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A Method to Supervise the Effect on Railway Radio Transmission of Pulsed Disturbances Based on Joint Statistical Characteristics

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Received: 8 June 2020; Accepted: 9 July 2020; Published: 13 July 2020



Abstract: Radiocommunication systems between train and trackside (RSTT) carry essential information for train operations between on-board radio equipment and the related radio infrastructure located along the trackside, such as the train control, voice dispatching, command, operational information as well as the monitoring data. In a high-speed railway environment, the electromagnetic interference (EMI) has been a major threat to RSTT, and may result in critical security issues for railway transportation and even passengers. Given the complex scenario of the high-speed railway, it is significant to monitor the impact of disturbances in order to guarantee the quality of RSTT. On one hand, RSTT operate in a complex electromagnetic environment where transient disturbances coexist with permanent ones, and they both vary dramatically while the train is running. On the other hand, various radiocommunication technologies have been used for railway applications, featuring forward error-correction codes to resist EMI. Therefore, this paper puts forward a novel approach to evaluate the impact on radio transmission based on the joint statistical characteristics of time-varying EMI. This approach applies a dynamic effective signal-to-interference-plus-noise ratio mapping model to establish the relation between the block error performance of on-board radio and the joint statistical characteristics of disturbances with a mutual information-based metric. Simulations on radio transmission using Turbo coding and low-density-parity-check coding under various interferences indicate that this approach is effective to evaluate the degradation of transmission signal with forward error-correction coding due to EMI with different characteristics.

Keywords: electromagnetic disturbance; amplitude probability distribution; pulse duration distribution; radio transmission between train and trackside; interference effect

1. Introduction

Railway radiocommunication systems between train and trackside (RSTT) carry train control, voice dispatching, command, operational information as well as monitoring data between on-board radio equipment and the related radio infrastructure located along the trackside. In a high-speed railway (HSR) system, RSTT provide improved railway traffic control, passenger safety and improved security for train operations [1]. Therefore, RSTT are considered as “mission critical” for train operations in general and the management of train emergency situations [2]. For example, among the dispatching communication functionalities specified for railway, the Global System for Mobile Communications-Railway (GSM-R) [3] provides a railway emergency call service (REC) for drivers and signalers to alert all trains when part of route assigned to them may be occupied and collision risk occurs, so that they can immediately start lowering the speed or braking, depending on the operational

rules [4]. The GSM-R REC service has helped to save lives and mitigate the severe consequences of rail accident in many cases [5,6]. Therefore, the availability of the GSM-R frequencies is essential for safe and interoperable operations [7].

Unfortunately, railway infrastructures operate in a harsh and complex electromagnetic (EM) environment, where interferences are generated both inside and outside the HSR system. While supporting train operations, the electric traction system and high-power electrical appliances radiate strong electromagnetic emission under some unavoidable circumstances, such as the arcs generated during the separation of the pantograph and the contact wire [8]. Additionally, railway is distributed through the public domain and exposed to EM sources at various places, such as public radio transmission equipment [9]. In the HSR EM environment, the EM disturbances can hardly be eliminated from the source, nor be prevented through the coupling path. Thus, the on-board RSTT devices are extremely vulnerable to the surrounding EM disturbances, which may cause transmission errors and even lead to critical communication failures [10]. The communication failures directly cause the operational consequences of the rail network, such as jammed traffic and major delays, which may further result in bad economic and commercial effect [6] and even potential threat to the safety of passengers [11]. The degradation of communication availability or quality due to interferences is not acceptable [12]. Therefore, in order to guarantee the reliability of communication services, the impact of EM disturbances on RSTT should be monitored and supervised.

Since the degradation of RSTT caused by different types of interferences is quite different, it is essential to consider the variety of disturbances in the HSR system. There have been several methodologies put forward to monitor the interference effect on RSTT based on the different measuring methods of received disturbances, such as classification based on the time-domain waveform [13], simulation and calculation based on the amplitude probability distribution (APD) detector [14] and the instantaneous frequency histogram [15]. Among these measuring methods, APD reflects the time-domain statistics of EMI and it can capture the dynamic behavior of a time-varying EMI with the measuring apparatus specified in the standards [16]. Besides, as a standard emission limit for EMI sources [17], APD is effective to analyze the effect of interferences. Therefore, statistics stand out as the suitable measuring methodology to characterize the disturbances in the complex HSR environment and to analyze the impact on RSTT.

Previous research has proved that the statistics of EMI in the time-domain are directly related to the error performance of digital radiocommunication systems with different modulation and coding schemes (MCSs). Some of them has focused on the interfered digital modulation signals, and the maximum bit error probability of the radio receiver was derived based on the APD of arbitrary interference [18–20], without consideration of the forward error correction (FEC) coding gain. As the coding gain is closely related to the signal-to-interference-plus-noise ratio (SINR) of a code block, which is determined by both the amplitude and duration of a burst, the impact on RSTT with FEC is much more complex than digital modulation signals. Since APD cannot provide information on the time patterns of a disturbance, the evaluation is usually limited to particular circumstances. For example, a method that maps the coding gain to the impulsiveness correction factor (ICF) was proposed to evaluate the performance degradation [21–23]. However, this method is only effective in the case of impulsive noise and requires prior simulation related to the statistics of EMI. As for the scenario of HSR environment where transient and permanent disturbances both exist, the acquisition of ICF would take lots of time-consuming simulation work and may cause a large error due to the various statistics of disturbances, so it can not be used to give a real-time evaluation of RSTT performance.

In this paper, a novel approach is proposed to evaluate the impact on RSTT of the complex interferences based on the time-domain statistics. Since the disturbances are generally regarded as pulses, the pulse duration and amplitude are both major factors that influence the performance of radio services. Therefore, we use the pulse duration distribution (PDD) and APD jointly to characterize EMI, in order to analyze the system performance in a pulsed noise environment. Furthermore, a dynamic effective SINR mapping model is proposed to establish the relation between the block error performance

of on-board radio and the joint statistical characteristics of disturbances with a mutual information (MI)—based metric.

This paper is organized as follows. In Section 2, we propose the methodology to supervise the interference effect of RSTT, and a general dynamic MI-effective SINR mapping (MI-ESM) model is proposed based on the statistical characteristics of pulsed disturbances. Then, in Section 3, a MI-based metric is analyzed to indicate the interference impact on encoded transmission under time-varying disturbances. Furthermore, the impact on RSTT by different disturbances is analyzed based on the APD and PDD in Section 4. The evaluation result is verified by the simulation in Section 5. Section 6 concludes the paper.

2. Problem Formulation

In this section, we propose a novel method to detect and supervise the degradation of RSTT caused by the EMI. As the on-site interferences are regarded as a series of pulses, they can be characterized by the statistics of amplitude and width. In this situation, the relation between the impact on RSTT and the interference measurement is established through a MI-based method.

2.1. Supervising Methodology of RSTT

To supervise the interference impact on RSTT during the train operations, an on-board supervision methodology for communication quality is proposed, as illustrated in Figure 1. In this method, the disturbances at the input of the receiving antenna ought to be monitored through a coupler, independent of the existing radio receiver. Thus, the performance degradation of the RSTT transmission can be estimated based on the measurement of disturbances. Furthermore, in comparison with the specified requirements in related regulations, it could be determined whether the disturbance is intense enough to threaten the reliability of RSTT [13]. By this means, the operator could get knowledge of the real-time quality of radio transmission, and even receive an early warning before the communication blackout occurs through the driver-machine interface (DMI). The question then becomes: how to establish the relation between the measurement of EMI and real-time performance degradation of interfered radio transmission.

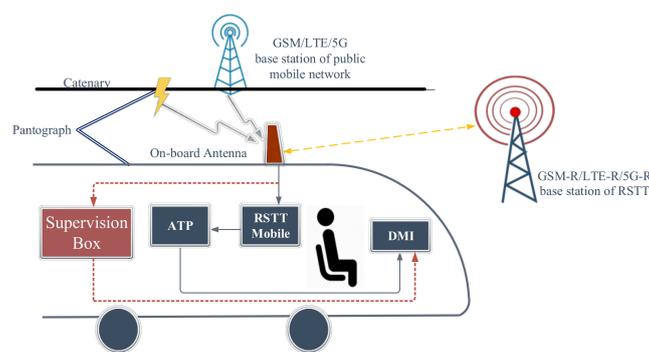


Figure 1. Illustration of the radiocommunication systems between train and trackside (RSTT) monitoring scheme at the on-board train. ATP: automatic train protection; DMI: driver-machine interface; GSM: Global System for Mobile Communications; LTE: long-term evolution.

Practically, RSTT are responsible for wireless data and voice communication between the train and the station for different railway applications. As stringent requirements for reliability, availability, safety and security are various for different train operations, numerous radiocommunication technologies have been used for railway operational applications and various MCSs have been adopted. For instance, as for dispatching, train control and other operational safety-related and efficiency needs of railway transportation systems, RSTT usually takes the form of dedicated mobile radio systems, such as GSM-R and Long-Term Evolution-Railway (LTE-R). Moreover, the technologies used for train-positioning

applications are based on radar and short-range radio, while the wireless local area network (WLAN) is used for train remote and surveillance applications [1].

In the complex HSR environment, RSTT suffer from disturbances with diverse statistical characteristics. On board moving trains, the radio receiver is mainly interfered with by transient disturbances occurring between the catenary and the pantograph, as well as permanent disturbances coming from the public mobile network base stations [7], as shown in Figure 1. On-site measurements of typical EMI in the GSM-R frequency band have been performed at the output port of a GSM-R antenna, and the results are shown in Figure 2. The pantograph arcing disturbance, shown in Figure 2a (with data from [24]), is the most typical interference generated in the HSR system. It has a wide frequency range up to several GHz, covering most working bands of the RSTT (with data from [25]). Besides, the on-board antenna of some RSTT network, like GSM-R and LTE-R, is usually fixed on the roof of the train close to the catenary, which makes it prone to emission from the sliding contact between the pantograph and the catenary. In addition, the signal from the public base station near the railroad is a critical external disturbance when it uses the adjacent frequency band of the railway radio service, as shown in Figure 2b [26]. This usually happens when the train is operating in the vicinity of a city, where the number of base stations and users of public mobile network significantly increases. Generally, both transient and permanent disturbances can be modeled as a series of pulses with a repeated cycle T_p , pulse amplitude A_i and pulse width W_i in the time domain, expressed as

$$n(t) = n_w(t) + \sum_{i=0}^{\infty} A_i p\left(\frac{t - iT_p}{W_i}\right) \tag{1}$$

where $n_w(t)$ refers to the background additive white Gaussian noise (AWGN), and $p(t)$ is the unit rectangular pulse function that refers to the single burst. As in (1), both impulsive and non-impulsive disturbances can be characterized by the statistics of pulse amplitude and width. Therefore, statistical parameters APD and PDD are jointly used to describe and characterize the interferences within the operating frequency bands of RSTT.

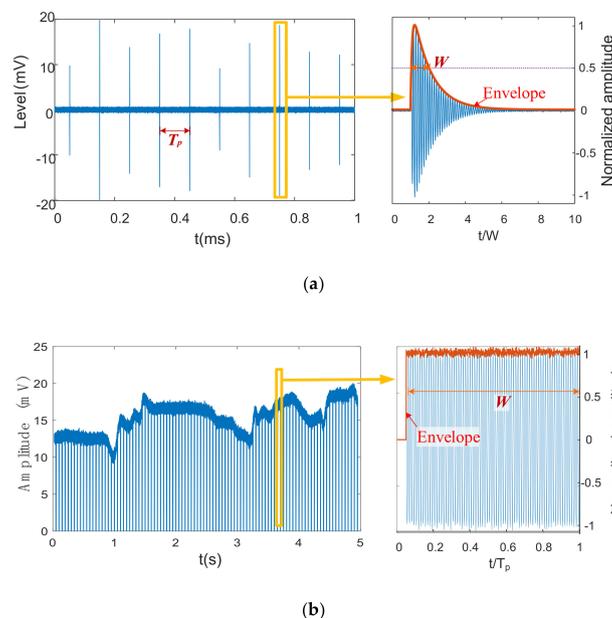


Figure 2. Example of the on-site measurement of disturbances in the Global System for Mobile Communications-Railway (GSM-R) band in the time-domain, (a) the pantograph arcing emission disturbance with data from [24] and (b) the interference from the GSM signal in the adjacent channel with data from [26].

Generally, the interference effect on RSTT depends both on the MCS of the transmitted signal and the statistical characteristics of the received disturbance. Considering the diversity of disturbances as well as RSTT signals, especially with the coding gain of FEC codes, the impact on radio transmission differs widely. Therefore, a universal method is required to evaluate the real-time transmission quality in such a complex situation.

2.2. MI-Based Method to Evaluate the Impact on RSTT of Time-Varying Interference

For the RSTT, reliability is among the most significant quality indicators closely related to train operation, and many security measures are considered based on the assumption of transmission error [1]. Thus, the block error rate (BLER) is taken as the criterion to indicate the effect of the pulsed disturbing noise on the RSTT using FEC codes. Therefore, to evaluate the impact on RSTT with different MCSs, the BLER of the on-board receiver should be achieved instantly based on the real-time statistical measurement of complex disturbances. As the coding gain of radio transmission in a stable fading channel is usually implemented by the MI-ESM algorithm [27], the MI metric is quite an effective channel quality indicator (CQI) to map the interference properties to the BLER performance. However, in the HSR environment, due to the fast movement of trains and the impulsive nature of EM disturbance sources, the RSTT performance changes in accordance with the dynamic interference, and it is almost impossible to obtain the corresponding BLER with a variable MI metric. As a result, an equivalent CQI is required for the time-varying EMI, through which the transmission quality can be derived.

Therefore, a dynamic quality model is proposed to achieve the MI-based CQI of transmission under time-varying disturbances, as illustrated in Figure 3. Firstly, the performance metric of every single code block is obtained by information mapping, based on the statistical characteristics of EMI. It is important to note that the APD and PDD of disturbance $n(t)$ should be measured using the equivalent bandwidth of the railway wireless service to be monitored [17]. According to MI-ESM algorithm, a received bit information rate (RBIR) is defined as the CQI to indicate the transmission quality. Then, a novel metric, long-term effective RBIR (RBIR_L), is put forward to reflect the general transmission performance in the presence of the dynamic disturbance. To combine the RBIR of each block in time-varying situations, RBIR_L is achieved by the weighted sum of the RBIR series. Therefore, the RBIR_L is the equivalent CQI of RBIR in a stable channel. Since RBIR_L can be mapped to the average BLER (BLER_{ave}) through the look-up table under the AWGN channel, the quality of the radio transmission is thus evaluated by the RBIR_L value.

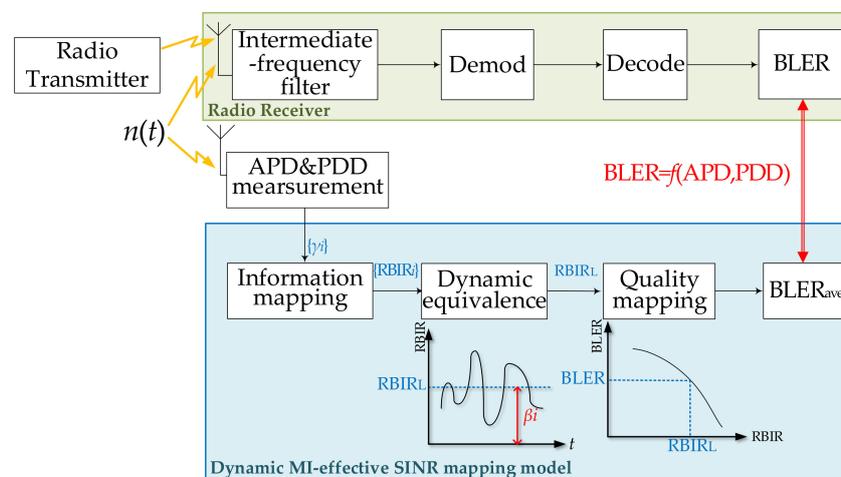


Figure 3. Illustration of the quality model under time-varying disturbance. BLER: block error rate; PDD: pulse duration distribution; RBIR: received bit information rate.

3. Information Mapping of Encoded Radio Transmission under Time-Varying Disturbance

In this section, an MI-based CQI is obtained to evaluate the impact on RSTT based on the joint statistical characteristics of disturbances. We first map the statistics of the disturbances during a single code block to RBIR, which indicates the quality of digital transmission using the FEC codes. Furthermore, due to the presence of dynamic EMI in the HSR environment, a method based on nonlinear optimization is proposed to obtain the equivalent metric $RBIR_L$ from a series of RBIR values.

3.1. Information Mapping Based on MI-ESM

Assuming that an information stream is encoded by some FEC codes into blocks of length Q symbols. Given the finite-alphabet transmitted constellation $\mathbb{Q} = \{q_i\} (i = 1, 2, \dots, M)$, the symbols of \mathbb{Q} are chosen according to a uniform probability distribution. To evaluate the interference effect on a single code block, the mutual information-based quality model is shown in Figure 4.

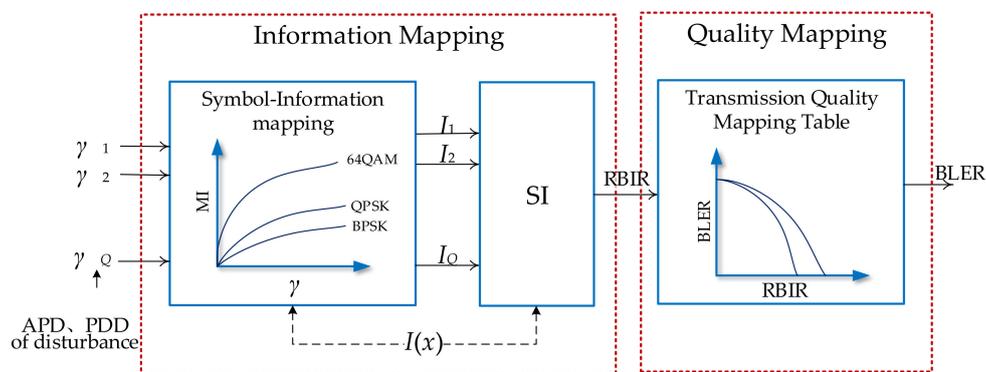


Figure 4. Illustration of an MI-based quality model. SI: symbol mutual information.

For RSTT, each symbol of the received signal can be expressed as

$$y = hx + n \tag{2}$$

where h is the channel gain, x refers to the transmitted signal, and n refers to the stochastic disturbance in the HSR environment. The symbol mutual information (SI) of each symbol is defined as

$$SI = I(X; Y) = \sum_i \int p(y|q_i) P(q_i) \log_2 \frac{p(y|q_i)}{p(y)} dy \tag{3}$$

where q_i represents the i -th ($i = 1, 2, \dots, M$) symbol in the transmitted constellation \mathbb{Q} .

To calculate the SI of a transmitted symbol, the corresponding SINR of this symbol should be determined in the first place. For modern FEC codes combined with interleaving technology, like turbo codes and low-density-parity-check (LDPC) codes, it is typically reasonable to assume a uniform distribution of the errors within a code block [28]. In order to deal with the problem of interleaved codes in a non-Gaussian channel, the block-fading channel model [29,30] is adopted. The block-fading channel represents a memoryless channel with random channel gain or random interference that is constant for a block of symbols, and then changes to a new independent value from a block to another [31]. That means, the SINR of each symbol in this block remains the same despite the burst noise. Therefore, the effective symbol SINR of the received symbol q_i is:

$$\gamma_i = \frac{|q_i|^2}{\sigma_w^2 + \sigma_A^2} \tag{4}$$

where σ_w and σ_A refer to the standard deviation of AWGN and the pulsed interference, respectively. Since the background AWGN is relatively weak compared to the pulses, the effective noise power of this symbol can be estimated by the average power of noise during one code block:

$$\sigma_e^2 = \sigma_w^2 + \sigma_A^2 \approx \int_0^\infty n^2 \cdot dAPD_n(n) \tag{5}$$

where n is limited to the noise within a single code block length. To simplify the calculation, the signal information when transmitting symbol q_i is approximate as [32]

$$SI_i(\sigma_e, m) = -\log_2 \frac{1}{M} \sum_{j=1}^M \exp\left(-\frac{d_{ij}^2 / \sigma_e^2}{3 - \exp(-d_{ij}^2 / (4\sigma_e^2))}\right) \tag{6}$$

where m is the number of information bits that compose the i -th symbol, and d_{ij} denotes the Euclidean measure between the i -th and j -th signal points in the constellation \mathbb{Q} .

Furthermore, $RBIR$ is computed from the SI value of symbols comprising a code block [33], which is obtained from the $SINR$ γ_k during one block. Thus, $RBIR$ is given as [34]

$$RBIR = \frac{\sum_{k=1}^Q SI(\gamma_k)}{\sum_{k=1}^Q m_k} = \frac{E[SI_k]}{E[m_k]} \tag{7}$$

where SI_k is the mutual information of the k -th ($k = 1, 2, \dots, Q$) transmitted symbol in the block.

3.2. Long-Term Coded RBIR under Time-Varying Disturbance Based on Nonlinear Optimization

Assuming the number of code blocks affected during the interference is N_{BL} and $RBIR$ -to- $BLER$ mapping in AWGN channel is $f_{R2B}(RBIR)$, the average $BLER$ of these N_{BL} blocks is denoted as $BLER_{ave} = \frac{\sum_{i=1}^{N_{BL}} f_{R2B}(RBIR_i)}{N_{BL}}$. To guarantee the validity of dynamic equivalence, $RBIR_L$ is defined as the inverse mapping of $BLER_{ave}$ in the AWGN channel, expressed as

$$RBIR_L \equiv f_{R2B}^{-1}(BLER_{ave}) \tag{8}$$

Given the $RBIR$ series of each code blocks under the disturbance, i.e., $\{RBIR_i\}$ ($i = 1, 2, \dots, N_{BL}$), the $RBIR_L$ of the radio receiver should be obtained by

$$RBIR_L = \frac{1}{N_{BL}} \sum_{i=1}^{N_{BL}} \beta_i RBIR_i \tag{9}$$

where $\{\beta_i\}$ ($i = 1, 2, \dots, N_{BL}$) is the weighting coefficient of the i -th $RBIR$. Therefore, the major problem is to find a proper parameter $\{\beta_i\}$ that could map the $RBIR$ of successive blocks to a long-term equivalent metric $RBIR_L$.

As stated in (8), the $RBIR_L$ is closely related to $f_{R2B}(RBIR)$. Generally, it can be approximated as a parametric function related to the encoding parameters such as the block size and coding rate (BCR) [32], expressed as

$$BLER = f_{R2B}(RBIR) = 0.5 \operatorname{erfc}\left(\frac{RBIR - b_{BCR}}{\sqrt{2} c_{cod} c_{BCR}}\right) \tag{10}$$

where $erfc(x)$ stands for the Gaussian complementary error function. The parameters b_{BCR} and c_{BCR} mainly depend on the code rate and block size, respectively, while the adjusting factor c_{cod} denotes the practical coding loss from the Shannon limit determined by the type of channel codes [27]. Due to the nonlinearity of $erfc(x)$, it is appropriate to apply the optimally nonlinear weighting method [35] so as to achieve the coefficients $\{\beta_i\}$. Intuitively, code blocks with different RBIR make a different contribution to $BLER_{ave}$, so β_i cannot have a linear relation with $BLER$. Therefore, to specify the relation between $RBIR$ and β_i , a parametric function $g(f_{R2B}(RBIR), t)$ is brought in to describe the contribution of the i -th block, where the argument t is the key factor that determines the degree of nonlinear. In this problem, function g is defined as

$$g = (f_{R2B}(RBIR), t)^t = f_{R2B}^t, t \in [0, \infty) \tag{11}$$

The function g is illustrated in Figure 5. As is shown, in the case of $t = 1$, β is in proportion to $f_{R2B}(RBIR)$, just referring to the linear relation. As for $t > 1$, the data block with the worse error performance has a higher weight, and vice versa. In fact, t is mainly dependent on the function $f_{R2B}(RBIR)$ other than the value of $RBIR$ [35].

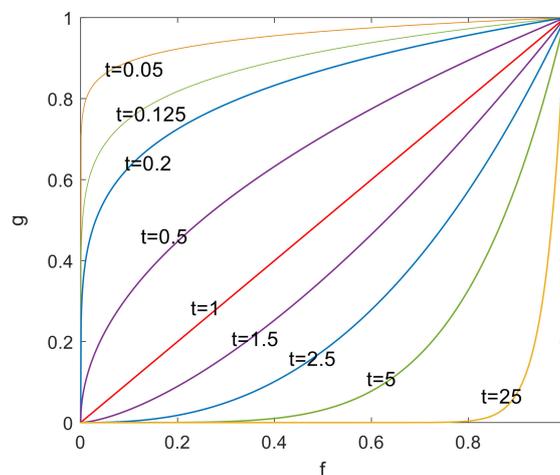


Figure 5. Illustration of the nonlinear weighting function $g = f_{R2B}^t$.

Therefore, the weighting coefficient β_i is in the form of:

$$\beta_i = \frac{g_i}{\sum_{k=1}^{N_{BL}} g_k} = \frac{f_{R2B}^t(RBIR_i)}{\sum_{k=1}^{N_{BL}} f_{R2B}^t(RBIR_k)} \tag{12}$$

The error between the estimated $BLER$ from the $RBIR_L$ and the exact $BLER_{ave}$ is expressed as $e = BLER_{ave} - f_{R2B}(RBIR_L)$. Based on MSE (minimum squared error) principle, $\{\beta_i\}$ is determine by

$$\beta_i = \arg \min_{t \in [0, \infty)} e^2 = \arg \min_{t \in [0, \infty)} \left[\sum_{i=1}^{N_{BL}} \frac{f_{R2B}(RBIR_i)}{N_{BL}} - f_{R2B} \left(\sum_{i=1}^{N_{BL}} \frac{f_{R2B}^t(RBIR_i) RBIR_i}{N_{BL} \sum_{k=1}^{N_{BL}} f_{R2B}^t(RBIR_k)} \right) \right]^2 \tag{13}$$

(13) reaches the optimal solution when $de^2/dt = 0$. It is very difficult to get the accurate analytical solution of t in consideration of $erfc(x)$, so we turned to approximate the numeric results instead.

Assuming that $f_{R2B}(x) = 0.5erfc(x)$, Figure 6 shows the value of the $BLER$ MSE as the variation of t , when $\{RBIR_i\}$ obey different distributions. It indicates that $t = 0.26$ – 0.28 when the squared error reaches the minimum, irrelevant with the number of blocks. Therefore, we specify $t = 0.27$ and the approving result is achieved.

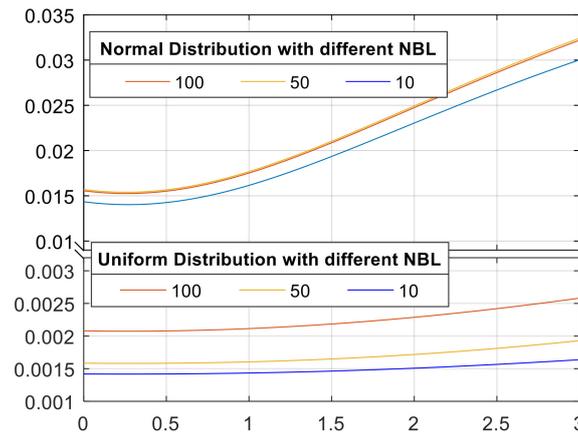


Figure 6. Squared error of the BLER with t in the different distributions of the RBIR.

Consequently, by substituting $t = 0.27$ into (12), the average long-term coded $RBIR_L$ is expressed as

$$RBIR_L = \frac{\sum_{i=1}^{N_{BL}} RBIR_i \left[\operatorname{erfc} \left(\frac{RBIR_i - b_{BCR}}{\sqrt{2} c_{cod} c_{BCR}} \right) \right]^{0.27}}{\sum_{i=1}^{N_{BL}} \left[\operatorname{erfc} \left(\frac{RBIR_i - b_{BCR}}{\sqrt{2} c_{cod} c_{BCR}} \right) \right]^{0.27}} \quad (14)$$

4. Impact on Encoded RSTT under Pulsed Disturbances in HSR Environment

In this section, the impact of pulsed disturbances on the encoded railway radio transmission is analyzed. Each $RBIR(\sigma_e)$ value of the received signal and its corresponding probability is analyzed, based on the statistical characteristics of disturbances, and the $RBIR_L$ is obtained according to (14). Thus, the BLER of the on-board receiver is then achieved as a metric of radio transmission performance through the $RBIR_L$.

As for the pulsed disturbances affecting the RSTT, the width mainly depends on the time-domain property of the sources, while the amplitude is also influenced by the coupling path. As a result, the amplitude is usually arbitrarily distributed without specific rules, and the width is discretely distributed. Therefore, the bursts could be grouped according to the pulse width $\{W_i\} (i = 0, 1, \dots, N_W)$, where $W_i = 0$ refers to the AWGN, and the amplitude of pulses in each group is arbitrarily distributed. Given the time allowance θ , the probability of each burst set whose pulse width $W \in [W_i - \theta, W_i + \theta]$ is:

$$p_i = \Pr(W_i - \theta < W < W_i + \theta) = \int_0^\infty \int_{W_i - \theta}^{W_i + \theta} dPDD(r, \tau) dAPD(r) \quad (15)$$

and the corresponding APD of each burst set is:

$$APD_{W_i}(r) = \frac{\int_r^\infty \int_{W_i - \theta}^{W_i + \theta} dPDD(r, \tau) dAPD(r)}{\int_0^\infty \int_{W_i - \theta}^{W_i + \theta} dPDD(r, \tau) dAPD(r)} \quad (16)$$

Since the sum of the interference power in one code block determines the actual transmission error, and the relative position of burst hardly affects the error-correcting capability of the FEC encoding [36], the pulse length and amplitude in every code block under $n(t)$ should be analyzed to obtain the RBIR value. As for the RBIR of blocks containing pulsed interference, the number, the width and the amplitude of the bursts in one block are crucial factors. To distinguish the situation where affected blocks containing a different number of bursts, the relation between T_p and code block length Q should be taken into account. Thus, the calculation of $RBIR_L$ is discussed in the following three cases.

1. Case $T_p \approx Q$

As shown in Figure 7, each code block contains almost one burst, and the ratio of the block that contains a burst with the pulse width W_i is:

$$\alpha_i = \begin{cases} \frac{p_i}{1-p_0} & , i = 1, 2, \dots, N_W \\ 0 & , i = 0 \end{cases} \tag{17}$$

the effective noise of blocks which contain a burst with a pulse width W_i and amplitude r is:

$$\sigma_e(W_i, r) = \sqrt{\frac{Q - W_i}{Q} \int_0^\infty r^2 \cdot dAPD_{W_0}(r) + \frac{W_i}{Q} r^2} \tag{18}$$

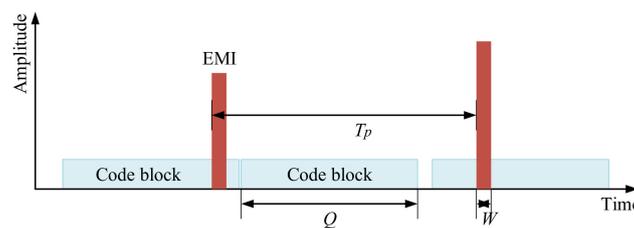


Figure 7. Illustration of the case that the repeated cycle T_p is nearly equal to the length of the code block Q . EMI: electromagnetic interference.

2. Case $T_p \gg Q$

As shown in Figure 8, there is a chance that some blocks are not influenced by the pulses, and their probability is α_0 , with the noise power to be $\sigma_0^2 = \int_0^\infty r^2 \cdot dAPD_{W_0}(r)$. The other code blocks contain only one burst, so the ratio of the blocks that contain a burst with width W_i is α_i , expressed as

$$\alpha_i = \begin{cases} \frac{Q p_i}{T_p (1-p_0)} & , i = 1, 2, \dots, N_W \\ 1 - \frac{Q}{T_p} & , i = 0 \end{cases} \tag{19}$$

and the corresponding effective value of noise is the same with (18).

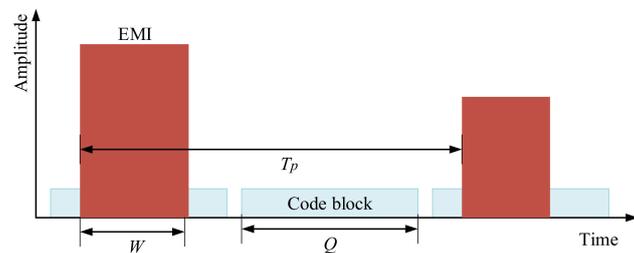


Figure 8. Illustration of the case that the repeated cycle T_p is much larger than the length of code block Q .

3. Case $T_p \ll Q$

As shown in Figure 9, the number of bursts in one code block is almost $K = Q/T_p$, where x denotes the smallest integer greater than or equal to x . It is assumed that the width and amplitude of bursts in the one block is the same. Therefore, the ratio of the blocks that contain bursts with the pulse

width W_i is the same with (19), and the effective noise of the blocks that contain a burst with a pulse width W_i and an amplitude r is:

$$\sigma_e(KW_i, r) = \sqrt{\frac{Q - KW_i}{Q} \int_0^\infty r^2 \cdot dAPD_{W_0}(r) + \frac{KW_i}{Q} r^2} \tag{20}$$

Generally, the total RBIR_L during $n(t)$ is expressed as

$$RBIR_L = \frac{\sum_{i=0}^{N_W} \alpha_i \int_r RBIR(\sigma_e(W_i, r)) \left[\operatorname{erfc} \left(\frac{RBIR(\sigma_e(W_i, r)) - b_{BCR}}{\sqrt{2} c_{BCR} c_{cod}} \right) \right]^{0.27} dAPD_{W_i}(r)}{\sum_{i=1}^{N_W} \alpha_i \int_r \left[\operatorname{erfc} \left(\frac{RBIR(\sigma_e(W_i, r)) - b_{BCR}}{\sqrt{2} c_{BCR} c_{cod}} \right) \right]^{0.27} dAPD_{W_i}(r)} \tag{21}$$

where c_{cod} , b_{BCR} and c_{BCR} are decided by the coding scheme. In this way, the $BLER_{ave}$ during the disturbance $n(t)$ is obtained by (10).

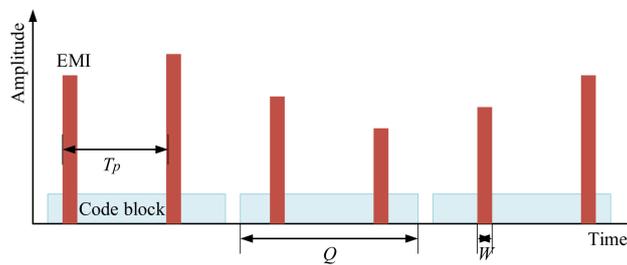


Figure 9. Illustration of the case that the repeated cycle T_p is much smaller than the length of the code block Q .

5. Simulation and Discussion

In this section, the hardware-in-the-loop simulation is used to verify the proposed method to evaluate the interference effect of the pulsed disturbances on RSTT. During this process, we assume that the intermediate-frequency filter of the APD measurement is the same as that of a radio receiver, and the channel symbols of one coding block are modulated in the same way.

The test bench employed in this simulation is presented in Figure 10, aiming to test the interference effect of RSTT in a high-speed railway environment.

- The radio transmission is established in the MATLAB (MathWorks, Natick, Massachusetts, USA, version R2016b) simulation platform of the computer, as well as the performance evaluation based on statistics;
- The EM disturbance is generated by the National Instruments (NI) NI-5793 radiofrequency transmitter (National Instruments, Austin, Texas, USA) adapter module, which can generate arbitrary waveform;
- The EMI receiver is built on NI FlexRIO architectures, composed of PXIe-1082 chassis, NI 5792 radiofrequency receiver adapter module, PXIe-7966R FPGA module and PXIe-8135 PXI Controller.

The signal generator produces pulses with the amplitude of A , the width of W and the repetition cycle of T_p , and the pulses and the AWGN make up the mixed disturbance coupled to the radio transmission. Without a loss of generality, we assume A obeys Gaussian distribution with the variance of σ_h^2 , and the variance of is AWGN σ_l^2 . Thus, the APD curve of the mixed disturbance is demonstrated as

$$APD_n(n) = \rho \operatorname{erf} \left(\frac{n}{\sqrt{2} \sigma_h} \right) + (1 - \rho) \operatorname{erf} \left(\frac{n}{\sqrt{2} \sigma_l} \right)$$

where $\rho = W/T_p$ refers to the duty ratio of the pulses. An example of the pulsed disturbance is shown in Figure 11 when $\sigma_l = 1$, $\sigma_h = 10$, and $\rho = 0.1$. In particular, the APD curves of interferences are the same if they have equal ρ , σ_l and σ_h , so they can be distinguished by PDD under this circumstance, as illustrated in Figure 12.

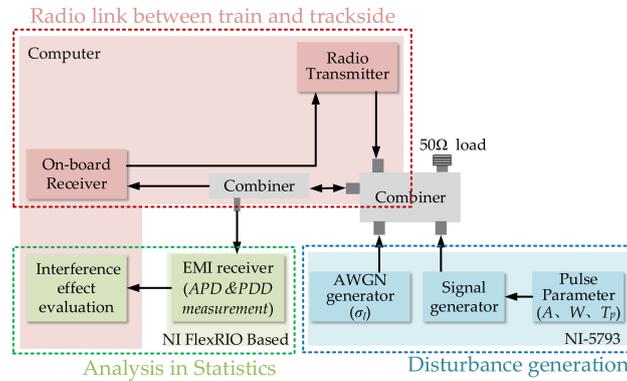


Figure 10. Test bench employed in the simulation.

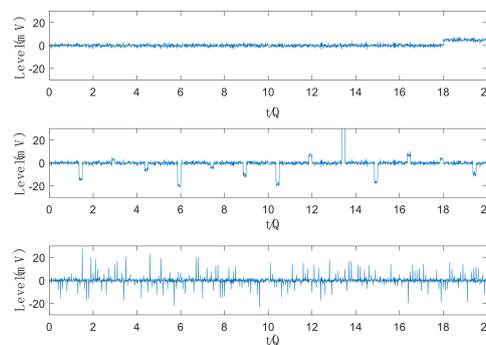


Figure 11. An example of the time-domain waveforms of the pulsed disturbance when $\sigma_l = 1$, $\sigma_h = 10$, $\rho = 0.1$, and the repeated cycle is $T_p = 20Q$, $T_p = 1.5Q$, $T_p = 0.1Q$, respectively.

In order to cover the typical cases of interfered encoded RSTT, the interference effect of disturbances with different statistical characteristics in the time domain should be taken into consideration. Nowadays, a turbo code specified by the 3rd Generation Partnership Project (3GPP) is widely used in GSM-R and LTE-R systems. Besides, the LDPC code is now used in WLAN and will be applied to 5G-R. Therefore, these popular FEC coding schemes are used in this simulation. As for the disturbances, we set the signal-to-noise ratio of AWGN to be constant $SNR_l = -5$ dB, and observed the predicted transmission error at each σ_h level, with a different W and T_p . According to the analysis above, we set the block-length to be $Q = 256$ symbols and the pulse cycle to be $T_p = 0.1Q$, $T_p = 1.5Q$, $T_p = 20Q$ with a duty ratio of $\rho = 0.1$ and $\rho = 0.9$, corresponding to disturbances from different sources. The *BLER* performance is estimated by a dynamic MI-based model. For each transmitted symbol, the varying SINR values caused by pulsed disturbances are mapped to instantaneous RBIR by the basic MI-based model. The statistics of block errors are collected and the effective $RBIR_L$ is computed to look up the *BLER* from the AWGN curve.

Figure 13 shows the simulated results of a rate-2/3 turbo code with 16QAM radio signal in the case of $\rho = 0.1$ and $\rho = 0.9$, respectively, and Figure 14 shows the simulated results of LDPC code. From Figure 13a, although the interferences of different repetition cycles have the same APD when $SNR_h = 2$ dB, the difference between their *BLER* is as large as almost two orders of magnitude. Therefore, a single APD parameter is not sufficient to evaluate the performance accurately, and may result in considerable errors. In addition, comparing Figure 13a,b, we can see that the smaller the duty ratio is, the larger error the APD method leads to, which is caused by the assumption of a uniform distribution of errors within a code word.

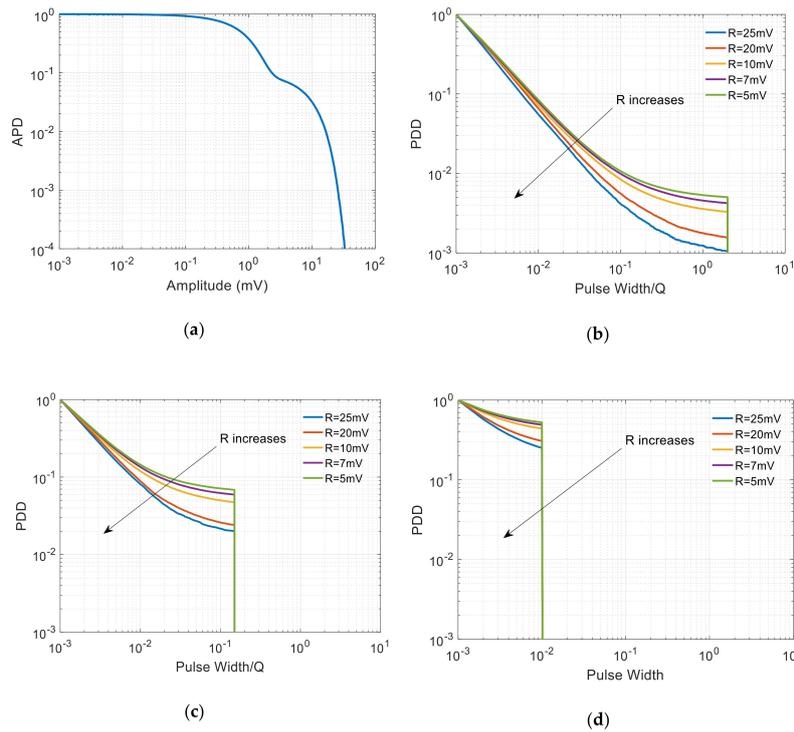


Figure 12. APD and PDD plots of the pulsed disturbances shown in Figure 11: (a) the same APD of all disturbances; (b) the PDD when $T_p = 20Q$, $\rho = 0.1$; (c) the PDD when $T_p = 1.5Q$, $\rho = 0.1$; and (d) the PDD when $T_p = 0.1Q$, $\rho = 0.1$.

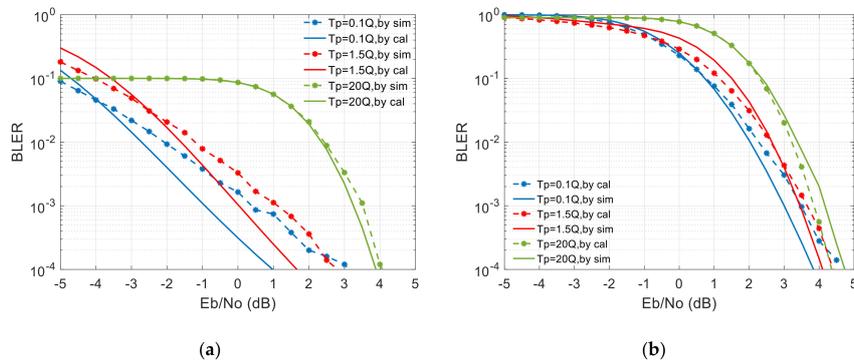


Figure 13. Simulation for the dynamic MI-based model, Long-Term Evolution (LTE) Turbo code (2/3 rate), 16QAM under different duty ratio (a) $\rho = 0.1$; (b) $\rho = 0.9$.

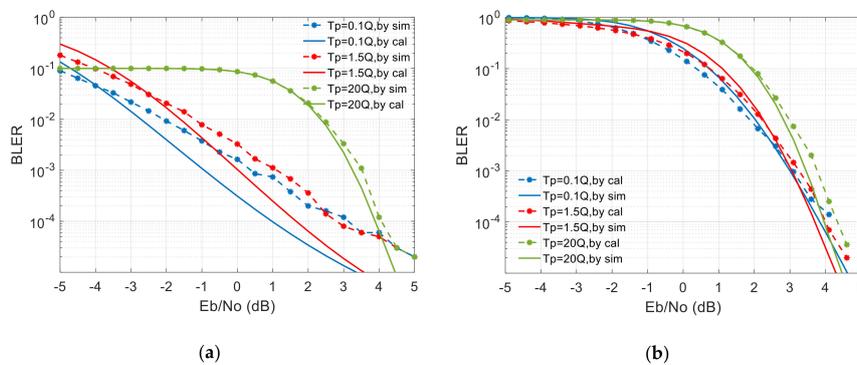


Figure 14. Simulation for the dynamic MI-based model, IEEE802.16 LDPC code (2/3 rate), 16QAM under different duty ratio (a) $\rho = 0.1$; (b) $\rho = 0.9$.

We can see that estimated *BLER* curves based on the MI-based model are close to the actual decoding error rate. As shown in Figure 13a, the maximum SINR errors at 1% *BLER* with different *T_p* are 1.2, 0.8 and 0.05 dB respectively. That is to say, as for the RBIRL-based model, the evaluation error tends to decrease as the *T_p* increases, because the pulsed interference is more likely to be approximated as two independent AWGN parts, which reduces the accidental and incidental effect of the burst interferences.

6. Conclusions

As the EMI has been a major threat to the reliability of railway communication systems, this paper proposed a novel methodology to supervise the real-time performance of RSTT under disturbances in the HSR environment. Based on the joint statistical characteristics of pulsed interference, a dynamic MI model is proposed to predict the degradation of RSTT using FEC codes. This model transforms joint time-domain statistical characteristics, i.e., APD and PDD of disturbances, to an MI metric through which the average *BLER* is obtained. According to the simulation results, the method based on joint statistical characteristics is valid under different interferences, even if they have the same distribution of amplitude, and the maximum estimated SINR errors at 1% *BLER* are no greater than 1.2 dB. That is to say, this method is effective in more complex situations where transmitted signals with various MCSs are affected with different disturbances, as shown in Table 1. Moreover, since this method does not require prior statistical information of the disturbance, it has the potential to be applied to the performance evaluation of disturbances in more practical applications, such as real-time supervising, risk analysis and early warning in the future.

Table 1. Comparison of the proposed method based on statistical characteristics with previous work. ICF: impulsiveness correction factor; FEC: forward error correction.

Method to Monitor Interference	Modulation Scheme	FEC Coding Scheme	Impulsive Disturbance	Non-Impulsive Disturbance
Classification [7]	√		√	
Instantaneous frequency histogram [15]	√		√	
APD without ICF [14]	√		√	√
APD with ICF [17]	√	√	√	
APD and PDD	√	√	√	√

Author Contributions: Conceptualization, J.Z., Y.W. and X.G.; methodology, J.Z. and X.G.; validation, J.Z. and X.G.; investigation, J.Z. and Y.W.; writing—original draft preparation, X.G.; writing—review and editing, J.Z., Y.W., and D.Z. All authors have read and agreed to the published version of the manuscript.

Funding: This research was funded by the National Natural Science Foundation of China (No. U1734203) and Beijing Municipal Science & Technology Commission (No. Z181100001018032).

Acknowledgments: The authors wish to thank the reviewers for their valuable comments and suggestions concerning this manuscript.

Conflicts of Interest: The authors declare no conflicts of interest.

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