



Article Deep Learning Based Detection of Missing Tooth Regions for Dental Implant Planning in Panoramic Radiographic Images

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Abstract: Dental implantation is a surgical procedure in oral and maxillofacial surgery. Detecting missing tooth regions is essential for planning dental implant placement. This study proposes an automated method that detects regions of missing teeth in panoramic radiographic images. Tooth instance segmentation is required to accurately detect a missing tooth region in panoramic radiographic images containing obstacles, such as dental appliances or restoration. Therefore, we constructed a dataset that contains 455 panoramic radiographic images and annotations for tooth instance segmentation and missing tooth region detection. First, the segmentation model segments teeth into the panoramic radiographic image and generates teeth masks. Second, a detection model uses the teeth masks as input to predict regions of missing teeth. Finally, the detection model identifies the position and number of missing teeth in the panoramic radiographic image. We achieved 92.14% mean Average Precision (mAP) for tooth instance segmentation and 59.09% mAP for missing teeth regions detection. As a result, this method assists diagnosis by clinicians to detect missing teeth regions for implant placement.

Keywords: missing tooth regions detection; tooth instance segmentation; dental implant placement; dental implant; panoramic radiographic image

1. Introduction

Dental implants are a common surgical procedure in oral and maxillofacial surgery [1]. Prior to implant placement surgery, it is essential to establish a surgical plan [2–4]. Generally, an implant placement plan is created using a patient's panoramic radiographic image or cone beam computed tomography (CBCT) image [5–7]. Implant placement is performed by finding missing tooth regions and determining a suitable implant product for the missing tooth regions [8,9]. Therefore, missing tooth region detection precedes implant placement. Furthermore, automatic detection of missing tooth regions is essential for developing an automatic implant placement plan.

A panoramic X-ray is one of the most commonly used diagnostic tools in modern dentistry along with CBCT due to its advantages of being more cost and time efficient than CBCT [10–17]. Furthermore, only a panoramic radiographic image is used for diagnosis instead of CBCT because of the cost of the device and imaging of CBCT in some cases [18]. As a result, we used a panoramic radiographic image in this study to reduce the amount of computation.

Due to the lack of automated technologies, clinicians had to plan dental implant placement manually. As a result, the diagnostic fatigue and burden on clinicians have steadily increased. Therefore, several studies have attempted to automatically detect missing tooth regions in order to generate an implant placement plan [8,9]. One study uses deep learning to detect missing teeth in CBCT images for implant placement planning.



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Copyright: © 2022 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). Because the missing tooth regions are predicted using surrounding information such as the location, tilt, and placement of adjacent teeth, the prediction may be inaccurate when teeth are lost consecutively [8]. A deep neural network is used to detect the missing left first molar in panoramic radiographic images, and the position and axis of the implant are generated in 3D simulation [9]. However, the previous two studies using deep learning can only detect the missing region of the specific tooth and have limitations in detecting multiple missing tooth regions simultaneously [8,9]. In actual clinical practice, multiple implants are frequently performed at the same time. Therefore, the detection of multiple missing tooth regions is necessary to establish multiple implant placement plans.

Deep learning is a type of computing method that focuses on learning successive layers of increasingly meaningful representations from data [19]. Therefore, a deep learning model can extract meaningful representations from not only linear data but also complex data. As a result, deep learning is applied to data classification, segmentation, and detection in various domains, such as images and signals [20–26]. In particular, deep learning demonstrates high performance in medical imaging [27–30]. Deep learning is also used to assist with various tasks, including caries detection and third molar extraction, in dentistry [14,15,31,32].

In this work, we propose a deep learning method to detect missing tooth regions through panoramic images as a process for dental implant planning. This method consists of tooth instance segmentation, which segments all teeth except third molars by instance in panoramic radiographic images, and missing tooth regions detection, which identifies areas of multiple missing teeth. Previously, there were no datasets for both tooth instance segmentation and missing tooth region detection at the same time. Therefore, we built a dataset for tooth instance segmentation and missing tooth region detection. Furthermore, this study can be used for the production of dental implant surgical guides, diagnostic assistance for clinicians, and the education of unskilled apprentices.

The goal of this work is to detect missing tooth regions as a process of automated dental implant placement. We propose a deep-learning-based method for the detection of missing tooth regions and tooth instance segmentation in panoramic radiographic images. The main contributions of this study are summarized as follows:

- We proposed a method of simultaneously detecting missing tooth regions for dental implant placement planning using a panoramic radiographic image.
- We constructed datasets for tooth instance segmentation and missing tooth region detection at the same time.
- By using a dataset composed of various panoramic radiographic images, we ensure consistent performance for our method.

2. Materials and Methods

2.1. Dataset

This study was approved by the Institutional Review Board (IRB) of the Chosun University Dental Hospital (CUDHIRB 2005008) and the Gwangju Institute of Science and Technology (20210217-HR-59-01-02). We used both a public dataset and acquired data in the dataset. There are 386 panoramic radiographic X-ray images in the public dataset, including images with missing teeth and teeth with restoration and dental applications [33]. In addition, the dataset we acquired contains 69 panoramic radiographic X-ray images of patients from Chosun University Dental Hospital. The dataset used in the study excluded the patient's personal information and are obtained from various panorama devices and settings. Of the 455 panoramic radiographic images, 348 images have ground truth for tooth instance segmentation, while 107 images have both the ground truth for tooth instance segmentation and missing tooth region detection. Therefore, 348 images were used to train, whereas 107 images were used to evaluate the performance of the model. As a result, the dataset is randomly split into 77.5% for training, 7.5% for validating, and 15% for testing.

2.1.1. Tooth Instance Segmentation Dataset

This dataset was used to train and evaluate models for segmenting teeth in the panoramic radiographic image on an instance-by-instance basis. The dataset contains panoramic radiographic images from various cases in which a number of teeth have been lost or include dental appliances and restoration. Figure 1 shows panoramic radiographic image and valid teeth label are required to train the tooth instance segmentation model. Therefore, the dataset was constructed by labeling each tooth with a polygon and tagging the tooth number. Labeling was performed on 28 teeth, excluding third molars, and tooth numbers were assigned based on Federation Dentaire Internationale (FDI).



Figure 1. Examples of panoramic radiographic images. (a) image with 28 teeth, (b) image with restoration, and (c) image with dental appliance.

2.1.2. Missing Tooth Regions Detection Dataset

The performance of the deep learning model depends on the amount of training data. Therefore, we constructed a dataset for the missing tooth regions detection through synthetic data generation. The synthetic dataset was constructed using teeth masks generated through tooth instance segmentation from 170 patients, as seen in Figure 2. The teeth masks assigned pixel values according to each tooth number. Synthetic teeth masks are generated by randomly removing up to 10 teeth from a tooth mask with all 28 teeth except the third molars. The ground truths for missing tooth regions are constructed in the form of a bounding box using the position information in the image of the excluded teeth. As a result, our dataset contains 37,323 synthetic images generated from 170 teeth masks.



Figure 2. Generation of synthetic data for missing tooth region detection. (**a**) Panoramic radiographic image that contains 28 teeth. (**b**) Teeth mask generated through tooth instance segmentation except third molars. (**c**) Synthetic data generated by randomly removing teeth from a tooth mask.

2.2. Tooth Instance Segmentation Model

The tooth instance segmentation model segments 28 teeth, excluding the third molars, in the panoramic radiographic image. For tooth instance segmentation, we used Mask R-CNN, which exhibited high performance in the image segmentation task [34]. ResNet-101 is used for the backbone of the segmentation model [35]. ResNet-101 is a deep neural network architecture commonly used to extract feature maps for image-based tasks, such as segmentation or object detection. In particular, ResNet-101 consists of 101 layers and contains a residual block that solves the degradation problem by reducing the difference between input and output. Figure 3 shows the schematic of the network architecture of ResNet-101. Furthermore, Figure 4 shows the results of the segmentation of teeth by instance in the panoramic radiographic image. As a result, the tooth mask generated by the tooth instance segmentation model is utilized as the input data for the missing tooth region detection model.

For data augmentation, brightness, contrast, and saturation augmentation is applied to images randomly. The segmentation model was trained by using an SGD optimizer with a learning rate of 1×10^{-2} , a batch size of 4, and the Smooth L1 loss function. The segmentation model was trained for 100,000 iterations and evaluated every 500 iterations, and the number of parameters of the model is 60.6 M.



Figure 3. Schematic of the network architecture of ResNet-101. The network is implemented by repeating the block of three convolutional layers 3, 4, 23, and 3 times, respectively. 3×3 pool means pooling layer with 3×3 filters. Furthermore, K and C are the mean size of kernel and the number of channels of convolutional layer, respectively.



(d) Result of missing tooth regions detection

(c) Generated teeth mask

Figure 4. Entire process for missing tooth region detection. Tooth instance segmentation model segments 28 teeth, excluding the third molars, in the (**a**) panoramic radiographic image. (**b**) shows result of the tooth instance segmentation model. Furthermore, then, (**c**) is generated from results of the segmentation model. The missing tooth region detection model detects the regions of missing teeth from the generated teeth mask. Furthermore, the result of the detection model is shown in (**d**).

2.3. Missing Tooth Region Detection Model

Missing tooth region detection is required for implant placement in the panoramic radiographic image. Through this model, missing tooth regions, except the third molars, are detected simultaneously. Missing tooth regions are detected in the form of bounding boxes and assigned numbers (#11~#47). For missing tooth region detection, we used Faster R-CNN, which exhibits high performance in object detection. The detection model's backbone is ResNet-101. The model was trained via the synthetic data, and real data were used for evaluation. To improve the training efficiency, the input image of the model was resized to 600×300 . Figure 4 shows the entire process for detecting missing tooth regions from the panoramic radiographic image. The detection model was trained using an SGD optimizer with a learning rate of 1×10^{-2} , a batch size of 32, and the Smooth L1 loss function. The detection model was trained for 100,000 iterations and evaluated every 500 iterations, and the number of parameters of model is 63.3 M.

2.4. Evaluation Metrics

The evaluation of the two modules is connected because the missing tooth region detection model takes segmented masks from the segmentation model as input. The mean Average Precision (mAP) was used to evaluate both the segmentation and detection models. mAP is the average of each class's AP values, with AP being the value obtained by calculating the area under the Precision–Recall curve. When the Intersection over Union (IoU) between ground truth and prediction is larger than the threshold, we considered it a correct prediction. mAP (0.5) is calculated by predicting the correct answer when IoU is >0.5, and mAP (0.5:0.95) is calculated by averaging the performance of IoUs within 0.5–0.95 in 0.05 steps.

3. Results

In this section, the performances of the tooth instance segmentation model and missing tooth region detection model are evaluated. mAP (0.5) and mAP (0.5:0.95) are used for evaluating the performance of both models.

3.1. Tooth Instance Segmentation Model

The performance of the segmentation model is evaluated using panoramic radiographic images. In Table 1, the segmentation model achieves 92.14% for mAP (0.5) and 76.78% for mAP (0.5:0.95). Furthermore, Table 2 shows the performance by each tooth number (#11 \sim #47), where #N indicates tooth number in this table. The segmentation performance of the second molars is less than the other teeth. Because the third molar's appearance and location is similar to the second molar, the segmentation model confuses the third molar with the second molar. Figure 5 describes the visualization of the segmentation model result.

3.2. Missing Tooth Regions Detection Model

We also evaluate the missing tooth region detection model using panoramic radiographic images. The detection model uses the teeth masks obtained from the tooth instance segmentation model. Table 3 shows the performance of the model. The model achieves 59.09% for mAP (0.5) and 20.40% for mAP (0.5:0.95). In addition, Table 4 exhibits the performance by each tooth number (#11~#47) where #N indicates tooth number. Because the actual patient's data was used as a test set, there is no result value for the tooth number that is not in the dataset in Table 4. In addition, the performance of the model for the second molars is lower than the other teeth. Due to the location of the second molars at the end of the tooth arrangement, there are often no adjacent teeth to guide the detection. Figure 6 illustrates the visualization of the missing tooth regions detection model results.

Table 1. Performance of tooth instance segmentation model.

Model	AP (0.5)	AP (0.5:0.95)		
Mask R-CNN	92.14%	76.78%		

Table 2. Performance of tooth instance segmentation model by tooth number.

#N	AP (0.5)	#N	AP (0.5)	#N	AP (0.5)	#N	AP (0.5)
 #11	99.67%	#21	98.01%	#31	94.99%	#41	96.76%
#12	99.64%	#22	100.0%	#32	94.72%	#42	95.33%
#13	99.35%	#23	99.08%	#33	94.44%	#43	92.71%
#14	95.14%	#24	92.79%	#34	95.60%	#44	87.51%
#15	93.21%	#25	87.15%	#35	92.97%	#45	93.70%
#16	91.08%	#26	91.70%	#36	77.49%	#46	82.81%
#17	94.60%	#27	86.58%	#37	78.70%	#47	76.58%



Figure 5. Visualization of tooth instance segmentation model result.



 $\label{eq:Figure 6.} Figure \ 6. \ Visualization \ of missing \ tooth \ regions \ detection \ model \ result.$

 Model
 AP (0.5)
 AP (0.5:0.95)

 Faster R-CNN
 59.09%
 20.40%

Table 4. Performance of missing teeth region detection model by tooth number.

Table 3. Performance of missing tooth regions detection model.

#N	AP (0.5)	#N	AP (0.5)	#N	AP (0.5)	#N	AP (0.5)
#11	50.95%	#21	50.49%	#31	-	#41	-
#12	-	#22	50%	#32	-	#42	-
#13	100%	#23	66.99%	#33	-	#43	-
#14	46.73%	#24	63.99%	#34	100%	#44	0%
#15	67.82%	#25	70.26%	#35	73.88%	#45	82.26%
#16	38.5%	#26	74.32%	#36	91.11%	#46	89.74%
#17	32.53%	#27	26.51%	#37	27.50%	#47	37.77%

4. Discussion

Recently, deep learning has been widely applied in the medical field [27–30]. In particular, deep learning demonstrates high performance in image classification, segmentation, and detection. Therefore, deep learning is used to diagnose diseases, such as specific diseases and abnormal signs in X-ray, CT, and MRI images [36–39]. In addition, previous studies demonstrate that deep learning exhibits a reliable performance in the diagnosis of dental disease [40–43].

Deep learning is a data-driven method of training. However, there are no studies and datasets for the detection of missing tooth regions for implant planning in panoramic radiographic images. Therefore, we constructed a dataset for a missing tooth region detection model and a tooth instance segmentation model.

Several studies have applied deep learning to detect missing tooth regions and segment various anatomical structures for implant planning [8,9]. Bayrakdar et al. developed an AI system that detects canal, sinus, fossa, and missing teeth in CBCT images for implant planning [8]. Liu Yun et al. proposed a deep learning method for implant planning of the mandibular left first molar. Previous studies have established implant placement plans using CBCT images [8,9]. However, CBCT requires a higher cost when compared to a panoramic radiographic X-ray. Additionally, previous studies have not fully automated methods and can only detect specific missing tooth regions. Therefore, there is a limit to detecting multiple missing tooth regions simultaneously [8,9].

In clinical practice, implant placement is frequently performed on several teeth at the same time. Thus, we developed a detection model for identifying multiple missing tooth regions simultaneously for implant placement using panoramic radiographic images. Tooth instance segmentation was conducted to improve the performance of missing teeth region detection by only segmenting the teeth in the panoramic radiographic images. As a result, we achieved that the performance of tooth instance segmentation is 92.14% for mAP (0.5) and 76.78% for mAP (0.5:0.95), while the performance of missing tooth regions detection is 59.09% for mAP (0.5) and 20.40% for mAP (0.5:0.95). Since the oral structure and tooth size vary depending on the person, there was a limit to the detection performance of the missing tooth regions.

A sufficient amount of data is required to achieve high-performance deep neural network, yet it is labor-intensive and expensive. Therefore, various previous studies have improved performance by using synthetic data when sufficient amounts of data are unavailable [44–49]. Thus, we generated 37,323 synthetic datasets and used them to achieve high performance. However, the synthetic dataset was created from only 170 teeth masks. Thus, the synthetic dataset has limitations in diversity. Therefore, if more real data are accumulated, we expect the detection performance of the missing tooth regions to improve.

For automatic dental implant placement planning, future work is required to develop a method that creates the position, axis, and size of the implant for the missing tooth regions in the panoramic radiographic image. Using a panoramic radiographic image for a deep learning model can reduce the computational cost more than using CBCT images. However, using CBCT is essential to planning the dental implant placement. As a result, future work is required to generate dental implant placement plans using a deep learning model from a 2D image and then convert the results into CBCT image. Through this methodology, we expect it to support clinicians in diagnosing quicker and providing patients with more transparency in their treatment. As a result, this work investigates a previous process in the generation of the implant placement plan that estimates the position, axis, and size of the implant in the panoramic radiographic image.

5. Conclusions

Detection of missing tooth regions is an essential part of implant placement planning. Therefore, this study proposes a method for detecting missing tooth regions through panoramic radiographic images. The results of this study demonstrate that a deep learning model can provide a great contribution to the automation of implant placement. This study also constructed a dataset for tooth instance segmentation and missing tooth region detection in panoramic radiographic images. In the future, the use of more data and an improved algorithm will be more helpful in automating implant placement.

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Informed Consent Statement: Informed consent was obtained from all subjects involved in the study.

Data Availability Statement: The datasets generated during and/or analyzed during the current study are available from the corresponding author on reasonable request but is subject to the permission of the Institutional Review Boards of the participating institutions.

Conflicts of Interest: The authors declare no conflict of interest.

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