



# Article Liouville-Type Theorem for Nonlinear Elliptic Equations Involving Generalized Greiner Operator

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**Abstract:** In this paper, we study the Liouville-type behaviors of the generalized Greiner operators with nonlinear boundary value conditions. We use the technique based upon the method of moving planes.

Keywords: Liouville-type theorem; moving plane; Greiner operator; nonlinear equations

MSC: 35J60; 35H20

## 1. Introduction

The purpose of this paper is to investigate Liouville properties for semi-linear elliptic equation with general nonlinearity

$$\begin{cases} \Delta_L u + f(u) = 0, \text{ in } \mathbb{R}^{2n+1}, \\ -\frac{\partial u}{\partial t} = g(u), \text{ on } \partial \mathbb{R}^{2n+1}_+ \setminus \{0\}, \end{cases}$$
(1)

where  $\Delta_L$  is the generalized Greiner operator, and f, g are nonnegative functions satisfying some appropriate conditions, which will be given later. The notation  $\partial \mathbb{R}^{2n+1}_+$  denotes the boundary of set  $\mathbb{R}^{2n+1}_+ = \{(x, y, t) \in \mathbb{R}^{2n+1} | t > 0\}$ . It is well known that the role played by the Liouville theorem is to establish a priori bounds for positive solutions of elliptic equations in bounded domains via the blow-up method.

Han and Zhao [1] studied a class of semi-linear elliptic equations with the principal part constructed by generalized Greiner vector fields, introducing the vector field method in their work. As an application, they studied the Liouville property of the following semi-linear equation:

$$\Delta_L u + h(\xi) u^p = 0, \tag{2}$$

on the generalized Greiner vector fields.

There are analogous results in the Euclidean case. In the splendid paper [2], Gidas and Spruck used the method of integral estimate to prove that, for  $1 , the following Equation (3) has no positive entire solution in the Euclidean space <math>\mathbb{R}^n$ :

$$-\Delta u = u^q. \tag{3}$$

Similar results first appear in [3] using the main tools of the method of moving planes. Furthermore, the Liouville-type theorem for integral equation and system was established in paper [4]. Other results can be found in [5–9].

Recently, some Liouville-type theorems were obtained even for nonlinear elliptic equations with nonlinear boundary conditions in the Heisenberg group; see Theorem 1.1 in [10].

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**Copyright:** © 2022 by the author. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). In addition to using the method of moving planes, the vector field method was also used to prove nonexistence results. Xu [11] obtained the nonexistence result on the Heisenberg group for the following equation:

$$\Delta_H u + h(x)u^p = 0, \text{ in } H^n, \tag{4}$$

and, supposing that weight function h(x) satisfies some assumptions, then Equation (4) possesses no positive solutions providing  $1 . We note that the exponent <math>1 + \frac{8n+7}{(2n+1)^2}$  is smaller than  $\frac{9+2}{2}$ .

 $1 + \frac{8n+7}{(2n+1)^2}$  is smaller than  $\frac{Q+2}{Q-2}$ .

Yu [6] studied the following elliptic equation:

$$\begin{cases} -\Delta u = f(u), \text{ in } \mathbb{R}^N_+, \\ -\frac{\partial u}{\partial \nu} = g(u), \text{ on } \partial \mathbb{R}^N_+. \end{cases}$$
(5)

He proved that this problem possess no positive solutions under some assumptions on nonlinear terms.

In recent years, the comparison principle and Liouville-type theorems for degenerate elliptic equations have been widely studied; see [12–16]. The Liouville-type theorem for cylindrical viscosity solutions of fully nonlinear CR invariant equations on the Heisenberg group were developed in [17]. As a by-product, the comparison principle with finite singularities for viscosity solutions to more general fully nonlinear operators on the Heisenberg group was obtained in [17].

The Hopf-type lemma and a CR type inversion for the generalized Greiner operator was first and extensively established in [18].

In this paper, we study problem (1); it is very well known that both the equation and the boundary conditions are nonlinear. We are now ready to state the main result.

**Theorem 1.** Let  $u \in C(\mathbb{R}^{2n+1})$  be a nonnegative cylindrical solution for problem (1), and  $f, g : [0, +\infty) \rightarrow [0, +\infty)$  are continuous functions satisfying (i) f(t), g(t) are nondecreasing in  $(0, +\infty)$ , (ii)  $h(t) = \frac{f(t)}{Q+2}, l(t) = \frac{g(t)}{t^{\frac{4k}{Q+2}}}$  are nonincreasing in  $(0, +\infty)$ , (iii) either h or l is not a constant, then  $u \equiv c$  with f(c) = g(c) = 0 is the only solution of the problem (1).

The paper is organized as follows. In Section 2, we introduced some notations and facts that will be followed throughout the work. Theorem 1 is finally proved in Section 3. The disscussion is given in Section 4.

## 2. Preliminary Facts

The aim of this section is to introduce some notation and definitions about the generalized Greiner vector fields. We consider the Liouville property associated with generalized Greiner operators

$$\Delta_L = \sum_{j=1}^n (X_j^2 + Y_j^2),$$

where

$$X_j = \frac{\partial}{\partial x_i} + 2ky_j |z|^{2k-2} \frac{\partial}{\partial t},\tag{6}$$

$$Y_j = \frac{\partial}{\partial y_j} - 2kx_j |z|^{2k-2} \frac{\partial}{\partial t},\tag{7}$$

$$j = 1, \cdots, n, x, y \in \mathbb{R}^n, t \in \mathbb{R}, z = x + \sqrt{-1}y, |z| = \left[\sum_{j=1}^n (x_j^2 + y_j^2)\right]^{\frac{1}{2}}, k \ge 1.$$

A function *u* is said to be cylindrical in  $\mathbb{R}^{2n+1}$  with respect to the operator  $\Delta_L$  if for any  $(x, y, t) \in \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}$ , it has u(x, y, t) = u(r, t),  $r = \sqrt{x^2 + y^2}$ .

If we denote by  $\mathbf{A} = (a_{ij})$  the  $(2n + 1) \times (2n + 1)$  symmetric matrix given by  $a_{ij} = \delta_{ij}$ if  $i, j = 1, \dots, 2n$ ,  $a_{2n+1,j} = 2ky_j |z|^{2k-2}$  if  $j = 1, \dots, n$ ,  $a_{2n+1,n+j} = -2kx_j |z|^{2k-2}$  if  $j = 1, \dots, n$ , and  $a_{2n+1,2n+1} = 4k^2 |z|^{4k-2}$ . We note that the matrix  $\mathbf{A}$  is related to  $\Delta_L$  by the formula

$$\Delta_L = \operatorname{div}(\mathbf{A}\nabla)_L$$

where  $\nabla$  and div denote the Euclidian gradient and Euclidian divergence operator of  $\mathbb{R}^{2n+1}$ , respectively.

Moreover, if we consider a  $(2n) \times (2n + 1)$  matrix whose rows are the coordinates of the vector field  $X_i$ ,  $Y_j$ , that is

$$\sigma := \begin{pmatrix} I_n & 0 & 2ky|z|^{2k-2} \\ 0 & I_n & -2kx|z|^{2k-2} \end{pmatrix},$$

where  $I_n$  is the identity  $n \times n$  matrix, then the generalized gradient  $\nabla_L$  of a function  $\psi : \mathbb{R}^{2n+1} \to \mathbb{R}$  is expressed by  $\nabla_L \psi = (X_1 \psi, \cdots, X_n \psi, Y_1 \psi, \cdots, Y_n \psi) = \sigma \nabla \psi$ , and

$$\Delta_L = \operatorname{div}(\sigma^T \sigma \nabla).$$

The dilation is defined as

$$\delta_{\lambda}(\xi) = (\lambda x, \lambda y, \lambda^{2k} t), \lambda > 0, \tag{8}$$

and the integer Q = 2n + 2k is called the homogeneous dimension with respect to dilation. Then, it is useful to consider the following homogeneous norm with respect to (8):

$$\rho(\xi) = \left[ |z|^{4k} + t^2 \right]^{\frac{1}{4k}},\tag{9}$$

and the associated quasi distance between two point  $\xi$ ,  $\eta$  in  $\mathbb{R}^{2n+1}$  by setting

$$d(\xi,\eta) = \left[ |z|^{4k} + |z'|^{4k} + (t-t')^2 \right]^{\frac{1}{4k}},\tag{10}$$

for  $\xi = (z, t) \in \mathbb{R}^{2n+1}$ ,  $\eta = (z', t') \in \mathbb{R}^{2n+1}$ . We denote by  $B_L(\xi, R)$  the quasi ball with center at  $\xi$  and radius R associated with the distance (10), that is

$$B_L(\xi, R) = \{ \eta \in \mathbb{R}^{2n+1} | d(\xi, \eta) < R \}.$$
(11)

Note that for R > 0 sufficiently large, if B(0, R) is the Euclidian ball of radius R centered at the origin, then

$$B(0,R) \subset B_L(0,R) \subset B(0,R^2).$$

Denote by

$$\nabla_L u = (X_1 u, \cdots, X_n u, Y_1 u, \cdots, Y_n u),$$

and

$$\Delta_L u := \sum_{j=1}^n X_j^2 u + Y_j^2 u$$
  
=  $\sum_{j=1}^n \frac{\partial^2 u}{\partial x_j^2} + \frac{\partial^2 u}{\partial y_j^2} + 4ky_j |z|^{2k-2} \frac{\partial^2 u}{\partial x_j \partial t} - 4kx_j |z|^{2k-2} \frac{\partial^2 u}{\partial y_j \partial t}$   
+  $4k^2 |z|^{4k-2} \frac{\partial^2 u}{\partial t^2}$ , (12)

the generalized gradient and the generalized Greiner operator, respectively.

Note that, when k = 1, the operator  $\Delta_L$  becomes the well know sub-Laplacian  $\Delta_{H^n}$  on the Heisenberg group  $H^n$  (see Folland [19]). If  $k = 2, 3, \dots, \Delta_L$  is the Greiner operator (see [20]). As is well known, the vector fields  $X_1, X_2, \dots, X_n, Y_1, Y_2, \dots, Y_n$  in (6) do not possess left translation invariance for k > 1 and, if  $k = 1, 2, 3, \dots$ , they do not meet the Hörmander condition [21].

As in [18], we introduce the CR inversion of a function u(x, y, t) in  $\mathbb{R}^{2n+1}$  as

$$v(x,y,t) = \frac{1}{\rho^{Q-2}} u(\tilde{x}, \tilde{y}, \tilde{t}), \tag{13}$$

with  $\tilde{x} = (\tilde{x_1}, \cdots, \tilde{x_n})$  and  $\tilde{y} = (\tilde{y_1}, \cdots, \tilde{y_n})$ , where

$$\tilde{x}_i = rac{x_i t + |z|^{2k} y_i}{
ho^{2k+2}}, \ \tilde{y}_i = rac{y_i t - |z|^{2k} x_i}{
ho^{2k+2}}, \ \tilde{t} = rac{1}{
ho^{4k}}$$

**Lemma 2.** Suppose that  $u \in C^2(\mathbb{R}^{2n+1}_+) \cap C(\overline{\mathbb{R}^{2n+1}_+})$  is a solution of (1), then v defined in (13) satisfies

$$\begin{cases} \Delta_L v = \frac{1}{\rho^{Q+2}} f(u), & \text{in } \mathbb{R}^{2n+1}, \\ -\frac{\partial v}{\partial t} = \frac{1}{\rho^{Q+4k-2}} g(u), & \text{on } \partial \mathbb{R}^{2n+1}_+ \setminus \{0\}. \end{cases}$$
(14)

**Proof.** The first equation of this lemma has been proved in [18]. It remains to prove the second equation. In fact,

$$-\lim_{t \to 0} \frac{\partial v}{\partial t} = -\lim_{\tilde{t} \to 0} \frac{1}{\rho^{Q-2}} \rho^{-4k} \frac{\partial u(\tilde{x}, \tilde{y}, \tilde{t})}{\partial \tilde{t}}$$
$$= \frac{1}{\rho^{Q+4k-2}} g(u).$$
(15)

## 3. Proof of Theorem 1

The proof of Theorem 1 uses the moving plane argument. Note that the function v might be singular at the origin and that

$$\lim_{\rho \to 0} \rho^{Q-2} v(r,t) = u(0).$$
(16)

We have previously seen that v satisfies the equation

$$\begin{cases} -\Delta_L v(x,y,t) = \frac{1}{\rho^{Q+2}} f(\rho^{Q-2} v(x,y,t)), & \text{in } \mathbb{R}^{2n+1} \setminus \{0\}, \\ -\frac{\partial v(x,y,t)}{\partial t} = \frac{1}{\rho^{Q+4k-2}} g(\rho^{Q-2} v(x,y,t)) & \text{on } \partial \mathbb{R}^{2n+1} \setminus \{0\}. \end{cases}$$

$$(17)$$

We define  $h(t) = \frac{f(t)}{t^{Q+2}}$ ,  $l(t) = \frac{g(t)}{t^{Q+4k-2}}$ , and we obtain

$$f(\rho^{Q-2}v) = h(\rho^{Q-2}v)\rho^{Q+2}v^{\frac{Q+2}{Q-2}}$$

and

$$g(\rho^{Q-2}v) = l(\rho^{Q-2}v)\rho^{Q+4k-2}v^{\frac{Q+4k-2}{Q-2}},$$

then, the above equation can also be written as

$$\begin{cases} -\Delta_L v(x, y, t) = h(\rho^{Q-2}v(x, y, t))v(x, y, t)^{\frac{Q+2}{Q-2}}, & \text{in } \mathbb{R}^{2n+1} \setminus \{0\}, \\ -\frac{\partial v(x, y, t)}{\partial t} = l(\rho^{Q-2}v(x, y, t))v(x, y, t)^{\frac{Q+4k-2}{Q-2}}, & \text{on } \partial \mathbb{R}^{2n+1} \setminus \{0\}. \end{cases}$$
(18)

Let  $\Sigma_{\mu} = \{(x, y, t) \in \mathbb{R}^{2n+1} | t \ge \mu\}$ ,  $T_{\mu} = \partial \Sigma_{\mu} = \{(x, y, t) \in \mathbb{R}^{2n+1} | t = \mu\}$ , and  $p^{\mu} = (0, 0, 2\mu)$ . We compare the values of the solution v on  $\Sigma_{\mu}$  with those on its reflection. Let

$$v_{\mu}(x,y,t) = v_{\mu}(r_0,t) = v(r_0,2\mu-t) = v(y,x,2\mu-t),$$

for any (x, y) such that  $(x^2 + y^2)^{\frac{1}{2}} = r_0$ . It is easy to see that  $v_{\mu}$  satisfies the same equation as v does, that is

$$\begin{cases} -\Delta_L v_{\mu}(x,y,t) = h(\rho_{\mu}^{Q-2}v_{\mu}(x,y,t))v_{\mu}(x,y,t)^{\frac{Q+2}{Q-2}}, & \text{in } \mathbb{R}^{2n+1} \setminus \{0\}, \\ -\frac{\partial v_{\mu}(x,y,t)}{\partial t} = l(\rho_{\mu}^{Q-2}v_{\mu}(x,y,t))v_{\mu}(x,y,t)^{\frac{Q+4k-2}{Q-2}}, & \text{on } \partial \mathbb{R}^{2n+1} \setminus \{0\}. \end{cases}$$
(19)

If we define  $w_{\mu}(\xi) = v_{\mu}(\xi) - v(\xi)$ , then we can get the following key lemma.

**Lemma 3.** For any fixed  $\mu > 0$ , the function  $v_{\mu}, v \in L^{2^{\sharp}}(\Sigma_{\mu}) \cup L^{\infty}(\Sigma_{\mu})$  with  $2^{\sharp} = \frac{2Q}{Q-2}$ . Furthermore, there exists  $C_{\mu} > 0$ , which is nonincreasing in  $\mu$ , such that

$$\int_{\Sigma_{\mu}} |\nabla_L (v - v_{\mu})^+|^2 d\xi$$

$$\leq C_{\mu} \left[ \left( \int_{A_{\mu}} \frac{1}{\rho^{2Q}} d\xi \right)^{\frac{2}{Q}} + \left( \int_{B_{\mu}} \frac{1}{\rho^{2kQ}} d\xi \right)^{\frac{2}{Q}} \right] \left( \int_{\Sigma_{\mu}} |\nabla_L (v - v_{\mu})^+|^2 d\xi \right), \tag{20}$$

where  $A_{\mu} = \{(x, y, t) \in \Sigma_{\mu} | v > v_{\mu}\}, B_{\mu} = \{(x, y, t) \in \partial \Sigma_{\mu} | v > v_{\mu}, t = 0\}.$ 

**Proof.** If  $\mu > 0$ , then there exists r > 0, such that  $\Sigma_{\mu} \subset \mathbb{R}^{2n+1} \setminus B_r(0)$ ; moreover, v is continuous and strictly positive in  $\mathbb{R}^{2n+1} \setminus \{0\}$ , with a possible singularity at the origin, and decays at infinity as  $u(0)\rho^{2-Q}$ , so that  $v \in L^{2^{\sharp}} \cap L^{\infty}(\Sigma_{\mu})$ . Now, we give a cylinder cut-off function  $0 \leq \eta_{\epsilon} \leq 1$ , such that

$$\eta_{\epsilon} = \begin{cases} 1, & \text{if } 2\epsilon \leq |\xi - p^{\mu}| \leq \frac{1}{\epsilon}, \\ 0 & \text{if } |\xi - p^{\mu}| \leq \epsilon \text{ or } |\xi - p^{\mu}| \geq \frac{2}{\epsilon}, \end{cases}$$
(21)

$$\begin{split} |\nabla_L \eta_{\epsilon}| &\leq \frac{C}{\epsilon} \text{ for } \epsilon < |\xi - p^{\mu}| \leq 2\epsilon \text{ and } |\nabla_L \eta_{\epsilon}| \leq C\epsilon \text{ for } \frac{1}{\epsilon} \leq |\xi - p^{\mu}| \leq \frac{2}{\epsilon}.\\ \text{Next, } \psi &= \eta_{\epsilon} (v - v_{\mu})^+ \text{ can be used as a test function, and we denote } \phi = \eta_{\epsilon}^2 (v - v_{\mu})^+; \end{split}$$

Next,  $\psi = \eta_{\epsilon}(v - v_{\mu})^+$  can be used as a test function, and we denote  $\phi = \eta_{\epsilon}^2(v - v_{\mu})^+$ ; then we have

$$\int_{\Sigma_{\mu} \cap \{2\epsilon \leq |\xi - p^{\mu}| \leq \frac{1}{\epsilon}\}} |\nabla_{L}(v - v_{\mu})^{+}|^{2} d\xi \leq \int_{\Sigma_{\mu}} |\nabla_{L}\psi|^{2} d\xi \\
= \int_{\Sigma_{\mu}} \nabla_{L}(v - v_{\mu})^{+} \nabla_{L}\phi d\xi + \int_{\Sigma_{\mu}} [(v - v_{\mu})^{+}]^{2} |\nabla_{L}\eta_{\epsilon}|^{2} d\xi \\
= \int_{A_{\mu}} -\Delta_{L}(v - v_{\mu})\phi d\xi + \int_{B_{\mu}} \frac{\partial(v - v_{\mu})}{\partial v}\phi d\xi' + I_{\epsilon} \\
= \int_{A_{\mu}} \left[ h(\rho^{Q-2}v)v^{\frac{Q+2}{Q-2}} - h(\rho^{Q-2}v_{\mu})v^{\frac{Q+2}{Q-2}}_{\mu} \right] \phi d\xi \\
+ \int_{B_{\mu}} \left[ l(\rho^{Q-2}v)v^{\frac{Q+4k-2}{Q-2}} - l(\rho^{Q-2}v_{\mu})v^{\frac{Q+4k-2}{Q-2}}_{\mu} \right] \phi d\xi' + I_{\epsilon},$$
(22)

where  $I_{\epsilon} = \int_{\Sigma_{\mu}} [(v - v_{\mu})^+]^2 |\nabla_L \eta_{\epsilon}|^2 d\xi.$ 

Due to the monotonicity of  $h, l, \rho > \rho_{\mu}$  and  $v(\xi) > v_{\mu}(\xi)$  in  $A_{\mu}$  and  $B_{\mu}$ , we have

$$h(\rho^{Q-2}v) \le h(\rho_{\mu}^{Q-2}v_{\mu}),$$
 (23)

and

$$l(\rho^{Q-2}v) \le l(\rho^{Q-2}_{\mu}v_{\mu}),$$
 (24)

in  $A_{\mu}$  and  $B_{\mu}$ , respectively. Hence, we get

$$\int_{\Sigma_{\mu} \cap \{2\epsilon \leq |\xi - p^{\mu}| \leq \frac{1}{\epsilon}\}} |\nabla_{L}(v - v_{\mu})^{+}|^{2} d\xi \\
\leq \int_{A_{\mu}} h(\rho^{Q-2}v) [v^{\frac{Q+2}{Q-2}} - v^{\frac{Q+2}{Q-2}}_{\mu}] \phi d\xi \\
+ \int_{B_{\mu}} l(\rho^{Q-2}v) [v^{\frac{Q+4k-2}{Q-2}} - v^{\frac{Q+4k-2}{Q-2}}_{\mu}] \phi d\xi' + I_{\epsilon}.$$
(25)

Moreover, since *u* is positive and bounded, there exists  $0 < a = a_{\mu} < b = b_{\mu} < +\infty$  such that  $a < \rho^{Q-2}v(\xi) = u(\xi) < b, \forall \xi, \xi \in \Sigma_{\mu} \setminus B_r(0)$ , so that  $h(\rho^{Q-2}v(\xi)) \le h(a_{\mu}) =: C^1_{\mu}$ . Finally, if  $0 \le v_{\mu} \le v$ , we conclude that

$$\begin{split} &\int_{A_{\mu}} h(\rho^{Q-2}v) [v^{\frac{Q+2}{Q-2}} - v^{\frac{Q+2}{Q-2}}_{\mu}] \phi d\xi \leq C^{1}_{\mu} \int_{A_{\mu}} v^{\frac{4}{Q-2}} (v - v_{\mu}) \phi d\xi \\ &\leq C^{1}_{\mu} \int_{A_{\mu}} \frac{1}{\rho^{4}} [(v - v_{\mu})^{+}]^{2} \eta^{2}_{\epsilon} d\xi \\ &\leq C^{1}_{\mu} (\int_{A_{\mu}} \frac{1}{\rho^{2Q}} d\xi)^{\frac{Q}{Q}} (\int_{\Sigma_{\mu}} [(v - v_{\mu})^{+}]^{\frac{2Q}{Q-2}} d\xi)^{\frac{Q-2}{Q}}, \end{split}$$
(26)

in the last inequality, we have used the Hölder's inequality.

Similarly, by the decay estimate of v, there exists  $C_{\mu}^2 > 0$ , which is nonincreasing in  $\mu$ , so that

$$\int_{B_{\mu}} l(\rho^{Q-2}v) [v^{\frac{Q+4k-2}{Q-2}} - v^{\frac{Q+4k-2}{Q-2}}_{\mu}] \phi d\xi' \leq C_{\mu}^{2} \int_{B_{\mu}} v^{\frac{4k}{Q-2}} (v - v_{\mu}) \phi d\xi' \\
\leq C_{\mu}^{2} \int_{B_{\mu}} \frac{1}{\rho^{4k}} [(v - v_{\mu})^{+}]^{2} \eta_{\epsilon}^{2} d\xi' \\
\leq C_{\mu}^{2} (\int_{B_{\mu}} \frac{1}{\rho^{2kQ}} d\xi')^{\frac{2}{Q}} (\int_{\Sigma_{\mu}} [(v - v_{\mu})^{+}]^{\frac{2Q}{Q-2}} d\xi')^{\frac{Q-2}{Q}}.$$
(27)

Therefore, it follows from the above inequalities that

$$\int_{\Sigma_{\mu} \cap \{2\epsilon \le |\xi - p_{\mu}| \le \frac{1}{\epsilon}\}} |\nabla_{L}(v - v_{\mu})^{+}|^{2} d\xi \\
\leq C_{\mu}^{1} \left(\int_{A_{\mu}} \frac{1}{\rho^{2Q}} d\xi\right)^{\frac{2}{Q}} \left(\int_{\Sigma_{\mu}} [(v - v_{\mu})^{+}]^{\frac{2Q}{Q-2}} d\xi\right)^{\frac{Q-2}{Q}} \\
+ C_{\mu}^{2} \left(\int_{B_{\mu}} \frac{1}{\rho^{2kQ}} d\xi\right)^{\frac{2}{Q}} \left(\int_{\partial\Sigma_{\mu}} [(v - v_{\mu})^{+}]^{\frac{2Q}{Q-2}} d\xi'\right)^{\frac{Q-2}{Q}} + I_{\epsilon}.$$
(28)

We claim now that  $I_{\epsilon} \rightarrow 0$  as  $\epsilon \rightarrow 0$ . If we denote

$$B_{\epsilon} = \{\xi \in \Sigma_{\mu} | \epsilon < |\xi - p^{u}| < 2\epsilon \text{ or } rac{1}{\epsilon} < |\xi - p^{u}| < rac{2}{\epsilon}\},$$

then we get

$$\int_{B_{\epsilon}} |\nabla_L \eta_{\epsilon}| d\xi \leq C.$$

Hence, we infer from Hölder's inequality that

$$I_{\epsilon} \leq \left(\int_{B_{\epsilon}} [(v-v_{\mu})^{+}]^{2^{\sharp}} d\xi\right)^{\frac{2}{2^{\sharp}}} \left(\int_{B_{\epsilon}} |\nabla_{L}\eta_{\epsilon}|^{Q} d\xi\right)^{\frac{2}{Q}} \leq C \left(\int_{B_{\epsilon}} [(v-v_{\mu})^{+}]^{2^{\sharp}} d\xi\right)^{\frac{2}{2^{\sharp}}} \to 0,$$

as  $\epsilon \to 0$  because  $(v - v_{\mu})^+ \in L^{2^{\sharp}}(\Sigma_{\mu})$ .

Finally, suppose for some  $\epsilon \to 0$  in Equation (28), and set  $C_{\mu} = C_{\mu}^{1}S + C_{\mu}^{2}S_{T}$  with *S* being the Sobolev constant and  $S_{T}$  being the Sobolev trace inequality constant, then we obtain

$$\int_{\Sigma_{\mu}} |\nabla_{L}(v - v_{\mu})^{+}|^{2} d\xi 
\leq C_{\mu} \left[ \left( \int_{A_{\mu}} \frac{1}{\rho^{2Q}} d\xi \right)^{\frac{2}{Q}} + \left( \int_{B_{\mu}} \frac{1}{\rho^{2kQ}} d\xi' \right)^{\frac{2}{Q}} \right] \left( \int_{\Sigma_{\mu}} |\nabla_{L}(v - v_{\mu})^{+}|^{2} d\xi \right).$$
(29)

We note that inequality (29) plays the same role as the maximum principle. If we can prove

$$C_{\mu}\left[\left(\int_{A_{\mu}}\frac{1}{\rho^{2\mathbb{Q}}}d\xi\right)^{\frac{2}{\mathbb{Q}}}+\left(\int_{B_{\mu}}\frac{1}{\rho^{2k\mathbb{Q}}}d\xi'\right)^{\frac{2}{\mathbb{Q}}}\right]<1,$$

then we get  $v \leq v_{\mu}$  in  $\Sigma_{\mu}$ , the same conclusion as the maximum principle implies.

The next lemma shows that

$$w_{\mu}(\xi) = v_{\mu}(\xi) - v(\xi) \ge 0, \forall \xi \in \Sigma_{\mu}.$$
(30)

**Lemma 4.** Under the assumptions of Theorem 1, there exists some  $\mu_0 > 0$ , such that  $v \le v_{\mu}$  in  $\Sigma_{\mu}$  for all  $\mu > \mu_0$ .

**Proof.** By the decay behavior of *v*, see Equation (16), we can choose  $\mu_0$  large enough such that

$$C_{\mu}\left[\left(\int_{A_{\mu}}\frac{1}{\rho^{2Q}}d\xi\right)^{\frac{2}{Q}}+\left(\int_{B_{\mu}}\frac{1}{\rho^{2kQ}}d\xi\right)^{\frac{2}{Q}}\right]\leq\frac{1}{2},$$

then Equation (29) implies that

$$\int_{\Sigma_{\mu}} |\nabla_L (v - v_{\mu})^+|^2 d\xi = 0,$$

the assertion follows.  $\Box$ 

We now decrease the value of  $\mu$  continuously, that is, we move the plane  $\Sigma_{\mu}$  to the left as long as inequality (30) holds. We show that by moving in this way, the plane will not stop before hitting the origin. More precisely, let

$$\mu_1 = \inf\{\mu | w_\mu(\xi) \ge 0, \forall \xi \in \Sigma_{\bar{\mu}}, \bar{\mu} \ge \mu\}.$$

**Lemma 5.** If  $\mu_1 > 0$ , then  $w_{\mu_1}(\xi) \equiv 0$  for all  $\xi \in \Sigma_{\mu_1}$ .

**Proof.** Arguing by contradiction, we claim that the plane  $\Sigma_{\mu_1}$  can still be moved a small distance to the left. More precisely, there exists a  $\delta_0 > 0$ , such that, for all  $0 < \delta < \delta_0$ , we have

$$w_{\mu_1-\delta}(\xi) \ge 0, \forall \xi \in \Sigma_{\mu_1-\delta}.$$
(31)

This would contradict with the definition of  $\mu_1$ , and hence (30) holds. Now, we prove our claim. Suppose that  $w_{\mu_1}(\xi) \neq 0$ , then we infer from the continuity that  $w_{\mu_1} \geq 0$ . At the same time, from *f* being nondecreasing and (ii) in Theorem 1, we have

$$h(\rho^{Q-2}v)v^{\frac{Q+2}{Q-2}} = \frac{f(\rho^{Q-2}v)}{\rho^{Q+2}} \le \frac{f(\rho^{Q-2}v_{\mu_1})}{\rho^{Q+2}} = \frac{f(\rho^{Q-2}v_{\mu_1})}{[\rho^{Q-2}v_{\mu_1}]^{\frac{Q+2}{Q-2}}}v^{\frac{Q+2}{Q-2}}_{\mu_1} \le \frac{f(\rho^{Q-2}v_{\mu_1})}{[\rho^{Q-2}v_{\mu_1}]^{\frac{Q+2}{Q-2}}}v^{\frac{Q+2}{Q-2}}_{\mu_1} = h(\rho^{Q-2}v_{\mu_1})v^{\frac{Q+2}{Q-2}}_{\mu_1}.$$
(32)

The above inequality implies

$$-\Delta_L v \leq -\Delta_L v_{\mu_1}$$
,

and, from the strong maximum principle in [18]

$$w_{\mu_1} > 0$$
 in the interior of  $\Sigma_{\mu_1}$ . (33)

Moreover, since  $\frac{1}{\rho^{2Q}}\chi_{A_{\mu}} \to 0$ ,  $\frac{1}{\rho^{2Q}}\chi_{B_{\mu}} \to 0$ , almost everywhere as  $\mu \to \mu_1$ , and  $\frac{1}{\rho^{2Q}}\chi_{A_{\mu}} \leq \frac{1}{\rho^{2Q}}\chi_{\Sigma_{\mu_1-\delta}}$ ,  $\frac{1}{\rho^{2Q}}\chi_{\Sigma_{\mu_1-\delta}}$  for  $\mu \in [\mu_1 - \delta, \mu_1]$  for some  $\delta > 0$ , then from the dominated convergence theorem, there holds

$$\int_{A_{\mu}} \frac{1}{\rho^{2Q}} d\xi \to 0$$

and

$$\int_{B_{\mu}} \frac{1}{\rho^{2kQ}} d\xi' \to 0$$

as  $\mu \to \mu_1$ . In particular, there exists  $\delta > 0$ , such that

$$C_{\mu}\left[\left(\int_{A_{\mu}}\frac{1}{\rho^{2Q}}d\xi\right)^{\frac{2}{Q}}+\left(\int_{B_{\mu}}\frac{1}{\rho^{2kQ}}d\xi'\right)^{\frac{2}{Q}}\right]\leq\frac{1}{2},$$

for all  $\mu \in [\mu_1 - \delta, \mu_1]$ , it follows from Lemma 4 that  $v \leq v_{\mu}$  for all  $\mu \in [\mu_1 - \delta, \mu_1]$ ; this contradicts the definition of  $\mu_1$ .  $\Box$ 

**Lemma 6.** Let f, g be as in Theorem 1 and assume also that u is positive. Let v be the CR inversion of u centered at a point  $p = (0, 0, t_0)$ ; then v is symmetric with respect to  $T_{t_0}$ .

**Proof.** We use the method of moving planes to prove this lemma. If  $\mu_1 > t_0$ , then we know from Lemma 5 that v is symmetric with respect to  $T_{\mu_1}$ . On the other hand, the symmetry together with Equations (18) and (19) imply that  $|\xi_{\mu}| = |\xi|$ . By the assumption, either h or l is not a constant, which is impossible, hence we get  $\mu_1 \leq t_0$ . Similarly, we can also move the plane from the left and find a corresponding  $\mu'_1 \geq t_0$ . Finally, we infer from  $v_{\mu_1}(\xi) \geq v(\xi)$  and  $v_{\mu'_1} \leq v(\xi)$  that  $\mu_1 = \mu'_1 = t_0$ , that is, v hence u is symmetric with respect to  $T_{t_0}$ .  $\Box$ 

The following result from [6] plays a role in our proof.

**Theorem 7.** Let  $u \in C^0(\mathbb{R}^N_+)$  be a nonnegative solution of problem (5), where  $f, g: [0, +\infty) \rightarrow [0, +\infty)$  are continuous functions with the properties (i) f(t), g(t) are nondecreasing in  $(0, \infty)$ . (ii)  $h(t) = \frac{f(t)}{\frac{N+2}{t}}, k(t) = \frac{g(t)}{\frac{N}{t}}$  are nonincreasing in  $(0, \infty)$ . Then  $u \equiv c$  with f(c) = g(c) = 0. **Proof of Theorem 1.** By Lemma 6, we have that, for any  $t_0 \in \mathbb{R}$ , the CR inversion function v of u at  $p = (0, 0, t_0)$  is symmetric with respect to  $T_{t_0}$ . Since  $t_0$  is arbitrary, then we have that u is independent of t, that is, u is a solution of

$$\begin{cases} -\Delta u = f(u), & \text{in } \mathbb{R}^{2n}_+, \\ -\frac{\partial u}{\partial t} = g(u) & \text{on } \partial \mathbb{R}^{2n}_+. \end{cases}$$
(34)

Since *f*, *g* is nondecreasing in  $(0, \infty)$ , and

$$\frac{f(t)}{t^{\frac{2n+2}{2n-2}}} = \frac{f(t)}{t^{\frac{Q+2}{Q-2}}} t^{\frac{Q+2}{Q-2}-\frac{2n+2}{2n-2}},$$
(35)

and

$$\frac{g(t)}{t^{\frac{2n}{2n-2}}} = \frac{g(t)}{t^{\frac{4k}{Q-2}}} t^{\frac{4k}{Q-2} - \frac{2n}{2n-2}},\tag{36}$$

is decreasing in *t*, then Theorem 7 implies that  $u \equiv c$  with f(c) = g(c) = 0.  $\Box$ 

#### 4. Discussion

A useful tool for the study of symmetry for semi-linear equations with critical growth in  $\mathbb{R}^n$  or in a ball is the moving planes method. This paper studied Liouville properties for semi-linear elliptic equations with general nonlinearity; the moving planes method based on integral inequalities was used to prove the Liouville theorem. As is known, when k = 1,  $\Delta_L$  becomes the sub-Laplacian  $\Delta_{H^n}$  on the Heisenberg group  $H^n$ , the nonexistence results for any positive of semi-linear or fully nonlinear equations in the Heisenberg group need further study.

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