



Comparison of Portable Emissions Measurement Systems (PEMS) with Laboratory Grade Equipment

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Featured Application: Determination of PEMS experimental measurement uncertainty in the laboratory.

Abstract: Real-driving emissions (RDE) testing with portable emissions measurement systems (PEMS) during the type approval and in-service conformity of light-duty vehicles was recently introduced in the European Union legislation. In this paper, three PEMS were compared with laboratory analyzers connected to the tailpipe and the dilution tunnel. The tests were conducted with two Euro 6 vehicles (one gasoline and one diesel) performing the World harmonized Light vehicles Test Cycle (WLTC) and a pre-recorded RDE cycle on a chassis dynamometer. The results showed that the differences of the PEMS gas analyzers compared to the laboratory references were typically within 2% for CO₂ and 5% for NO_x. The CO₂ and NO_x mass emissions were within 10% and 15%, respectively, with only a few exceptions. The exhaust flow rate measurements were within 10% at low speeds (urban conditions), and 5% at higher speeds. These results confirm the legislated permitted tolerances and the 2017 PEMS uncertainty estimates.

Keywords: Portable Emissions Measurement System (PEMS); Worldwide harmonized Light vehicles Test cycle (WLTC); Real Driving Emissions (RDE); conformity factor (CF); validation test; CO₂; NO_x; exhaust flow meter (EFM); measurement uncertainty

1. Introduction

Air quality control at an urban scale is one of the biggest challenges for many countries and cities worldwide. One of the main sectors contributing to air quality issues is the transport sector; in 2016, it was responsible for about 23% of the carbon dioxide (CO_2) emissions in Europe [1], and light duty vehicles contributed around 44% of the transport sector emissions [2]. The road transport contributed to 39% of the NO_x emissions in Europe in 2015 [3].

The European Union (EU) has set emission limits for certification tests, where all new vehicles must comply with, not only during type approval, but also during normal use [4]. The European passenger cars (M1) and vans (N1) pollutant emission standards, also called 'Euro' standards, are currently in stage six (Euro 6), and define the acceptable limits for the exhaust emissions of pollutants for new vehicles sold in the EU member states, namely CO, HC, and NO_x, as well as the



particulate matter and particle number. To verify the compliance with the targets, specific vehicle certification procedures are used, which include performing driving cycles (pre-defined speed profiles) on a chassis dynamometer under controlled laboratory conditions.

Since 2017, in EU, the new Worldwide harmonized Light vehicle Test Procedure (WLTP) has been implemented and the new test cycle is the Worldwide harmonized Light vehicle Test Cycle (WLTC) [4]. Even though the WLTC is based on the driving patterns of many countries, there are still concerns that will not close the gap (mainly of CO_2) between the real driving emissions and the type approval [5]. In addition, to reduce the differences found between the laboratory and on-road pollutant emissions and to limit the use of illegal strategies, the EU incorporated a real driving emissions (RDE) test procedure for the Euro 6d standard from 2017 [4].

EC Regulation (EU) 2017-1151 [4] establishes the rules for RDE testing, stating that the vehicle must be equipped with a portable emissions measurement system (PEMS), which is, in general, a compact equipment composed of portable analyzers, an exhaust mass flow meter (EFM), a weather station, and a Global Positioning System (GPS). All of this equipment must be integrated and use an acquisition frequency of 1 Hz. The regulation also establishes the trip requirements, such as the maximum and minimum duration, covered distance, ranges of speed, and the ambient boundary conditions, such as the maximum and minimum altitude and temperature [6]. The trip must cover a wide range of real world conditions, having defined shares of urban, suburban (also called rural), and highway (also called motorway) operation.

PEMS are a useful tool for emission inventories because they provide emissions under a wide range of operating conditions, including those that would otherwise be difficult to replicate in the laboratory (e.g., large road gradients, strong accelerations, and variations in altitude). PEMS measurements have increased in the last years and will further increase, not only because they are a part of the type approval and in-service monitoring EU regulation, but because they are robust and reliable tools for the market surveillance of vehicles on the roads [7,8] and a support for vehicle manufacturers in the development of new vehicles. Member states will be able to take measures (including ordering vehicle recalls and revoking type-approval certificates) against non-compliant vehicles sold in their national markets. The new regulation for the type-approval and market surveillance of motor vehicles was voted for in 19 April 2018. and will replace Directive 2007/46/EC in September 2020.

As summarized previously, PEMS have many sub-systems synchronized to a main platform. Thus, uncertainty associated to the measurements can be propagated through the data used for emissions calculations. According to a study by the Joint Research Centre (JRC) of the EU [9] the main sources of uncertainty are the exhaust flow meter (EFM), the gas analyzers, and their drift. The extra PEMS measurement uncertainty compared to the well-established and more accurate legislated method (measurement of bags from a full dilution tunnel) is covered by a margin that determines the conformity factor. The conformity factor defines the maximum allowed emission levels of the vehicles on the road. The comparison between the PEMS and laboratory equipment over a test cycle (called validation test) is a check of the proper setup and functioning of the PEMS. The permissible differences are given in the regulation (e.g., 15% or 15 mg/km for NO_x, 10% or 10 g/km for CO₂, whichever is larger).

Only a few studies have addressed the differences found between the PEMS and laboratory grade equipment for the latest generation RDE compliant PEMS. Comparisons (validations) of PEMS on the chassis dynamometers with the bags (from the full dilution tunnel with Constant Volume Sampling [CVS]) using various driving cycles were in good agreement in most studies [10–12]; however, in some cases, the differences were high and exceeded the permissible tolerances [13]. However, none of these studies conducted a detailed analysis using two PEMS simultaneously, by comparing them with both the legislated method and laboratory grade analyzers at the tailpipe.

Based on this background, it was deemed important to further evaluate the PEMS measurement uncertainty by direct comparison with laboratory grade equipment. Three different PEMS were evaluated in this work, performing the WLTC and a predetermined RDE cycle under laboratory conditions (lab-RDE) for two different vehicles, one spark-ignition (SI) internal combustion engine powered vehicle and one compression-ignition (CI) vehicle. The results are also compared with the above-mentioned studies [10–13].

2. Materials and Methods

2.1. Vehicles

In this study, one Euro 6 gasoline SI vehicle and one Euro 6 diesel CI vehicle were tested on a chassis dynamometer laboratory with certified fuels (i.e., E10 and B7, respectively). Table 1 summarizes the vehicle characteristics.

Technology	Vehicle 1 (SI)	Vehicle 2 (CI) 1.6	
Displacement (L)	1.4		
Power (kW)	57	90	
Transmission/gearbox	Manual/5	Manual/6	
Vehicle mass (kg)	1130	1360	
Exhaust after treatment	TWC	DOC + DPF + NS	
Fuel	Gasoline	Diesel	
Fuel system	MPFI	Common rail	
Emission standard	Euro 6	Euro 6	

DOC—diesel oxidation catalytic converter; DPF—diesel particulate filter; TWC—three-way catalytic converter; NS—NO_x Storage system; MPFI—multi point fuel injection; SI—spark-ignition; CI—compression-ignition.

2.2. Test Cycles

Two driving cycles were performed, the WLTC with an engine cold start, and a pre-recorded RDE cycle with an engine hot (Figure 1), which will be called the Lab-RDE cycle. Some constant speed parts were added at the end of each phase of the Lab-RDE cycle, in order to be able to detect any differences between the real time analyzers.

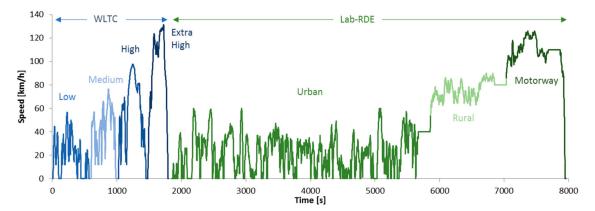


Figure 1. A Worldwide harmonized Light vehicle Test Cycle (WLTC) Class 3 divided in four phases (low, medium, high, and extra high), and a pre-recorded real driving emissions (RDE) cycle under laboratory conditions (lab-RDE) cycle divided in three phases (urban, rural, and motorway).

2.3. Measurement Equipment

The laboratory tests were conducted at the one-axis roller dynamometer Vehicle Emissions Laboratory (VELA 1) of the JRC in Italy (Figure 2). The exhaust gas was connected to the full dilution tunnel with a <3 m tube. A flow rate of 9 m³/min was used at the full dilution tunnel, with Constant Volume Sampling (CVS).

As required by the regulation, for the WLTC, the sampling bags were filled with the diluted exhaust and were analyzed at the end of the test. As a result of the long duration of the lab-RDE cycle, no bag measurements were taken, but the emissions were calculated using the integrated real time data of the analyzer connected to the CVS (diluted gas).

One analyzer (AMA i60 from AVL) was used to measure the diluted gas in real time (lab-RDE) or the bags filled with diluted exhaust at the end of the test (WLTC). The bag and/or diluted measurements were considered as the reference values. Another analyzer (AMA i60) was used to measure the raw exhaust from the tailpipe of the vehicle, after the two PEMS (technical specifications in Table 2).

PEMS #1 (OBS-ONE, Horiba, Kyoto, Japan) and PEMS #2 (M.O.V.E., AVL, Graz, Austria) were tested with the SI gasoline vehicle, while PEMS #2 and PEMS #3 (M.O.V.E. and AVL) were tested with the CI diesel vehicle (technical specifications in Table 2). Each PEMS was connected to its own exhaust flow meter (EFM). Attention was given to leave enough tube diameters length (>four diameters) before and after the EFMs to ensure their proper operation, and additionally, not to cause any significant pressure drop by reducing the tailpipe inner diameter. For this reason, bigger flow meters were used for the CI vehicle, which has higher flow rates.

The zero and span calibration of the analyzers was conducted before each test. The zero and span drift of the PEMS was checked only after the RDE tests. All of the results were well within the regulation requirements (NO_x zero drift <5 ppm, NO_x span drift <2%) and there was no systematic drift (positive or negative), thus, all of the presented results include the contribution of the drift (if any).

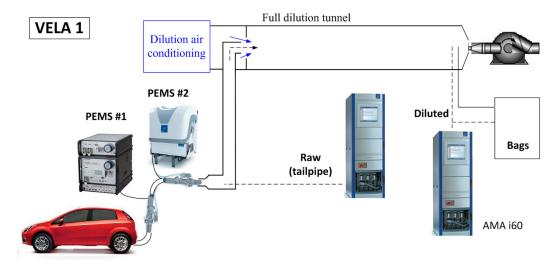


Figure 2. Vehicle Emissions Laboratory (VELA 1) experimental setup (spark-ignition [SI] vehicle). For the compression-ignition (CI) vehicle, the setup was identical with portable emissions measurement systems (PEMS) #3 and PEMS #2.

Table 2. Characteristics of the equipment.

Technology	PEMS #1	PEMS #2, #3	Tailpipe	Diluted/Bags
Manufacturer	Horiba	AVL	AVL	AVL
Model	OBS-ONE	M.O.V.E.	AMA i60	AMA i60
Principle CO ₂	Heated NDIR	NDIR	NDIR	NDIR
Range CO ₂	20%	20%	1%, 20%	1%,6%
Principle NO _x	Heated CLD	NDUV	CLD	CLD
Range NO_x (ppm)	3000	5000	100, 1000, 10,000	10, 100, 1000
EFM	Pitot 2"	Pitot 2&2.5"	CO ₂ tracer	-

NDIR—on-dispersive infrared detection; CLD—chemiluminescence detection, NDUV—non-dispersive ultraviolet; EFM—exhaust flow meter; PEMS—portable emissions measurement systems.

2.4. Calculations

2.4.1. Bags/Diluted Mass

According to WLTP [4], the mass emissions of a pollutant *i* (CO₂ or NO_x), calculated from the dilution tunnel for each phase or cycle ($m_{i,CVS}$) (g/km), are given by the following:

$$m_{i,CVS} = V_{mix} \,\rho_i \,k_h \,C_{i,corr} \,10^{-6}/d, \tag{1}$$

where V_{mix} (litre) is the volume of the diluted exhaust gas corrected to standard conditions (273.2 K and 101.3 kPa), ρ_i (g/litre) is the density of the pollutant *i* at standard temperature and pressure; k_h (–) is the humidity correction factor applicable only to the mass emissions of NO_x; $C_{i,corr}$ (ppm) is the concentration of the pollutant *i* in the diluted exhaust gas, corrected by the amount of the pollutant *i* contained in the dilution air; and *d* (km) is the distance of the phase or total cycle.

For RDE, where no bags were used, $C_{i,corr}$ was estimated from the real time data of the gas analyzer connected to the dilution tunnel.

2.4.2. Tailpipe Exhaust Mass

The tailpipe mass emissions of a pollutant $i (m_{i,tailpipe})$ (g/km) were calculated summing the instantaneous emissions from a pollutant i as prescribed in the regulation [4].

$$m_{i,tailpipe} = \Sigma \left(u_i C_{i,tailpipe} q_{mew} \right) / d, \tag{2}$$

where u_i (–) is the ratio density of the pollutant *i* and the overall density of the exhaust, $C_{i,tailpipe}$ (ppm) is the measured concentration of the pollutant in the exhaust, and q_{mew} (kg/s) is the exhaust mass flow rate measured (by PEMS) or estimated (by CVS). The CVS estimated exhaust flow rate was based on the CO₂ tracer method (i.e., by dividing the total CVS flow rate with the dilution ratio at the dilution tunnel) [14]. The dilution ratio was given by the ratio of the diluted and raw CO₂ measurements. Some abnormal gas concentration spikes during the decelerations [14] were manually removed.

All of the data was acquired at 1 Hz and the synchronization between the different equipment was also made to enable a comparison between them.

2.4.3. Extracted Mass

Equation (3) was used by the automation system to take into account the mass of a pollutant extracted by the instruments connected to the tailpipe (two PEMS and a raw exhaust analyzer, around 20 lpm). The calculated extracted mass emissions of the pollutant $i (m_{i,extracted})$ (g/km) was added to the calculated bags or diluted mass.

$$m_{i,extracted} = \Sigma \left(u_i C_i q_{instr.} \right) / d, \tag{3}$$

where $q_{instr.}$ (kg/s) is the extracted flow rate from the instruments. This correction was <3% for CO₂. For the tailpipe exhaust analyzer and the PEMS, no correction was applied because the exhaust flow was measured/calculated before any extraction of the sample.

3. Results and Discussion

Initially, the tailpipe data (concentrations— $C_{i,tailpipe}$; exhaust flow rates— q_{mew}) obtained from each system will be compared to each other, to evaluate the uncertainty they can introduce. Then, the mass emissions of the tailpipe systems ($m_{i,tailpipe}$) will be compared to the regulated method (bags form the dilution tunnel) ($m_{i,CVS}$).

3.1. Tailpipe Measurements

3.1.1. Exhaust Flow Rates Comparisons

Figure 3 presents the differences of each exhaust flow measurement system (PEMS or derived from CVS flows) to their mean value for each cycle phase (smaller symbols) or the whole cycle (larger symbols). The frameless symbols refer to the WLTC phases, while the framed symbols refer to the lab-RDE phases. The dashed lines indicate a 10% difference based on the currently assumed uncertainty of the flow meters [9]. Each point is the mean value of three repetitions.

As a reference, the mean (average) of the three measurement systems (PEMS and CVS derived) was chosen because none of the methods can be considered as a reference method with low uncertainty. The differences were within ± 4 kg/h (few exceptions), which translated to a deviation of around $\pm 10\%$ of their mean value for low mean flow rates (<40 kg/h), and a lower than $\pm 5\%$ deviation for higher flow rates. PEMS #2, which was used with both of the vehicles presented consistent behavior (differences were around zero), while the CVS derived flow was slightly overestimating (1–5 kg/h) for the SI vehicle and underestimating (2–3 kg/h) for the CI vehicle. The authors were not aware of any studies comparing exhaust flow measurements, other than the 2017 margins review study [9], where, in most cases, the differences were within $\pm 10\%$.

For these measurements, the setup of the flowmeters was carried out according to good engineering practice (i.e., having a straight tube between the two flowmeters, and avoiding sharp curves or sudden changes of diameter); however, it cannot be excluded that some of the deviation mentioned above was due to the set of instruments installed in the series.

Figure 4 presents examples of the flow measurements in real time, obtained from the three systems. Although they generally agreed well, at low flowrates (PEMS #1 SI vehicle), differences of around 4 kg/h were observed. At low flow rates, the uncertainty of all of the methods was high.

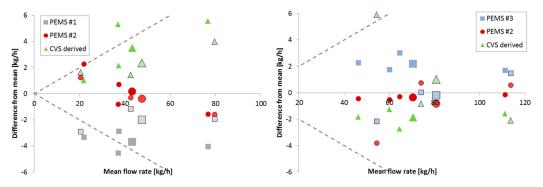


Figure 3. Differences of flow measurement systems from their mean value for each cycle phase. **Left panel:** SI vehicle. **Right panel:** CI vehicle. The frameless symbols are the WLTC phases, while the framed symbols indicate the Lab-RDE phases. The larger symbols represent the overall cycle results, and the smaller symbols represent each cycle phase. Each point is the mean value of three repetitions. The dashed lines indicate a 10% difference.

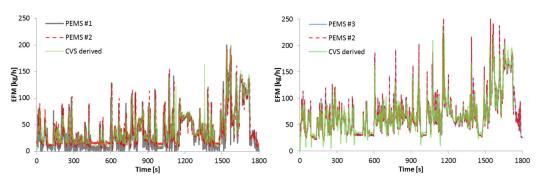


Figure 4. Examples of real time comparison of systems measuring exhaust flow. Left panel: SI vehicle. Right panel: CI vehicle.

3.1.2. CO₂ Concentrations Comparison

Figure 5 presents the differences between the CO₂ analyzers measuring at the tailpipe of the vehicle. As all of the analyzers had similar specifications, their mean value was considered as the reference value. For the SI vehicle, the measured absolute CO₂ concentrations were within 11% and 13%, while for the CI vehicle, they were between 3% and 7%. The differences between the instruments were within approximately 1% for the SI vehicle, and approximately 2% for the CI vehicle. The smaller uncertainty at the 11–13% range was probably due to the measured range, which was close to the calibrated concentration (around 14%). There was no particular trend of any of the PEMS underestimating, or having linearity issues. There was an indication that the tailpipe laboratory analyzer was generally measuring slightly lower than the PEMS.

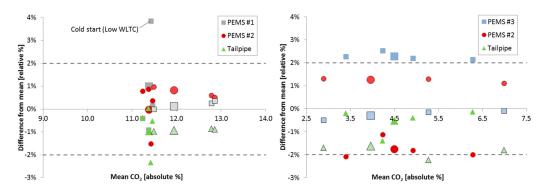


Figure 5. Differences of CO_2 analyzers. **Left panel:** SI vehicle. **Right panel:** CI vehicle. Each point is the mean value of three repetitions. The dashed lines show the 2% limit when compared with the calibration span gas.

There was one point that had higher differences, the cold start with the SI vehicle (PEMS #1 measured 4% higher than the mean), as shown in Figure 6, which presents the real time data of the three analyzers for the two vehicles. The agreement was very good, with the exception of the cold start. PEMS #1 measured a 'wet' concentration (heated NDIR, i.e., without using a drier to remove the water content), while PEMS #2, PEMS #3, and the laboratory equipment measured on a dry basis and used a correction factor to report in the 'wet' basis. This correction factor was based on the RDE regulation based on the fuel composition and the measured CO and CO₂ concentrations (approximately 0.89 for the SI and 0.95 for the CI vehicle). The observed cold start differences were probably due to the condensation and evaporation of water during the cold start, which the dry–wet corrections do not take into account accurately. Nevertheless, the effect of this over (or under) estimation for the whole WLTC was small (see larger symbols in Figure 5, all within 2.5%).

The results of Figure 5 are in agreement with the specifications of the analyzers of 2%, which however refers to comparisons with reference to the calibration gas in a cylinder. Similar differences between the analyzers (2% for CO_2) were also found by another study [10].

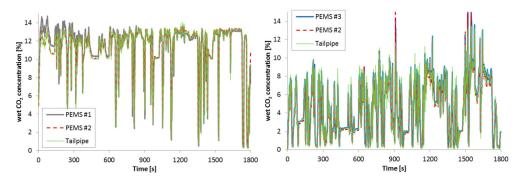


Figure 6. Examples of CO₂ concentration (%) real time profiles. **Left panel:** SI vehicle. **Right panel:** CI vehicle.

3.1.3. NO_x Concentrations Comparison

Figure 7 presents the differences between the NO_x analyzers measuring at the tailpipe of the vehicle. As all of the analyzers had similar specifications, their mean value was considered as the reference. For the SI vehicle, the mean measured NO_x concentrations were <30 ppm, while for the CI vehicle, they were between 20 and 140 ppm. The differences of the instruments were within 5% for the CI vehicle, but up to 30% for the SI vehicle. The 5% uncertainty is in agreement with the estimated uncertainty of the current analyzers [9]. The higher uncertainty at the low range is also in line with the higher uncertainty of the analyzers at low concentration ranges that approach their zero levels [9], and a study that compared NO_x analyzers (10%) [10]. NO_x analyzers are typically calibrated from 2000 ppm down to 100 ppm. A limited number of data showed that below 100 ppm, the uncertainty increases from 2% to around 5–10% at 10 ppm [9]. These results confirm that current PEMS have a high level of variation at low NO_x levels; thus, for low NO_x emission levels, the measurement uncertainty (margin in percentage) is higher than what is currently prescribed. Alternatively, for keeping a similar margin, PEMS need to reduce the uncertainty at low levels.

There was no particular trend of specific PEMS or of principle (e.g., chemiluminescence detection [CLD] or non-dispersive ultraviolet [NDUV]) underestimating, overestimating, or having non-linearity issues. There was an indication that the tailpipe measurements were slightly lower than the PEMS.

Figure 8 presents an example of the time aligned NO_x data of the analyzers. The signals were almost indistinguishable from each other. Although PEMS #1 was tested with low concentrations in general, the few spikes with high concentrations (Figure 8, left panel) were at the same levels as the rest systems, indicating that the good results of Figure 7 (left panel) would also be valid at higher concentrations.

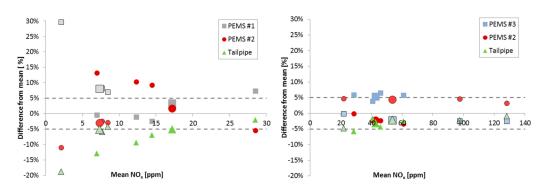


Figure 7. Differences of NO_x analyzers. **Left panel**: SI vehicle. **Right panel**: CI vehicle. Each point is the mean value of three repetitions. Dashed lines indicate the 5% assumed uncertainty [9].

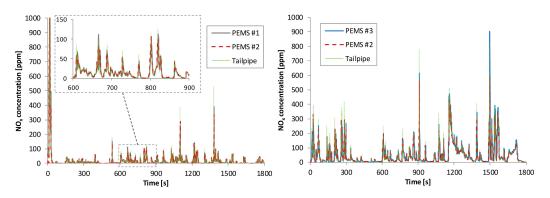


Figure 8. Examples of NO_x concentration [ppm] real time profiles. **Left panel**: SI vehicle. The first spike of 2000 ppm with the SI vehicle is not shown so as to improve the readability at the lower range. **Right panel**: CI vehicle.

3.2. Tailpipe Versus Dilution Tunnel

3.2.1. CO₂ Distance Specific Results

Figure 9 presents the differences of the PEMS and the tailpipe analyzers to the dilution tunnel results for each phase of the WLTC (smaller symbols without frame) or the lab-RDE cycles (smaller symbols with frame) for the two vehicles. The larger symbols are the overall cycle results. The dashed lines show permissible tolerance according to regulation [4]. Each point is the mean value of three repetitions.

The CO₂ emissions were 110–200 g/km for the SI vehicle and 90–150 g/km for the CI vehicle. The differences of the PEMS and the tailpipe measurements compared to the CVS results were within the permissible range of the regulation limits (10 g/km or 10%, whichever is larger), with a few exceptions, namely: for the SI vehicle, PEMS #1 was outside the (lower) limits for the lab-RDE test (urban phase), and similarly, for the CI vehicle, PEMS #2 and PEMS #3 were outside the limits for the lab-RDE test (urban phase). The real data signals revealed that these differences were probably due to the underestimation of the mass emissions (in particular exhaust gas flow) at idle for the SI vehicle (Figure 3 or Figure 4) and the CO₂ concentrations for the CI vehicle (Figure 6).

Most researchers have found differences below 3.6% [11–13,15,16] for CO₂ mass emissions, and one study found a difference of 8% for one PEMS [13] compared with the laboratory equipment. The higher differences found in this study have to do with the higher flow rate uncertainties discussed previously (Figure 3).

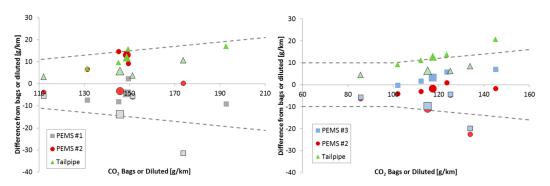


Figure 9. CO₂ emission differences of PEMS and tailpipe analyzers from bags (WLTC) or dilution tunnel (lab-RDE). **Left panel:** SI vehicle. **Right panel:** CI vehicle. The dashed lines are the permissible tolerance according to the regulation [4].

3.2.2. NO_x Distance Specific Results

Figure 10 presents the differences of the PEMS and the tailpipe analyzers to the dilution tunnel results for each phase of the WLTC or lab-RDE cycles for the two vehicles, using the same symbols as before (Figure 9).

The NO_x emissions were very low for the SI vehicle, below 30 mg/km, except during the WLTC cold start, which reached 90 mg/km. The NO_x emissions of the CI vehicle ranged from 80 to 230 mg/km. The differences of the PEMS to the CVS were within the permissible by the regulation limits (15 mg/km or 15%, whichever is larger), with a few exceptions (tailpipe analyzer). The differences for the SI vehicle were within 5 mg/km, while for the CI vehicle, the scatter was up to ± 40 mg/km, although most of the results were within ± 20 mg/km or $\pm 15\%$. Other PEMS validation studies have found differences of around 15% at the 20 mg/km NO_x range (i.e., differences around 3 mg/km) [12,13] and around 10% at the 500 mg/km NO_x range [11,16].

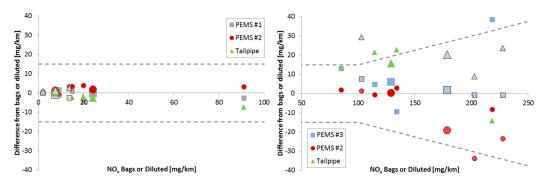


Figure 10. NO_x emission differences of PEMS and tailpipe analyzers from bags (WLTC) or dilution tunnel (lab-RDE). **Left panel:** SI vehicle. **Right panel:** CI vehicle. The dashed lines show permissible tolerance according to the regulation [4].

4. Conclusions

The PEMS from two manufacturers were compared with laboratory grade analyzers connected to the tailpipe, the dilution tunnel, and/or the bags, as prescribed by the regulation. Two vehicles, one spark ignition (SI, gasoline) and one compression ignition (CI, diesel), were used to evaluate the performance of the PEMS during the WLTC and a lab simulated RDE cycle.

The CO₂ concentrations from the PEMS and tailpipe gas analyzers were within 2.5%. However, the PEMS that measured the 'wet' concentrations (heated NDIR) showed higher concentrations (+4%) at the cold start of the SI vehicle. The NO_x concentration from the PEMS analyzers were within 5% for the mean levels of 20 ppm or higher, but the differences increased to 15% at 7 ppm and 30% at 1 ppm. Similar behavior was seen for both techniques (CLD and NDUV). The exhaust flow measurements had an uncertainty of around ± 4 kg/h, that is, $\pm 10\%$ for exhaust mass rates equal or lower than 40 kg/h, but around 5% at higher flow rates.

The distance specific CO_2 emissions (in g/km) of the PEMS were typically lower (but within 10%) than the bag (diluted) results, while the laboratory tailpipe emissions were higher (but within 10%). The differences were mainly attributed to the exhaust flow measurement uncertainties. The distance specific NO_x emissions of PEMS were within 10% of the bag (diluted) results in most cases.

The results of this study underline that current technology PEMS provide measures with good accuracy, particularly the gas analyzers, which present results close to the levels of laboratory grade equipment. However, the biggest contribution of the differences between the PEMS and bags (diluted) measurements comes from the exhaust flow measurements. At the moment, there is no simple way to check the flow meters of PEMS, and the validation test on the chassis dynamometer remains the most valid check. Systems without exhaust flow meters that estimate the exhaust flow (however, they are not considered PEMS) will probably have a higher uncertainty. Moreover, for technologies with

low NO_x levels, PEMS should improve the current relative high uncertainty at low concentrations, near their zero levels.

These findings are important, because they confirm that air quality studies and emission inventories based on PEMS measurements have a low measurement uncertainty (values as reported above) for vehicles with emission levels of approximately 100 mg/km and higher. The introduction of the real driving emissions test procedure will contribute to the reduction of urban air pollution, because new vehicles will emit lower emissions; however, the PEMS relative measurement uncertainty will be higher. The results of this study can help in a better estimation of the PEMS measurement uncertainty during the annual reviews, as follows: (1) the uncertainty of NO_x at lower levels was quantified and (2) the flow meter uncertainty was almost constant (and not relative).

What should be further investigated is whether there is any drift of the analyzers on the road as well as any influence of the environmental conditions (temperature and pressure) that would further increase the differences and uncertainty of the measurements. In addition, investigation on how acceleration and power can influence the PEMS measurement could be an add-on to the current research.

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