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# A Semi-Discretization Method Based on Finite Difference and Differential Transform Methods to Solve the Time-Fractional Telegraph Equation 

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#### Abstract

The telegraph equation is a hyperbolic partial differential equation that has many applications in symmetric and asymmetric problems. In this paper, the solution of the time-fractional telegraph equation is obtained using a hybrid method. The numerical simulation is performed based on a combination of the finite difference and differential transform methods, such that at first, the equation is semi-discretized along the spatial ordinate, and then the resulting system of ordinary differential equations is solved using the fractional differential transform method. This hybrid technique is tested for some prominent linear and nonlinear examples. It is very simple and has a very small computation time; also, the obtained results demonstrate that the exact solutions are exactly symmetric with approximate solutions. The results of our scheme are compared with the twodimensional differential transform method. The numerical results show that the proposed method is more accurate and effective than the two-dimensional fractional differential transform technique. Also, the implementation process of this method is very simple, so its computer programming is very fast.


Keywords: time-fractional telegraph equation; finite difference method; fractional differential transform method; convergence

JEL Classification: 26A33; 35R11; 35Q60; 65M06

## 1. Introduction

The differential transform method (DTM) is an iterative method based on Taylor's series. DTM has been used to solve various differential equations. It was first applied to solve electrical circuit problems. After that, it was used to solve ordinary differential equations (ODEs), partial differential equations (PDEs), fuzzy PDEs, fractional-order ODEs and PDEs, systems of ODEs, systems of PDEs, differential-algebraic equations, and eigenvalue problems [1-7]. Additionally, fractional DTM, which is based on a generalized Taylor's series, has been applied to solve various differential, differential-algebraic, and integral equations of fractional order [8-14]. In this paper, we intend to apply a combination of the finite difference (FD) and fractional differential transform (FDT) methods (FD-FDTM) to solve the one-dimensional time-fractional telegraph equation (FTE).

We consider the FTE in the following form [15-17]:

$$
\begin{equation*}
\frac{\partial^{2 \gamma} v(x, t)}{\partial t^{2 \gamma}}+2 \lambda \frac{\partial^{\gamma} v(x, t)}{\partial t^{\gamma}}+\mu v(x, t)=v \frac{\partial^{2} v(x, t)}{\partial x^{2}}+q(x, t), a<x<b, t \geq 0, \tag{1}
\end{equation*}
$$

with initial conditions

$$
\begin{equation*}
v(x, 0)=f_{1}(x), v_{t}(x, 0)=f_{2}(x), a<x<b \tag{2}
\end{equation*}
$$

and boundary conditions

$$
\begin{equation*}
v(a, t)=g_{1}(t), v(b, t)=g_{2}(t), t \geq 0 \tag{3}
\end{equation*}
$$

where $0<\gamma<1, \lambda, \mu$, and $v$ are arbitrary positive constants and $f_{1}, f_{2}, g_{1}$, and $g_{2}$ are known functions.

Also, $\frac{\partial^{2 \gamma} v(x, t)}{\partial t^{2 \gamma}}$ and $\frac{\partial^{\gamma} v(x, t)}{\partial t^{\gamma}}$ denote the Caputo fractional derivative of order $2 \gamma$ and $\gamma$, respectively. The $\gamma$-order Caputo fractional derivative of the function $f$ for $\gamma>0, n-1<\gamma<n$, is defined as follows:

$$
D_{0}^{\gamma} f(x)=\frac{1}{\Gamma(n-\gamma)} \int_{0}^{x}(x-t)^{n-\gamma-1} f^{(n)}(t) d t
$$

The telegraph equation is a hyperbolic PDE that has many applications in physics and engineering, for example, in signal analysis, random walk theory, anomalous diffusion processes, wave phenomena, and wave propagation of the electrical signal in the cable of a transmission line. Different numerical and analytical techniques have been used to solve fractional-order telegraph equations [15-33].

This work aims to obtain an approximate solution to the FTE (1) using a hybrid method. In 2008, a hybrid method based on the combination of DTM and FDM was presented to solve a nonlinear heat conduction differential equation [34]. Also, in 2012, some nonlinear PDEs were solved with the hybrid method [35]. Arsalan (2020) applied a hybrid scheme to solve the one-dimensional integer-order telegraph equations [36,37].

We organize the rest of the paper as follows. In Section 2, we present the FDTM and related theorems. We propose our hybrid method to solve FTE in Section 3 and prove its convergence in Section 4. Also, in Section 5, we give some examples and solve them with the proposed method, we draw a conclusion in Section 6.

## 2. Fractional Differential Transform Method

The fractional differential transform method (or generalized differential transform method) is based on the fractional Taylor's formula. The $\alpha$-order fractional Taylor expansion of function $u(t)$ about point $t=t_{0}$ is defined as [38]

$$
\begin{equation*}
u(t)=\left.\sum_{k=0}^{\infty} \frac{\left(t-t_{0}\right)^{k \alpha}}{\Gamma(k \alpha+1)}\left(\frac{d^{\alpha}}{d t^{\alpha}}\right)^{k} u(t)\right|_{t=t_{0}} \tag{4}
\end{equation*}
$$

where $\frac{d^{\alpha}}{d t^{\alpha}}$ is the $\alpha$-order Caputo fractional derivative and $\left(\frac{d^{\alpha}}{d t^{\alpha}}\right)^{k}=\underbrace{\frac{d^{\alpha}}{d t^{\alpha}} \cdots \frac{d^{\alpha}}{d t^{\alpha}}}_{k-\text { times }}$.
The $\alpha$-order FDT of the function $u(t)$ about $t=t_{0}$ is denoted by $U^{\alpha}(k)$ and defined as $U^{\alpha}(k)=\left.\frac{1}{\Gamma(k \alpha+1)}\left(\frac{d^{\alpha}}{d t^{\alpha}}\right)^{k} u(t)\right|_{t=t_{0}}$, and the inverse transform is $u(t)=\sum_{k=0}^{\infty} U^{\alpha}(k)(t-$ $\left.t_{0}\right)^{k \alpha}$ [9]. Therefore, at $t=0$, we have

$$
\begin{equation*}
u(t)=\sum_{k=0}^{\infty} U^{\alpha}(k) t^{k \alpha}=\sum_{k=0}^{\infty} \varphi_{k}(t) \tag{5}
\end{equation*}
$$

where $\varphi_{k}(t)=U^{\alpha}(k) t^{k \alpha}$.
Also, the $m$-approximation fractional differential transform of $u(t)$ is defined as

$$
U^{m}(t)=\sum_{k=0}^{m} U^{\alpha}(k) t^{k \alpha}=\sum_{k=0}^{m} \varphi_{k}(t) .
$$

Theorem 1 ([39]). Suppose that $F^{\alpha}(k), G^{\alpha}(k)$, and $H^{\alpha}(k)$ are the differential transformations of the functions $f(t), g(t)$, and $h(t)$, respectively. Then we have
(a) if $f(t)=g(t) \pm h(t)$, then $F^{\alpha}(k)=G^{\alpha}(k) \pm H^{\alpha}(k)$,
(b) if $f(t)=\left(t-t_{0}\right)^{q}$, then $F^{\alpha}(k)=\delta\left(k-\frac{q}{\alpha}\right)$, where $\delta(k)= \begin{cases}1, & \text { if } k=0 \\ 0 . & \text { if } k \neq 0\end{cases}$
(c) if $f(t)=g(t) h(t)$, then $F^{\alpha}(k)=\sum_{l=0}^{k} G^{\alpha}(l) H^{\alpha}(k-l)$,

Theorem 2 ([39]). Suppose that $f(t)=t^{\lambda} g(t)$, where $\lambda>-1$ and $g(t)$ has the generalized power series expansion $g(t)=\sum_{n=0}^{\infty} a_{n}\left(t-t_{0}\right)^{n \alpha}$ with radius of convergence $R>0,0<\alpha \leq 1$. Then

$$
D_{a}^{\gamma} D_{a}^{\beta} f(t)=D_{a}^{\gamma+\beta} f(t),
$$

for all $t \in(0, R)$ if:
(a) $\beta<\lambda+1$ and $\alpha$ arbitrary or
(b) $\quad \beta \geq \lambda+1, \gamma$ arbitrary, and $a_{k}=0$ for $k=0,1, \ldots, m-1$, where $m-1<\beta \leq m$.

Theorem 3 ([39]). If $f(t)=D_{t_{0}}^{\gamma} g(t), m-1<\gamma \leq m$, and the function $g(t)$ satisfies the conditions in theorem (2), then

$$
F^{\alpha}(k)=\frac{\Gamma(k \alpha+\gamma+1)}{\Gamma(k \alpha+1)} G^{\alpha}\left(k+\frac{\gamma}{\alpha}\right) .
$$

## 3. FD-FDTM for Solving the FTE

Consider the FTE (1). If the $x$-derivative at $(x, t)$ is replaced by $\frac{1}{h^{2}}\{v(x-h, t)-$ $2 v(x, t)+v(x+h, t)\}+O\left(h^{2}\right)$ and $x$ is considered as a constant, Equation (1) can be written as the following ordinary differential equation
$\frac{d^{2 \gamma} v(t)}{d t^{2 \gamma}}+2 \lambda \frac{d^{\gamma} v(t)}{d t^{\gamma}}+\mu v(t)=v \frac{1}{h^{2}}\{v(x-h, t)-2 v(x, t)+v(x+h, t)\}+O\left(h^{2}\right)+q(x, t)$.
We subdivide the interval $[a, b]$ into $N$ equal subintervals of step-length $h=\frac{b-a}{N}$. Thus, the mesh points $x_{i}=a+i h, i=0,1, \ldots, N$ are obtained. Now, we write Equation (6) at the mesh point $x_{i}, i=1, \ldots, N-1$, along with time level $t$. If we discard the local truncation error $O\left(h^{2}\right)$ and denote $u_{i}(t)$ as the approximate solution of $v_{i}(t)=v\left(x_{i}, t\right)$, we have the following system of ODEs:

$$
\begin{equation*}
\frac{d^{2 \gamma} u_{i}(t)}{d t^{2 \gamma}}+2 \lambda \frac{d^{\gamma} u_{i}(t)}{d t \gamma}+\mu u_{i}(t)=\frac{v}{h^{2}}\left\{u_{i-1}(t)-2 u_{i}(t)+u_{i+1}(t)\right\}+q_{i}(t), i=1, \ldots, N-1 . \tag{7}
\end{equation*}
$$

We solve the system (7) using FDTM. For this purpose, we consider the solution of equation, $u_{i}(t)$, as follows:

$$
\begin{equation*}
u_{i}(t)=\sum_{k=0}^{\infty} U_{i}^{\alpha}(k) t^{k \alpha} \tag{8}
\end{equation*}
$$

where the unknown coefficients $U_{i}^{\alpha}(k)$ are the FDT of $u_{i}(t)$ and should be obtained.
By choosing a suitable value for $\alpha$, assuming $q_{i}^{\alpha}(k)$ as the $\alpha$-fractional differential transform of $q_{i}(t)$, and by using Theorems 2 and 3 , the fractional differential transform of Equation (7) leads to the following relation:

$$
\begin{array}{r}
\frac{\Gamma(k \alpha+2 \gamma+1)}{\Gamma(k \alpha+1)} U_{i}^{\alpha}\left(k+\frac{2 \gamma}{\alpha}\right)+2 \lambda \frac{\Gamma(k \alpha+\gamma+1)}{\Gamma(k \alpha+1)} U_{i}^{\alpha}\left(k+\frac{\gamma}{\alpha}\right)+\mu U_{i}^{\alpha}(k)= \\
\frac{v}{h^{2}}\left\{U_{i-1}^{\alpha}(k)-2 U_{i}^{\alpha}(k)+U_{i+1}^{\alpha}(k)\right\}+q_{i}^{\alpha}(k) . \tag{9}
\end{array}
$$

Now, suppose that $G_{1}^{\alpha}(k)$ and $G_{2}^{\alpha}(k)$ are the fractional differential transforms of the functions $g_{1}(t)$ and $g_{2}(t)$, respectively. Therefore, by applying the FDTM to conditions (2) and (3), we have the initial conditions

$$
\begin{align*}
U_{i}^{\alpha}(0) & =f_{1}\left(x_{i}\right) \\
U_{i}^{\alpha}\left(\frac{1}{\alpha}\right) & =f_{2}\left(x_{i}\right) \tag{10}
\end{align*}
$$

and the boundary conditions

$$
\begin{align*}
U_{0}^{\alpha}(k) & =G_{1}^{\alpha}(k)  \tag{11}\\
U_{N}^{\alpha}(k) & =G_{2}^{\alpha}(k)
\end{align*}
$$

We rewrite relations (9)-(11) as follows:

$$
\begin{align*}
& U_{i}^{\alpha}\left(k+\frac{2 \gamma}{\alpha}\right)=\frac{\Gamma(k \alpha+1)}{\Gamma(k \alpha+2 \gamma+1)}\left[v \frac{U_{i-1}^{\alpha}(k)-2 U_{i}^{\alpha}(k)+U_{i+1}^{\alpha}(k)}{h^{2}}-\mu U_{i}^{\alpha}(k)+q_{i}^{\alpha}(k)\right] \\
&-2 \lambda \frac{\Gamma(k \alpha+\gamma+1)}{\Gamma(k \alpha+2 \gamma+1)} U_{i}^{\alpha}\left(k+\frac{\gamma}{\alpha}\right), \quad \forall k \geq 0  \tag{12}\\
& U_{i}^{\alpha}(0)=f_{1}(i h), \\
& U_{i}^{\alpha}\left(\frac{1}{\alpha}\right)=f_{2}(i h),  \tag{13}\\
& U_{0}^{\alpha}(k)=G_{1}^{\alpha}(k),  \tag{14}\\
& U_{N}^{\alpha}(k)=G_{2}^{\alpha}(k) .
\end{align*}
$$

Also, according to [9], the unknown coefficients $U_{i}^{\alpha}(1), U_{i}^{\alpha}(2), \ldots, U_{i}^{\alpha}\left(\frac{2 \gamma}{\alpha}-1\right)$, will be available as follows:

$$
U_{i}^{\alpha}(k)=\left\{\begin{array}{lll}
\frac{1}{\Gamma(k \alpha+1)}\left[\frac{d^{k \alpha}}{d t^{k \alpha}} u_{i}(t)\right]_{t=0}, & \text { if } & k \alpha \in \mathbb{Z}^{+}  \tag{15}\\
0, & \text { if } & k \alpha \notin \mathbb{Z}^{+}
\end{array} \quad \forall k=0,1, \ldots\left(\frac{2 \gamma}{\alpha}-1\right) .\right.
$$

Therefore, all the unknown coefficients $U_{i}^{\alpha}(k), i=0,1,2, \ldots, N, \forall k \geq 0$ are calculated according to the recursive formula (12) and relations (13)-(15).

## 4. Convergence of FD-FDTM for FTE

Here, we discuss the convergence of FD-FDTM for solving the FTE (1). First, we present the following lemma [40].

Lemma 1. Suppose that for some $k_{0} \in \mathbb{N}_{0}$ and for every $j \geq k_{0}$, there exist $0<\delta_{j}<1$ such that $\left\|\varphi_{j+1}\right\| \leq \delta_{j+1}\left\|\varphi_{j}\right\|,\left(\left\|\varphi_{j}\right\|=\max _{t}\left|\varphi_{j}(t)\right|\right)$. Then the series $\sum_{k=0}^{\infty} \varphi_{k}(t)$ converges to $u(t)$.

Proof. Consider the sequence $s_{0}, s_{1}, s_{2}, \ldots$, where $s_{n}=\sum_{k=0}^{n} \varphi_{k}(t)$. To prove the lemma, we show the sequence $s_{n}$ is a Cauchy sequence in $\left(C[[0,1]],\|\cdot\|_{\infty}\right)$.

For $0<\delta_{j}<1$, we can write

$$
\left\|s_{j}-s_{j-1}\right\|=\left\|\varphi_{j}\right\| \leq \delta_{j}\left\|\varphi_{j-1}\right\| \leq \delta_{j} \delta_{j-1}\left\|\varphi_{j-2}\right\| \leq \ldots \leq \delta_{j} \delta_{j-1} \ldots \delta_{k_{0}}\left\|\varphi_{k_{0}}\right\|
$$

Thus, for $n \geq m \geq k_{0}$, we have

$$
\left\|s_{n}-s_{m}\right\|=\left\|\sum_{j=m+1}^{n}\left(s_{j}-s_{j-1}\right)\right\| \leq \sum_{j=m+1}^{n}\left\|s_{j}-s_{j-1}\right\| \leq \sum_{j=m+1}^{n} \delta_{j} \delta_{j-1} \ldots \delta_{k_{0}}\left\|\varphi_{k_{0}}\right\|,
$$

If we let $\delta=\max \left\{\delta_{k_{0}}, \delta_{k_{0}+1}, \ldots, \delta_{m}, \delta_{m+1}, \ldots, \delta_{n}\right\}$, the following relation is obtained:

$$
\begin{equation*}
\left\|s_{n}-s_{m}\right\| \leq \sum_{j=m+1}^{n} \delta^{j-k_{0}+1}\left\|\varphi_{k_{0}}\right\| \leq\left\|\varphi_{k_{0}}\right\| \delta^{m-k_{0}+2}\left[1+\delta+\delta^{2}+\cdots+\delta^{n-m-1}\right]=\frac{1-\delta^{n-m}}{1-\delta} \delta^{m-k_{0}+2}\left\|\varphi_{k_{0}}\right\| \tag{16}
\end{equation*}
$$

Since $0 \leq \delta<1$, we can derive $\lim _{n, m \rightarrow \infty}\left\|s_{n}-s_{m}\right\|=0$, which means $\left\{s_{n}\right\}_{n=0}^{\infty}$ is a Cauchy sequence in $\left(C[I],\|.\|_{\infty}\right)$. Since the space $C[I]$ with $\|.\|_{\infty}$ is a Banach space, we can derive that the series $\sum_{k=0}^{\infty} \varphi_{k}(t)$ is convergent to $u(t)$.

Theorem 4. Suppose that $v\left(x_{i}, t\right)$ is the exact solution of the FTE at point $\left(x_{i}, t\right), u_{i}(t)$ is the exact solution of Equation (7), and $U_{i}^{m}(t)=\sum_{k=0}^{m} \varphi_{k}(t)$, is the m-approximation of $u_{i}(t)$ as the approximate solution of FTE at point $\left(x_{i}, t\right)$. Also, suppose for some $k_{0} \in \mathbb{N}_{0}$ and for every $n \geq m \geq k_{0}, \exists 0<\delta_{i}<1$, such that $\left\|\varphi_{i+1}\right\| \leq \delta_{i+1}\left\|\varphi_{i}\right\|$, where $\left\|\varphi_{i}\right\|=\max _{t}\left|\varphi_{i}(t)\right|$. Then the solution $U_{i}^{m}(t)$ converges to the exact solution, $v_{i}(t)$, as $m \rightarrow \infty$. Furthermore, for some $a<\xi<b$ the maximum absolute error of the m-series, $U_{i}^{m}(t)$, as an approximation of the FTE's exact solution satisfies the following relation:

$$
\left\|v\left(x_{i}, t\right)-U_{i}^{m}(t)\right\| \leq \frac{h^{2}}{12} \frac{\partial^{4} u(\xi, t)}{\partial x^{4}}+\frac{1}{1-\delta} \delta^{m-k_{0}+2}\left\|\varphi_{k_{0}}\right\|,
$$

where $\delta=\max \left\{\delta_{k_{0}}, \delta_{k_{0}+1}, \ldots, \delta_{n}\right\}$.
Proof. We can write

$$
\begin{equation*}
\left\|v\left(x_{i}, t\right)-U_{i}^{m}(t)\right\|=\left\|v\left(x_{i}, t\right)-u_{i}(t)+u_{i}(t)-U_{i}^{m}(t)\right\| \leq\left\|v\left(x_{i}, t\right)-u_{i}(t)\right\|+\left\|u_{i}(t)-U_{i}^{m}(t)\right\|, \tag{17}
\end{equation*}
$$

where $v\left(x_{i}, t\right)$ and $u_{i}(t)$ are the solutions of Equations (6) and (7), respectively.
Also, Equation (6) has been obtained by replacing the second $x$-derivative of $v(x, t)$ with the central FD formula in Equation (1). Therefore, for some $a<\xi<b$ we can write

$$
\begin{equation*}
\left\|v\left(x_{i}, t\right)-u_{i}(t)\right\| \leq \frac{h^{2}}{12} \frac{\partial^{4} u(\xi, t)}{\partial x^{4}} \tag{18}
\end{equation*}
$$

From relation (16), for $n \geq m \geq k_{0}$, we have

$$
\left\|s_{n}-s_{m}\right\| \leq \frac{1-\delta^{n-m}}{1-\delta} \delta^{m-k_{0}+2}\left\|\varphi_{k_{0}}\right\|
$$

and since $0 \leq \delta<1$, then $1-\delta^{n-m}<1$, so we have

$$
\left\|s_{n}-s_{m}\right\| \leq \frac{1}{1-\delta} \delta^{m-k_{0}+2}\left\|\varphi_{k_{0}}\right\|
$$

If $n$ approaches $\infty$, then $s_{n} \rightarrow u_{i}(t)$ and we have

$$
\left\|u_{i}(t)-s_{m}\right\| \leq \frac{1}{1-\delta} \delta^{m-k_{0}+2}\left\|\varphi_{k_{0}}\right\|
$$

in the other words,

$$
\begin{equation*}
\left\|u_{i}(t)-U_{i}^{m}(t)\right\| \leq \frac{1}{1-\delta} \delta^{m-k_{0}+2}\left\|\varphi_{k_{0}}\right\| \tag{19}
\end{equation*}
$$

By replacing relations (18) and (19) in relation (17), the theorem is proved.

## 5. Numerical Examples

In this section, we give some examples to show the efficiency and convenience of the mentioned method. The examples include linear and non-linear FTEs. We present the results of FD-FDTM for solving the examples and calculate the maximum absolute error (MAE) for different values of $N$ using the following formula:

$$
E(N)=\max _{1 \leq i \leq N}\left|v\left(x_{i}, t\right)-U_{i}^{m}(t)\right| .
$$

Also, we compare the results of FD-FDTM with two-dimensional FDTM (2D-FDTM). Moreover, we obtain the rate of convergence (ROC) of FD-FDTM with the following formula:

$$
R O C=\log _{2}\left(\frac{E(N)}{E(2 N)}\right)
$$

Example 1. Consider the following linear FTE [30]:

$$
\begin{equation*}
\frac{\partial^{2 \gamma} v(x, t)}{\partial t^{2 \gamma}}+2 \frac{\partial^{\gamma} v(x, t)}{\partial t^{\gamma}}+v(x, t)=\frac{\partial^{2} v(x, t)}{\partial x^{2}}, 0<\gamma<1,0<x<1, t>0, \tag{20}
\end{equation*}
$$

with the following conditions

$$
\begin{align*}
& v(x, 0)=e^{x}, v_{t}(x, 0)=-2 e^{x}  \tag{21}\\
& v(0, t)=e^{-2 t}, v(1, t)=e^{1-2 t} \tag{22}
\end{align*}
$$

which has the exact solution $v(x, t)=e^{x-2 t}$ for $\gamma=1$.
We describe the mentioned method to solve Equations (20)-(22) for $\gamma=0.75, \alpha=0.25$, and $h=0.1(N=10)$. Using Theorem 3, we can obtain the differential transform of the derivatives in Equation (20) as follows:

$$
\begin{aligned}
\frac{\partial^{1.5} v(x, t)}{\partial t^{1.5}} & \rightarrow \frac{\Gamma(0.25 k+2.5)}{\Gamma(0.25 k+1)} U_{i}^{0.25}(k+6) \\
\frac{\partial^{0.75} v}{\partial t^{0.75}} & \rightarrow \frac{\Gamma(0.25 k+1.75)}{\Gamma(0.25 k+1)} U_{i}^{0.25}(k+3), \\
v(x, t) & \rightarrow U_{i}^{0.25}(k), \\
\frac{\partial^{2} v}{\partial x^{2}} & \rightarrow \frac{U_{i-1}^{0.25}(k)-2 U_{i}^{0.25}(k)+U_{i+1}^{0.25}(k)}{h^{2}} .
\end{aligned}
$$

According to relation (13), for the initial conditions we have

$$
\begin{aligned}
v(x, 0)=e^{x} \rightarrow U_{i}^{0.25}(0) & =e^{x_{i}}, \forall i=0,1, \ldots, 10, \\
v_{t}(x, 0)=-2 e^{x} \rightarrow U_{i}^{0.25}(4) & =-2 e^{x_{i}}, \forall i=0,1, \ldots, 10,
\end{aligned}
$$

and according to relation (15), we have

$$
U_{i}^{0.25}(1)=U_{i}^{0.25}(2)=U_{i}^{0.25}(3)=U_{i}^{0.25}(5)=0, \forall i=0,1,2, \ldots, 10 .
$$

Also, we use relation (14) for the boundary conditions, and for the right side of these relations, we use the FDT of the $e^{-2 t}, e^{1-2 t}$ functions, so we obtain

$$
\left.\begin{array}{l}
v(0, t)=e^{-2 t} \rightarrow U_{0}^{0.25}(k)=\left\{\begin{array}{lll}
\frac{(-2) \frac{k}{4}}{\Gamma\left(\frac{k}{4}+1\right)}, & \text { if } & \frac{k}{4} \in \mathbb{Z}^{+} \\
0 . & \text { if } & \frac{k}{4} \notin \mathbb{Z}^{+}
\end{array} \quad \forall k \geq 0\right.
\end{array}\right\} \begin{array}{llll}
e \times \frac{(-2) \frac{k}{4}}{\Gamma\left(\frac{k}{4}+1\right)}, & \text { if } & \frac{k}{4} \in \mathbb{Z}^{+} \\
v(1, t)=e^{1-2 t} \rightarrow U_{10}^{0.25}(k)=\{ & \text { if } & \frac{k}{4} \notin \mathbb{Z}^{+}
\end{array}
$$

By replacing the above relations in Equation (20), we obtain the following recursive relationship:

$$
\begin{aligned}
U_{i}^{0.25}(k+6)=\frac{\Gamma(0.25 k+1)}{\Gamma(0.25 k+2.5)} & {\left[\frac{U_{i-1}^{0.25}(k)-2 U_{i}^{0.25}(k)+U_{i+1}^{0.25}(k)}{h^{2}}-U_{i}^{0.25}(k)\right] } \\
& -2 \frac{\Gamma(0.25 k+1.75)}{\Gamma(0.25 k+2.5)} U_{i}^{0.25}(k+3) . \quad \forall i \geq 1
\end{aligned}
$$

Thus, the solution in $\left(x_{i}, t\right), i=0,1, \ldots, 10$ is obtained as follows:

$$
\begin{aligned}
x_{0}=0, \quad u_{0}(t) & =\sum_{k=0}^{\infty} U_{0}^{0.25}(k) t^{0.25 k}=U_{0}^{0.25}(0)+U_{0}^{0.25}(1) t^{0.25}+U_{0}^{0.25}(2) t^{0.5}+U_{0}^{0.25}(3) t^{0.75}+U_{0}^{0.25}(4) t+\ldots, \\
& =1+0 t^{0.25}+0 t^{0.5}+0 t^{0.75}-2 t+\ldots, \\
x_{1}=0.1, \quad u_{1}(t) & =\sum_{k=0}^{\infty} U_{1}^{0.25}(k) t^{0.25 k}=U_{1}^{0.25}(0)+U_{1}^{0.25}(1) t^{0.25}+U_{1}^{0.25}(2) t^{0.5}+U_{1}^{0.25}(3) t^{0.75}+U_{1}^{0.25}(4) t+\ldots \\
& =e^{0.1}+0 t^{0.25}+0 t^{0.5}+0 t^{0.75}-2 e^{0.1} t+\ldots, \\
& \vdots \\
x_{10}=1, \quad u_{10}(t) & =\sum_{k=0}^{\infty} U_{10}^{0.25}(k) t^{0.25 k}=U_{10}^{0.25}(0)+U_{10}^{0.25}(1) t^{0.25}+U_{10}^{0.25}(2) t^{0.5}+U_{10}^{0.25}(3) t^{0.75}+U_{10}^{0.25}(4) t+\ldots, \\
& =e+0 t^{0.25}+0 t^{0.5}+0 t^{0.75}-2 e t+\ldots
\end{aligned}
$$

We show the results of our method for solving Example 1 in Tables 1 and 2. Table 1 contains the maximum absolute error of the obtained solution using the FD-FDTM for $\gamma=1, m=3$, and different values of $N$ at $t=0.001$. Also, we compared the results of FD-FDTM with twodimensional FDTM. Table 1 shows the our method is more accurate than the two-dimensional DTM. Also, we can see that as N increases, the error decreases and the numerical ROC confirms the theoretical ROC. Table 2 compares the approximate solution of FD-FDTM and 2D-FDTM at $t=0.01$, for $\gamma=0.75, m=10$, and $N=10$. Figure 1 shows the comparison between the exact solution for $\gamma=1$ and the results of FD-FDTM for $\gamma=0.5,0.7,0.8,0.9$.

Table 1. The MAE for Example 1 at $t=0.001$, for $\gamma=1, m=3$, and different values of $N$.

| $\boldsymbol{N}$ | MAE of FD-FDTM $(\boldsymbol{\gamma}=\mathbf{1})$ <br> for $\boldsymbol{\alpha}=\mathbf{1}$ | ROC | CPU Time | MAE of 2D-DTM $(\boldsymbol{\gamma}=\mathbf{1})$ <br> for $\boldsymbol{\alpha}=\mathbf{1}$ | CPU Time |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 10 | $1 \times 10^{-9}$ | - | 0.11 | $3.3 \times 10^{-2}$ | 0.09 |
| 20 | $2.7 \times 10^{-10}$ | 1.89 | 0.11 | $4.1 \times 10^{-2}$ | 0.09 |
| 40 | $6.7 \times 10^{-11}$ | 2.01 | 0.11 | $4.6 \times 10^{-2}$ | 0.09 |
| 80 | $1.5 \times 10^{-11}$ | 2.16 | 0.11 | $4.8 \times 10^{-2}$ | 0.11 |
| 160 | $2.6 \times 10^{-12}$ | 2.51 | 0.16 | $5.01 \times 10^{-2}$ | 0.14 |

Table 2. The approximate solution of Example 1 obtained with FD-FDTM and 2D-FDTM at $t=0.01$, for $\gamma=0.75, \alpha=0.25, m=10$, and $N=10$.

| $x_{i}$ | FD-FDTM <br> $\gamma=\mathbf{0 . 7 5}$ | 2D-FDTM <br> $\gamma=\mathbf{0 . 7 5}$ | Exact Solution <br> $\boldsymbol{\gamma}=\mathbf{1}$ |
| :---: | :---: | :---: | :---: |
| 0.1 | 1.08391073378 | 1.08391006915 | 1.08328706767 |
| 0.2 | 1.19790662077 | 1.19790588623 | 1.19721736312 |
| 0.3 | 1.32389155984 | 1.32389074805 | 1.32312981233 |
| 0.4 | 1.46312645063 | 1.46312555346 | 1.46228458943 |
| 0.5 | 1.617004802 | 1.61700381117 | 1.61607440219 |
| 0.6 | 1.7870666823 | 1.7870655864 | 1.78603843075 |
| 0.7 | 1.9750141259 | 1.9750129144 | 1.9738777322 |
| 0.8 | 2.1827281748 | 2.1827268341 | 2.1814722654 |
| 0.9 | 2.41228770087 | 2.412286213 | 2.4108997064 |



Figure 1. Comparison between the exact solution of Example 1 for $\gamma=1$ and numerical solutions for $\gamma=0.5,0.7,0.8,0.9$.

Example 2. In this example, we consider a non-homogeneous FTE [17]

$$
\begin{equation*}
\frac{\partial^{2 \gamma} v(x, t)}{\partial t^{2 \gamma}}+40 \frac{\partial^{\gamma} v(x, t)}{\partial t^{\gamma}}+100 v(x, t)=\frac{\partial^{2} v(x, t)}{\partial x^{2}}+23 e^{-2 t} \sinh (x), 0<\gamma<1,0<x<1, t>0, \tag{23}
\end{equation*}
$$

with the following conditions:

$$
\begin{equation*}
v(x, 0)=\sinh (x), v_{t}(x, 0)=-2 \sinh (x) \tag{24}
\end{equation*}
$$

$$
\begin{equation*}
v(0, t)=0, v(1, t)=e^{-2 t} \sinh (1) \tag{25}
\end{equation*}
$$

The exact solution of (23) for $\gamma=1$ with conditions (24) and (25) is $v(x, t)=e^{-2 t} \sinh (x)$. For example, we put $\gamma=0.6$ in (23) and consider $h=0.1$ and $\alpha=0.1$. For these values of $\gamma, h$, and $\alpha$, we can write

$$
\begin{aligned}
\frac{\partial^{1.2} v(x, t)}{\partial t^{1.2}} & \rightarrow \frac{\Gamma(0.1 k+2.2)}{\Gamma(0.1 k+1)} U_{i}^{0.1}(k+12), \\
\frac{\partial^{0.6} v}{\partial t^{0.6}} & \rightarrow \frac{\Gamma(0.1 k+1.6)}{\Gamma(0.1 k+1)} U_{i}^{0.1}(k+6), \\
v(x, t) & \rightarrow U_{i}^{0.1}(k), \\
\frac{\partial^{2} v}{\partial x^{2}} & \rightarrow \frac{U_{i-1}^{0.1}(k)-2 U_{i}^{0.1}(k)+U_{i+1}^{0.1}(k)}{h^{2}} .
\end{aligned}
$$

According to relation (13), for the initial conditions we have:

$$
\begin{gathered}
v(x, 0)=\sinh (x) \rightarrow U_{i}^{0.1}(0)=\sinh \left(x_{i}\right), \forall i=0,1,2, \ldots, 10 \\
v_{t}(x, 0)=-2 \sinh (x) \rightarrow U_{i}^{0.1}(10)=-2 \sinh \left(x_{i}\right), \forall i=0,1,2, \ldots, 10
\end{gathered}
$$

and according to (15), we have

$$
U_{i}^{0.1}(1)=U_{i}^{0.1}(2)=\ldots=U_{i}^{0.1}(9)=U_{i}^{0.1}(11)=0, \forall i=0,1, \ldots, 10
$$

We use relation (14) for the boundary conditions, and for the right side of the boundary conditions, we use the FDT of the $e^{-2 t} \sinh (1)$ function. Therefore, we have

$$
\begin{aligned}
& v(0, t)=0 \rightarrow U_{0}^{0.1}(k)=0, \forall k \geq 0 \\
& U_{10}^{0.1}(k)=\left\{\begin{array}{llll}
\sinh (1) \times \frac{(-2) \frac{k}{10}}{\Gamma\left(\frac{k}{10}+1\right)}, & \text { if } & \frac{k}{10} \in \mathbb{Z}^{+} & \\
0 . & \text { if } & \frac{k}{10} \notin \mathbb{Z}^{+} & \forall k \geq 0
\end{array}\right.
\end{aligned}
$$

By putting the above relations in Equation (23), we conclude the following recursive relationship:

$$
\begin{aligned}
U_{i}^{0.1}(k+12)=\frac{\Gamma(0.1 k+1)}{\Gamma(0.1 k+2.2)} & {\left[23 E^{0.1}(k) \sinh \left(x_{i}\right)-100 U_{i}^{0.1}(k)+\frac{U_{i-1}^{0.1}(k)-2 U_{i}^{0.1}(k)+U_{i+1}^{0.1}(k)}{h^{2}}\right] } \\
& -40 \frac{\Gamma(0.1 k+1.6)}{\Gamma(0.1 k+2.2)} U_{i}^{0.1}(k+6),
\end{aligned}
$$

where $E^{0.1}(k)$ is the fractional differential transform of $e^{-2 t}$ and can be obtained as follows:

$$
E^{0.1}(k)=\left\{\begin{array}{lll}
\frac{(-2) \frac{k}{10}}{\Gamma\left(\frac{k}{10}+1\right)}, & \text { if } & \frac{k}{10} \in \mathbb{Z}^{+} \\
& & \\
0 . & \text { if } & \frac{k}{10} \notin \mathbb{Z}^{+}
\end{array}\right.
$$

Thus, in the points $\left(x_{i}, t\right), i=0,1, \ldots, N$, we can write:

$$
\begin{aligned}
& x_{0}=0, \quad u_{0}(t)=\sum_{k=0}^{\infty} U_{0}^{0.1}(k) t^{0.1 k}=U_{0}^{0.1}(0)+U_{0}^{0.1}(1) t^{0.1}+U_{0}^{0.1}(2) t^{0.2}+U_{0}^{0.1}(3) t^{0.3}+U_{0}^{0.1}(4) t^{0.4}+\ldots, \\
& =0+0 t^{0.1}+0 t^{0.2}+0 t^{0.3}+0 t^{0.4}+\ldots, \\
& x_{1}=0.1, \quad u_{1}(t)=\sum_{k=0}^{\infty} U_{1}^{0.1}(k) t^{0.1 k}=U_{1}^{0.1}(0)+U_{1}^{0.1}(1) t^{0.1}+U_{1}^{0.1}(2) t^{0.2}+\ldots+U_{1}^{0.1}(9) t^{0.9}+U_{1}^{0.1}(10) t+\ldots, \\
& =\sinh (0.1)+0 t^{0.1}+0 t^{0.2}+\ldots+0 t^{0.9}-2 \sinh (0.1) t+\ldots, \\
& x_{10}=1, \quad u_{10}(t)=\sum_{k=0}^{\infty} U_{10}^{0.1}(k) t^{0.1 k}=U_{10}^{0.1}(0)+U_{10}^{0.1}(1) t^{0.1}+U_{10}^{0.1}(2) t^{0.2}+\ldots+U_{10}^{0.1}(9) t^{0.9}+U_{10}^{0.1}(10) t+\ldots, \\
& =\sinh (1)+0 t^{0.1}+0 t^{0.2}+\ldots+0 t^{0.9}-2 \sinh (1) t+\ldots .
\end{aligned}
$$

To compare the exact and numerical solution of Example 2 obtained using FD-FDTM and 2DFDTM, we compute the MAE of the obtained solution at $t=0.001$, and present them in Table 3. Also, we show the results of the $F D-F D T M$ and $2 D-F D T M$ at $t=0.001$, for $\gamma=0.6, m=15$, and $N=10$ in Table 4. Figure 2 shows the comparison between the exact solution for $\gamma=1$ and the numerical solution for $\gamma=0.5,0.7,0.8,0.9$.


Figure 2. Comparison between the exact solution of Example 2 for $\gamma=1$ and numerical solutions for $\gamma=0.5,0.7,0.8,0.9$.

Table 3. The MAE for Example 2 at $t=0.001$, for $\gamma=1, m=3$, and different values of $N$.

| $\boldsymbol{N}$ | MAE of FD-FDTM <br> for $\boldsymbol{\alpha}=\mathbf{1}$ | ROC | CPU Time | MAE of 2D-FDTM <br> for $\boldsymbol{\alpha}=\mathbf{1}$ | CPU Time |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 10 | $4.2 \times 10^{-10}$ | - | 0.11 | $9.1 \times 10^{-1}$ | 0.14 |
| 20 | $1.1 \times 10^{-10}$ | 1.8 | 0.12 | $9.5 \times 10^{-1}$ | 0.12 |
| 40 | $2.8 \times 10^{-11}$ | 1.97 | 0.11 | $9.7 \times 10^{-1}$ | 0.11 |
| 80 | $6.7 \times 10^{-12}$ | 2.06 | 0.14 | $9.8 \times 10^{-1}$ | 0.11 |
| 160 | $1.09 \times 10^{-12}$ | 2.61 | 0.17 | $9.9 \times 10^{-1}$ | 0.17 |

Table 4. The approximate solution for Example 2 at $t=0.001$, for $\gamma=0.6, \alpha=0.1, m=15$, and values of $N=10$.

| $x_{i}$ | FD-FDTM <br> $\gamma=\mathbf{0 . 6}$ | 2D-FDTM <br> $\gamma=\mathbf{0 . 6}$ | Exact Solution <br> $\gamma=\mathbf{1}$ |
| :---: | :---: | :---: | :---: |
| 0.1 | 0.097705 | 0.0164227 | 0.099966 |
| 0.2 | 0.19633389 | 0.0330099 | 0.2009337 |
| 0.3 | 0.297038 | 0.049763 | 0.30391186 |
| 0.4 | 0.40066 | 0.0666829 | 0.409931642 |
| 0.5 | 0.508292 | 0.083771 | 0.52005415 |
| 0.6 | 0.621011 | 0.101028 | 0.63538154 |
| 0.7 | 0.739945 | 0.118456 | 0.757068 |
| 0.8 | 0.866285 | 0.136056 | 0.8863315 |
| 0.9 | 1.0013 | 0.153829 | 1.024465743 |

Example 3. In this example, we solve the following nonlinear FTE [23]:
$\frac{\partial^{2 \gamma} v(x, t)}{\partial t^{2 \gamma}}+2 \frac{\partial^{\gamma} v(x, t)}{\partial t^{\gamma}}+u^{2}(x, t)=\frac{\partial^{2} v(x, t)}{\partial x^{2}}+e^{2 x-4 t}-e^{x-2 t}, 0<\gamma<1,0<x<1, t>0$,
with the following conditions

$$
\begin{align*}
& v(x, 0)=e^{x}, v_{t}(x, 0)=-2 e^{x}  \tag{27}\\
& v(0, t)=e^{-2 t}, v(1, t)=e^{1-2 t} \tag{28}
\end{align*}
$$

The exact solution of Equation (26) for $\gamma=1$ with conditions (27) and (28) is $v(x, t)=e^{x-2 t}$.
To explain the FD-FDTM, we put $\gamma=0.75$ in (26) and consider $h=0.1$ and $\alpha=0.25$. For these values of $\gamma, h$, and $\alpha$, we can write

$$
\begin{aligned}
\frac{\partial^{1.5} v(x, t)}{\partial t^{1.5}} & \rightarrow \frac{\Gamma(0.25 k+2.5)}{\Gamma(0.25 k+1)} U_{i}^{0.25}(k+6), \\
\frac{\partial^{0.75} v}{\partial t^{0.75}} & \rightarrow \frac{\Gamma(0.25 k+1.75)}{\Gamma(0.25 k+1)} U_{i}^{0.25}(k+3), \\
v(x, t) & \rightarrow U_{i}^{0.25}(i, k), \\
\frac{\partial^{2} v}{\partial x^{2}} & \rightarrow \frac{U_{i-1}^{0.25}(k)-2 U_{i}^{0.25}(k)+U_{i+1}^{0.25}(k)}{h^{2}} .
\end{aligned}
$$

According to relation (13), for the initial conditions we have

$$
\begin{gathered}
v(x, 0)=e^{x} \rightarrow U_{i}^{0.25}(0)=e^{x_{i}}, \forall i=0,1, \ldots, 10, \\
v_{t}(x, 0)=-2 e^{x} \rightarrow U_{i}^{0.25}(4)=-2 e^{x_{i}}, \forall i=0,1, \ldots, 10 .
\end{gathered}
$$

From relationship (15), we can write

$$
U_{i}^{0.25}(1)=U_{i}^{0.25}(2)=U_{i}^{0.25}(3)=U_{i}^{0.25}(5)=0, \forall i=0,1,2, \ldots, 10 .
$$

We use relation (14) for the boundary conditions and an FDT of $e^{-2 t}, e^{1-2 t}$ for the right side of the boundary conditions. Therefore, we have

$$
\left.\begin{array}{c}
v(0, t)=e^{-2 t} \rightarrow U_{0}^{0.25}(k)=\left\{\begin{array}{lll}
\frac{(-2)^{\frac{k}{4}}}{\Gamma\left(\frac{k}{4}+1\right)}, & \text { if } & \frac{k}{4} \in \mathbb{Z}^{+} \\
0 . & \text { if } & \frac{k}{4} \notin \mathbb{Z}^{+}
\end{array} \quad \forall k \geq 0\right.
\end{array}\right\} \begin{array}{lll}
e \times \frac{(-2)^{\frac{k}{4}}}{\Gamma\left(\frac{k}{4}+1\right)}, & \text { if } & \frac{k}{4} \in \mathbb{Z}^{+} \\
0 . & \text { if } & \frac{k}{4} \notin \mathbb{Z}^{+}
\end{array}
$$

In Example 3, we have $q(x, t)=e^{2 x-4 t}-e^{x-2 t}$, so by using FD-FDTM, we have:

$$
q_{i}^{0.25}(k)=e^{2 x_{i}} \times E_{1}^{0.25}(k)-e^{x_{i}} \times E_{2}^{0.25}(k), \forall i=0,1, \ldots, 10,
$$

where $E_{1}^{0.25}(k)$ and $E_{2}^{0.25}(k)$ are the FDT of the $e^{-4 t}$ and $e^{-2 t}$ functions, respectively, and are obtained as follows:

$$
E_{1}^{0.25}(k)=\left\{\begin{array}{lll}
\frac{(-4)^{\frac{k}{4}}}{\Gamma\left(\frac{k}{4}+1\right)}, & \text { if } & \frac{k}{4} \in \mathbb{Z}^{+} \\
& & \\
0, & \text { if } & \frac{k}{4} \notin \mathbb{Z}^{+}
\end{array} \quad \forall k \geq 0\right.
$$

and

$$
E_{2}^{0.25}(k)=\left\{\begin{array}{lll}
\frac{(-2)^{\frac{k}{4}}}{\Gamma\left(\frac{k}{4}+1\right)}, & \text { if } & \frac{k}{4} \in \mathbb{Z}^{+} \\
& & \\
0 . & \text { if } & \frac{k}{4} \notin \mathbb{Z}^{+}
\end{array} \quad \forall k \geq 0\right.
$$

By substituting the above relations in Equation (26), we obtain the following recursive formula

$$
\begin{aligned}
U_{i}^{0.25}(k+6)=\frac{\Gamma(0.25 k+1)}{\Gamma(0.25 k+2.5)} & {\left[q_{i}^{0.25}(k)+\frac{U_{i-1}^{0.25}(k)-2 U_{i}^{0.25}(k)+U_{i+1}^{0.25}(k)}{h^{2}}-\sum_{j=0}^{k} U_{i}^{0.25}(j) U_{i}^{0.25}(k-j)\right] } \\
& -2 \frac{\Gamma(0.25 k+1.75)}{\Gamma(0.25 k+2.5)} U_{i}^{0.25}(k+3) . \quad \forall i \geq 1
\end{aligned}
$$

In the points $\left(x_{i}, t\right), i=0,1, \ldots, N$, we have:

$$
\begin{aligned}
x_{0}=0, \quad u_{0}(t) & =\sum_{k=0}^{\infty} U_{0}^{0.25}(k) t^{0.25 k}=U_{0}^{0.25}(0)+U_{0}^{0.25}(1) t^{0.25}+U_{0}^{0.25}(2) t^{0.5}+U_{0}^{0.25}(3) t^{0.75}+U_{0}^{0.25}(4) t+\ldots \\
& =1+0 t^{0.25}+0 t^{0.5}+0 t^{0.75}-2 t+\ldots, \\
x_{1}=0.1, \quad u_{1}(t) & =\sum_{k=0}^{\infty} U_{1}^{0.25}(k) t^{0.25 k}=U_{1}^{0.25}(0)+U_{1}^{0.25}(1) t^{0.25}+U_{1}^{0.25}(2) t^{0.5}+U_{1}^{0.25}(3) t^{0.75}+U_{1}^{0.25}(4) t+\ldots \\
& =e^{0.1}+0 t^{0.25}+0 t^{0.5}+0 t^{0.75}-2 e^{0.1} t+\ldots, \\
& \vdots \\
x_{10}=1, \quad u_{10}(t) & =\sum_{k=0}^{\infty} U_{10}^{0.25}(k) t^{0.25 k}=U_{10}^{0.25}(0)+U_{10}^{0.25}(1) t^{0.25}+U_{10}^{0.25}(2) t^{0.5}+U_{10}^{0.25}(3) t^{0.75}+U_{10}^{0.25}(4) t+\ldots \\
& =e+0 t^{0.25}+0 t^{0.5}+0 t^{0.75}-2 e t+\ldots .
\end{aligned}
$$

We show the results of our method for solving Example 3 in Table 5. Table 5 contains the MAE of the solution obtained using FD-FDTM, for $\gamma=1, m=3$, and different values of $N$ at $t=0.01$. Also, we compared the results of FD-FDTM with two-dimensional FDTM. Table 5 shows that the FD-FDTM is more accurate than the two-dimensional FDTM. Figure 3 compares the exact solution for $\gamma=1$ with the numerical solution for $\gamma=0.5,0.7,0.8,0.9$.

Table 5. The MAE for Example 3 at $t=0.01$, for $\gamma=1, m=3$, and different values of $N$.

| $\boldsymbol{N}$ | MAE of FD-FDTM <br> for $\boldsymbol{\alpha}=\mathbf{1}$ | CPU Time | MAE of 2D-DTM <br> for $\boldsymbol{\alpha}=\mathbf{1}$ | CPU Time |
| :---: | :---: | :---: | :---: | :---: |
| 10 | $7.04 \times 10^{-9}$ | 0.11 | $3.1 \times 10^{-1}$ | 0.11 |
| 20 | $8.64 \times 10^{-9}$ | 0.12 | $4.1 \times 10^{-2}$ | 0.11 |
| 40 | $9.3 \times 10^{-9}$ | 0.12 | $4.62 \times 10^{-2}$ | 0.11 |
| 80 | $9.59 \times 10^{-9}$ | 0.16 | $4.88 \times 10^{-2}$ | 0.11 |
| 160 | $9.72 \times 10^{-9}$ | 0.17 | $5.01 \times 10^{-2}$ | 0.12 |



Figure 3. Comparison between the exact solution of Example 3 for $\gamma=1$ and numerical solutions for $\gamma=0.5,0.7,0.8,0.9$.

Example 4. Consider the following time-fractional multi-term wave equation [32]:

$$
\begin{equation*}
\frac{\partial^{1.7} v(x, t)}{\partial t^{1.7}}-\frac{1}{2} \frac{\partial v(x, t)}{\partial t}=\frac{\partial^{2} v(x, t)}{\partial x^{2}}, 0<x<4, t>0 \tag{29}
\end{equation*}
$$

with initial conditions

$$
\begin{equation*}
v(x, 0)=\sin (\pi x), v_{t}(x, 0)=0, \tag{30}
\end{equation*}
$$

and boundary conditions

$$
\begin{equation*}
v(0, t)=0, v(4, t)=0 \tag{31}
\end{equation*}
$$

We describe the mentioned method to solve Equations (29)-(31) for $\alpha=0.1$ By using theorem (3), we can obtain the differential transform of the derivatives in Equation (29) as follows:

$$
\begin{aligned}
\frac{\partial^{1.7} v(x, t)}{\partial t^{1.7}} & \rightarrow \frac{\Gamma(0.1 k+2.7)}{\Gamma(0.1 k+1)} U_{i}^{0.1}(k+17) \\
\frac{\partial v}{\partial t} & \rightarrow \frac{\Gamma(0.1 k+2)}{\Gamma(0.1 k+1)} U_{i}^{0.1}(k+10) \\
\frac{\partial^{2} v}{\partial x^{2}} & \rightarrow \frac{U_{i-1}^{0.1}(k)-2 U_{i}^{0.1}(k)+U_{i+1}^{0.1}(k)}{h^{2}} .
\end{aligned}
$$

According to relation (13), for the initial conditions we have

$$
\begin{gathered}
v(x, 0)=\sin (\pi x) \rightarrow U_{i}^{0.1}(0)=\sin \left(\pi x_{i}\right), \forall i=0,1, \ldots, N, \\
v_{t}(x, 0)=0 \rightarrow U_{i}^{0.1}(10)=0, \forall i=0,1, \ldots, N,
\end{gathered}
$$

and according to relation (15) we have

$$
U_{i}^{0.1}(1)=U_{i}^{0.1}(2)=\ldots=U_{i}^{0.1}(15)=U_{i}^{0.1}(16)=0, \forall i=0,1, \ldots, N,
$$

and

$$
\begin{aligned}
& v(0, t)=0 \rightarrow U_{0}^{0.1}(k)=0, \\
& v(4, t)=0 \rightarrow U_{N}^{0.1}(k)=0 .
\end{aligned}
$$

By replacing the above relations in Equation (29), we obtain the following recursive relationship:

$$
\begin{aligned}
U_{i}^{0.1}(k+17)=\frac{\Gamma(0.1 k+1)}{\Gamma(0.1 k+2.7)} & \left(\frac{U_{i-1}^{0.1}(k)-2 U_{i}^{0.1}(k)+U_{i+1}^{0.1}(k)}{h^{2}}\right) \\
& +\frac{1}{2} \frac{\Gamma(0.1 k+2)}{\Gamma(0.1 k+2.5)} U_{i}^{0.1}(k+10) . \quad \forall i \geq 1
\end{aligned}
$$

We show the results of our method for solving Example 4 in Figures 4 and 5 for $t=1$.


Figure 4. Solution of Example 4 for $N=40, m=20$.


Figure 5. Solution of Example 4 for $N=80, m=20$.

## 6. Conclusions

In this work, a hybrid method has been used to solve the linear and non-linear timefractional telegraph equation approximately. The central difference method has been applied to discretize the spatial derivative and the fractional differential transform method has been used to solve the obtained system of fractional ordinary equations. A convergence analysis of the mentioned method has been conducted. The numerical results show that the proposed hybrid method is more accurate and effective than two-dimensional FDTM. Also, the implementation process of this method is very simple, so its computer programming is very fast.

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