

Review



# **Experimental and Numerical Analysis of Formation and Flame Precession of Fire Whirls: A Review**

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**Abstract:** Fire whirls are a particular case of flame behaviour characterized by a rotating column of fire driven by intense convective heating of air close to the ground. They typically result in a substantial increase in burning rate, temperature, and flame height. Fire whirls can occur in any intense flame environment, including urban areas, particularly within combustible structures, and in wildland or forest fires. Recently, investigations on the creation of fire whirls have attracted much attention. However, most analyses are focused on fire whirl structure, formation, and controlling their unique state. In effect, revisiting the available experimental techniques and numerical simulations used in analyzing fire whirls has received less attention. In this paper, experimental arrangements including empirical set ups and employed fuels are presented in detail. Subsequently, major research progress focused on experimental studies and their laboratory setup is fully discussed, followed by the available numerical simulations, including combustion and turbulence models. Applied methodologies and chosen software in the recent numerical studies are also reviewed exclusively. Finally, the latest findings are featured, and prospective pathways are advised.

Keywords: fire whirls; burning rates; simulation methods; turbulence and combustion model

# 1. Introduction

A fire whirl is a unique concentrated vortex driven by and consisting primarily of combustion processes and products [1]. Fire whirls are rare but can be catastrophic and are formed in instances where intense flames produce significant vertical convective currents in the presence of a local rotation of the surrounding air near the fire base [2]. The most prominent fire whirl event occurred in Japan during the Kanto earthquake of 1923 [3]. In this incident, the fire whirl reached one hundred meters in height and caused the death of about 38,000 people. Scientists and researchers in Canberra reported that they have observed the first instance of a fire tornado from the investigation of the evidence gathered from the January 2003 Canberra fires. Approximately 70 percent of the Australian Capital Territory's nature park, pine plantations, and pastures were seriously destroyed, and most of the Mount Stromlo Observatory was damaged [4]. Because fire whirls produce a strong intensification of combustion and the risks they pose during large wildland fires, the necessity of studying this phenomenon is obvious. In this regard, many different studies have been conducted to explore the behavior of fire whirls from different extents. However, the need to review governing equations, up-to-date proposed models, and solution methods for fire whirls is essential. This paper is aimed to review the available simulation methods and discusses the capability and competency of such methods. First, a summary of the fundamentals, classification, and formation mechanism of fire whirls is given. Then, the experimental arrangements and numerical simulation techniques,



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**Copyright:** © 2021 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). including combustion and turbulence models, are presented. The review finally classifies the research that are conducted thus far based on their simulation methods and techniques to examine the behaviour of fire whirls.

# 2. Fire Whirl Phenomenon

# 2.1. Definition, Classification, and Formation Mechanism

Fire whirls are a type of standing vortex stimulated under specific air entrainment conditions, where circular movement is developed by the arriving flow and forms a flame rotation near its center core [5]. Fire whirls are not exclusively formed of fire, as several fire whirls have been observed which consist of hot gases formed downwind of fires (Figure 1a) [6]. Fire whirls are formed due to the interplay between fire fuels, with distinctive impacts including cross stream and vortex breakdown. Some of them are created from multiple fires with no wind. There are three main processes involved in the structure of fire whirls: (1) an eddy production process (vorticity), (2) a surface drag force to produce a radial boundary layer, and (3) a thermally driven fluid sink [2]. It is possible to have intensive eddies including shear forces and fluid sinks at the base coalesce within fires [7,8]. The scorching gases produced by the fire act as a fluid sink, pulling the surrounding air with an angular motion from the eddy vorticities to the core of the flame [9]. The rotation in the air that gathers up into the fire whirl can come from various sources, including wind dragging along the ground (see Figure 1c,d). The burning gases in the fire plume heats up the air so that it accelerates upward, stretching and consolidating the fire whirl into long, thin tubes (See Figure 1b). Fire whirls are well-categorized and can be separated into three major types [10].

Type 1. Stationary, on-source (formed directly over the fuel source), and reacting [11]. (Reacting fire whirls consist primarily of combusting materials, while non-reacting whirls consist of non-combusting materials and gases).

Type 2. Unsteady, on-source, and reacting with periodic shedding. Formed when a line fire is subject to angled crosswinds.

Type 3. Off-source and can be reacting or non-reacting.

Figure 1. Cont.







(b)



**Figure 1.** (a): Fire whirls in Australia 2012, photo courtesy of Chris Tangey; (b) Fire whirls from a 3-meter diameter pool in the Fire Laboratory for Accreditation of Modeling by Experiment, or FLAME, facility at Sandia National Laboratories; (c) The process of forming rotating columns of flame; (d) The laboratory fire whirl. Credit: Bryan Christie Design [12].

When the rotating vortex column is created right over the fuel source, the fire whirl is identified as "on source", and once it moves away or is offset to the fuel surface, it is identified as "off source" [13]. The formation of a fire whirl begins with a ground fire producing a convective updraft of hot gases, including air and combustion products. This produces a low-pressure area just above the flame that pulls in ambient air. In the event of a crosswind or rotating wind, the vorticity of the column of combustion gases is increased as the lateral momentum of the wind is converted to angular momentum centered at the low-pressure zone. In fire whirls, this effect is intensified by means of vortex dragging due to the strain field formed by the rising air [14,15]. The combination of effects creates a concentrated vertical vortex core characteristic of a fire whirl (as shown in Figure 1c).

(**d**)

## 2.2. Source of Vorticity

(c)

There are various potential sources of ambient vorticity that can cause fire whirls to form. One key source is the shear layer, which develops when ambient wind flows over the ground, creating horizontally leaning vorticity. This horizontal vorticity can then be rearranged, or tilted, by the fire's buoyant flow and turned to the vertical axis, becoming a key contributor to various fire whirls. Equally, it is expected that the inflow generated by a buoyant plume forms a shear layer closer to the ground, which also creates horizontal vorticities. These horizontal vorticities can be tilted or reoriented to the vertical (Horizontal vectors change direction to vertical vectors) (Figure 2). This source of vorticity could be present even in no wind situations. Complex topography (Wildland–urban interface (WUI) with manmade structures) can also form vorticity through phenomena such as channeling, a shear of ambient and fire-induced winds [16]. Other sources of vorticity are shown in Figures 3 and 4 , including fire whirls that form inside the bend of an L-shaped heat source in crossflow [17] (Figure 2a) and fire whirl that occur due to the interaction of multiple fire plumes with no crossflow wind (Figure 2b).



**Figure 2.** (a) Schematic of fire whirl formation for an L-shaped heat source in a crossflow wind. View is from above [17]. (b) Schematic showing one configuration that can cause a multiple interacting plume type fire whirl [17].



Figure 3. Fixed frames used in construction of fire whirls. (a) L-shaped covers; (b) cylinder halves.

Numerous observations of fluid dynamics phenomena happening in large-scale pool fires, particularly fire in the existence of wind, have been described by Tieszen et al. [18], who asserted that baroclinic vortex generation is especially prominent for large-scale pool fires. The misalignment of the pressure gradient from the density gradient is referred to as the baroclinicity at a point. Typically, the gradients of density and pressure act on the same axis, but the conditions close to a fire sometimes result in warm air rising due to surrounding cold air, producing two disparate local strata. Air above the fire extends and lines of constant density (called isopycnals) are formed. The colder surrounding air has a greater density compared to the fire area, tilting the isopycnals towards the fire area. The tilting of isopycnals and isobars in the contrary axis is a baroclinic resource of vorticity, as both gradients influence the fluid. These produce forces acting in different axes, resulting in a rotation and leading to the generation of baroclinic vorticity. Fire whirls can form from relatively small fires under suitable wind or topographic conditions such as at the WUI with artificial structures. Laboratory-scale tests have illustrated that an approximately stationary pool fire might produce a fire whirl, resulting in a much larger burning rate and temperature compared to the primary fire [19–21]. This transient occurs in the model as the fire is tilted to one side first, commences to spin, and afterwards pulls upward prior to forming a fire whirl. The flame heights from pool fires and fire whirls can vary from centimeters to kilometers [22].

#### 3. Experimental Arrangements (Experimental Setup, Fuels, and Burning Behavior)

The modeling tests of fire whirl are conducted based on a burner-type laboratory fire whirl. The tests are performed by a mechanism including a support flame, a burner, a bed, and a mechanical wind wall. Both the pool fire and burner might be applied to produce buoyancy [23,24]. The whirls can be formed using the constant frame technique. Some constant-frame-type whirl generators consist of a pair of L-shaped covers (see Figure 3a) [2]. The covers are set to produce a swirling stream by means of entrained air. In addition, the whirls can be created using the constant frame technique, that is, cylinder halves symmetrically staggered around a burner which is flush to a basis sheet to produce the background vorticity (see Figure 3b) [25].

In the constant frame technique, the fire strength can either alter or be constant. In fact, the chosen geometry specifies the swirl strength. Moreover, both the fire strength and the imposed circulation can be determined. In all conditions, the thermal release rate is controlled by regulating the fuel mass flow rate [26].

To analyze fire whirls in the laboratory, several types of fuels are employed. Liquid, solid, and gas fuels can be utilized to analyze the behavior of fire whirl, each with their own advantages and disadvantages. Test fuels may either be fed into the system during the test or located at the container's center for a certain burning period. Solid fuels must be set in place prior to ignition, while gas fuels must be fed in. Liquid fuels can utilize either method. Chauh et al. [27] employed a fuel pan for inclined fire whirl tests using methanol, two-propanol, and ethanol as fuel. Aluminum slits were used in some tests to keep the fuel surface coplanar to the surrounding surface.

In the context of burning behavior, some small-scale empirical analyses were conducted to find correlations between the flame length, burning rate, and the fuel type used. Semi-experimental simulations coupling the rates of burning with the ambient circulation and the pool size for turbulent and laminar fire whirls including liquid fuels were presented by Lei et al. [28]. The authors asserted that the growth of the burning rate in this phenomenon is due to the increased convective mass and heat transfer in the inflow boundary layer above the surface of the liquid fuel. An empirical analysis to investigate the burning rate of various fuels in fire whirls and pool fires was conducted by Hariharan [29]. Experiments were done using two types of fuel, Alaska North Slope crude oil and nheptane. The authors used pool fire. A constant-frame, four-wall configuration was used to produce the fire whirls. The four walls were positioned to form a container, and the fuel pool was located at the container's centre on the bottom face. This setup allows the natural entrainment of air to the fire via the four gaps, forming an on-source, quasi-steady fire whirl. To produce a pool fire, the walls were picked up to allow radially symmetric air entrainment to the fire. A circulate dish formed of aluminium was applied to include the fuel pool. The dish was applied to keep a water sublayer upper which the fuel slick floated, mimicking open-water conditions at the laboratory scale. The resulting flames are shown in Figures 4 and 5. For tests with heptane fuel (see Figure 4), the total mass loss was equal to both fire whirls and pool fires, as no residue remained behind following extinction. The mass loss can be considered linear for heptane fire because the rate of mass change is constant over time; however, the rate decreases over time for Alaska North Slope fires (see Figure 5).

The rate of burning of the pool fire regime was lower than the fire whirl regime for all considered conditions. For both ANS crude oil and heptane, the pool fire regime consumes fuel at a rate almost half of the corresponding fire whirls. There was residue following extinction of the ANS crude oil fires.



Figure 4. Instances of pool fire (A–D) and fire whirls (panels E–H) constituted by heptane [29].



Figure 5. Instances of pool fire (A–C) and fire whirls (panels D–F) constituted applying ANS crude oil [29].

# 4. Numerical Simulations of Fire Whirls (Turbulence Simulations, Combustion Models, Heat Transfer)

# 4.1. Governing Equations of Computational Fluid Dynamics for Fire Whirls

The general equations for fire whirls are derived by considering the compressible, reactive, time-dependent Navier–Stokes equations with source terms  $\dot{\omega}_i$ ,  $\dot{q}$ , and an added scalar  $Y_i$  expressing the rate of species production, the rate of energy release, and the mass fraction for species *i*, respectively.

$$\frac{\partial \rho}{\partial t} = -\nabla .(\rho V) \tag{1}$$

$$\frac{\partial(\rho V)}{\partial t} = -V\nabla .(\rho V) - \nabla P + \rho g - \nabla .\hat{\tau}$$
<sup>(2)</sup>

$$\frac{\partial E}{\partial t} = -\nabla .((E+P)V) - \nabla .(V.\hat{\tau}) - \nabla .(K\nabla T) + \dot{q}$$
(3)

$$\frac{\partial(\rho Y_i)}{\partial t} = -\nabla .(\rho Y_i V) + \nabla .(\rho D \nabla Y_i) + \dot{w}_i \tag{4}$$

$$\hat{\tau} = \rho v \left(\frac{2}{3} (\nabla V) I - (\nabla V) - (\nabla V)^t\right)$$
(5)

where, *I*, *K*, *T*, *V*, *E*, *P*,  $\rho$ , *D*, and *t* are the identity matrix, heat conductivity, temperature, velocity vector, total energy, pressure, density, mass diffusivity, and time, respectively (the nomenclature is also presented in Nomenclature). It is assumed that the fluid is Newtonian, giving the stress tensor  $\hat{\tau}$ , as illustrated in Equation (5).  $\nu$  is the kinematic viscosity [30,31] Most fluid flows in engineering and nature, such as fire whirls, are of a turbulent nature. In fluid dynamics, turbulence is determined by chaotic variations in flow velocity and pressure. Turbulence can be seen in the Navier–Stokes equations governing fluid dynamics, where the presence of non-linear terms leads to highly complex behaviour. Highly dissipative and diffusive properties are the two major factors of turbulent flows, resulting in a significant degree of mass and heat transfer in a turbulent fluid. Turbulent behaviour can be modelled using a variety of methods utilizing correction factors, alternate forms of the equations, and other correlations or sub-models to obtain a system of equations/correlations. These processes have been developed to reduce the typically prohibitive computational cost of performing fluid dynamics simulations. These models include important physical variables including velocity, fluid density, kinematic viscosity, and pressure.

# 4.2. Turbulence Simulations

Modern techniques, enabled by the improvement of computational resources, allow for the efficient simulation of fluid flow and allow certain fluid properties to be investigated when a physical experiment may be impractical, especially in turbulent streams. Four broad modelling categories have emerged as the most popular methods with which to simulate turbulent flows. These models are: Direct Numerical Simulation (DNS), large eddy simulation (LES), and Reynolds Stress Transport (RST). While a variety of other techniques exist, those listed above have proven to be the most useful and applicable and are the most popular methods to use in simulating fire whirls [30,32].

## 4.2.1. Direct Numerical Simulation (DNS)

Direct numerical simulation (DNS) is the process of calculating the direct solution of the unsteady Navier–Stokes equations. DNS is capable of resolving even the smallest eddies and time scales of turbulence within a flow. When the Reynolds number (Re) grows, the range of the eddy scales will become greater, and the requirement for more precise grids is necessary to resolve all the behavior in the flow area, particularly at the smallest scales. The characteristic length at which a turbulent eddy is dissipated into molecular friction is given according to the fluid viscosity and dissipation as follows [33–37]:

$$\eta = \left(\frac{v^3}{\varepsilon_d}\right)^{\frac{1}{4}} \tag{6}$$

where v is the viscosity and  $\varepsilon_d$  is the dissipation rate. One of the major challenges of this modeling technique is the nearly impossible or difficult implementation of direct numerical simulations in complicated geometries. The requirement to apply exact numerical techniques are usually incompatible with their implementation in complicated geometries. DNS simulation is barely applied, as the computations are very expensive in terms of calculating resources for turbulence streams. The Navier–Stokes correlations should be resolved on adequately fine spatial meshes with adequately small time steps in this method.

## 4.2.2. Large Eddy Simulation (LES)

In the fluid stream, large scales (or eddies) are the major transporters of energy and momentum. In LES, the larger turbulent eddies are resolved and the impact of small eddies on the mainstream is simulated using a sub-grid scale (SGS) model [38-41]. LES benefits from a decomposition of the Navier–Stokes equations. Instead of separating the flow behaviour into mean and fluctuating behaviours, however, the LES method uses a filtering procedure so that the smallest scale eddies in the flow are not resolved explicitly and are instead described by an SGS model. The process of LES, in dealing with detached eddies in turbulent streams, allows it to produce good agreement with DNS at a lower computational cost compared to DNS. The simulation of the unresolved small scales is the main area of development in LES turbulence simulations and was first introduced by Smagorinsky [42]. Other SGS models have been presented, such as the wall-adapting local eddy-viscosity (WALE) model, the Smagorinsky simulation (SM), the Standard oneequation model (OM), the standard dynamic Smagorinsky model (DSM), the one-equation Vreman model (OVM), and the one-equation dynamic model (ODM). The major target of such models is preparing an efficient simulation to deal with the unresolved eddies in the turbulent stream. LES can be separated into three different classifications in relation to sub-grid scale (SGS) simulation, called the eddy-viscosity simulation, the mixed model, and the similarity model. Eddy-viscosity simulations are more well-known compared to the others. This model has its basis in the Boussinesq assumption [43] that links the turbulent and molecular transports to a turbulent or eddy-viscosity (it is an artificial viscosity) model. The SGS stress tensor in 1D can be written as:

$$\tau = -2v_{SGS}E + \sigma \tag{7}$$

where *E* is strain tensor, and  $\sigma$  is normal stress. Each *SGS* simulation expresses a particular formulation for sub-grid scale eddy-viscosity, presented in Table 1.

#### 4.2.3. Reynolds Stress Transport Model (RST)

In the RST model, the equations are solved along with separate correlations for each independent part of the Reynolds stress tensor and a transport equation for the scalar rate of turbulent kinetic energy dissipation. In these models the eddy-viscosity hypothesis is ignored, and the Reynolds stress tensor components are calculated directly. Such models apply the equations of the Reynolds stress transport for the formulation. They consider the directional impacts of the complicated interplays in turbulent flows and the Reynolds stresses. Reynolds stress simulations present much better accuracy compared to eddy-viscosity based turbulence simulations, in addition to being inexpensive in terms of computation compared to DNS and LES.

For the specific Reynolds stress tensor in the RST simulation,  $R = \frac{-q_f}{\rho}$  is introduced as below ( $q_f$  is the vector of the turbulent thermal flux) [33]:

$$\frac{\partial}{\partial t}(\rho R) + \nabla (\rho R V) = \nabla D - \frac{2}{3}\rho I \chi_M + \phi + \varepsilon_d + \dots$$
(8)

Here, the Dilation Dissipation is  $\chi_M$ , the tensor of the turbulent dissipation rate is  $\varepsilon_d$ , and other specific resources are "...". D (the generalized gradient diffusion) was applied for the turbulent thermal flux vector.

Smagorinsky Model (SM) [42]	$\begin{split} \nu_{SGS} &= \left(C_s\overline{\Delta}\right)^2  \varepsilon , \\  \varepsilon  &= \sqrt{2\varepsilon_{ij}\varepsilon_{ij}} \\ (0.5 \prec C_s \prec 0.22) \end{split}$	$\overline{\Delta}$ is the filter width (size of mesh spacing), $\varepsilon$ is the resolved strain-rate tensor
Dynamic Smagorinsky Model (DSM) [44] Based on Lilly's Idea [45]	$\nu_{SGS} = (C_s \overline{\Delta})^2  \varepsilon , \ (C_s)^2 = \frac{L_{ij} M_{ij}}{M_{ij} M_{ij}}$ $M_{ij} = 2\overline{\Delta}^2 ( \widetilde{\varepsilon} \widetilde{\varepsilon}_{ij} - \alpha^4 \eta^2  \widetilde{\varepsilon} \widetilde{\varepsilon}_{ij})$ mostly $\alpha = 2, \ \eta = 1$	The stress <i>Lij</i> can be expressed as the stress related to the smallest solved scales between the grid–filter scale $(\overline{\Delta})$ and test–filter scale $(\Delta')\Delta' = \omega\overline{\Delta}$ .
Wall-Adapting Local Eddy-Viscosity (WALE) Model [46]	$\nu_{SGS} = (C_w \overline{\Delta})^2 \frac{(\epsilon^d_{ij} \epsilon^d_{ij})^{\frac{3}{2}}}{(\epsilon^s_{ij} \epsilon^s_{ij})^{\frac{5}{2}} + (\epsilon^d_{ij} \epsilon^d_{ij})^{\frac{5}{4}}}$ $\epsilon^d_{ij} = \frac{1}{2} (v_{gik} v_{gkj} + v_{gjk} v_{gki}) - \frac{1}{3} \delta_{ij} (v_{gkk})^2$ $\epsilon^s_{ij} = \frac{1}{2} (\frac{\partial v_i}{\partial u_j} + \frac{\partial v_j}{\partial u_i})$ $0.55 \le C_w \le 0.6$	Here, $v_g$ is the tensor of the velocity gradient. Cs and Cw can take different values depending on the nature of the flow, and $\delta_{ij}$ is Kronecker Delta function
Vreman Model [47]	$egin{aligned} & u_{SGS} = C_V \sqrt{rac{eta}{ar{lpha}_{ij}ar{lpha}_{ij}}  arepsilon  \ \ \overline{lpha}_{ij} = rac{\partial V_j}{\partial x_i} \ & eta_{ij} = \overline{\Delta}^2 lpha_{mi} lpha_{mj}, \  arepsilon  = \sqrt{2arepsilon_{ij}arepsilon_{ij}} \end{aligned}$	$\overline{\Delta}$ is the filter width (size of mesh spacing), and $C_v = 2.5C_s$ , Cs can take different values depending on the nature of the flow
Standard One-Equation Model (OM) [48]	$\nu_{sgs} = C_{\nu}\overline{\Delta}_{\nu}\sqrt{k_{sgs}}, k_{sgs} = (\overline{V_i}\overline{V_i} - \overline{V}_i\overline{V}_i)/2 = \tau_{ii}/2$ $\Delta_{\nu} = \frac{\overline{\Delta}}{1 + C_k\overline{\Delta}^2\epsilon^2/k_{sgs'}}$	$v_{sgs}$ is the SGS viscosity, $Cv$ is a constant and always taken to be $0.1, C_k = 0.08, \varepsilon$ , and $\overline{\Delta}$ are defined in previous models.

Table 1. Displays each SGS model's formulation for sub-grid scale eddy-viscosity.

# 4.3. Combustion Models

The chemical reactions influence turbulence by a change in density due to thermal energy release and changes in density impact the rate of chemical reaction. In turbulent streams, the rate of chemical reaction is specified by two factors: (1) molecular-level mixing and (2) mixing because of the collision between randomly travelling turbulent eddies. Turbulence increases both the mass and heat transfer in a fluid and grows the rate of time-mean reaction by strengthening the mixing among combustion products and disparate reactants. Turbulence leads to the oscillation of temperature and species, which grows the rate of the time-mean reaction. To model turbulent combustion, the main challenge is that the rate of reaction in terms of mean variables is not the same as the time-mean amount of the reaction rate.

#### 4.3.1. Eddy Break-Up (EBU) Model

Because of the simplicity of the Eddy Break-Up (EBU) model first presented by Spalding [49] and then revised by Magnussen and Hjertager [50], EBU simulations became a popular method in combustion modelling. This model uses the assumption that when turbulence mixing is included, the rate of reaction is primarily reliant on the presence of turbulent eddies. The outcomes of reference [51] showed the potential of applying RST method to contribute in better understanding of fundamental knowledge of the driving system and the physical response of the fire whirls. Many researchers have found that the EBU model is appropriate for the estimation of higher temperature air combustion efficiency; however, there is some disagreement between numerical results and laboratory observations due to some uncertainties and simplifications performed in numerical analyses. Su et al. [52] presented a modified EBU model to address this issue. Based on empirical case studies, the average thermal release rate was predicted by the fuel combustion rate;

however, the power curve is not presented. As the chemical reactions in most models are very quick, the combustion rate can be specified by the intermixing rate on a molecular scale of oxygen and fuel eddies. The individual species are transferred at various rates based on their equations. The time mean of the instantaneous equation is presented as below [31,33,50]:

$$\frac{\partial}{\partial t}(\rho \overline{Y}) + \nabla .(\rho u \overline{Y}) = \nabla ((\frac{k}{C_p} + \frac{\nu_t}{\Pr_t})\nabla \overline{Y})$$
(9)

where *k* is the laminar thermal conductivity of the combination, and  $C_p$  is the specific heat capacity of the mixture. The mixing rate is presented in terms of the turbulence time scale  $(\frac{\zeta}{k})$ . The individual rates of dissipation for combustion products, oxygen and fuel are presented as below:

$$\dot{w}_{fu} = C_r \rho Y_{fu} \frac{\zeta}{k}$$

$$\dot{w}_{ox} = C_r \rho \frac{Y_{ox}}{s} \frac{\zeta}{k}$$

$$\dot{w}_{pr} = C_r \rho \frac{Y_{pr}}{1+s} \frac{\zeta}{k}$$
(10)

Here, the stoichiometric factor is *s*, and the component mass is *Y*. The EBU model considers the individual wastage rates for the actual rate of the fuel and applies the slowest of [33].

$$R_f = -\rho \frac{\zeta}{k} \min[C_r Y_{fu}, C_r \frac{Y_{ox}}{s}, C_r \frac{Y_{pr}}{1+s}]$$
(11)

#### 4.3.2. Mixture Fraction Combustion Model Based on the EDC

Most extensively applied ways for turbulence–chemistry interactions are a conserved variable way. In this method, a transport equation for the conserved variable including mixture fraction is resolved. This fraction presents the mixedness of the oxidizer and the fuel. Turbulence and local equivalence ratio are presented by the mixture fraction variance, the scalar dissipation rate, and the filtered mixture fraction. With a flamelet equation solved in the mixture fraction space, the chemical kineticity is coupled [53].

#### 4.3.3. Gas-phase Combustion Model

In the model of Gas-phase combustion, the chemical kinetics are expressed as a onestage reaction wherein fuel reacts with the ambient oxygen, nitrogen, carbon dioxide, soot, and water vapour. The value of species produced is specified based on the value of gasphase fuel and the oxygen content at the grid control volume. The gas-phase fuel volatiles emission is controlled by the liquid fuel evaporation. The value of heat generation through combustion is specified by summation of the species mass fraction, which multiplies its formation heat [54].

### 4.4. Modeling of Soot Formation and Combustion

In combustion phenomena, the generation of soot particles is very complicated, affected by many terms such as the pressure, the temperature, and the chemical composition of gas in the constituted soot particle pathway. As a result, the flow field has an important role. Syed et al. [55] considered a semi-experimental soot model. The main term applied to specify soot constitutive equations is soot mass function ( $\gamma_{soot}$ ):

$$\frac{\partial}{\partial t}(\rho\gamma_{soot}) + \frac{\partial}{\partial x}(\rho u\gamma_{soot}) = \frac{\partial}{\partial x}(\frac{\nu_t}{\Pr_{soot}}\frac{\partial\gamma_{soot}}{\partial x}) + \frac{dM}{dt}$$
(12)

The turbulence Pr number for soot transfer (equal to 0.4) is  $Pr_{soot}$ , and M is the soot mass concentration that is computed using the balance of combustion and soot formation. The radiation heat transfer and soot formation are coupled by the highly nonlinear reliance of these processes on temperature. The significance of coupling of soot kinetics and radia-

tion in sooting flames has been analyzed and shown in numerous references: According to the study of Wang and Niioka [56], it is expected that radiation attraction should be observed in the prediction of soot formation in diffusion flames at low stretch. The outcomes of the investigation done by Liu et al. [57] stated that in a moderately sooting diffusion flame, the soot radiation is significant in terms of the soot volume fraction and the visible flame height. In a numerical analysis done on ethylene diffusion flames, Liu et al. [58] developed a CFD code which combines both radiative transfer simulations and simplified soot chemistry. They showed that the accurate chemical and physical procedures related to the modified soot rates are not completely found and there is no guarantee that the simulation can be precise in other configurations. Modeling the impact of radiation on soot formation is very complicated because it influences the soot kinetic rate linked to the soot precursors.

### 4.5. Heat Transfer of Liquid Fuel in Fire Whirl Tests

#### 4.5.1. One-Dimensional Heat Conduction Equation

The liquid fuel temperature T(x, t), where X is the axis pointing into the depth of the fuel, is solved using 1D thermal conduction equation [31,59,60]:

$$\rho C_p \frac{\partial T}{\partial t} = \frac{\partial}{\partial x} [k \frac{\partial T}{\partial x}] + \dot{q}_{chem} + \dot{q}_{rad}$$
(13)

Here, *k* and  $C_p$  are the heat conductivity and specific heat of liquid fuel, respectively. The parameters  $\dot{q}_{rad}$  and  $\dot{q}_{chem}$  are the thermal rates associated with radiation absorption and chemical reactions, respectively. The boundary condition at the surface of the liquid fuel is [61–63]:

$$-k\frac{\partial T(0,t)}{\partial x} = \dot{q}''_{conv} + \dot{q}''_{rad}$$
(14)

Here,  $q''_{conv}$  is the convective thermal flux at the surface of the liquid fuel. It is assumed that the radiation incident rays  $q''_{rad}$  penetrate the fuel and therefore do not act on the surface of the liquid fuel. This term is therefore assumed to be zero on the boundary. It should be said that the liquid fuel modeling in some computational codes such as the Fire Dynamics Simulator [54] does not have moving interface properties. The depth of the pool fire therefore cannot be directly simulated and must be accounted for using other methods.

# 4.5.2. Radiation Heat Transfer

In Equation (13), the source parameter owing to radiation heat transfer from the fire to the liquid fuel can be estimated by the "two flux" simulation according to Schuster-Schwarzschild estimation [64]. It is considered that the strength of the radiative flux is fixed for the "back" and "front" of the hemispheres. The radiation parameter is computed by the sum of "backward" and "forward" incoming flux gradients, which are presented as follows [65]:

$$\dot{q}_{rad} = \frac{d^+_{rad}(x)}{dx} + \frac{d\bar{q}_{rad}(x)}{dx}$$
(15)

The existence of soot particles can highly influence radiative features such as the medium's absorption coefficient. This coefficient is used by the soot simulations to specify the impact of soot on radiative heat transfer. In most analyses, the summation of absorption factor of soot and gas is employed as the medium's effective absorption factor. This factor because of soot particles is computed as a function of soot concentration. The following correlation for the interaction of soot radiation was used by AshokeDe [66]:

$$\nabla(\nabla G\Gamma_{\lambda}) = \alpha_{\lambda}G_{\lambda} + S_{G\lambda} - 4\alpha_{\lambda}n^{2}\sigma T^{4}$$
(16)

In Equation (16), the left side is the radiative thermal flux gradient, and the right side represents the radiative heat source which is added to the equation of energy. In this correlation,  $S_{G\lambda}$  is the user-defined parameter which replaces the energy equation to

calculate the thermal sources because of radiation, and *n* expresses the refractive index of the medium.  $\alpha_{\lambda}$  is the effective absorption factor which accounts for the combination of an absorbing gas and soot that is introduced by Equation (17):

$$\alpha_{\lambda} = \alpha_{Absorbing-Gas} + \alpha_{soot} \tag{17}$$

The impact of soot particulates on radiative heat transfer is considered using a mean gray soot absorption factor that is expressed by Equation (18):

$$\alpha_{soot} = b_1 \rho \gamma_{soot} (1 - b_2 (T - 2000)) \tag{18}$$

Here,  $\gamma_{soot}$  and  $\rho$  are the soot mass fraction and the soot density, respectively. Using the Taylor–Foster estimation,  $b_1$  and  $b_2$  are obtained. In Equation (17), using the Weighted-Sum-of-Gray-Gases (WSSG) simulation,  $\alpha_{Absorbing-Gas}$  is calculated [67,68].

# 4.5.3. Convective Heat Transfer

The convective thermal flux parameter in Equation (14) is needed for the expression of typical thermal feedback from the fire resource to the liquid fuel surface. In large eddy simulations, this parameter can be assessed by the heat transfer factor  $H_c$  and the temperature difference at the grid control volume and the fuel surface. The heat transfer factor is considered as the maximum of the forced or natural convection correlations presented by the following [68]:

$$H_c = \max(C_{conv-n} \left| T_g - T_f \right|^{\frac{1}{3}}, \frac{kNu}{L})$$
(19)

Here, Nu = hl/k is the Nusselt number, and  $C_{cony-n}$  is the natural convection factor describing an experimental value relying on the model shapes.  $T_g$  is the temperature of grid control volume, and  $T_f$  is the fuel surface temperature.

## 4.5.4. Evaporation of Liquid Fuels

The simulation of liquid fuel utilizes a discontinuous phase transition model between two phases of a single constituent [1]. The liquid fuel evaporation rate, as a result of burning, is associated with the liquid temperature and the fuel vapor concentration above the pool surface. The volume fraction of the fuel vapor above the fuel surface can be computed as a function of the liquid fuel boiling temperature, which can be presented as follows:

$$V_{fuel,surf} = \exp[-\frac{h_v w_{fuel}}{R} (\frac{1}{T_l} - \frac{1}{T_b})]$$
(20)

Here, the liquid fuel heat of vaporization is  $h_v$ , the fuel gas molecular weight is  $w_{fuel}$ , and the fuel boiling temperature is  $T_b$ . The rate of the liquid fuel evaporation is defined as [1]:

$$m''_{evap} = \frac{ShD_{l,g}}{L} \frac{PW_{fuel}}{RT_g} \ln[\frac{V_{fuel,grid} - 1}{V_{fuel,surf} - 1}]$$
(21)

Here, the Sherwood number is Sh ( $Sh \approx 0.04Sc^{\frac{1}{3}}Re^{\frac{5}{5}}$ ), Sc is the Schmidt number for the fuel gas, and Re is the Reynolds number, which is obtained as  $Re = \frac{uL}{v}$ .

# 5. Review of Experimental Studies and Numerical Simulations on Fire Whirls including the Considered Models

Numerous empirical research works have been published on burner and small-scale pool fire whirls and gaseous fuel fire whirls employing a split cylinder and constant-frame apparatus to analyze the tangential and axial velocity profiles, the radial and axial distribution of temperature, the rates of burning, and the flame heights. The empirical facilities are usually categorized into two types depending on if the circulation is produced by entrained air streams entering the facility tangentially from spiraling gases or is imposed by a mechanically driven rotating screen [69–74]. The details of some presented simulation endeavors to-date and the fire whirl behaviour they attempted to capture are expressed in Table 2.

Table 2. Experimental studies discussed fire whirls and presenting their considered models.





Table 2. Cont.

A fire whirl generator including a vertical channel with a quadrangular part with two faces constituted of steel plate and tempered glass was regarded. There was a sheet which was covered by ceramic tiles to protect the fuel enclosure. The generator was located in the great hall of Forest Fire Reseach Laboratory.



A wind tunnel was applied to produce a cross stream of velocity U, and a blocking board was located to cover the wind-tunnel exit and control its opening height (h).



Tests were done in an open blowdown wind tunnel. The experiment section consisted of a flat floor, heat-resistant glass. The burner exit was a porous rectangular sheet built of sintered stainless-steel particles. However, significant studies have been conducted to better examine the behavior and mechanisms of fire whirl production in empirical research works. It is hard to obtain outcomes that match the various analyses under the same conditions, as demonstrated by Hayashi et al. [88]. In fact, empirical research on fire whirls is a complex task due to the many limitations of the laboratory. A successful simulation should consider both the quantitative view and the qualitative view of a fire whirl. The qualitative aspects should include some conditions including the transition from a buoyant diffusion gas flame to a stable fire whirl, as well as the stability conditions for the fire whirl.

There is much research that has attempted to estimate the empirical behaviour of fire whirl utilizing various simulation software and methods. The details of some presented simulation endeavors to date and the fire whirl behaviour they attempted to capture are expressed in Table 3.

Table 3. Recent numerical analyzed fire whirls and presenting their simulations.



References	Outcomes	Numerical Method/Software	Fuel Type	Turbulence Model	Combustion Model	Schematic Diagram of Numerical Method
Parente et al. [51] (2019)	Studied the ability of the RST to measure physical behaviour of fire whirls (for example, the effects of used swirl generator on the flame height).	Star-CCM+ software	Propane	RST	Eddy Break-Up	
Fang et al. [31] (2020)	Illustrated the capability of the generic LES model in capturing the dynamic response of fire whirl.	ANSYS Fluent	Propane	LES (Smagorinsky– Lilly model)	Combination fraction	
Chung et al. [90] (2020)	Illustrated that the blue whirl is made of various flame regimes: lean, premixed rich, and a diffusion flame.	The algorithm of Barely implicit correction (BIC)	Ethanol and hep- tane		Superimposed thermal release rate	A 30 cm 5 cm All walls: nonslip, adiabatic 1.4 cm 11 cm Heptane vapor: 371 K, 5.8 cm/s

Table 3. Cont.

Based on the results presented in Table 3, in the DNS model, a full range of scales from the smallest to the largest are solved both in time and space. Therefore, the DNS model's needs are highly computationally demanding; however, in the LES model, only the large scales are solved, and the impacts of the smaller scales are simulated. This is due to the fact that the LES are highly influenced by the boundary conditions and so should be calculated, but smaller scales, which are highly independent of the flow geometry, are isotropic and homogeneous without considering the geometry, and so they can be easily simulated. As a result, the LES model requires lower calculation expenses. The calculation expense related to LES is usually orders of magnitudes greater compared to that for steady RANS computations regarding CPU time and memory. It is known that LES is more reliable and exact compared to RANS for streams in which large-scale unsteadiness appears such as the streams on bluff bodies [33]. Based on the presented results of [71], referenced in Table 3, the Barely Implicit Correction flux-corrected transport algorithm (BIC-FCT) [91], omits the sound velocity limitation by resolving the equations at large time steps specified by the velocity of the fluid (FDS uses the low Mach number formulation), and after that using a pressure correction which efficiently balances the acoustic waves. Specifically, the pressure field is corrected with respect to the energy and momentum equations at each time step. In addition, the flux-corrected transport is applied to estimate the next required time step. Despite the fact that a large number of experiments were conducted on this topic (Table 1), few numerical studies were made. This might be because of the complicated interplays that happen in the generation and the growth of fire whirls [67,68,92,93].

# 6. Conclusions

Fire whirls produce an intense combustion and have been analyzed by fire researchers due to the hazard they present in wildland and urban fires. Most of the presented data regarding fire whirls has been obtained from simulating tests in the laboratory because the destructive strength of fire whirls covers many properties of their structure. In the present review, empirical arrangements including experimental set up, and applied fuels are presented. In addition, the available simulation methods in numerical studies, including combustion and turbulence models used for the analysis of fire whirls are expanded. This paper demonstrates that more research works should be conducted to find the conditions under which fire whirl is produced, extending the range of factors considered so far and applying other sensors to investigate the temperature and flow field of the flames, presenting information to better investigate, and finding the physical mechanism related to the constitution and complicated dynamics of fire whirls. Based on the presented review, the main findings of the experimental and numerical methods used in fire whirls investigations can be summarized as follows:

- A successful simulation should consider both quantitative and qualitative aspects of fire whirl. The qualitative approach should include conditions incorporating transition from a buoyant diffusion gas flame to a stable fire whirl, together with stability conditions for the fire whirl.
- The qualitative features of the models used for numerical analyses should be based on the real physical nature of fire whirls.
- One of the strengths of the numerical simulation methods is that all ranges of temporal and spatial scales of turbulence in fire whirls are resolved in the computational mesh.
- While numerical studies will allow for better investigations of the fundamental mechanisms of fire whirl initiation and stability, there are currently not enough studies conducted in this area.

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## Nomenclature

- $C_p$  specific heat capacity
- Cvar dynamic stress constant
- K thermal conductivity
- Nu Nusselt number
- *q* heat flux
- Re Reynolds number
- T temperature
- $T_g$  temperature of grid control volume
- $T_f$  fuel surface temperature
- V displacement
- *x* direction
- Y combination fraction
- $\rho$  density
- $\nu$  viscosity

- $v_t$  eddy-viscosity
- $\varepsilon_d$  dissipation rate
- $\varepsilon_{ij}$  the mean strain-rate tensor
- $\delta_{ij}$  Kronecker's delta
- $\tau_{ij}$  the stress tensor of SGS
- $\overline{\Delta}$  grid–filter scale
- $\Delta'$  test-filter scale
- $\chi_M$  dilatation dissipation
- $\gamma_{soot}$  soot mass function

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