

Article

B-GPS: Blockchain-Based Global Positioning System for Improved Data Integrity and Reliability

Seunghyeon Lee ^{1,†} , Hong-Woo Seok ^{2,†} , Ki-rim Lee ³  and Hoh Peter In ^{1,*} 

¹ Department of Computer Science, Korea University, Seoul 02841, Korea; 2square@korea.ac.kr

² Department of Geoinformatic Engineering, Inha University, Incheon 22212, Korea; hwseok@inha.edu

³ Department of Spatial Information, Kyungpook National University, Daegu 41566, Korea; geolee@knu.ac.kr

* Correspondence: hoh_in@korea.ac.kr

† These authors contributed equally to this work.

Abstract: When surveying national reference points using a global positioning system (GPS), appropriate work regulations pertaining to the surveying time must be observed. However, such data can be modified easily, so identifying non-compliance with work regulations and forgeries is challenging. If such incidents occur in cadastral surveys, it may result in financial damages to stakeholders, such as citizens and the state. Therefore, it is necessary to improve the reliability by ensuring the integrity of the GPS positioning data and allowing anyone to track them. In this study, a prototype system was developed to record GPS data and the corrections generated during survey processes using the Ethereum blockchain network. Blockchain is a distributed ledger system that prevents the manipulation of uploaded data without the need for a centralized institution by allowing anyone to check the data. Unlike in the past, the proposed system improves the data integrity and reliability for the entire survey process through blockchain, thereby ensuring transparency of the checks using smart contract addresses.

Keywords: blockchain; smart contract; GPS positioning; data integrity; data reliability



Citation: Lee, S.; Seok, H.-W.; Lee, K.-r.; In, H.P. B-GPS:

Blockchain-Based Global Positioning System for Improved Data Integrity and Reliability. *ISPRS Int. J. Geo-Inf.* **2022**, *11*, 186. <https://doi.org/10.3390/ijgi11030186>

Academic Editors: Wolfgang Kainz and Peng Yue

Received: 11 February 2022

Accepted: 5 March 2022

Published: 9 March 2022

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1. Introduction

A global navigation satellite system (GNSS) is a satellite-based navigation technology that determines the three-dimensional position at any time and location, and weather conditions developed by the United States (US) as GPS, Russia as GLONASS, Europe—known as Galileo, China—known as BeiDou, and so on. The positioning accuracy was dramatically improved with the development of these positioning systems [1]. Various types of positioning exist, such as static measurement, real-time kinematic (RTK), and smartphone location tracking. These systems are used in various fields that require precise positioning, such as those that involve drones of kinematic changes and in autonomous driving [2–6]. In both cases, correction information is received in real-time to estimate precise coordinates. The method of providing correction is divided into state-space representation (SSR) and observation space representation (OSR), such as single RTK and network RTK [7–9]. Moreover, there are other techniques, such as a satellite-based augmentation system (SBAS), wide area RTK (WARTK), and precise point positioning RTK (PPP-RTK) [10–12].

Geodetic surveys are currently being conducted using GNSS in various countries. In Korea, UK, and the USA, the survey and regulation of the operations of GNSS and network RTK usage are required within the accuracy of 3–10 cm. Depending on the grade, the USA requires accuracy up to 1 cm with the limited data latency to less than 2 s. Most network RTK techniques are used in GPS surveying are centralized systems, wherein the central server data of continuously operating reference stations (CORS) are also centralized. Accordingly, transmitting and receiving with the “Rover” are thus conducted based on this scheme [13].

In this process, the user can send “forged” ; the National Marine Electronics Association (NMEA) and the server can generate the Radio Technical Commission for Maritime Services (RTCM) message based on these data. Thus, there are limitations in that all of the data can be counterfeit [14]. There are several cases of manipulation of survey results in Korea and the USA, and the possibility of forgery and falsification by surveyors was confirmed during the survey using GPS. GPS not only identifies the location of an object, but it diversifies its role by analyzing the congestion level of traffic information and distributing the congestion level by routes in the vehicular navigation service. Considering these trends, positioning reliability improvement is also considered important. Samios et al. (2021) created an attack path for seismometers, accelerometers, and GPS receivers, and identified security vulnerabilities [15]. Thus, countermeasures are necessary because there are limitations in terms of the security and integrity of the GPS receiver and server-side data.

Research studies conducted on the identification of solutions of data forgery and falsification cases by centralized structures using blockchains is increasing. Unlike the traditional system, in which only a single group manages the database, the blockchain secures the integrity of the database by recording and storing data from multiple groups. Furthermore, by disclosing it to users, the transparency of data are secured. Kowaiski et al. (2021) confirmed the improvement of the trust relationship and security between business partners through blockchains in trade finance [16]. In turn, Majeed et al. (2021) improved blockchain technologies applied to smart cities and their reliability and security [17]. In turn, Li et al. (2021) proposed a framework using blockchain and improved positioning accuracy through data filtering [18].

Therefore, the current study was conducted to solve the problem of data forgery and falsification, which relates to the existing satellite survey system using the Ethereum blockchain. Assuming that there are no forged data in the communication between CORS and the server, and forged data in the communication between the user and the server, a blockchain-based decentralized satellite surveying system is implemented using data from the NMEA and RTCM. In the NMEA transmission/reception process, the received NMEA is transmitted to the server and recorded on the Ethereum network simultaneously. Subsequently, the RTCM received from the ground station is recorded on the Ethereum network, and correction is performed simultaneously. To this end, prototype software that communicates between the GPS receiver and the Ethereum blockchain network is produced, and the reliability and stability of this network is verified and compared with the existing system. It is crucial to prevent damage by securing the integrity of survey data, including surveyors and survey processes, but this has not been resolved in decades.

In this study, we solved this problem by uploading data to the blockchain in the process of obtaining the data at the software level. The contributions of this study are as follows: first, in the GPS positioning process, a blockchain-based positioning system is proposed to check data injection and compliance. Second, to improve the integrity of GPS data, blockchains using Keccak-256 functions, Merkle tree, and P2P-based consensus proof algorithms are applied to GPS positioning. Third, in order to improve the reliability of the GPS positioning process, the hash value on the blockchain makes it possible to verify the data source, the positioning record by the worker, and the positioning process of the positioning point. Fourth, the efficiency of introduction is evaluated by calculating the cost incurred when using the public blockchain.

The remainder of this paper is structured as follows. Section 2 presents some background on GPS positioning and blockchain technology, to illustrate the motivation of the study. Section 3 describes the flow of blockchain-based GPS positioning as proposed in this work, and presents a schematic, with explanations of the main algorithms in the software. Section 4 describes the checking of the operation of the software, and presents the results, as well as analyses of the cost and security concerns regarding the use of blockchain. Finally, Section 5 presents the conclusions of this study.

2. Background

2.1. GPS Positioning

As observation data, pseudorange, carrier-phase, and Doppler observations for each frequency are provided, and the pseudorange and carrier-phase are mainly used for navigation. The pseudorange is mainly used for smartphone navigation, etc., and it is possible to secure m-level accuracy for standalone positioning [19]. During the use of the carrier-phase, a dual-frequency GPS receiver is required to solve the integer ambiguity, and it is possible to secure cm-level accuracy through differential positioning with the reference station observations. Unlike the initial development of such a GPS for military purposes, the GPS is currently being used in various fields, such as geodetic surveying, autonomous driving, and a forecasting model [20]. In the case of a geodetic survey using GPS, precise positioning is possible within seconds–minutes. In the case of indirect leveling using GPS, 90% and 75% of time and costs are reduced, respectively, compared to the case of direct leveling through the level [21]. GPS surveying is divided into real-time and post-processing.

In real-time GPS surveying, the multi-reference station-based network RTK that overcomes the limitation of the baseline distance is preferred over the single RTK due to spatial decorrelation when the baseline distance increases [22]. In post-processing, GPS software, such as GipsyX/RTGx of NASA JPL and Bernese of Bern University, are used to acquire precise coordinates, where accuracy is mm-level. Real-time surveying can converge within a few seconds using RTCM messaging, such as Flächen-Korrektur parameter (FKP) correction or virtual reference station (VRS) observations, and coordinates with cm-level accuracy can be acquired. It was difficult to secure visible satellites in urban areas using only GPS/GLONASS, so the FIX rate of integer ambiguity during positioning was low. Through multi-GNSS (GPS/GLONASS/Galileo/BeiDou), the number of visible satellites is secured, and stability of the FIX rate is also improved [23]. Post-processing surveying can acquire precise coordinates, but it requires about two weeks of waiting because precise a final orbit product is required. The obtained coordinates are the antenna phase center (APC), which means the antenna receives the signal, and there is a difference from the geometric center of the antenna. Therefore, it is necessary to consider the variation according to the azimuth and elevation angle for each satellite provided through the ANTEX file.

In South Korea, the National Geographic Information Institute (NGII) provides single RTK and network RTK services as OSR correction through the NTRIP server and Geo++ SSRG services as SSR corrections [23]. Among these, for GPS surveying for geodetic surveying purposes, VRS and FKP methods are used among network RTK. When using network RTK, the user transmits NMEA to the server every second, and the server sets up a virtual reference station near the user and creates a virtual observation value or transmits a FKP correction to the user. The user conducts RTK using the given RTCM message, and the NMEA received from the user is used in future survey performance evaluations. Since SSR correction is not currently standardized, the formats of correction information provided by IGS and Geo++ are all different. In addition, as the verification of geodetic surveying has not been performed, it is not being used for geodetic surveying. Therefore, research is in progress targeting the simultaneous use of multiple users, such as autonomous driving.

These methods are performed at a single institution using a centralized server, making them more vulnerable to manipulation than decentralized systems, such as blockchain. An additional disadvantage is that the user must request disclosure every time, or establish a separate disclosure system for data verification. Anyone can check the data in the blockchain by providing the contract address without building a separate system.

2.2. Blockchain

Blockchain technology connects nodes based on a P2P network, and constructs a network using a distributed ledger [24]. This technology solves many problems of existing centralized systems [25–27]. Since more than 51% of nodes must be hacked for data manipulation, data integrity is guaranteed high stability, and in fact, the Bitcoin network is never “tampered”. In addition, even if some nodes fail due to a DDoS attack, other nodes are maintained, and services are not paralyzed. The transparency that data are open to everyone solves the problem of information asymmetry. Therefore, with the question of the existing money system, a safe and transparent electronic money system was devised. In addition, by rewarding an unspecified number of nodes participating in the network with cryptocurrency, the degree of node participation is improved, and the stability of the network can be secured further. However, it could be mainly used for banking and payment systems to replace traditional currencies.

If the characteristics of the blockchain guarantee the integrity of the code and data generated by the program, various reliability problems that exist in existing computer systems can be solved. Ethereum, also called a second-generation blockchain, runs code written on a Turing completeness language called Solidity on a blockchain network [28]. Turing completeness languages are important because they can algorithmically solve any computable problem. Ethereum uses this to create an application that solves contract problems in the real world that could not be solved with the existing system. Given that this application uses decentralized nodes, it is called a decentralized application.

In addition, various blockchain frameworks exist, and are selected according to the purpose, closure, and speed of the service to be implemented. Furthermore, according to the restrictions on the participation qualification of nodes, three types of blockchains are largely determined: public, private, and consortium, and the consensus method between nodes is applied differently depending on the purpose [29]. Bitcoin and Ethereum are public blockchains, wherein an unspecified number of unspecified people can participate as nodes. At this time, the concept of cryptocurrency is attached because compensation for maintaining the node is required. However, in the case of private and consortium blockchains, only authorized nodes and users are allowed, such as the private network of the existing internet network configuration. Unlike public consortium blockchains, which entrusts server maintenance to anonymous users, it does not require compensation, such as cryptocurrency, because it uses existing resources.

Most devices are connected to networks to enable efficient control, a situation that may lead to facility damage and power supply problems in the case of power plants [30]. Since these issues arise from data manipulation, it is important to ensure data integrity. Algorithms and devices to address these issues have been researched, and trusted third-party solutions have been used to handle such problems [31–34]. However, it is not easy to ensure reliability using this approach, because all of these systems are centralized. Currently, blockchain networks are used to solve such problems in other fields [35–37]. The main limitation, with respect to the existing solutions, is that there is no method to reliably monitor malicious modifications to recorded data; however, blockchain was able to resolve this problem by ensuring integrity while simultaneously facilitating appropriate monitoring [38]. As this approach improves reliability, it can also be used to improve GPS positioning accuracy by using data between objects, such as self-driving cars [18,39]. However, there are cases where the blockchain is not suitable for rapid communication in an environment, such as internet of vehicles, because it consumes relatively high energy compared to the cryptography technique [40,41]. In addition, it is limited in that it has the same weakness as the 51% attack, in that it trusts all nodes without evaluating the reputation [42]. However, GPS surveying does not generate many transactions on the blockchain network and the 51% attack requires enormous costs, the attack occurs for financial gain, so cryptocurrency theft is the main target. In other words, even if the attack succeeds, no data are injected, and the blockchain used in this study has never been

successfully attacked. Therefore, blockchain was judged as the most suitable method to solve the problems introduced above in this study.

3. Blockchain-Based Global Positioning System

In this study, we developed and implemented a GPS positioning system using a smart contract of Ethereum to improve the integrity of GPS data. It receives NMEA data from the GPS receiver and transmits it to NTRIP Caster to receive RTCM data. The two data are then uploaded to the blockchain network, and the RTCM is transmitted to the GPS receiver for NTRIP-based position correction. By repeating this process for a certain period of time, the GPS receiver continuously corrects the position of the measured information to improve the positional accuracy, and all data are uploaded to the blockchain network. (Figure 1).

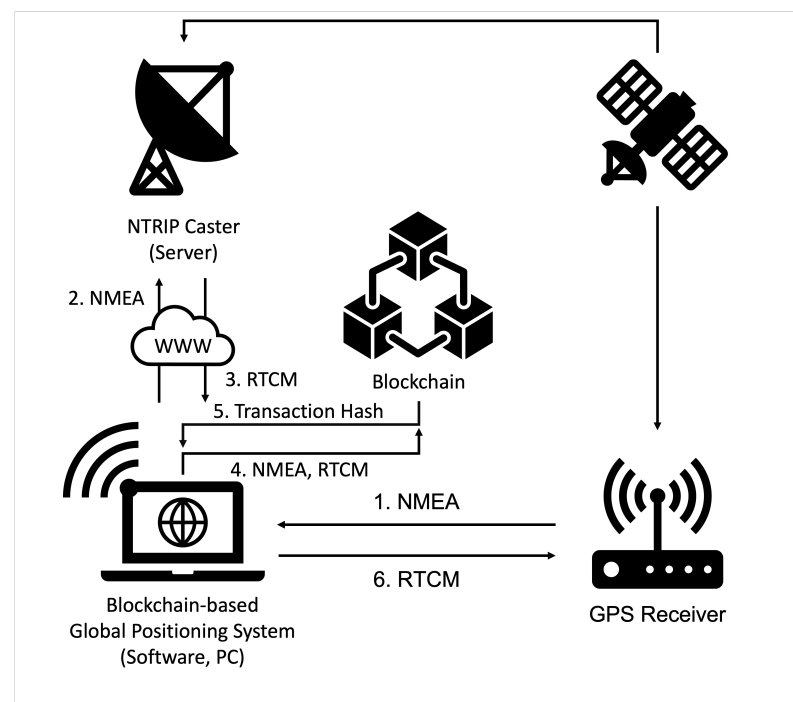


Figure 1. Overview of the blockchain-based global positioning system.

Transactions have several attributes: transaction hash refers to identifiers; contract addresses refer to survey points and survey processes; wallet addresses refer to surveyors; and data refer to NMEA and RTCM data. Unlike the traditional system, the entire process, other than the final result, can be checked for compliance with regulations pertaining to issues, such as survey time, and the work of surveyors can be traced (Table 1). Using this approach, even if a value in the system is manipulated, anyone can inquire about the transaction hash to perform integrity checks and track the original data.

Table 1. Hash role descriptions.

Hash Types	Descriptions
Transaction hash	The identifier of the positioning
Contract address	The identifier of the positioning point, which has transaction hashes
Wallet address	The identifier of the surveyor, which has transaction hashes

The integrity of all data are guaranteed by the blockchain. A blockchain generates transaction hashes using transaction attribute values, input data, and the Keccak-256 function, and creates a transaction root using the value of the transaction hashes and the Merkle tree. When a block is mined, a block hash is generated using the attribute values of the block, including the transaction root and the Keccak-256 function, and is used as one of the attributes of the following block, Figure 2. Therefore, as the block attempts to manipulate the data at a more extended point, the cost of injecting it increases exponentially. In this way, the blockchain prevents the injection.

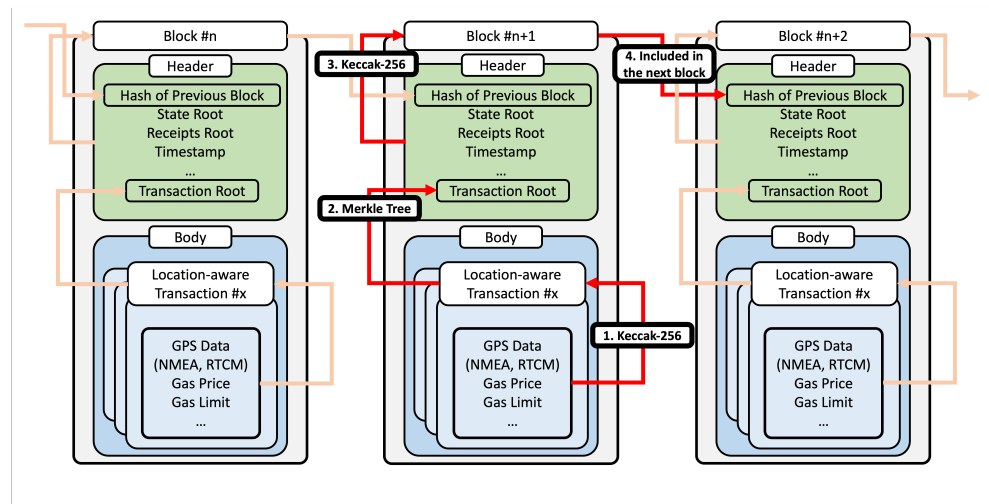


Figure 2. Connection of the block and transaction.

In this system, a low-cost GPS receiver (u-blox ZED-F9P) was used for GPS surveying [43]. We then developed software that send and receive the NMEA and RTCM data to the GPS receiver and NTRIP Caster. Moreover, it sent them to the Ropsten testnet of the Ethereum blockchain network for the experiment. The target network can be changed to the other network using the Ethereum virtual machine (EVM) for the actual case. It was developed on Python, and a smart contract that was executed on the Ethereum network was also developed with Solidity and inserted into the Python code. Python takes advantage of this by compiling the Solidity compiler and separating the application binary interface (ABI) and bytecode. Given that the smart contract is executed after the system operates using the user's Ethereum wallet, the wallet address remains, and the wallet address becomes a value that can identify the worker involved in the GPS positioning process.

In the original GPS survey process, Algorithm 2, which performs device initialization for surveying and connection with the NTRIP server, is started once, and Algorithm 3, which receives and corrects RTCM information and re-transmits NMEA information, is repeated for a specific time. In this study, Algorithm 1, a smart contract operating on Ethereum, was added. The Ethereum network connection and smart contract distribution, which is performed once in Algorithm 1, is executed in Algorithm 2, and data recording in the blockchain through smart contract execution is executed in Algorithm 3. Based on these, all data generated and used by GPS devices are recorded in the Ethereum network and integrity is secured.

Algorithm 1: Smart contract: ensure or return the surveyor, NMEA, RTCM.

Data: *Wallet Address*
Surveyor = Wallet Address
Function 1 : *GPS Positioning*
 Data: *NMEA from Receiver, RTCM from Caster*
 NMEA = NMEA from Receiver
 RTCM = RTCM from Caster
end
Function 2 : *Call the data*
 Result: *Surveyor, NMEA, RTCM*
end

Algorithm 1 is constructed to input the surveyor's address when the contract is deployed that stores the user's wallet address, when deploying a smart contract. Algorithm 1-1 (first function for GPS positioning) stores NMEA and RTCM, and Algorithm 1-2 reads operator and GPS information. It is defined as Algorithm 1-2 (second function for return the data). In the case of the construct, it is an area that is executed together with the distribution of the smart contract, and the user's wallet address is automatically saved as soon as Algorithm 1 operates. Algorithm 1-1 receives data from Algorithm 4 and stores them as data types. Subsequently, the GPS information and workers stored in this contract can be checked by Algorithms 1 and 2. Although the structure of Algorithm 3 is simple, it is a smart contract code written in Solidity and works on the Ethereum network. That is, the integrity of the GPS data and operator information stored in Algorithm 2 is guaranteed by Ethereum.

Algorithm 2: Connect to the GPS receiver and NTRIP caster.

Data: *Serial, NTRIP Caster*
Result: *Receiver, NTRIP Client*
while *Receiver is not connected* **do**
 Receiver = Connect through the Serial
end
while *Client is not connected* **do**
 NMEA = Parsing from Receiver
 NTRIP Client = Connect to NTRIP Caster using NMEA
end

Algorithm 2 initiates the execution and connection of the sensor using serial communication for GPS positioning. It is set to receive various types of information through connection and communication with the satellite at the same time the device is running, so GPS positioning starts. Subsequently, to connect with the NTRIP server, the input caster information is used to create the NTRIP client. In this study, the mount point VRS_V32 of the NGIS server was used. Thereafter, GNSS data was read from the information measured by positioning from the device and transmitted to the server through the NTRIP client to perform the initial connection. This is a general GPS positioning process. In this study, the connection of the Ethereum network and the execution of Algorithm 1-1 were added.

Algorithm 3: Connect to the Ethereum blockchain and deploy the smart contract.**Data:** *Network URL, Wallet Address, Private Key, Contract Code***Result:** *Web3, Contract***if** *Web3 is not connected* **then**| *Web3* = Connect through HTTP provider with *Network URL***end***Compiled Code* = compile the *Contract Code**ABI* = Parsing from *Compiled Code**Bytecode* = Parsing from *Compiled Code**TxHash* = Transact the contract using *ABI, Bytecode***while** *Tx is not mined* **do**| *Tx* = Wait for transaction receipt using *TxHash***end***Contract* = Defined using *ABI* and Address of *Tx*

NMEA and RTCM generated in the positioning process through Algorithm 1 were recorded on the Ethereum blockchain. However, this requires that the device is connected to the Ethereum network and deploys a smart contract. This algorithm manage this task. To achieve proof-of-concept, we entered the URL address of the test net. Additionally, the wallet address and private key were entered to execute the smart contract. Subsequently, connection to the network was established through the HTTP provider and a Web3 instance was created. The contract was then deployed using the ABI and bytecode extracted from the Web3 instance and the compiled Solidity code (Algorithm 3). Through the address of the deployed smart contract, the user (surveyor) can be identified, and GPS information can be tracked. After deploying, the receipt of the transaction was returned, which confirmed that the contract had been distributed correctly. Using only the address of the transaction that occurred in this process, the operator and GPS information whose integrity was secured in Algorithm 3 can be checked.

Algorithm 4: GPS positioning.**Data:** *Web3, Contract, Receiver, NTRIP Caster, NTRIP Client, Deadline***while** *RunningTime* $\neq$ *Deadline* **do**| *NMEA* = Parsing from *Receiver***if** *NMEA is True* **then**| | *RTCM* = send *NMEA* to *NTRIP Caster* through *NTRIP Client*| | *Tx Hash* = Function 1 of Algorithm 1 with *NMEA, RTCM* using *Web3*| | *NMEA* = Send *RTCM* to *Receiver***end****end**

To improve the integrity and reliability of GPS data and processes, Algorithm 4 performs blockchain-based GPS positioning for as long as the surveyor sets the time. When NMEA and RTCM data are input to the system through GPS surveying, through Algorithm 1, to record data on the blockchain and store the transaction hash value together in the system, this method prevents the injection of blockchain-based data and allows anyone to trace and prove the original data using hash values. For one survey point, a transaction hash occurs as long as there is a contract address and the time is set by the surveyor. Unlike the traditional system, data on the entire survey process can be tracked using this method.

4. Result

4.1. Results of Implementation

We implemented and developed a decentralized GPS positioning prototype system using the Ethereum blockchain. Solidity and Python were mainly used as development tools for smart contract application development. If the prototype works appropriately in the network, it also works in the main network or the test network. Thus, we experimented with the Ropsten test network.

The contract address deployed through Algorithm 3 is `0x4cDD2600bd83A308dF598F5FdA8D3Ef2BdFbf348` (Figure 3). This address is generated each time the prototype is executed for GPS positioning at a new location, and all data generated by Algorithm 4 can be found at that address. One coordinate and record process corresponds to each contract address. It also contains the address of the wallet that deployed it, which allows us to identify the worker who operated it.

The deployed smart contract was recorded in block 1 and the first measured coordinate is the Tables 2 and 3. Subsequently, Algorithm 4 was executed 56 times to execute a total of 56 additional transactions (Figure 4).

Table 2. The first recording GPS positioning data.

Field	Value
NMEA Data	\$GNGGA,025610.00,3735.2330935,N,12700.9212481,E,5,12,0.77,54.482,M,18.504,M,1.0,4095*5B <code>\xd3\x00\t?_ \xff\xe8\xde\x15\x18\x80H\xfa\xe4R\xd3\x00\x15 ></code> <code>\xef\xff\x03\xf8\xc5#6\xc5\tR\x1e\x13\x9f\x88\xfd\xabI\xfa\x00\x00h\xe8S\xd3\x00\x14@\x8f\xff</code> <code>\x00\x008\xba\xf0\x8b\xe5%JZ[\xb8\x8fR\xfb\x0c\x94\x90\xc3\xd3\x00(@\x9f\xff</code> <code>\x0eGPPNULLANTENNA\x00\x00rTrimbleNetR9\x045.37\x00/\x9c\x84\xd3\x00\x14?\x0f\xff</code> <code>\x0eGPPNULLANTENNA\x00\x00xc0e\x00\xd3\x00\x0cL\xef\xff\x8f\x03\x8a\x03?\x03P\x03MY\xac</code> <code>\x9d\xd3\x002@f\xca1\xa9\xff\xf0\xa7\x0c4 :</code> <code>\x00\x16\x0c\xac\x08\x08\x00\t\x05\x19\x06\x07\x00\x04\x82m\x02\x82\x0c0\x02\x81gA\x81\x0c0\x04\x02;</code> <code>\xe0\x80\x90\x00pF\x00@H\x00\x12</code>
RTCM Data	

Transaction Details
<
>

Overview
State

[This is a Ropsten Testnet transaction only]

Transaction Hash: 0x4c3ed0a8f2933bb5336717d3bf38fbbcc3fa12b180fe82afb8a001d8da1321c

Status: Success

Block: 11942465 1087 Block Confirmations

Timestamp: 6 hrs 16 mins ago (Feb-10-2022 01:50:11 AM +UTC)

From: 0x49b99615b39430993ce8d2fc4577b2585d24a68b

To: [Contract 0x4cdd2600bd83a308df598f5da8d3ef2bdfbf348 Created]

Value: 0 Ether (\$0.00)

Transaction Fee: 0.000991693586536829 Ether (\$0.00)

Gas Price: 0.000000002106494951 Ether (2.106494951 Gwei)

Gas Limit & Usage by Txn: 470,779 | 470,779 (100%)

Gas Fees: Base: 0.014566102 Gwei

Figure 3. Block and transaction information by contract deploying.

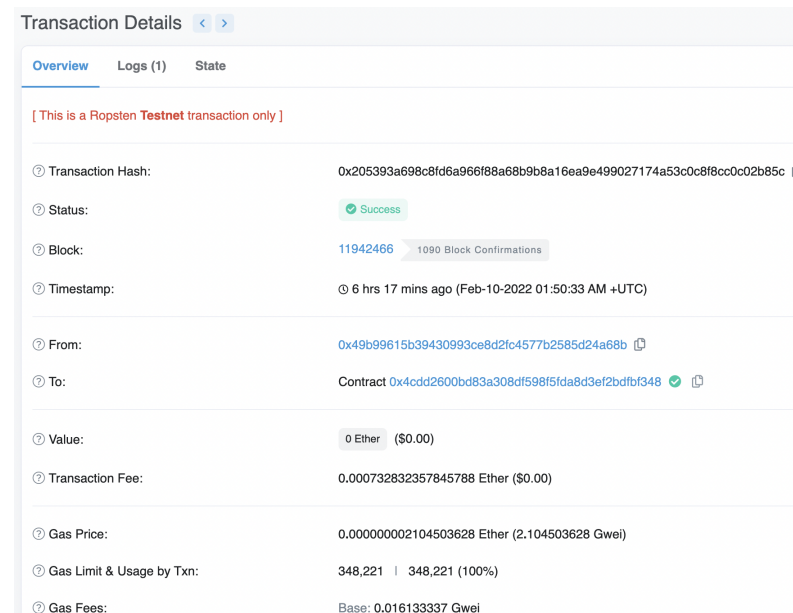
Table 3. Transaction information of first GPS positioning.[illegible]

Figure 4. Transaction information of the first recording GPS positioning data at Etherscan explorer.

The last recorded coordinates are seen in Tables 4 and 5. Algorithms 1–3 were executed to see the value recorded in the contract. It was confirmed that the measured coordinate and the value recorded in the Ethereum network matched (Figure 5).

Table 4. The last recording GPS positioning data.

Field	Value
NMEA Data	\$GNGGA,030002.00,3735.2333839,N,12700.9215485,E,5,12,0.63,55.661,M,18.504,M,1.0,4095*5C
RTCM Data	Error at LaTeX. We'll send it to Editorial office.

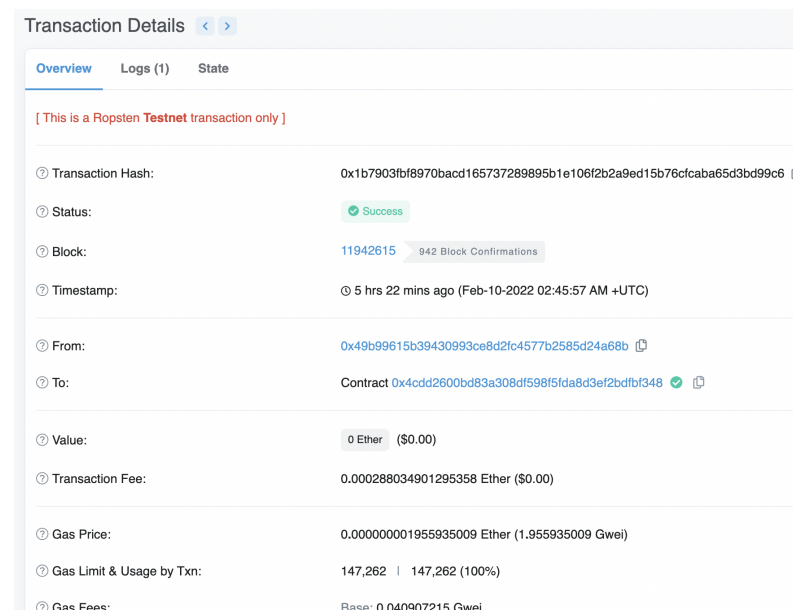
Table 5. Transaction information of last GPS positioning data.[illegible]

Figure 5. Transaction information of the last GPS positioning at Etherscan explorer.

4.2. Security Analysis

Integrity: in this study, location-based transactions were created and uploaded to the blockchain using NMEA from GPS surveys and RTCM received from NTRIP Caster, to improve the integrity of GPS data. The matching of GPS data stored in the blockchain and data stored in the system were verified using the data uploaded to the blockchain through the Etherscan explorer (Figure 6). Location-based transactions can use hash values for transactions produced through the Keccak-256 function as identifiers. Changing data leads to changes in transaction hash values, providing a means of monitoring integrity. The blockchain also prevents injection using a method that must be agreed upon by more

than 51% of nodes. The integrity of all data generated during the GPS surveying process is thus guaranteed.

The screenshot shows a blockchain explorer interface for an Ethereum address: 0x49B99615B39430993Ce8D2fC4577b2585d24a68B. The interface includes an 'Overview' section with the balance (3.718653894245902021 Ether) and a 'More Info' section with a 'My Name Tag' (Not Available). The 'Transactions' section displays a list of transactions, with the latest 25 shown. Each transaction entry includes the Txn Hash, Method, Block, Age, From, To, Value, and Txn Fee.

Txn Hash	Method	Block	Age	From	To	Value	Txn Fee
0x1b7903b8970bacd16...	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	11942615	5 hrs 7 mins ago	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0 Ether	0.000288034901
0x7e6293d42bc5eab075...	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	11942614	5 hrs 8 mins ago	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0 Ether	0.000288034901
0x451187e32580689017...	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	11942613	5 hrs 8 mins ago	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0 Ether	0.000288034901
0x5d5b1f1e1d46279683...	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	11942612	5 hrs 9 mins ago	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0 Ether	0.000288034901
0x04e12b335be38c5b4...	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	11942611	5 hrs 9 mins ago	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0 Ether	0.000288034901
0x1bb7e0b5c1ec51bdc...	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	11942610	5 hrs 9 mins ago	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0 Ether	0.000288034901

Figure 6. Verification of the uploading to a blockchain through Explorer.

Reliability: it was confirmed that reliability was improved by allowing anyone to prove GPS data using hash values on the blockchain. In this study, the transaction hashes occur for each Algorithm 4, and NMEA and RTCM data are stored (Figure 7). Therefore, even if a user reports a result in the form of a file, data can be tracked using only the transaction address. The algorithm proposed in this study distributes one contract to one location to be measured, and generates one transaction per point (Figure 8). When the system is executed to produce 60 surveys at one point, 60 transactions occur, and are connected to one contract address. In the past, if only one point could be received as a final result, the contract address could be used to track whether regulations, such as overall data, and survey working hours for one location could be observed (Figure 9). Wallet addresses can distinguish between workers. All transactions and contracts that occurred can be queried, so that all of the surveyed behaviors of the workers could be tracked (Figure 10).

The screenshot shows a table with four columns: Transaction Hash, Worker ID (Wallet Address), Point ID (Contract Address), and Data (Parsed from Transaction). The table contains multiple rows of data, showing the mapping between transaction hashes, worker IDs, and point IDs.

Transaction Hash	Worker ID (Wallet Address)	Point ID (Contract Address)	Data (Parsed from Transaction)
0x205393a698c8fd6a966f88a68b9b8a16ea9e49902717...	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	("_NMEA": "b'GNGGA,025610.00,3735.233098,N,12..."
0x89191e023e7b391e596d95013542b3b9858c018...	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	("_NMEA": "b'GNGGA,025610.00,3735.233098,N,12..."
0x76822e1e7343c5eb5474016de12faaf563f94ec...	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	("_NMEA": "b'GNGGA,025610.00,3735.233098,N,12..."
0xad85fabc73cd4fc07abdfc3704dc81ffa4a007796...	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	("_NMEA": "b'GNGGA,025610.00,3735.233098,N,12..."
0x858db7e5e63d5dec64af31617786517030e5f9e...	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0x49B99615B39430993Ce8D2fC4577b2585d24a68B	("_NMEA": "b'GNGGA,025610.00,3735.233098,N,12..."

Figure 7. Tracking the GPS data and point and worker by the transaction hashes.



Figure 8. Mapping the GPS data parsed from the transaction hash.

Point ID(Contract Address)	Transaction Hash
0x4cDD2600bd83A308dF598F5FdA8D3Ef2BdFbf348	0x205393a698c8fd6a966f88a68b9b8a16ea9e49902717...
0x4cDD2600bd83A308dF598F5FdA8D3Ef2BdFbf348	0xe891f9e023e61bb39b1e596d95013bf42b3b9858c018...
0x4cDD2600bd83A308dF598F5FdA8D3Ef2BdFbf348	0x176622c61e73431c5eb5474f016de12faaf563f94ec...
0x4cDD2600bd83A308dF598F5FdA8D3Ef2BdFbf348	0xad85fa5c73cd4fc0f7abd0fc3704dc81ffa4ad007796...
0x4cDD2600bd83A308dF598F5FdA8D3Ef2BdFbf348	0x858db67e55e63d5dec64daf3f6f178b65170306e5f9e...
...	...
0xF42b8A2C6196E701DDcB341d21e18Ee0e1E1abD5	0x70f1b6185b822299607b8de4eb6b1a76bfdfc93a5362...
0xF42b8A2C6196E701DDcB341d21e18Ee0e1E1abD5	0x33f19b5853c64aaa06afee7aca50dac7043bfbd4261f...
0xF42b8A2C6196E701DDcB341d21e18Ee0e1E1abD5	0x821a97f5af8a4b0e8e24aa2cdcf8e655fdb425305042...
0xF42b8A2C6196E701DDcB341d21e18Ee0e1E1abD5	0xe3388a5be4539912d0d7b44e3652350d48e12c57d9d2...
0xF42b8A2C6196E701DDcB341d21e18Ee0e1E1abD5	0xa19ff961596d26023b5b4a2c0811d871b91b61df0219...

Figure 9. The transaction hashes by the contract addresses.

Worker ID(Wallet Address)	Transaction Hash
0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0x205393a698c8fd6a966f88a68b9b8a16ea9e49902717...
0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0xe891f9e023e61bb39b1e596d95013bf42b3b9858c018...
0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0x176622c61e73431c5eb5474f016de12faaf563f94ec...
0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0xad85fa5c73cd4fc0f7abd0fc3704dc81ffa4ad007796...
0x49B99615B39430993Ce8D2fC4577b2585d24a68B	0x858db67e55e63d5dec64daf3f6f178b65170306e5f9e...
...	...
0x834844CefEec34305d14ad9c20D887891eDa935	0x70f1b6185b822299607b8de4eb6b1a76bfdfc93a5362...
0x834844CefEec34305d14ad9c20D887891eDa935	0x33f19b5853c64aaa06afee7aca50dac7043bfbd4261f...
0x834844CefEec34305d14ad9c20D887891eDa935	0x821a97f5af8a4b0e8e24aa2cdcf8e655fdb425305042...
0x834844CefEec34305d14ad9c20D887891eDa935	0xe3388a5be4539912d0d7b44e3652350d48e12c57d9d2...
0x834844CefEec34305d14ad9c20D887891eDa935	0xa19ff961596d26023b5b4a2c0811d871b91b61df0219...

Figure 10. The transaction hashes by the wallet addresses.

4.3. Cost Analysis

The gas used in the deploying of smart contracts shown in this experiment was 348,221 gas, and the GPS positioning function was calculated as an average of 267,316 gas (Table 6). It slightly depends on the transmitted data. Therefore, performing GPS positioning for 56 times includes the deploying of smart contracts using “15,317,889 gas”. In the case of the view function, gas is not required, because it is a function that returns only the result without the calculation. The more considerable the amount of data recorded on the blockchain, the more gas is used, so the gas usage tends to increase according to the length of the RTCM message (Figure 11).

Table 6. Cost of smart contract execution.

Field	Cost (Gas)
Deploying	348,221
GPS Positioning (Function 1, Avg)	267,316
GPS Positioning (Function 1, 56 times)	15,317,889

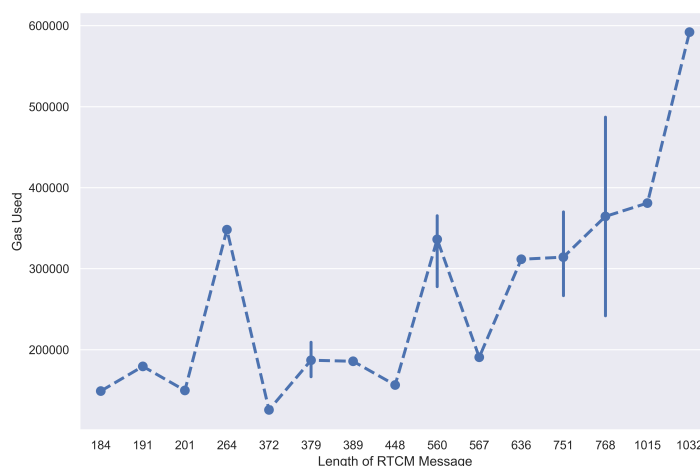


Figure 11. Gas usage of transactions according to the length of the RTCM message.

5. Discussion and Conclusions

In this study, we proposed a system that uploads the GPS positioning process to the blockchain network, using smart contracts, and ensuring data integrity. The Ropsten testnet of Ethereum networks were used, but they can work in the same way on Ethereum's main network and many other blockchains using EVM. All users were able to check GPS data at a specific location, as well as workers and processes, using the provided contract address. These concerns can be addressed earlier if such information is written together in areas vulnerable to easy manipulation and financial damage, such as cadastral surveys. Therefore, the government needs to prevent legal disputes and improve administrative efficiency by operating a blockchain network that records such GPS information. In addition, based on the structure of the existing algorithm, it was suggested that the blockchain could be applied in a simple method, such as by putting information on the blockchain network and wallet to be used in the existing survey software and smart contracts. However, networks such as Ethereum and Binance Smart Chain may involve prohibitively high costs, and Klaytn requires a reasonable level of costs. This concern can be addressed by using various blockchains using Solidity-based smart contracts. Furthermore, if a part of the ground station system is operated as a private blockchain, the cost concern will be resolved entirely. Therefore, future research will focus on cost issues and the configuration of the blockchain network.

Author Contributions: Conceptualization, Seunghyeon Lee; methodology, Seunghyeon Lee and Hong-Woo Seok; software, Seunghyeon Lee and Hong-Woo Seok; investigation, Ki-rim Lee; writing—original draft preparation, Seunghyeon Lee and Hong-Woo Seok; writing—review and editing, Seunghyeon Lee, Hong-Woo Seok and supervision, Hoh Peter In. All authors have read and agreed to the published version of the manuscript.

Funding: This work was supported by the National Research Foundation (NRF) of Korea grant funded by the Korean government (MSIT), no. NRF-2021R1A2C2012476.

Institutional Review Board Statement: Not applicable.

Informed Consent Statement: Not applicable.

Data Availability Statement: Not applicable.

Conflicts of Interest: The authors declare no conflict of interest.

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