



Article Bidirectional Chaotic Synchronization Communication of Closed-Loop Mutually Coupled Nano-Lasers

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Abstract: It is well known that the dynamical characteristics of nano-lasers (NLs) have been extensively studied, but there is limited research on chaotic synchronization communication. In this paper, we propose a closed-loop system of mutually coupled NLs. Firstly, the autocorrelation function is employed to evaluate the capability of the system to conceal the time-delayed signature (TDS), and then, based on this, we specifically analyze the effects of the injection strength, frequency detuning, and parameter mismatch of two NLs on the chaotic synchronization performance, as well as the bidirectional communication. The detailed studies indicate that the proposed closed-loop mutually coupled system based on NLs can achieve high-quality chaotic synchronization with a low TDS and large bandwidth. In addition, the system maintains high-quality chaotic synchronization and communication performance even under significant parameter mismatch.

Keywords: chaotic synchronization; nano-lasers; communication



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1. Introduction

Semiconductor lasers (SLs) are widely used in optical fiber communication and are one of the most common light sources. It is well accepted that these lasers can exhibit rich nonlinear dynamics by introducing additional degrees of freedom. With the reasonable choice of control parameters, they are prone to generate chaotic optical signals with a low time-delay signature (TDS) and wide bandwidth, which can be widely used in important fields such as chaotic secure communication [1–5], chaotic radar [6,7], neural computing [8,9], compressive sensing [10], reservoir computing [11], and high-speed physical random number generation [12,13]. In particular, a necessary condition for implementing secure optical chaotic communication is the achievement of good chaotic synchronization between the SLs at the transmitter and receiver. Message transmission based on chaotic synchronization refers to the encoding of a useful message into chaotic carriers using methods such as chaos masking (CMS), chaos shift keying (CSK), and chaos modulation (CM). This encoded message is then transmitted through the transmission channel to the receiver. At the receiver, the useful message is recovered using the chaotic filtering effect [14].

Therefore, chaotic synchronization and secure communication based on SLs have become a focal point of research for many scholars. So far, research has primarily focused on unidirectional coupling [15–17] or bidirectional coupling between SLs [18–26], as well as configurations involving coupled SLs forming circular or network topologies [27–30]. Unlike master–slave systems, the outputs of mutually coupled systems synchronize under a symmetric operation mechanism, which requires that the lasers and external optical injection should be identical. On the other hand, mutually coupled systems, due to their higher security and potential for bidirectional data transmission, have been widely explored. For example, Chiang et al. theoretically demonstrated the general synchronization conditions for a system of mutually coupled SLs with feedback and experimentally verified them

using optoelectronic feedback schemes [21]. Vicente et al. proposed a scheme for complete synchronization between two mutually coupled SLs with a partially transparent mirror in the middle, and discussed its potential applications in simultaneous bidirectional message transmission [22]. Subsequently, Jiang et al. further explored chaotic synchronization and its applications in the multi-channel communication of external optical feedback mutually coupled semiconductor lasers (EOF-MCSLs) [24], external optical injection mutually coupled semiconductor lasers (EOI-MCSLs) [25], and high-frequency chaotic-state multitime-delay mutually coupled external-cavity semiconductor lasers (MTDMC-ECSLs) [26]. The study results demonstrated that the EOF-MCSLs system exhibits high security. In addition, enhancing the synchronization communication security of the system can be achieved by appropriately increasing the information rate, adopting an asymmetric rate information transmission method, and monitoring the synchronization performance at both the transmitter and receiver. Compared with the EOF-MCSL system, the EOI-MCSL system indicates a strong parameter-mismatch robustness and frequency-detuning tolerance in real-time chaotic synchronization. This means that the EOI-MCSL system achieves higher security in bidirectional synchronous communication. Finally, the multi-channel chaotic communication based on MTDMC-ECSLs greatly enhances the communication capacity between two SLs, providing important guidance for realizing chaotic communication networks. In recent years, Jiang et al. proposed a scheme using dynamically synchronized SLs that are subject to a common dual injection from two mutually coupled SLs. Based on this, they realized a new secure key distribution approach, and this innovative method has achieved high-quality chaotic secure optical communication [31]. The research on the abovementioned mutually coupled systems has all utilized traditional SLs, while synchronous communication using nano-lasers (NLs), which exhibit faster response times and a lower power consumption and are more easily integrated, has not been adequately explored. In a previous work, we achieved chaotic synchronization for secure communication using a unidirectional injection system with NLs [17]. Therefore, in this context, it is appropriate to study the chaotic synchronization and bidirectional communication of mutually coupled NL systems to determine whether such systems can offer new capabilities in the context of photonic integrated circuits (PICs).

It has been found that external-cavity SLs can provide higher security for communication systems and are integral components of chaotic secure communication systems. However, in this case, many scholars have found that laser chaotic communication systems have security vulnerabilities. This is because the process of generating chaotic signals through external optical feedback or external optical injection into SLs inevitably introduces periodicity, known as TDS [32]. The periodicity in the signals can degrade the performance of chaos-based applications. For instance, the presence of time-delay information poses a risk of information leakage, as eavesdroppers can extract transmission signal time-delay information from chaotic signals using time-series analysis techniques such as autocorrelation function (ACF) [32], delay mutual information (DMI) [33], permutation entropy (PE) [34], etc. Consequently, eavesdroppers can obtain the key parameters of the communication system and threaten the security of chaotic secure communication systems by reproducing chaotic secure systems using reconstruction techniques [35]. Therefore, how to conceal TDS in the system is also a hot topic for researchers. In recent years, many published papers have proposed various schemes to reduce or even eliminate TDS [36–43]. On the one hand, complex feedback schemes are considered in the system, i.e., adding multiple feedback paths. On the other hand, multiple injection paths are added, or another SL is introduced, all of which increase the complexity of the system so that the TDS can be concealed over a larger parameter range. Recently, we have completed work on the concealment of the TDS in the open-loop structure, semi-open-loop structure, and closed-loop structure of mutually coupled NLs [44]. The simulation results suggest that, compared to the open-loop and semi-open-loop structures, the closed-loop structure performs better in concealing TDS, almost achieving TDS concealment across the entire parameter plane.

Hence, in this paper, we investigate the chaotic synchronization and bidirectional communication of optical feedback mutually coupled NLs. The paper is organized as follows: in Section 2, the model of closed-loop mutually coupled NLs and the corresponding rate equations are presented in detail. The simulation results are given in Section 3, based on TDS concealment, which focuses on the impact of internal parameters and system parameters on chaotic synchronization and bidirectional communication. Finally, we draw our key conclusions in Section 4.

2. Theoretical Model

The structure of the closed-loop mutually coupled NL system is illustrated in Figure 1. In particular, NL1 and NL2 are bidirectionally coupled through a common channel, and each of them receives two signals: one is its own feedback optical signal, and the other is the injection signal from the opposite NL. Thus, the dynamic characteristics of NL1 and NL2 are jointly determined by these two signals. Additionally, it is noteworthy that NL1 and NL2 operate symmetrically, so they allow for high-quality chaotic synchronization. In this system, the two opposite-direction channels on the common link can be easily separated by a fiber coupler (FC), facilitating duplex communication between NL1 and NL2 (both can serve as both transmitter and receiver simultaneously). Furthermore, the system message security can be further enhanced because the messages are transmitted simultaneously over a common link [22]. For the coding and decoding of messages in this system, the differences between two photodetectors (PDs) are first compared. Then, high-frequency components are eliminated through a Butterworth low-pass filter (LPF), and finally, the transmitted message can be accurately recovered.



Figure 1. The schematic diagram of bidirectional synchronous communication based on closed-loop mutually coupled NLs in a closed-loop system. NL1: the first nano-laser; NL2: the second nano-laser; M: mirror; FC: fiber coupler; OI: optical isolator; OC: optical circulator; EDFA: erbium-doped optical fiber amplifier; OSC: oscilloscope; LPF: low-pass filter; PD: photodetector; D: demodulator; m(t): message; m'(t): decrypted message.

The rate equations for the proposed system are [44–46]:

$$\frac{dS_{1,2}(t)}{dt} = \Gamma \left[\frac{F\beta N_{1,2}(t)}{\tau_n} + \frac{g_n (N_{1,2}(t) - N_0)}{1 + \varepsilon S_{1,2}(t)} \right] - \frac{1}{\tau_p} S_{1,2}(t) + 2kr_{1,2} \sqrt{S_{1,2}(t)} S_{2,1}(t - tr) \cos(\theta_{1,2}(t)) + 2kd_{1,2} \sqrt{S_{1,2}(t)} S_{1,2}(t - td) \cos(\theta_{3,4}(t))$$
(1)

$$\frac{dN_{1,2}(t)}{dt} = \frac{I_{1,2}}{eV_b} - \frac{N_{1,2}(t)}{\tau_n} (F\beta + (1-\beta)) - \frac{g_n(N_{1,2}(t) - N_0)}{1 + \varepsilon S_{1,2}(t)} S_{1,2}(t)$$
(2)

$$\frac{d\phi_{1,2}(t)}{dt} = \frac{\alpha}{2} \Gamma g_n(N_{1,2}(t) - Nth) \pm \Delta \omega - kr_{1,2} \sqrt{\frac{S_{2,1}(t-tr)}{S_{1,2}(t)}} \sin(\theta_{1,2}(t)) -kd_{1,2} \sqrt{\frac{S_{1,2}(t-td)}{S_{1,2}(t)}} \sin(\theta_{3,4}(t))$$
(3)

$$\theta_{1,2}(t) = \pm \Delta \omega t + 2\pi f_{2,1} tr + \phi_{1,2}(t) - \phi_{2,1}(t - tr)$$
(4)

$$\theta_{3,4}(t) = 2\pi f_{1,2}td + \phi_{1,2}(t) - \phi_{1,2}(t - td)$$
(5)

where S(t) is the photon density, N(t) is the carrier density, and $\phi(t)$ is the phase. In these equations, the subscripts '1' and '2' stand for NL1 and NL2, respectively. In this structure, the Purcell factor F, the spontaneous emission coupling factor β , and the bias current I(I = 2Ith) are key internal parameters, where Ith is the threshold current. Some other parameters within the system are the confinement factor Γ , the differential gain g_n , the gain saturation factor ε and the linewidth enhancement factor α , the transparent carrier density N_0 , the threshold carrier density $Nth(Nth = N_0 + 1/\Gamma\tau_p g_n)$, the electron charge e, the volume of the active region V_b ; τ_n and τ_p are the carrier lifetime and photon lifetime, respectively. $\Delta\omega(\Delta\omega = 2\pi\Delta f, \Delta f = f_1 - f_2)$ denotes the angular frequency detuning between NL1 and NL2, where Δf represents the frequency detuning.

It is important to note that the last term in Equations (1) and (3) stands for the feedback term. The term contains both the feedback delay *td* and the feedback strength *kd*, and the expression for *kd* can be formulated as [46]:

$$kd = f(1-R)\sqrt{\frac{R_{ext}}{R}}\frac{c}{2nL}$$
(6)

where *f* denotes the feedback coefficient, *R* represents the cavity surface reflectivity of NLs, R_{ext} is the mirror reflectivity, *c* stands for the speed of light, *n* is the refractive index, and *L* is the length of the feedback cavity. Similarly, in Equations (1) and (3), the penultimate term stands for the injection term, where *kr* and *tr* are the injection strength and injection delay of the injection path, respectively. Here, R_{inj} is the injection ratio, and its calculation formula is written as [46]:

$$kr = (1-R)\sqrt{\frac{R_{inj}}{R}\frac{c}{2nL}}$$
(7)

In this study, we employ the fourth-order Runge–Kutta method to numerically solve Equations (1)–(5). We assumed that the internal parameters of NL1 and NL2 are identical in the system, and noise effects are neglected in the simulations. Noise encompasses both the noise from the NLs and the noise from the detection chain. It is well known that under the injection scheme, the injection delay (*tr*) has minimal impact on the dynamic characteristics of the laser output. Therefore, we assume tr = 0 in the following study. Table 1 lists numerical values for some key parameters used in the simulations.

Table 1. Parameters employed in the numerical simulations [17].

| Parameter | Description | Value |
|-------------|-----------------------------------|---|
| Г | Confinement factor | 0.645 |
| $	au_n$ | Carrier lifetime | 1 ns |
| $	au_p$ | Photon lifetime | 0.36 ps |
| td | Feedback delay | 0.2 ns |
| g_n | Differential gain | $1.64 \times 10^{-6} \mathrm{cm}^3 / \mathrm{s}$ |
| N_0 | Transparency carrier density | $1.1~	imes~10^{-18}~{ m cm}^{-3}$ |
| ε | Gain saturation factor | $2.3 \times 10^{-17} \mathrm{cm}^3$ |
| α | Linewidth enhancement factor | 5 |
| V_b | Volume of active region | $3.96 \times 10^{-13} \mathrm{cm}^3$ |
| λ_0 | Wavelength of NL | 1591 nm |
| R | Laser facet reflectivity | 0.85 |
| R_{ext} | External facet power reflectivity | 0.95 |
| R_{inj} | Injection ratio | 0-0.1 |
| n | Refractive index | 3.4 |
| L | Cavity length | 1.39 μm |
| Q | Quality factor | 428 |
| f | Feedback coupling fraction | 0–0.9 |

To quantitatively assess TDS in numerical terms, we utilize the efficient autocorrelation function (ACF). In the following analysis, we consider that TDS is effectively concealed when the peak value of the ACF is less than 0.2. We express the ACF function using the following equation [32]:

$$C(\Delta t) = \frac{\langle [I(t + \Delta t) - \langle I(t + \Delta t) \rangle] [I(t) - \langle I(t) \rangle] \rangle}{\sqrt{\langle [I(t + \Delta t) - \langle I(t + \Delta t) \rangle]^2 \rangle \langle [I(t) - \langle I(t) \rangle]^2 \rangle}}$$
(8)

where $\langle \rangle$ denotes the average value of the time series, and Δt stands for the lag time. On the other hand, this paper primarily analyzes the synchronization performance of chaotic outputs from the two NLs in the system. To quantify the correlation between NL1 and NL2, we employ the cross-correlation function (CCF), and the defined correlation coefficient is [47]:

$$C_{12}(\Delta t) = \frac{\langle [I_1(t+\Delta t) - \langle I_1(t+\Delta t) \rangle] [I_2(t) - \langle I_2(t) \rangle] \rangle}{\sqrt{\langle [I_1(t+\Delta t) - \langle I_1(t+\Delta t) \rangle]^2 \rangle \langle [I_2(t) - \langle I_2(t) \rangle]^2 \rangle}}$$
(9)

where Δt stands for the displacement between the two chaotic time series, and $\langle \rangle$ is the time average. The subscripts '1' and '2' represent NL1 and NL2, respectively. It should be noted that when |C| = 1, NL1 and NL2 achieve complete synchronization, while there is no correlation between the two lasers when |C| = 0. In this paper, we consider that high-quality chaotic synchronization between NL1 and NL2 is achieved when |C| > 0.95.

3. Numerical Results

In this section, we firstly consider the TDS in the closed-loop mutually coupled NL system. Figure 2 displays the chaotic time series, ACF, and power spectrum plots for NL1 and NL2. The system parameters between NL1 and NL2 are set as follows: the feedback coefficient f1 = f2 = 0.01, $kr_1 = kr_2 = 250 \text{ ns}^{-1}$, and $\Delta f = 25 \text{GHz}$. In addition, F = 14, $\beta = 0.05$, I = 2Ith, and Ith = 1.1 mA. Under these parameter settings, it can be clearly observed that the maximum peak value of the ACF is 0.14, indicating that TDS is effectively concealed, as shown in Figure 2(b1,b2). This suggests that the chaotic behavior of the system has been optimized. What is more, from the power spectra in Figure 2(c1,c2), it can be seen that the power spectra of NL1 and NL2 are remarkably flat under the mentioned parameters, and the bandwidths of NL1 and NL2 are 50.9 and 49.4 GHz, respectively. This result indicates that in the structure of bidirectional synchronous communication, both NLs can achieve chaotic bandwidth. In other words, NL1 and NL2 can facilitate high-speed message transmission, which lays the foundation for subsequent bidirectional synchronous communication. On the other hand, NL1 and NL2 not only exhibit similar ACF curves but also have very similar chaotic time series. Building upon this, the chaotic synchronization between NL1 and NL2 is investigated, as shown in Figure 3. As can be seen, the maximum correlation coefficient C_{12} at the injection delay of NL1 and NL2 exceeds 0.95, which results in high-quality chaotic synchronization.

To this end, in order to discuss the effects of injection strength and frequency detuning on the chaotic synchronization performance of a closed-loop mutually coupled NL system, Figure 4 illustrates the C_{12} with respect to the injection strength kr and frequency detuning Δf . From Figure 4a, it can be seen that C_{12} gradually increases with the gradual increase in kr. When 180 ns⁻¹ < kr < 253 ns⁻¹, C_{12} > 0.95, which confirms the achievement of high-quality chaotic synchronization between NL1 and NL2. As kr is further increased to and beyond 253 ns⁻¹, NL1 and NL2 achieve complete chaotic synchronization due to the significant injection strength leading to injection-locking effects. From a physical point of view, this is attributed to the injection-locking effect caused by an excessively high injection intensity between the two lasers. In this case, injection-locking synchronization makes use of this effect, resulting in the nonlinear output of the lasers behaving identically to the master laser. In turn, when kr = 250 ns⁻¹, chaotic synchronization is maintained over the entire range of $\Delta f = [-30, 30]$, symmetrically about $\Delta f = 0$. Our results show that Δf has a relatively minor impact on achieving chaotic synchronization in the optically feedback mutually coupled NL system as shown in Figure 4b; this is because frequency detuning has a relatively minor impact on injection locking.

Figure 2. The time-series plots (in red), ACF (in blue), and power spectrum (in black) of the chaotic signals from NL1 and NL2. (**a1–c1**): NL1, (**a2–c2**): NL2.

Figure 3. Cross-correlation function (CCF) plots of NL1 and NL2.

With the guidance presented in Figure 4, we present Figure 5 to further explain the distribution pattern of chaotic synchronization. The horizontal axis of the graph represents the frequency detuning, while the vertical axis represents the injection strength. From Figure 5, it is evident that the results of C_{12} change with simultaneous variations in kr and Δf . Specifically, the chaotic synchronization is symmetric about $\Delta f = 0$, and when kr is greater than approximately 200 ns⁻¹, C_{12} exceeds 0.95. Subsequently, as kr gradually increases, chaotic synchronization is achieved throughout the entire plane. On the other hand, C_{12} changes when $\Delta f > 20$ GHz, but this change is small, which is due to the fact

Figure 4. Line plots of the variation in the cross-correlation coefficient C_{12} with (**a**) the injection intensity and (**b**) the frequency detuning.

Figure 5. The two-dimensional colormap of the cross-correlation coefficient C_{12} on the $(kr, \Delta f)$ plane.

For the results obtained above, all parameters of NL1 and NL2 are assumed to be perfectly identical. However, in practical applications, parameter mismatches in chaotic synchronization systems are inevitable. Therefore, it is necessary to investigate the mismatch robustness of the system. For convenience, the parameters of NL1 are kept constant, while those of NL2 are altered. In this paper, we consider five key parameters: the linewidth enhancement factor α , the photon lifetime τ_p , the carrier lifetime τ_n , the differential gain g_n , and the transparent carrier density N_0 . Changing their values will directly impact the synchronization performance. To this end, the parameter mismatch ratio μ is defined as follows [47]:

$$\mu = \frac{\Pi^{NL1} - \Pi^{NL2}}{\Pi^{NL1}}$$
(10)

where Π can take values such as α , τ_p , τ_n , g_n , and N_0 ; the other parameters of NL1 and NL2 have been given above.

Figure 6 depicts the variation in C_{12} with μ at different injection strengths. It can be observed from Figure 6 that the impact of each parameter is different. At moderate kr $(kr = 250 \text{ ns}^{-1})$, C_{12} increases with the introduction of μ , as shown in Figure 6a. The results presented here indicates a strong robustness of chaotic synchronization to internal parameter mismatch in the system, which is conducive to enhancing communication security. When kr is very large, it can be seen from Figure 6b that the value of C_{12} remains consistently high across the entire range of μ ; i.e., the effect of μ on the chaotic synchronization is very small. From a physical perspective, both NL1 and NL2 are subject to injection locking. Figure 7 further presents a two-dimensional colormap of C_{12} with simultaneous variations in μ and kr, where the horizontal axis represents the parameter mismatch ratio, and the vertical axis stands for the injection strength with $\Delta f = 25$ GHz. As can be seen from Figure 7, C_{12} is greater than 0.95 throughout the entire plane when $kr > 150ns^{-1}$. However, at moderate injection strength levels and μ in the range (-0.1, 0), C_{12} significantly increases, and the synchronization is better. This result is consistent with Figure 6, which further verifies that the system is robust to parameter mismatch; that is, the impact of parameter mismatch on synchronization is not significant.

Figure 6. The effect of parameter mismatch on the synchronization performance of the system at different injection strengths. $\Delta f = 25$ GHz. (a) kr = 250 ns⁻¹; (b) kr = 500 ns⁻¹.

Figure 7. The two-dimensional colormap of the cross-correlation coefficient C_{12} on the (μ, kr) plane.

It is meaningful to evaluate the achievable transmission bandwidth of the proposed scheme before proceeding with message encoding and decoding. Since the outputs of NL1 and NL2 are almost identical, it is sufficient to study the bandwidth of NL1 here. Figure 8 displays the spectra for different values of *F*, β , and two injection currents *I*. From these spectra, it can be seen that the bandwidths for the (*F*, β) values (14, 0.05), (14, 0.1), and (30, 0.1) are 50.9, 7.1, and 2.5, respectively. In comparison, under the same (*F*, β) settings, for higher threshold *I* = 4*Ith*, the bandwidths are 65.7, 32.1, and 16.1, respectively. These results indicate that a chaotic bandwidth can be achieved in all considered scenarios, which means that NL1 and NL2 can achieve high-speed message transmission. However, when *I* = 2*Ith*, noticeable frequency spacings can be observed in the spectra for *F* = 14, β = 0.1, and *F* = 30, β = 0.1, as shown in Figure 8(a2,a3). This implies potential information leakage, which is closely related to TDS. Therefore, the selected values of *F* = 14, β = 0.05, and *I* = 2*Ith* in our study, as exhibited in Figure 8(a1), are more suitable.

Figure 8. Spectra of NL1 at different values of *F*, β , and *I*. (**a1–a3**): *I* = 2*Ith*, (**b1–b3**): *I* = 4*Ith*. (**a1,b1**): *F* = 14, β = 0.05. (**a2,b2**): *F* = 14, β = 0.1. (**a3,b3**): *F* = 30, β = 0.1.

Finally, we focus on the encoding and decoding process of bidirectional messages. In this system, NL1 and NL2 denote the communication pair (NL1 and NL2 can function as both the transmitter and the receiver), and we assume that NL1 and NL2 operate at the operating point shown in Figure 1, where the TDS of the chaotic carrier is very low, and the bandwidth is large (as in Figure 8(a1)). At the transmitter, the message is modulated onto the chaotic carrier via chaotic modulation (CM), expressed mathematically as [17,47]: $I_{1m,2m}(t) = I_{1,2}(t)[1 + hm_{1,2}(t)]$, where $I_m(t)$ is the modulated carrier transmitted over the public channel, m(t) stands for the original message, and h represents the modulation depth. At the receiver, the received modulated chaotic carrier is subtracted from the local chaotic carrier, and the resulting difference signal is passed through an LPF to recover the message.

Figures 9–11 illustrate the results of the message encryption and decryption processes in bidirectional communication. For observation and illustration purposes, we shift the original message upward by 3.1 (depicted in blue in Figures 9(a1,a2), 10(a1,a2), and 11(a1,a2)). In this paper, the performance of the chaotic communication system is measured using the *Q*-factor and eye diagram. This is because calculating the *Q*-factor is one of the most effective methods to directly reflect the system's bit-error rate (BER)

without requiring the extensive computational load involved in calculating the BER. The mathematical expression for the Q-factor is [5]: $Q = (I_1 - I_0)/(\sigma_1 + \sigma_0)$, where I_1 and I_0 are the average powers of bit "1" and bit "0" in the demodulated message, respectively, and σ_1 and σ_0 are their corresponding standard deviations. It is underlined that, when Q > 6, the communication performance of the system is considered acceptable. Firstly, when the *kr* is moderate and there is no parameter mismatch, the bidirectional message transmission process is simultaneously explored in the results shown in Figure 9. The blue indicates the original message at the transmitter, and the red represents the corresponding recovered message at the receiver. It can be observed that NL1 and NL2 can recover the message, and the Q during decryption reaches approximately 8.7, which indicates that NL1 and NL2 can achieve bidirectional synchronous communication, and the communication performance of the two NLs is similar. Next, we further consider the parameter mismatch of NL2 [47], i.e., $\tau_n^{NL2} = (1+\mu)\tau_n^{NL1}$, $\tau_p^{NL2} = (1-\mu)\tau_p^{NL1}$, $g_n^{NL2} = (1-\mu)g_n^{NL1}$, $N_0^{NL2} = (1+\mu)N_0^{NL1}$, $\alpha^{NL2} = (1-\mu)\alpha^{NL1}$. Figure 10 depicts the process of bidirectional synchronous communication at $kr_1 = kr_2 = 250 \text{ ns}^{-1}$ and $\mu = -0.05$, from which it is apparent that the eye diagram has widened and Q has increased to 9.5, indicating complete message recovery. Finally, increasing kr to 500 ns⁻¹, μ is still equal to -0.05; the results are shown in Figure 11. The message can still be completely recovered, with Q = 9.7. It is worth noting that the increase in kr enhances the quality of synchronous communication but may compromise the security of the system. The conclusions from this section are consistent with the results in Figures 6 and 7, which further demonstrate the system's strong robustness to parameter mismatch, where parameter mismatch can enhance synchronous communication performance.

Figure 9. The encoding and decoding process of NL1 and NL2. h = 0.8, 8 Gbit/s original message. $kr_1 = kr_2 = 250 \text{ ns}^{-1}$, $\Delta f = 25 \text{ GHz}$, $\mu = 0$. (**a1,b1**) NL1 decryption and eye diagram, (**a2,b2**) NL2 decryption and eye diagram. In the first row, blue—original message m(t), red—recovered message m'(t). The original message is shifted upward by 3.1.

Figure 10. The encoding and decoding process of NL1 and NL2. h = 0.8, 8 Gbit/s original message. $kr_1 = kr_2 = 250 \text{ ns}^{-1}$, $\Delta f = 25 \text{ GHz}$, $\mu = -0.05$. (**a1,b1**) NL1 decryption and eye diagram, (**a2,b2**) NL2 decryption and eye diagram. In the first row, blue—original message m(t), red—recovered message m'(t). The original message is shifted upward by 3.1.

Figure 11. The encoding and decoding process of NL1 and NL2. h = 0.8, 8 Gbit/s original message. $kr_1 = kr_2 = 500 \text{ ns}^{-1}$, $\Delta f = 25 \text{ GHz}$, $\mu = -0.05$. (**a1,b1**) NL1 decryption and eye diagram, (**a2,b2**) NL2 decryption and eye diagram. In the first row, blue—original message m(t), red—recovered message m'(t). The original message is shifted upward by 3.1.

4. Conclusions

In this paper, we systematically and numerically investigate the system of two mutually coupled NLs under the influence of optical feedback. The Lang–Kobayashi equations are employed for modeling, and the impact of internal parameter mismatches and injection parameters on chaotic synchronization and communication is discussed. Our research results demonstrate that the system can simultaneously meet the requirements of large bandwidth and low TDS during chaotic synchronization. Based on this, in terms of chaos synchronization performance and bidirectional message transmission, some large parameter mismatches can still maintain high-quality synchronization and communication performance, which indicates the system's strong robustness. These findings confirm the feasibility of the proposed scheme. Therefore, this study has significance for guiding and achieving higher security in chaotic secure communication using novel NLs in future research.

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