

Article

Improving Generalizability of PET DL Algorithms: List-Mode Reconstructions Improve DOTATATE PET Hepatic Lesion Detection Performance

Xinyi Yang ¹, Michael Silosky ², Jonathan Wehrend ³, Daniel V. Litwiller ⁴, Muthiah Nachiappan ², Scott D. Metzler ⁵, Debashis Ghosh ¹, Fuyong Xing ^{1,6,7} and Bennett B. Chin ^{2,7,*}

¹ Department of Biostatistics and Informatics, University of Colorado Anschutz Medical Campus, Aurora, CO, USA; xinyi.2.yang@cuanschutz.edu (X.Y.); debashis.ghosh@cuanschutz.edu (D.G.); fuyong.xing@cuanschutz.edu (F.X.)

² Department of Radiology, University of Colorado Anschutz Medical Campus, Aurora, CO, USA; michael.silosky@cuanschutz.edu (M.S.); muthiah.nachiappan@cuanschutz.edu (M.N.)

³ Department of Radiology, Santa Clara Valley Medical Center, San Jose, CA, USA; jwehrend@gmail.com

⁴ GE HealthCare, Denver, CO, USA; daniel.litwiller@ge.com

⁵ Department of Radiology, University of Pennsylvania, Philadelphia, PA, USA; scott.metzler@uphs.upenn.edu

⁶ The Computational Bioscience Program, University of Colorado Anschutz Medical Campus, Aurora, CO, USA

⁷ University of Colorado Cancer Center, University of Colorado Anschutz Medical Campus, Aurora, CO, USA; Fuyong.xing@cuanschutz.edu, bennett.chin@cuanschutz.edu

* Correspondence: bennett.chin@cuanschutz.edu

Supplementary Materials:

A U-Net-like architecture [12] was used for the lesion detection (Figure S1). The neural network has performed well on lesion detection in PET datasets. The down-sampling path contains four residual learning blocks [19]. In the up-sampling path, there are four residual learning blocks and two transposed convolutional layers [20] to aggregate contextual information [21].

The model was optimized with a Combo loss, which is a linear combination of binary cross-entropy loss and Dice loss [22].

$$\mathcal{L}_{COMBO}(y_n, \hat{y}_n) = \alpha \mathcal{L}_{BCE}(y_n, \hat{y}_n) + \mathcal{L}_{DICE}(y_n, \hat{y}_n)$$

$$\mathcal{L}_{BCE}(y_n, \hat{y}_n) = \mathbb{E}_{(x,y) \sim (X,Y)} \left[-\frac{1}{N} \sum_{n=1}^N (\omega y_n \log(\hat{y}_n + \varepsilon) + (1 - y_n) \log(1 - \hat{y}_n + \varepsilon)) \right]$$

$$\mathcal{L}_{DICE}(y_n, \hat{y}_n) = \mathbb{E}_{(x,y) \sim (X,Y)} \left[1 - \frac{\sum_{n=1}^N y_n \hat{y}_n + \delta}{\sum_{n=1}^N y_n + \hat{y}_n + \delta} - \frac{\sum_{n=1}^N b_n \hat{b}_n + \delta}{\sum_{n=1}^N b_n + \hat{b}_n + \delta} \right]$$

where $y_n \in y$ is the i^{th} value of the gold-standard label y and $\hat{y}_n \in \hat{y}$ is the i^{th} value of the corresponding prediction \hat{y} .

Implementation Details

We empirically set $\alpha = 6$, $\omega = 5$, $\delta = 1$. We optimize the lesion detection network using stochastic gradient descent with Nesterov momentum: learning rate = 0.0005, momentum = 0.99, batch size = 8, and total iterations = 10^5 .

Additionally, a data augmentation module was used to help train the model. The module consists of random shifting, random flipping, and random rotation.

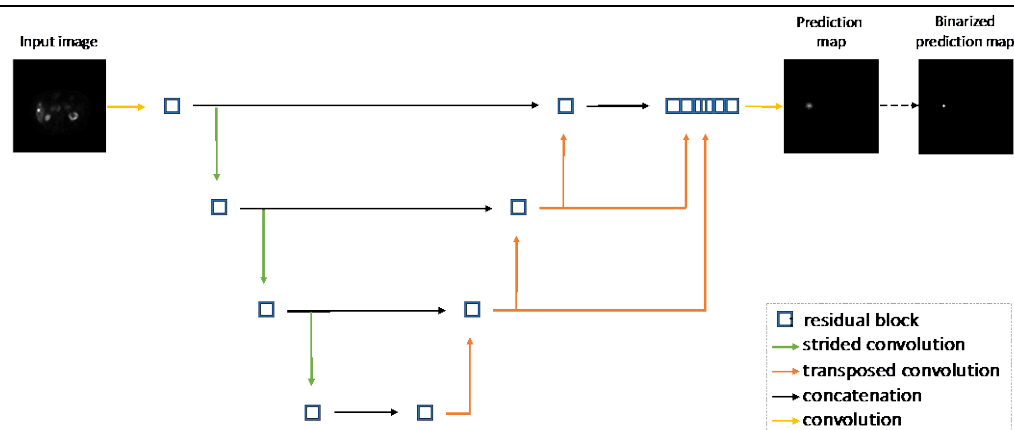


Figure S1. Model Training for Lesion Detection—Network architecture.