



Article Adaptive Prediction of Enhanced Oil Recovery by N₂ huff-n-puff in Fractured-Cavity Reservoir Using an FNN-FDS Hybrid Model

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Abstract: N₂ huff-n-puff has proven to be a promising technique to further improve oil recovery in naturally fractured-cavity carbonate reservoirs. The effect of enhanced oil recovery (EOR) by N₂ huff-n-puff is significantly affected by various dynamic and static factors such as type of reservoir space, reservoir connectivity, water influx, operational parameters, and so on, typically leading to a significant increase in oil production. To reduce the prediction uncertainty of EOR performance by N₂ huff-n-puff, an adaptive hybrid model was proposed based on the fundamental principles of fuzzy neural network (FNN) and fractional differential simulation (FDS); a detailed prediction process of the hybrid model was also illustrated. The accuracy of the proposed FNN-FDS hybrid model was validated using production history of N₂ huff-n-puff in a typical fractured-cavity carbonate reservoir. The methodology can serve as an effective tool to optimize developmental design schemes when using N₂ huff-n-puff to tap more remaining oil in similar types of carbonate reservoirs.

Keywords: N₂ huff-n-puff; fractured-cavity reservoir; adaptive performance prediction; fuzzy neural network; fractional differential simulation

1. Introduction

The main reservoir spaces of typical fractured-cavity reservoirs consist of karst caves, high-angle fracture networks, and many dissolved pores [1,2]. The reservoir heterogeneity is extremely important, mainly because the distribution is random, the internal structure is very uneven, the spatial configuration pattern of caverns and cracks is complex, and oil-water relationship and flow dynamics are complicated [3,4]. In the early development stage of a fractured-cavity carbonate reservoir, oil production typically depends on natural or bottom water energy. Water injection is one of the more widely used strategies to increase oil production and slow down its decline. However, as the oil-water interface gradually rises, the increase of oil production usually diminishes after water huff-n-puff; a large portion of crude oil remains underground and cannot be produced [5]. Many pilot tests demonstrate that after N_2 gas is injected into a cavity it will move up due to gravity segregation, and gradually occupy the upper space of the cavity, thus displacing crude oil down into the producing wells. N₂ can also be used to replenish reservoir energy, slow down the decline of oil production, and improve oil recovery [6,7]. It is of great importance to make an accurate prediction about N2 huff-n-puff in order to explore its potential in fractured-cavity carbonate reservoirs.



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The artificial neural network-improved fuzzy inference system (ANFIS), firstly developed by Jang (1993) [8], was proven to be an effective tool for exploring inherent behaviors in different areas of study (e.g., water drought, sediment transport, PCP-based NMDA receptor antagonists, elastic constants of rocks, hepatitis C Virus, hydrologic modelling, and hydropower stream flow [9-15]). In recent decades, the ANFIS model has appealed great attentions to improve its predictive ability. By integrating advantages of grey wolf optimization and adaptive neuro-fuzzy inference system, an improved ANFIS is proposed by Dehghani et al. [16], showing better prediction capability. Goodarzi and Freitas [17] studied the feasibility of principal component analysis to design an adaptive neuro-fuzzy inference. By selecting the grid partition (GP), fuzzy c-means (FCM), and subtractive clustering (SC) as three fuzzy inference system structures, Mostafaei [18] developed novel ANFIS models to predict the cetane number of biodiesels. Dastorani et al. [19] applied the artificial neural network (ANN) and ANFIS models to reconstruct missing flow data. Some other self-adaptive methods were also developed in previous oil and gas studies [20,21]. Vardian et al. [22–24] concluded that the ANFIS system can serve as an excellent model with relatively few errors. The ANFIS model has a strong training capability, which is akin to the ANN. Using the back-propagation algorithm, the parameters involved in the ANFIS model were adjusted until an expected error was reached.

The goal of grey prediction is to construct differential equations for prediction, so it can be regarded as one form of differential simulation prediction. There may be multiple controlling factors of the forecasting indicator. Mao et al. [25] presented a novel fractional grey prediction model by substituting the fractional differential equations with their first-order forms. The model is highly accurate and can overcome the class ratio test restrictions of the conventional grey model (GM) (1,1). It demonstrated that the fractional differential simulation (FDS) can greatly improve the prediction ability of differential simulation [26]. Zeng and Li [27] developed a novel GM model originating from a dynamic background-value coefficient. Ma et al. [28] attempted to build a nonlinear grey Bernoulli multivariate prediction model. The GM (1, n) model was widely applied in various fields [29-34]. Yang and Xue [35] proposed a generalized fractional-order form of grey prediction model, which provides more freedom by using fractional derivatives. Meng et al. [36] introduced the residual sequence to improve the prediction accuracy of the fractional order grey model. The fractional order grey models were widely used with the improved GM (1,1) model [37,38]. These previous studies show that the prediction ability is strong when the fuzzy neural network (FNN) and fractional differential simulation (FDS) model are integrated. However, the adaptive hybrid model by combining FNN with FDS is still underexplored. In this study, an adaptive hybrid model is developed based on the fundamental theories of FNN and FDS that is then used to predict the EOR performance of N₂ huff-n-puff in a naturally fractured-cavity carbonate reservoir.

2. Research Background

The geological heterogeneity of naturally fractured-cavity reservoirs is extremely strong. It was proven that several types of reservoir spaces coexist, mainly including karst cavities, tectonic fractures, and dissolved pores. For typical fractured-cavity carbonate reservoirs that are widely distributed, there is a lack of efficient methods to obtain a high oil recovery during exploitation of these difficult-to-produce reserves due to great lateral and vertical heterogeneity. Figure 1a shows the lateral amplitude distribution retrieved from seismic data of a typical fractured-vuggy carbonate reservoir. The deeper the red color, the greater the amplitude, indicating a larger possibility to represent a cavity. Figure 1b displays the vertical amplitude distribution of a typical fractured-cavity body selected from Figure 1a. Figure 1c reflects the 3-D porosity field of the typical fractured-cavity body as shown in Figure 1b, where the deeper the red color, the higher value the porosity of cell grid in the 3-D geological model of the typical fractured-cavity body.



Figure 1. Geological characteristics of typical fractured-cavity reservoir. (**a**) lateral distribution of amplitude; (**b**) vertical distribution of amplitude; (**c**) 3-D geological model.

The production performance in the early stage depends heavily on formation energy. To keep oil production stable, water injection is usually selected to supply energy into reservoir space. However, the decline rate of oil production remains stubbornly high due to a poor understanding of reservoir heterogeneity and configuration patterns of multiple fractured-cavity units, leading to a great amount of oil remaining unexploited in the fractured-cavity reservoir. N₂ huff-n-puff is proven to be an efficient technique to further tap the potential of remaining oil. Figure 2 displays the underlying mechanisms of N₂ huff-n-puff in a fractured-cavity carbonate reservoir. It is found that three steps are necessary to carry out one cycle of N₂ huff-n-puff: gas injection, soaking, and production. When N₂ gas is injected into a typical fractured-cavity carbonate reservoir, driven by gravity segregation, it will gradually move to an upper position of the targeted cavity. The secondary gas cap will gradually move down the oil–water interface, and a large amount of crude oil will flow into the bottom hole of producing wells. The supply of formation energy by N₂ huff-n-puff can effectively inhibit the decline of oil production and rise of water cut.

Figure 3 displays the production performance of N_2 huff-n-puff for a producer in a typical fractured-cavity reservoir. It indicates that N_2 huff-n-puff achieves a better oil production rate even if the producer is shut down because of abrupt water-rising. However, the actual effect of increasing oil production by N_2 huff-n-puff differs greatly. It is difficult to achieve an adaptive prediction of EOR performance by N_2 huff-n-puff in a fractured-cavity carbonate reservoir. Many factors can affect the performance of enhanced oil recovery by N_2 huff-n-puff in karst reservoirs (e.g., remaining oil saturation, reservoir thickness, formation pressure, cumulative gas storage rate, daily oil production, natural fracture permeability, injection–production strategy, etc.). By taking all influential factors into account, the actual effect of N_2 huff-n-puff enhanced oil recovery in karst reservoirs can be accurately evaluated, but it is difficult to implement. Selecting certain controlling factors provides an alternative to solve this issue.



Figure 2. Mechanisms of N_2 huff-n-puff in karst reservoir (red: oil; blue: water; yellow: gas).



Figure 3. Actual production performance of N_2 huff-n-puff for a typical producer.

3. Adaptive FNN-FDS Hybrid Model

Here, the structure flowchart and calculation procedures of the proposed fuzzy neural network (FNN)-fractional differential simulation (FDS) hybrid model will be displayed after the relevant principles are described as follows.

3.1. Adaptive Neuro-Fuzzy Inference System

An artificial neural network is a promising tool due to its self-learning ability, but it lacks a good way to describe the reasoning function. Conversely, the fuzzy system shows good reasoning function with no self-adaptive ability. To resolve this issue, Jang et al (1993) initially developed an adaptive neuro-fuzzy inference system (ANFIS) [8] by integrating the self-learning mechanism of a neural network with the good reasoning ability of the fuzzy system. Moreover, the proposed fuzzy system is converted into an adaptive artificial neural network to carry out the self-learning process. The generalized schematic flowchart of ANFIS that includes five layers is shown in Figure 4. Both the first and the fourth nodes are self-adaptive, but the others are fixed. To make adaptive predictions of EOR performance by N_2 huff-n-puff in a fractured-cavity carbonate reservoir, the ANFIS with only two inputs is utilized.



Figure 4. Schematic architecture of the ANFIS model.

The adaptive network is a multilayer feedforward network in which nodes correspond to learning parameters. The significance of each layer will be introduced for an ANFIS model with n inputs [16,26].

Layer 1 is composed of the input variable membership function, which is selected to fuzzify the input signal. Layer 2 is used to release the regular strength, in which the input signals will be multiplied at the node. Layer 3 is established for normalization, and the fuzzy rule is described as follows:

$$O_i^3 = \overline{\omega}_i = \frac{\omega_i}{\omega_1 + \omega_2 + \dots + \omega_n}, \ i = 1, 2, \dots n$$
(1)

Each node in layer 4 is self-adaptive, and the output is expressed as

$$O_i^4 = \overline{\omega}_i f_i = \overline{\omega}_i (p_i x + q_i x + r_i), \ i = 1, 2, \dots n$$
⁽²⁾

where $\overline{\omega}_i$ is the output of node, and $\{p_i, q_i, r_i\}$ acts as post-piece parameter set.

Layer 5 denotes a fixed node, indicating the output of signals, which can be defined as a linear combination of the post-piece parameters:

$$O^{5} = \sum_{i=1}^{n} \overline{\omega}_{i} f = \sum_{i=1}^{n} ((\overline{\omega}_{i} x) p_{1} + (\overline{\omega}_{i} y) q_{1} + \overline{\omega}_{i} r_{1})$$
(3)

where O^5 denotes the prediction data of production by N₂ injection in a fractured-cavity carbonate reservoir.

3.2. Fractional Order Differential Simulation Model

Define the sequence $\mathbf{X}_1^{(0)}$ as the decision sequence and the sequence $\mathbf{X}_i^{(0)}$ as the control sequence of the grey system. The r-order accumulating generation operator of $\mathbf{X}^{(0)}$ is called *r*-AGO, ($r \in R^+$).

$$x^{(r)}(k) = \sum_{i=1}^{k} \frac{\Gamma(r+k-i)}{\Gamma(k-i+1)\Gamma(r)} x^{(0)}(i), k = 1, 2, \dots m$$
(4)

Within the continuous form of *r*-AGO sequences, the whiten equation of the grey system can be established as:

$$\frac{dx_1^{(r)}(t)}{dt} + ax_1^{(r)}(t) = \sum_{i=2}^n b_i x_i^{(r)}(t) + u$$
(5)

The widely used least squares GM (1, n) model is expressed as

$$\hat{\alpha} = \left(\mathbf{K}^T \mathbf{K}\right)^{-1} \mathbf{K}^T \Phi \tag{6}$$

The response function is in the following:

$$\hat{x}_{1}^{(r)}(k+1) = \alpha_{1}^{k} x_{1}^{(0)}(1) + \sum_{i=0}^{k-1} \alpha_{1}^{i} \left(\sum_{j=2}^{n} \alpha_{j} x_{j}^{(r)}(k+1-i) \right) + \frac{1-\alpha_{1}^{k}}{1-\alpha_{1}} \beta$$
(7)

After the series $\hat{x}_1^{(r)}(k)$ is obtained, the predicted series $\hat{x}^{(0)}(k+1)$ will be computed using the r-order inverse accumulating generation operator (*r*-IAGO), which takes the form of

$$\hat{x}_{1}^{(0)}(k+1) = \left(\hat{x}_{1}^{(r)}(k+1)\right)^{(-r)}$$
(8)

where $\hat{x}_1^{(0)}(k+1)$ represents the prediction result of increasing oil production by N₂ injection in a fractured-cavity carbonate reservoir.

3.3. Calculation of Enhanced Oil Recovery Ratio

The ratio of EOR ($\hat{\eta}$) by N₂ huff-n-puff can be calculated by integral of the deviation between the predicted oil production with and without N₂ huff-n-puff when the effect of production decline is considered. This takes the form of

$$\hat{\eta} = \frac{\sum_{i=1}^{m} \int_{t_1}^{t_2} (\hat{Q}_i - Q_i) dt}{R_0}$$
(9)

where R_0 is original oil in place; *m* is the well number; \hat{Q}_i and Q_i are predicted values of oil production rate with and without N₂ huff-n-puff, respectively; and t_1 and t_2 are the time for start and end of N₂ injection, respectively.

$$Q_i = \overline{Q}_i e^{-at} \tag{10}$$

where *a* is the decline rate of oil production, and \overline{Q}_i is the initial oil production rate.

3.4. Calculation Procedures of FNN-FDS Hybrid Model

According to principles of the adaptive FNN-FDS hybrid model, the structure flowchart is given in Figure 5. The calculation steps are summarized as follows:

Step 1: Convert raw training data into matrix form.

Step 2: Apply training data matrix to FNN model and FDS model, and evaluate the prediction accuracy.

Step 3: Evaluate the prediction accuracy of FNN model and FDS model, which is defined as P1 and P2, respectively. If the maximum value of P1 and P2 is lower than P0 where P0 is predefined as the converge criterion, detect the singular value of the raw data; otherwise, repeat the calculation of the FNN-FDS hybrid prediction.

Step 4: If P1 is higher than P2, apply prediction data matrix to FNN model, otherwise apply prediction data matrix to FDS model, and calculate the predicted increasing oil production rate of targeted producers by N₂ huff-n-puff;

Step 5: Determine the EOR ratio by N_2 huff-n-puff in fractured-cavity carbonate reservoir and evaluate the oil incremental effect.



Figure 5. The structure flowchart of the FNN-FDS hybrid model.

4. Results and Discussion

In this section, adaptive prediction of enhanced oil recovery by N_2 huff-n-puff in a fractured-cavity carbonate reservoir will be performed using the proposed FNN-FDS hybrid model. The performance appraisal of the predicted results and analysis will also be given.

4.1. Raw Data

The factors greatly affecting the degree of increased oil production by N₂ huff-n-puff in a fractured-cavity carbonate reservoir mainly include geological characteristics of reservoir body and various operation parameters of N₂ huff-n-puff. The most important geological characteristics consist of porosity, permeability, and well depth. The main operation parameters include cumulative gas injection, gas storage rate, and cycle of gas injection. There is good evidence that permeability strongly correlates with porosity in a typical fractured-cavity reservoir [39,40], thus permeability is enough to describe the effect of reservoir properties on increasing oil production by N₂ huff-n-puff. Cumulative gas storage can serve as an indicator to the amount of injected gas and gas storage rate. N₂ huff-n-puff is typically used to improve oil recovery of fractured-cavity carbonate reservoirs when water injection becomes invalid, thus cumulative water storage can greatly influence increasing oil production by this method. In this study, the principal component analysis [39,41] is applied to reduce the dimensionality of controlling parameters and to alleviate the dependency of different influential factors. Cumulative gas storage, cumulative water storage, permeability, and total well depth are selected as the main controlling factors of N_2 huff-n-puff in karst reservoirs, which easily originate from production history. Production data for all 22 producing wells were collected in a typical fractured-cavity carbonate reservoir. Table 1 displays the original data of the four controlling factors, in which 17 sets of data were utilized to train the FNN and FDS models and the other five sets of data were selected to validate the accuracy of the proposed FNN-FDS hybrid model for adaptive prediction of EOR performance by N₂ huff-n-puff.

Well No.	Annual Output (m ³)	Cumulative Gas Storage (10 ⁴ m ³)	Cumulative Water Storage (m ³)	Permeability (mD)	Well Depth (m)
LG01	6231	186	7361	11000	6800
LG02	2281	150	526	5000	6200
LG03	4062	100	2995	8000	6500
LG04	5033	120	2763	9500	6600
LG05	2556	200	1474	5500	6200
LG06	2437	80	740	5300	6200
LG07	6450	600	800	11000	6800
LG08	2086	1000	658	4800	6100
LG09	3929	200	800	7700	6400
LG10	2817	168	46	6000	6200
LG11	6530	600	800	12000	6800
LG12	3427	400	720	7000	6400
LG13	7340	100	4067	13000	7000
LG14	2218	100	636	5000	6200
LG15	2215	600	918	5000	6200
LG16	4725	150	3905	8500	6500
LG17	1986	260	3578	4500	6100
LG18	1045	200	2403	3100	6000
LG19	2935	180	942	6100	6300
LG20	1447	180	1907	3700	6000
LG21	3138	200	605	6500	6300
LG22	4825	100	3968	9000	6600

Table 1. Raw data of the four controlling factors to N₂ huff-n-puff.

4.2. Model Appraisal

The root-mean-square error [42] (RMSE) and mean absolute percentage error [43] (MAPE) are utilized in this study for performance appraisal of the FNN-FDS hybrid model.

RMSE is one of the most commonly used indicators to validate the accuracy of the predicted data, which takes the form of

RMSE =
$$\sqrt{\frac{1}{m} \sum_{i=1}^{m} (x_{i,p} - x_{i,e})^2}$$
 (11)

MAPE is used to evaluate the overall accuracy of the predicted values, described as

MAPE =
$$\frac{1}{m} \sum_{i=1}^{m} \left| \frac{x_{i,e} - x_{i,p}}{x_{i,e}} \right| \times 100(\%)$$
 (12)

where $x_{i,e}$ is the actual value and $x_{i,p}$ is the predicted value.

4.3. Adaptive Prediction and Discussion

Adaptive prediction of EOR performance by N₂ huff-n-puff in a typical fracturedcavity carbonate reservoir using the FNN-FDS hybrid model is given as follows:

Step 1: Standardize raw data and determine the initial matrix. X_x is the main controlling factor matrix for enhanced oil recovery by N₂ huff-n-puff in a fractured-cavity reservoir; X_y is the increased oil production by N₂ huff-n-puff; X is the initial matrix of raw data; X_{xp} and X_{yp} are the initial matrices for training; and X_{xv} and X_{yv} are the initial matrices for performance appraisal, respectively.

$$X_x = \begin{bmatrix} X_x^1 \\ X_x^2 \end{bmatrix}, X_y = \begin{bmatrix} X_y^1 \\ X_y^2 \end{bmatrix}, X = \begin{bmatrix} X^1 \\ X^2 \end{bmatrix}$$

where

$$X_x^1 = \begin{bmatrix} 186 & 7361 & 11000 & 6800 \\ 150 & 526 & 5000 & 6200 \\ 100 & 2995 & 8000 & 6500 \\ 120 & 2763 & 9500 & 6600 \\ 200 & 1474 & 5500 & 6200 \\ 80 & 740 & 5300 & 6200 \\ 600 & 800 & 11000 & 6800 \\ 1000 & 658 & 4800 & 6100 \\ 200 & 800 & 7700 & 6400 \\ 168 & 46 & 6000 & 6200 \\ 600 & 800 & 12000 & 6800 \end{bmatrix}, X_x^2 = \begin{bmatrix} 400 & 720 & 7000 & 6400 \\ 100 & 4067 & 13000 & 7000 \\ 600 & 918 & 5000 & 6200 \\ 150 & 9368 & 8500 & 6500 \\ 260 & 3578 & 4500 & 6100 \\ 200 & 605 & 6500 & 6300 \\ 100 & 3968 & 9000 & 6600 \end{bmatrix}^T$$

$$X_y^1 = \begin{bmatrix} 6231 & 2281 & 4062 & 5033 & 2556 & 2437 & 6450 & 2086 & 3929 & 2817 & 6530 \end{bmatrix}^T$$

$$X_y^2 = \begin{bmatrix} 3427 & 7340 & 2218 & 2215 & 4725 & 1986 & 1045 & 2935 & 1447 & 3138 & 4825 \end{bmatrix}^T$$

$$X_y^1 = \begin{bmatrix} 6231 & 186 & 7361 & 11000 & 6800 \\ 2281 & 150 & 526 & 5000 & 6200 \\ 4062 & 100 & 2995 & 8000 & 6500 \\ 5033 & 120 & 2763 & 9500 & 6600 \\ 2437 & 80 & 740 & 5300 & 6200 \\ 2438 & 1000 & 658 & 4800 & 6100 \\ 3929 & 200 & 800 & 7700 & 6400 \\ 235 & 180 & 942 & 6100 & 6300 \\ 1447 & 180 & 1907 & 3700$$

$$X_{xp} = \begin{bmatrix} X_{xp}^1 \\ X_{xp}^2 \end{bmatrix}, X_{yp} = \begin{bmatrix} X_{yp}^1 \\ X_{yp}^2 \end{bmatrix}$$

where

$$X_{xp}^{1} = \begin{bmatrix} 186 & 7361 & 11000 & 6800 \\ 150 & 526 & 5000 & 6200 \\ 100 & 2995 & 8000 & 6500 \\ 120 & 2763 & 9500 & 6600 \\ 200 & 1474 & 5500 & 6200 \\ 80 & 740 & 5300 & 6200 \\ 600 & 800 & 11000 & 6800 \\ 1000 & 658 & 4800 & 6100 \\ 200 & 800 & 7700 & 6400 \end{bmatrix}, X_{xp}^{2} = \begin{bmatrix} 168 & 46 & 6000 & 6200 \\ 600 & 800 & 12000 & 6800 \\ 100 & 4067 & 13000 & 7000 \\ 100 & 636 & 5000 & 6200 \\ 600 & 918 & 5000 & 6200 \\ 150 & 3905 & 8500 & 6500 \\ 260 & 3578 & 4500 & 6100 \\ 200 & 800 & 7700 & 6400 \end{bmatrix}, X_{yp}^{2} = \begin{bmatrix} 6231 & 2281 & 4062 & 5033 & 2556 & 2437 & 6450 & 2086 & 3929 \end{bmatrix}^{T}$$
$$X_{y}^{1} = \begin{bmatrix} 2817 & 6530 & 3427 & 7340 & 2218 & 2215 & 4725 & 1986 \end{bmatrix}^{T}$$
$$X_{xv} = \begin{bmatrix} 260 & 3578 & 4500 & 6100 \\ 200 & 2403 & 3100 & 6000 \\ 180 & 942 & 6100 & 6300 \\ 180 & 1907 & 3700 & 6000 \\ 200 & 605 & 6500 & 6300 \end{bmatrix}, X_{yv} = \begin{bmatrix} 1986 \\ 1045 \\ 2935 \\ 1447 \\ 3138 \end{bmatrix}$$

Step 2: Adaptive production prediction by N₂ huff-n-puff using the structure flowchart (shown in Figure 3) based on the initial matrix X, X_{xp} , X_{yp} , X_{xv} , X_{yv} .

Step 3: Obtain the predicted results of increasing oil production by N_2 huff-n-puff with the proposed FNN-FDS hybrid model. Figure 6 compares the predicted and raw data of increasing annual oil production by N_2 huff-n-puff. Figure 7 displays the absolute percentage error of predicted annual oil production.



Figure 6. Comparison of predicted and actual annual oil production by N2 huff-n-puff.



Figure 7. Absolute percentage error of annual oil production prediction.

Step 4: Calculate the predicted value of enhanced oil recovery by N₂ huff-n-puff in a typical fractured-cavity carbonate reservoir. According to the raw data of oilfield production, the annual output decline rate equals 15%. The geological reserve of the oilfield is 2×10^7 m³. The duration time of N₂ huff-n-puff is one year. Table 2 displays the annual oil production of the 22 producers predicted by taking the production decline rate of 15% into consideration. The ratio of enhanced oil recovery ($\hat{\eta}$) by N₂ huff-n-puff is ultimately computed. The predicted value of $\hat{\eta}$ is 0.1173%.

Well No.	Annual Production (m ³)	Well No.	Annual Production (m ³)
LG01	5121	LG12	2637
LG02	2031	LG13	6824
LG03	3526	LG14	1865
LG04	4542	LG15	1754
LG05	2019	LG16	3951
LG06	2028	LG17	1468
LG07	5965	LG18	896
LG08	1506	LG19	2087
LG09	3017	LG20	1065
LG10	2027	LG21	2614
LG11	5684	LG22	3687

Table 2. Predicted annual oil production for the 22 producers with decline rate of 15%.

When raw data are used for training, the RMSE and MAPE for the FNN-FDS hybrid model were found to be 144.33 and 2.67, respectively. When raw data are used for prediction, the RMSE and MAPE for the FNN-FDS hybrid model were found to be 107.40 and 4.78, respectively. It can be seen from the results of RMSE and MAPE that the prediction ability of the proposed FNN-FDS hybrid model is satisfactory, showing that the predicted EOR ratio by N_2 huff-n-puff in a fractured-cavity reservoir is credible.

5. Conclusions

Fuzzy neural network (FNN)–fractional differential simulation (FDS) hybrid model is proposed to make an adaptive prediction of enhanced oil recovery (EOR) performance by N_2 huff-n-puff in naturally fractured-cavity carbonate reservoirs.

The performance appraisal of N_2 huff-n-puff in a typical carbonate reservoir shows that the prediction ability of the FNN-FDS hybrid model is satisfactory, indicating that the proposed model is efficient for EOR prediction by N_2 huff-n-puff.

The proposed model can guide optimal design of development scheme when using N_2 huff-n-puff to tap more remaining oil in similar carbonate reservoirs.

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