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An Efficient Cellular Automata-Based Classifier with Variance Decision Table

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Abstract: Classification is an important task of machine learning for solving a wide range of problems in conforming patterns. In the literature, machine learning algorithms dealing with non-conforming patterns are rarely proposed. In this regard, a cellular automata-based classifier (CAC) was proposed to deal with non-conforming binary patterns. Unfortunately, its ability to cope with high-dimensional and complicated problems is limited due to its applying a traditional genetic algorithm in rule ordering in CAC. Moreover, it has no mechanism to cope with ambiguous and inconsistent decision tables. Therefore, a novel proposed algorithm, called a cellular automata-based classifier with a variance decision table (CAV), was proposed to address these limitations. Firstly, we apply a novel butterfly optimization, enhanced with a mutualism scheme (m-MBOA), to manage the rule ordering in high dimensional and complicated problems. Secondly, we provide the percent coefficient of variance in creating a variance decision table, and generate a variance coefficient to estimate the best rule matrices. Thirdly, we apply a periodic boundary condition in a cellular automata (CA) boundary scheme in lieu of a null boundary condition to improve the performance of the initialized process. Empirical experiments were carried out on well-known public datasets from the OpenML repository. The experimental results show that the proposed CAV model significantly outperformed the compared CAC model and popular classification methods.

Keywords: cellular automata; pattern recognition; variance decision table; variance coefficient; periodic boundary condition



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1. Introduction

Data mining and pattern recognition are critical components of many fields and represent essential classification processes. Popular algorithms include the Support Vector Machine (SVM) [1,2], Dense Neural Network (DNN) [3,4], Deep Learning [5–7], K-nearest neighbor (k-NN) [8–10], and Naive Bayes [11–13]. In particular, Deep Learning is a widely used to solve a variety of problems, such as Alzheimers Disease classification [14–17]. In contemporary times, the challenges associated with classification have become increasingly complex and diverse. This is particularly true when dealing with non-conforming binary formats, which are low-level binary data. Therefore, it remains challenging to use recognition or classification techniques and implement a classifier that can directly handle the aforementioned data type.

However, classifier-based cellular automata (CA) successfully handle the complex problem of binary pattern classification tasks using a simple CA rule. For example, image compression [18], image classification [20], image encryption [21,22], and texture recognition [23,24], especially for pattern classification [25], have been proposed as highly reliable classifier methods based on elementary cellular automata (CAC). These methods play a role in non-conforming and conforming patterns for binary data.

The primary objective of this research is to employ the “network-reduction” technique to improve the ability of the cellular automata-based classifier to handle increasingly complex and challenging issues [26]. Despite its utilization of basic cellular automata

rule matrices and the concept of two-class classification akin to SVM, the classification performance of CAC remains encumbered by two key issues. Firstly, the data with ambiguity impact the rule ordering process to generate the rule matrices from the decision of the genetic algorithm (GA) by a random boundary cutting point without a statistical background for classification using only random values does not produce effective results in the classification model. Secondly, when working with high-dimensional data, the rule ordering procedure that utilizes GA may become trapped in a local optimal solution [27] because GA is limited when dealing with high-dimensional problems [28]. One alternative to GA is butterfly optimization, which has been shown to improve usage in a number of applications, including feature selection [29,30] and enhancing the BOA utilizing a mutualism scheme [31]. Butterfly optimization performs better than classical optimization. In this paper, we proposed an efficient classification called cellular automata-based with a variance decision table (CAV) using the percentage coefficient of variation (%CV).

This study makes three critical contributions to the literature. First, we created an initial rule matrix based on finding the edge using the periodic boundary condition instead of zero constants (null boundary condition) to reduce data redundancy and demonstrate the proper form of the data for a more precise classification. Secondly, besides the ability to classify data patterns instead of random intersections by using a meta-heuristic algorithm, coefficients of variation were used to determine the relationships between classes, giving the data pattern more clarity and reducing the solution area from two-variable solutions to only a single variable that was less reliant on the search algorithm's ability. Finally, an efficient butterfly optimization algorithm (m-MBOA) was implemented instead of a genetic algorithm. We evaluated CAV using well-known classification algorithms in RapidMiner studio [32] and used 15 datasets for classification tasks from an OpenML repository [33].

This study is divided into six parts: the introduction in Section 1, related work on the proposed cellular automata classifier, and a novel butterfly optimization algorithm (m-MBOA) (Section 2). Section 3 expands on our proposed CAV method. Section 4 contains a comparison of experimental results. Section 5 presents an empirical study of the experimental results. Section 6 concludes the paper.

2. Related Work

2.1. Cellular Automata for Pattern Recognition

Cellular automata (CA) are lattice-based systems that evolve according to a local transition function [34]. The simplest form of 1-dimensional cellular automata that focuses on the left neighbor, right neighbor, and present-state cell is called an elementary cellular automata (ECA) [35].

Cellular automata are widely used as a basis in pattern recognition and classification research, such as texture recognition based on local binary patterns [23], melanoma skin disease detection [36], and real-time drifting data streams [37], mainly based on ECA, such as reservoir computing systems [38] and texture analysis [24].

On the other hand, in 2016, an efficient classifier based on ECA was proposed and is called the cellular automata base classifier (CAC) [25]. Figure 1 shows the process of CAC rule ordering output as rule matrices R^+ and $R^- \in \{0, 1\}$, which are the best solutions for the classifier with the decision function $f(Q_{R^+}^{t+1}, Q_{R^-}^{t+1}) \in \{-1, 1\}$. They were designed based on the decision support ECA (DS-ECA). $f(Q_{R^+}^{t+1}, Q_{R^-}^{t+1})$ is a sign function that depends on $(Q_{R^+}^{t+1}, Q_{R^-}^{t+1})$, as expressed in Equation (1).

$$f(Q_{R^+}^{t+1}, Q_{R^-}^{t+1}) = \text{sgn}\left(\sum_{i=0}^{n-1} (Q_{i,R^+}^{t+1} - Q_{i,R^-}^{t+1})\right) \quad (1)$$

where $Q_{R^+}^{t+1}$ and $Q_{R^-}^{t+1}$ are the next states generated by the rule matrices R^+ and R^- . Q_{i,R^+}^{t+1} and Q_{i,R^-}^{t+1} are the i th cells of n bits from $Q_{R^+}^{t+1}$ and $Q_{R^-}^{t+1}$.

The next two states $Q_{R^+}^{t+1}$ and $Q_{R^-}^{t+1}$ are generated as follows in Equations (2) and (3)

$$Q_{R^+}^{t+1} = (R^+, Q^t) \tag{2}$$

$$Q_{R^-}^{t+1} = (R^-, Q^t) \tag{3}$$

As shown in Figure 1, the process of ordering the rule matrices using the initial rule matrices $[Q_P]$ and $[Q_N]$ in the first step consists of continuous data. Rule matrices with values of 0 and 1 resulting from the rule ordering process transform the data from a fuzzy set into a discrete set.

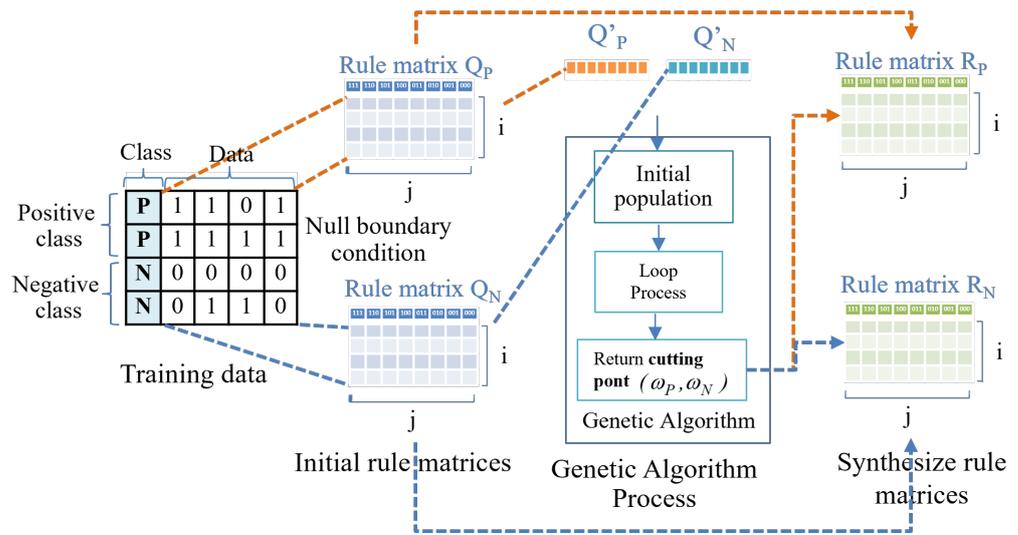


Figure 1. CAC rule ordering.

2.2. An Enhanced Butterfly Optimization Algorithm (m-MBOA)

The m-MBOA is an improved BOA with the mutualism phase of the SOS algorithm to determine the characteristics of the relationship between the two organisms.

The effectiveness of m-MBOA depends on variable configurations to control the probability that the simulated butterfly will either fly directly to the food source or fly randomly [39,40]. Its structure is mostly based on the butterfly prey approach, which employs scent recognition to detect the location of sustenance or mating sets. The discovery and handling concept is based on three critical conditions: fragrance (f), sensory exposure (c), stimulus intensity (I), and power (a). Based on these hypotheses, the fragrance in the BOA is described as a component of the boost’s physical strength, as follows:

$$f = cI^a \tag{4}$$

where f represents the magnitude of scent recognition, i.e., the intensity of smell identification by other butterflies; c represents the sensory receptor; I represents the stimulating force, and a represents the exponent power, depending on the modality. The m-MBOA has four phases: (1) startup, (2) iteration, (3) mutualism, and (4) recursive search in the initial m-MBOA operation. The algorithm is terminated at the last stage after obtaining the best response.

In the first step, the algorithm determines the problem-solving region and function purpose, as well as the parameters used in the m-MBOA set. The butterfly’s position in the search zone was generated at random, and its fragrance and suitability values were computed and stored. Further parts of this technique involve initial and recursive phase computations. An algorithm is used to accomplish the second stage of the method, which is the looping phase and several iterations. All butterflies in the solution region are transferred to a new position and evaluated for suitability in each iteration. The first algorithm determines the suitability of all butterflies in various spots in the solution region. These butterflies then use Equation (4) to

produce smells based on their position. This method has two critical steps: the local and global search algorithms. Butterflies go to the most appropriate butterfly g^* response in the global search process, as stated by Equation (5).

$$b_i^{t+1} = b_i^t + (r^2 \times g^* - b_i^t) \times f_i \tag{5}$$

where g^* is the best solution for all butterflies in the current iteration, b_i^t is the i th butterfly number in iteration t , f_i is the fragrance of the i th butterfly, and a random number $[0, 1]$ is represented by r . The next best butterfly position is as follows (6).

$$b_i^{t+1} = b_i^t + (r^2 \times b_j^t - b_k^t) \times f_i \tag{6}$$

where b_j^t and b_k^t are the j th and k th butterfly positions in the solution space. If b_j^t and b_k^t result in the same local space, and random numbers between $[0, 1]$ are represented by the parameter r , then Equation (6) is the result of the random butterfly behavior. An additional phase is then used to calculate the symbolic relation of the two distinct m-MBOAs, which calculates the mutual phase in the last decision using Equations (7) and (8).

$$b_{i_{new}} = b_i + rand[0,1] \times (b_{best} - Mutual_{Vector} \times BF1) \tag{7}$$

$$b_{j_{new}} = b_j + rand[0,1] \times (b_{best} - Mutual_{Vector} \times BF2) \tag{8}$$

where $b_{i_{new}}$ and $b_{j_{new}}$ is a new butterfly value, the $Mutual_{Vector}$ from (9) is used randomly. b_{best} is the final solution answer; BF1 and BF2 are the random numbers of benefit factors 1 and 2, respectively.

$$Mutual_{Vector} = (b_i \times b_j) / 2 \tag{9}$$

where $Mutual_{Vector}$ is a mean of butterfly vector b_i and b_j .

The threshold for stopping an answer can be defined in many ways. For example, it can be determined by the operation of the CPU, the number of calculation cycles, or the error value that occurs. If there is no error, the calculation can be stopped. This algorithm exports the most appropriate solution. The three steps described above comprise the complete algorithm of the butterfly optimization algorithms, as shown in Algorithm 1.

Algorithm 1: m-MBOA.

```

input :  $n, l, a, p, c$ .
output: Best  $bf$ 

1 Initialization;
2 Objective function  $f(b), b = (b_1, b_2, \dots, b_{dim})$ 
3  $fitness$  = the classification accuracy (29)
4  $dim$  = number of dimensions
5 Generate initialised population of  $n$  butterflies  $x_i (i = 1, 2, \dots, n)$ 
6  $f(b_i)$  represents the stimulus intensity  $I_i$  of butterfly  $b_i$ 
7  $c$  is the sensor modality value,  $a$  is the power exponent value, and  $p$  is the random
  switch probability.
8 LOOP Process:
9 while  $t \leq 20 \vee fitness \neq 0$  do
10   foreach number of  $bf$  do
11     Calculate the fragrance for  $bf$  using Equation (4).
12     Calculate the fitness for each  $bf$ .
13   end
14   Find the best  $bf$  foreach number of  $bf$  do
15     Random numbers between  $\{0, 1\}$  for  $r$ .
16     if  $r < p$  then
17       Calculate Equation (5).
18       Select the butterfly randomly with the condition  $i \neq j$ .
19       Calculate Equation (9) for the mutual relationship vector
        ( $Mutual_{vector}$ ).
20       Mutual relationship updates base according to (7) and (8).
21       Generate the new fitness value of the butterfly.
22     else
23       Calculate Equation (6) to move randomly.
24     end
25   end
26   Update the value of  $a$ .
27 end
28 return best  $bf$ 

```

3. Proposed Method

We propose a novel classifier-based elementary cellular automaton that uses the variance of the initial rule matrices. In this section, several preliminaries are presented, and some essential equations are simplified. Additionally, we present the motivation for the model based on the limitations of the traditional classifier. In Table 1, we first introduce some notations that are frequently used in this study.

First, let us provide an example of the equations for finding the rule matrices according to Equations (10) and (11) before analyzing the problem.

$$[R^+]_{ij} = \begin{cases} 1, & [U_p]_{ij} \geq \omega_p \\ 0, & \text{otherwise} \end{cases} \quad (10)$$

$$[R^-]_{ij} = \begin{cases} 1, & [U_n]_{ij} \geq \omega_n \\ 0, & \text{otherwise} \end{cases} \quad (11)$$

where R^+ and R^- are the rule matrices of the positive and negative classes, respectively; ω_p and ω_n are the cutting-point decisions used to eliminate some values from the initial rule matrices U_p and U_n in the i th column and j th row, respectively, where $i, j = 1, 2, 3, \dots, n$ in order to generate rule matrices with the best classification accuracy.

Table 1. Notation.

Notation	Description
i, j	Number of datasets (binary data) features, number of possible ECA configuration ($2^3 = 8$)
k	Number of samples from U_p and $U_n = 2$
$U_p \in \mathbb{R}^{i \times j}$	Initial rule matrix of the data in positive class
$U_n \in \mathbb{R}^{i \times j}$	Initial rule matrix of the data in negative class
$V \in \mathbb{R}^{i \times j}$	Variance Decision Table matrix
V'	Variance Decision Table vector
$W_p \in \mathbb{R}^{i \times j}$	Rule matrix of the positive class
$W_n \in \mathbb{R}^{i \times j}$	Rule matrix of the negative class
\bar{x}	Mean of each $[U_p]_{ij}$ and $[U_n]_{ij}$
S	Standard deviation of each $[U_p]_{ij}$ and $[U_n]_{ij}$
%CV	Percentage coefficient of variance
\mathcal{D}_t	Training data
ω_v	The variation coefficient

Definition 1 (conflict value). *A conflict value is the difference between the same position element of the initial rule matrices $[U_p]_{ij}$ and $[U_n]_{ij}$, arising from the creation processes of the rule matrices $[R^+]_{ij}$ and $[R^-]_{ij}$. The conflict value can be represented by Equation (12).*

$$Conflict\ value = \begin{cases} |[U_p]_{ij} - [U_n]_{ij}|, & [U_p]_{ij}\ and\ [U_n]_{ij} \geq 1 \\ 0, & [U_p]_{ij}\ or\ [U_n]_{ij} = 0 \end{cases} \tag{12}$$

where Conflict value $\in I^+$

Lemma 1. *The higher the conflict value the lower the classification accuracy.*

Proof of Lemma 1. Equations (10) and (11) show that all elements of $[U_p]_{ij}$ and $[U_n]_{ij}$ would convert to 1 if their value is greater than 0.

Assume that $U_p \gg U_n$ when $\lim_{x \rightarrow \infty} [U_p]_{ij} = \infty$ and $\lim_{x \rightarrow \infty} [U_n]_{ij} = 1$ then

$$\begin{aligned} Conflict\ value &= |[U_p]_{ij} - [U_n]_{ij}| \\ &= \infty - 1 \\ &= \infty \end{aligned} \tag{13}$$

From the above Equation (13), the conflict value $[U_p]_{ij}$ is much greater than $[U_n]_{ij}$. The conflict value is equivalent to the maximum value. However, from (10) and (11), it can be observed that small values are equalized with large values. Unfair behavior leads to an unreasonable increase in the amount of data. This increase in the number affects the prediction of the test data because both $[U_p]_{ij}$ and $[U_n]_{ij}$ are converted to 1 in the rule ordering process. □

Definition 2 (percentage of variation coefficient). *The coefficient of variation (CV) is defined as the ratio of the standard deviation (S) in Equation (14) and the sample mean (\bar{x}) in Equation (15).*

$$\bar{x} = \frac{\sum_{k=1}^n x_k}{N} \tag{14}$$

where \bar{x} represents the sample mean of the elements at the same position in the initial rule matrices $[U_p]$ and $[U_n]$. x_k is the observed value, where $k = (1, 2, \dots, n)$, and N represents

the total number of observations. In this particular case, the number of observations is always $N = 2$.

$$S = \sqrt{\sum_{k=1}^n \left(\frac{(x_k - \bar{x})^2}{N - 1} \right)} \tag{15}$$

where S is the standard deviation of the elements in the initial rule matrices U_p and U_n at corresponding positions and the percentage CV (%CV) can be represented as (16)

$$\%CV = \frac{S}{\bar{x}} \times 100 \tag{16}$$

Lemma 2. *The percentage coefficient of variance can measure the classification ability of the initial rule matrices for each position.*

To make all positions of the initial matrix comparable, we used the percentage coefficient of variation to measure the abilities of each initial rule matrix position, instead of using direct conflict values that do not allow for comparisons.

Proof of Lemma 2. First, we simplify (16) to calculate the %CV of matrices U_p and U_n as follows:

Represent $\bar{x}(U_p, U_n)$ for each element, i is the row and j is the column of matrices U_p and U_n as following (17)

$$\bar{x}(U_p, U_n) = \frac{[U_p]_{ij} + [U_n]_{ij}}{2} \tag{17}$$

Substituting $N = 2$, $x = [U_p]_{ij}$ and $[U_n]_{ij}$ into (15)

$$\begin{aligned} S(U_p, U_n) &= \sqrt{\frac{([U_p]_{ij} - \bar{x})^2 + ([U_n]_{ij} - \bar{x})^2}{2 - 1}} \\ &= \sqrt{([U_p]_{ij} - \bar{x})^2 + ([U_n]_{ij} - \bar{x})^2} \end{aligned} \tag{18}$$

Substitute $\bar{x}(U_p, U_n)$ from (17) in (18), we obtain:

$$\begin{aligned} S &= \sqrt{\left([U_p]_{ij} - \left(\frac{[U_p]_{ij} + [U_n]_{ij}}{2} \right) \right)^2 + \left([U_n]_{ij} - \left(\frac{[U_p]_{ij} + [U_n]_{ij}}{2} \right) \right)^2} \\ &= \sqrt{\left(\frac{2[U_p]_{ij} - [U_p]_{ij} - [U_n]_{ij}}{2} \right)^2 + \left(\frac{2[U_n]_{ij} - [U_p]_{ij} - [U_n]_{ij}}{2} \right)^2} \\ &= \sqrt{\left(\frac{[U_p]_{ij} - [U_n]_{ij}}{2} \right)^2 + \left(\frac{[U_n]_{ij} - [U_p]_{ij}}{2} \right)^2} \\ &= \sqrt{\frac{([U_p]_{ij} - [U_n]_{ij})^2 + ([U_n]_{ij} - [U_p]_{ij})^2}{4}} \end{aligned} \tag{19}$$

Assuming that

$$\frac{([U_p]_{ij} - [U_n]_{ij})^2}{4} = \frac{([U_n]_{ij} - [U_p]_{ij})^2}{4} \tag{20}$$

where $\frac{([U_p]_{ij}' - [U_n]_{ij}')^2}{4}, \frac{([U_n]_{ij} - [U_p]_{ij})^2}{4} \in \mathbb{R}^+$.

Substitute Equation (20) in to Equation (19)

$$\begin{aligned}
 S &= \sqrt{\frac{([U_p]_{ij} - [U_n]_{ij})^2}{4} + \frac{([U_p]_{ij} - [U_n]_{ij})^2}{4}} \\
 &= \sqrt{2 \frac{([U_p]_{ij} - [U_n]_{ij})^2}{4}} \\
 &= \frac{|[U_p]_{ij} - [U_n]_{ij}|}{\sqrt{2}}
 \end{aligned}
 \tag{21}$$

Substituting \bar{x} and S from (17) and (21) into (16)

$$\begin{aligned}
 \%CV_{ij} &= \frac{\frac{|[U_p]_{ij} - [U_n]_{ij}|}{\sqrt{2}}}{\frac{[U_p]_{ij} + [U_n]_{ij}}{2}} \times 100 \\
 &= \begin{cases} \sqrt{2} \frac{|[U_p]_{ij} - [U_n]_{ij}|}{[U_p]_{ij} + [U_n]_{ij}} \times 100, [U_p]_{ij} + [U_n]_{ij} > 0 \\ 0, otherwise \end{cases}
 \end{aligned}
 \tag{22}$$

Assuming that $[U_p]_{ij} > [U_n]_{ij}$ then

$$\text{Conflict value} = |[U_p]_{ij} - [U_n]_{ij}|
 \tag{23}$$

Substitute (23) into (22), then

$$\%CV_{ij} = \begin{cases} \sqrt{2} \frac{(\text{Conflict value})}{[U_p]_{ij} + [U_n]_{ij}} \times 100, [U_p]_{ij} + [U_n]_{ij} > 0 \\ 0, otherwise \end{cases}
 \tag{24}$$

From Equation (24), we can observe that as the conflict value increases, the percentage of variance also increases. This implies that the two values are directly proportional to each other, indicating that the percentage variance can be used to measure classification ability. □

Lemma 3. *Eliminating the element with the lower value could improve classification accuracy.*

Proof of Lemma 3. Assuming that $[U_p]_{ij} \gg [U_n]_{ij}$ and $\omega_p, \omega_n = 0$ from (10) and (11), then

$$\begin{aligned}
 \text{Conflict value} &= [U_p]_{ij} - [U_n]_{ij} \\
 \text{Conflict value} &\approx [U_p]_{ij}
 \end{aligned}
 \tag{25}$$

where $[U_n]_{ij} > 0$.

From Equation (25), if we set $[U_n]_{ij}$ to 0, only the data for $[U_n]_{ij}$ will be lost, where $\lim_{x \rightarrow \infty} [U_n]_{ij} = 1$. From (24), we can reduce the *conflict value* and *%CV* by setting $[U_p]_{ij}$ to 0. This means that the classifier can better classify patterns because a lower *%CV* indicates greater classification ability. □

Definition 3 (Variance decision table). *The variance decision table (V) is the %CV representation in the matrix form.*

Definition 4 (Loss of data). *The loss of data is part of the data converted to zero to improve overall classification accuracy.*

Lemma 4. *Appropriate estimation of the percentage coefficient of variance can produce a suitable rule matrix.*

Proof of Lemma 4. From Lemma 3 $\min([U_p]_{ij}, [U_n]_{ij})$ is eliminated to increase the ability to classify patterns when $[U_p]_{ij} \gg [U_n]_{ij}$ or $[U_n]_{ij} \gg [U_p]_{ij}$.

However, when $[U_p]_{ij} \approx [U_n]_{ij}$, if we convert $\min([U_p]_{ij}, [U_n]_{ij})$ to 0, loss of data $\approx [U_p]_{ij}$ and $[U_n]_{ij}$, which could result in overfitting of the classifier model. Appropriate approximations were used to prevent the above problems and to obtain results that provided the best classification capability. □

Definition 5 (Variation coefficient). *The variation coefficient (ω_v) was obtained using V . This was estimated using the m-MBOA algorithm, which can be used to generate the best rule matrices in the synthesis process.*

Theorem 1. *The coefficient of variation and variance decision table can create effective rule matrices for the classification.*

3.1. Proposed Method

This paper proposes an efficient cellular automata-based classifier with a variance decision table (CAV). We present this algorithm in Algorithm 2. As a result, when using only the estimated random border to determine the class using the GA in rule ordering, the traditional technique has a classification accuracy problem and cannot handle high-dimensional problems. This work overcomes this limitation by adopting a unique butterfly optimization technique (m-MBOA) instead of the genetic approach depicted in Figure 2.

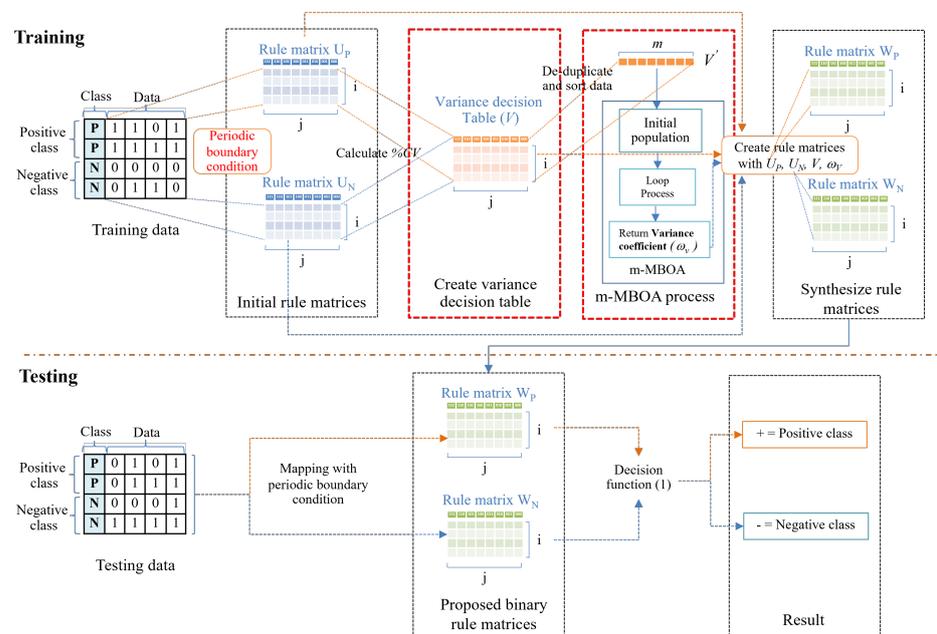


Figure 2. An overview of the proposed CAV methods.

3.1.1. Initial Values of Rule Matrices

If the input data is not binary, the rule ordering procedure begins by converting it to binary code using a Gray code [41–43] encoder. Cyclical or periodic [44,45] boundary conditions are used to maximize the rule-output equality of the available systems, whereas null boundary conditions can be relied upon to increase the overall complexity of a system [46,47]. Figure 3 shows U_p and U_n are the initial rule matrices created by counting

the *PAB* and *NAB* attractor basins, respectively. The initial rule matrix U_p is represented in matrix form with the i th ($i = 1, 2, \dots, n$) row and the j th ($j = 1, 2, \dots, n$) column. The rows reflect the number of binary features in the data, and the columns represent the number of patterns from *PAB* in which the nearest neighbors ($U_{i-1}^t, U_i^t, U_{i+1}^t$) for the i th cell decoded to decimal must equal j . Similarly, *NAB* is used to formulate an element of matrix U_n .

Algorithm 2: CAV labeled.

```

Input :Dataset  $\mathcal{D}_t$ .
Output: Rule matrices  $W_p$  and  $W_n$ .

1 Initialization:
2 if  $\mathcal{D}_t \neq$  Binary data then
3   | Convert  $\mathcal{D}_t$  to binary data using Gray code
4 end
5 The initial rule matrices  $U_p$  and  $U_n$  are created with periodic boundary conditions;
6 Create a variance decision table:
7 for  $i \leq m$  do
8   | for  $j \leq n$  do
9     | Calculate each  $\%CV_{ij}$  of the initial matrices  $U_p$  and  $U_n$  from Equation (24);
10  | end
11 end
12 Create  $V$  matrix from (26)

13 m-MBOA process:
14 Prepare array  $V'$ 
15 Process Algorithm 1. to find an  $\omega_v$  from  $V'$ 

16 Synthesis of rule matrices:
17 Create the rule matrices  $W_p$  and  $W_n$  from Equations (27) and (28) return  $W_p$ 
    and  $W_n$ 
    
```

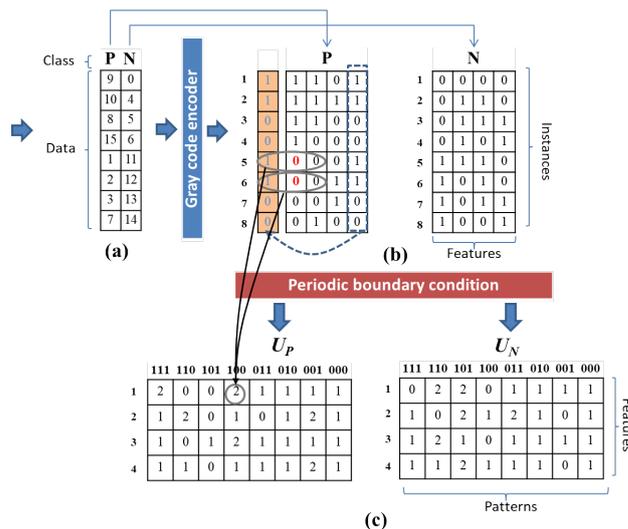


Figure 3. The initial rule matrices process consists of three steps: (a) converting the input data into binary data using a gray code encoder; (b) creating initial rule matrices with periodic boundary conditions; and (c) generating initial rule matrices for both positive and negative data.

3.1.2. Create Variance Decision Table

The variance decision table (V) corrects the percentage of the variance coefficient value and is represented in matrix form.

Subsequently, (22) is used to generate the variance decision table when $[U_p]_{ij} + [U_n]_{ij} > 0$.

$$V = \begin{bmatrix} \%CV_{11} & \%CV_{12} & \dots & \%CV_{18} \\ \%CV_{21} & \%CV_{22} & \dots & \%CV_{28} \\ \vdots & \vdots & \ddots & \vdots \\ \%CV_{n1} & \%CV_{n2} & \dots & \%CV_{n8} \end{bmatrix} \tag{26}$$

where n refers to the number of features in the dataset represented by the binary patterns. An example of creating a variance decision table is shown in Figure 4.

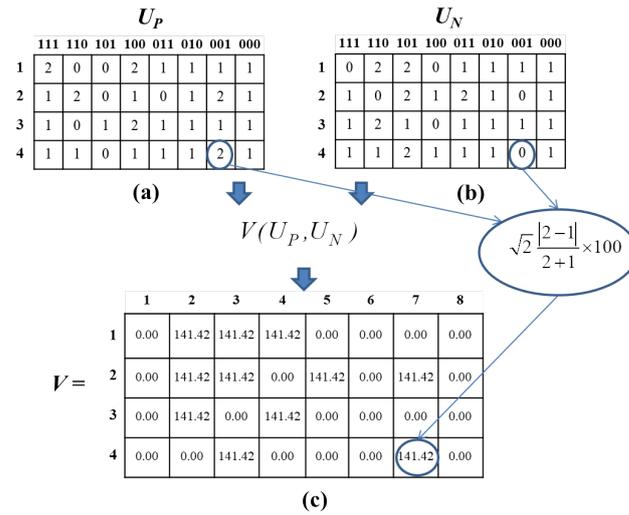


Figure 4. The Create Variance Decision Table process. (a) Initial rule matrix of positive data; (b) initial rule matrix of negative data; and (c) generating variance decision table.

3.1.3. m-MBOA Process

The CAV starts by transforming V into vector V' under the following conditions, as shown in Figure 5:

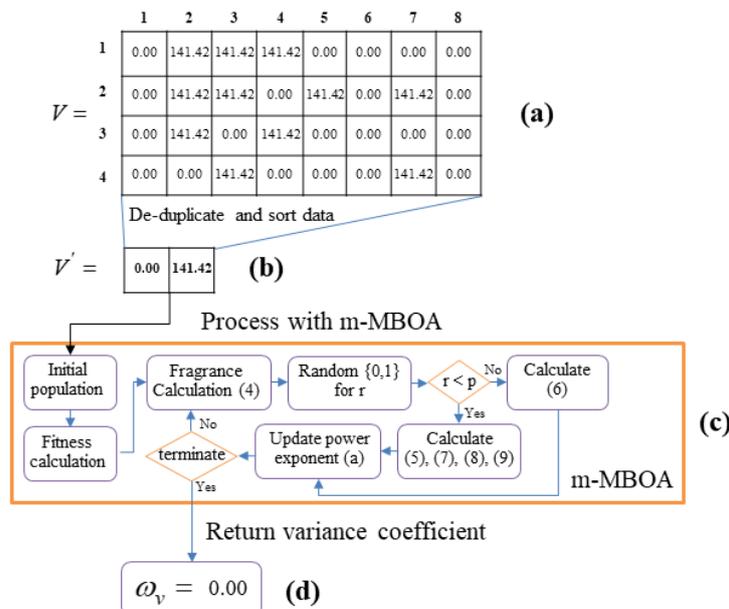


Figure 5. The m-MBOA process. (a) Variance decision table; (b) Create vector V' by de-duplicate and sort data; (c) process m-MBOA algorithm to create the variation coefficient; and (d) variation coefficient.

Matrix V is transformed into an array that is sorted but not complete, and the result is stored in array V' . The result from m-MBOA includes a variable, the variation coefficient (ω_v), which serves as a threshold that helps the classifier converge to the best solution for creating rule matrices using Equations (27) and (28).

3.1.4. Rule Matrices Synthesis

Under the following conditions, this is the final stage in generating the rule matrices.

$$[W_p]_{ij} = \begin{cases} 1, & [U_p]_{ij} \geq [U_n]_{ij} \text{ or } V_{ij} \leq \omega_v \\ 0, & \text{otherwise} \end{cases} \quad (27)$$

$$[W_n]_{ij} = \begin{cases} 1, & [U_n]_{ij} \geq [U_p]_{ij} \text{ or } V_{ij} \leq \omega_v \\ 0, & \text{otherwise} \end{cases} \quad (28)$$

where ω_v is the threshold required to converge the model to the best answer.

Although the CAV uses the same process as the traditional classifier for synthesizing the rule matrices, each element is compared between the positive and negative values of the initial rule matrices and ω_v . The CAV improves the performance of generating the final rule matrices by using the statistical relationship between U_p and U_n . We can obtain a better quality rule matrix than with the traditional method, as shown in the example in Figure 6.

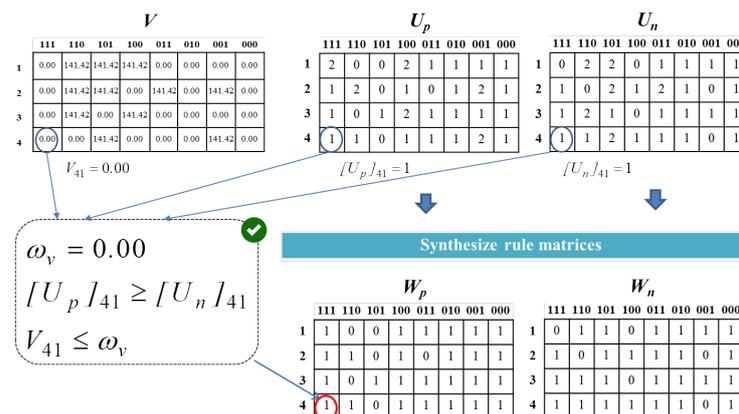


Figure 6. Synthesis rule matrices.

4. Experimentals

In this part, we present a method for assessing the effectiveness of the suggested classifier. The datasets, classifier comparison, and commentary are all given.

4.1. Experimental Setup

The classification accuracy of the classifiers was tested with both training and sample data, using 10-fold cross-validation as per CAV. A confusion matrix was utilized to determine the accuracy of classification. For multiclass classification, CAV implements a DDAG scheme [48]. To evaluate the performance of the model, standard classifiers were utilized, and non-binary datasets were first converted into Gray code during the preprocessing phase.

We compared the accuracy, precision, recall, F1, specificity, and G-mean between CAV, CAC, and several well-known classifiers, including SVM, kNN, Naïve Bayes, and two dense neural networks methods, DNN-1 and DNN-2. The DNN-1 and DNN-2 methods were distinguished by different activation functions, hidden layer numbers, and hidden layer sizes.

Finally, the butterfly optimization parameters were set up in the last preprocessing step, using the configuration shown in Table 2, to achieve optimal performance for the proposed method.

Table 2. Classification method parameters.

Classifier	Parameters	Value
CAV	Population	100
	Probability switch (p)	0.5
	Power exponent	0.4
	Sensory modality	0.03
	Max iteration	20
CAC	Sample	100
	Crossover probability	48
	Mutation probability	40
	Max iteration	20
SVM	SVM type	C-SVM
	Kernel type	Rbf
	Class weight	1.0
kNN	K (neighbor)	5
	Weighted vote	Yes
DNN-1	Activation	Rectifier
	Hidden layer number	2
	Hidden layer size	50
DNN-2	Activation	Maxout
	Hidden layer number	3
	Hidden layer size	100
Naïve Bayes	Laplace correction	Yes

4.2. Datasets

Datasets from the OpenML repository were used, consisting of different types of instances, features, and numbers of dataset classes, as shown in Table 3. The results demonstrate that the datasets form clusters, as shown by Analcatdata boxing2 (Figure 7a), Breast_w dataset (Figure 7b), Prnn synth (Figure 7d), and Mammographic mass dataset (Figure 7h), which clustered with the mean datasets. However, non-conforming data, such as Hayes roth (Figure 7c), Tae (Figure 7e), Wisconsin (Figure 7f), and SPECTheart (Figure 7g), were identified. The scatter plot results reveal ambiguous data, as most of the data from different classes are mixed, and the classification accuracy is lower when dealing with this type of data.

Table 3. Datasets.

Dataset	Class	Instances	Features
Soybean (small)	4	47	35
SPECT heart	2	80	23
Analcatdata boxing2	2	132	10
Tae	3	151	6
Hayes-Roth	3	160	5
Wisconsin	2	194	33
Sonar	2	208	61
Prnn synth	2	256	3
Thyroid Disease	2	306	3
Ecoli	8	336	8
Congressional Voting	2	435	16
Monk Problem 2	2	601	7
Breast w	2	699	10
Pima Indians Diabetes	2	768	8
Mammographic Mass	2	961	6

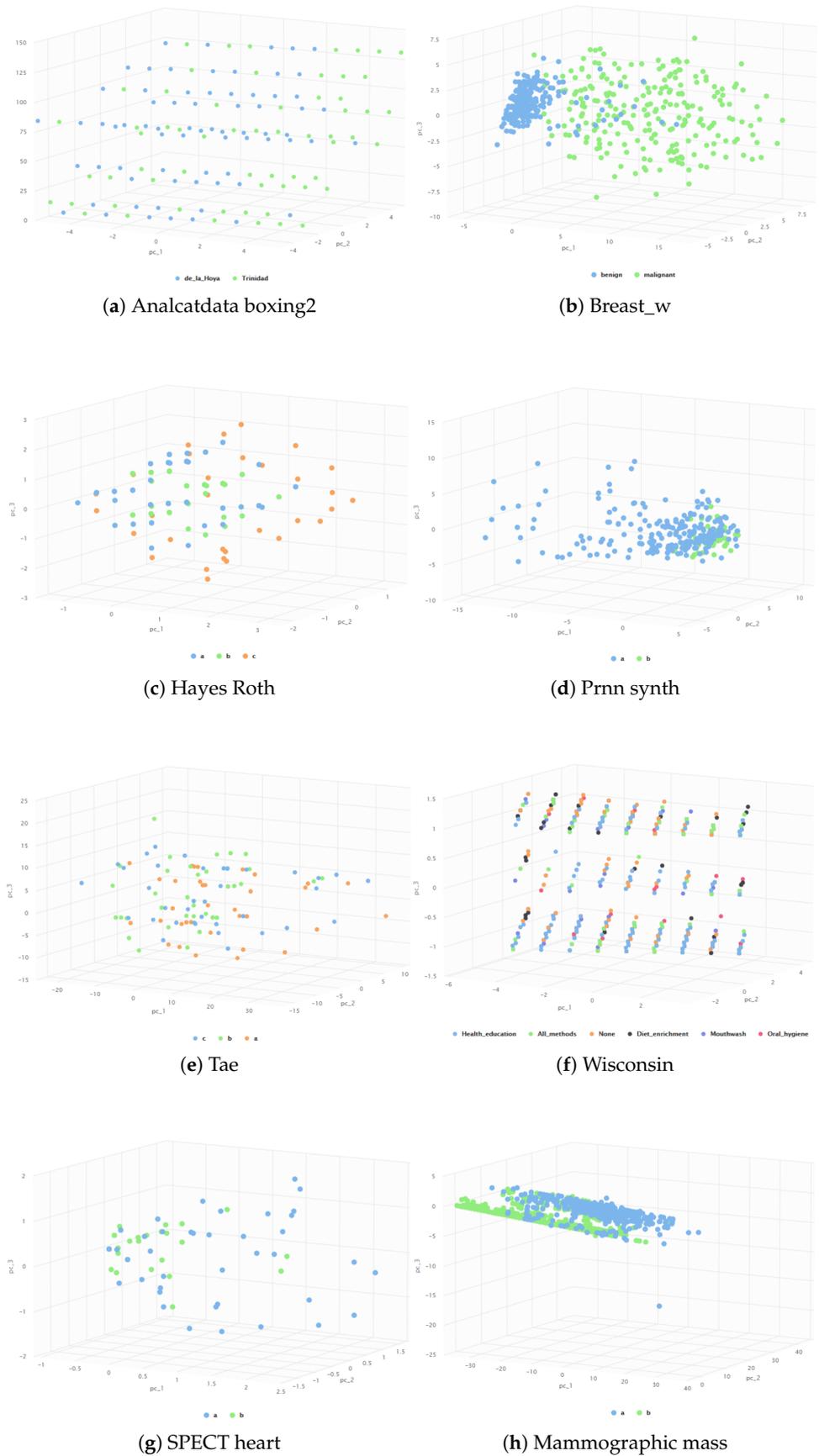


Figure 7. Illustration of dataset distribution using the PCA technique.

4.3. Classifier Performance Evaluation Method

This step involves a testing process to validate the algorithm’s classification capability and compare the performance of each model. We have chosen the following parameters: accuracy, precision, recall, F1, specificity, and G-mean. Accuracy (29) measures the model’s performance as the ratio of correctly computed data to all the data. Precision (30) is the proportion of positive data accurately measured. Recall (31) is a parameter that indicates the efficiency of positive data classification. F1 (32) is the harmonic mean of accuracy and recall, which provides an idea of the accuracy and efficiency of positive data classification. Next, the Specificity (33) parameter calculates the true proportion of validity measures for negative data, where the performance of both positive and negative data can be derived and determined using G-mean (34).

$$Accuracy = \frac{a + b}{a + b + c + d} \times 100 \tag{29}$$

$$Precision = \frac{a}{a + c} \tag{30}$$

$$Recall = \frac{a}{a + d} \tag{31}$$

$$F1 = \frac{2(Precision \times Recall)}{(Precision + Recall)} \tag{32}$$

$$Specificity = \frac{b}{b + d} \tag{33}$$

$$G - mean = \sqrt{Recall \times Specificity} \tag{34}$$

where a is a true positive (TP_i), b is a true negative (TN_i), c is false positive (FP_i), and d is false negative (FN_i), all define parameters based on confusion matrix structure.

5. Results and Discussion

Experiments were conducted on 15 OpenML datasets with varying instances and feature numbers to evaluate performance in terms of accuracy, precision, recall, F1, specificity, and G-mean, which are shown in Tables 4–9, with the best performance highlighted. A comparison of the classification results between CAV and the other classifiers is also summarized in Figures 8–13.

Table 4. The accuracy of the proposed CAV compared with CAC, SVM, k-NN, DNN-1, DNN-2, and naïve Bayes (the bold number indicates the maximum value).

Dataset	Classification Accuracy (K = 10)							Average Improvement
	CAV	CAC	SVM	kNN	DNN-1	DNN-2	Naïve Bayes	
Analcatdata boxing2	72.360	69.200	71.970	64.390	56.820	63.640	67.420	
Breast w	97.420	96.850	96.850	97.000	96.570	96.570	95.990	
Congressional voting	96.980	95.270	92.240	93.970	95.260	95.260	94.830	
Ecoli	88.240	67.510	43.740	85.120	81.850	79.510	79.170	
Hayes-Roth	78.950	77.250	43.750	66.250	58.750	66.870	70.000	
Mammographic mass	82.640	82.430	80.480	79.520	82.170	81.330	80.600	
Monk’s problems 2	67.500	63.400	82.530	66.560	63.890	74.210	64.390	
Pima indian diabetes	72.700	69.263	72.010	71.740	74.220	74.350	75.520	
Prnn synth	83.279	78.704	84.400	81.600	83.200	82.800	84.400	
Sonar	74.550	74.143	87.020	80.290	80.290	81.250	67.790	
Soybean small	100.000	100.000	100.000	97.870	100.000	100.000	100.000	
SPECTheart	75.000	62.500	68.750	63.750	71.250	71.250	68.750	
Tae	59.040	57.536	47.020	47.680	46.360	41.720	51.660	
Thyroid disease	93.960	94.892	80.930	95.350	93.490	93.490	96.740	
Wisconsin	97.510	97.217	97.070	97.360	96.930	96.930	96.190	
Average	82.675	79.078	76.584	79.230	78.737	79.945	79.563	
Improvement		3.60	6.09	3.45	3.94	2.73	3.11	4.58

Table 5. The precision of the proposed CAV compared with CAC, SVM, k-NN, DNN-1, DNN-2 and naïve Bayes (the bold number indicates the maximum value).

Dataset	Classification Accuracy (K = 10)							Average Improvement
	CAV	CAC	SVM	kNN	DNN-1	DNN-2	Naïve Bayes	
Analcatdata boxing2	0.720	0.750	0.873	0.747	0.521	0.648	0.761	
Breast w	0.993	0.994	0.972	0.974	0.965	0.965	0.952	
Congressional voting	0.983	0.977	0.887	0.927	0.944	0.960	0.960	
Ecoli	0.880	0.723	0.088	0.558	0.595	0.739	0.547	
Hayes-Roth	0.835	0.830	0.366	0.637	0.631	0.693	0.751	
Mammographic mass	0.815	0.803	0.873	0.814	0.772	0.757	0.811	
Monk's problems 2	0.889	0.727	0.779	1.000	0.527	0.676	0.980	
Pima indian diabetes	0.809	0.846	0.466	0.519	0.474	0.489	0.605	
Prnn synth	0.854	0.789	0.832	0.920	0.776	0.760	0.848	
Sonar	0.744	0.786	0.814	0.722	0.773	0.835	0.804	
Soybean small	1.000	1.000	1.000	0.975	1.000	1.000	1.000	
SPECTheart	0.815	0.583	0.450	0.450	0.700	0.700	0.450	
Tae	0.629	0.622	0.468	0.475	0.461	0.410	0.518	
Thyroid disease	0.927	0.940	0.580	0.910	0.863	0.911	0.965	
Wisconsin	0.991	0.991	0.973	0.978	0.964	0.964	0.955	
Average	0.859	0.824	0.695	0.774	0.731	0.767	0.794	
Improvement		0.035	0.164	0.085	0.128	0.092	0.065	0.114

Table 6. The recall of the proposed CAV compared with CAC, SVM, k-NN, DNN-1, DNN-2 and naïve Bayes (the bold number indicates the maximum value).

Dataset	Classification Accuracy (K = 10)							Average Improvement
	CAV	CAC	SVM	kNN	DNN-1	DNN-2	Naïve Bayes	
Analcatdata boxing2	0.631	0.500	0.689	0.646	0.617	0.667	0.675	
Breast w	0.967	0.958	0.980	0.980	0.982	0.982	0.986	
Congressional voting	0.960	0.935	0.965	0.958	0.967	0.952	0.944	
Ecoli	0.835	0.700	0.200	0.551	0.571	0.755	0.563	
Hayes-Roth	0.798	0.783	0.601	0.735	0.615	0.679	0.742	
Mammographic mass	0.834	0.851	0.760	0.775	0.847	0.843	0.794	
Monk's problems 2	0.400	0.400	0.849	0.663	0.874	0.908	0.653	
Pima indian diabetes	0.760	0.646	0.635	0.612	0.690	0.686	0.664	
Prnn synth	0.791	0.808	0.853	0.762	0.874	0.880	0.841	
Sonar	0.819	0.728	0.898	0.833	0.798	0.779	0.619	
Soybean small	1.000	1.000	1.000	0.986	1.000	1.000	1.000	
SPECTheart	0.700	0.500	0.857	0.628	0.718	0.718	0.857	
Tae	0.589	0.576	0.469	0.479	0.511	0.282	0.513	
Thyroid disease	0.927	0.925	0.806	0.960	0.962	0.911	0.942	
Wisconsin	0.971	0.966	0.982	0.982	0.989	0.989	0.986	
Average	0.799	0.752	0.769	0.770	0.801	0.802	0.785	
Improvement		0.047	0.029	0.029	−0.002	−0.003	0.014	0.023

Table 7. The F1 of the proposed CAV compared with CAC, SVM, k-NN, DNN-1, DNN-2 and naïve Bayes (the bold number indicates the maximum value).

Dataset	Classification Accuracy (K = 10)							Average Improvement
	CAV	CAC	SVM	kNN	DNN-1	DNN-2	Naïve Bayes	
Analcatdata boxing2	0.662	0.600	0.770	0.693	0.565	0.657	0.715	
Breast w	0.980	0.975	0.976	0.977	0.974	0.974	0.969	
Congressional voting	0.971	0.971	0.924	0.943	0.955	0.956	0.953	
Ecoli	0.850	0.921	0.122	0.553	0.574	0.738	0.544	
Hayes-Roth	0.786	0.788	0.310	0.663	0.622	0.685	0.742	
Mammographic mass	0.823	0.825	0.813	0.794	0.808	0.797	0.803	
Monk's problems 2	0.552	0.516	0.812	0.797	0.657	0.775	0.783	
Pima indian diabetes	0.784	0.732	0.538	0.562	0.562	0.571	0.633	
Prnn synth	0.817	0.789	0.842	0.833	0.822	0.816	0.845	
Sonar	0.773	0.748	0.854	0.774	0.785	0.806	0.700	
Soybean small	1.000	1.000	1.000	0.980	1.000	1.000	1.000	
SPECTheart	0.730	0.529	0.590	0.651	0.709	0.709	0.590	
Tae	0.569	0.551	0.464	0.474	0.445	0.327	0.501	
Thyroid disease	0.914	0.927	0.600	0.932	0.971	0.911	0.953	
Wisconsin	0.980	0.978	0.977	0.980	0.976	0.976	0.970	
Average	0.813	0.790	0.706	0.774	0.762	0.780	0.780	
Improvement		0.023	0.107	0.039	0.051	0.033	0.033	0.057

Table 8. The specificity of the proposed CAV compared with CAC, SVM, k-NN, DNN-1, DNN-2 and naïve Bayes (the bold number indicates the maximum value).

Dataset	Classification Accuracy (K = 10)							Average Improvement
	CAV	CAC	SVM	kNN	DNN-1	DNN-2	Naïve Bayes	
Analcata data boxing2	0.804	0.857	0.786	0.640	0.528	0.603	0.673	
Breast w	0.988	0.988	0.947	0.951	0.936	0.936	0.914	
Congressional voting	0.981	0.973	0.881	0.920	0.937	0.953	0.953	
Ecoli	0.850	0.921	0.000	0.978	0.973	0.948	0.969	
Hayes-Roth	0.887	0.873	0.718	0.819	0.777	0.823	0.837	
Mammographic mass	0.820	0.799	0.861	0.816	0.801	0.791	0.818	
Monk's problems 2	0.675	0.857	0.807	1.000	0.485	0.583	0.000	
Pima indian diabetes	0.727	0.780	0.750	0.762	0.759	0.763	0.798	
Prnn synth	0.872	0.767	0.836	0.899	0.799	0.789	0.847	
Sonar	0.663	0.753	0.850	0.782	0.807	0.846	0.768	
Soybean small	1.000	1.000	1.000	0.993	1.000	1.000	1.000	
SPECTheart	0.800	0.750	0.627	0.649	0.707	0.707	0.627	
Tae	0.795	0.789	0.737	0.739	0.735	0.724	0.768	
Thyroid disease	0.960	0.960	0.809	0.975	0.935	0.951	0.971	
Wisconsin	0.983	0.983	0.951	0.959	0.936	0.936	0.921	
Average	0.854	0.870	0.771	0.859	0.808	0.824	0.791	
Improvement		-0.016	0.083	-0.005	0.046	0.030	0.063	0.040

Table 9. The G-mean of the proposed CAV compared with CAC, SVM, k-NN, DNN-1, DNN-2, and naïve Bayes (the bold number indicates the maximum value).

Dataset	Classification Accuracy (K = 10)							Average Improvement
	CAV	CAC	SVM	kNN	DNN-1	DNN-2	Naïve Bayes	
Analcata data boxing2	0.712	0.655	0.736	0.643	0.571	0.634	0.674	
Breast w	0.977	0.973	0.963	0.965	0.959	0.959	0.950	
Congressional voting	0.970	0.954	0.922	0.939	0.952	0.953	0.949	
Ecoli	0.843	0.803	0.000	0.734	0.745	0.846	0.738	
Hayes-Roth	0.841	0.827	0.657	0.776	0.691	0.748	0.788	
Mammographic mass	0.827	0.825	0.809	0.795	0.824	0.816	0.806	
Monk's problems 2	0.520	0.585	0.827	0.814	0.651	0.728	0.000	
Pima indian diabetes	0.743	0.710	0.690	0.683	0.724	0.723	0.728	
Prnn synth	0.831	0.787	0.844	0.827	0.835	0.833	0.844	
Sonar	0.737	0.740	0.874	0.807	0.802	0.812	0.690	
Soybean small	1.000	1.000	1.000	0.990	1.000	1.000	1.000	
SPECTheart	0.748	0.612	0.733	0.638	0.713	0.713	0.733	
Tae	0.684	0.674	0.587	0.595	0.612	0.452	0.628	
Thyroid disease	0.943	0.942	0.808	0.967	0.948	0.931	0.956	
Wisconsin	0.977	0.974	0.966	0.970	0.962	0.962	0.953	
Average	0.824	0.804	0.761	0.810	0.799	0.807	0.762	
Improvement		0.020	0.063	0.014	0.024	0.016	0.061	0.040

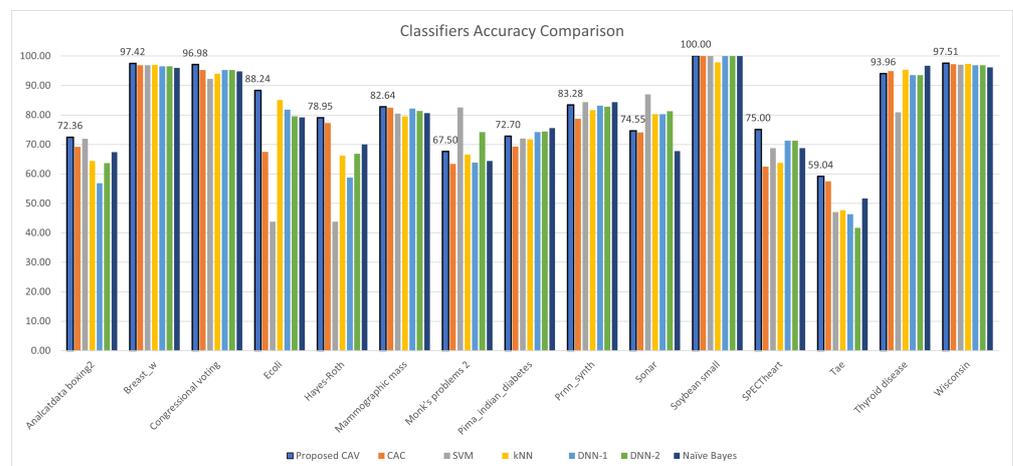


Figure 8. CAV with other classifiers; accuracy comparison for the test datasets.

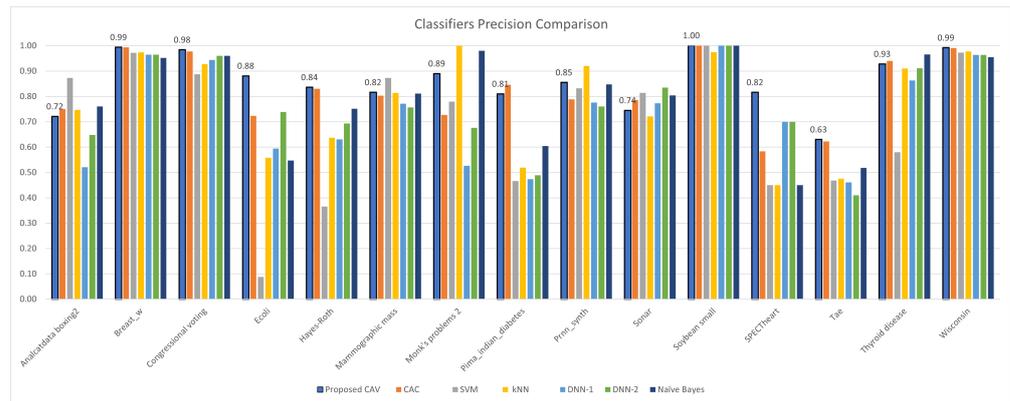


Figure 9. CAV with other classifiers; precision comparison for the test datasets.

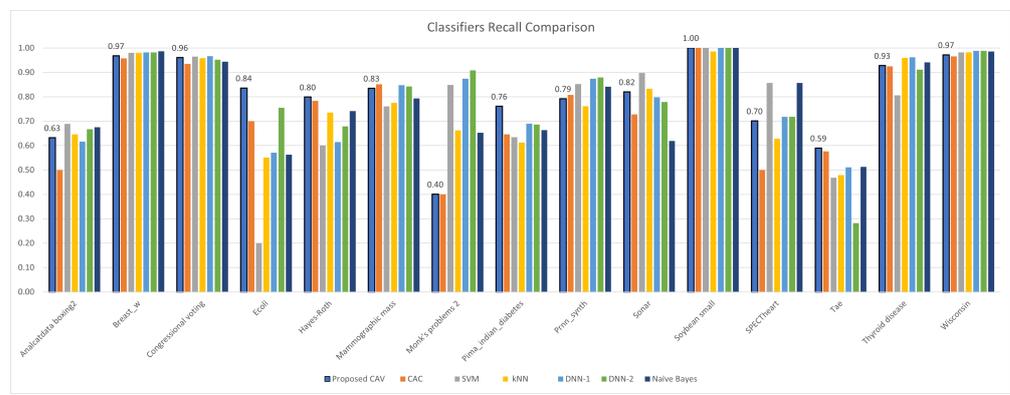


Figure 10. CAV with other classifiers; recall comparison for the test datasets.

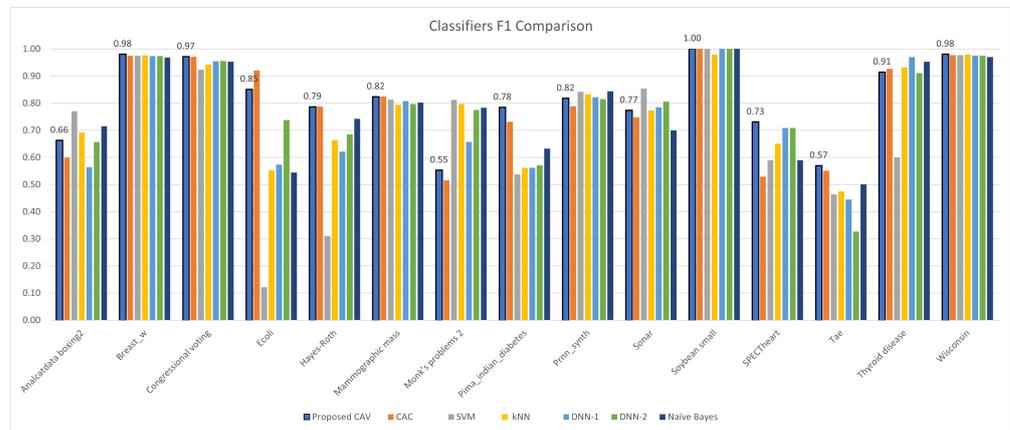


Figure 11. CAV with other classifiers; F1 comparison for the test datasets.

In terms of classification accuracy, Table 4 shows that the proposed methods have the highest classification accuracy for the following datasets: congressional voting, monk problem 2, SPECT heart, mammographic mass, Hayes–Roth, Tae, Breast w, Analcattdata boxing2, soybean (small), and Pima Indians diabetes. For the Sonar dataset, SVM achieved the highest accuracy, while the naive Bayes algorithm was the most accurate for the thyroid disease dataset. CAV was the second-best classification result for the thyroid disease dataset, and k-NN was the best for the Ecoli dataset. SVM and naive Bayes yielded the best classification results for the Prnn synth dataset. For the Wisconsin dataset, the k-NN classifier produced the best results. The results demonstrate that CAV is the best classifier for most of the test datasets, but there are a few datasets in which it is inferior to other classification algorithms.

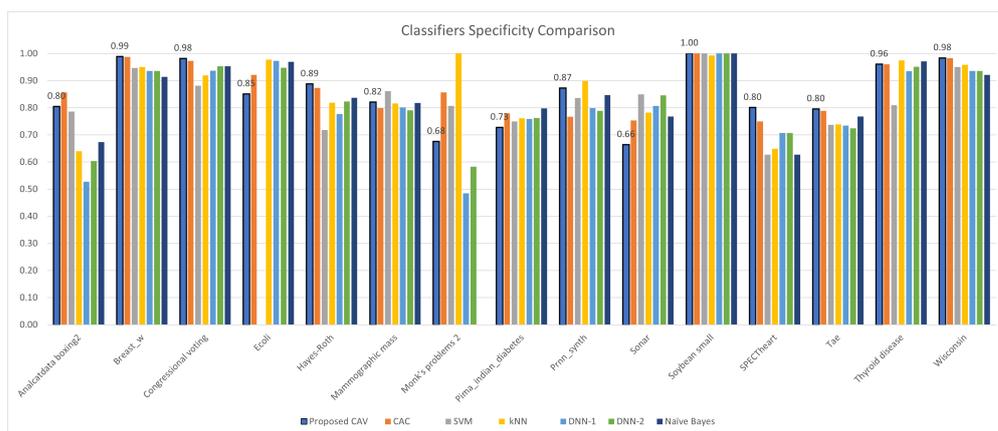


Figure 12. CAV with other classifiers; specificity comparison for the test datasets.

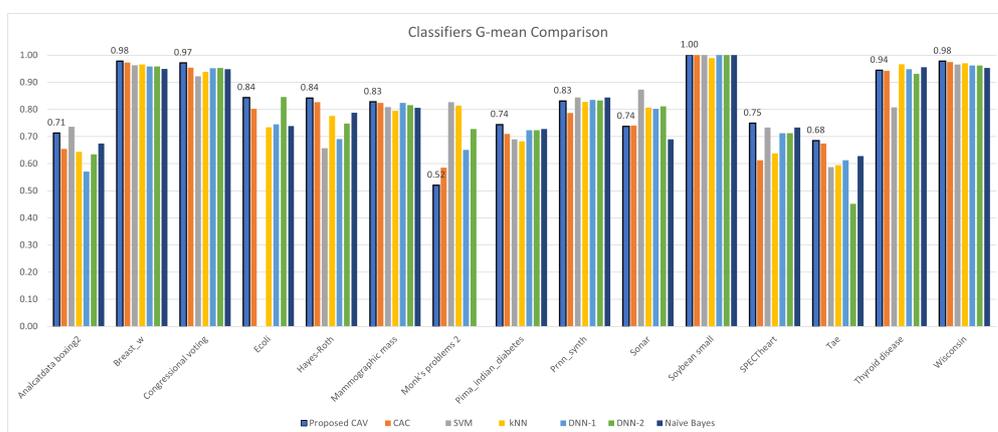


Figure 13. CAV with other classifiers; G-mean comparison for the test datasets.

The average accuracy and improvement shows that the proposed algorithm can handle classification problems more efficiently than other classifiers. However, different classification models perform well only for specific datasets. Figure 14a presents an analysis of the mean classification ability, indicating that the proposed model is the most effective classifier compared to the others.

Conversely, the proposed method also reported high classification accuracy, which was significantly different. The classification accuracy for datasets with non-conforming patterns was much lower than that for conforming datasets due to ambiguous datasets. Nevertheless, if we consider only the correctness of the classification between CAC and CAV when comparing the classification accuracy results with the conforming pattern datasets, both obtained a high classification performance. However, CAV still obtains good results for non-conforming pattern datasets that contain more noise. In contrast, for datasets with non-conforming patterns, the classification accuracy was much lower because the dataset patterns were unclear.

In terms of classification precision (Table 5), F1 score (Table 7), and G-mean (Table 9), it can be observed that the proposed method outperforms other classifiers. Upon ranking the performance of the classifiers presented in Figure 14b,d,f, it is evident that the proposed model accurately predicted positive data, as evidenced by its high precision value. Furthermore, the proposed classifier demonstrated superior performance in handling positive data, as indicated by its high F1 score. Notably, the proposed model’s classification efficiency for both positive and negative data, as measured by the G-mean parameter, surpassed that of all other classifiers tested in the experiment. Regrettably, the proposed classifier model demonstrated suboptimal performance with respect to recall, as indicated by the values presented in Table 6, and specificity, as evidenced by the data in Table 8. Specifically, the mean of the recall sequence plotted in Figure 14c suggests that the proposed model, which

incorporates correlations derived from both positive and negative data, achieved inferior results compared to DNN-1, DNN-2, and Naive Bayes. Nevertheless, the proposed model exhibited superior performance in terms of specificity, as demonstrated by its ranking relative to comparable models in Figure 14e.

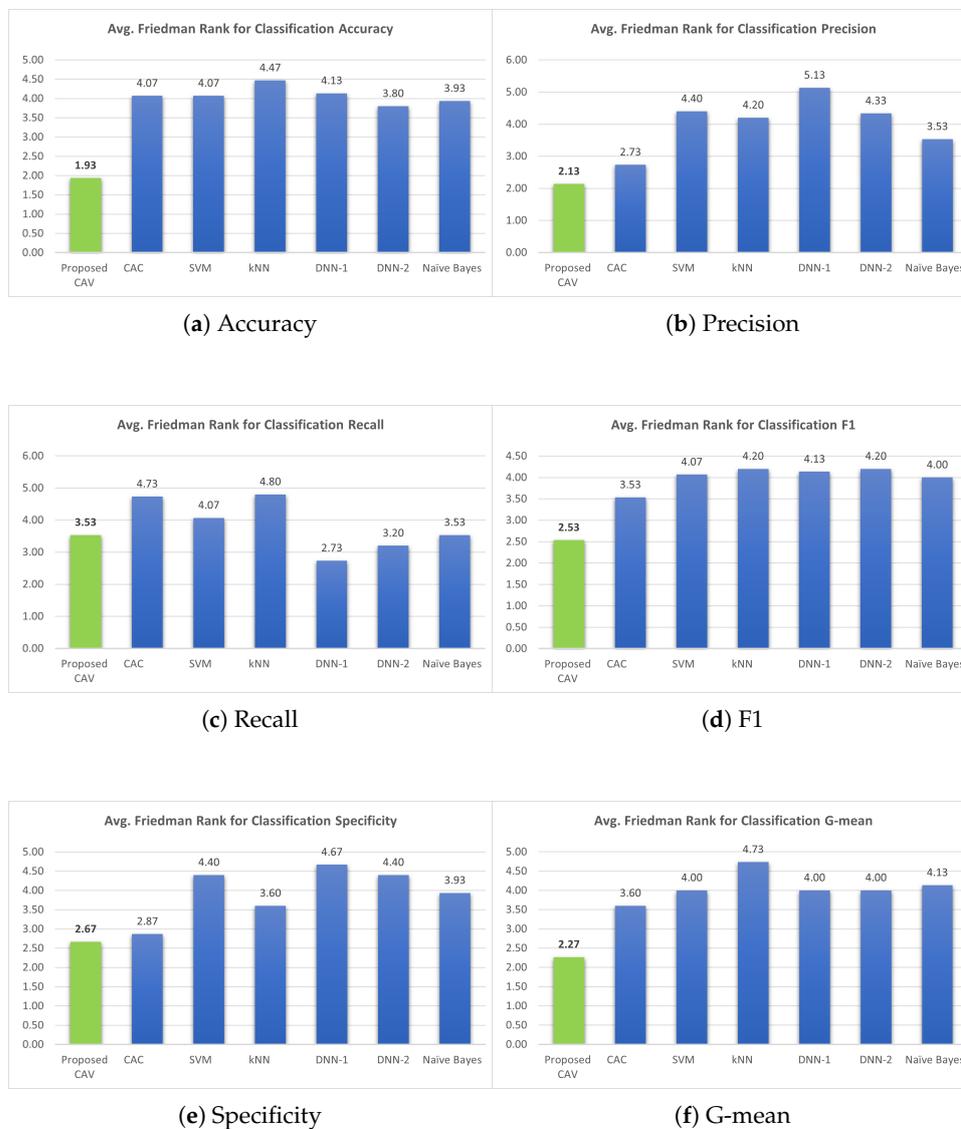


Figure 14. Illustration of the average Friedman rank for CAV, CAC, SVM, kNN, DNN-1, DNN-2, and Naïve Bayes. The green bar graph represents the value of the average Friedman rank in the proposed model, while the blue bar graph represents the corresponding value of the classifier used for comparison with the proposed model.

6. Conclusions

The CAV is a high-performance classifier capable of handling both conforming and non-conforming binary patterns to address and solve the limitation of finding decision boundaries to divide difficult data, and GA in the rule ordering process cannot handle complicated high-dimensional problems. When tested on 15 OpenML datasets with varying examples, features, and class numbers, CAV outperformed promising state-of-the-art classification approaches such as SVM, k-NN, DNN-1, DNN-2, naive Bayes, and CAC.

To increase accuracy, the following difficulties should be addressed in future studies. First, an efficient method for transforming data into binary data, other than Gray code, must be determined. Second, multiclass classification in binary classifiers (CAC and CAV) utilizing the DDAG approach was restricted. To increase classification performance, an

effective strategy may be used. Finally, in terms of classifier-based elementary cellular automata, we assume that the dataset contains equal instances for each class and does not focus on the imbalance problem. Improving the classifier performance on imbalanced data without an exciting data imbalance management method while changing the classifier process directly is an interesting area of study.

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Data Availability Statement: The data that support the findings of this study are openly available in the open machine learning foundation (OpenML) repository at <https://www.openml.org>.

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