vehicles

Correction

Correction: Feng et al. Enhancing Autonomous Driving Perception: A Practical Approach to Event-Based Object Detection in CARLA and ROS. *Vehicles* 2025, *7*, 53

Jingxiang Feng [1,†], Peiran Zhao [2,†], Haoran Zheng [3,4], Jessada Konpang [1,*], Adisorn Sirikham [1,*] and Phuri Kalnaowakul [1]

[1] Faculty of Engineering, Rajamangala University of Technology Krungthep, Bangkok 10120, Thailand; 659041610083@mail.rmutk.ac.th (J.F.); phuri.k@mail.rmutk.ac.th (P.K.)
[2] Department of Electrical, Computer, and Software Engineering, University of Auckland, Auckland 1010, New Zealand; pzha418@auckland.ac.nz
[3] Department of Chemical & Materials Engineering, University of Auckland, Auckland 1010, New Zealand; hzhe810@aucklanduni.ac.nz
[4] School of Intelligent Vehicles, Guangzhou Panyu Polytechnic, Guangzhou 511483, China
* Correspondence: jessada.k@mail.rmutk.ac.th (J.K.); adisorn.s@mail.rmutk.ac.th (A.S.)
† These authors contributed equally to this work.

Removal of Affiliation

In the published publication [1], there was an error regarding the affiliation for Jingxiang Feng. The author was previously listed with two affiliations. Affiliation 2 has been removed, and only Affiliation 1 should be retained as follows: Faculty of Engineering, Rajamangala University of Technology Krungthep, Bangkok 10120, Thailand. The authors state that the scientific conclusions are unaffected. This correction was approved by the Academic Editor. The original publication has also been updated.

Reference

1. Feng, J.; Zhao, P.; Zheng, H.; Konpang, J.; Sirikham, A.; Kalnaowakul, P. Enhancing Autonomous Driving Perception: A Practical Approach to Event-Based Object Detection in CARLA and ROS. *Vehicles* **2025**, *7*, 53. [CrossRef]

Disclaimer/Publisher's Note: The statements, opinions and data contained in all publications are solely those of the individual author(s) and contributor(s) and not of MDPI and/or the editor(s). MDPI and/or the editor(s) disclaim responsibility for any injury to people or property resulting from any ideas, methods, instructions or products referred to in the content.

Received: 17 June 2025
Accepted: 21 July 2025
Published: 28 July 2025

Citation: Feng, J.; Zhao, P.; Zheng, H.; Konpang, J.; Sirikham, A.; Kalnaowakul, P. Correction: Feng et al. Enhancing Autonomous Driving Perception: A Practical Approach to Event-Based Object Detection in CARLA and ROS. *Vehicles* 2025, *7*, 53. *Vehicles* **2025**, *7*, 78. https://doi.org/10.3390/vehicles7030078

Copyright: © 2025 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https://creativecommons.org/licenses/by/4.0/).