

Supplementary Material

An Embedded System based on Raspberry Pi for Effective Electrocardiograph Monitoring

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S.1: The ECG Signal Generation

The following is the code used to generate the ECG signal.

Byte const

```
display[]={ 69,69,71,71,72,72,72,72,72,71,71,71,69,69,69,71,71,72,72,72,74,74,74,74,72,72,72,7
2,71,71,71,71,71,71,69,69,69,71,71,71,72,72,74,74,74,74,72,72,71,71,69,67,67,67,66,66,66,66,6
6,64,64,64,63,61,61,59,59,58,58,59,59,61,63,64,64,64,64,64,64,64,66,66,66,66,64,63,61,59,5
6,56,56,56,58,61,63,63,64,64,63,61,59,58,58,59,59,61,64,66,67,69,69,69,71,69,69,69,67,67,66,6
4,64,63,64,66,67,69,72,74,76,77,76,74,72,71,67,66,64,63,63,61,59,56,54,53,53,51,51,53,54,54,5
6,56,56,56,56,54,54,54,53,53,51,51,49,48,46,46,46,46,46,46,46,44,44,43,41,39,39,39,39,39,4
1,41,39,38,36,35,35,38,44,58,74,95,122,150,178,204,225,243,253,255,247,232,209,179,146,112,
79,49,26,10,2,0,3,12,20,30,36,41,44,44,43,41,38,38,36,36,36,36,38,38,38,36,36,36,35,35,35,35,3
5,35,36,36,38,39,39,41,41,41,41,41,41,41,41,39,39,39,39,41,41,43,43,44,46,46,46,46,46,46,46,4
6,46,48,49,51,53,54,56,58,58,59,59,61,63,64,66,67,71,72,72,74,74,74,74,74,76,77,79,81,84,87,8
9,92,94,95,95,97,97,97,97,97,99,99,100,102,104,105,107,107,105,104,100,95,92,89,87,86,84,82,
81,77,74,69,64,59,54,51,48,48};
```

```
int i;
void setup() {
    // put your setup code here, to run once:
    DDRD=255;
    PORTD=0;
}
void loop() {
    // put your main code here, to run repeatedly:

    for (i=0;i<=339;i++){
        PORTD=display[i];
```

```

delayMicroseconds(1500);
}
i=0;
}

```

S.2 The Gain of INA122

INA122 is a precision instrumentation amplifier that is used for accurate, low noise differential signal acquisition. It is known of its very low input bias current of only 25nA max, very low voltage noise of only 60nV/sqrt(Hz).

Based on the datasheet of the INA122 instrumentation amplifier:

$$G=5+200k/R_G$$

If $R_G=4.7k$, then the gain is 47.55

S.3 Filters and Peak Detector

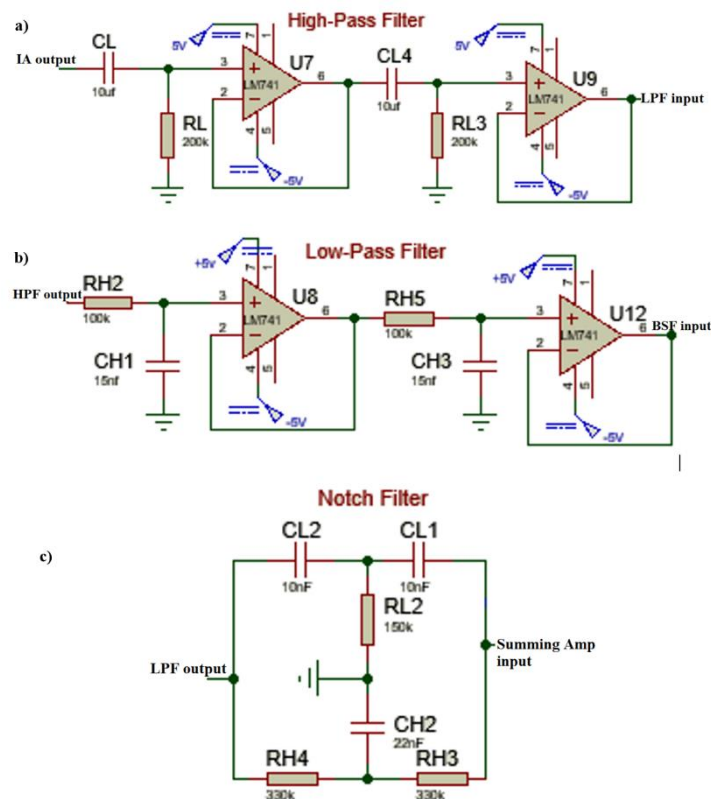


Fig.S.1 The second order HPF. **b)** The second order LPF. **c)** The second order BSF.

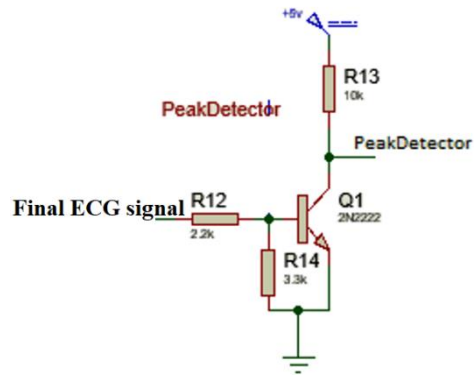


Fig.S.2 The Peak Detector

S.4 Circuit Connection on Proteus Professional Software

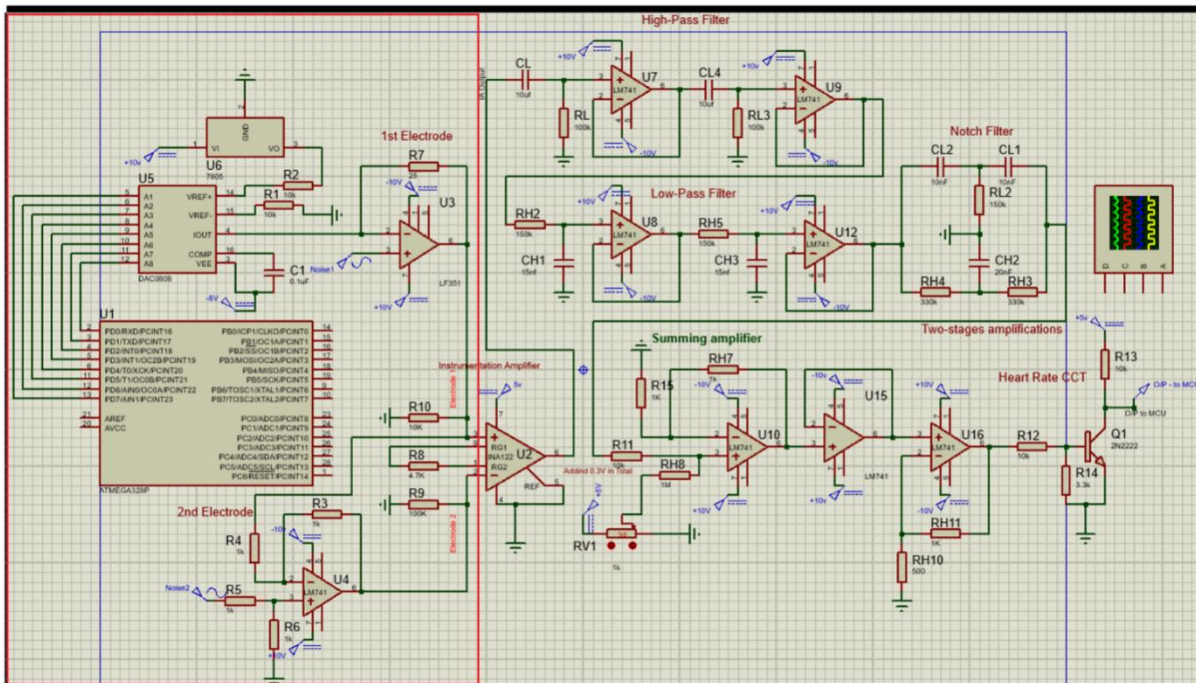


Fig.S.3 The ECG Circuit Simulation Using Proteus Professional Software.

S.5 The Printed Circuit Board Schematic and Layout on Altium

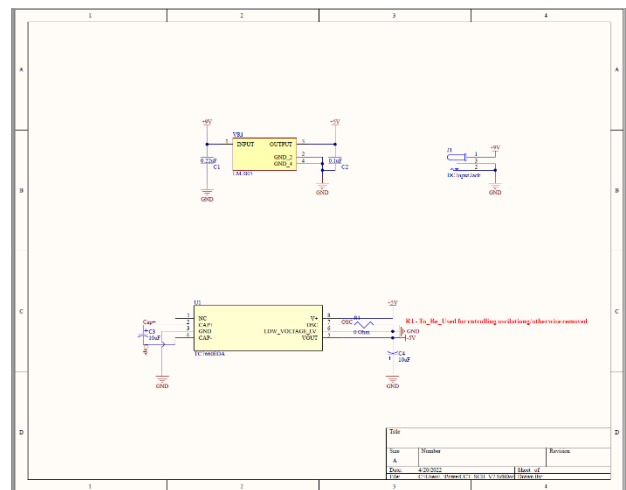
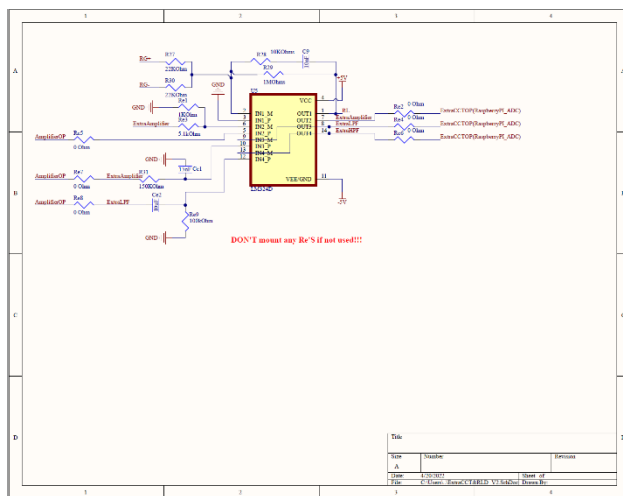
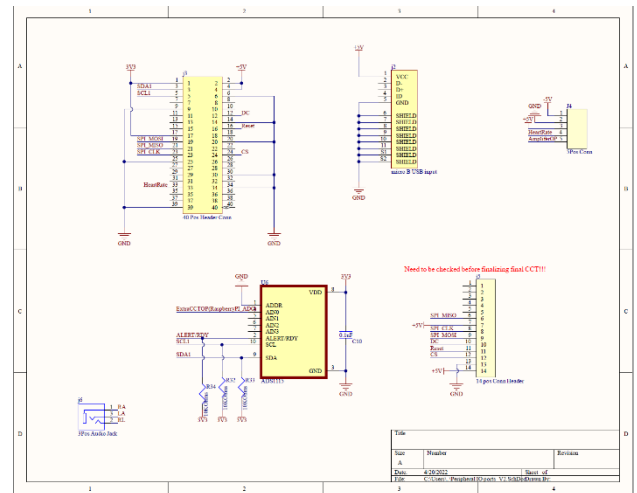
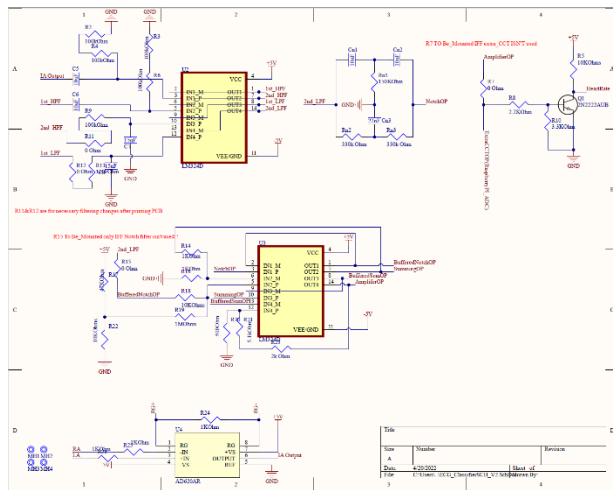
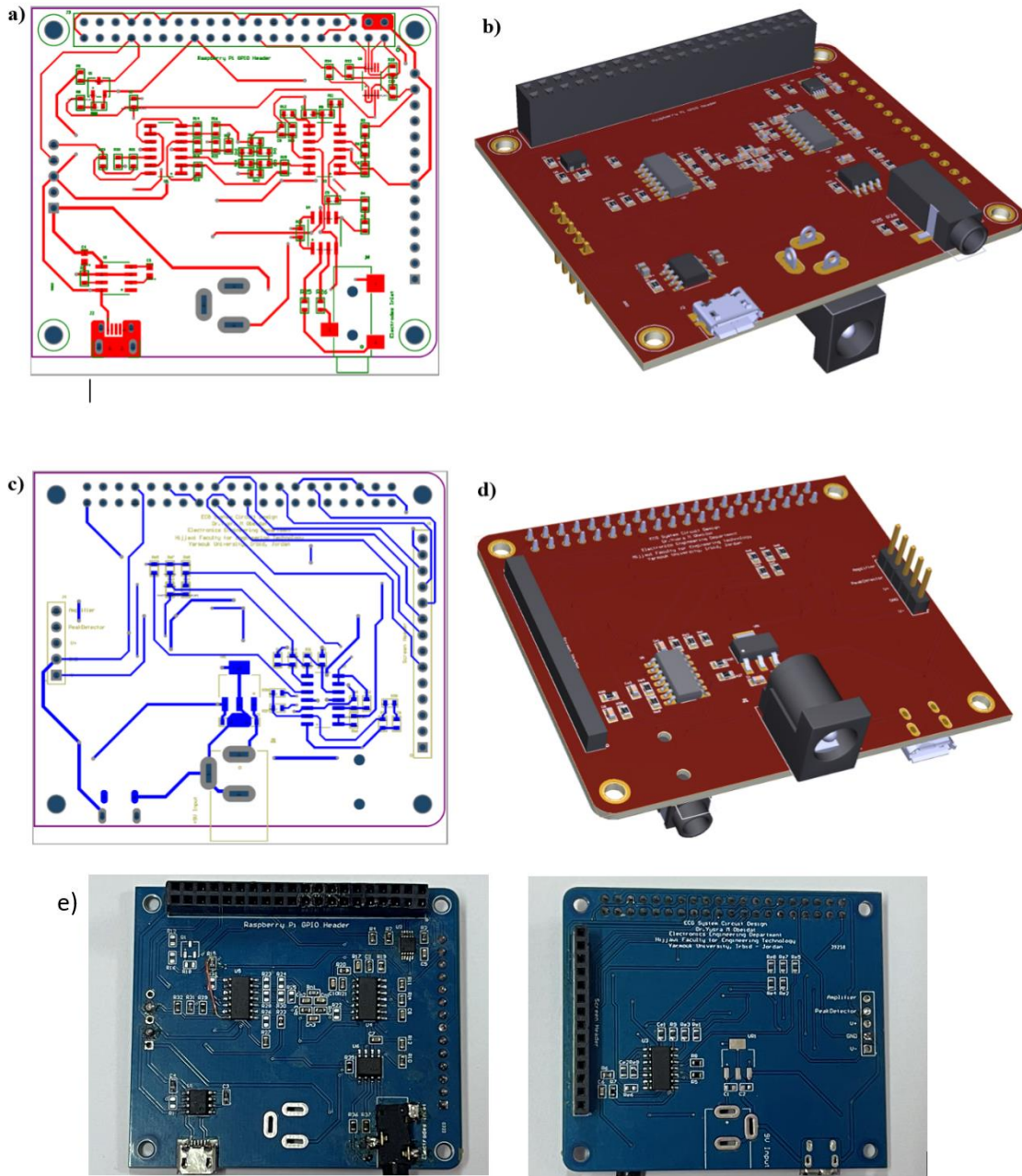


Fig.S.4 The Printed Circuit Board Schematic.

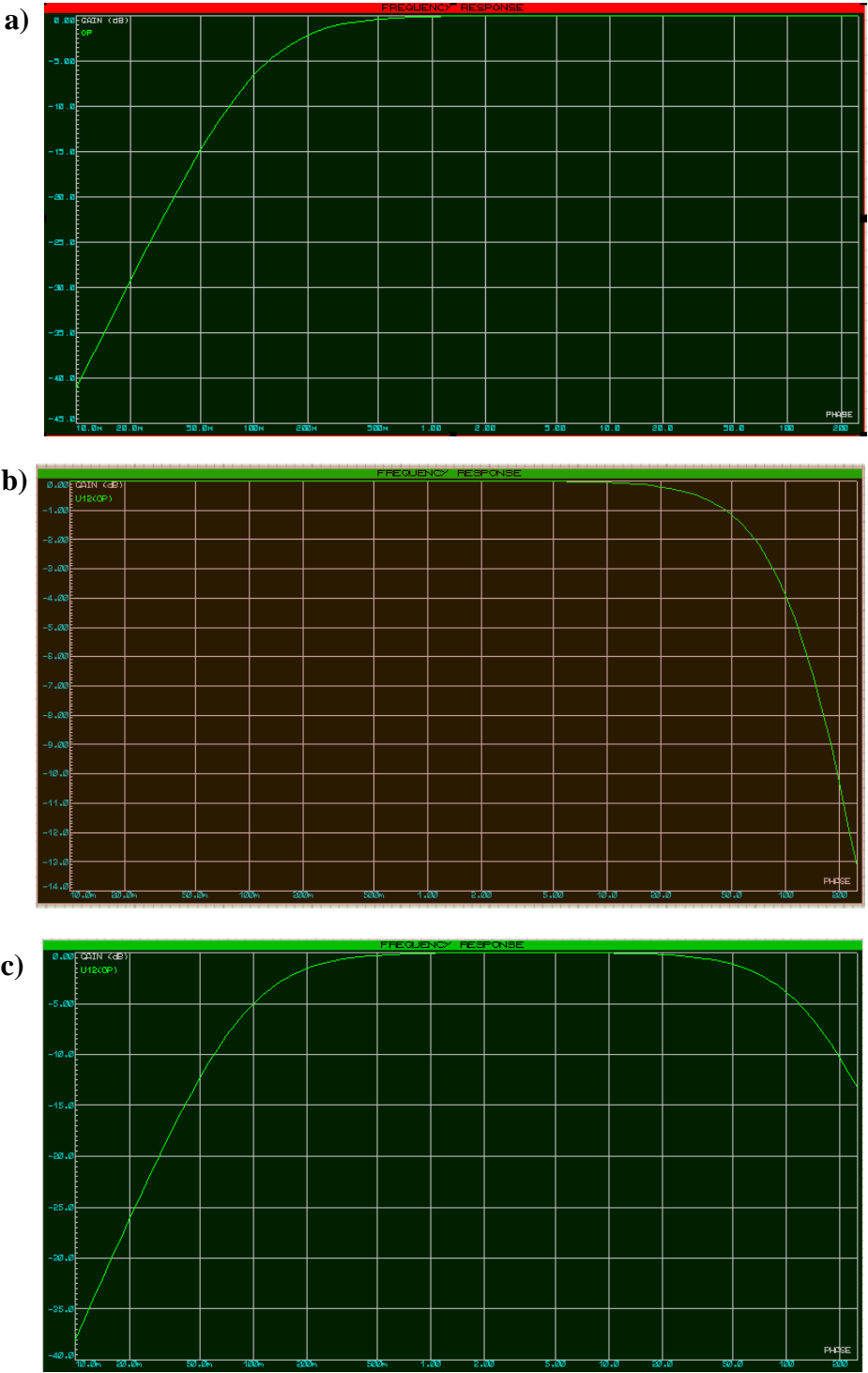


Top layer of PCB

Bottom layer of PCB

Fig.5.5 The ECG PCB Layout: **a)** The Top Layer (2D). **b)** The Top Layer (3D). **c)** The Bottom Layer (2D). **d)** The Bottom layer (3D). **e)** printed circuit board after soldering all necessary components

S.6 The Filters Bode Plots



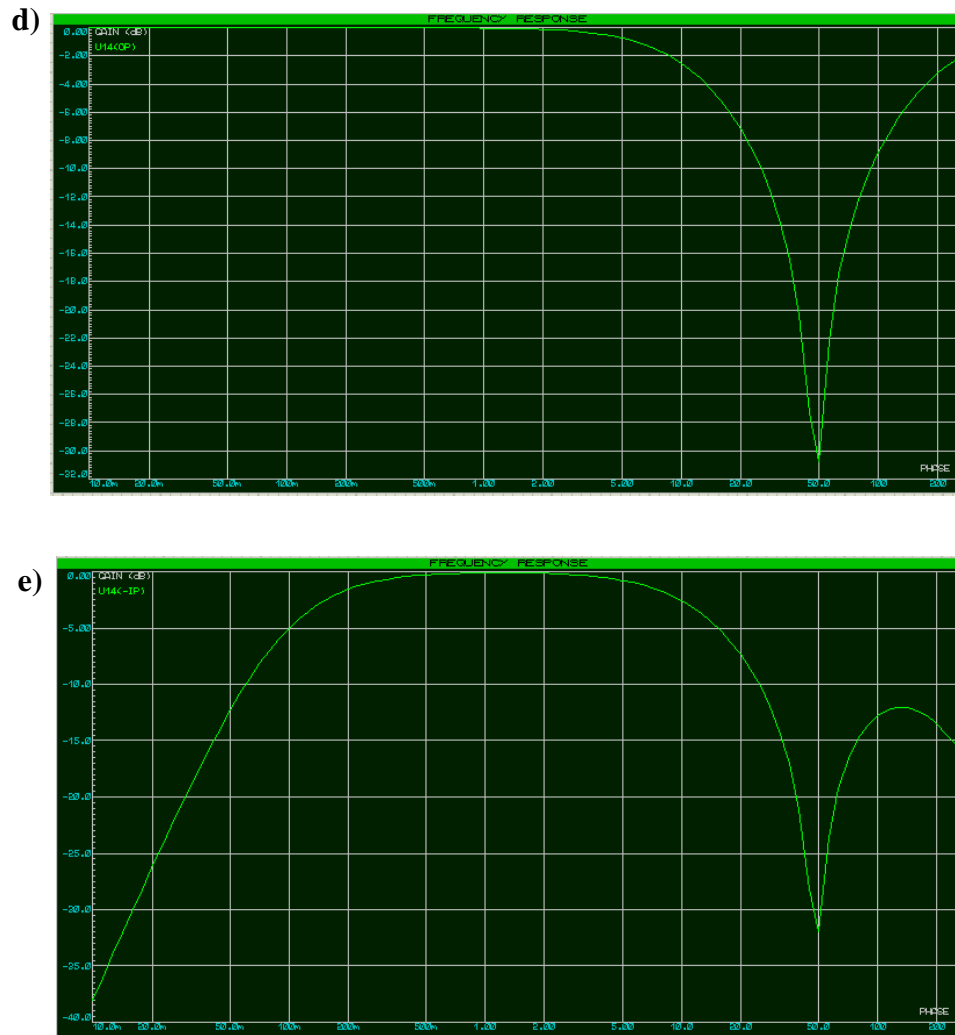


Fig.S.6: The Bode Plots for Filters: a) High Pass Filter. b) Low Pass Filter. c)Band Pass Filter. d) Notch Filter. e) All filters.

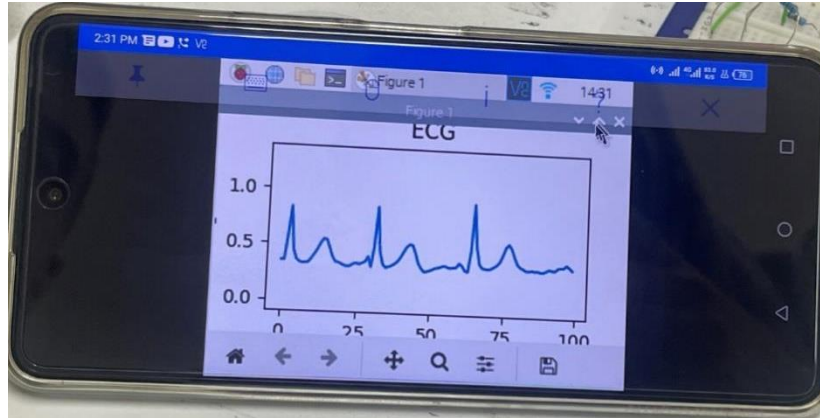


Fig.S.7: An ECG signal from human displayed on a smart phone through VNC viewer.

S.7 The programming code in python

```
fs=1000

x_len = 186      # Number of points to display

y_range = [-0.25, 1.5] # Range of possible Y values to display

rate = 0

sample=[0] * 100

# load model

model = load_model('ECG_CNNLSTM_Model.h5')

# Create figure for plotting

fig = plt.figure(figsize=(3.3,1.7))

ECG = fig.add_subplot(1, 1, 1)

xs = list(range(0, 100))

ys = [0] * x_len

ECG.set_ylim(y_range)

# Create a blank line. We will update the line in animate

line, = ECG.plot(ys)

# Add labels

plt.title(' ECG ')

plt.xlabel(' Time(ms/18.75) ')

plt.ylabel(' Voltage(V) ')

###

class Pan_Tompkins_QRS():

    def band_pass_filter(self,signal):

        """
```


Band Pass Filter

:param signal: input signal

:return: prcoessed signal

Methodology/Explanation:

Bandpass filter is used to attenuate the noise in the input signal.

To acheive a passband of 5-15 Hz, the input signal is first passed through a low pass filter having a cutoff frequency of 11 Hz and then through a high pass filter with a cutoff frequency of 5 Hz, thus achieving the required thresholds.

The low pass filter has the recursive equation:

$$y(nT) = 2y(nT - T) - y(nT - 2T) + x(nT) - 2x(nT - 6T) + x(nT - 12T)$$

The high pass filter has the recursive equation:

$$y(nT) = 32x(nT - 16T) - y(nT - T) - x(nT) + x(nT - 32T)$$

'''

Initialize result

result = None

Create a copy of the input signal

sig = signal.copy()

 # Apply the low pass filter using the equation given

for index in range(len(signal)):

 sig[index] = signal[index]

 if (index >= 1):

 sig[index] += 2*sig[index-1]

 if (index >= 2):

 sig[index] -= sig[index-2]

 if (index >= 6):

 sig[index] -= 2*signal[index-6]

 if (index >= 12):

 sig[index] += signal[index-12]

 # Copy the result of the low pass filter

result = sig.copy()

Apply the high pass filter using the equation given

for index in range(len(signal)):

 result[index] = -1*sig[index]

```
if (index >= 1):  
    result[index] -= result[index-1]  
if (index >= 16):  
    result[index] += 32*sig[index-16]  
if (index >= 32):  
    result[index] += sig[index-32]  
# Normalize the result from the high pass filter  
max_val = max(max(result),-min(result))  
result = result/max_val  
return result
```