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Sensitivity Test of Jet Velocity and Void Fraction on the Prediction of Rise Height and Performance of a Confined Plunging Liquid Jet Reactor

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Abstract: Jet velocity is an important parameter affecting the air entrainment rate of plunging liquid jet processes. While the vast majority of researchers have investigated the effect of jet velocity, only a few of them considered the effect of jet length in calculating the jet velocity at impingement point. This study investigates the difference (ΔV) between the jet velocity at the inception of the nozzle (V_j) and the impingement point (V_L) for a range of operating conditions. Furthermore, bubble voidage inside the downcomer, another critical parameter in plunging jets, is estimated using three different voidage equations incorporated inside a momentum balance model to predict the two-phase elevation level (H_R) inside the downcomer. Results showed that ΔV is significant ($V_L > V_j$), especially at low jet flow rates and high jet lengths. Generally, the momentum balance model predicted the H_R well, and its prediction improves with downcomer diameter. Given that, the model still needs to be refined for more accuracy for a wide range of operating conditions.

Keywords: multiphase flow; rise height; confined plunging jet reactor; aeration; dilution

1. Introduction

In nature, gas entrainment occurs due to the impingement of a falling liquid into a receiving water body like in waterfalls, rivers, and streams that result in a dispersion of air bubbles into the water body, which ultimately results in self-purification or reaeration of the water body [1]. In fact, in environmental scenarios like breaking waves, the aeration rate can increase 200 times since many air bubbles entrain into the wave, and there is a tremendous increase in the air–water interfacial area [2]. Entrainment by plunging jets is a phenomenon that is advantageous in many applications such as aerobic wastewater treatment, fermentation processes, brine dilution, oxygen dissolution, air pollution abatement, and froth flotation as it achieves gas absorption and diffusion by bringing two phases in contact [1,3–5]. The mass transfer between the two phases can be significantly increased if large interfacial areas for contact are provided, i.e., the most common method is by dispersing the gas phase as fine bubbles into the liquid phase [6] However, in some instances, such as the formation of gas bubbles when molten liquids are poured into a container, gas entrainment is undesirable and must be avoided [1].

Among all the gas-liquid reactors, the jet mixing reactors, i.e., those with contacting surfaces like nozzles, venturies, or ejectors, are gaining more popularity because of the high interfacial areas for the gas and liquid contact and rigorous mixing of the liquid content at a low cost. In these reactors, the fluid's kinetic energy is used to achieve dispersion and mixing between the phases.

The concept of plunging liquid has been around for about five decades (since the 1970s). It started out as an unconfined plunging liquid jet reactor (UPLJR) [7–14] Later on, a confined PLJR (CPLJR), was introduced to overcome the limited penetration depth provided by the UPLJR by introducing a confining tube [15–19]. The CPLJR enhanced



Citation: Al-Anzi, B.S.; Fernandes, J. Sensitivity Test of Jet Velocity and Void Fraction on the Prediction of Rise Height and Performance of a Confined Plunging Liquid Jet Reactor. *Processes* **2022**, *10*, 160. https:// doi.org/10.3390/pr10010160

Academic Editor: Nicolas Dietrich

Received: 14 November 2021 Accepted: 11 January 2022 Published: 13 January 2022

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Copyright: © 2022 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). the oxygen dissolution into the liquid by increasing bubble–liquid contact time (residence time) due to an increase in bubble penetration depth at no or low cost. In 2007, Al-Anzi introduced a novel system of CPLJR incorporating an annular airlift column to dilute the almost saturated liquid ejecting from the base of a long downcomer in the CPLJR system with fresh liquid to enable further mass transfer.

Furthermore, the PLJR is an excellent gas-liquid contactor as it is energy efficient and can achieve sufficiently high mass transfer rates. This is possible since it can entrain gas bubbles into a liquid phase at low costs (operating and capital costs) [3,4,18] The liquid phase ejects from a nozzle, thereby forming a jet, which then falls through ambient headspace and plunges into the surface of a receiving pool of the same liquid. As it falls through the headspace, it entrains air along with it, thus promoting aeration of the two phases. If the liquid falls into the receiving body through a confined tube (downcomer), this system is called the confined liquid jet reactor (Figure 1b). In contrast, the reactor without a confining tube is called an unconfined plunging jet reactor (Figure 1a) or simply a plunging jet reactor. When the impact velocity of the impinging jet is greater than the critical jet velocity, air bubbles are entrained in the liquid [20]. The air that is entrained by a plunging jet gets dispersed into the receiving body, but the penetration depth of the bubbles is small since the jet spreads across the receiving water, reducing the contact time of the bubble. However, by adding a confining tube (CPLJR), the downcomer surrounds the liquid jet, which helps to maintain the liquid superficial velocity of the jet, which then helps to carry the entrained bubbles to larger depths.



Figure 1. (a) An unconfined plunging jet system (b) the same jet surrounded by a confining down-comer column [4].

Results showed that the liquid leaving the end of a long downcomer in a CPLJR was almost saturated with oxygen (>90%) [21]. This was resolved by introducing an annulus around the confining tube, as shown in Figure 2 which brings fresh unaerated water from the surrounding liquid in contact with the bubbles leaving with saturated liquid from the base of the downcomer to promote further mass transfer at no extra cost [3].



Figure 2. Schematic diagram of the air-lift column in the confined plunging liquid jet reactor (CPLJR). (1) top flange; (2) bottom flange; (3) liquid jet; (4) supporting rods; (5) riser rods; (6) nozzle; (7) down-comer; (8) air tapping; (9) water tank; (10) water supply; (11) drain; (12) recycled water; (13) bypass; (14) pump; (15) valve; (16) rotameter; (17) bubble meter; (18) wires; (19) annulus; (20) connection point; (21) amplifier; (22) PC; (23) injecting salt by syringe; (24) electrode rings [3].

Plunging liquid jets have multiple applications in industries and are primarily used when two-phase mixing is required. They are of great use in aerobic wastewater treatment plants, in froth flotation, and can also be used in desalination outfalls [4]. Recently, a group of researchers from Kuwait University and MIT explored the idea of utilizing such technology (both confined and unconfined) as a brine dispenser and for oxygen dissolution [5,22]. Another application of using this technology is using an airlift column that surrounds the confining tube (Figure 2). The role of this annulus is to collect the upward gas-liquid flow that exits from the bottom of the downcomer resulting in entraining pure freshwater from the surrounding through the bottom of the confining tube for additional mass transfer [3].

The mechanism and behavior of the plunging jets have been extensively investigated by many authors. Parameters such as jet lengths (L_j), nozzle diameter (d_n), jet velocity (V_j), fluid properties, and downcomer diameter (D_c) affect the volumetric gas entrainment rate (Q_a), and various studies have been conducted in the past to design an optimal plunging jet reactor [2–5,7,9,11,18,23,24]. The velocity of the jet is one of the primary variables that significantly affects the performance of a PLJR. Many researchers have justified how the jet velocity and its interaction with the receiving body are significant in air entrainment. Chanson and Lee [25]. even talked in their report about how the bubble entrainment is critically dependent on two factors—the impact velocity and the impact angle. Wang et al. [26] discussed that air entrainment happens only when the plunging velocity exceeds the critical velocity point. In their research study, Miwa et al. [24]) stated that the entrainment rates differ with jet velocity ranges and have given two different correlations for such cases (when V_j is less than 5 m/s and when V_j is less than 10 m/s but greater than 5 m/s). Dimensions of the nozzle and the diameter of the confining tube are other secondary factors to consider, along with the effect of jet velocity. In addition to this, Chanson et al. [2]. also pointed out that the jet length (L_j) is another critical variable responsible for creating this momentum impact for a deeper penetration level and contributes to the jet velocity at the impingement point (V_L) .

The voidage is a vital parameter to understand the liquid-gas interaction in the column and is the other variable of interest in our work [27]. The amount of bubbles in a two-phase system can be represented by their voidage or void fraction (n). The simplest approximation of voidage is when the air dis-entrainment rate is not accounted for, and the gas void fraction is considered simply to be a fraction of the total mixture (Q_2).

Since
$$Q_a = n Q_2$$
 and $Q_2 = Q_a + Q_j$ (1)

$$n_1 = \frac{Q_a}{\left(Q_a + Q_j\right)} \tag{2}$$

where Q_a and Q_i represent the volumetric flowrate of gas and liquid, respectively.

However, Al-Anzi [3] stressed that gas void fraction could not be a simple gas ratio in the mixture of liquid and gas flowrates as the slip velocity between the phases, and the effects caused due to the non-uniform flows and the concentration distribution must be considered. Zuber and Findalay [26] have given an equation to quantify the gas void fraction which considered these factors. It was Clark and Flemmer [28] who used that equation and simplified it to predict the voidage accurately in a downcomer. Their equation is as follows:

$$n_2 = \frac{Q_a}{C_0 \left(Q_j + Q_a\right) - U_0 \operatorname{Ac}}$$
(3)

where C_0 is a constant whose value equals 1.16 U_0 is the bubble rise velocity, and A_c is the area of the downcomer [28].

This paper discusses the effect of the jet length (L_j) on jet velocity for a range of jet velocity values by calculating the differences between the jet velocities (ΔV) at the nozzle inception (V_j) , at rise height inside the downcomer (V_R) , and at the impingement point (V_L) . The current study also covers the effect of bubble voidage (n) on the rise height of gas-liquid inside the downcomer (H_R) . This is achieved by incorporating three voidage equations $(n_1, n_2, and n_3)$ into a momentum mass balance to predict H_R theoretically and compare it against local experimental data obtained in the College of Life Sciences laboratory at Kuwait University.

2. Model Calculations

2.1. Jet Velocity along the Jet Length

Jet length (L_j), or the length that the jet has to vertically travel before it reaches the impact or impingement point, is a significant parameter for design, as it is responsible for the air entrainment rate in the PLJR process. Al-Anzi [3,4] have mentioned that as the jet length increases, the disturbances on the jet length also increases since the jet is exposed to air for a longer time since its inception. Along with the jet length, the nature of the falling jet (laminar or turbulence) can affect the amount of air entrained. Some of the previous studies [3] have not considered the effect of jet length on the jet velocity and kept it at a constant value in the experiments due to either short jet length or high jet velocities; thus, they did not have significant H_R .

With regards to the jet velocity parameter (Figure 3c), there are two groups of researchers. The early researchers focused on the velocity of the jet at nozzle point (V_j) in their correlations and calculations for air entrainment [3,18]. Recently, researchers have shown that the velocity at impingement point (that could be the velocity at the receiving body surface (V_L) or velocity at the rise height surface (V_R)) is significantly higher than that at the nozzle inception, especially at low jet velocity and high jet length [24,29–31]. The V_L velocity is the velocity effect coupled with the gravitational forces due to jet length L_j , which adds to the momentum of the flowing jet, and is worth considering in the equations used to calculate air entrainment rates. From Qu et al. [29] V_R is expressed as Equation (4) given below:



$$T_{\rm R} = \sqrt{V_j^2 + 2g(L_j - H_{\rm R})} \tag{4}$$

Figure 3. Cont.



Figure 3. (a) The schematic of the CPLJR unit illustrating the different parts: (1) bubble meter, (2) air tapping, (3) nozzle, (4) downcomer, (5) inner frame, (6) water tank, (7) drain outlet, (8) rotameters, and (9) pump; (b) the CPLJR unit in the Kuwait University laboratory; (c) schematic of the CPLJR model showing the variables used in the momentum model study; (d) the scaled downcomers used in this study.

Similarly, V_L is expressed as Equation (5) given below:

$$V_{\rm L} = \sqrt{V_j^2 + 2g(L_j)} \tag{5}$$

2.2. Voidage Formulae

The amount of air entrained in a liquid or the voidage fraction of air inside the liquid is another parameter that is crucial for determining the air entrainment rate and can be calculated using three voidage equations described in detail below. Firstly, we consider the most straightforward equation to define voidage: the volume fraction of the bubbles in a total mixture of air and liquid, which is the Equation (2):

$$n_1 = \frac{Q_a}{\left(Q_a + Q_j\right)} \tag{6}$$

Secondly, we consider the approximation that Clark and Flemmer [28] considered and used in their equation:

$$n_2 = \frac{Q_a}{C_0 \left(Q_j + Q_a\right) - U_0 \operatorname{Ac}}$$
(7)

To further simplify the above equation, we considered a voidage equation where we consider the disentrainment effect U_0Ac as negligible.

$$n_3 = \frac{Q_a}{C_0 \left(Q_j + Q_a\right)} \tag{8}$$

2.3. Momentum Balance

In the current study, a hydraulic model was developed to describe the confined plunging jet reactor performance using momentum and volume balances, based on the model outlined by Cumming et al. [5]. This model was then used to predict the rise height of the bubbles in the downcomer (H_R) and compare it with experimental data.

A schematic and an actual impression of the CPLJR system utilized in the current work are shown in Figure 3a,b, respectively. Figure 3c illustrates the variables used in the momentum study, where Q_j flowrate of the jet, and Q_2 is the combined flow rate of air and liquid exiting from the bottom of the downcomer; V_j is the jet velocity at the nozzle, V_R is the jet velocity at the rise height (H_R), and V_L is the jet velocity at the impingement point; V_1 and V_2 are the liquid velocities at Sections 1 and 2, respectively, where $V_2 = \frac{Q_j}{A_c(1-n)}$; L_j is the jet length, and H_c is the downcomer submergence, D_c is the diameter of the downcomer, A_c is the cross-sectional area of the downcomer and n is the bubble voidage within the downcomer. The density of water is represented as ρ_j , ρ_w is the density of receiving water, and $\rho_{aj} \approx (1-n)\rho_j$ is the density of the air–water mixture within the downcomer. P_1 is the pressure at Section 1, P_2 is the pressure at Section 2, and Q_a is the air flowrate which is calculated by multiplying the cross-sectional area of the inner diameter of the bubble meter and the velocity of air (which is found out by dividing the distance of bubble rise in the bubble column by the time taken throughout the rise).

Volume and momentum balances:

$$Q_2 = Q_a + Q_j \tag{9}$$

and

$$P_2 - P_1)A_c + \left(-\frac{dP}{dZ}ZA_c\right) - Z\rho_{aj}gA_c = \rho_j Q_j\{v_1 - v_2\}$$
(10)

where $Z = H_R + H_c$

 $(P_2 = P_1 + \rho_w gZ) \tag{11}$

Substituting Equations (9) and (10) in Equation (8), yields,

$$\rho_{w}gA_{c}(H_{R}+H_{c}) + \left(-\frac{dP}{dZ}(H_{R}+H_{c})A_{c}\right) - \rho_{j}(1-n)g(H_{R}+H_{c})A_{c} = \rho_{j}Q_{j}\{v_{1}-v_{2}\}$$
(12)

where

$$-\frac{\mathrm{dP}}{\mathrm{dZ}} = \frac{\left\{4 C_{\mathrm{fd}} \left(\frac{Q_{\mathrm{a}}}{A_{\mathrm{c}}} + \frac{Q_{\mathrm{j}}}{A_{\mathrm{c}}}\right)^{2} \rho_{\mathrm{aw}}\right\}}{2 D_{\mathrm{c}}} (\text{Cumming et al. 2002})$$
(13)

where $C_{fd} = 0.079 \text{ Re}^{-0.25}$ And $\text{Re} = \frac{\left\{\frac{Q_a}{A_c} + \frac{Q_j}{A_c}\right\} D_c \rho_{aw}}{\mu_f}$ (Cumming et al. 2002). H_R can be predicted from Equation (11).

3. Experimental Work

3.1. Description of Our Apparatus

The confined plunging liquid jet apparatus constructed at the local laboratory in Kuwait University (College of Life Sciences) is shown in Figure 3b. A centrifugal pump recirculated tap water from the bottom of a $1.25 \times 0.5 \times 0.5$ m³ reservoir and fed it through a nozzle in the form of a liquid jet. A rotameter was used to measure the liquid flow rates of 9, 15, and 30 LPM, and two nozzle diameters of 10 mm and 8 mm were also used in the present study. Jet lengths (distance between the receiving pool and the nozzle through which the jet ejects) were in the range from 200 to 600 mm. Downcomers of different diameters (D_c) were used in the study ($D_c = 2.5 \text{ cm}$, 4.4 cm, 6.4 cm, 7.4 cm and 9.4 cm). The downcomer submergence (H_c) was also varied from 5cm to 40cm. Volumetric air entrainment rate, Q_a , was measured adopting the same technique employed by Al-Anzi [3,4] utilizing a soap bubble meter. This soap bubble meter is a cylindrical tube having an inner diameter of 74 mm and is 1000 mm long. The bubbles were generated using a soap solution mixture of 10% household detergent, 5% glycerin (5%), and the rest is water. While the CPLJR reactor is in progress, the volume of air entering the reactor is indicated by the bubble formation inside the bubble meter. The time that the bubble takes to travel a certain distance (in this case X = 40 cm) is noted and the velocity of the bubble is determined. The volumetric flowrate is then deduced by multiplying this bubble velocity to the cross-sectional area of the bubble meter.

3.2. Jet Length (L_i) and Rise Height (H_R) Experimental Measurement

All the downcomers were scaled so that the distance between the nozzle tip and the water surface was measured easily during the run (Figure 3d). L_j was adjusted by controlling the receiving pool level inside the tank. During the experimental work, a rise height (H_R) of the two-phase mixture was noticed inside the downcomer, especially for small downcomer diameter. H_R fluctuated due to the operating conditions prevailing during the plunging jet operation. For each run, three H_R measurements were recorded and averaged for the final H_R value.

4. Results and Discussion

4.1. Significance of Jet Length (L_i) and (H_R) on Final Water Jet Velocity, V_L

To illustrate the effect of L_j and H_R on V_j , V_R , and V_L , model graphs (Figures 4 and 5) called "V vs. Q_j map" were generated for this purpose. Values of V_j were selected to match the experimental ones and then used to calculate V_L and V_R using Equations (4) and (5). Figure 4 shows the effect of L_j and H_R on V_j , V_R , and V_L at $L_j = 20$ cm. Furthermore, Figure 5 shows the same effect for other L_j s (20, 40 and 60 cm), wherein a wide range of L_j , H_R , and Q_j values as well as some experimental data points of previous authors were shown.

Figure 4 clearly shows that for a fixed L_j and low jet velocity (V_j), the difference between V_L and V_j is significant ($\Delta V_{Lj} = V_L - V_j$). However, this difference decreases as V_j increases to become negligible at high V_j for a fixed L_j . This also applies to the difference between V_R and V_j ($\Delta V_{Rj} = V_R - V_j$), where the effect of V_R diminishes at small H_R . This is because of the impact of the first term (V_j^2) in Equations (4) and (5), which predominates over the other hydrostatic velocity terms [2gL_j and 2g($L_j - H_R$)], particularly at high V_j reducing the corresponding velocity differences (ΔV_{Lj} and ΔV_{Rj}) as shown in Figure 4. In contrast, ΔV_{Lj} and ΔV_{Rj} increase with L_j (Figure 5), however, to a lesser extent than V_j . At $L_j = 20$ cm, ΔV_{Lj} changes from 84% to 0.8% as the velocity of jet increases, while at $L_j = 60$ cm, the ΔV_{Lj} changes from 90% until 3% as the velocity of jet increases. As the L_j increases, in this case from 20 cm to 60 cm, the ΔV_{Lj} at the lowest flowrate point has also increased, i.e., from 84% to 90%. Also, Figure 4 shows that the difference between V_R and V_L is negligible due to small H_R compared to V_j^2 (predominant term); and hence V_R is not plotted in V vs. Qj map (Figure 5). Experimental data from selected authors were added to the "V vs. Q_j map", and some of them (Miwa et al. [24]; Current study 1, 2021; Current study 2, 2021) lay

within the map's range; however, some lay outside the map's range (Al-Anzi [3]) due to different operating conditions.



Figure 4. V_j , V_L , and V_R values at $L_j = 20$ for a wide range of Q_j and H_R .



Figure 5. V vs. Q_j map for $L_j = 20$, 40, and 60 cm. Colored points represent experimental data from different authors' studies (Miwa et al. [24]; Al-Anzi, [3]; Current study 1, 2021; Current study 2, 2021).

The ΔV_{Lj} for each L_j decreases as the flow rate increases, and it is 0.8%, 2%, and 3% for $L_j = 20, 40$, and 60, respectively, at high Q_j values.

The foregoing facts were beneficial in determining whether ΔV_{Lj} is significant for the selected range or not. The selected range for the current experimental work is indicated by the shaded area in Figure 5, which suggests that the L_j effect should be included in jet velocity calculation (V_L). Figure 6 illustrates the impact of L_j experimentally on ΔV_{Lj} for jet lengths of 25, 45, and 60 cm and a Q_j range of 100–600 cm³/s. All sets show that the difference between V_L and V_j (ΔV_{Lj}) decreases with jet flowrate and increases with jet length. For example, at a fixed L_j of 25 cm, when Q_j increases from 167–333 cm³/s, ΔV_{Lj} reduces from 42% to 13% whereas for a fixed flowrate of Qj = 167 cm³/s, when L_j changes from 25 to 45, ΔV_{Lj} increases from 42% to 72%. This confirms that the effect of the V_j term on ΔV_{Lj} predominates over that of L_j.



Figure 6. ΔV_{Lj} experimentally for (a) $L_j = 25$ cm, (b) $L_j = 45$ cm, (c) $L_j = 60$ cm.

Furthermore, a general sensitivity test is carried out experimentally to (a) measure H_R over a wide range of V_i and (b) investigate the effect of L_i on ΔV_{Li} for a selected range of V_i .

4.2. Confined Plunging Liquid Jet Reactor (CPLJR) Sensitivity Test

4.2.1. Effect of Rise Height (H_R) on Jet Velocity at the Rise Height Point (V_R)

Figure 7 below shows data sets for the 10 mm nozzle diameter and jet lengths of 25, 35, and 45 cm and downcomer diameter of 6.4. Since V_L and V_R are a function of L_j and H_R , the initial velocity is expected to vary for each L_j , as shown in the figure. Figure 7 consistently shows that H_R increases with V_L or V_R for all L_j s until it reaches a maximum and decreases except for L_j of 45 cm. At longer jet lengths, the superficial velocity of the liquid in the

downcomer (momentum) is sufficient to carry most of the entrained bubbles downwards, and hence the net entrainment rate increases (Figure 7b); a negligible fraction of the bubbles are entrained and then rise up in the recirculation eddy and disentrain at the free surface. In the regions where the gas entrainment rate increases with increasing jet length, the liquid superficial velocity is greater than about 0.20–0.25 m/s, which corresponds to a typical bubble terminal velocity. Thus, a fraction of the entrained bubbles is able to descend with the downflowing liquid exiting the bottom of the downcomer that increases net entrainment rate, which reduces the formation of H_R (Figure 7b). The maximum value (hump) for L_j of 25 and 35 cm is reached at V_j = 4.11–4.77 m/s, respectively. This slight variation is due to the L_j difference. Similar trends are observed as the downcomer diameter increases including a long jet length of 45; however, the maximum H_R value was not reached at the current jet velocity range because the system behaved as an unconfined system. Figure 7a also shows the difference between V_L and V_R (dotted lines), confirming that the H_R effect is negligible on the impact velocity values.



Figure 7. (a) H_R vs. V_R for a range of V_L and V_R cases (b) H_R vs. Q_a graph for different L_j s (25, 35, and 45 cm) for $D_c = 6.4$ cm.

4.2.2. Effect of Jet Length (L_i) on Impact Velocity (V_R)

Since V_R is the actual impact velocity of the system, although there is a negligible difference between V_R and V_L , Figure 8 is generated to show the effect of L_j on V_R for low and high jet flowrates. Figure 8a,b shows that V_R is increasing linearly with L_j for a given flowrate. Furthermore, the effect of D_c on V_R is not a simple monotonic relationship as there are other factors that contribute to the value of V_R . Such factors are disentrainment rate, jet length, jet flowrate, H_R formation, and the D_c .



Figure 8. Effect of jet length (L_j) on the velocity (V_R) for different $D_c(6.4 \text{ cm}, 7.4 \text{ cm} \text{ and } 9.4 \text{ cm})$ for (**a**) $Q_j = 167 \text{ cm}^3/\text{s}$ (**b**) $Q_j = 417 \text{ cm}^3/\text{s}$.

4.3. Comparison between Theoretical and Experimental H_R for Different Void Fraction Equations

As discussed in the previous sections, rise height (H_R) values were measured experimentally utilizing CPLJR for given operating conditions. These values were compared against predicted H_R values calculated by the momentum model Equation (11) for three void fraction Equations (2), (3) and (6). The air entrainment phenomenon is complex in CPLJR due to many factors such as eddies and vortices [3] and bubble coalescence that impacts the amount of dis/net entrainment rate. This contributes significantly to the void fraction in the downcomer. In general, high jet velocities improve the prediction of H_R for all three voidage equations. This is due to the minimization of the disentrainment term at such high velocities.

4.3.1. Effect of Downcomer Submergence Depth (H_c) on Rise Height (H_R)

To understand which of the void fraction equations were most appropriate, various experimental conditions were used, and the following graphs were generated accordingly. The effect of downcomer submergence (H_c) on H_R is depicted in Figure 9. For a D_c of 6.4 cm, the model predicts the data satisfactorily at low H_c with a better prediction for n_1 and n_3 than n_2 ; this prediction improves with V_j . However, model prediction slightly worsens for all ns as the H_c increases (doubled in this case). This is maybe due to the disentrainment phenomenon that is prevalent for longer H_c and is challenging to estimate such phenomena theoretically. Furthermore, fluctuations inside the downcomer, due to headspace pressure difference and bubble disentrainment rate [3] also contribute to the change in the H_R levels that is not accounted for in the model equation.

Figure 10 shows the relationship between H_c and H_R . As the downcomer submergence length increases, the rise height also increases for all D_c . The relationship between H_R and H_c is not a simple monotonic, because of the effect of various operating conditions at the same time (V_j , L_j , H_c and D_c).



Figure 9. Comparison of experimental H_R values with that predicted by model for $D_c = 6.4$ cm and (a) $H_c = 10$ cm and (b) $H_c = 20$ cm.



Figure 10. H_R vs. H_c for three diameters at (a) $V_j = 211$ cm/s and (b) $V_j = 527$ cm/s.

4.3.2. Effect of Diameter of Downcomer (Dc) on Rise Height (H_R)

Figure 11 shows that model prediction of H_R improves with downcomer diameter (Dc) for n_1 and n_3 . In wider downcomer (9.4 in this case), measured H_R values are insignificant (1–3 cm) as opposed to narrower ones where H_R values go up to 6 cm. Furthermore, H_R fluctuations were significantly reduced with wider downcomers that may have contributed to the accuracy of the model prediction. This can be seen clearly from Figure 11b where H_R values are insignificant compared to that of smaller downcomer diameters.



Figure 11. Comparing experimental H_R to model generated H_R for (**a**) $D_c = 7.4$ cm and (**b**) $D_c = 9.4$ cm at $H_c = 10$ cm.

5. Conclusions

The current study investigated the effect of L_j and H_R on the difference between jet velocities of CPLJR at the inception and impingement points (ΔV). In addition, a momentum balance model was developed to predict the two-phase elevation level inside the downcomer (H_R) for three void fraction equations (n). Results showed that L_j has more of an effect than H_R on ΔV and this effect is more pronounced at low jet velocity. At higher jet velocities, L_j effect wanes, leading to negligible (ΔV). The momentum model predicted H_R satisfactorily for shorter H_c and larger D_c with better predictions for n_1 and n_3 than n_2 .

Author Contributions: Conceptualization, B.S.A.-A.; methodology, B.S.A.-A.; data curation, J.F.; writing—original draft preparation, B.S.A.-A. and J.F.; writing—review and editing, B.S.A.-A. All authors have read and agreed to the published version of the manuscript.

Funding: This work has been funded by Kuwait Foundation for Advancement of Sciences (Grant no: PN1815EV07).

Institutional Review Board Statement: This study did not require any ethical approval.

Informed Consent Statement: Not applicable.

Data Availability Statement: The data in this manuscript has been generated from our laboratory experiments and is contained within the article.

Acknowledgments: The authors would like to thank Kuwait Foundation for Advancement of Sciences for their financial support through project PN1815EV07.

Conflicts of Interest: The authors declare no conflict of interest.

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