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# Modulation and Control Technology for Generating Movable Super-Diffraction Optical Needle by Oblique Incidence

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Abstract: The movable super-diffraction optical needle (MSON) is a tightly focused beam like a "needle", which can realize vector scanning on the focusing plane. Not only does it have a long focal depth, but its resolution also exceeds the diffraction limit. The modulation and control technology required for generating MSON by oblique incidence is explored in this manuscript for the purpose of processing high-aspect-ratio, sub-wavelength structures. As the optical needle generated by traditional methods is static and sensitive to variation of the angle information of the incident beam, here we introduce a confocal scanning system by using a two-dimensional galvanometer system, a scan lens, and a tube lens to control the oblique incidence angle. The effects of the oblique incidence angle on the resolution, depth of focus, uniformity, and side lobes of the MSON were analyzed. Further, the voltage-controlled liquid crystal located between the scan lens and the 2D galvanometer system can be used to compensate for the additional phase difference caused by oblique incidence. The aspect ratio is defined as the ratio of depth of focus to resolution. By modulating and controlling the light field, the MSON with high aspect ratio (7.36), sub-diffractive beam size  $(0.42\lambda)$ , and long depth of focus  $(3.09\lambda)$  has been obtained with homogeneous intensity, and suppressed side lobes. High speed, high axial positioning tolerance, and high-resolution laser processing can also be achieved, which removes the restrictions presented by traditional laser processing technology, for which high resolution and long depth of focus cannot be achieved simultaneously.

Keywords: optical needle; resolution; depth of focus; high aspect ratio; movable

## 1. Introduction

High-aspect-ratio, sub-wavelength structures have a wide range of applications in major projects such as metasurfaces, X-ray diffraction spectroscopy devices, space particle capture, and deep-grain film imaging devices for space-to-ground observation [1,2]. Laser processing technologies, which are universal tools for manufacturing, have become one of the main methods of nano-processing due to their high precision [3]. To manufacture a high-aspect-ratio, sub-wavelength structure, the resolution and depth of focus (DOF) in laser processing technologies need to be improved simultaneously. Generally, in traditional laser processing technologies such as nanoimprint lithography, electron beam direct-writing lithography, multi-photon direct writing, etc. [4–6], resolution can be improved by increasing the numerical aperture (NA) of the lens, but this will cause rapid divergence along the focal point in the direction of beam propagation. Therefore, laser processing cannot be realized within a

certain depth range. Breaking through the physical limitations of long DOF and high resolution has always been a major scientific problem in super-diffraction laser processing.

However, an optical needle with high purity longitudinal polarization and homogeneous intensity along the optical axis can increase resolution while increasing the DOF. This has potential applications in optical manipulation and acceleration [7], optical trapping [7,8], material processing [9], super-resolution focus [10,11], and optical data storage [12], which has attracted great attention from scientists in this field. The traditional method of creating an optical needle is to use a high NA objective lens to tightly focus a cylindrical vector beam incident parallel to the optical axis [13]. In addition, to improve the DOF and resolution of the optical needle, many scientists have designed filters with different structures to modulate the incident beam. For instance, Wang et al. designed a phase filter composed of a 0,  $\pi$  ring phase structure. The phase filter was introduced to control the light field in the focal region by polarization and phase modulation [14]. According to the principle of multi-focus superposition, an amplitude filter based on Euler transformation, which was applied to modulate the amplitude and phase of the incident radial polarized Bessel-Gaussian beam, was proposed to generate the longitudinally polarized long focal depth structure [15]. Moreover, a high-purity longitudinal polarization field with extremely long depth of focus can be obtained by focusing the polarized beam using a simplified discrete complex pupil filter and a high NA lens [16]. All of the above methods improve the resolution or the DOF of the optical needle. However, the created optical needle is immovable, which is called a static optical needle. Traditional laser processing technologies usually use both mechanical scanning and vector scanning to increase processing speed [17], while the laser processing method based on a static optical needle can only use mechanical scanning. In addition, it has been found that the oblique incidence angle of the incident beam will reduce the DOF of the optical needle, so it is necessary to accurately control the angle of the incident beam, which is difficult for laser processing.

In this paper, we propose a modulation and control technology for generating movable super-diffraction optical needles by oblique incidence. The confocal scanning system consists of a two-dimensional (2D) galvanometer system, a scan lens, and a tube lens, which is used to achieve oblique incidence control instead of normal incidence. According to vector diffraction theory, we establish a mathematical and physical model for modulating and controlling the movable super-diffraction optical needle (MSON). We then simulate and analyze the effect of oblique incidence on the resolution, DOF, uniformity, and side lobes of the MSON. In addition, a voltage-controlled liquid crystal is used to compensate for the phase difference caused by oblique incidence. We compare and analyze the characteristics of the MSON obtained before and after phase compensation. By modulating and controlling the light field, we obtained a MSON with sub-diffractive beam size ( $0.42\lambda$ ), long DOF ( $3.09\lambda$ ), high aspect ratio (7.36), uniform intensity, and suppressed side lobes, which can resolve the scientific problem that DOF and resolution cannot be improved at the same time. In addition, the MSON can realize two-dimensional vector scanning on the focusing plane. Compared with the traditional method of generating static optical needles with normal incidence, a combination of vector scanning and mechanical scanning can be used in this oblique incidence method to increase processing speed.

#### 2. Principle and Model

A schematic diagram of the optical setup is shown in Figure 1. The radially polarized beam with a certain angle to the optical axis first passes through a confocal scanning system composed of a 2D galvanometer system, a scan lens, and a tube lens, then transmits through a binary phase pupil filter (BPPF), and is finally subsequently focused by a high NA lens. A radially polarized beam can be generated by modulating a linearly polarized laser beam with a polarization converter. The structure of the BPPF is shown in Figure 1c. A phase difference of  $\pi$  is created between the bright yellow and dark gray regions of the BPPF. The three-dimensional view of the 2D galvanometer system is shown in Figure 1b. The radially polarized beam can be deflected by the galvanometer mirrors in the x- and y-directions. For convenience, a box labeled liquid crystal is used to indicate a voltage-controlled

liquid crystal that can produce small phase differences. The axis center of the x-axis galvanometer is at the same level as the focus of the scan lens (*f*1), tube lens (*f*2), and the high NA lens (*f*3). Because any lateral motion would distort the linearity of the scan, the galvanometer mirror must be placed at image planes conjugate to the entrance pupil. When passing through *f*1, *f*2, and *f*3, the laser beams are parallel, but at different angles to the optical axis. Although the scanning optic is afocal, it acts as a focal system for the motion of the beam. At the field diaphragm, the angle between the laser beam and the optical axis is called the oblique incidence angle ( $\theta$ ).



**Figure 1.** (**a**) Schematic of the optical setup. The insets (**b**) and (**c**) are enlarged views of the 2D galvanometer system and the binary phase pupil filter, respectively.

In the process of the interaction between light and substance, the high NA lens tightly focuses the light field to achieve spatial light field modulation. The optical needle produced by tight focusing of the radially polarized incident beam is formed by the coherent superposition of various spatial spectral components in the focused space. According to the principle of interference, a BPPF is used to further modulate the light field to reduce the focal spot size or extend the DOF. According to the principle of confocal scanning, the angle of incident light can be controlled by a 2D galvanometer system. Although oblique incidence attenuates the DOF, the DOF can be elongated by compensating for the additional phase difference caused by oblique incidence. Next, its optical propagation characteristics will be further analyzed.

#### 3. Parameter Analysis and Theoretical Calculation

When the incident beam is perpendicular to the optical axis, the simplified schematic diagram from Figure 1 becomes that shown in Figure 2, where the radially polarized beam transmits through a BPPF and is subsequently focused by a high NA lens. According to Richards and Wolf's vector diffraction theory, the transverse and longitudinal electric fields near the focal region in Figure 2 can be written as Equation (1) and Equation (2), respectively.

$$E_r(r,z) = A \int_0^\alpha \cos^{1/2} \theta \sin(2\theta) l(\theta) T'(\theta) J_1(kr\sin\theta) e^{ikz\cos\theta} d\theta,$$
(1)

$$E_z(r,z) = 2iA \int_0^\alpha \cos^{1/2} \theta \sin^2 \theta l(\theta) T'(\theta) J_0(kr\sin\theta) e^{ikz\cos\theta} d\theta.$$
(2)



**Figure 2.** Schematic of focusing of a radially polarized beam with a binary phase pupil filter (BPPF) and high numerical aperture (NA) lens.

In Equations (1) and (2), *A* is the coefficient of power (*A* = 1), *k* is the wavenumber ( $k = 2\pi/\lambda$ ),  $J_0$  and  $J_1$  denote Bessel functions,  $l(\theta)$  describes the amplitude distribution of the incident beam, and  $\alpha$  is the maximum angle of the focus given by  $\arcsin(NA/n_0)$ , where *NA* is the numerical aperture. In this manuscript, *NA* is set to 0.95, the refractive index  $n_0 = 1$ , and the wavelength  $\lambda = 405 \text{ nm}$ .

The transmission function of the BPPF is  $T(\beta) = \exp[i\varphi(\beta)]$ , where  $\varphi(\beta)$  is the phase distribution corresponding to each ring. According to the principles of constructive and destructive interference, the simulated annealing algorithm [18,19] is used to optimize the filter structure. Using a five-ring BPPF, the angle  $\beta_i$  (i = 1~4) corresponds to the four radial positions  $r_i = (\sin \beta_i)/NA$ . For different ranges of the angle  $\beta$ ,  $\varphi(\beta) = 0$  or  $\varphi(\beta) = \pi$ . Therefore, the transmittance function can be expressed as

$$T(\beta) = \begin{cases} 1, & \text{for } 0 \le \beta < \beta_1, \ \beta_2 \le \beta < \beta_3, \ \beta_4 \le \beta < \alpha \\ -1, & \text{for } \beta_1 \le \beta < \beta_2, \ \beta_3 \le \beta < \beta_4 \end{cases}$$
(3)

Essentially, the BPPF modulates the optical field through phase difference. When the focused beam is incident parallel to the optical axis, the oblique incidence angle is 0°, and the optical path difference of the phase modulation is completely derived from the BPPF, as displayed in Figure 3a. In the case shown in Figure 1a, oblique incidence adds additional phase difference. To simplify the calculation, the oblique incidence of a radially polarized beam can be regarded as the normal incidence of a radially polarized beam, while the BPPF is placed at a certain angle to the optical axis, as shown in Figure 3b. In Figure 3, the wider step (*h*1) represents a phase of size  $\pi$ , and the narrower step (*h*2) represents a phase of size 0.



**Figure 3.** Microstructure diagrams of a BPPF placed (**a**) perpendicular and (**b**) oblique to the optical axis. IB: incident beam; EB: ejected beam.

When the BPPF is placed perpendicular to the optical axis, the optical path difference is

$$\Delta L_1 = h_1 n - (\Delta h n_0 + h_2 n) = \Delta h (n - n_0).$$
(4)

The corresponding phase difference is

$$\Delta \varphi_1 = \varphi(\theta) = \frac{2\pi}{\lambda} \Delta h(n - n_0), \tag{5}$$

where *n* is the refractive index of the BPPF with wavelength  $\lambda$ .

When the BPPF is placed obliquely, the optical path difference is

$$\Delta L_2 = (n_0 l_2 + \frac{nh_1}{\cos \theta_1}) - (n_0 l_1 + \frac{n_0 \Delta h}{\cos \theta} + \frac{nh_2}{\cos \theta_1}).$$
(6)

The angle between the BPPF and the optical axis is  $\theta$ , and the refraction angle is  $\theta_1$ . When  $\theta$  is small, the increased optical path of the incident beam ( $l_1$ ) is considered equal to the increased optical path of the ejected beam ( $l_2$ ). Based on the law of refraction ( $n_0 \sin \theta = n \sin \theta_1$ ),  $\Delta L_2$  can be simplified to

$$\Delta L_2 = \Delta h \left( \frac{n^2}{\sqrt{n^2 - n_0^2 \sin^2 \theta}} - \frac{n_0}{\cos \theta} \right). \tag{7}$$

The phase difference is

$$\Delta \varphi_2 = \frac{2\pi}{\lambda} \Delta h \left( \frac{n^2}{\sqrt{n^2 - n_0^2 \sin^2 \theta}} - \frac{n_0}{\cos \theta} \right).$$
(8)

Therefore, compared to a BPPF placed perpendicular to the optical axis, a BPPF placed obliquely adds an additional phase difference ( $\Delta \varphi = \Delta \varphi_2 - \Delta \varphi_1$ ):

$$\Delta \varphi = \frac{2\pi}{\lambda} \Delta h \left( \frac{n^2}{\sqrt{n^2 - n_0^2 \sin^2 \theta}} - \frac{n_0}{\sqrt{1 - \sin^2 \theta}} - n + n_0 \right). \tag{9}$$

As shown in Equation (9),  $\Delta \varphi$  is related to the oblique incident angle  $\theta$ , and the transmittance function can be written as

$$T'(\theta) = \exp[i(\varphi(\beta) + \Delta\varphi)]. \tag{10}$$

The optical field distribution near the focus under the condition of oblique incidence can be obtained by substituting Equation (10) into Equations (1) and (2).

#### 4. Simulations and Discussion

Based on the established theoretical model, the simulation was carried out using matlab software. Here, the influence of the oblique incidence angle on the characteristics of the MSON was analyzed. In addition, the voltage-controlled liquid crystal was selected for phase compensation of oblique incidence. By analyzing the characteristics of the MSON before and after compensation, a MSON with high aspect ratio that can move in the focal plane was obtained. Finally, the relationship between the moving distance of the MSON and the oblique incidence angle was established.

#### 4.1. The Influence of Oblique Incidence Angle on the Characteristics of MSON

For oblique incidence, the light intensity distributions in the *r*-*z* plane at oblique incidence angles of 0°, 10°, 15°, and 20° are illustrated in Figure 4a–d, respectively. Normally, the DOF of the MSON is measured by the axial length whose axial intensity is more than 80% of the maximum axial intensity, and the resolution is characterized by the maximum full width at half-maximum (FWHM) [20] of all longitudinal plane optical fields. Moreover, when the light intensity is more than 0.8 times the maximum light intensity, the MSON is considered to have a homogeneous intensity. The intensity distribution in the transverse plane with r = 0 (marked by a black dashed line in Figure 4a) is plotted in Figure 4e. For the longitudinal plane (marked by white dashed line in Figure 4a), intensity distribution at  $z = 0.7\lambda$  is plotted in Figure 4f. As expected, as the angle of oblique incidence increased, both the DOF and the uniformity of the MSON deteriorated. When the oblique incidence angle was 10°, the DOF and uniformity changed little. However, when the oblique incidence angle was 20°, the DOF was nearly attenuated by half compared with normal incidence. In addition, the resolution of the MSON remained the same as the oblique incident angle increased. However, the MSON had a tendency to focus to the left. This is because as the oblique incidence angle increases, the peak intensity on the longitudinal plane at  $z = -0.7\lambda$  remains almost constant, while the peak intensity of the longitudinal plane at  $z = 0.7\lambda$  decreases, especially when the oblique incidence angle is larger than 10°.

#### 4.2. Characteristics of MSON before and after Compensation

In order to solve the DOF attenuation problem caused by the oblique incidence in principle, a voltage-controlled liquid crystal located between the scan lens and the 2D galvanometer system can be used to compensate for the additional phase difference caused by oblique incidence. The characteristics of the MSON obtained before and after phase compensation using voltage-controlled liquid crystal are compared in Figure 5. As shown in Figure 5a, when the incidence angle  $\theta = 0^{\circ}$ ,  $10^{\circ}$ , or  $20^{\circ}$ , the DOF before compensation was  $3.09\lambda$ ,  $2.93\lambda$ , and  $1.50\lambda$ , respectively. It can be found from the simulation results that the attenuation of DOF in the range of  $10^{\circ}$  was rather small. By adding a voltage-controlled liquid crystal to compensate for the additional phase difference caused by oblique incidence, the MSON with a constant DOF ( $3.09\lambda$ ) in a specific angular range can be obtained. In addition, as shown in Figure 5b, the FWHM of the MSON remained unchanged at  $0.42\lambda$ . Optical focusing focal spot size is divided into sub-resolution ( $0.61\lambda$ /NA) and super-oscillation criterion ( $0.38\lambda$ /NA) [21]. In the area between the two criteria, while achieving super-diffraction-limited focusing, the effect of side lobes can be effectively suppressed. Therefore, the MSON not only achieves super-diffraction-limited focusing, but also effectively suppresses side lobes.

The aspect ratio of the MSON is measured by the ratio of DOF to resolution as shown in Equation (11) [22]. The aspect ratio of the MSON is as high as 7.36.

$$AR = DOF/FWHM \tag{11}$$



**Figure 4.** Creation of the movable super-diffraction optical needle (MSON) at different oblique incidence angles. Contours of  $|E|^2$  in the *r*-z plane when oblique incident angles are (**a**) 0°, (**b**) 10°, (**c**) 15°, and (**d**) 20°. (**e**) and (**f**) are the depth of focus (DOF) and full width at half-maximum (FWHM) of the MSON when the oblique incidence angles are (**a**) 0°, (**b**) 10°, (**c**) 15°, and (**d**) 20°. The intensity distribution at the longitudinal plane, as marked by the black dashed line in (**a**), is plotted in (**e**). The intensity distribution at the transverse plane, as marked by the white dashed line in (**a**), is plotted in (**f**).



**Figure 5.** (a) The depth of focus (DOF) of the movable super-diffraction optical needle (MSON) before and after phase compensation. The red curve denotes the DOF before compensation, and the purple dotted line denotes the DOF after compensation. (b) The full width at half-maximum (FWHM) of the MSON. The black line denotes the FWHM, the blue dashed line denotes the diffraction limit, and the green dashed line denotes the super-oscillation criterion of the lens.

#### 4.3. The Relationship between the Moving Distance of the MSON and the Oblique Incidence Angle

Apart from the characteristic analysis, the relationship between the position of the MSON and the angle of incidence should be further stressed. The simplified optical path diagram of the schematic diagram in Figure 1a is shown in Figure 6. In Figure 6, *f*1, *f*2, and *f*3 represent the object focal lengths of the scan lens, the tube lens, and the high NA lens, respectively. The distance from the reflected beam to the optical axis is *h*, and the angle between the reflected beam and the incident beam is  $\sigma$ . The axis center of the x-axis galvanometer is at the same level as the focus of the scan lens (*f*1), tube lens (*f*2),

and the high *NA* lens (*f*3). According to the geometric optical path shown in Figure 6, a mathematical model can be established. The relationship between the oblique incident angle ( $\theta$ ) and the deflection angle of the x-axis galvanometer ( $\gamma$ ) can be expressed as Equation (12), and the moving distance (h') of the MSON and the galvanometer deflection angle ( $\gamma$ ) satisfy Equation (13).

$$\tan \theta = \frac{f_1}{f_2' \tan(\sigma)} = \frac{f_1}{f_2 \tan(2\gamma)},\tag{12}$$

$$h' = f_3 \tan \theta = \frac{f_1 f_3}{f_2} \frac{1}{\tan(2\gamma)}.$$
(13)



Figure 6. The schematic of the geometric optical path.

The radius selected for the high NA lens was 13.2mm. The moving distances (h') of the MSON for different oblique incident angles ( $\theta$ ) can be calculated by Equation (13). The results are shown in Figure 7. Figure 7a shows that the moving distances (h') of the MSON and the oblique incident angle ( $\theta$ ) were non-linear. In contrast, as shown in Figure 7b, for the case where the oblique incidence angle was less than 10°, the moving distances of the MSON and the oblique incident angle were approximately linear. When the oblique incident angle was 10°,  $h' = 765.0176 \,\mu\text{m}$ . The 2D galvanometer system can make the oblique incidence angle change in the range of  $[-10^{\circ}, 10^{\circ}]$ . Therefore, the MSON can be arbitrarily moved in a 2D focusing plane with a size of  $[-765.0176 \,\mu\text{m}, 765.0176 \,\mu\text{m}]$ . This provides a strong basis for constituting small-scale vector scanning. Within the range  $[-765.0176 \,\mu\text{m}, 765.0176 \,\mu\text{m}]$ , by controlling the angle of oblique incidence, the MSON can move linearly on the two-dimensional focus plane to achieve vector scanning. When the range exceeds  $[-765.0176 \,\mu\text{m}, 765.0176 \,\mu\text{m}]$ , combined with mechanical scanning, the speed of laser processing can also be increased.



**Figure 7.** (**a**) Relationship between the moving distance of the movable super-diffraction optical needle (MSON) relative to the optical axis and the oblique incidence angle. (**b**) When the oblique incidence angle is less than 10°, the relationship between the moving distance of the MSON relative to the optical axis and the oblique incidence angle is shown.

#### 5. Conclusions

In summary, the galvanometer can control the oblique incidence angle of the incident beam. Through the establishment of mathematical and physical models, simulation analysis found that the DOF was attenuated with the increase of the oblique incidence angle, while the resolution remained unchanged, and the moving distance of the optical needle in the focal plane was proportional to the oblique incidence angle ( $\theta \leq 10^{\circ}$ ). For oblique incident focal depth attenuation problems, voltage-controlled liquid crystal can be used for phase compensation. Finally, we obtained a high-aspect-ratio (7.36) MSON with sub-diffraction beam size ( $0.42\lambda$ ), long depth of focus ( $3.09\lambda$ ), homogeneous intensity, and suppressed side lobes. Combined with mechanical scanning, applying the obtained MSON to laser processing can not only increase the speed of laser processing, but also solve the scientific problem that the resolution and DOF of traditional laser processing are mutually restricted. The sub-wavelength cross-section and large focusing depth of the MSON can achieve high resolution for nanolithography and high tolerance in axial positioning. Further study of the MSON experiment will be carried out, which will effectively improve the understanding of MSONs. In addition, it may be possible to further increase the resolution and DOF with more complex filters. The modulation and control technology for generating movable super-diffraction optical needles by oblique incidence can be widely used in optical micromachining and photolithography. In particular, it provides a new idea for preparation of high-aspect-ratio sub-wavelength structures. The optical needle we developed also has other important applications, including optical manipulation, particle acceleration, laser cutting, optical trapping, etc.

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