

Article

Randomized Nonuniform Sampling for Random Signals Bandlimited in the Special Affine Fourier Transform Domain

Yingchun Jiang ^{1,2,3} , Ni Gao ^{1,2,3} and Haizhen Li ^{4,*}

¹ School of Mathematics and Computing Science, Guilin University of Electronic Technology, Guilin 541002, China; guilinjiang@126.com (Y.J.); 18878747402@163.com (N.G.)

² Center for Applied Mathematics of Guangxi (GUET), Guilin 541002, China

³ Guangxi Colleges and Universities Key Laboratory of Data Analysis and Computation, Guilin 541002, China

⁴ Guilin Institute of Information Technology, Guilin 541002, China

* Correspondence: hizhen530@163.com

Abstract: The nonuniform sampling and reconstruction of bandlimited random signals in the SAFT domain is discussed in the paper, where the nonuniform samples are obtained by randomly disturbing the uniform sampling. First, we prove that the concerned nonuniform problem is equivalent to the process of uniform sampling after a prefilter in the statistic sense. Then, an approximate reconstruction method based on sinc interpolation is proposed for the randomized nonuniform sampling of SAFT-bandlimited random signals. Finally, we offer the mean square error estimate for the corresponding approximate recovery approach. The results generalize the conclusions of nonuniform sampling of bandlimited random signals in the FrFT and LCT domains to the SAFT domain.

Keywords: special affine Fourier transform; randomized nonuniform sample; bandlimited random signals; mean square error estimate; approximate recovery

MSC: 46E22; 94A20



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1. Introduction

The special affine Fourier transform (SAFT) was first proposed in [1] to model optical systems. It offers a unified viewpoint of many known signal processing transforms, such as Fourier transform (FT), fractional Fourier transform (FrFT), linear canonical transform (LCT), Laplace transform (LT), and so on. It can also include some optical operations on light waves, such as rotation, magnification, hyperbolic transformation, free space propagation, Lens transformation, and so on. The SAFT is also called the offset linear canonical transform (OLCT) since it is defined by offsetting two extra parameters on the basis of the LCT [2]. It has been proven that the SAFT is a useful tool for signal processing, communications, quantum mechanics and optics [3–6]. Many classical results such as Zak transform, Poisson summation formula, uncertainty principles, and convolution theorems are established in the SAFT domain [7–10].

We let

$$A = \begin{bmatrix} a & b & u_0 \\ c & d & \omega_0 \end{bmatrix} \quad (1)$$

be a matrix with six real parameters satisfying $ad - bc = 1$. The continuous-time SAFT associated with the parameter matrix A of signal $f(t)$ is defined as in [1],

$$F_A(u) = \text{SAFT}[f](u) = \begin{cases} \int_{-\infty}^{+\infty} f(t)K_A(t, u)dt, & b \neq 0, \\ \sqrt{d}e^{\frac{jcd(u-u_0)^2}{2}} + jw_0uf[d(u - u_0)], & b = 0, \end{cases} \quad (2)$$

where kernel function $K_A(t, u)$ is given by

$$K_A(t, u) = \sqrt{\frac{1}{2\pi j b}} e^{\frac{j d u_0^2}{2b}} e^{\frac{j}{2b} [a t^2 + 2t(u_0 - u) - 2u(du_0 - b w_0) + d u^2]} \tag{3}$$

We only restrict our attention to the case of $b \neq 0$ because case $b = 0$ is essentially a chirp multiplication. We suppose that x and k are position and wave numbers, respectively; then, it is shown in [1,7,11] that the SAFT can be understood as a general inhomogeneous lossless linear mapping in phase space as

$$\begin{bmatrix} x' \\ k' \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ k \end{bmatrix} + \begin{bmatrix} u_0 \\ \omega_0 \end{bmatrix}, \tag{4}$$

which transforms any convex body into another convex body under any linear deformations, rotations, and translations in the phase space. Condition $ad - bc = 1$ is used to guarantee that the area of the body is preserved by Transform (4). The definition in (2) is just the integral representation of the wave function transform associated with (4), which is derived by the authors in [1].

It can be verified that the inverse SAFT [12] is

$$f(t) = C \int_{-\infty}^{+\infty} F_A(u) K_{A^{-1}}(u, t) du, \tag{5}$$

where $C = e^{\frac{j}{2}(c d u_0^2 - 2 a d u_0 w_0 + a b w_0^2)}$ and

$$A^{-1} := \left[\begin{array}{cc|c} d & -b & b\omega_0 - du_0 \\ -c & a & cu_0 - a\omega_0 \end{array} \right]. \tag{6}$$

If matrix

$$A = \left[\begin{array}{cc|c} a & b & 0 \\ c & d & 0 \end{array} \right] \text{ or } A = \left[\begin{array}{cc|c} 0 & 1 & 0 \\ -1 & 0 & 0 \end{array} \right], \tag{7}$$

the SAFT reduces to LCT and FT, respectively.

Sampling and reconstruction builds a connection between the continuous signals and the discrete digital signals, which is the theoretical basis of signal and processing. Beginning with the Shannon’s sampling theorem of bandlimited signals [13], various samplings such as nonuniform sampling, average sampling, dynamic sampling, random sampling, mobile sampling, timing sampling, and multi-channel sampling have been generally studied for signals bandlimited in the FT domain [14–17]. With the appearance and developments of the more general transforms, the corresponding sampling theories are extended to the signals bandlimited in the FrFT and LCT domains [3,5,18–22]. In particular, the sampling problems associated with the SAFT have generated wide research interests in recent years due to its extensiveness and flexibility [6,7,9,12,23–25], which can include more signal models. For example, it is easy to verify that signal

$$f(t) = \text{sinc}(t) e^{-\frac{it^2}{2}} e^{-it} \tag{8}$$

is bandlimited in the SAFT domain associated with matrix

$$A = \left[\begin{array}{cc|c} 1 & 1 & 1 \\ 0.5 & 1.5 & 0 \end{array} \right]. \tag{9}$$

However, $f(t)$ is not bandlimited in the FT domain. Of course, we also must pay attention to the fact that a bandlimited signal space in the SAFT domain is not shift-invariant as

$$\text{SAFT}[f(t - \beta)](u) = e^{\frac{j}{2b}[2b\beta(a\omega_0 - cu_0) + bc\beta(2u - a\beta)]} \text{SAFT}[f](u - a\beta), \tag{10}$$

which is a different situation from the bandlimited space in the FT domain.

Signals in the real world often present random characteristics, and sampling for random signals bandlimited in the FT domain has been generally studied [16,26–28]. In recent years, there emerged a lot of research on the sampling of random signals bandlimited in the FrFT and LCT domains [29–33], including uniform sampling and nonuniform sampling. Nonuniform sampling is a more realistic sampling scheme due to the limitations of data acquisition and processing ability. Various nonuniform sampling schemes such as the periodic nonuniform model, the N -order recurrent nonuniform model, the migration of a finite number of uniform samples, and the general nonuniform mode have been considered for random signals bandlimited in the LCT domain [33], respectively. In particular, a randomized nonuniform sampling method with nonuniform samples being the random perturbations of uniform grids and a class of approximate recovery approaches by using sinc interpolation functions were studied in [30] for random signals bandlimited in the LCT domain, which extends the corresponding results in the FT and FrFT domains [22,34]. For random signals bandlimited in the SAFT domain, the multichannel uniform sampling theorems were established in [35], and the deterministic nonuniform sampling and reconstruction considered in [33] were studied in [12,36]. To the best of our knowledge, the randomized nonuniform sampling for random SAFT-bandlimited signals is still not seen. In the current paper, we study a kind of randomized nonuniform sampling method for SAFT-bandlimited random signals, which is a generalization of [22,30] from the reconstruction of random signals bandlimited in the FrFt and LCT domains to that of random signals bandlimited in the SAFT domain.

The paper is organized as follows. In Section 2, we offer the definition for the power spectral density in the SAFT domain. In Section 3, we study the nonuniform sampling scheme and propose an approximate recovery approach. In Section 4, the mean square error estimate for the proposed approximate recovery method is demonstrated.

2. Power Spectral Density in the SAFT Domain

Given probability space (Ω, \mathcal{F}, p) , $x(t)$ is called to be a wide stationary stochastic process if it has zero mean and the auto-correlation function

$$R_{xx}(t + \tau, t) = E[x(t + \tau)x^*(t)] \tag{11}$$

is independent of $t \in \mathbb{R}$, i.e., $R_{xx}(t + \tau, t) = R_{xx}(\tau)$, where $E[\cdot]$ denotes mathematical expectation and superscript $*$ stands for the complex conjugate. Two stochastic processes $x(t)$ and $y(t)$ are said to be jointly stationary if $x(t)$ and $y(t)$ are both stationary and their cross-correlation function

$$R_{xy}(t + \tau, t) = E[x(t + \tau)y^*(t)] \tag{12}$$

is independent of $t \in \mathbb{R}$, i.e., $R_{xy}(t + \tau, t) = R_{xy}(\tau)$.

The SAFT cross-correlation function, the SAFT auto-power spectral density, and the SAFT cross-power spectral density are defined as in [35]. For two random signals $x(t)$ and $y(t)$, the SAFT auto-correlation function of $x(t)$ is defined as

$$R_{xx}^A(\tau) = \lim_{T \rightarrow +\infty} \frac{1}{2T} \int_{-T}^T R_{xx}(t + \tau, t) e^{j\frac{a}{b}t\tau} dt. \tag{13}$$

Similarly, the SAFT cross-correlation function of $x(t)$ and $y(t)$ is defined as

$$R_{xy}^A(\tau) = \lim_{T \rightarrow +\infty} \frac{1}{2T} \int_{-T}^T R_{xy}(t + \tau, t) e^{j\frac{a}{b}t\tau} dt. \tag{14}$$

Remark 1. If random signal $\tilde{x}(t) = x(t)e^{j\frac{a}{2b}t^2}$ is stationary, then $x_1(t) = \tilde{x}(t)e^{j\frac{a}{b}t^2}$ is also stationary. In fact,

$$R_{x_1x_1}(t + \tau, t) = e^{j\frac{a}{b}t\tau} R_{\tilde{x}\tilde{x}}(t + \tau, t). \tag{15}$$

Moreover, one has

$$\begin{aligned}
 R_{\tilde{x}\tilde{x}}(t + \tau, t) &= E[\tilde{x}(t + \tau)\tilde{x}^*(t)] \\
 &= E\left[x(t + \tau)e^{j\frac{a}{2b}(t+\tau)^2}x^*(t)e^{-j\frac{a}{2b}t^2}\right] \\
 &= E\left[x(t + \tau)x^*(t)e^{j\frac{a}{2b}\tau^2}e^{j\frac{at\tau}{b}}\right] \\
 &= R_{xx}(t + \tau, t)e^{j\frac{at\tau}{b}}e^{j\frac{a}{2b}\tau^2}.
 \end{aligned}
 \tag{16}$$

Therefore, $R_{xx}(t + \tau, t)e^{\frac{jat\tau}{b}}$ must be independent of t . In such a case, we have

$$R_{xx}^A(\tau) = R_{x_1x_1}(\tau)e^{-j\frac{a}{2b}\tau^2}e^{-j\frac{u_0}{b}\tau}.$$
(17)

We define the SAFT auto-power spectral density of the random signal $x(t)$ by

$$P_{xx}^A(u) = \sqrt{\frac{1}{-j2\pi b}}e^{-j\frac{d}{2b}u^2}e^{-j\frac{du_0^2}{2b}}e^{j\frac{u}{b}(du_0-bw_0)}F_A\{R_{xx}^A(\tau)\}(u)$$
(18)

and the SAFT cross-power spectral density of the random signals $x(t)$ and $y(t)$ as

$$P_{xy}^A(u) = \sqrt{\frac{1}{-j2\pi b}}e^{-j\frac{d}{2b}u^2}e^{-j\frac{du_0^2}{2b}}e^{j\frac{u}{b}(du_0-bw_0)}F_A\{R_{xy}^A(\tau)\}(u).$$
(19)

It follows from (2) and (18) that

$$\begin{aligned}
 R_{xx}^A(\tau) &= C \cdot \int_{-\infty}^{+\infty} P_{xx}^A(u) \frac{1}{\sqrt{\frac{1}{-j2\pi b}}e^{j\frac{d}{2b}u^2}e^{j\frac{u}{b}(du_0-bw_0)}} \sqrt{\frac{1}{-j2\pi b}} \\
 &\quad \times e^{-j\frac{a}{2b}(bw_0-du_0)^2}e^{-j\frac{d}{2b}u^2}e^{-j\frac{u}{b}(bw_0-du_0-\tau)}e^{-j\frac{u_0}{b}\tau}e^{-j\frac{a}{2b}\tau^2}du \\
 &= C \cdot \int_{-\infty}^{+\infty} P_{xx}^A(u)e^{j\frac{d}{2b}u_0^2}e^{-j\frac{a}{2b}(bw_0-du_0)^2}e^{j\frac{u}{b}\tau}e^{-j\frac{u_0}{b}\tau}e^{-j\frac{a}{2b}\tau^2}du \\
 &= e^{\frac{j}{2}(cd u_0^2 - 2adu_0w_0 + abw_0^2)} \int_{-\infty}^{+\infty} P_{xx}^A(u)e^{j\frac{d}{2b}u_0^2}e^{-j\frac{a}{2b}(bw_0-du_0)^2}e^{j\frac{u}{b}\tau}e^{-j\frac{u_0}{b}\tau}e^{-j\frac{a}{2b}\tau^2}du \\
 &= \int_{-\infty}^{+\infty} P_{xx}^A(u)e^{-j\frac{a}{2b}\tau^2}e^{j\frac{1}{b}(u-u_0)\tau}du.
 \end{aligned}
 \tag{20}$$

We let $F_1(u) = F_A\{f_1(t)\}(u)$ and $F_2(u) = F_1(u)H(u)$. The multiplicative filtering in the SAFT domain which was introduced in [35] is demonstrated in Figure 1.

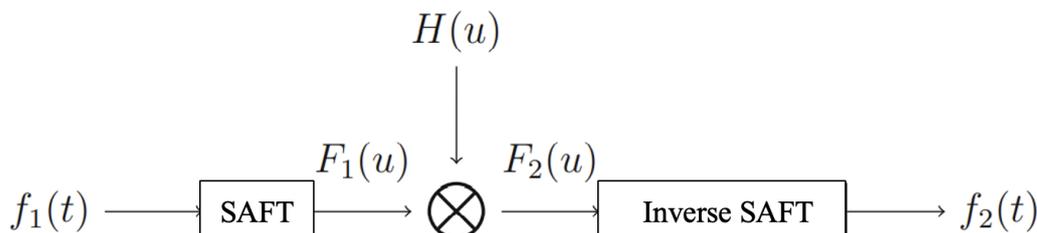


Figure 1. Multiplicative filtering in the SAFT domain.

We define normalized convolution

$$(f\Theta g)(t) = \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x)g(t-x)e^{-j\frac{a}{2b}(t^2-x^2)}dx$$
(21)

for $f, g \in L^2(\mathbb{R})$ [5]. Then, we have the following conclusion:

Proposition 1. We let

$$H(u) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{+\infty} h(t)e^{-j\frac{(u-u_0)}{b}t} dt. \tag{22}$$

Then, the multiplicative filter in Figure 1 is equivalent to

$$f_2(t) = (f_1 \ominus h)(t). \tag{23}$$

Proof. We only need to prove

$$F_A\{(f_1 \ominus h)(t)\}(u) = F_1(u)H(u). \tag{24}$$

It follows from the definition of the SAFT that \square

$$\begin{aligned} & F_A\{(f_1 \ominus h)(t)\}(u) \\ &= \int_{\mathbb{R}} (f_1 \ominus h)(t) \sqrt{\frac{1}{2\pi j b}} e^{\frac{jdu_0^2}{2b}} e^{\frac{j}{2b} [at^2 + 2t(u_0 - u) - 2u(du_0 - bw_0) + du^2]} dt \\ &= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} \int_{\mathbb{R}} f_1(x) h(t-x) e^{-j\frac{a}{2b}(t^2 - x^2)} \sqrt{\frac{1}{2\pi j b}} e^{\frac{jdu_0^2}{2b}} e^{\frac{j}{2b} [at^2 + 2t(u_0 - u) - 2u(du_0 - bw_0) + du^2]} dx dt \\ &= \int_{\mathbb{R}} f_1(x) \sqrt{\frac{1}{2\pi j b}} e^{\frac{jdu_0^2}{2b}} e^{\frac{j}{2b} [ax^2 + 2x(u_0 - u) - 2u(du_0 - bw_0) + du^2]} dx \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} h(t-x) e^{\frac{j}{b}t(u_0 - u)} e^{-\frac{j}{2b} [2x(u_0 - u)]} dt \\ &= \int_{\mathbb{R}} f_1(x) \sqrt{\frac{1}{2\pi j b}} e^{\frac{jdu_0^2}{2b}} e^{\frac{j}{2b} [ax^2 + 2x(u_0 - u) - 2u(du_0 - bw_0) + du^2]} dx \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} h(t) e^{-j\frac{(u-u_0)}{b}t} dt \\ &= F_1(u)H(u). \end{aligned} \tag{25}$$

Lemma 1 ([35]). We suppose that $x(t)$ and $y(t)$ are the input and output random signals in Figure 1, respectively; then,

$$P_{xy}^A(u) = H(u)P_{xx}^A(u) \tag{26}$$

and

$$P_{yy}^A(u) = |H(u)|^2 P_{xx}^A(u). \tag{27}$$

3. Nonuniform Sampling and Approximate Recovery

The sampling and reconstruction of random signals bandlimited in the SAFT domain based on nonuniform samples with random characteristics are studied in this section.

Definition 1 ([35]). We say that random signal $x(t)$ is SAFT-bandlimited (or bandlimited in the SAFT domain) if its SAFT power spectral density $P_{xx}^A(u)$ satisfies

$$P_{xx}^A(u) = 0, \quad |u| > u_r, \tag{28}$$

where u_r is called the bandwidth.

Lemma 2. We suppose that random signal $x(t)$ is SAFT-bandlimited with bandwidth u_r and $\tilde{x}(t) = x(t)e^{j\frac{a}{2b}t^2}$ is stationary. Then, $x_1(t)$ is FT-bandlimited with bandwidth $\frac{u_r}{b}$ and the power spectral density satisfies $\text{supp}\{P_{x_1x_1}(u)\} \subseteq [-\frac{u_r}{b}, \frac{u_r}{b}]$.

Proof. Since $x_1(t)$ is stationary, it follows from (17) and (18) that

$$\begin{aligned}
 P_{xx}^A(u) &= \sqrt{\frac{1}{-j2\pi b}} e^{-j\frac{d}{2b}u^2} e^{-j\frac{d}{2b}u_0^2} e^{j\frac{u}{b}(du_0-bw_0)} F_A\{R_{xx}^A(\tau)\}(u) \\
 &= \sqrt{\frac{1}{-j2\pi b}} e^{-j\frac{d}{2b}u^2} e^{-j\frac{d}{2b}u_0^2} e^{j\frac{u}{b}(du_0-bw_0)} F_A\{R_{x_1x_1}(\tau)e^{-j\frac{a}{2b}\tau^2} e^{-j\frac{u_0}{b}\tau}\}(u) \\
 &= \sqrt{\frac{1}{-j2\pi b}} e^{-j\frac{d}{2b}(u^2+u_0^2)} e^{j\frac{u}{b}(du_0-bw_0)} \int_{-\infty}^{+\infty} R_{x_1x_1}(\tau)e^{-j\frac{a}{2b}\tau^2} e^{-j\frac{u_0}{b}\tau} \\
 &\quad \times \sqrt{\frac{1}{2\pi j b}} e^{j\frac{du_0^2}{2b}} e^{j\frac{u}{2b}[a\tau^2+2\tau(u_0-u)-2u(du_0-bw_0)+du^2]} d\tau \\
 &= \frac{1}{2\pi b} \int_{-\infty}^{+\infty} R_{x_1x_1}(\tau)e^{-j\frac{u}{b}\tau} d\tau \\
 &= \frac{1}{2\pi b} P_{x_1x_1}\left(\frac{u}{b}\right). \tag{29}
 \end{aligned}$$

Note that $P_{xx}^A(u) = 0, |u| > u_r$. Then, the desired result is proven. \square

First, we show that the proposed nonuniform sampling is equivalent to the process of uniform sampling after a prefilter in the statistic sense.

Theorem 1. We suppose that random signal $x(t)$ is SAFT-bandlimited with bandwidth u_r and $\tilde{x}(t) = x(t)e^{j\frac{a}{2b}t^2}$ is stationary. Then, the nonuniform sampling of $x(t)$ at sampling points $t_n = nT + \xi_n$ (Figure 2) is identical to the uniform sampling after SAFT filter $h_1(t)$ as in Figure 3 in the sense of second-order statistic characters, that is,

$$R_{y_1y_1}(nT, (n - k)T) = E[R_{x_1x_1}(kT + \xi_n - \xi_{n-k})], \tag{30}$$

where $T \leq T_N = \frac{\pi b}{u_r}$, $\{\xi_n\}$ is a sequence of independent identically distributed random variables with zero mean in interval $(-T/2, T/2)$. Moreover,

$$H_1(u) = \phi_{\xi}\left(\frac{u}{b}\right) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{+\infty} h_1(t)e^{-j\frac{(u-u_0)}{b}t} dt, \tag{31}$$

and $\phi_{\xi}(u)$ denotes the characteristic function of ξ_n .

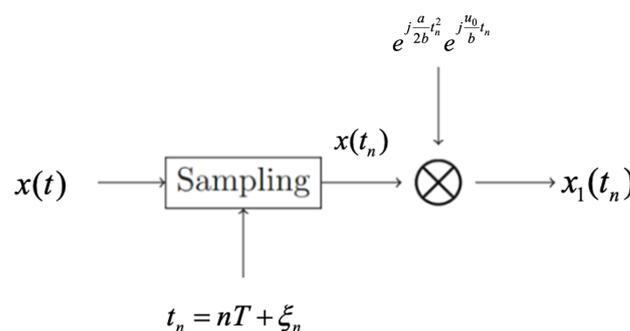


Figure 2. The nonuniform sampling process.

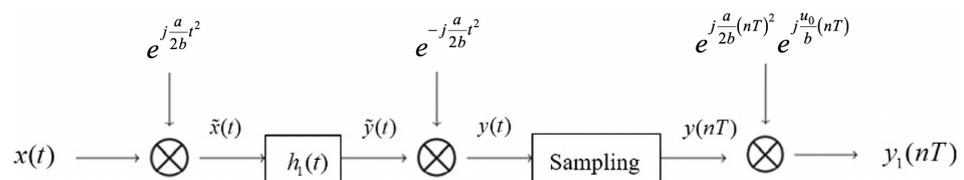


Figure 3. The equivalent system of the nonuniform sampling, where the filtering through filter $h_1(t)$ means that $\tilde{y}(t) = \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} \tilde{x}(s)h_1(t - s)ds$.

Proof. Note that $y(t) = (x \odot h_1)(t)$. Then, it follows from Lemma 1 that

$$P_{yy}^A(u) = |H_1(u)|^2 P_{xx}^A(u). \tag{32}$$

Moreover, one has

$$\begin{aligned} y_1(t) &= y(t) e^{j \frac{u_0}{2b} t^2} e^{j \frac{u_0}{b} t} \\ &= \frac{1}{\sqrt{2\pi}} e^{j \frac{u_0}{b} t} \int_{\mathbb{R}} x(s) h_1(t-s) e^{j \frac{a}{2b} s^2} ds \\ &= \frac{1}{\sqrt{2\pi}} e^{j \frac{u_0}{b} t} \int_{\mathbb{R}} \tilde{x}(s) h_1(t-s) ds. \end{aligned} \tag{33}$$

Hence, we have

$$R_{y_1 y_1}(t + \tau, t) = \frac{1}{2\pi} e^{j \frac{u_0}{b} \tau} \int_{\mathbb{R}} \int_{\mathbb{R}} h_1^*(s) R_{\tilde{x}\tilde{x}}(\tau - s' + s) h_1(s') ds' ds, \tag{34}$$

which is independent of t and $y_1(t)$ is stationary. It follows from (20) and (32) that

$$\begin{aligned} R_{yy}^A(kT) &= \int_{-u_r}^{u_r} P_{yy}^A(u) e^{-j \frac{a}{2b} (kT)^2 + j \frac{1}{b} (u-u_0) kT} du \\ &= \int_{-u_r}^{u_r} |H_1(u)|^2 P_{xx}^A(u) e^{-j \frac{a}{2b} (kT)^2 + j \frac{1}{b} (u-u_0) kT} du. \end{aligned} \tag{35}$$

This together with (17) obtains

$$\begin{aligned} R_{y_1 y_1}(nT, (n-k)T) &= R_{y_1 y_1}(kT) \\ &= R_{yy}^A(kT) e^{j \frac{a}{2b} (kT)^2} e^{j \frac{u_0}{b} kT} \\ &= e^{j \frac{a}{2b} (kT)^2} e^{j \frac{u_0}{b} (kT)} \int_{-u_r}^{u_r} |H_1(u)|^2 P_{xx}^A(u) e^{-j \frac{a}{2b} (kT)^2 + j \frac{1}{b} (u-u_0) kT} du \\ &= \int_{-u_r}^{u_r} |H_1(u)|^2 P_{xx}^A(u) e^{j \frac{u}{b} kT} du. \end{aligned} \tag{36}$$

Combining (17) and (20), we have

$$\begin{aligned} &E[R_{x_1 x_1}(kT + \zeta_n - \zeta_{n-k})] \\ &= E \left[R_{xx}^A(kT + \zeta_n - \zeta_{n-k}) e^{j \frac{a}{2b} (kT + \zeta_n - \zeta_{n-k})^2} e^{j \frac{u_0}{b} (kT + \zeta_n - \zeta_{n-k})} \right] \\ &= E \left[\int_{-u_r}^{u_r} P_{xx}^A(u) e^{-j \frac{a}{2b} (kT + \zeta_n - \zeta_{n-k})^2 + j \frac{1}{b} (u-u_0) (kT + \zeta_n - \zeta_{n-k})} du \cdot e^{j \frac{a}{2b} (kT + \zeta_n - \zeta_{n-k})^2} e^{j \frac{u_0}{b} (kT + \zeta_n - \zeta_{n-k})} \right] \\ &= E \left[\int_{-u_r}^{u_r} P_{xx}^A(u) e^{j \frac{u}{b} (kT + \zeta_n - \zeta_{n-k})} du \right] \\ &= \int_{-u_r}^{u_r} P_{xx}^A(u) e^{j \frac{u}{b} kT} E \left[e^{j \frac{u}{b} (\zeta_n - \zeta_{n-k})} \right] du. \end{aligned} \tag{37}$$

We let $Z = \zeta_n - \zeta_{n-k}$ and $f_Z(\eta)$ be its probability density function. We suppose that $f_{\zeta}(\eta)$ is the common probability density function of ζ_n and ζ_{n-k} , which are independent and have identical distributions; then,

$$f_Z(\eta) = [f_{\zeta}(\cdot) * f_{\zeta}(-\cdot)](\eta), \tag{38}$$

where $*$ denotes the convolution operator. Moreover, one has

$$\begin{aligned}
 E \left[e^{j\frac{u}{b}(\xi_n - \xi_{n-k})} \right] &= \int_{-\infty}^{+\infty} f_{\xi}(\eta) e^{j\frac{u}{b}\eta} d\eta \\
 &= \int_{-\infty}^{+\infty} [f_{\xi}(\cdot) * f_{\xi}(-\cdot)](\eta) e^{j\frac{u}{b}\eta} d\eta \\
 &= \int_{-\infty}^{+\infty} f_{\xi}(\eta) e^{j\frac{u}{b}\eta} d\eta \cdot \int_{-\infty}^{+\infty} f_{\xi}(-\eta) e^{j\frac{u}{b}\eta} d\eta \\
 &= \left| \phi_{\xi} \left(\frac{u}{b} \right) \right|^2,
 \end{aligned} \tag{39}$$

where

$$\phi_{\xi}(u) = \int_{-\infty}^{+\infty} f_{\xi}(\eta) e^{j\eta u} d\eta. \tag{40}$$

Substituting (39) into (37) obtains

$$E[R_{x_1 x_1}(kT + \xi_n - \xi_{n-k})] = \int_{-u_r}^{u_r} \left| \phi_{\xi} \left(\frac{u}{b} \right) \right|^2 P_{xx}^A(u) e^{j\frac{u}{b}kT} du. \tag{41}$$

This together with $H_1(u) = \phi_{\xi} \left(\frac{u}{b} \right)$ and (36) proves the desired result. \square

In the following, we offer an approximate recovery method for bandlimited signals in the SAFT domain based on randomized nonuniform samples.

Lemma 3 ([34]). *We suppose that random signal $x(t)$ is bandlimited in the Fourier transform domain with bandwidth $\frac{u_r}{b}$; $\{\xi_n\}$ and $\{\zeta_n\}$ are two sequences of independent identically distributed random variables with zero mean. Then, an approximate recovery formula of nonuniform sampling for random signal $x(t)$ can be represented by*

$$x''(t) = \frac{T}{T_N} \sum_{n=-\infty}^{+\infty} x(t_n) h_2(t - \tilde{t}_n), \tag{42}$$

where $h_2(t) = \text{sinc} \left(\frac{u_r t}{b} \right)$, $\text{sinc}(x) \triangleq \frac{\sin x}{x}$, $t_n = nT + \zeta_n$, and $\tilde{t}_n = nT + \xi_n$.

Theorem 2. *We suppose that random signal $x(t)$ is SAFT-bandlimited with bandwidth u_r and $\tilde{x}(t) = x(t) e^{j\frac{u_0}{2b}t^2}$ is stationary. Then, $x(t)$ can be approximated by*

$$\hat{x}(t) = \frac{T}{T_N} e^{-j\frac{u_0}{b}t} e^{-j\frac{u_0}{2b}t^2} \sum_{n=-\infty}^{+\infty} x(t_n) e^{j\frac{u_0}{2b}t_n^2} e^{j\frac{u_0}{b}t_n} h_2(t - \tilde{t}_n), \tag{43}$$

where t_n and \tilde{t}_n are as in Lemma 3.

Proof. It follows from Lemma 2 that $x_1(t)$ is FT-bandlimited with bandwidth $\frac{u_r}{b}$. By (42), one can obtain that

$$x_1''(t) = \frac{T}{T_N} \sum_{n=-\infty}^{+\infty} x_1(t_n) h_2(t - \tilde{t}_n) = \frac{T}{T_N} \sum_{n=-\infty}^{+\infty} x(t_n) e^{j\frac{u_0}{2b}t_n^2} e^{j\frac{u_0}{b}t_n} h_2(t - \tilde{t}_n) \tag{44}$$

is an approximation of $x_1(t)$. Note that $x(t) = e^{-j\frac{u_0}{b}t} e^{-j\frac{u_0}{2b}t^2} x_1(t)$. Then, $\hat{x}(t)$ in (43) is an approximate recovery approach of $x(t)$ and the proof is completed. \square

We let

$$\bar{x}(t) = \frac{T}{T_N} \sum_{n=-\infty}^{+\infty} x_1(t_n) h_2(t - \tilde{t}_n). \tag{45}$$

Figure 4 shows the approximate recovery approach based on the sinc interpolation for a SAFT-bandlimited random signal.

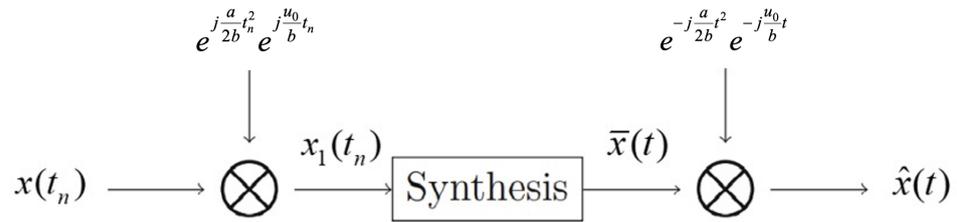


Figure 4. The approximate reconstruction of a SAFT-bandlimited random signal.

4. Error Estimate for Nonuniform Sampling

Since the reconstruction provided in Theorem 2 is an approximate method, we estimate the approximation error in this section.

Lemma 4. We let $x_1(t)$ and $y_1(t)$ be the input and output random signals of the FT multiplicative filter as in Figure 5. Then,

$$P_{y_1y_1}(u) = |\hat{h}_3(u)|^2 P_{x_1x_1}(u), \tag{46}$$

where $\hat{h}_3(u)$ is the FT of $h_3(t)$, that is,

$$\hat{h}_3(u) = \int_{\mathbb{R}} h_3(t) e^{-jut} dt. \tag{47}$$

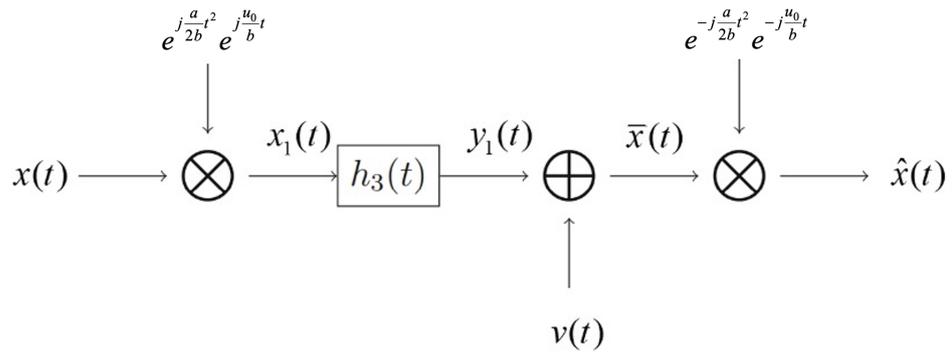


Figure 5. A system equivalent to Figure 4.

Proof. Note that $y_1(t) = \int_{-\infty}^{+\infty} x_1(t-u)h_3(u)du$. Then,

$$R_{y_1x_1}(t+\tau, t) = E[y_1(t+\tau)x_1^*(t)] = \int_{-\infty}^{+\infty} R_{x_1x_1}(\tau-u)h_3(u)du, \tag{48}$$

which is independent of t . Moreover, one has

$$R_{y_1y_1}(t+\tau, t) = E[y_1(t+\tau)y_1^*(t)] = \int_{-\infty}^{+\infty} R_{y_1x_1}(\tau+u)h_3^*(u)du. \tag{49}$$

Taking FT on both sides of (48) and (49) obtains

$$P_{y_1x_1}(u) = \hat{h}_3(u)P_{x_1x_1}(u) \tag{50}$$

and

$$P_{y_1y_1}(u) = \hat{h}_3^*(u)P_{y_1x_1}(u). \tag{51}$$

Combining (50) and (51) provides

$$P_{y_1y_1}(u) = |\hat{h}_3(u)|^2 P_{x_1x_1}(u). \tag{52}$$

□

Theorem 3. We suppose that random signal $x(t)$ is SAFT-bandlimited with bandwidth u_r and $\tilde{x}(t) = x(t)e^{j\frac{a}{2b}t^2}$ is stationary. We let $v(t)$ be an additive stationary noise with zero mean and power spectral density

$$P_{vv}(u) = T \int_{-u_r}^{u_r} P_{xx}^A(u_1) \left[1 - \left| \phi_{\xi\xi} \left(\frac{u_1}{b}, -u \right) \right|^2 \right] du_1, \quad |u| \leq \frac{u_r}{b}, \tag{53}$$

where $\phi_{\xi\xi}(s, t)$ is the joint characteristic function of random variables ξ_n and ζ_n . If $v(t)$ is uncorrelated with $x(t)$ and $\phi_{\xi\xi}(u, -u)$ is the frequency response of filter $h_3(t)$, then the model described in Figure 5 is identical to the procedure represented in Figure 4 in the sense of second-order statistic characters. Moreover,

$$E \left[|\hat{x}(t) - x(t)|^2 \right] = \int_{-u_r}^{u_r} P_{xx}^A(u) \left| 1 - \phi_{\xi\xi} \left(\frac{u}{b}, -\frac{u}{b} \right) \right|^2 du + \frac{T}{2\pi b} \int_{-u_r}^{u_r} P_{xx}^A(u) \int_{-u_r}^{u_r} \left[1 - \left| \phi_{\xi\xi} \left(\frac{u}{b}, -\frac{u_1}{b} \right) \right|^2 \right] du_1 du. \tag{54}$$

Proof. It follows from Theorem 2 that

$$\tilde{x}(t) = \hat{x}(t)e^{j\frac{u_0}{b}t}e^{j\frac{a}{2b}t^2} = \frac{T}{T_N} \sum_{n=-\infty}^{+\infty} x(t_n)e^{j\frac{a}{2b}t_n^2}e^{j\frac{u_0t_n}{b}}h_2(t - \tilde{t}_n). \tag{55}$$

Then, one has

$$R_{\tilde{x}\tilde{x}}(t, t - \tau) = \left(\frac{T}{T_N} \right)^2 E \left[\left(\sum_{n=-\infty}^{+\infty} x(nT + \xi_n)e^{j\frac{a}{2b}(nT + \xi_n)^2}e^{j\frac{u_0(nT + \xi_n)}{b}}h_2(t - nT - \xi_n) \right) \left(\sum_{k=-\infty}^{+\infty} x^*(kT + \xi_k)e^{-j\frac{a}{2b}(kT + \xi_k)^2}e^{-j\frac{u_0(kT + \xi_k)}{b}}h_2^*(t - \tau - kT - \xi_k) \right) \right] = \left(\frac{T}{T_N} \right)^2 \sum_{n=-\infty}^{+\infty} \sum_{k=-\infty}^{+\infty} E \left[R_{x_1x_1}(nT - kT + \xi_n - \xi_k)h_2(t - nT - \xi_n)h_2^*(t - \tau - kT - \xi_k) \right]. \tag{56}$$

Moreover, it can be represented by two terms as

$$R_{\tilde{x}\tilde{x}}(t, t - \tau) = \left(\frac{T}{T_N} \right)^2 R_{x_1x_1}(0) \sum_{n=-\infty}^{+\infty} E \left[h_2(t - nT - \xi_n)h_2^*(t - \tau - nT - \xi_n) \right] + \left(\frac{T}{T_N} \right)^2 \sum_{n \neq k} E \left[R_{x_1x_1}(nT - kT + \xi_n - \xi_k)h_2(t - nT - \xi_n)h_2^*(t - \tau - kT - \xi_k) \right] \triangleq I + II. \tag{57}$$

Note that $\sum_n e^{j(u_2 - u_1)nT} = 2\pi \sum_k \delta((u_2 - u_1)T - 2\pi k)$ and

$$h_2(t) = \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} H_2(u)e^{j\frac{u}{b}t} du = \frac{b}{\sqrt{2\pi}} \int_{\mathbb{R}} H_2(bu)e^{jut} du. \tag{58}$$

These together with the fact that $H_2(u) = \frac{\pi}{\sqrt{2\pi u_r}} \chi_{[-u_r, u_r]}(u)$ show that

$$I = \frac{1}{2\pi} \left(\frac{Tb}{T_N} \right)^2 R_{x_1x_1}(0) \int_{\mathbb{R}} \int_{\mathbb{R}} H_2(bu_1)H_2^*(bu_2)e^{j(u_1 - u_2)t}e^{ju_2\tau} \sum_{n=-\infty}^{+\infty} e^{j(u_2 - u_1)nT} E \left[e^{j(u_2 - u_1)\xi_n} \right] du_1 du_2 = \left(\frac{Tb}{T_N} \right)^2 R_{x_1x_1}(0) \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} \frac{1}{T} |H_2(bu)|^2 e^{ju\tau} du = T \left(\frac{b}{T_N} \right)^2 \frac{1}{2\pi} \left[\int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} P_{x_1x_1}(u_1) du_1 \right] \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} |H_2(bu)|^2 e^{ju\tau} du = \frac{T}{4\pi^2} \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} e^{ju\tau} \left[\int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} P_{x_1x_1}(u_1) du_1 \right] du. \tag{59}$$

Moreover, we have

$$\begin{aligned}
 II &= \left(\frac{bT}{2\pi T_N}\right)^2 \sum_{n \neq k} E \left[\int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} P_{x_1 x_1}(u) e^{ju(nT - kT + \zeta_n - \zeta_k)} du \int_{\mathbb{R}} H_2(bu_1) e^{ju_1(t - nT - \zeta_n)} du_1 \right. \\
 &\quad \left. \int_{\mathbb{R}} H_2^*(bu_2) e^{-ju_2(t - \tau - kT - \zeta_k)} du_2 \right] \\
 &= \left(\frac{bT}{2\pi T_N}\right)^2 \sum_{n \neq k} \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} \int_{\mathbb{R}} \int_{\mathbb{R}} P_{x_1 x_1}(u) H_2(bu_1) H_2^*(bu_2) e^{ju_2 \tau} e^{j(u_1 - u_2)t} e^{j(u - u_1)nT} e^{-j(u - u_2)kT} \\
 &\quad \cdot E \left[e^{ju\zeta_n} e^{-ju\zeta_k} e^{-ju_1\zeta_n} e^{ju_2\zeta_k} \right] du_1 du_2 du \\
 &= \left(\frac{bT}{2\pi T_N}\right)^2 \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} \int_{\mathbb{R}} \int_{\mathbb{R}} P_{x_1 x_1}(u) H_2(bu_1) H_2^*(bu_2) \phi_{\zeta\zeta}(u, -u_1) \phi_{\zeta\zeta}^*(u, -u_2) e^{ju_2 \tau} e^{j(u_1 - u_2)t} \\
 &\quad \cdot \left(\sum_n e^{j(u - u_1)nT} \right) \left(\sum_k e^{-j(u - u_2)kT} \right) du_1 du_2 du - \left(\frac{bT}{2\pi T_N}\right)^2 \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} \int_{\mathbb{R}} \int_{\mathbb{R}} P_{x_1 x_1}(u) H_2(bu_1) H_2^*(bu_2) \\
 &\quad \cdot \phi_{\zeta\zeta}(u, -u_1) \phi_{\zeta\zeta}^*(u, -u_2) e^{ju_2 \tau} e^{j(u_1 - u_2)t} \left(\sum_n e^{j(u_2 - u_1)nT} \right) du_1 du_2 du \\
 &= \left(\frac{b}{T_N}\right)^2 \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} P_{x_1 x_1}(u) |\phi_{\zeta\zeta}(u, -u)|^2 |H_2(bu)|^2 e^{ju\tau} du - \\
 &\quad \frac{T}{2\pi} \left(\frac{b}{T_N}\right)^2 \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} P_{x_1 x_1}(u_1) |\phi_{\zeta\zeta}(u_1, -u)|^2 |H_2(bu)|^2 e^{ju\tau} du_1 du \\
 &= \left(\frac{b}{T_N}\right)^2 \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} |H_2(bu)|^2 e^{ju\tau} \left[P_{x_1 x_1}(u) |\phi_{\zeta\zeta}(u, -u)|^2 - \frac{T}{2\pi} \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} P_{x_1 x_1}(u_1) |\phi_{\zeta\zeta}(u_1, -u)|^2 du_1 \right] du \\
 &= \frac{1}{2\pi} \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} e^{ju\tau} \left[P_{x_1 x_1}(u) |\phi_{\zeta\zeta}(u, -u)|^2 - \frac{T}{2\pi} \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} P_{x_1 x_1}(u_1) |\phi_{\zeta\zeta}(u_1, -u)|^2 du_1 \right] du. \tag{60}
 \end{aligned}$$

Substituting (59) and (60) into (57) obtains

$$\begin{aligned}
 R_{\bar{x}\bar{x}}(t, t - \tau) &= \frac{T}{4\pi^2} \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} \left(\int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} P_{x_1 x_1}(u_1) \left[1 - |\phi_{\zeta\zeta}(u_1, -u)|^2 \right] du_1 \right) e^{ju\tau} du \\
 &\quad + \frac{1}{2\pi} \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} e^{ju\tau} P_{x_1 x_1}(u) |\phi_{\zeta\zeta}(u, -u)|^2 du. \tag{61}
 \end{aligned}$$

Similarly, we can obtain

$$R_{\bar{x}x_1}(t, t - \tau) = \frac{1}{2\pi} \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} P_{x_1 x_1}(u) e^{ju\tau} \phi_{\zeta\zeta}(u, -u) du. \tag{62}$$

Therefore, we have

$$P_{\bar{x}\bar{x}}(u) = P_{x_1 x_1}(u) |\phi_{\zeta\zeta}(u, -u)|^2 + \frac{T}{2\pi} \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} P_{x_1 x_1}(u_1) \left[1 - |\phi_{\zeta\zeta}(u_1, -u)|^2 \right] du_1 \tag{63}$$

and

$$P_{\bar{x}x_1}(u) = P_{x_1 x_1}(u) \phi_{\zeta\zeta}(u, -u). \tag{64}$$

It follows from Lemma 4 that the first term of $P_{x_1 x_1}(u) |\phi_{\zeta\zeta}(u, -u)|^2$ in (63) is the FT power spectral density of $y_1(t)$ in Figure 5. Furthermore, since $\bar{x}(t) = y_1(t) + v(t)$ and $v(t)$ is uncorrelated with $x(t)$, then

$$\begin{aligned}
 R_{\bar{x}\bar{x}}(t + \tau, t) &= E \left[(y_1(t + \tau) + v(t + \tau))(y_1(t) + v(t))^* \right] \\
 &= R_{y_1 y_1}(t + \tau, t) + R_{y_1 v}(t + \tau, t) + R_{v y_1}(t + \tau, t) + R_{v v}(t + \tau, t) \\
 &= R_{y_1 y_1}(t + \tau, t) + R_{v v}(t + \tau, t). \tag{65}
 \end{aligned}$$

Moreover, one has

$$P_{\hat{x}\hat{x}}(u) = P_{y_1y_1}(u) + P_{vv}(u), \tag{66}$$

which shows that the second term in (63) is just the power spectral density of $v(t)$, that is,

$$\begin{aligned} P_{vv}(u) &= \frac{T}{2\pi} \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} P_{x_1x_1}(u_1) \left[1 - |\phi_{\zeta\zeta}(u_1, -u)|^2\right] du_1 \\ &= T \int_{-u_r}^{u_r} P_{xx}^A(u_1) \left[1 - \left|\phi_{\zeta\zeta}\left(\frac{u_1}{b}, -u\right)\right|^2\right] du_1, \quad |u| \leq \frac{u_r}{b}. \end{aligned} \tag{67}$$

Therefore, the model described in Figure 5 is identical to the procedure represented in Figure 4 in the sense of second-order statistic characters.

Next, we estimate $E\left[|\hat{x}(t) - x(t)|^2\right]$. Let $\varepsilon(t) = \hat{x}(t) - x(t)$. Combining (29) and (63), we obtain

$$\begin{aligned} P_{\hat{x}\hat{x}}^A(u) &= \frac{1}{2\pi b} P_{\hat{x}\hat{x}}\left(\frac{u}{b}\right) \\ &= \frac{1}{2\pi b} P_{x_1x_1}\left(\frac{u}{b}\right) \left|\phi_{\zeta\zeta}\left(\frac{u}{b}, -\frac{u}{b}\right)\right|^2 + \frac{T}{4\pi^2 b} \int_{-\frac{u_r}{b}}^{\frac{u_r}{b}} P_{x_1x_1}(u_1) \left[1 - \left|\phi_{\zeta\zeta}\left(u_1, -\frac{u}{b}\right)\right|^2\right] du_1 \\ &= P_{xx}^A(u) \left|\phi_{\zeta\zeta}\left(\frac{u}{b}, -\frac{u}{b}\right)\right|^2 + \frac{T}{2\pi b} \int_{-u_r}^{u_r} P_{xx}^A(u_1) \left[1 - \left|\phi_{\zeta\zeta}\left(\frac{u_1}{b}, -\frac{u}{b}\right)\right|^2\right] du_1. \end{aligned} \tag{68}$$

Similarly, we can obtain

$$P_{\hat{x}\hat{x}}^A(u) = P_{xx}^A(u) \phi_{\zeta\zeta}\left(\frac{u}{b}, -\frac{u}{b}\right). \tag{69}$$

In fact, it is easy to see that

$$\begin{aligned} R_{\hat{x}x_1}(t + \tau, t) &= E\left[\hat{x}(t + \tau) e^{j\frac{u_0}{b}(t+\tau)} e^{j\frac{a}{2b}(t+\tau)^2} x^*(t) e^{-j\frac{u_0}{b}t} e^{-j\frac{a}{2b}t^2}\right] \\ &= R_{\hat{x}x}(t + \tau, t) e^{j\frac{u_0}{b}\tau} e^{j\frac{a}{b}t\tau} e^{j\frac{a}{2b}\tau^2}. \end{aligned} \tag{70}$$

Therefore, $R_{\hat{x}x}(t + \tau, t) e^{j\frac{a}{b}t\tau}$ is independent of t due to (62). Then,

$$\begin{aligned} R_{\hat{x}\hat{x}}^A(\tau) &= R_{\hat{x}x}(t + \tau, t) e^{j\frac{a}{b}t\tau} \\ &= R_{\hat{x}x_1}(t + \tau, t) e^{-j\frac{u_0}{b}\tau} e^{-j\frac{a}{2b}\tau^2}. \end{aligned} \tag{71}$$

Moreover, it follows from (19) that

$$\begin{aligned} P_{\hat{x}\hat{x}}^A(u) &= \sqrt{\frac{1}{-j2\pi b}} e^{-j\frac{d}{2b}u^2} e^{-j\frac{u_0}{2b}u^2} e^{j\frac{u}{b}(du_0 - bw_0)} F_A\left\{R_{\hat{x}x_1}(\tau) e^{-j\frac{u_0}{b}\tau} e^{-j\frac{a}{2b}\tau^2}\right\}(u) \\ &= \sqrt{\frac{1}{-j2\pi b}} e^{-j\frac{d}{2b}(u^2 + u_0^2)} e^{j\frac{u}{b}(du_0 - bw_0)} \int_{-\infty}^{+\infty} R_{\hat{x}x_1}(\tau) e^{-j\frac{u_0}{b}\tau} e^{-j\frac{a}{2b}\tau^2} \sqrt{\frac{1}{2\pi j b}} e^{j\frac{du_0^2}{2b}} \\ &\quad \cdot e^{\frac{j}{2b}[a\tau^2 + 2\tau(u_0 - u) - 2u(du_0 - bw_0) + du^2]} d\tau \\ &= \frac{1}{2\pi b} \int_{-\infty}^{+\infty} R_{\hat{x}x_1}(\tau) e^{-j\frac{u}{b}\tau} d\tau \\ &= \frac{1}{2\pi b} P_{\hat{x}x_1}\left(\frac{u}{b}\right) \\ &= \frac{1}{2\pi b} P_{x_1x_1}\left(\frac{u}{b}\right) \phi_{\zeta\zeta}\left(\frac{u}{b}, -\frac{u}{b}\right) \\ &= P_{xx}^A(u) \phi_{\zeta\zeta}\left(\frac{u}{b}, -\frac{u}{b}\right). \end{aligned} \tag{72}$$

Hence, the SAFT auto-power spectral density of reconstruction error $\varepsilon(t)$ is

$$\begin{aligned}
 P_{\varepsilon\varepsilon}^A(u) &= P_{\hat{x}\hat{x}}^A(u) - P_{\hat{x}x}^A(u) - P_{x\hat{x}}^A(u) + P_{xx}^A(u) \\
 &= P_{xx}^A(u) \left| \phi_{\xi\xi} \left(\frac{u}{b}, -\frac{u}{b} \right) \right|^2 + \frac{T}{2\pi b} \int_{-u_r}^{u_r} P_{xx}^A(u_1) \left[1 - \left| \phi_{\xi\xi} \left(\frac{u_1}{b}, -\frac{u}{b} \right) \right|^2 \right] du_1 \\
 &\quad - P_{xx}^A(u) \phi_{\xi\xi} \left(\frac{u}{b}, -\frac{u}{b} \right) - \left[P_{xx}^A(u) \phi_{\xi\xi} \left(\frac{u}{b}, -\frac{u}{b} \right) \right]^* + P_{xx}^A(u) \\
 &= P_{xx}^A(u) \left| 1 - \phi_{\xi\xi} \left(\frac{u}{b}, -\frac{u}{b} \right) \right|^2 + \frac{T}{2\pi b} \int_{-u_r}^{u_r} P_{xx}^A(u_1) \left[1 - \left| \phi_{\xi\xi} \left(\frac{u_1}{b}, -\frac{u}{b} \right) \right|^2 \right] du_1, \tag{73}
 \end{aligned}$$

where we use the fact that $P_{xx}^A(u)$ is real due to (29). Note that

$$\varepsilon_1(t) = \varepsilon(t) e^{j\frac{u_0}{b}t} e^{j\frac{a}{2b}t^2} = (\hat{x}(t) - x(t)) e^{j\frac{u_0}{b}t} e^{j\frac{a}{2b}t^2} = \bar{x}(t) - x_1(t). \tag{74}$$

Then, $\varepsilon_1(t)$ is stationary. Moreover, it follows from (17) and (20) that

$$\begin{aligned}
 E \left[|\varepsilon(t)|^2 \right] &= R_{\varepsilon_1\varepsilon_1}(0) = R_{\varepsilon\varepsilon}^A(0) = \int_{-u_r}^{u_r} P_{\varepsilon\varepsilon}^A(u) du = \\
 &= \int_{-u_r}^{u_r} P_{xx}^A(u) \left| 1 - \phi_{\xi\xi} \left(\frac{u}{b}, -\frac{u}{b} \right) \right|^2 du + \frac{T}{2\pi b} \int_{-u_r}^{u_r} P_{xx}^A(u) \int_{-u_r}^{u_r} \left[1 - \left| \phi_{\xi\xi} \left(\frac{u}{b}, -\frac{u_1}{b} \right) \right|^2 \right] du_1 du. \tag{75}
 \end{aligned}$$

This completes the proof. \square

Remark 2. If ξ_n and ζ_n are equal to zero, then the sampling considered in the paper is just the classical uniform sampling. In such a case, $\phi_{\xi\xi}(s, t) \equiv 1$. Then, we know from Theorem 3 that

$$\begin{aligned}
 E \left[|\hat{x}(t) - x(t)|^2 \right] &= \int_{-u_r}^{u_r} P_{xx}^A(u) \left| 1 - \phi_{\xi\xi} \left(\frac{u}{b}, -\frac{u}{b} \right) \right|^2 du \\
 &\quad + \frac{T}{2\pi b} \int_{-u_r}^{u_r} P_{xx}^A(u) \int_{-u_r}^{u_r} \left[1 - \left| \phi_{\xi\xi} \left(\frac{u}{b}, -\frac{u_1}{b} \right) \right|^2 \right] du_1 du \\
 &= 0. \tag{76}
 \end{aligned}$$

We let $T = T_N = \frac{\pi b}{u_r}$. The approximation of $x(t)$ given in (43) reduces to

$$\hat{x}(t) = e^{-j\frac{a}{2b}t^2} \sum_{n=-\infty}^{+\infty} x(nT) e^{j\frac{a}{2b}(nT)^2} e^{j\frac{u_0}{b}(nT-t)} \text{sinc} \left(\frac{u_r(t-nT)}{b} \right), \tag{77}$$

which is just Theorem 3 in [35].

Remark 3. We provide a reconstruction method based on sinc interpolation for random signals bandlimited in the SAFT domain, which is theoretically similar to that for the classical bandlimited signals in the FT domain. However, the the numerical performance may show a different case, because the strong and rapid oscillations of the chirp-modulation multiplier in the SAFT background may cause instability against a minor jitter error. As we showed in (10), a bandlimited signal space in the SAFT domain is not shift-invariant, which may require an additional step to identify both the chirp and shift parameters from the data. However, although the support of the band-limitedness is changed and the bandwidth could increase, a modest amount of oversampling can make up the effects of missing the exact determination of the offset parameters to the reconstruction, because a small shift of the signal only leads to a slight disturbance to the support in the SAFT domain.

5. Conclusions

Since the six-parameter SAFT has more flexibility relative to the four-parameter LCT and can accommodate more signal models, we extend the sampling theory with samples being the randomized perturbation of the classical uniform scheme from the FrFT and LCT backgrounds to the SAFT-bandlimited random signals. We show that the proposed

nonuniform model is equivalent to the uniform sampling after a pre-filter in the statistic sense. Moreover, an approximate recovery method based on the sinc functions and the corresponding error analysis in the sense of mean square convergence are given for random signals bandlimited in the SAFT domain.

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