# SENSITIVITY ANALYSIS OF GENERAL MIXED MULTIVALUED MILDLY NONLINEAR VARIATIONAL INEQUALITIES

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Abstract- Dafermos [1] studied the sensitivity properties of solutions of a variational inequality with respect to a parameter  $\lambda$  In this paper, we extend this analysis for general mixed multivalued mildly nonlinear variational inequalities in the setting of Hilbert spaces.

**Keywords-** Sensitivity analysis, general mixed multivalued mildly nonlinear variational inequality, monotone and Lipschitz mappings, Hausdorff metric.

### **1. INTRODUCTION**

Dafermos [1] studied the sensitivity property of solutions of a particular kind of variational inequality on a parameter which takes values on an open subset of Euclidean space R<sup>K</sup>. Siddiqi et al [4], Tobin [5], Verma et al [6] studied the sensitivity analysis of various types of variational inequalities.

Let H be a Hilbert space and D be a nonempty closed and convex subset of H. Let A,T:D  $\rightarrow 2^{H}$  be the multivalued mappings. We consider the problem of finding  $u \in D$ ,  $p \in A(u)$ ,  $q \in T(u)$  such that  $g(u) \in D$ 

 $\langle g(v) - g(u), p + q \rangle + b(u, g(v)) - b(u, g(u)) \ge 0$ , for all  $g(v) \in D$ , (1) where  $b(.,.) : H \times H \rightarrow R$  satisfying the following properties:

(i) b(.,.) is linear in the first argument;

(ii) b(.,.) is bounded, that is there exists constant  $\gamma > 0$  such that

$$|\mathbf{u},\mathbf{v}\rangle| \le \gamma \|\mathbf{u}\| \|\mathbf{v}\|, \text{ for all } \mathbf{u},\mathbf{v} \in \mathbf{H};$$

$$(2)$$

(iii) |b(.,.)| is either convex or linear in the second argument;

(iv) for every  $u, v, w \in H$ 

$$|b(u,v) - b(u,w)| \le b(u,v-w)$$
 (3)

$$\mathbf{b}(\mathbf{u},\mathbf{v}\pm\mathbf{w}) \leq \mathbf{b}(\mathbf{u},\mathbf{v}) + \mathbf{b}(\mathbf{u},\mathbf{w}).$$

In this paper, we study the sensitivity analysis of general mixed multivalued mildly nonlinear variational inequality problem (GMMMNVIP) of the type (1).

## 2. SENSITIVITY ANALYSIS

To formulate the problem, let M be an open subset of H in which the parameter  $\lambda$  takes values and assume that  $\{K_{\lambda}: \lambda \in M\}$  is a family of closed convex subset of H. The parametric general mixed multivalued mildly nonlinear variational inequality is to find  $u \in D$ ,  $(p, \lambda) \in A(u, \lambda)$ ,  $(q, \lambda) \in T(u, \lambda)$  such that  $g(u) \in K_{\lambda}$ 

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 $\langle g(v) - g(u), (p, \lambda) + (q, \lambda) \rangle + b(u, g(v)) - b(u, g(u)) \ge 0$ , for all  $g(v) \in K_{\lambda}$  (4) where A(u,  $\lambda$ ) and T(u,  $\lambda$ ) are multivalued mappings, which are define on the set (u,  $\lambda$ ) with  $\lambda \in M$ . We also assume that for some  $\overline{\lambda} \in M$ , the problem (4) admits a solution  $\overline{u}$ . We want to investigate those conditions under which, for each  $\lambda$  is a neighbourhood of  $\overline{\lambda}$ . The problem (4) has a unique solution  $u(\lambda)$  near  $\overline{u}$  and the function  $u(\lambda)$  is continuous and differentiable. We assume that B is the closure of a ball in H centered at  $\overline{u}$ . We need the following concepts.

**2.1 Definition-** An operator g defined on B to H is said to be locally,  $u, v \in B$ ,

(i)  $\xi$ -strongly monotone, if there exists a constant  $\xi >0$  such that

$$\langle g(\mathbf{u}) - g(\mathbf{v}), \mathbf{u} - \mathbf{v} \rangle \ge \xi \| \mathbf{u} - \mathbf{v} \|^2$$
 (5)

(ii)  $\sigma$ -h-Lipschitz continuous, if there exists a constant  $\sigma >0$  such that

 $||g(u) - g(v)|| \le \sigma ||u - v||.$ (6)

In particular, it follows that  $\xi \leq \sigma$ .

**2.2 Definition-** A multivalued mapping  $T(u, \lambda)$  defined on B×M to C(H) is said to be locally v-h-Lipschitz continuous, if there exists a constant v >0 such that

$$h(T(u,\lambda), T(v,\lambda)) \le v || u - v ||, \text{ for all } u, v \in B,$$
(7)

where h(.,.) is a Hausdorff metric on C(H), and C(H) denotes the family of all nonempty compact subsets of H.

**2.3 Definition-** A multivalued mapping  $A(u,\lambda)$  defined on B×M to C(H) is said to be locally  $\alpha$ -strongly monotone if there exists a constant  $\alpha > 0$  such that

 $\langle (p_1, \lambda) - (p_2, \lambda), u - v \rangle \ge \alpha || u - v ||^2$  for all  $u, v \in B$ ,  $(p_1, \lambda) \in A(u, \lambda)$ ,  $(p_2, \lambda) \in A(v, \lambda)$ . (8) We have the following lemmas which can be proved by the techniques of Noor [3].

**2.1 Lemma-** A point  $u \in K_{\lambda}$  is a solution of the parametric general mixed multivalued mildly nonlinear variational inequalities (4) iff it is fixed point of the map

 $\begin{aligned} \phi(u,\lambda) &= u - g(u) + P_{K^{\lambda}} \left[ g(u) + F(u) - \rho((p,\lambda) + (q,\lambda)) \right] \end{aligned} \tag{9} \\ \text{for all } \lambda \in M, \ (p,\lambda) \in A(u,\lambda), \ (q,\lambda) \in T(u,\lambda) \text{ for some } \rho > 0, \text{ where } P_{K^{\lambda}} \text{ is the projection of } H \text{ on the family of closed convex sets } K_{\lambda} \text{ and } F:H \rightarrow H \text{ is a single valued function } defined by, \text{ for every } (p,\lambda) \in A(u,\lambda) \text{ and } (q,\lambda) \in T(u,\lambda) \end{aligned}$ 

 $\langle F(u), g(v) \rangle = \langle u, g(v) \rangle - \rho \langle (p, \lambda) + (q, \lambda), g(v) \rangle - \rho b(u, g(v)), \text{ for all } g(v) \in K_{\lambda}.$  (10) Since we are interested in the case, when the solution of the problem (4) lies in the interior of B. So we consider the map  $\varphi^*(u, \lambda)$  define by

 $\varphi^*(u, \lambda) = u - g(u) + P_{K_{\lambda \cap B}}[g(u) + F(u) - \rho((p, \lambda) + (q, \lambda))]$ , for all  $(u, \lambda) \in B \times M$ . (11) We have to show that the map  $\varphi^*(u, \lambda)$  has a fixed point, which by (9) is also a solution of (4). First of all, we prove that the map  $\varphi^*(u, \lambda)$  is a contraction map with respect to u, uniformly in  $\lambda \in M$ , by using locally  $\alpha$ -strongly monotonicity and locally  $\beta$ -h-Lipschitz continuity of the operator A(u, $\lambda$ ), locally  $\xi$ -strongly monotonicity and  $\sigma$ -h-Lipschitz continuity of g(u) and locally  $\upsilon$ -h-Lipschitz continuity of T(u, $\lambda$ ).

**2.2 Lemma-** For all  $u_1, u_2 \in B$  and  $\lambda \in M$ , we have

$$\parallel \phi^{*}(u_{1},\lambda) - \phi^{*}(u_{2},\lambda) \parallel \leq \theta \parallel u_{1} - u_{2} \parallel$$

where for

$$\theta = k + 2\rho \upsilon + \rho \gamma + 2(1 - 2\rho \alpha + \rho^2 \beta^2)^{1/2}$$

$$((1-k)(2\upsilon+\gamma)) 4^{-1} < \alpha < \beta,$$
  $k < 1$ 

$$\begin{aligned} \alpha &> (1-k)(\gamma+2\upsilon) \ 4^{-1} + ((\beta^2 - ((2\upsilon+\gamma) \ 2^{-1})^2)(3-k)(1+k) \ 4^{-1})^{1/2} \\ \text{and} \\ &|\rho - (\alpha + (k-1)(\gamma+2\upsilon) \ 4^{-1} \ )(\beta^2 - ((2\upsilon+\gamma) \ 2^{-1})^2 \ )^{-1}| < \end{aligned}$$

 $\{ (\alpha + (k - 1)(\gamma + 2\upsilon) 4^{-1})^2 - (\beta^2 - ((2\upsilon + \gamma)2^{-1})^2)(1 + k)(3 - k)4^{-1}) \}^{1/2} \{ \beta^2 - ((2\upsilon + \gamma)2^{-1})^2 \}^{-1}$  with

$$k = 2 (1 - 2\xi + \sigma^2)^{1/2}.$$

**Proof-** Using (11), we have

 $\| \phi^{*}(u_{1}, \lambda) - \phi^{*}(u_{2}, \lambda) \| = \| \{u_{1} - g(u_{1}) + P_{K^{\lambda}} [g(u_{1}) + F(u_{1}) - \rho ((p_{1}, \lambda) + (q_{1}, \lambda))] \} \\ - \{ u_{2} - g(u_{2}) + P_{K^{\lambda}} [g(u_{2}) + F(u_{2}) - \rho ((p_{2}, \lambda) + (q_{2}, \lambda))] \} \|$ and using the fact that the projection operator is nonexpansive, we have

$$\| \phi^{*}(u_{1}, \lambda) - \phi^{*}(u_{2}, \lambda) \| \leq 2 \| u_{1} - u_{2} - (g(u_{1}) - g(u_{2})) \| + \|F(u_{1}) - F(u_{2})\| + \| u_{1} - u_{2} - \rho ((p_{1}, \lambda) - (p_{2}, \lambda)) \| + \rho \|(q_{1}, \lambda) - (q_{2}, \lambda)\|.$$
(12)

Now, the operator g(u) is both locally  $\xi$ -strongly monotone and  $\sigma$ -h-Lipschitz continuous and the operator  $A(u, \lambda)$  is locally  $\alpha$ -strongly monotone and locally  $\beta$ -h-Lipschitz continuous, so by the method of Noor [2],

$$\| u_{1} - u_{2} - (g(u_{1}) - g(u_{2})) \|^{2} = \| u_{1} - u_{2} \|^{2} + \| g(u_{1}) - g(u_{2}) \|^{2} - 2 \langle g(u_{1}) - g(u_{2}), u_{1} - u_{2} \rangle$$
  
 
$$\leq (1 - 2\xi + \sigma^{2}) \| u_{1} - u_{2} \|^{2},$$
 (13)

where  $\sigma$  and  $\xi$  are Lipschitz and strongly monotone constants of g(u), respectively and  $\langle F(u_1) - F(u_2), g(v) \rangle = \langle u_1 - u_2, g(v) \rangle - \rho \langle (p_1, \lambda) - (p_2, \lambda), g(v) \rangle - \rho \langle (q_1, \lambda) - (q_2, \lambda), g(v) \rangle - \rho b(u_1 - u_2, g(v))$ 

$$\leq \{ \| u_1 - u_2 - \rho ((p_1, \lambda) - (p_2, \lambda)) \| + \rho \| (q_1, \lambda) - (q_2, \lambda) \| + \rho \gamma \| u_1 - u_2 \| \} \| g(v) \|$$
  
 
$$\leq \{ (1 - 2\alpha\rho + \rho^2\beta^2)^{1/2} + \rho \upsilon + \rho \gamma \} \| u_1 - u_2 \| \| g(v) \|.$$

 $|| F(u_1) - F(u_2) || = \sup_{g(v) \in K} \left\{ \langle F(u_1) - F(u_2), g(v) \rangle / || g(v) || \right\}$ 

$$\leq \{ (1 - 2\alpha\rho + \rho^{2}\beta^{2})^{1/2} + \rho\upsilon + \rho\gamma \} \| u_{1} - u_{2} \|$$
(14)

and

$$\| u_{1} - u_{2} - \rho((p_{1}, \lambda) - (p_{2}, \lambda)) \|^{2} = \| u_{1} - u_{2} \|^{2} + \rho^{2} \| (p_{1}, \lambda) - (p_{2}, \lambda) \|^{2} - 2\rho \langle u_{1} - u_{2}, (p_{1}, \lambda) - (p_{2}, \lambda) \rangle.$$
(15)

Using (6) and (8), we have

$$\| (p_1, \lambda) - (p_2, \lambda) \| \le h(A(u_1, \lambda), A(u_2, \lambda)) \le \beta \| u_1 - u_2 \|$$

$$\langle \mathbf{u}_1 - \mathbf{u}_2, (\mathbf{p}_1, \lambda) - (\mathbf{p}_2, \lambda) \rangle \ge \alpha \parallel \mathbf{u}_1 - |\mathbf{u}_2||^2$$

Therefore (15) becomes

$$\| u_{1} - u_{2} - \rho ((p_{1}, \lambda) - (p_{2}, \lambda)) \|^{2} \leq \| u_{1} - u_{2} \|^{2} + \rho^{2} \beta^{2} \| u_{1} - u_{2} \|^{2} - 2\rho\alpha \| u_{1} - u_{2} \|^{2}$$

$$\leq (1 - 2\alpha\rho + \rho^{2}\beta^{2}) \| u_{1} - u_{2} \|^{2}$$
(16)

where  $\beta$  and  $\alpha$  are the constants appearing in (5), (6), again

 $\| (q_1, \lambda) - (q_2, \lambda) \| \le h(T(u_1, \lambda), T(u_2, \lambda)) \le \upsilon \| u_1 - u_2 \|.$ Since  $T(u, \lambda)$  is locally  $\upsilon$ -h-Lipschitz continuous, using (13)-(17), we have (17)

$$\| \varphi^*(u_1, \lambda) - \varphi^*(u_2, \lambda) \| \le \theta \| u_1 - u_2 \|$$
$$\theta = k + 2\rho \upsilon + \rho \gamma + 2(1 - 2\rho \alpha + \rho^2 \beta^2)^{1/2}$$

where with

 $k = 2(1 - 2\xi + \sigma^2)^{1/2}.$ 

Now, using the technique of Noor [3], we can show that  $\theta < 1$  from which it follows that the map  $\varphi^*(u, \lambda)$  defined by (11) is a contraction map.

**2.1 Remark-** From Lemma 2.2, It is clear that the map  $\varphi^*(u, \lambda)$  defined by (11) has a <u>unique fixed point</u>  $u(\lambda)$  that is  $u(\lambda) = \varphi^*(u, \lambda)$ , we also know by assumption, the function u for  $\lambda = \overline{\lambda}$  is a solution of the parametric general mixed multivalued mildly nonlinear variational inequality problem (4), we see that  $\overline{u}$  is a fixed point of  $\underline{\phi}(u, \lambda)$  and it is also a fixed point of  $\varphi^*(u, \lambda)$ , consequently we have  $u(\lambda) = u = \varphi^*(u(\lambda), \lambda)$ , now we show that the solution  $u(\lambda)$  of problem (4) is  $\beta$ -h-Lipschitz continuous.

**2.3 Lemma-** If  $T(\overline{u}, \lambda), A(\overline{u}, \lambda)$  is the multivalued operators and the map

$$\lambda \to P_{K_{\lambda \cap B}} \left[ g(\overline{u}) + F(\overline{u}) - \rho((\overline{p, \lambda}) + (\overline{q}, \overline{\lambda})) \right]$$

are  $\beta$ -h- Lipschitz continuous in  $\lambda$  at  $\overline{\lambda}$ , then  $u(\lambda)$  is  $\beta$ -h- Lipschitz continuous at  $\lambda = \overline{\lambda}$ . **Proof-** Fix  $\lambda \in M$ , then using the triangle inequality and Lemma 2.2, we have

$$\| u(\lambda) - u(\overline{\lambda}) \| \leq \| \phi^*(u(\lambda), \lambda) - \phi^*(u(\overline{\lambda}), \lambda) \| + \| \phi^*(u(\overline{\lambda}), \lambda) - \phi^*(u(\overline{\lambda}), \overline{\lambda}) \|$$

$$\leq \theta \| u(\lambda) - u(\overline{\lambda}) \| + \| \phi^*(u(\overline{\lambda}), \lambda) - \phi^*(u(\overline{\lambda}), \overline{\lambda}) \|.$$
(18)

From (11) and the fact that the projection operator is nonexpansive, we have

$$\| \phi^{*}(u(\overline{\lambda}), \lambda) - \phi^{*}(u(\overline{\lambda}), \overline{\lambda}) \| = \| P_{K_{\lambda \cap B}} [g(u(\overline{\lambda})) + F(u(\overline{\lambda})) - \rho((\overline{p(\lambda)}, \lambda) + (\overline{q(\lambda)}, \lambda))] - P_{K_{\lambda \cap B}} [g(u(\overline{\lambda})) + F(u(\overline{\lambda})) - \rho((\overline{p(\lambda)}, \overline{\lambda}) + (\overline{q(\lambda)}, \overline{\lambda}))] \| \leq \rho \| (p(\overline{\lambda}), \lambda) - (\overline{p(\lambda)}, \overline{\lambda}) \| + \rho \| (q(\overline{\lambda}), \lambda) - (\overline{q(\lambda)}, \overline{\lambda}) \| + \| P_{K_{\lambda \cap B}} [g(u(\overline{\lambda})) + F(u(\overline{\lambda})) - \rho((\overline{p(\lambda)}, \overline{\lambda}) + (\overline{q(\lambda)}, \overline{\lambda}))] \\ - P_{K_{\lambda \cap B}} [g(u(\overline{\lambda})) + F(u(\overline{\lambda})) - \rho((\overline{p(\lambda)}, \overline{\lambda}) + (\overline{q(\lambda)}, \overline{\lambda}))] \| .$$
(19)

Now from Remark 2.1 and combining (18) and (19), we have

$$\| u(\lambda) - \overline{u} \| \le \rho (1 - \theta)^{-1} \| (p(\overline{\lambda}), \lambda) - (p(\overline{\lambda}), \overline{\lambda}) \| + \rho (1 - \theta)^{-1} \| (q(\overline{\lambda}), \lambda) - (q(\overline{\lambda}), \overline{\lambda}) \|$$
$$+ \rho (1 - \theta)^{-1} \| P_{K_{\lambda \cap B}} [\overline{g(u)} + \overline{F(u)} - \rho ((p(\overline{\lambda}), \overline{\lambda}) + (q(\overline{\lambda}), \overline{\lambda}))]$$

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 $-P_{K_{\lambda \cap B}} \left[ g(\overline{u}) + F(\overline{u}) - \rho((p(\lambda), \overline{\lambda}) + (q(\overline{\lambda}), \overline{\lambda}))) \right] \|.$ From which the required result follows:

Using the technique of Dafermos [1], we can show that there exists a neighbourhood N containing in M of  $\overline{\lambda}$  such that for  $\lambda \in N$ ,  $u(\lambda)$  is the unique solution of problem (4) in the interior of B.

Combining the above results we arrive at the following:

**2.1 Theorem-** Let  $\overline{u}$  be the solution of parametric general mixed multivalued mildly nonlinear variational inequality problem (4) at  $\lambda = \lambda$ , the multivalued mapping  $T(u, \lambda)$ be locally v-h-Lipschitz continuous and the multivalued mapping  $A(u, \lambda)$  be locally  $\alpha$ strongly monotone and locally  $\beta$ -h-Lipschitz continuous, the map  $\overline{g(u)}$  be locally  $\xi$ strongly monotone and  $\sigma$ -h-Lipschitz continuous. Suppose that  $T(u, \lambda)$ ,  $A(\overline{u}, \lambda)$ ,  $\overline{g(u)}$  and the map

 $\lambda \to P_{K_{\lambda \cap B}} \ [g(\overline{u}) + \overline{F(u)} - \rho(\overline{(p, \lambda)} + \overline{(q, \lambda)})]$ 

are  $\beta$ -<u>h</u>-Lipschitz continuous at  $\lambda = \overline{\lambda}$ , then there exists a neighbourhood N containing in M of  $\lambda$  such that for  $\lambda \in N$ , the problem (4) has a unique solution  $u(\lambda)$  in the interior of B,  $u(\overline{\lambda}) = \overline{u}$  and  $u(\lambda)$  are continuous ( $\beta$ -h-Lipschitz continuous) at  $\lambda = \overline{\lambda}$ .

**2.2 Remark-** The function  $u(\lambda)$  as defined in Theorem 2.1 is continuously differentiable on some neighbourhood N of  $\lambda$ . For this see Dafermos [1].

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