, 2, 3$  and the resulting  $g_{AB}$  is positive.

Our approach to deriving a quantum-induced revisiting metric tensor shall be outlined in Section 2. However, before we begin, some comments on the Finsler manifold are now in order.

- First, the Finsler manifolds characterized by  $M_4$  and  $F^2(x^{\mu}, \dot{x}^{\nu})$ . By this, we mean that the Finsler manifold is composed of (i) a base space and (ii) a real scalar-valued function *F*. The base space is a set of positions in  $\mathbb{R}^4$ . The real scalar-valued function  $\mathbb{R}^4 \times \mathbb{R}^4 \to \mathbb{R}^+$  captures the additional structure of the space.
- Second, in *TM*, the covariant derivatives represent the standard operators of the Heisenberg algebra and the components of the curvature tensor represent the noncommutation relations [5–7].
- Third, the Finsler geometry, which is Riemann geometry but with relaxed quadratic measure restriction, is also concerned with measuring distances on abstract spaces. In the context of the present script, we recall that the distance between two points on the Finsler manifold is defined in a similar manner to the standard Euclidean distance, i.e., the length of the shortest curve connecting those two points. On the Euclidean manifold, the length of a curve is a sum over infinitesimal line elements *ds*. On the Finsler manifold, on the other hand, the summation over *ds* is weighted depending on position and direction. Therefore, the Finsler geometry is formulated with the directions of the tangent vectors  $\dot{x}^{\mu}$ , but not with their magnitudes. This leads to two kinds of affine connections. One is with respect to the infinitesimal changes in the directional variables. The other one is with respect to the infinitesimal changes in the coordinates.

A possible discretization of the spacetime manifold is based on qravitized quantum mechanics, i.e., the relativistic generalized uncertainty principle (RGUP) [8–11]. In Section 2, we first introduce our approach to manifolds. This is an almost ad hoc imposition of the minimum measurable length on the continuous Finsler structure.

#### 2. First Fundamental Form on Continuous Finsler Manifold

The proposed approach is based on the existence of a minimum measurable length, which was proved in loop quantum gravity, doubly special relativity, and string theory, for instance. The minimum measurable length could be interpreted as a nonvanishing position uncertainty that emerged from the impacts of finite gravitational fields on the Heisenberg uncertainty principle, the fundamental theory of quantum mechanics [8–11].

The Finsler structure of the Riemann manifold is conjectured to satisfy

$$F^{2}(x, \dot{x}) = g_{\mu\nu}(x) \dot{x}^{\mu} \dot{x}^{\nu}, \qquad (2)$$

where  $g_{\mu\nu}(x)$  is Finsler metric which is apparently distinct from the Riemann metric  $g_{\mu\nu}$ . Then, the length of the curve  $s : [0, L] \to M_4$  is given as

$$\mathcal{L}(s) = \int_0^L F\left(s(t), \frac{\dot{s}(t)}{||\dot{s}(t)||}\right) ||\dot{s}(t)|| dt, \tag{3}$$

where  $\dot{s}(t) = ds(t)/dt$ ,  $t \mapsto s(t)$  on  $M_4$ , and the tangent norm does not need to be induced by an inner product. The Euclidean length of that curve can be deduced from Equation (3), at F = 1.

As *F* at any point  $(x, \dot{x})$  is positively homogeneous of degree one in  $\dot{x}(t)$ ,

$$\mathcal{L}(x) = \int_0^L F(x(t), \dot{x}(t)) dt, \qquad (4)$$

so that the function *F* is locally acting on the first fundamental form *ds*. The resulting length of the curve does not depend on the choice of the parameter *t* along the curve measure.

The Riemannian geometry is obtained as a particular case, namely,  $F^2(x^{\mu}, \dot{x}^{\nu}) = g_{\mu\nu}(x)\dot{x}^{\mu}\dot{x}^{\nu}$ . Riemann metric  $g_{\mu\nu}$  and the Finsler metric  $g_{\mu\nu}(x)$ , are equal, especially at the point x. This is not the case with general Finsler metrics. Both  $F(x^{\mu}, \dot{x}^{\nu})$  and  $g_{\mu\nu}(x)$  determine the Finslerian geometry, while the Riemannian geometry is merely derived from  $g_{\mu\nu}$ .

With the finite positive minimum measurable length

$$\Delta x_{\min} = \sqrt{-|g||\beta_0|\ell_{\rm P}}, \tag{5}$$

where  $\ell_p$  is the Planck length, *g* is the fundamental metric and  $|\beta_0|$  is a dimensionless RGUP parameter that can be determined from cosmological observations [11,12] or table-top laboratory experiments [13], the Finsler structure reads

$$F(x^{\mu}, \sqrt{-|g||\beta_0|}\ell_{\mathbf{p}} \dot{x}^{\mu}) = \sqrt{-|g||\beta_0|}\ell_{\mathbf{p}} F(x^{\mu}, \dot{x}^{\mu}), \quad \forall \sqrt{-|g||\beta_0|}\ell_{\mathbf{p}} \in \mathbb{R}^+.$$
(6)

Other RGUP approaches have been discussed in the literature [14–16]. As for the RGUP approach proposed by the authors of [17–19],

- $\sqrt{-|g|}$  characterizes the relevance to curved spacetime.
- It assigns physical dimensions to the spacetime coordinates of the general theory of relativity.
- It also ensures physical interpretation is independent of the choices of coordinates, while |β<sub>0</sub>| introduces the consequences of gravity to the relativistic Heisenberg uncertainty principle [17–19].

Accordingly, the local coordinates on TM are expressed as

$$x^{A} = \left(x^{\alpha}, \sqrt{-|g||\beta_{0}|} \dot{x}^{\alpha}\right), \tag{7}$$

and the first fundamental form, the infinitesimal distance in the relativistic eight-dimensional spacetime tangent bundle *TM*, reads,

$$d\tilde{s}^2 = g_{AB} \, dx^A \, dx^B. \tag{8}$$

Equation (7) introduces a relation between eight- and four-dimensional spaces.

With the eight parametric equations

$$x^A = x^A(\zeta), \tag{9}$$

$$\dot{x}^{\alpha} = \frac{\partial x^{\alpha}(\zeta)}{\partial \zeta^{\mu}} \dot{\zeta}^{\mu}, \qquad (10)$$

the four-coordinates  $x^{\mu}$  on *TM* are correlated with the parameterization  $\zeta$ , four-coordinates parameterizing the four-dimensional spacetime manifold  $M_4$  [5], the counterpart first fundamental form, line element, can be parameterized as

$$d\tilde{s}^2 = \tilde{g}_{\mu\nu} d\zeta^{\mu} d\zeta^{\nu}. \tag{11}$$

Then, by equating (8) and (11), we get

$$\tilde{g}_{\mu\nu} = g_{AB} \frac{\partial x^A(\zeta)}{\partial \zeta^{\mu}} \frac{\partial x^B(\zeta)}{\partial \zeta^{\nu}}.$$
(12)

Differentiating the eight-dimensional coordinates on TM with respect to the fourdimensional coordinates  $\zeta^{\mu}$  on  $M_4$  determines the quantum-induced corrections to the fundamental tensor

$$\tilde{g}_{\mu\nu} = \left[1 + \left(-|g\beta_0|\ell_{\rm P}^2\right)|\ddot{x}|^2\right]g_{\mu\nu}.$$
(13)

where  $|\ddot{x}|^2 \equiv \ddot{x}^{\lambda} \ddot{x}_{\lambda} = g_{\delta\gamma} \ddot{x}^{\delta} \ddot{x}^{\gamma}$  with  $\lambda$ ,  $\delta$ ,  $\gamma$  are dummy indices and  $\ddot{x}^{\lambda} = \partial \dot{x}^{\lambda} / \partial \zeta^{\lambda}$ .  $\ddot{x}^{\lambda}$  could be interpreted as proper spacelike four-acceleration [20,21]. Alternatively,  $\ddot{x}^{\lambda}$  would be interpreted as geodesic, related to the additional curvature. To avoid any controversial discussion about the physical meaning of  $\ddot{x}^{\lambda}$ , we suggest normalizing  $\ddot{x}^{\lambda}$  to  $-|g\beta_0|\ell_p^2$ . A second reason for this normalization would be the conservative representation of the key results concluded in the present paper, which states that we are presenting quantum-induced corrections, but not a full quantization.

To summarize the present section, we conclude that the first fundamental form reads

$$d\tilde{s}^{2} = \left[1 + \left(-|g\beta_{0}|\ell_{\rm p}^{2}\right)|\ddot{x}|^{2}\right]g_{\mu\nu}dx^{\mu}dx^{\nu}.$$
 (14)

As discussed, Equation (13) refers to a quantum-induced revisiting metric tensor derived deduced from the *continuous* Finsler manifold.

Section 3 introduces an improvement based on proper inclusion of RGUP, not just its minimum measurable length, within the curved spacetime. This is a profound contribution of the present study.

#### 3. First Fundamental Form on Discretized Finsler Manifold

In Section 2, we have introduced our approach based on the emergence of an additional curvature on the relativistic eight-dimensional spacetime tangent bundle *TM*, which is equipped with a continuous nonnegative Finsler norm  $F : TM \rightarrow [0, +\infty)$ . We have also introduced the assumption that both infinitesimal distances on *TM* and *M*<sub>4</sub> are identical, so that

$$d\tilde{s}^2 = g_{AB} dx^A(\zeta) dx^B(\zeta) = \tilde{g}_{\mu\nu} d\zeta^\mu d\zeta^\nu.$$
(15)

We realized the measure of  $d\tilde{s}^2$  is apparently precise without quantum nature.

In order to endow quantum nature to this measure, we urgently need to

- Express the metric tensor as an operator, especially considering that the 1-form could be an operator;
- Suggest noncommutative relations for these quantities;
- Integrate probability distributions and quantum superposition.

In this regard, we emphasize that neither the metric tensor nor the 1-form,  $dx^{\mu}$ , has noncommutative translations [22]. Alternatively, we might recall noncommutative metric tensor [23] and noncommutative differential calculus [24,25] to define a noncommutative line element [26]. This could be performed elsewhere.

To remain within the scope of the present script, we resume with the RGUP approach, which was introduced in Section 2. Here, we concretely aim at discretizing the eight-dimensional tangent bundle. For a test particle with mass *m* normalized to the Planck mass  $\bar{m} = m/m_p$ , the Finsler structure reads

$$F(\hat{x}^{\mu}, \bar{m}\dot{x}^{\nu}) = F(\hat{x}^{\mu}, \hat{p}^{\nu}), \quad \forall \bar{m} \in \mathbb{R}^{+},$$
(16)

where  $\hat{x}^{\mu} = \mathbf{x}^{\mu} = \hat{x}^{\mu}_{0} = (\hat{x}^{0}_{0}, \hat{x}^{i}_{0}) = (ct, \hat{x}^{i}_{0})$  and  $\hat{p}^{\nu} = -i\hbar\partial/\partial\hat{x}^{\nu} = \hat{p}^{\nu}_{0} = (\hat{p}^{0}_{0}, \hat{p}^{i}_{0}) = (E/c, \hat{p}^{i}_{0})$ . These are the typical definitions in ungravitized QM and most probably remain unchanged in quantized QM. On Finsler manifold with RGUP and the parameterization  $x^A = x^A(\zeta)$ , Equation (1) reads

$$g_{AB} = \frac{1}{2} \frac{\partial^2}{\partial \hat{p}_0^{\mu} \partial \hat{p}_0^{\nu}} F^2(\hat{x}_0^{\mu}, \hat{p}_0^{\nu}(1 + \beta \hat{p}_0^{\rho} \hat{p}_{0\rho}))$$
(17)

$$= \left(1 + \beta \hat{p}_0^{\rho} \hat{p}_{0\rho}\right) \frac{1}{2} \frac{\partial^2}{\partial \hat{p}_0^{\mu} \partial \hat{p}_0^{\nu}} F^2\left(\hat{x}_0^{\mu}, \hat{p}_0^{\nu}\right), \tag{18}$$

where  $\beta = \beta_0 G / (c^3 \hbar) = \beta_0 (\ell_p / \hbar)^2$  is the RGUP parameter, *G* is the gravitational constant, *c* is the speed of light,  $\hbar$  is the Planck constant, and  $\ell_p$  is the Planck length [8–11]. Equation (18) assumes that  $F(\hat{x}_0^{\mu}, \hat{p}_0^{\nu})$  is homogeneous of degree one in  $\hat{p}_0^{\mu}$  and  $(1 + \beta \hat{p}_0^{\rho} \hat{p}_{0\rho}) > 0$ . Both  $\hat{x}_0^{\alpha}$  and  $\hat{p}_0^{\beta}$  are also parameterized with  $\zeta$ .

If we limit the discussion on the Finsler structure of Riemann manifold, Equation (2), [27], we get

$$F(\hat{x}_{0}^{\mu}, \hat{p}_{0}^{\nu}) = \left[\frac{|\hat{p}_{0}^{\nu}|^{2} - |\hat{x}_{0}^{\mu}|^{2}|\hat{p}_{0}^{\nu}|^{2} + \left(\hat{x}_{0}^{\mu} \cdot \hat{p}_{0}^{\nu}\right)^{2}}{1 - |\hat{x}_{0}^{\mu}|^{2}}\right]^{1/2},$$
(19)

where RGUP suggests that  $\hat{p}_0^{\nu} = \hat{p}_0^{\nu}(1 + \beta \hat{p}_0^{\rho} \hat{p}_{0\rho}))$  [8,9]. Then, Equations (12) and (13) lead to

$$\tilde{g}_{\mu\nu} = \frac{1}{2} \frac{\partial^2}{\partial \hat{p}_0^{\mu} \partial \hat{p}_0^{\nu}} \left[ \frac{\sum_{\nu=0}^3 (\hat{p}_0^{\nu})^2 - \sum_{\mu=0}^3 (\hat{x}_0^{\mu})^2 \sum_{\nu=0}^3 (\hat{p}_0^{\nu})^2 + \left(\sum_{\mu|\nu=0}^3 \hat{x}_0^{\mu} \hat{p}_0^{\nu}\right)^2}{1 - \sum_{\mu=0}^3 (\hat{x}_0^{\mu})^2} \right] \\ \left[ \frac{d\hat{x}_0^{\mu}(\zeta^{\mu})}{d\zeta^{\mu}} \frac{d\hat{x}_0^{\nu}(\zeta^{\nu})}{d\zeta^{\nu}} + \left(1 + 2\beta \hat{p}_0^{\rho} \hat{p}_{0\rho}\right) \bar{m}^2 \frac{d\hat{x}_0^{\mu}(\zeta^{\mu})}{d\zeta^{\mu}} \frac{d\hat{x}_0^{\nu}(\zeta^{\nu})}{d\zeta^{\nu}} \right].$$
(20)

The quantized metric tensor, Equation (20), could be approximated as

$$\tilde{g}_{\mu\nu} \simeq \left[1 + \left(1 + 2\beta \hat{p}_0^{\rho} \hat{p}_{0\rho}\right) \bar{m}^2 \left(\frac{|\vec{x}|}{\mathcal{A}}\right)^2\right] g_{\mu\nu},\tag{21}$$

where A is the maximal proper acceleration [20,21,28,29].

Relative to Equation (13), Equation (20) refers to a full-quantized version of the fundamental tensor, which is obtained when RGUP is properly imposed on the Finster structure. Then, the first fundamental form reads

$$d\tilde{s}^2 = \left[1 + \left(1 + 2\beta \hat{p}_0^{\rho} \hat{p}_{0\rho}\right) \bar{m}^2 \left(\frac{|\ddot{x}|}{\mathcal{A}}\right)^2\right] g_{\mu\nu} d\hat{x}^{\mu} d\hat{x}^{\nu}.$$
 (22)

We conclude that finite  $|\ddot{x}|$  and  $\bar{m}$  are essential for the quantization of the fundamental tensor,  $\tilde{g}_{\mu\nu}$ , Equation (21), and first fundamental form,  $d\tilde{s}^2$ , Equation (22). In the relativistic regime, in which the approach of RGUP and, hence, the spacetime quantization are possible, an additional source of spacetime curvature emerges. This is the curvature associated with the mass  $\bar{m}$ , whose test particle's motion has acceleration  $|\ddot{x}|$ . Vanishing  $|\ddot{x}|$  and  $\bar{m}$  entirely restore the unquantized versions of the fundamental tensor,  $g_{\mu\nu}$ , and first fundamental form,  $ds^2$ .

As for the relativistic formulation of GUP [17–19], comments on Ref. [30] are now in order. This script studies the inconsistency in the original HUP approach with special relativity and characterizes the motion of a particle crossing the worldline. The resulting minimal measurable length is suggested to be  $1/2mc^2$ . Compared to Equation (5) this estimation does not seem to manifest various relativity principles; for example, that the coordinates in GR are fundamentally arbitrary.

Funding: This research received no external funding.

Institutional Review Board Statement: Not applicable.

Informed Consent Statement: Not applicable.

Data Availability Statement: All types of relevant data are included in the manuscript.

**Acknowledgments:** The author acknowledges the generous support of the Egyptian Center for Theoretical Physics (ECTP) and the World Laboratory for Cosmology And Particle Physics (WLCAPP) at the Future University in Egypt (FUE).

**Conflicts of Interest:** The author declares no conflict of interest regarding the publication of this paper and full compliance with ethical standards regarding the contents of the present paper! No data are associated with this paper.

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