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Analysis of a Supercapacitor/Battery Hybrid Power System for a Bulk Carrier

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Abstract: Concerns about harmful exhaust emissions from ships have been an issue. Specifically, the emissions at ports are the most serious. This paper introduces a hybrid power system that combines conventional diesel generators with two different energy storage systems (ESSs) (lithium-ion batteries (LIB) and supercapacitors (SC)) focused on port operations of ships. To verify the proposed system, a bulk carrier with four deck cranes is selected as a target ship, and each size (capacity) of LIB and SC is determined based on assumed power demands. The determined sizes are proven to be sufficient for a target ship through simulation results. Lastly, the proposed system is compared to a conventional one in terms of the environmental and economic aspects. The results show that the proposed system can reduce emissions (CO_2 , SO_X , and NOx) substantially and has a short payback period, particularly for ships that have a long cargo handling time or visit many ports with a short-term sailing time. Therefore, the proposed system could be an eco-friendly and economical solution for bulk carriers for emission problems at ports.

Keywords: hybrid power system; lithium-ion battery (LIB); supercapacitor (SC); alternative maritime power (AMP); bulk carrier

1. Introduction

Although road vehicles currently represent about 70% of total greenhouse gas (GHG) emissions in the transport sector, other forms of transport—including aviation, maritime, and off-road vehicles—are also substantial emissions sources and are expected to see continued growth in the coming years. Specifically, the maritime sector is expected to rise gradually because of its slower improvement efficiency compared to other vehicles; its GHG share is expected to increase from 10% in 2018 to 20% in 2060 among the global transport-related GHG emissions [1].

In this regard, many countries and the international maritime organization (IMO) have been implementing environmental regulations or policies, especially in emission-control areas (ECAs), which are designated areas near ports where ships are required to further reduce emissions. For example, the sulfur limit is currently 0.1% within ECAs; it is 35 times stricter than the outside ECAs. These strict regulations are related to the fact that premature deaths have been increasing each year due to cardiopulmonary disease and lung cancer caused by pollutants emitted from ships at ports [2]. Shipping emissions in East Asia accounted for 16% of global shipping CO₂ in 2013, compared to only 4%–7% in 2002–2005. This increase in emissions resulted in large adverse health impacts, with 14,500–37,500 premature deaths per year [3].

Therefore, ship owners have been making efforts to reduce harmful emissions using exhaust gas treatment systems such as sulfur dioxide (SO_X) scrubbers, selective catalyst reactors (SCRs), or changing ship fuels from heavy fuel oil (HFO) to liquefied natural gas (LNG) or marine gas oil (MGO), etc.

In addition, major ports have been expanding shore power facilities (or alternative maritime power (AMP)), which can supply electric power for ships from land-based electric power plants while staying at a port. Notably, low voltage AMP facilities have already been installed in many dominant ports worldwide. Additionally, high voltage (3.3kV, 6.6kV, 11kV, etc.) AMP facilities are being installed in major ports for large ships such as in the U.S., Canada, European countries, China, etc., and the European Union (EU) requires European ports to offer shore-based electricity to ships by 2025.

In this regard, hybrid systems using an energy storage system (ESS) have gained attention as an alternative solution to solve the environmental issues in the marine industry, and research regarding hybrid systems has already been performed. For example, Lan et al. [4] proposed a hybrid system combined with a photovoltaic (PV) generation system, a diesel generator, and batteries. Choi et al. [5] and Han et al. [6] each proposed a fuel cell–battery hybrid system for a boat. In addition, Ovrum et al. proposed a hybrid system with lithium-ion batteries (LIBs) and diesel generators for a bulk carrier [7].

However, there is not much research regarding the supercapacitor (SC) and LIB hybrid system yet, except for some research focused on small ships; Trieste et al. chose a SC as the power source for a ferry and proposed a charging strategy [8], and Bellache et al. investigated the LIB–SC hybrid system to improve the dynamic response of a boat [9]. On the contrary, many research studies have been conducted to develop the LIB–SC hybrid system for land vehicles, especially in [10–14]; these are SC–LIB hybrid systems for electric cars. These results show that the hybrid system could improve system performance by overcoming individual limitations (disadvantages) and enabling synergistic effects. In other words, LIBs, which are the most common battery types, have a high energy density; however, their power densities are low compared to that of an SC of the same size. Also, LIBs have a short life cycle compared to an SC, which has an approximately 1000× longer life cycle than LIBs (refer to Table 1).

Туре	Energy Density	Power Density	Life Cycles	Voltage	Charging/Discharging
	(Wh/kg)	(W/kg)	(cycles)	(V/cell)	Time
Lithium-ion Battery (LIB)	150~250	50~2,000	500~2,000	3.6~4.2	Minutes ~ Hours
Supercapacitor (SC)	5~10	~100,000	500,000~2,500,000	2.7~3.0	Seconds ~ Minutes

Table 1. Comparison between lithium-ion batteries (LIBs) and supercapacitors (SCs) [15–20].

This paper proposes an SC–LIB hybrid system for a ship focused on port operations, where most emissions are caused by onboard engine-generator sets (gensets). The rest of this paper is structured as follows: in Section 2, detailed explanations of a target ship and the proposed system are presented. In Section 3, the capacity (size) of the LIB and SC is determined with the given assumed operating conditions. And in Section 4, harmful exhaust emissions at a port are calculated and compared between the conventional system and proposed one based on simulation results. Additionally, an economic study for the entire lifetime of a ship is performed in that section. Lastly, the results are reviewed along with a conclusion. The novelty of this paper is a new approach toward the eco-friendly power system of a bulk carrier using two kinds of ESSs.

2. System Description

2.1. Target Ship

In this paper, a medium-sized bulk carrier was selected as the target ship. The target ship's deadweight was about 50,000 tons, and it had five hatches. The target ship was fitted with three gensets as power sources and four electric-driven deck cranes (Figure 1). In addition to these deck cranes, windlass/mooring winches were also of the electric-driven type controlled by each motor drive. Although hydraulic-driven equipment has been used for a long time, it has many disadvantages including low efficiency, high noise and vibration, high maintenance cost, pollution risk through oil, etc. [21]. Therefore, the use of electric-driven equipment has been increasing in the marine industry.



Figure 1. Typical layout of a bulk carrier with deck cranes [22].

In general, this kind of bulk carrier has four (4) operation modes, as below:

- Normal seagoing mode (at sea);
- Port in/out mode (near a port);
- Cargo loading/unloading mode (at a port);
- Harbor mode (at a port).

First, in the normal seagoing mode, the heaviest electric load is the main engine (M/E) auxiliaries and engine room auxiliaries to propel the ship, and additional electric power is required to maintain the living environment for crews at sea. In the port in/out mode, the heaviest load is the windlass/mooring winches, which are used for lowering/pulling an anchor or hauling-in/winding mooring ropes. The second heaviest load is the ballast pumps, which are used for pumping water into/out from ballast tanks in preparation for cargo loading/unloading or cargo hold cleaning. Additionally, the load on the main air compressors and M/E auxiliary blowers also increases because of the slower speed or frequent stops of a ship while approaching/departing a port.

In the cargo loading/unloading mode, the heaviest load is the onboard deck cranes used for cargo loading or unloading to the shore-side, which is a highly repetitive process. The second heaviest load is the ballast pumps, which ensures the stability of a ship even though its weight is changed during (un)loading cargo. Lastly, in the harbor mode, the majority of the load comes from the activities of crews such as from the air conditioner compressor, lighting, galley, and laundry equipment, etc.

2.2. Conventional System

The simple layout of a conventional power system is shown in Figure 2. Even though three gensets are installed as power sources, the number of gensets in operation is different depending on the power required for each operation mode. Primarily, only one genset is in operation in the normal seagoing mode with about 54.3% load factor (Table 2). The second generator is only used for the port in/out operations or the crane operations, and the last one is installed for redundancy.

	Mode	1 Normal Seagoing	② Port In/Out	③ Load/Unload	④ Harbor
Maximum demand power		380 kW	700 kW	1015 kW	250 kW
Conventional system	Power sources Gensets in use (load factor)	G1 1 × 700 kW (54.3%)	G1 + G2 2 × 700 kW (50.0%)	G1 + G2 2 × 700 kW (71.4%)	G1 1 × 700 kW (35.7%)
Proposed system	Power sources Gensets in use (load factor)	G1' 1 × 500 kW (76.0%)	G2 + LIB 1 × 700 kW (71.4%)	AMP + SC	AMP -

Table 2. Comparison of power demands between a conventional and the proposed system.



Figure 2. Layout of a conventional power system.

The steps for one voyage cycle in a conventional system are shown in Figure 3. Step 3 includes not only deck crane operation for cargo handling but also simply staying at a harbor. In this study, it was assumed that three (3) of four (4) deck cranes were in operation during cargo handling, because safety risks would be increased if all cranes were in operation simultaneously.



Figure 3. Docking/undocking procedure of a ship in a conventional system.

2.3. Proposed System

In the proposed system, one of the onboard gensets was replaced with two kinds of ESSs (LIB and SC). The LIB and SC were used as a power source during port operations. Also, one of the remaining gensets was downsized from 700 kW to 500 kW to obtain a higher fuel efficiency in the normal seagoing mode. The layout of the proposed power system is shown in Figure 4.



Figure 4. Layout of the proposed power system.

The reason for adopting two different ESSs was that each **has** different characteristics as an energy storage system. In the case of port in/out operations, high load demand occurred only twice (port-in and port-out). Thus, the LIB was more suitable because of its high energy density. On the other hand, the SC was more suitable for highly repetitive deck crane operations because of its long life cycle capacity and high power density. Therefore, the number of gensets in operation in each mode was changed, as shown in Table 2, and it was shown that load factors of the onboard gensets increased to above 70% even in the normal seagoing mode and port in/out mode. In the proposed system, two steps were added for one voyage cycle, as shown in Figure 5, because of the AMP connection/disconnection processes for shore power.



Figure 5. Docking/undocking procedure of a ship in the proposed system.

3. Proposed Hybrid Power System

The main purpose of the proposed system was to reduce harmful emissions at ports (especially in ECAs) rather than in the normal seagoing mode at sea. In the port in/out mode, in which additional power is required for a short time, the LIB was selected as an auxiliary power source that replaced a stand-by onboard genset. In the cargo loading/unloading mode, in which additional power is repeatedly required hundreds to thousands of times depending on cargo quantity, the SC and AMP were selected as the main power sources that replaced onboard gensets.

3.1. Port In/Out Mode

In this mode, the mooring and windlass winches were the heaviest loads unless bow thrusters were installed onboard. The combined windlass/mooring winch, which is used to handle both anchors and mooring ropes together, is typically installed towards the fore side of a ship, and mooring winches are installed towards the aft side. The specifications of the selected winches are described in Table 3.

	Classification	Specification
	Туре	Electric-Driven Type
Rated motor capacity	Combined windlass/mooring winch Mooring winch	100 kW \times 2 (Forward) (one is standby) 50 kW \times 3 (AFT) (one is standby)
Rated pulling force Combined windlass/mooring winch Mooring winch		300 kN 150 kN
Motor drive type		Active front-end (bi-directional) type
Electric voltage		AC 440 V

Table 3. S	Specifications	of wind	lass/moo	ring w	vinches.
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The regenerated power rate when lowering an anchor was difficult to define due to various factors such as the inertia of the motor, angular speed, rotation speed, and mechanical loss, etc. [23]. Therefore, regenerated power rate was assumed to be about 50%, according to similar cases [7,24,25]. The power demands for one operation cycle were assumed, as shown in Table 4, based on empirical evidence from crews. In this study, the instantaneous peak braking and initial starting power were not taken into consideration for simulation simplification. Based on the battery manufacturer's datasheet, the specifications of the selected LIB modules are shown in Table 5.

	Operation Mode	Time (min)	Power (kW)	Energy (kWh)
	 Lowering (heaving up) an anchor 	5	-50	-4.15
Port-in	② Veering out and hauling in mooring ropes to the port side	10	200 ¹	33.40
	Total	15	-	29.25
	③ Pulling (hoisting) an anchor	10	100	16.70
Port-out	④ Winding mooring ropes to onboard rope drums	10	150 ²	25.05
	Total	20	-	41.75

	Table 4.	Expected	power	demands for	the	port in	/out mode.
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 1 Combined windlass/mooring winch (100 kW \times 1), mooring winch (50 kW \times 2). 2 Combined windlass/mooring winch (50 kW \times 1), mooring winch (50 kW \times 2).

Table 5. Specificati	ons of the selected	LIB module [26].
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Category	Specification
Cell type	Lithium nickel manganese cobalt oxide (NMC)
Nominal voltage	88.8 V _{DC}
C-rate	Max. 1.4 C (continuous)
Stored energy	10 kWh
Capacity	112 Ah
Weight	90 kg
Size (m)	$0.58~(L) \times 0.32~(W) \times 0.38~(H)~(0.0705~m^3)$

The minimum capacity of the LIB is calculated as shown below [27]:

$$C_{\min} = (E_d \times k_a) / (V_{dc} \times k_{DoD} \times k_e) (Ah), \qquad (1)$$

where C_{min} (Ah) is the minimum battery capacity, E_d (VAh) is the demanded energy, V_{dc} (V) is the nominal battery voltage, k_{DoD} is the battery depth of discharge (DoD), k_a is the battery aging factor, k_e is the system efficiency, and other factors are not considered. In this case, k_e was set to 0.9, k_a was set to 1.2, and k_{DoD} was set to 0.8, assuming that the operating range of the state of charge (SOC) was 10%–90%. The output voltage of the SC pack was determined to be DC 355 V, which was achieved by arranging four (4) battery modules in series. Moreover, two (2) parallel strings were required to meet the demanded energy capacity. Therefore, C_{min} was calculated to be about 196.0 Ah, and the designed battery capacity (E_{LIB_design}) was calculated to be about 76.5 kWh, incorporating a 10% safety margin (k_s) as below. The specifications of the selected LIB pack are shown in Table 6. This LIB pack was split into two sets with the same capacities, and installed at different places for safety reasons.

$$E_{LIB_design} = C_{min} \times V_{dc} \times k_s = 196.0 \text{ Ah} \times 355 \text{ V} \times 1.1 \cong 76.5 \text{ (kWh)} < 80 \text{ (kWh)}.$$
(2)

Category	Specification
Target terminal voltage	355 V
Configuration	2 strings \times 4 modules in series
Usable energy	80 kWh
Total weight (8 modules)	720 kg
Total size (8 modules)	0.5642 m^3

Table 6. Specifications of the selected LIB pack.

3.2. Cargo Loading/Unloading Mode

In this mode, the onboard deck cranes were the heaviest loads, and they needed repetitive peak power while unloading or loading cargo. These cranes were generally required to perform three functions, namely, to hoist/lower, to luff and to slew.

- Hoisting (lowering) is bringing up (down) a crane wire while a crane jib remains in a constant position.
- Luffing is the raising or lowering of a crane jib.
- Slewing is the swinging round (or rotation) of a crane.

Among these crane operations, the biggest load is the hoist motor, which raises and lowers cargo. When lowering the cargo, the motor drive must be capable of handling the inverse power by feeding it back to the onboard main power grid. The specifications of the selected deck crane are shown in Table 7.

Classification		Specifications	
Crane type		Electric-driven type	
Hoisting max. ca	pacity	30 t	
Max. lifting he	eight	40 m	
Crane weight		45 t	
Hoisting/slewing speed		20 m/min (full load) 40 m/min (no load)	
Luffing speed		10 m/min (full load)	
Hoisting		145 kW	
Motor rated nowor	Luffing	90 kW	
Motor rated power	Slewing	40 kW	
	Grab	20 kW	
Motor drive type		AFE (bi-directional) type	
Electric volta	ge	AC 440 V	

Table 7.	Specificatio	ons of the	selected	deck crar	ne.
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The power demand for hoisting or luffing is dependent on the weight required to carry the cargo by a crane, as shown in the below equation. The crane jip weight (m_j) is only applied to the luffing operation [28,29]:

$$P_{\text{hoist}} = (m_{\text{h}} \times v_{\text{h}}) / (6.12 \times \eta) = ((m_{\text{load}} + m_{\text{g}} + (m_{\text{j}})) \times v_{\text{h}}) / (6.12 \times \eta) \text{ (kW)}, \tag{3}$$

where, m_h (t) is the hoisting weight, m_{load} (t) is the cargo load weight, m_g (t) is the grab weight, v_h (m/min) is the hoisting speed, and η is the mechanical efficiency. In this study, m_{load} was set to the maximum load of 30 t, m_g was assumed to be 5 t, m_j was 10 t, and η was 0.85. The power demand for slewing was also dependent on the weight required to turn the load by a crane, as shown below:

$$P_{slew} = (m_s \times v_h) / (6.12 \times \eta) = ((m_{load} + m_{st}) \times R_S \times v_s) / (6.12 \times \eta) (kW),$$
(4)

where, m_s (t) is the slewing weight, m_{st} (t) is the weight of the slewing structure, R_s is the resistance to slewing, v_s (m/min) is the slewing speed, and η is the mechanical efficiency. In this study, it was assumed that m_{st} was 10 t, η was 0.85 and R_s was 0.2. The regenerative power rate was assumed to be 50% according to similar cases [7,24,25] as mentioned in Section 3.1. There are ten (10) steps for a deck crane operation, and the expected power demands for one cycle are assumed, as shown in Table 8, based on the empirical evidence from crews. Then, the minimum energy of the SC pack (E_{sc_min}) was obtained through the demand energy (E_{sc_demand}), aging factor (k_a), safety factor (k_s), and the system efficiency of (k_e). If k_a was assumed to be 1.2, k_s was assumed to be 1.1, and k_e was assumed to be 0.9, The E_{sc_min} is calculated as below:

 $E_{sc_min} = E_{sc_demand} \times (k_a/k_e) \times k_s = 1,005.92 \text{ (Wh)} \times (1.2/0.9) \times 1.1 \cong 1.48 \text{ (kWh)} \cong 5,311 \text{ (kJ)}.$ (5)

No.	Step	Time (s)	Power (kW)	Energy (Wh)
1	Lowering with no load	20	-19.2	-106.68
2	Grab (close)	10	20.0	55.56
3	Hoisting with full load	25	134.6	934.66
4	Luffing in (up)	5	86.5	120.15
5	Slewing to port side	15	34.6	144.18
6	Lowering with full load	15	-67.3	-280.44
\overline{O}	Grab (open)	5	20.0	27.78
8	Hoisting with no load	10	38.4	106.68
9	Slewing to ship side	10	23.1	64.17
10	Luffing out (down)	5	-43.3	-60.14
Total About 4 min/cycle (including overhauling time)		1005.92 Wh/cycle		

Table 8. Expected power demands for deck crane operations.

In most applications, the SC pack is assembled in modules, and these are connected in series and parallel to increase both the working voltage and overall capacitance. The total capacitance of the SC pack ($C_{SC,t}$) is then evaluated as:

$$C_{SC,t} = C_{SC,module} \times (P/S) (F), \tag{6}$$

where P is the number of parallel strings and S is the number of series modules. The selected SC module specifications are as shown in Table 9. Then, the SC pack capacity was calculated using Equation (7).

$$E_{SC} = (1/2) \times C_{SC,t} \times V_{SC,t}^{2} (J),$$
 (7)

where $V_{SC,t}$ is the voltage of an SC pack, which is proportional to the number of SC modules. In general, the voltage variation of an SC pack is to be kept between 100% and 50% of its maximum voltage. As shown in Figure 6, the LIB offers a fairly constant discharge voltage performance throughout the spectrum of usable energy, whereas the SC voltage shows a linear and decreasing behavior from the maximum value up to 50% in general. Even if the stored energy is proportional to the product of the capacitance for the square of the voltage, the delivered power decreased in the discharging phase because the current is limited [31,32]. Thus, the available energy of the designed SC pack (E_{SC_design}) is calculated by the following equation [31,33]:

$$E_{SC_{design}} = (1/2) \times C_{SC,t} \times (V_{SC,t,max}^2 - V_{SC,t,min}^2) = (1/2) \times C_{SC,t} \times (V_{SC,t,max}^2 - ((1/2) \times V_{SC,t,max}))^2) = (3/8) \times C_{SC,t} \times V_{SC,t,max}^2 (J),$$
(8)

where $V_{SC,t,max}$ is the maximum terminal voltage, and $V_{SC,t,min}$ is the minimum terminal voltage of the SC pack. If the output voltage of the SC pack was determined to be DC 625 V, which was achieved by

arranging five (5) SC modules in series, then, the SC pack needed have three (3) parallel strings to obtain the demand capacity according to the below equation:

$$E_{sc_design} = (3/8) \times (C_{SC,module} \times (P/S)) \times V_{SC,t,max}^2 = (3/8) \times (63 \text{ (F)} \times (3/5)) \times (625 \text{ (V)})^2 \cong 5,537 \text{ (kJ)} \cong 1.54 \text{ (kWh)} > 1.48 \text{ (kWh)}.$$
(9)

The design specifications of the SC pack are as shown in Table 10. If the SC pack was discharged, it could be charged with a C-rate of 180 within about 20.1 seconds during the luffing (10) and lowering (1) steps.

Category	Specification				
Rated capacitance	63 F				
Rated voltage	125 V				
Max. initial equivalent DC series resistance (ESR _{DC})	18 mΩ				
Max. leakage current (at 25 °C)	10 mA				
Number of cells	48 in series				
Stored energy	140 Wh				
Usable specific power	1700 W/kg				
Specific energy	2.3 Wh/kg				
Cycle life (at 25 °C)	1,000,000 cycles				
Weight	61 kg				
Size (m)	$0.619 (L) \times 0.425 (W) \times 0.265 (H) (0.0697 \text{ m}^3)$				

Table 9. Specifications of the selected SC module [30].



Figure 6. Comparison of charging/discharging characteristics between SC and LIB.

Table 10. Specifications of the selected SC pack.

Category	Specifications
Target terminal voltage	625 V
Configuration	3 strings \times 5 modules in series
Usable energy	5537 kJ (1.54 kWh)
Total weight (15 modules)	915 kg
Total size (15 modules)	1.0455 m^3

4. Results and Discussion

4.1. Simulation Results

A simulation was conducted using MATLAB/Simulink (MathWorks, Natick, MA, USA) which is a graphics-based simulation environment to validate whether the determined capacities of the LIB and SC packs were suitable for each required power demand. Figure 7a shows the LIB pack with two parallel strings of four modules each, as indicated in Table 6. Figure 7b presents the SC pack with three parallel strings of five modules each, as specified in Table 10. Each LIB and SC pack was charged or discharged according to each required power demand, shown in Tables 4 and 8. The LIB and SC modules used in the simulation were the generic models provided in Simulink. The applied parameters were obtained from the data in Tables 5 and 9, which were based on the manufacturer's specifications [26,30], and the other parameters were assigned predetermined default values in the model (Table 11).



(a) LIB pack model.

(b) SC pack model.

Model Description Value Unit V Nominal voltage 88.8 Rated capacity 112 Ah Li-ion Battery (LIB) Fully charged voltage 103.36 V Nominal discharge 48.70 А current 7.93 Internal resistance mΩ Rated capacitance 63 F Rated voltage 125 V Surge voltage 130 V Supercapacitor (SC) Initial voltage 122 V Equivalent DC series 18 mΩ resistance (ESR_{DC}) Leakage current 10 mΑ

Figure 7. Simulation models of the proposed energy storage systems (ESSs).Table 11. Applied parameters of LIB and SC modules for the simulation.

The change in the voltage and SOC of the designed LIB pack according to the power demand is shown in Figure 8. The lowest SOC of the LIB pack was 49.3% after port-in, and 40.1% after port-out, so the capacity of the designed LIB pack was sufficient for windlass/mooring winch operation. In other words, its SOC was within the limited operating range (10%–90%). The change in the voltage and SOC of the designed SC pack during cargo handling is shown in Figure 9. The lowest SOC of each SC pack was 67.7% after the first operation cycle, so the designed SC pack capacity was sufficient for deck crane operation. In other words, its SOC was within the limited operating range (50%–100%), and it could be recharged by shore power for a short time during steps 1 and 10, as mentioned in Section 3.2.



Figure 8. LIB pack voltage and state of charge (SOC) changes (port in/out mode).



Figure 9. SC pack voltage and SOC changes (deck crane mode).

4.2. Fuel Consumption and CO₂ Emissions

The fuel consumption of a genset varies depending on the load factor, as shown in Figure 10, and the lowest fuel consumption is between 70%–85%. In this study, this graph was used to calculate the fuel consumption of the gensets. The emissions from fuels can be calculated by multiplying the fuel consumption of the onboard engine with the emission factor (E_f). This E_f varies according to the engine type (main and auxiliary engines, auxiliary boilers), engine rating, engine speed, type of fuel, etc. [34].

Total emissions (kg) = Fuel consumption
$$\times E_{\rm f}$$
. (10)



Figure 10. Example of a genset fuel consumption graph [35].

For CO₂ emissions, the E_f for each fuel type was based on IMO guidelines [36]. The E_f of HFO was 3.114 based on its lower calorific value of 40,200 kJ/kg and carbon content of 0.8493. The E_f of MGO was 3.206 based on its low calorific value of 42,700 kJ/kg and carbon content of 0.8744. And, the E_f of SO_X emissions was calculated by multiplying 0.02 with the sulfur content S (%) present in the fuel. In the case of MGO, S (%) did not exceed 0.1 %, whereas the average value of HFO was 2.7%. The E_f used for NO_X emissions was the suggested value for Tier I ships without the use of a scrubber system. These emission factors are summarized in Table 12 [37]. Based on the emission factors, the emissions from onboard gensets for the conventional power system were calculated as shown in Table 13, and those for the proposed power system were calculated as shown in Table 14.

Table 12. Emission factors for different pollutant ty	pes.
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Fuel		Emission factors	
ruei	CO ₂ (g·CO ₂ /g·fuel)	SO_X (g· SO_X /g·fuel)	NO_{χ} (g· NO_{χ} /g·fuel)
Heavy Fuel Oil (HFO)	3.114	0.054	0.057
Marine Gas Oil (MGO)	3.206	0.002	0.057

Table 13. Emissions from onboard gensets for each mode (conventional system).

Ma	1.	Electric Power	Time (h)	Fuel Efficiency	Fuel (kg)	Emissions (kg)		
Mode		Demand (kW)	Time (ii)	(g/kWh)	Tuer (kg)	CO ₂	sox	NO _X
Normal seagoi	ng (10 days)	380	240	195	17,784.0	55,379.38	960.34	1013.69
	Excluding winch loads	500	2 [38]		198.0	634.79	0.40	11.29
Port in/out	Winch (Port-in)	29.25 kWh (Table 4) 41.75 kWh (Table 4)		198	5.8	18.59	0.01	0.33
	Winch (Port-out)				8.3	26.61	0.02	0.47
	Excluding crane loads	550	120 ¹	102	12,672.0	40,626.43	25.34	722.30
Cargo loading/unloading	Crane loads (3 cranes)	1.01 kWh × 3 1800 cycle ² (7	each × Table 8)	192	1047.2	3357.32	2.09	59.69
Harbor		250	48	213	2556.0	8194.54	5.11	145.69
Total			-		34,271.3	108,237.66	993.31	1953.46

¹ Assuming crane operators work in shifts of 6 h (120 h = 6 h \times 20 turns) [39]. ² Assuming each crane was operated for 15 cycles per hour (1800 cycles = 120 h \times 15 cycles).

Mode		Electric Power	Time (h)	Fuel Efficiency	Fuel (kg)	Emissions (kg)			
	moue		Demand (kW)	Time (ii)	(g/kWh)	Emissions (kg) Emissions (kg) (g/kWh) Fuel (kg) CO_2 SO_X NO_2 191 17,419.2 54,243.39 940.64 992.8 191 6.8 21.18 0.37 0.39 192 192.0 615.55 0.38 10.94 17,618.0 54,880.12 941.39 1004.	NOX		
	Normal seagoing	Ship loads	380	240	191	17,419.2	54,243.39	940.64	992.89
Ship power (AMP) -	(10 d)	LIB Charging (After port-out)	80 kWh × (85%	6–40.1%)	191	6.8	21.18	0.37	0.39
	Port in/out (Excluding winch loads)		500	2	192	192.0	615.55	0.38	10.94
	Total			-		17,618.0	54,880.12	941.39	1004.23

Table 14. Emissions from onboard gensets for each mode (proposed system).

Even though the ESS did not generate harmful emissions directly at a port, the emissions were generated indirectly, because it had to be recharged using the AMP; shore power was originally transferred from land-based power plants. Thus, the generated emissions from the used shore power were calculated as shown in Table 15. In this study, emission factors that generated 1 kWh of electricity were assumed to be 151 g·CO₂/kWh, 0.03 g·SO_X/kWh, and 0.16 g·NO_X/kWh based on a European electricity company [40]. This value changed depending on the country. For example, in Denmark where the dominant electricity power source is from wind power plants (about 44%, 2016) [41], the total CO₂ emission factor is 75 g/kWh, whereas the world average is 507 g/kWh [42].

Table 15. Emissions from shore charging (proposed system).

	Mode		Electric Power Demand (kW)	Time (h)	Emissions (kg)		g)
	moue				CO ₂	$\mathbf{SO}_{\mathbf{X}}$	NOX
		Excluding crane loads	550	120	9966.00	1.98	10.56
Shore power (AMP)	Cargo loading/unloading	Crane loads (SC charging)	1.54 kWh × 3 each × (97.4%–67.7%) × 1800 cycle		372.95	0.07	0.40
	Uarbor	LIB charging (After port-in)	80 kWh × (90%–49.3 %)	4.92	0.00	0.01
	Harbor Harbor loads		250	48	1812.00	0.36	1.92
	Tota	1	80,502.41	kWh	12,155.86	2.42	12.88

Overall, the proposed system could reduce CO_2 , SO_X , and NO_X emissions, especially in the cargo handling and harbor modes at a port (Figure 11c,d). There was about a 77% reduction for CO_2 , about a 93% reduction for SO_X , and a 99% reduction for NO_X . On the contrary, the emission reduction rates for the normal seagoing mode (Figure 11a) and the port in/out mode (Figure 11b) were not high (under 10%).

In addition, the emission reduction rate varied depending on the ship's schedule. As shown in Table 16, when the cargo handling time was 60 h, the emission reduction rate was approximately 28% for CO₂, 4% for SOx, and 35% for NOx, but this increased to 45%, 6%, and 56% each for 180 h of long cargo handling operations. And, as shown in Table 17, when the sailing time was 20 d, the emission reduction rate was approximately 26% for CO₂, 4% for SOx, and 32% for NOx, but this increased to 50%, 8%, and 64% each for 5 d of short sailing time. Therefore, the proposed system is more eco-friendly if a ship has a long cargo handling time or visits many ports with a short-term sailing time.

Table 16. Comparison of emissions according to different cargo handling times.

Cargo Handling	Conventional System (ton/yr)			Proposed System (ton/yr)			Emission Reduction (%)		
Time at a Port (h) t ¹	CO ₂	SOχ	NO _X	CO ₂	SO _X	NO _X	CO ₂	SOχ	NO _X
60	1724.91	19.59	31.25	1237.33	18.86	20.23	28.27	3.73	35.26
90	1944.83	19.73	35.16	1289.03	18.87	20.29	33.72	4.36	42.29
120	2164.75	19.87	39.07	1340.72	18.88	20.34	38.07	4.98	47.94
150	2384.67	20.00	42.98	1392.41	18.89	20.40	41.61	5.55	52.54
180	2604.59	20.14	46.89	1444.11	18.90	20.45	44.56	6.16	56.39

¹ Assuming that the ship visits 20 ports per year with a sailing time of 10 d.

Sailing Time for	Conventional System (ton/yr)			Proposed System (ton/yr)			Emission Reduction (%)		
Port-To-Port (d) ¹	CO ₂	SO _X	NO _X	CO ₂	SO _X	NO _X	CO ₂	SO _X	NO _X
5 (27 ports/yr)	2174.79	13.85	39.06	1,077.69	12.78	14.06	50.45	7.73	64.00
10 (20 ports/yr)	2164.75	19.87	39.07	1,340.72	18.88	20.34	38.07	4.98	47.94
15 (16 ports/yr)	2174.84	23.58	39.36	1,506.52	22.63	24.22	30.73	4.03	38.47
20 (13 ports/yr)	2127.02	25.40	38.57	1,576.63	24.50	26.13	25.88	3.54	32.25

¹ Assuming that the ship stays at a port for 200 h with a cargo handling time of 120 h.

Table 17. Comparison of emissions according to different sailing times.



Figure 11. Comparison of emissions for each operation mode.

4.3. Economic Study

An economic study was conducted to compare the conventional power system and proposed one. Some assumptions were made for the study (below) since it was difficult to obtain exact data from the industry, and the data were changeable depending on the cases.

- Only the main equipment was considered;
- The bulk carrier visited 20 ports per year;
- The lifespan of the ship was 25 years.

First, the initial capital expenditure (CAPEX) is the sum of the equipment cost for the system. The cost data for the main equipment were obtained from several references [43–47]. The cost of the LIB was assumed to be 600 /kWh USD, and it was changeable according to the C-rate capacity, cell type, and cooling method, etc. The CAPEX results for the conventional and proposed systems are shown in Table 18. Secondly, the operational expenditure (OPEX) is the sum of each fixed operation & maintenance (O&M) cost, fuel cost for genset(s), and the electricity cost; only the electricity cost for the AMP was considered for the proposed system (Table 19).

The fixed O&M cost data of each main equipment were obtained from several references [48–50]. In this study, the variable O&M costs, which included cooling water or consumable materials used in

maintenance, were assumed negligible because they comprised a relatively small portion in general power systems [51–53]. It was also assumed that it was necessary to switch the onboard fuel from HFO to MGO in port areas to meet environmental regulations for the conventional power system. The total savings during *N* years is the sum of the yearly savings (S_{year}), taking into account the interest rate (i) for the capital, as below [54]:

Total savings =
$$\sum_{n=1}^{N} \frac{S_{year}}{(1+i)^n}$$
. (11)

In this study, i was set to 5%, and the annual inflation rates for the fixed O&M cost (a), fuel oil cost (b), and electricity cost (c) were set to 2% each. The replacement of the LIB and SC packs was considered with a replacement cost rate of 80% [55] of the initial cost. And the lifespan was assumed to be about 10 years for the LIB [56] and 15 years for the SC [17].

Туре	Conventional Po	wer System	Proposed Powe	er System		
Main	Equipment	Cost	No.	Equipment	Cost	No.
	Generator (700 kW)	149,800 USD	3	Generator (500 kW)	107,000 USD	1
	Crane converter (300 kW)	90,000 USD	4	Generator (700 kW)	149,800 USD	1
	-	-	-	LIB (40 kWh)	24,000 USD	2
equipment	-	-	-	SC (1.54 kWh)	15,400 USD	4
cost	-	-	-	Converter of LIB (40 kW)	12,000 USD	2
	-	-	-	Converter of SC (280 kW)	84,000 USD	4
	-	-	-	AMP converter (750 kW)	225,000 USD	2
				Cable system for AMP	1,300 USD	1
Total cost	809,400 USD			1,177,700	USD	

Table 18. Comparison of the capital expenditure (CAPEX) for each system.

Thus, the payback period was obtained by solving for *n* when the initial investment cost was equal to the sum of the yearly savings. Payback occurred at around 5.8 years where the curve passed through the zero of the *y*-axis in the case of the below assumptions:

- The electricity cost for the AMP was 9.2 cents/kWh;
- The HFO cost was 400/t USD, and the MGO cost was 630/t USD.
- The LIB cost was 600/kWh USD, and the SC cost was 10,000/kWh USD.

However, the payback period increased to around 10 years or deceased to around 4 years according to the electricity and fuel costs, as shown in Figure 12a,b; these were more critical variables compared to the LIB or SC cost during the lifetime of a ship, as shown in Figure 12c,d. For a 25-year lifespan of a ship, the total savings would be about 0.78 million USD, and the difference was greatly dependent on the fuel and electricity cost, as shown in Figure 13. Even though electricity cost was additionally included for the proposed system, it could be economically beneficial because of the fuel savings (up to 60.2%) compared with the conventional one.



Figure 12. Cont.





Table 19	. Comparison of	the operation	nai expendi	ture (OPEX)	for each system	n per year.

Туре	Conventio	onal Power System		Propose	d Power System	
	Equipment	Unit cost (/kW/yr)	No.	Equipment	Unit cost (/kW/yr)	No.
	Generator (700 kW)	15 USD	3	Generator (500 kW)	15 USD	1
Endow	Crane converter (300 kW)	2 USD	4	Generator (700 kW)	15 USD	1
Fixed Owin	-		-	LIB (40 kWh)	3 USD	2
cost/year	-	-	-	SC (1.54 kWh)	5.55 USD	4
	-	-	-	Converter (LIB) (40 kW)	2 USD	2
	-	-	-	Converter (SC) (280 kW)	2 USD	4
	-	-	-	AMP converter (750 kW)	2 USD	2
Total cost	33,9	00/year USD		23,67	/4/year USD	
Tuno	Fuel	No. of visited	Unit	Fuel	No. of visited	Unit
Type	Consumption	ports/yr	price	Consumption	ports/yr	price
HFO	17.784 (t/port)	20	400/t USD 1	17.426 (t/port)	20	400/t USD 1
MGO	16.487 (t/port)	20	630/t USD 1	0.192 (t/port)	20	630/t USD 1
Electricity (AMP)	-	-	-	80,502.41 (kWh/port) (Table 15)	20	9.2 cents/kWh ²
Total cost	350.0	008/vear USD		289.9	52/vear USD	

¹ BW380, BW0.1%S price (as of Jan. 2018) [57]. ² At Halifax port (Canada) [58,59].



Figure 13. Total life cycle costs for conventional and proposed systems based on present values (25 years; i = 5%; a, b, c = 2%; electricity cost = 9.2 cents/kWh).

In addition, the payback period varied depending on the ship's schedule. As shown in Figure 14, when the cargo handling time was 60 h, payback occurred at around 10.2 years, but this decreased to 4.2 years for 180 h of long cargo handling operations. And, as shown in Figure 15, when the sailing time was 20 d, payback occurred at around 8.2 years, but this decreased to 4.5 years for 5 d in a short sailing time. Therefore, the proposed system is more economical if a ship has a long cargo handling time or visits many ports with a short-term sailing time.



Figure 14. Cumulative saving costs for the lifespan of a ship depending on different cargo handling times (assuming that the ship visits 20 ports per year with a sailing time of 10 days).



Figure 15. Cumulative saving costs for the lifespan of a ship depending on different sailing times (assuming that the ship stays at a port for 200 h with a cargo handling time of 120 h).

5. Conclusions

This paper presents a new alternative solution to reduce harmful emissions at ports, which are mostly generated from onboard gensets. The hybrid power system with two different ESS types is proposed for port operations based on a bulk carrier with deck cranes. In the target ship, the LIB is optimal for the port in/out mode, and the SC is optimal for highly repetitive deck crane operations. To verify the proposed system, the optimal sizes for the LIB and SC are determined according to the load demands, and each capacity is verified using simulations. The emission reductions are then compared with those of the conventional power system. Lastly, an economic study is performed based on the expected CAPEX and OPEX of each system.

The results show that the emission problems in port areas can be solved using this onboard hybrid power system with an AMP facility. And these environmental benefits would be increased if shore power is only generated by clean power sources such as solar power, wind power, fuel cells, etc. Moreover, the economic study shows that this proposed system will be beneficial in terms of the total lifespan of a ship. Particularly, this proposed system can be more advantageous for ships that have a long cargo handling time or visit many ports with a short-term sailing time. However, benefits are highly variable depending on the fuel oil cost for gensets and the electricity cost for the AMP. Even though this paper focused on one type of ship, the two types of ESSs (LIB and SC) could also be applied to other ship types. Therefore, this new approach to for eco-friendly ship could be helpful for many ship owners who are faced with urgent environmental regulation problems.

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