






## Article

# Development of Advanced Computer Aid Model for Shear Strength of Concrete Slender Beam Prediction

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Received: 31 March 2020; Accepted: 27 May 2020; Published: 30 May 2020



**Abstract:** High-strength concrete (HSC) is highly applicable to the construction of heavy structures. However, shear strength ( $S_s$ ) determination of HSC is a crucial concern for structure designers and decision makers. The current research proposes the novel models based on the combination of adaptive neuro-fuzzy inference system (ANFIS) with several meta-heuristic optimization algorithms, including ant colony optimizer (ACO), differential evolution (DE), genetic algorithm (GA), and particle swarm optimization (PSO), to predict the  $S_s$  of HSC slender beam. The proposed models were constructed using several input combinations incorporating several related dimensional parameters such as effective depth of beam ( $d$ ), shear span ( $a$ ), maximum size of aggregate ( $a_g$ ), compressive strength of concrete ( $f_c$ ), and percentage of tension reinforcement ( $\rho$ ). To assess the impact of the non-homogeneity of the dataset on the prediction result accuracy, two possible modeling scenarios, (i) non-processed (initial) dataset (NP) and (ii) pre-processed dataset (PP), are inspected by several performance indices. The modeling results demonstrated that ANFIS-PSO hybrid model attained the best prediction accuracy over the other models and for the pre-processed input parameters. Several uncertainty analyses were examined (i.e., model, variables, and data), and results indicated predicting the HSC shear strength was more sensitive to the model structure uncertainty than the input parameters.

**Keywords:** structure monitoring; shear strength prediction; machine learning; hybrid ANFIS model; high-strength concrete

## 1. Introduction

Among the high-performance concrete (HPC) used in structural engineering, high-strength concrete (HSC) has received the most significant attention. The HSC is used in several structural engineering projects and is mostly considered at a compressive strength of  $>60$  MPa due to the benefits it offers [1]. Despite the lack of a clear difference between HSC and normal-strength concrete (NSC), several approaches and studies have determined varying ranges of compressive strength (CS) for differentiating NSC from HSC [2]. This study, however, followed the ACI 363R-10, which described HSC as concrete with CS of  $>40$  MPa [3]. HSC has significant benefits, which have boosted its implementation in construction activity globally. Such advantages include its improved physicomechanical properties such as CS, long-term durability, and stiffness. HSC attracts great interest due to the economic usefulness associated with it as it helps in reducing geometrical sections and gain in structures. Thus, HSC is preferred over NSC for economic, aesthetic, and technical purposes [4]. Practically, HSC is known to be brittle [4] as studies have shown sudden cracking and traversing aggregate particles in HSC, which produces fracture planes that are relatively smooth [5]. As with NSC, these cracks do not cover whole aggregate particles. Concrete shear strength is significantly reduced by smooth fracture surfaces by reducing the aggregate interlock contribution at the shear fracture planes.

For a reinforced concrete (RC) beam without transverse reinforcement, its failure mechanism can be considered as the generation of three internal forces that contribute to shear resistance. These internal forces include the concretes' contribution in the compression region ( $V_c$ ), the shear contribution due to the dowel action of longitudinal rebars ( $V_d$ ), and the shear contribution due to the aggregate interlock ( $V_a$ ). Consequently, the overall shear resistance is the summation of all these internal forces. Components  $V_a$  and  $V_d$  are ineffective if the diagonal crack opening is excessive. As a result, all the shear on the section will be on component  $V_c$ , leading to beam collapse as the concrete is crushed in compression [6].

The shear capacity of beams is mainly influenced by the aggregate interlocking mechanism; thus, the beams' ultimate load capacity under shear is influenced by this mechanism [7,8]. As per [9],  $V_a$  for beams of CS ranging between 26 and 49 MPa accounts for 33% to 50% of the overall shear resistance of such beams. However,  $V_a$  seems not to contribute significantly towards shear at higher concrete strengths as evidenced by the smooth fracture planes and straight cracks, which do not cover the whole aggregates as earlier mentioned. Similarly, [10] suggested taking  $V_a$  as zero for concrete with CS of  $>62$  MPa.

Based on the existing literature on RC shear slender beams without web reinforcement, it is evident that no common rational theory exists to explain the collaboration between the three internal forces that contribute to shear resistance, particularly for HSC [11]. It appears that the precise estimation of shear capacity of HSC slender RC beam in the absence of shear stirrups is an open topic in research communities of structural engineering [12,13]. The relationship between the intricate modeling variable has a remarkable influence on the shear capacity of HSC slender beams without stirrups. As such, the regression-based models are not considered ideal for such an application [14]. The existing stochasticity or nonlinearity in the experimental database initiates a very complex regression problem that needs a sophisticated modeling approach to mimic its actual internal mechanism. Artificial intelligence (AI) models have found wide application in solving different problems in civil engineering due to their interesting features, such as their auto-search and adaptation capability when finding multi-variable interrelationships [15–20]. The shear strength ( $S_s$ ) problem related to the structural engineering field has been investigated using the feasibility of AI models that have demonstrated positive progress [8,21,22].

Several versions of AI models have been developed for beam  $S_s$  prediction, such as artificial neural network (ANN) [15,23–25], support vector machine (SVM) [26–29], evolutionary computing models (ECM) [30–33], and adaptive neuro-fuzzy inference system (ANFIS) [34–38]. Among all the aforementioned AI models, ANFIS confirmed its potential in modeling beam  $S_s$  mechanisms over the other models. The ANFIS model is characterized by the capability to mimic and capture the associated non-linearity and stochasticity of data time series [39]. However, the ANFIS model is associated

with a major drawback, which is the membership function tuning parameters. Thus, combining the optimization algorithms, which are inspired by the behavior of animals and plants in nature, with a standalone ANFIS model appears as a new alternative model for improving its performances in solving difficult problems [40,41]. The hybrid ANFIS model exhibited a noticeable implementation for diverse civil engineering applications [42–44]. In the current research, some parameters of the optimization algorithms (e.g., mutation probability) were assigned based on the reported literature review studies, while the appropriate values of those parameters can be obtained using the Taguchi approach [45]. This study assumes that the prediction modeling is associated with only input variables and model structures uncertainties, while the other uncertainty sources such as measurement errors, data handling, and inadequate sampling were ignored. The modeled dataset was hypothesized to be associated with redundant observations, and thus the dataset was constructed based on two scenarios of non-processed and pre-processed.

The main motivation of this study is to investigate the feasibility of the novel hybrid ANFIS models for modeling high-strength concrete beam Ss. The modeling procedure is involved in several experiments of HSC slender beams. Being that deep beams behave differently compared to the slender beams (owing to size effect), only slender beams were used in this research. The data analysis focused on ascertaining the model validity and establishing its limitations. Before the prediction process, several input combinations were constructed using the related physical properties including the effective depth of beam ( $d$ ), shear span ( $a$ ), maximum size of aggregate ( $a_g$ ), compressive strength of concrete ( $f'_c$ ), and percentage of tension reinforcement ( $\rho$ ). The Ss of the HSC slender beams is predicted using two different modeling scenarios based on (i) non-processed (initial) dataset (NP) and (ii) pre-processed dataset (PP) to investigate the impact of the non-homogeneity of the dataset on prediction result accuracy.

## 2. Materials and Methods

### 2.1. Database Description

An experimental dataset of HSC slender beams which fails in shear has been selected for constructing the applied hybrid AI models. The data were gathered from 33 intensive published types of research from between 1957 and 2013 [4,46–77]. Total observations of the dataset are 250, which are based on rectangular HSC slender RC beams. In general, the data were selected based on geometric and material characteristics appearance. Furthermore, the followings precise standards were considered strictly during the selection of the esteemed database:

- i. The selection of beams was based on those that were longitudinally reinforced with pre-stressed and fewer steel rebars and lack of shear stirrups.
- ii. Shear failure was the primary benchmark for the specimens which were uniformly loaded along with one or two weights.
- iii. Range of shear span ( $a$ ) was observed between 399–2745, where the data are skewed right (Skewness = 1.85) and leptokurtic (Kurtosis = 3.73). However, in the case of  $a_g/d$ , the calculated value was found to be between 0.010811–0.176056, where data were characterised by leptokurtic (kurtosis = 2.02) but considerably symmetric skewness (0.33).
- iv. The majority (83.6%) of observations contained the range of effective depth of beam ( $d$ ) from 133 to 300 mm; besides, 65.2% of data lie between 200 and 300 mm.
- v. Acceptance of the dimension of the shear span was  $\geq 2.5$  times the  $a/d$  (effective depth), where the majority (84%) of the data falls in the 2.5–4 range of  $a/d$ . Moreover,  $a_g$  varies from 9.5 to 25.4 mm, where 92.0% of the dataset contains the maximum size of aggregate between 9.5 and 19 mm.
- vi. Most of the data (92%) contain the aggregate size between 9.5 and 19 mm; in case of compressive strength of concrete ( $f'_c$ ), 90% of the data lie at  $\leq 100$  MPa of  $f'_c$ , and 4% out of 100 MPa. Among 90%, the majority (56%) were between 40–60 MPa; in case of the percentage of tension reinforcement ( $\rho$ ), the majority of the data (91.2%) are up to 4%.

It is worth mentioning that there are some limitations in the data which have not been considered, such as rebar diameter, the concrete tensile strength, the initial shrinkage/thermal strains at early ages, which might have an impact on shear strength of HCS slender RC beams due to being absent in the database; hence, these have been excluded from this study.

## 2.2. Soft Computing Models Overview

Artificial intelligence models are used to solve complex engineering applications associated with non-linear phenomena that cannot be generally solved using classical regression models. AI models eliminate the disadvantages of hard computing simulation. For instance, hard computing requires exact models, but since the AI model's procedure is similar to a black box, the problem does not need to be perfectly modeled. Hence, AI can consider both partial truth and approximation, and models that are soft computing methods can incorporate uncertainty. The goal of the present study is to assess the shear strength of a high-strength concrete slender beam utilizing efficient hybrid fuzzy-logic-based approaches. These models include the integrated ANFIS-ACO (ANFIS Ant Colony Optimization), ANFIS-PSO (ANFIS particle swarm optimization), ANFIS-DE (ANFIS differential evolution), and ANFIS-GA (ANFIS genetic algorithm). This section is explained by the main theories of the applied models.

### 2.2.1. Adaptive Neuro-Fuzzy Inference System (ANFIS)

Fuzzy logic (FL) was introduced many decades ago as a method for identifying several aspects of data that can consider partial set membership [78]. The prime reason behind its popularity is that FL permits input variable even though it is not precisely classified as numerical input [79]. The most important advantage of FL is that it easily generates conclusions from noisy or imprecise input data.

Choosing the appropriate types of membership functions and the reasonable fuzzy rules to yield the best results depends on having relevant experience and knowledge. In some cases, heavy computing tasks, such as repetitive calculation, must also be used. To train the fuzzy logic model, artificial neural networks can be applied to train the model. A synthesis of neural networks with fuzzy logic approaches could offer a practical tool with the primary abilities of both methods [80–82].

A neuro-fuzzy model can be applied as a hybrid algorithm for making decisions from a fuzzy modern soft-computing-based approach using ANN. ANFIS was introduced in 1993 by Jang [83]. The neuro-fuzzy model was improved with the intrinsic learning abilities of ANN. The essential components of fuzzy systems are rules, which are also the basic parts of the whole algorithm. The ANN is used to optimize these rules [84].

The first proposed ANFIS model had five layers. Figure 1 schematically depicts the structure of ANFIS. The rules are as follows [83].

$$\text{Rule \#1 : } f \text{ } X \text{ is } A_1 \text{ and } Y \text{ is } B_1, \text{ then } f_1 = p_1x + q_1y + r_1 \quad (1)$$

$$\text{Rule \#2 : } \text{If } X \text{ is } A_2 \text{ and } Y \text{ is } B_2, \text{ then } f_2 = p_2x + q_2y + r_2 \quad (2)$$

In the above relations,  $A_1$ - $A_2$  and  $B_1$ - $B_2$  refer to membership functions for input  $x$  and input  $y$ , respectively.

In the first phase, each node is described as a square node for making the membership grades. Applying the membership function, inputs ( $x$  and  $y$ ) are mapped as linguistic terms.

$$O_{1,i} = \mu_{A_i}(x), \quad i = 1, 2. \quad (3)$$

where  $x$  is the input value to node  $i$ , and  $A_i$  is the linguistic term.  $O_i^1$  is the membership function of  $A_i$ . In general, there are three significant types of membership functions, named Gaussian, triangular, and

trapezoidal. The mathematical expression of the Gaussian function is determined as the following formula:

$$\mu_{A_i}(x) = \exp\left(-\left(\frac{x-a_i}{b_i}\right)^2\right) \quad (4)$$

where  $a_i$  and  $b_i$  are defined as the distribution parameters.

Similar to the previous phase, in layer two, each node is circular, and the output is measured utilizing the following relation:

$$O_{2,i} = w_i = \mu_{A_i}(x) * \mu_{B_i}(x), \quad i = 1, 2. \quad (5)$$

In the above relation,  $w_i$  is determined as the weight of the rule.

In the next phase, the nodes compute the ratio of the weight of rules, divided by the sum of total weights, as the following relation:

$$O_{3,i} = \bar{w}_i = \frac{w_i}{w_1 + w_2}, \quad i = 1, 2. \quad (6)$$

The task of this phase is the measurement of the outputs associated with each if-then rule, obtained using the flowing function.

$$O_{4,i} = \bar{w}_i f_i = \bar{w}_i (p_i x + q_i y + r_i), \quad i = 1, 2. \quad (7)$$

In the above relation,  $\bar{w}_i$  refers to the output of the previous layer.  $p_i$ ,  $q_i$ , and  $r_i$  are updated during the training phase.

In the final phase, the summation of the layers in one circle node is computed as follows:

$$O_{5,i} = \sum_i \bar{w}_i f_i = \frac{\sum_i w_i f_i}{\sum_i w_i}, \quad i = 1, 2. \quad (8)$$

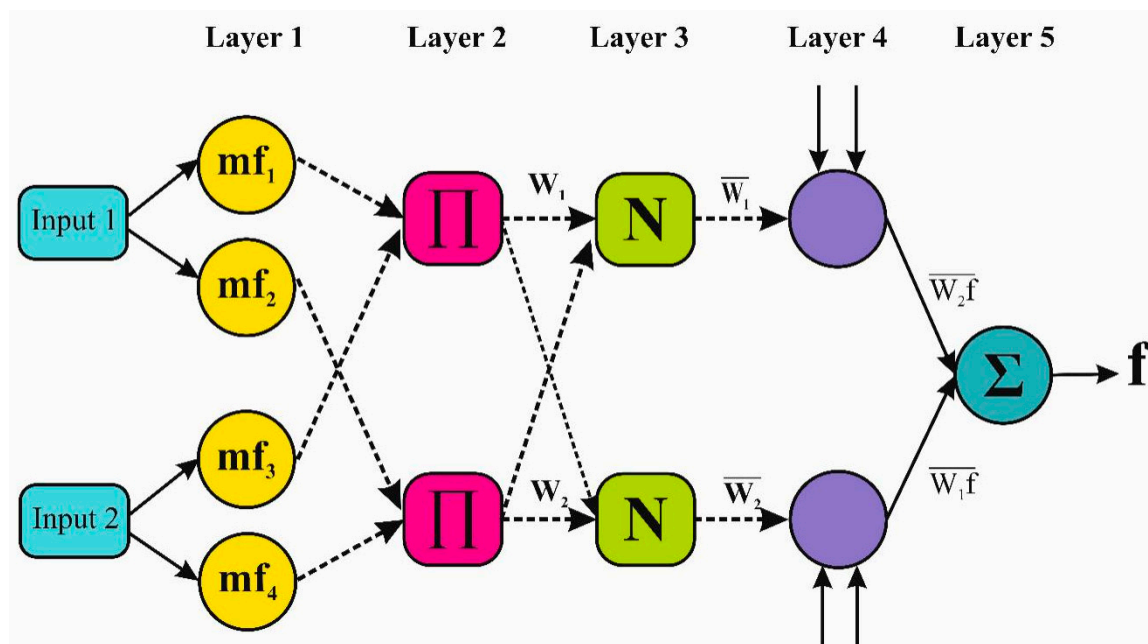


Figure 1. The structure of the adaptive neuro-fuzzy inference system model.

## 2.2.2. PSO Algorithm

Particle swarm optimization is inspired by the behavior and migration of a group of birds and was presented by Eberhart and Kennedy a few decades ago [85]. They considered three operators: alignment, separation, and cohesion. This optimization model utilizes a body of particles which move in the search space to explore the optimum solution. In the search space, the positions of particles are determined based on their own experience in combination with others' experiences [86]. Their speeds are similarly adjusted. The positions of the particles change as determined by their current position, velocity, and distance to the superior particle. In each iteration, the update rule for each particle determined as follows

$$p = p + v \quad (9)$$

with,

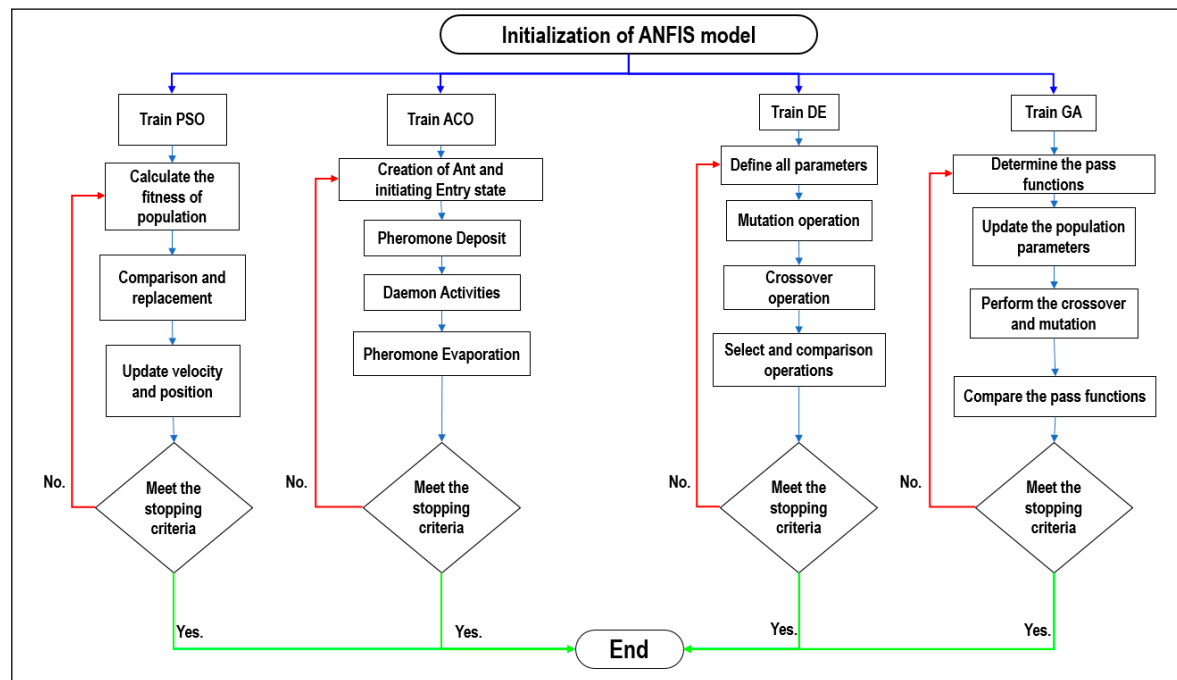
$$v = v + c_1 \cdot \text{rand} \cdot (p_{\text{Best}} - p) + c_2 \cdot \text{rand} \cdot (g_{\text{Best}} - p) \quad (10)$$

where  $p$ ,  $v$ ,  $c_1$ ,  $c_2$ ,  $p_{\text{Best}}$ ,  $g_{\text{Best}}$ , and  $\text{rand}$  refer to the position, the direction, the weight of local solution, the weight of global solution, the best position associated with total particles, the best-obtained position of the swarm and a random operator which generates random values between 0 and 1, respectively.

In each iteration, the velocities of the particles are re-computed using the following equation:

$$V_i^{t+1} = v_i^t + c_1 U_1^t (p_{\text{Best}} - p_i^t) + c_2 U_2^t (g_{\text{Best}} - p_i^t) \quad (11)$$

The three parameters in the equation as mentioned earlier stand for inertia, personal effect, and swarm effect coefficients, respectively. Figure 2 presents the flowchart of PSO.



**Figure 2.** The flow chart of the proposed hybrid adaptive neuro-fuzzy inference system (ANFIS) model, the optimization procedure of each integrated nature-inspired algorithm.

## 2.2.3. Ant Colony Optimization Algorithm (ACO)

This optimization model (ACO) was introduced by Dorigo about 30 years ago [87]. Many researchers subsequently extended the system. Since ACO algorithms are capable of solving statics problems as well as dynamic ones, they can be undertaken as reliable models in different optimization problems. This model is inspired by some behaviours such as food searching, the division of labor,



brood sorting, and co-operative transport (stigmergy), which make ant colonies more organized. In nature, ant colonies are well known as complex but well-organized structures with their activities being in line with stigmergy.

Ants communicate with each other using pheromone trails which help them to seek the shortest way to the source of food. A similar procedure is used in the ACO algorithm for finding the optimal point in the search space. The ants are moved through the paths in forward and backward manners. The ants apply an iterative procedure to explore the perfect solution associated with the problem [88,89]. Figure 2 shows the flowchart for ACO.

#### 2.2.4. DE Algorithm

In engineering problems, objective functions may be continuous, nonlinear, or multi-dimensional. Some may trap in local minima. In such issues, a population-based approach which has stochastic features is required to achieve the solution. The differential evolution (DE) model, which was presented by Storn and Price in 1996, has these features [90,91].

To find the best solution for a specific objective function which contains different real parameters ( $n$ ), the vectors are expressed the following form

$$x_i, G = [x_{1,i}, G, x_{2,i}, G, \dots, x_{n,i}, G] \quad i = 1, 2, \dots, k. \quad (12)$$

In the above relation,  $G$  refers to the generation number. Identifying maximum and minimum values for each parameter is described as follows:

$$xL_j \leq x_{j,i}, 1 \leq xU_j \quad (13)$$

Therefore, the primary values of the parameters are associated with identical probabilities. The schematic flowchart of the DE algorithm is shown in Figure 2.

#### 2.2.5. Genetic Algorithm (GA)

The genetic algorithm (GA) is an evolutionary search model which can be utilized to solve for optimization problems [92,93]. The idea of natural selection, which originated from Darwinian theory, is the basis of this model. The model starts by generating the primary population randomly. The fitness of each individual is assessed utilizing the fitness function. Afterward, in the selection phase, approaches, e.g., the Roulette Wheel approach, are used. To produce new offspring, crossover and mutation operators are applied. These new offspring could be considered as the new solutions (for optimization problems). Figure 2 schematically presents the GA [94].

#### 2.2.6. Tuning Procedure of the ANFIS Parameters

Previous studies confirmed that the standalone ANFIS is limited in solving complex problems due to trapping in local optimum results [95]. Besides, it requires a time-consuming process to tune the parameters of membership functions and fuzzy logic rules [96]. The combination of classical ANFIS with meta-heuristic optimization techniques inspired by nature can provide fast convergence speed while the trapping in of local optimum results can be tackled. The classical ANFIS includes two major sections as antecedent and consequent parts. Tuning the antecedent ( $a_i$  and  $b_i$  in Equation (4)) and consequent ( $p_i$ ,  $q_i$  and  $r_i$  in Equation (7)) parameters is essential to obtain reliable solutions. The ANFIS uses gradient-based techniques to tune those parameters. The major disadvantage of these techniques is trapping in local optimum solutions. This study aims to tune ANFIS parameters (antecedent and consequent parameters) by several meta-heuristic optimization algorithms (e.g., PSO, GA, DE and ACO) according to following steps:

- i. Select the training data.
- ii. Provide a primary structure for ANFIS.

- iii. Determine the initial values of antecedent and consequent parameters.
- iv. In iterative computation, tune the ANFIS parameters using the meta-heuristic techniques.
- v. In each iteration, assess the value of the objective function (i.e., root mean square error (RMSE)).
- vi. Save the best parameter set of the fuzzy model and terminate the tuning process when the stopping criterion is satisfied; otherwise, restart step iv.

### 2.3. Modeling Development Phase

The developed models were built based on several related variables including depth of beam ( $d$ ), shear span ( $a$ ), maximum size of aggregate ( $a_g$ ), compressive strength of concrete ( $f_c$ ) and percentage of tension reinforcement ( $\rho$ ). Non-processed (NP) and pre-processed (PP) modeling scenarios were established to investigate the impact of non-homogeneity of the dataset on prediction result. Table 1 presents the constructed input combinations for both pre-processed and non-pre-processed dataset modeling development. A total of eighteen models (Model 1–18) were initiated by different input combination for the possibility to achieve higher prediction accuracy. All these models of input combinations were used to develop classical ANFIS, ANFIS-ACO, ANFIS-DE, ANFIS-GA, and ANFIS-PSO models. The total number of dataset items is 250 observations. For the non-pre-processed dataset scenario, 30%–70% data division was utilized for the training and testing stages, whereas, for the pre-processed data, a total of 232 observations were used for the modeling with the same data division percentage.

**Table 1.** The input combinations constructed for building the proposed hybrid estimator models for both pre-processed and non-preprocessed dataset.

Models	Data	$d$	$a$	$a_g$	$f_c$	$\rho$	$a/d$	$a_g/d$
Model-1	Not Pre-processed	✓	✓	✓	✓	✓	-	-
Model-2	Not Pre-processed	-	✓	✓	✓	✓	-	-
Model-3	Not Pre-processed	✓	-	✓	✓	✓	-	-
Model-4	Not Pre-processed	✓	✓	-	✓	✓	-	-
Model-5	Not Pre-processed	✓	✓	✓	-	✓	-	-
Model-6	Not Pre-processed	✓	✓	✓	✓	-	-	-
Model-7	Pre-processed	✓	✓	✓	✓	✓	-	-
Model-8	Pre-processed	-	✓	✓	✓	✓	-	-
Model-9	Pre-processed	✓	-	✓	✓	✓	-	-
Model-10	Pre-processed	✓	✓	-	✓	✓	-	-
Model-11	Pre-processed	✓	✓	✓	-	✓	-	-
Model-12	Pre-processed	✓	✓	✓	✓	-	-	-
Model-13	Pre-processed	✓	-	-	✓	✓	✓	✓
Model-14	Pre-processed	-	-	-	✓	✓	✓	✓
Model-15	Pre-processed	✓	-	-	✓	✓	-	✓
Model-16	Pre-processed	✓	-	-	✓	✓	✓	-
Model-17	Pre-processed	✓	-	-	-	✓	✓	✓
Model-18	Pre-processed	✓	-	-	✓	-	✓	✓

### 2.4. Description of Performance Indices

To evaluate the accuracy of proposed estimator models, the performance indices such as mean square error (RMSE), Standardized Root Mean Square Error (SRMSE), mean absolute error (MAE),



Legate and McCabe's index (LMI), correlation coefficient (CC), PBIAS, Willmott's index (WI), and relative root mean square error (RRMSE) are employed as following equations [27,97–100]:

$$RMSE = \sqrt{\frac{1}{N_s} \sum_{j=1}^{N_s} ((Ss)_{exp} - (Ss)_{sim})^2} \quad (14)$$

$$SRMSE = \frac{\sqrt{\frac{1}{N_s} \sum_{j=1}^{N_s} ((Ss)_{exp} - (Ss)_{sim})^2}}{\left(\frac{d_s}{D}\right)_{Obs}} \quad (15)$$

$$MAE = \frac{1}{N_s} \sum_{j=1}^{N_s} |(Ss)_{exp} - (Ss)_{sim}| \quad (16)$$

$$CC = \frac{\sum_{j=1}^{N_s} ((Ss)_{exp} - \overline{(Ss)_{exp}})(\overline{(Ss)_{sim}} - (Ss)_{sim})}{\sqrt{\sum_{j=1}^{N_s} ((Ss)_{exp} - \overline{(Ss)_{exp}})^2 \sum_{j=1}^{N_T} ((Ss)_{sim} - \overline{(Ss)_{sim}})^2}} \quad (17)$$

$$WI = 1 - \left[ \frac{\sum_{i=1}^{N_s} ((Ss)_{exp} - (Ss)_{sim})^2}{\sum_{i=1}^{N_s} (|(Ss)_{sim} - \overline{(Ss)_{exp}}| + |(Ss)_{exp} - \overline{(Ss)_{exp}}|)^2} \right] \quad (18)$$

$$LMI = 1 - \left[ \frac{\sum_{i=1}^{N_s} |(Ss)_{exp} - (Ss)_{sim}|}{\sum_{i=1}^{N_s} |(Ss)_{exp} - \overline{(Ss)_{exp}}|} \right] \quad (19)$$

$$PBIAS = \left[ \frac{\sum_{i=1}^{N_s} ((Ss)_{exp} - (Ss)_{sim})}{\sum_{i=1}^{N_s} (Ss)_{exp}} \right] \times 100 \quad (20)$$

where the  $(Ss)_{exp}$  and  $(Ss)_{sim}$  are the experimental and simulated shear strength,  $\overline{(Ss)_{exp}}$  and  $\overline{(Ss)_{sim}}$  are their mean values, and  $N_s$  is the sample size.

### 3. Results and Discussion

The main focus of this paper is to establish a reliable and robust model based on the ability of different types of hybrid ANFIS approaches to predict the  $S_s$  prediction of HSC. The challenges of the mathematical and empirical relations establishing the appropriate relationship between the  $S_s$  and HSC properties highlight the intervention of soft computing aids. However, establishing the internal mechanism between the related predictors towards the  $S_s$  of HSC has a substantial motive for investigation and examination. Furthermore, robust and reliable models can always construct a precise intelligence-optimizing technology in the field of structural engineering. Thus, the proposal of a new hybrid intelligence model can enhance the reliable contribution to the structure design along with various reinforcement concrete engineering perspectives.

The proposed hybrid intelligence models and the standalone ANFIS models were evaluated based on various performance metrics and graphical presentations, including heat map, scatterplot, boxplot, and Taylor diagrams over the training and testing phase for modeling  $S_s$  of HSC. Besides, the new ANFIS models were assessed based on the hybridization algorithms, variables, and data uncertainty.

The performance of classical ANFIS is assessed in both training and testing period for different input combination models (Model 1–18) using RMSE, MAE, LMI, CC, WI, and SRMSE (Table 2). The input combination of Model 8 (Incorporated:  $a$ ,  $a_g$ ,  $fc$ , and  $\rho$ ) appeared to be the most appropriate choice for generating good prediction results over the training and testing stages. The acquired magnitudes of assessing metrics in training and testing are: ANFIS ( $RMSE = 0.263, 0.314$ ;  $MAE = 0.198, 0.224$ ;  $LMI = 0.675, 0.640$ ;  $CC = 0.936, 0.920$ ;  $WI = 0.966, 0.957$ ;  $SRMSE = 15.011, 19.584$ ).

**Table 2.** The prediction performance of the standalone ANFIS model for all proposed input combinations over the training and testing stage. The boldfaced represents the best ANFIS model.

Predictive Models	Input Combination	Stage	RMSE	MAE	LMI	CC	WI	SRMSE
ANFIS	Model-1	Train	0.317	0.227	0.626	0.905	0.948	17.883
ANFIS	Model-1	Test	0.427	0.313	0.495	0.848	0.917	25.706
ANFIS	Model-2	Train	0.298	0.220	0.639	0.917	0.955	16.792
ANFIS	Model-2	Test	0.397	0.279	0.550	0.871	0.926	23.887
ANFIS	Model-3	Train	0.359	0.248	0.593	0.876	0.930	20.221
ANFIS	Model-3	Test	1.221	0.486	0.216	0.439	0.558	73.470
ANFIS	Model-4	Train	0.290	0.209	0.656	0.921	0.957	16.371
ANFIS	Model-4	Test	0.417	0.303	0.512	0.857	0.921	25.088
ANFIS	Model-5	Train	0.330	0.245	0.597	0.896	0.943	18.634
ANFIS	Model-5	Test	0.430	0.318	0.487	0.845	0.912	25.872
ANFIS	Model-6	Train	0.456	0.346	0.431	0.790	0.875	25.730
ANFIS	Model-6	Test	0.537	0.418	0.325	0.748	0.851	32.298
ANFIS	Model-7	Train	0.295	0.218	0.642	0.919	0.956	16.852
ANFIS	Model-7	Test	0.320	0.241	0.613	0.916	0.956	19.936
<b>ANFIS</b>	<b>Model-8</b>	<b>Train</b>	<b>0.263</b>	<b>0.198</b>	<b>0.675</b>	<b>0.936</b>	<b>0.966</b>	<b>15.011</b>
<b>ANFIS</b>	<b>Model-8</b>	<b>Test</b>	<b>0.314</b>	<b>0.224</b>	<b>0.640</b>	<b>0.920</b>	<b>0.957</b>	<b>19.584</b>
ANFIS	Model-9	Train	0.356	0.244	0.598	0.879	0.932	20.321
ANFIS	Model-9	Test	1.076	0.426	0.316	0.477	0.614	67.103
ANFIS	Model-10	Train	0.289	0.211	0.653	0.922	0.958	16.483
ANFIS	Model-10	Test	0.327	0.228	0.635	0.912	0.951	20.403
ANFIS	Model-11	Train	0.308	0.230	0.623	0.911	0.951	17.603
ANFIS	Model-11	Test	0.391	0.290	0.535	0.872	0.927	24.373
ANFIS	Model-12	Train	0.451	0.341	0.439	0.797	0.879	25.787
ANFIS	Model-12	Test	0.481	0.380	0.390	0.798	0.881	29.972
ANFIS	Model-13	Train	0.288	0.223	0.633	0.923	0.958	16.445
ANFIS	Model-13	Test	0.366	0.273	0.562	0.889	0.936	22.811
ANFIS	Model-14	Train	0.297	0.229	0.623	0.918	0.955	16.965
ANFIS	Model-14	Test	0.333	0.243	0.611	0.909	0.951	20.743
ANFIS	Model-15	Train	0.347	0.255	0.580	0.885	0.936	19.849
ANFIS	Model-15	Test	0.415	0.315	0.494	0.861	0.909	25.859
ANFIS	Model-16	Train	0.302	0.223	0.633	0.915	0.954	17.228
ANFIS	Model-16	Test	0.305	0.227	0.636	0.925	0.957	19.045
ANFIS	Model-17	Train	0.284	0.215	0.646	0.925	0.960	16.223
ANFIS	Model-17	Test	0.356	0.258	0.586	0.895	0.944	22.180
ANFIS	Model-18	Train	0.470	0.354	0.418	0.778	0.862	26.841
ANFIS	Model-18	Test	0.505	0.402	0.355	0.777	0.859	31.477

The hybrid ANFIS-ACO model produced the lowest magnitudes of *RMSE*, *MAE*, *SRMSE*, and highest *LMI*, *CC*, and *WI* values (*RMSE*  $\approx$  0.377, 0.399, *MAE*  $\approx$  0.282, 0.289, *SRMSE*  $\approx$  21.563, 24.912) and (*LMI*  $\approx$  0.537, 0.536, *CC*  $\approx$  0.863, 0.870, *WI*  $\approx$  0.921, 0.918) for both training and testing stages, respectively. The best prediction was achieved for the input combination of Model-16 (incorporated: *d*,  $\rho$ , *a/d*, *fc*). These metrics for other input combination models using ANFIS-ACO can be seen in Table 3. Likewise, the preciseness of ANFIS-ACO with input combination in Model-16 is considerably good for predicting *Ss* (Table 3).

Tables 4 and 5 present the statistical performance accuracy of ANFIS-DE and ANFIS-GA models. The ANFIS-DE with input combination in Model-13 (incorporated: *d*,  $\rho$ , *a/d*, *a<sub>g</sub>/d*, *fc*) performed the reasonable prediction for the *Ss* by obtaining (*RMSE* = 0.375, 0.398; *MAE* = 0.281, 0.291; *LMI* = 0.538, 0.533; *CC* = 0.865, 0.870; *WI* = 0.922, 0.919; *SRMSE* = 21.417, 24.838) for both training and testing phases. However, ANFIS-GA with Model-16 (incorporated: *d*,  $\rho$ , *a/d*, *fc*) achieved highest level of accuracy in accordance the statistical metrics (*RMSE* = 0.286, 0.296; *MAE* = 0.224, 0.243; *LMI* = 0.632, 0.610; *CC* = 0.924, 0.930; *WI* = 0.959, 0.962; *SRMSE* = 16.358, 18.477) (Table 5).

**Table 3.** The prediction performance of the hybrid ANFIS-ACO model for all proposed input combinations over the training and testing stage. The boldface denotes the best ANFIS-ACO model.

Predictive Models	Input Combination	Stages	RMSE	MAE	LMI	CC	WI	SRMSE
ANFIS-ACO	Model-1	Train	0.381	0.286	0.530	0.860	0.919	21.460
ANFIS-ACO	Model-1	Test	0.414	0.307	0.505	0.859	0.914	24.940
ANFIS-ACO	Model-2	Train	0.388	0.291	0.522	0.853	0.915	21.889
ANFIS-ACO	Model-2	Test	0.425	0.313	0.495	0.852	0.906	25.569
ANFIS-ACO	Model-3	Train	0.418	0.314	0.484	0.828	0.898	23.567
ANFIS-ACO	Model-3	test	0.467	0.355	0.427	0.817	0.879	28.103
ANFIS-ACO	Model-4	Train	0.382	0.283	0.535	0.859	0.919	21.525
ANFIS-ACO	Model-4	Test	0.414	0.306	0.506	0.859	0.913	24.931
ANFIS-ACO	Model-5	Train	0.390	0.289	0.525	0.852	0.914	22.003
ANFIS-ACO	Model-5	Test	0.417	0.303	0.511	0.857	0.912	25.092
ANFIS-ACO	Model-6	Train	0.575	0.474	0.221	0.635	0.743	32.431
ANFIS-ACO	Model-6	Test	0.648	0.522	0.158	0.599	0.737	38.993
ANFIS-ACO	Model-7	Train	0.377	0.284	0.533	0.863	0.922	21.557
ANFIS-ACO	Model-7	Test	0.405	0.296	0.525	0.865	0.916	25.261
ANFIS-ACO	Model-8	Train	0.386	0.289	0.525	0.856	0.917	22.050
ANFIS-ACO	Model-8	Test	0.421	0.306	0.508	0.853	0.906	26.274
ANFIS-ACO	Model-9	Train	0.419	0.314	0.483	0.828	0.898	23.914
ANFIS-ACO	Model-9	Test	0.477	0.367	0.411	0.804	0.872	29.763
ANFIS-ACO	Model-10	Train	0.379	0.280	0.540	0.862	0.921	21.659
ANFIS-ACO	Model-10	Test	0.404	0.293	0.530	0.866	0.916	25.229
ANFIS-ACO	Model-11	Train	0.383	0.285	0.531	0.859	0.919	21.876
ANFIS-ACO	Model-11	Test	0.408	0.293	0.530	0.862	0.914	25.465
ANFIS-ACO	Model-12	Train	0.580	0.478	0.215	0.630	0.738	33.146
ANFIS-ACO	Model-12	Test	0.602	0.487	0.219	0.655	0.770	37.556
ANFIS-ACO	Model-13	Train	0.377	0.283	0.535	0.863	0.922	21.552
ANFIS-ACO	Model-13	Test	0.399	0.289	0.536	0.870	0.918	24.914
ANFIS-ACO	Model-14	Train	0.418	0.306	0.497	0.829	0.898	23.865
ANFIS-ACO	Model-14	Test	0.438	0.317	0.491	0.840	0.896	27.338
ANFIS-ACO	Model-15	Train	0.427	0.320	0.474	0.820	0.893	24.407
ANFIS-ACO	Model-15	Test	0.478	0.366	0.413	0.807	0.866	29.828
<b>ANFIS-ACO</b>	<b>Model-16</b>	<b>Train</b>	<b>0.377</b>	<b>0.282</b>	<b>0.537</b>	<b>0.863</b>	<b>0.921</b>	<b>21.563</b>
<b>ANFIS-ACO</b>	<b>Model-16</b>	<b>Test</b>	<b>0.399</b>	<b>0.289</b>	<b>0.536</b>	<b>0.870</b>	<b>0.918</b>	<b>24.912</b>
ANFIS-ACO	Model-17	Train	0.384	0.286	0.530	0.858	0.918	21.936
ANFIS-ACO	Model-17	Test	0.403	0.288	0.538	0.866	0.916	25.162
ANFIS-ACO	Model-18	Train	0.581	0.477	0.215	0.630	0.739	33.162
ANFIS-ACO	Model-18	Test	0.599	0.477	0.235	0.659	0.773	37.391

**Table 4.** The prediction performance of the hybrid ANFIS-DE model for all proposed input combinations over the training and testing stage. The boldface denotes the best modeling results.

Predictive Models	Input Combination	Stages	RMSE	MAE	LMI	CC	WI	SRMSE
ANFIS-DE	Model-1	Train	0.378	0.281	0.538	0.862	0.920	21.299
ANFIS-DE	Model-1	Test	0.414	0.304	0.509	0.859	0.913	24.914
ANFIS-DE	Model-2	Train	0.383	0.286	0.529	0.858	0.917	21.583
ANFIS-DE	Model-2	Test	0.988	0.403	0.350	0.292	0.608	59.465
ANFIS-DE	Model-3	Train	0.408	0.314	0.485	0.838	0.903	23.023
ANFIS-DE	Model-3	Test	0.459	0.357	0.424	0.827	0.883	27.628
ANFIS-DE	Model-4	Train	0.382	0.283	0.535	0.859	0.919	21.521
ANFIS-DE	Model-4	Test	0.414	0.306	0.506	0.859	0.913	24.931
ANFIS-DE	Model-5	Train	0.390	0.289	0.525	0.852	0.914	22.003
ANFIS-DE	Model-5	Test	0.417	0.303	0.511	0.857	0.912	25.092
ANFIS-DE	Model-6	Train	0.574	0.469	0.229	0.637	0.741	32.372
ANFIS-DE	Model-6	Test	0.646	0.518	0.164	0.600	0.734	38.882
ANFIS-DE	Model-7	Train	0.356	0.263	0.568	0.883	0.929	20.337
ANFIS-DE	Model-7	Test	0.407	0.297	0.523	0.868	0.917	25.371

Table 4. Cont.

Predictive Models	Input Combination	Stages	RMSE	MAE	LMI	CC	WI	SRMSE
ANFIS-DE	Model-8	Train	0.376	0.284	0.533	0.865	0.925	21.474
ANFIS-DE	Model-8	Test	0.406	0.299	0.520	0.863	0.917	25.314
ANFIS-DE	Model-9	Train	0.416	0.308	0.494	0.831	0.902	23.745
ANFIS-DE	Model-9	Test	0.470	0.358	0.426	0.811	0.876	29.340
ANFIS-DE	Model-10	Train	0.379	0.280	0.540	0.862	0.921	21.659
ANFIS-DE	Model-10	Test	0.404	0.293	0.530	0.866	0.916	25.229
ANFIS-DE	Model-11	Train	0.383	0.285	0.531	0.859	0.919	21.876
ANFIS-DE	Model-11	Test	0.408	0.293	0.529	0.862	0.914	25.466
ANFIS-DE	Model-12	Train	0.559	0.450	0.260	0.674	0.780	31.958
ANFIS-DE	Model-12	Test	0.583	0.471	0.243	0.692	0.797	36.364
<b>ANFIS-DE</b>	<b>Model-13</b>	<b>Train</b>	<b>0.375</b>	<b>0.281</b>	<b>0.538</b>	<b>0.865</b>	<b>0.922</b>	<b>21.417</b>
<b>ANFIS-DE</b>	<b>Model-13</b>	<b>Test</b>	<b>0.398</b>	<b>0.291</b>	<b>0.533</b>	<b>0.870</b>	<b>0.919</b>	<b>24.838</b>
ANFIS-DE	Model-14	Train	0.404	0.307	0.496	0.845	0.909	23.073
ANFIS-DE	Model-14	Test	0.411	0.308	0.506	0.858	0.915	25.631
ANFIS-DE	Model-15	Train	0.402	0.295	0.515	0.844	0.913	22.941
ANFIS-DE	Model-15	Test	0.462	0.345	0.445	0.815	0.889	28.833
ANFIS-DE	Model-16	Train	0.377	0.281	0.538	0.863	0.922	21.542
ANFIS-DE	Model-16	Test	0.399	0.289	0.536	0.870	0.918	24.912
ANFIS-DE	Model-17	Train	0.381	0.283	0.534	0.861	0.919	21.745
ANFIS-DE	Model-17	Test	0.399	0.287	0.540	0.870	0.917	24.893
ANFIS-DE	Model-18	Train	0.580	0.477	0.216	0.631	0.740	33.116
ANFIS-DE	Model-18	Test	0.599	0.477	0.235	0.659	0.773	37.391

**Table 5.** The prediction performance of the hybrid ANFIS-GA model for all proposed input combinations over the training and testing stage. The boldface denotes the best modeling results.

Predictive Models	Input Combination	Stages	RMSE	MAE	LMI	CC	WI	SRMSE
ANFIS-GA	Model-1	Train	0.291	0.222	0.636	0.922	0.958	16.416
ANFIS-GA	Model-1	Test	0.368	0.271	0.562	0.889	0.939	22.172
ANFIS-GA	Model-2	Train	0.313	0.235	0.614	0.908	0.951	17.673
ANFIS-GA	Model-2	Test	0.433	0.297	0.520	0.844	0.915	26.069
ANFIS-GA	Model-3	Train	0.383	0.270	0.556	0.859	0.921	21.571
ANFIS-GA	Model-3	Test	0.457	0.345	0.443	0.822	0.896	27.497
ANFIS-GA	Model-4	Train	0.301	0.215	0.647	0.915	0.953	16.976
ANFIS-GA	Model-4	Test	0.356	0.262	0.578	0.897	0.943	21.442
ANFIS-GA	Model-5	Train	0.325	0.245	0.598	0.900	0.944	18.343
ANFIS-GA	Model-5	Test	0.392	0.282	0.544	0.874	0.926	23.577
ANFIS-GA	Model-6	Train	0.479	0.385	0.367	0.766	0.858	27.024
ANFIS-GA	Model-6	Test	0.571	0.427	0.311	0.711	0.828	34.367
ANFIS-GA	Model-7	Train	0.347	0.256	0.579	0.887	0.932	19.838
ANFIS-GA	Model-7	Test	0.385	0.284	0.544	0.881	0.923	24.027
ANFIS-GA	Model-8	Train	0.300	0.231	0.620	0.918	0.957	17.127
ANFIS-GA	Model-8	Test	0.328	0.237	0.619	0.913	0.955	20.444
ANFIS-GA	Model-9	Train	0.352	0.249	0.591	0.883	0.932	20.101
ANFIS-GA	Model-9	Test	0.448	0.336	0.461	0.828	0.896	27.925
ANFIS-GA	Model-10	Train	0.352	0.259	0.574	0.884	0.930	20.111
ANFIS-GA	Model-10	Test	0.389	0.285	0.542	0.876	0.923	24.277
ANFIS-GA	Model-11	Train	0.336	0.258	0.576	0.894	0.940	19.167
ANFIS-GA	Model-11	Test	0.376	0.280	0.551	0.882	0.933	23.466
ANFIS-GA	Model-12	Train	0.457	0.350	0.424	0.791	0.870	26.120
ANFIS-GA	Model-12	Test	0.431	0.344	0.447	0.842	0.905	26.884
ANFIS-GA	Model-13	Train	0.300	0.232	0.618	0.916	0.955	17.119
ANFIS-GA	Model-13	Test	0.331	0.262	0.579	0.912	0.951	20.650
ANFIS-GA	Model-14	Train	0.295	0.237	0.610	0.922	0.959	16.836
ANFIS-GA	Model-14	Test	0.370	0.279	0.552	0.897	0.945	23.062
ANFIS-GA	Model-15	Train	0.378	0.270	0.556	0.863	0.923	21.571
ANFIS-GA	Model-15	Test	0.447	0.328	0.474	0.828	0.898	27.859

Table 5. Cont.

Predictive Models	Input Combination	Stages	RMSE	MAE	LMI	CC	WI	SRMSE
ANFIS-GA	Model-16	Train	0.286	0.224	0.632	0.924	0.959	16.358
ANFIS-GA	Model-16	Test	0.296	0.243	0.610	0.930	0.962	18.477
ANFIS-GA	Model-17	Train	0.317	0.243	0.601	0.906	0.950	18.103
ANFIS-GA	Model-17	Test	0.366	0.268	0.570	0.893	0.944	22.812
ANFIS-GA	Model-18	Train	0.467	0.370	0.392	0.783	0.874	26.649
ANFIS-GA	Model-18	Test	0.491	0.405	0.349	0.806	0.894	30.637

The best performing hybrid model (i.e., ANFIS-PSO) used input combination Model-7 configured with pre-processed variables ( $d$ ,  $a$ ,  $a_g$ ,  $fc$ , and  $\rho$ ) (Table 6). The best inputs combination (i.e., Model-7) was generated good prediction results over both modeling phases with statistical results (RMSE = 0.206, 0.283; MAE = 0.157, 0.213; LMI = 0.742, 0.659; CC = 0.961, 0.935; WI = 0.980, 0.965; SRMSE = 11.791, 17.671).

**Table 6.** The prediction performance of the hybrid ANFIS-PSO model for all proposed input combinations over the training and testing stage. The boldface denotes the best modeling results.

Predictive Models	Input Combination	Stages	RMSE	MAE	LMI	CC	WI	SRMSE
ANFIS-PSO	Model-1	Train	0.294	0.198	0.675	0.919	0.956	16.558
ANFIS-PSO	Model-1	Test	0.394	0.291	0.531	0.871	0.928	23.716
ANFIS-PSO	Model-2	Train	0.235	0.187	0.693	0.949	0.973	13.266
ANFIS-PSO	Model-2	Test	0.497	0.317	0.488	0.816	0.901	29.904
ANFIS-PSO	Model-3	Train	0.340	0.236	0.612	0.890	0.939	19.183
ANFIS-PSO	Model-3	Test	0.432	0.314	0.493	0.844	0.906	26.010
ANFIS-PSO	Model-4	Train	0.305	0.224	0.632	0.912	0.952	17.197
ANFIS-PSO	Model-4	Test	0.397	0.291	0.531	0.869	0.927	23.916
ANFIS-PSO	Model-5	Train	0.265	0.182	0.701	0.935	0.966	14.916
ANFIS-PSO	Model-5	Test	0.401	0.274	0.558	0.868	0.929	24.129
ANFIS-PSO	Model-6	Train	0.459	0.352	0.421	0.787	0.873	25.894
ANFIS-PSO	Model-6	Test	0.541	0.407	0.343	0.743	0.848	32.564
<b>ANFIS-PSO</b>	<b>Model-7</b>	<b>Train</b>	<b>0.206</b>	<b>0.157</b>	<b>0.742</b>	<b>0.961</b>	<b>0.980</b>	<b>11.791</b>
<b>ANFIS-PSO</b>	<b>Model-7</b>	<b>Test</b>	<b>0.283</b>	<b>0.213</b>	<b>0.659</b>	<b>0.935</b>	<b>0.965</b>	<b>17.671</b>
ANFIS-PSO	Model-8	Train	0.208	0.162	0.733	0.960	0.980	11.886
ANFIS-PSO	Model-8	Test	0.403	0.277	0.555	0.876	0.934	25.109
ANFIS-PSO	Model-9	Train	0.346	0.246	0.596	0.886	0.936	19.766
ANFIS-PSO	Model-9	Test	0.414	0.310	0.502	0.855	0.914	25.852
ANFIS-PSO	Model-10	Train	0.267	0.201	0.670	0.934	0.965	15.260
ANFIS-PSO	Model-10	Test	0.307	0.232	0.628	0.923	0.958	19.156
ANFIS-PSO	Model-11	Train	0.347	0.255	0.580	0.886	0.936	19.798
ANFIS-PSO	Model-11	Test	0.629	0.356	0.429	0.690	0.828	39.252
ANFIS-PSO	Model-12	Train	0.404	0.290	0.523	0.841	0.907	23.078
ANFIS-PSO	Model-12	Test	0.467	0.355	0.429	0.812	0.891	29.123
ANFIS-PSO	Model-13	Train	0.258	0.186	0.695	0.938	0.967	14.757
ANFIS-PSO	Model-13	Test	0.379	0.274	0.560	0.880	0.936	23.629
ANFIS-PSO	Model-14	Train	0.244	0.184	0.698	0.945	0.971	13.950
ANFIS-PSO	Model-14	Test	0.401	0.284	0.544	0.875	0.934	25.006
ANFIS-PSO	Model-15	Train	0.360	0.258	0.575	0.876	0.931	20.570
ANFIS-PSO	Model-15	Test	0.440	0.322	0.484	0.835	0.900	27.448
ANFIS-PSO	Model-16	Train	0.256	0.195	0.680	0.939	0.968	14.652
ANFIS-PSO	Model-16	Test	0.292	0.217	0.652	0.931	0.964	18.211
ANFIS-PSO	Model-17	Train	0.288	0.216	0.645	0.923	0.959	16.430
ANFIS-PSO	Model-17	Test	0.313	0.244	0.608	0.920	0.957	19.547
ANFIS-PSO	Model-18	Train	0.399	0.295	0.516	0.845	0.912	22.818
ANFIS-PSO	Model-18	Test	0.479	0.386	0.380	0.810	0.896	29.878

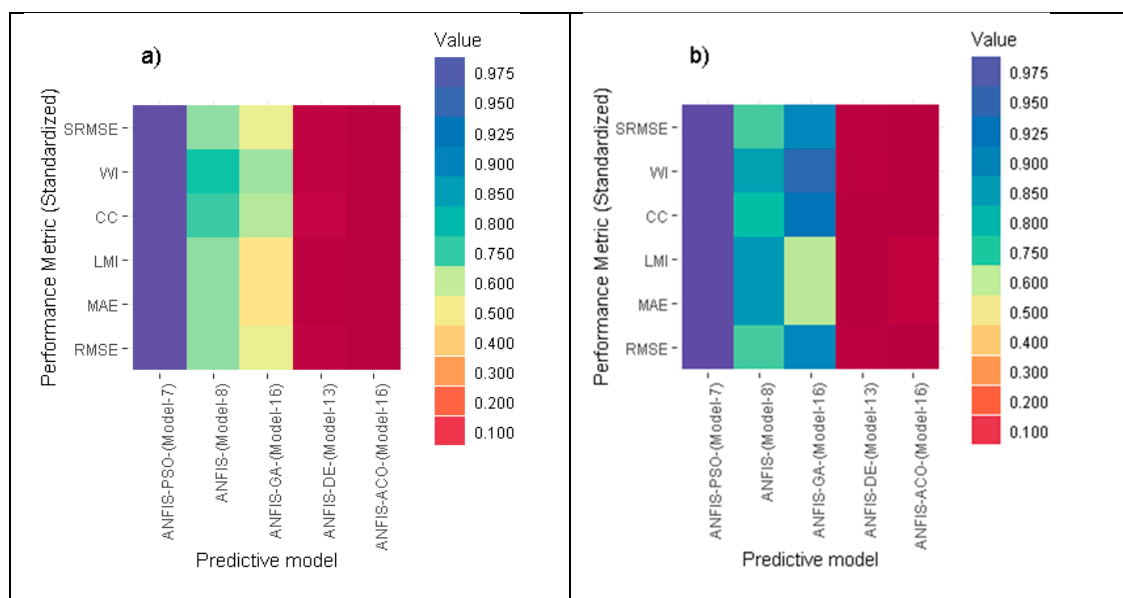
The uncertainties arise in model, variables, and data are reported in Table 7 based on the interquartile range (IQR) indices. The assessment metrics attained in investigating model and variable

uncertainties are  $RMSE = 0.691, 0.403$ ;  $MAE = 0.649, 0.424$ ;  $LMI = 0.649, 0.424$ ;  $CC = 0.687, 0.482$ ;  $WI = 0.806, 0.702$ , and  $SRMSE = 0.806, 0.403$ , respectively. Based on the minimal absolute error metrics (i.e.,  $RMSE$ ,  $MAE$ , and  $SRMSE$ ), the model uncertainty was higher as compared to variable and data uncertainty.

**Table 7.** The uncertainty analysis of the proposed model-based IQR of indices.

	RMSE	MAE	LMI	CC	WI	SRMSE
Model Uncertainty	0.691	0.649	0.649	0.687	0.806	0.691
Variable Uncertainty	0.403	0.424	0.424	0.482	0.702	0.403
Data Uncertainty	0.334	0.383	0.340	0.348	0.332	0.404

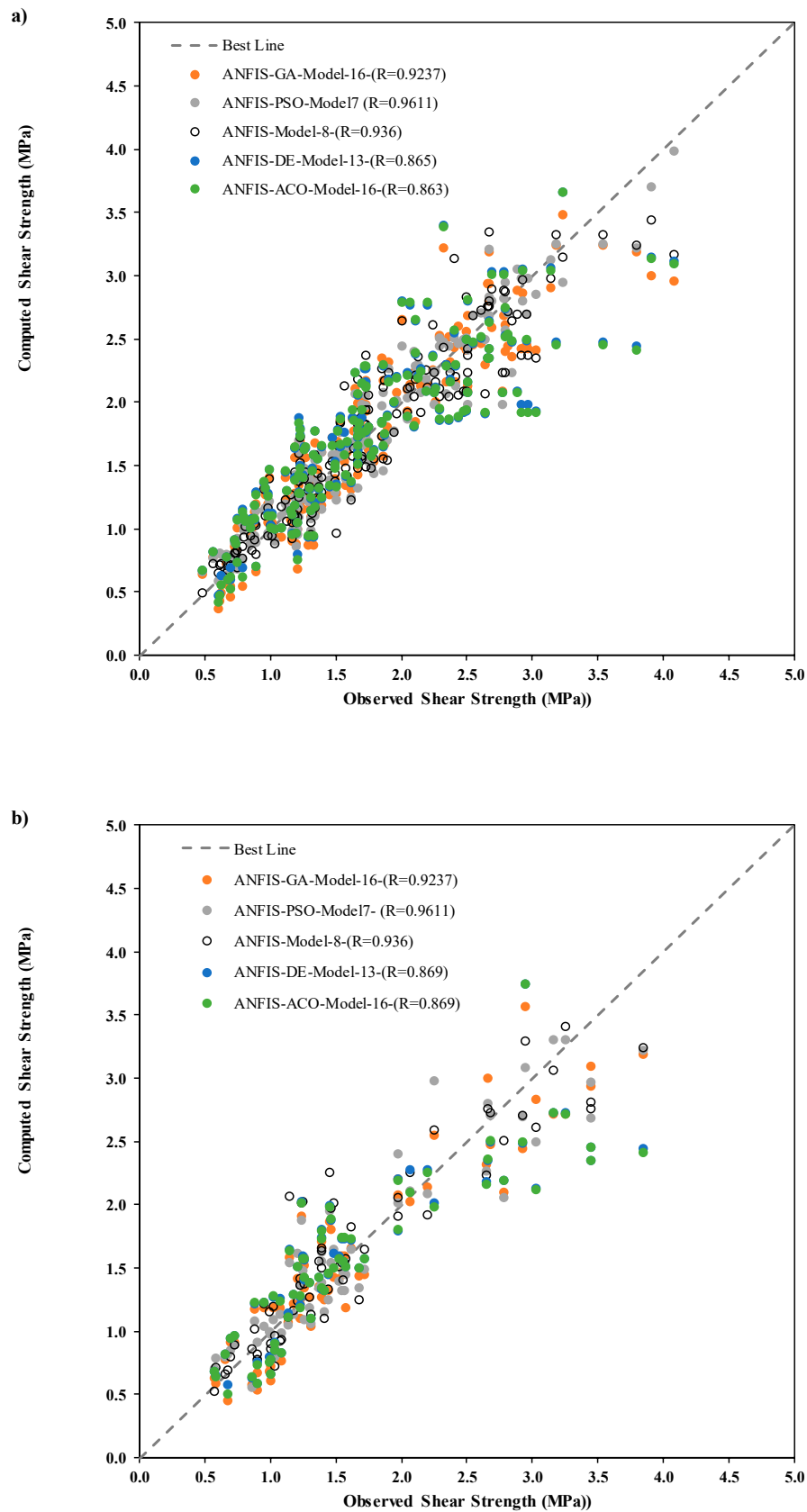
To finalize the best relation between proposed models and the performance metrics, a heat map was created, where this diagram depicts the graphical comparison between models in term of standardized performance indices. It can be seen in Figure 3 that all the standardized performance indices of ANFIS-PSO (Model-7) have a dark blue color (best performance) in both training and testing phases, while ANFIS-ACO (Model-16) appeared to be the lowest in terms of these performance metrics (dark red color).



**Figure 3.** Heat map of the applied hybrid predictive models: (a) Training stage and (b) Testing stage.

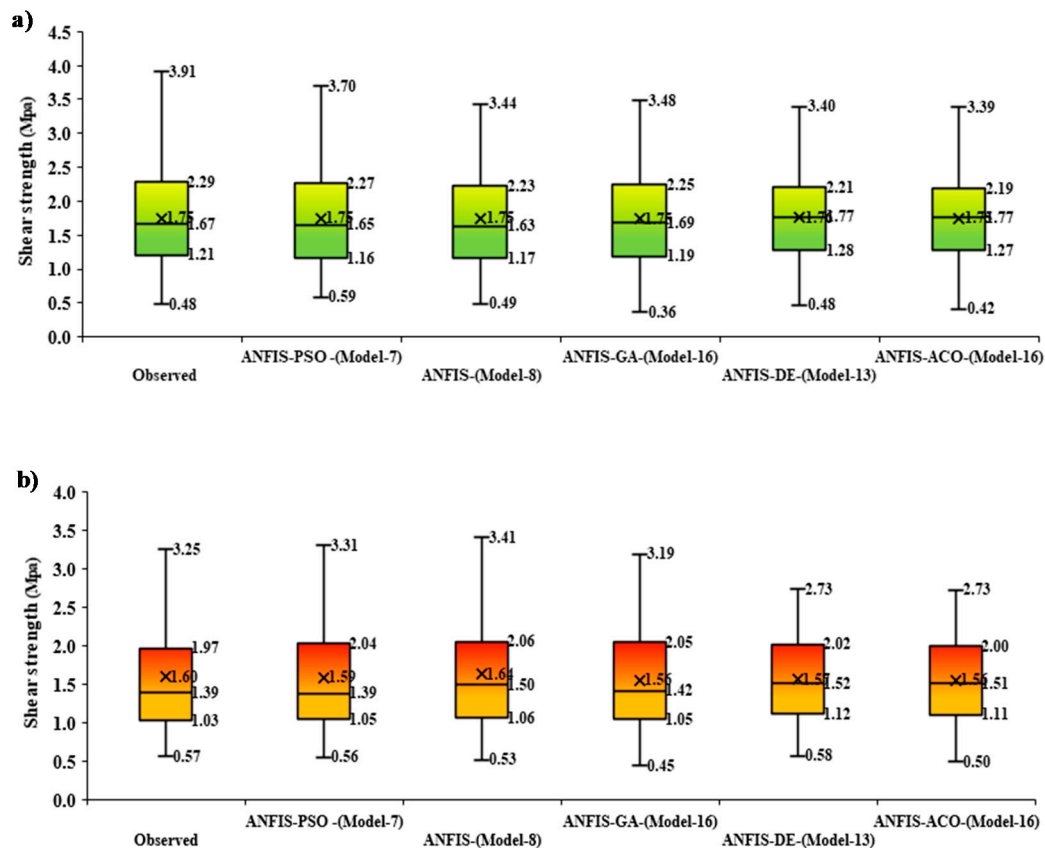
The scatter plots were generated between observed and predicted  $S_s$  for the cases of training and testing phases to strengthen the visualization of the applied model's performance accuracy with the correlation coefficient ( $R$ ) magnitude (Figure 4). The ANFIS-PSO model was revealed to have better correlation in comparison with the other applied models by achieving higher  $R$  value as follows: (ANFIS-PSO  $\approx 0.9611$ , ANFIS  $\approx 0.936$ , ANFIS-GA  $\approx 0.9237$ , ANFIS-DE  $\approx 0.865$ , ANFIS-ACO  $\approx 0.863$ ) in training phase and (ANFIS-PSO  $\approx 0.9611$ , ANFIS  $\approx 0.936$ , ANFIS-GA  $\approx 0.9237$ , ANFIS-DE  $\approx 0.869$ , ANFIS-ACO  $\approx 0.869$ ) in the testing phase.





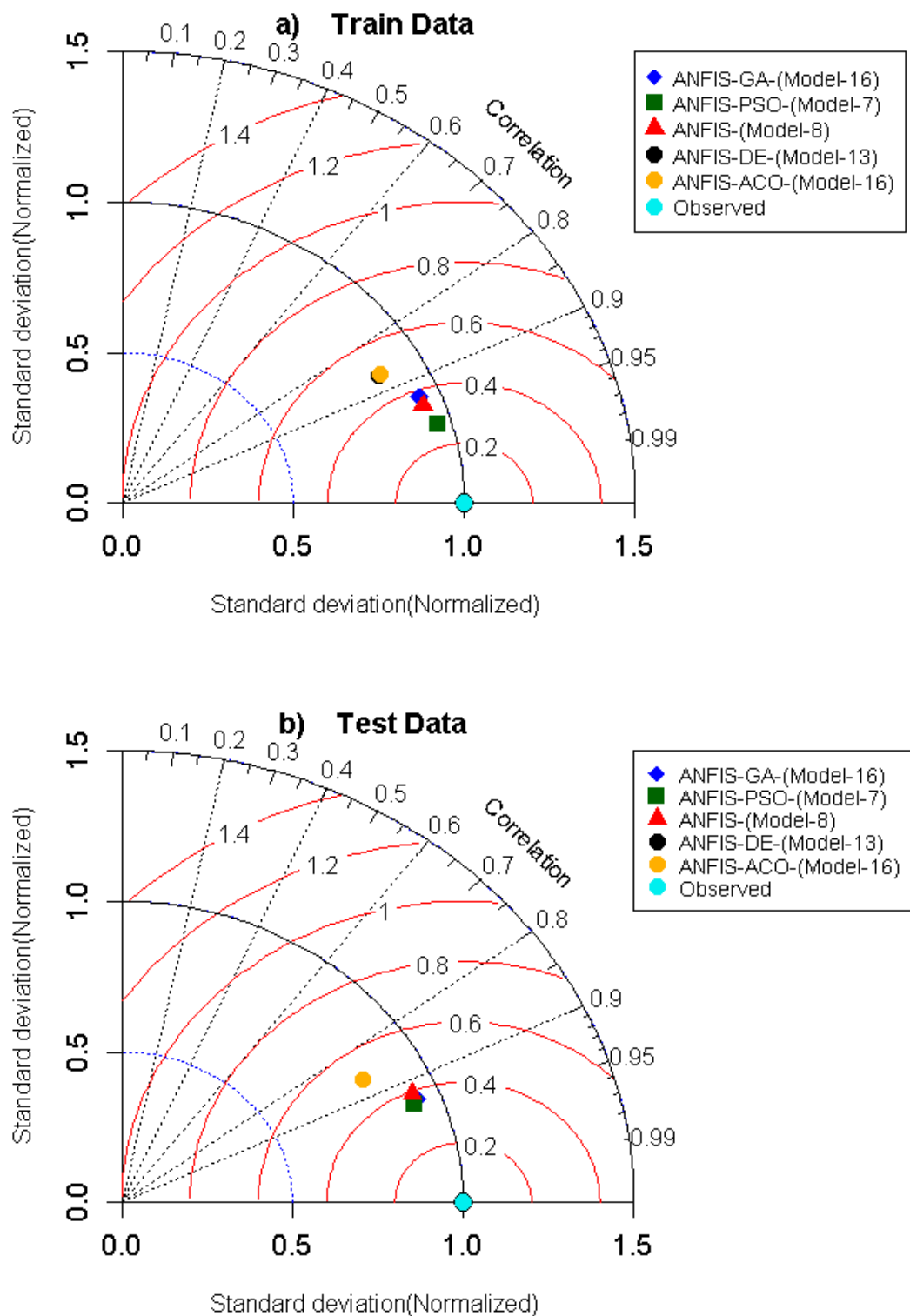
**Figure 4.** Scatter plots presentation between the observed and predicted values of computed shear strength for the best input combination and models: **(a)** Training stage and **(b)** Testing stage.

To establish the relationship of the interquartile range (IQR) between observed and predicted  $S_s$  by various proposed models, the boxplots of both training (yellow) and testing (green) phases were displayed in Figure 5. The distinction of performances is visible since the prediction was generated via ANFIS-PSO (Model-7) against observed (experimental)  $S_s$ , which were significantly accurate in comparison with ANFIS (Model-8), ANFIS-GA (Model-16), ANFIS-DE (Model-13), and ANFIS-ACO (Model-16). Hence, the boxplots, together with the benchmark models against observed  $S_s$ , ascertain the better accuracy of ANFIS-PSO model.



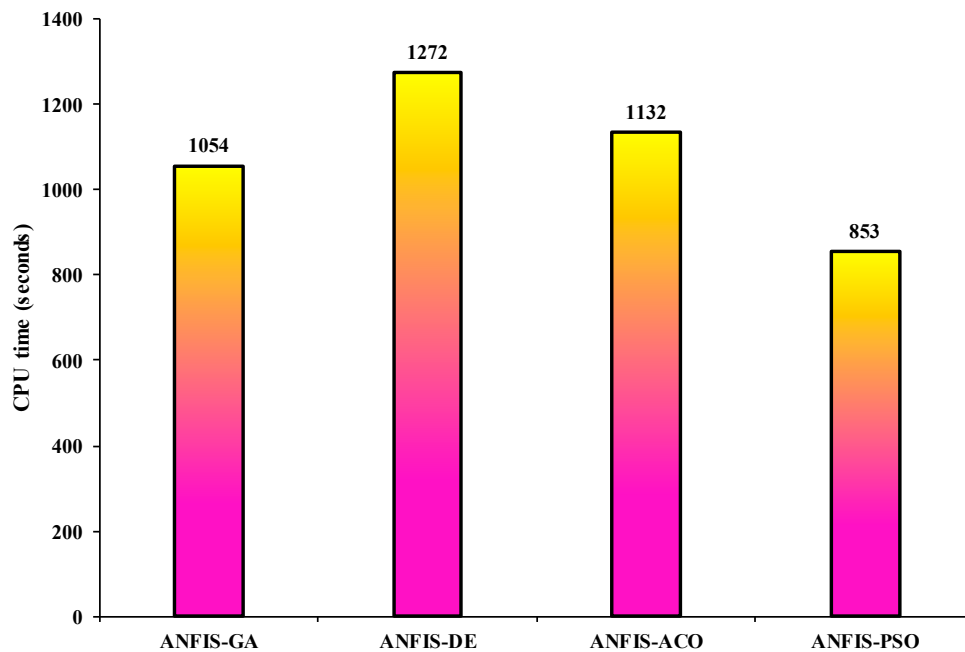
**Figure 5.** Boxplot of computed shear strength against predicted ones (a) Training stage and (b) Testing stage.

To scale the degree between predicted and experimental  $S_s$  of HSC for all proposed hybrid and standalone ANFIS models, a Taylor diagram was drawn (Figure 6). The magnitudes of correlation are shown in the form of the Taylor diagram that generates a more detailed appraisal of the model performances [101] for training and testing phases. The Taylor diagram illustrates a more tangible and convincing statistical relationship between the predicted and observed  $S_s$  depending on correlation with respect to standard deviations. It is seen that the benchmark models ANFIS-DE and ANFIS-ACO are not appropriate in the training session, as the correlation to standard deviation points was highly parted from the ideal observed point as compared to ANFIS-PSO, ANFIS, and ANFIS-GA. The hybrid ANFIS-PSO model lay close to the perfect observed point in the testing phase more closely, followed by ANFIS-GA, ANFIS, ANFI-DE, and ANFIS-ACO models, which confirms that the prediction accuracy of ANFS-PSO was reasonably higher than the benchmark models.



**Figure 6.** Normalized Taylor diagrams of predicted and observed standardized shear strength: (a) Training stage and (b) Testing stage.

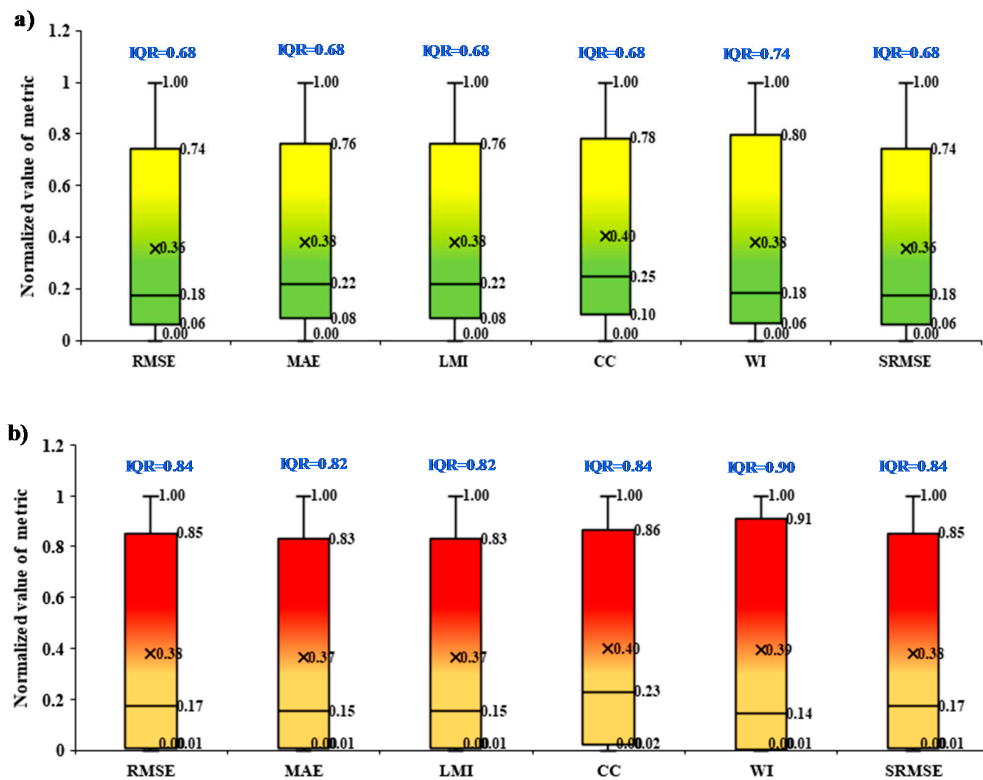
To evaluate the trade-off between the accuracy and efficiency of the newly developed models, their computational time (CPU time) is presented in Figure 7.



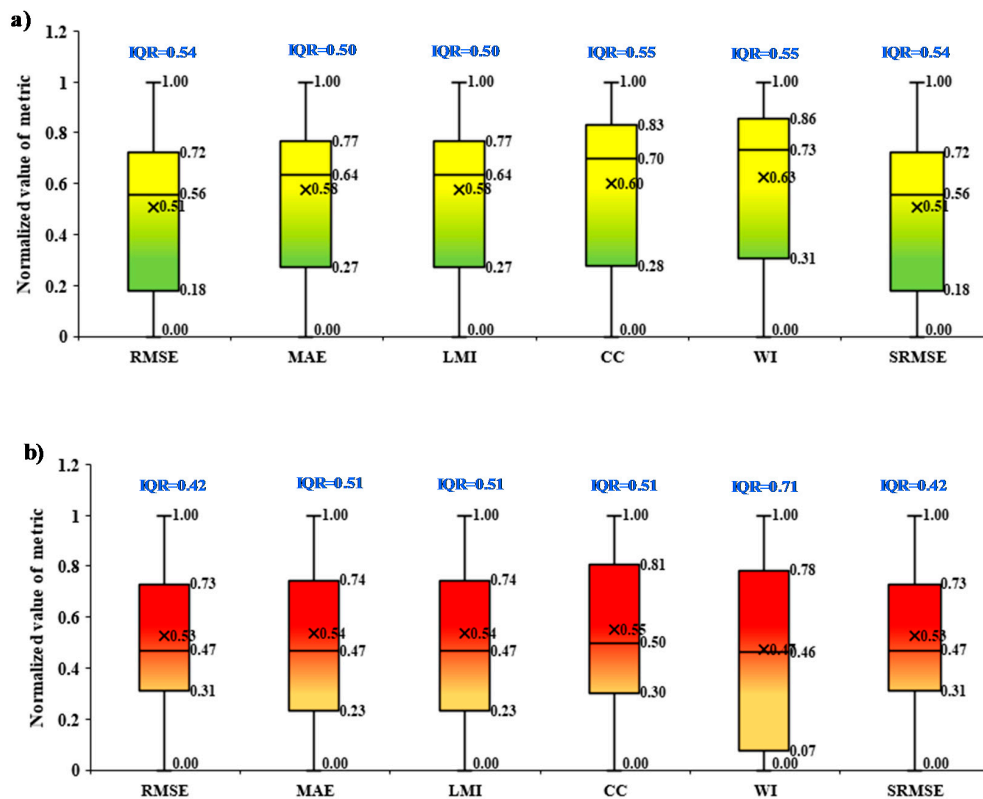
**Figure 7.** Comparison between computational time (CPU time) obtained from hybrid ANFIS models.

From Figure 7, it is evident that the lowest CPU time (853.23 s) is observed in ANFIS-PSO, while the ANFIS-DE offers the highest value (1272.06 s). The results confirm that the ANFIS-PSO model provides the highest performance prediction with most top convergence speed in comparison with other hybrid techniques.

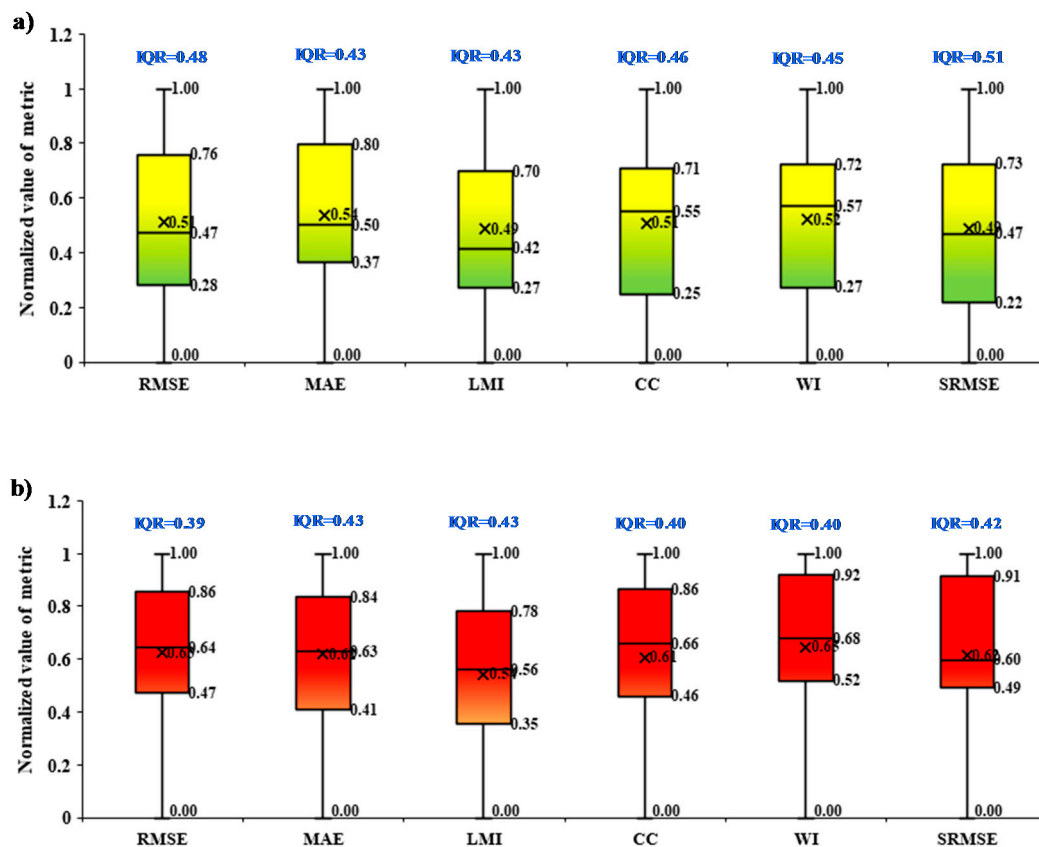
The uncertainties of model, variables, and data were evaluated on the basis of boxplots presentation based on the performance metrics over the training and testing phases at 25%, 50%, and 75% quantile together with IQR (Figure 8, 9, and 10). In the cases of the model's uncertainty based on performance metrics over the training and testing phases, the majority of the cases revealed a median value towards the 1<sup>st</sup> quartile for both training and testing phases (Figure 8). However, in the case of the training set, all performance metrics exhibited marginal higher redundant than testing phase with the average values of IQR lies at 0.68 and 0.84, respectively. In cases of variable's uncertainty based on performance metrics over the training and testing phases were exhibited the distinguished characters (Figure 9); during the training phase, the median value tends towards the 3<sup>rd</sup> quartile in most of the performance metrics. In contrast, it was mixed, tending towards the 1<sup>st</sup> quartile (for *RMSE*, *CC*, and *SRMSE*), 2<sup>nd</sup> quartile (for *MAE* and *LMI*), and 3<sup>rd</sup> quartile (for *WI*) in the testing phase. In the cases of the data's uncertainty based on performance metrics over the training and testing phases were presented mixed characteristics such as the median line of boxplot tends towards 1<sup>st</sup> quartile for *RMSE*, *MAE* and *LMI*, whereas *CC* and *WI* were opposite towards the 3<sup>rd</sup> quartile but remained almost in the middle position in case of *SRMSE* (Figure 10). However, the testing phase has demonstrated the stability, which is near the middle for all performance metrics except *WI* and *SRMSE*, which were towards the 1<sup>st</sup> quartile.



**Figure 8.** Boxplot of the model's uncertainty based on performance index over (a) Training stage and (b) Testing stage.



**Figure 9.** Boxplot of variable's uncertainty based on performances index over (a) Training stage and (b) Testing stage.



**Figure 10.** Boxplot of data's uncertainty based on indices over (a) Training stage and (b) Testing stage.

The aptness of the hybrid and standalone ANFIS models using different input combinations (Model-1, Model-2 ... Model-18) to predict  $S_s$  was explored in this paper. The accuracy of the hybrid ANFIS-PSO with input combination (Model-7) was reasonably superior to the other models (i.e., ANFIS-ACO, ANFIS-GA, ANFIS-DE, and ANFIS) with different combinations of inputs (Tables 2–6), demonstrating that the ANFIS-PSO was a well-designed algorithm to extract pertinent features for  $S_s$  prediction. The precision of ANFIS-PSO with other algorithms revealed that the different input combinations were also advantageous in indicating the pertinent features making the model parsimonious.

Since the fundamental operations of the AI models of machine learning are significantly contingent upon the patterns in historical datasets that can substantially disturb the learning strategy, the results here assured the suitability of input combinations to sort out the best combination capturing minimum pertinent features and characteristics. Prior to the prediction process, several input combinations are constructed using related physical properties. The  $S_s$  of the HSC slender beams was predicted using two different modeling scenarios based on (i) non-processed (initial) dataset (NP) (i.e., Model-1, Model-2, ... , Model-6) and (ii) pre-processed dataset (PP) (i.e., Model-7, Model-8, ... , Model-18). This was to examine the influence of the non-homogeneity of the dataset on model prediction accuracy. Apparently, the PP data were excellent data cleaning prior to the model's construction. This is due to the fact that some redundant measures associated with some error can influence the learning process, which leads to poor predictability capacity.

Based on the attained modeling results, a couple limitations are observed, which are worth to be highlighted for future research. The investigated computer aid model's performance can be inspected based on the changes in the type of aggregated consideration and evaluating the weight of the interlock strength of the total shear strength. Besides, this is clear, noting that the impact of high strength beam was reported successfully. However, the impact of normal beam shear strength could be a



prospective objective. Further, the lateral stability of the slender beam can be investigated, which is totally dependent upon the data availability of the experiments.

#### 4. Conclusions

A contemporary AI model established the prediction of the shear strength of HSC slender beam. The efficiencies of several optimization algorithms (ACO, DE, GA, and PSO) were reported along with pre-processed and non-processed data modeling scenarios. Those modeling scenarios were investigated for the possibility to enhance the prediction accuracy of the applied predictive models. Among all the optimization algorithms, PSO showed the best optimizer for the current intensive dataset in case of pre-processed variables ( $d$ ,  $a$ ,  $a_g$ ,  $fc$ , and  $\rho$ ) (excluding  $a/d$  and  $a_g/d$ ) as depicted by the performance metrics such as  $R = 0.9611$ ;  $RMSE = 0.206$ ;  $MAE = 0.157$ ;  $CC = 0.961$ ;  $WI = 0.980$ . The IQR characteristic of the dataset between the observed and predicted  $S_s$  using ANFIS-PSO exhibited significant similarity. It is clearly visible that the selected pre-processed data alleviate the performance of the hybrid model remarkably. There is need for a prospective study where a lesser exploratory data analysis (EDA) process along with a homogeneous large dataset, with or without a pre-processed dataset, might achieve the best prediction accuracy using the proposed hybrid AI model. In the case in which the performance does maintain a stable result for the non-monotonous IQR dataset, there is a possible prospective study objective to use more derivative data from the primary character of  $S_s$  for another either HSC or medium strength concrete.

**Author Contributions:** Conceptualization, Z.M.Y., A.S., and N.A.-A.; data curation, A.S.; formal analysis, Z.M.Y., M.S.A., M.H.M., A.W.A.Z., M.A., and S.K.B.; investigation, Z.M.Y., M.H., M.S.A., M.H.M., A.W.A.Z., M.A., and N.A.-A.; methodology, A.S. and M.H.; project administration, Z.M.Y.; software, A.S. and M.H.; supervision, Z.M.Y. and N.A.-A.; validation, Z.M.Y., A.S., M.S.A., M.H.M., A.W.A.Z., M.A., and N.A.-A.; visualization, Z.M.Y., M.S.A., M.H.M., A.W.A.Z., and S.K.B.; writing—original draft, Z.M.Y., A.S., M.H., M.S.A., M.H.M., A.W.A.Z., M.A., S.K.B., and N.A.-A.; writing—review and editing, Z.M.Y., A.S., A.W.A.Z., and N.A.-A. All authors have read and agreed to the published version of the manuscript.

**Funding:** This research received no external funding.

**Conflicts of Interest:** The authors declare no conflict of interest.

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