



# Article An Infinite Family of Compact, Complete, and Locally Affine *k*-Symplectic Manifolds of Dimension Three

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**Abstract:** We study the complete, compact, locally affine manifolds equipped with a *k*-symplectic structure, which are the quotients of  $\mathbb{R}^{n(k+1)}$  by a subgroup  $\Gamma$  of the affine group A(n(k+1)) of  $\mathbb{R}^{n(k+1)}$  acting freely and properly discontinuously on  $\mathbb{R}^{n(k+1)}$  and leaving invariant the *k*-symplectic structure, then we construct and give some examples and properties of compact, complete, locally affine two-symplectic manifolds of dimension three.

Keywords: k-symplectic structure; locally affine manifolds; foliations; Lagrangian submanifolds

MSC: 53A15; 53D05; 53C12; 53D12

# 1. Introduction

The notion of a *k*-symplectic structure [1–6] is a natural generalization of the classical notion of a polarized symplectic structure [7]. This last notion plays an important role in the geometric quantization of Kostant–Souriau [8,9]. The study of a *k*-symplectic structure was motivated by the implementation of a formalism of Nambu's mechanics [10] by analogy with the symplectic geometry. The canonical model of a *k*-symplectic manifold is the bundle of  $k^1$ -covelocities, that is  $(T_k^1)^*M$ , while the canonical model of a symplectic geometry has increased especially in recent years due to the awareness of its applications in field theories [11,12]. In fact, the *k*-symplectic formalism is a geometric approach of the mechanics of Y. Nambu, having the same specific features of symplectic geometry as a formalism of the mechanics Hamiltonian [13–15].

The main goal of this work is to obtain some examples of compact manifolds endowed with a *k*-symplectic structure. This leads to the study of the locally affine manifolds [16–21], which represent the simplest differentiable manifolds because of the changes of coordinates in whose atlas are affine mappings. Similar approaches have been studied by: M. Goze, Y. Haraguchi on the r-systems of contact [22], and T. Sari on the locally affine contact manifolds [20].

We know [23,24] that the complete, compact, locally affine manifolds of dimension n are the quotient  $\mathbb{R}^{n(k+1)}/\Gamma$ , where  $\Gamma$  is a subgroup of the affine group A(n) of  $\mathbb{R}^n$ , acting freely and properly discontinuously on  $\mathbb{R}^n$  and  $\Gamma = \pi_1(M)$  [25].

The affine manifolds have been studied by several authors. See, for example, L. Auslander, D. Fried, W. Goldman, P. Benzecri, Y. Carrière, T. Sari, etc, while our purpose is to give new examples of compact and complete locally affine manifolds equipped with an additional structure, which is the *k*-symplectic structure.

These manifolds are the quotients  $\mathbb{R}^{n(k+1)}/\Gamma$ , of  $\mathbb{R}^{n(k+1)}$  by a subgroup  $\Gamma$  of the affine group A(n(k+1)) of  $\mathbb{R}^{n(k+1)}$ , acting freely and properly discontinuously on  $\mathbb{R}^{n(k+1)}$  and leaving invariant the *k*-symplectic structure.



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**Copyright:** © 2021 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). By constructing subgroups  $\Gamma$  of the group A(3) acting freely and properly discontinuously on  $\mathbb{R}^3$  [26,27] and leaving invariant the canonical 2-symplectic structure of  $\mathbb{R}^3$ , we obtain an infinite family of 2-symplectic manifolds of dimension 3 not isomorphic to the torus  $\mathbb{T}^3$ .

## 2. Preliminaries

2.1. k-Symplectic Manifolds

Let *M* be a smooth manifold of dimension n(k + 1) equipped with a foliation  $\mathfrak{F}$  of codimension *n*, and let  $\omega^1, \ldots, \omega^k$  be *k* differential two-forms on *M*.

The sub-bundle of *TM* defined by the tangent vectors of leaves of the foliation  $\mathfrak{F}$  is denoted by *E*, the set of all cross-sections of the *M*-bundle

 $TM \longrightarrow M$  (resp.,  $E \longrightarrow M$ ) is denoted by  $\mathfrak{X}(M)$  (resp.,  $\Gamma(E)$ ), and the set of all differential *p*-forms on *M* is denoted by  $\Lambda^p(M)$ .

We denote by  $C_x(\omega^1), \ldots, C_x(\omega^k)$  the characteristic spaces of the two-forms  $\omega^1, \ldots, \omega^k$  at *x* where  $x \in M$  [28]. Recall that:

$$C_x(\omega^p) = \{X_x \in T_x M \mid i(X_x)\omega^p = 0 \text{ and } i(X_x)d\omega^p = 0\}$$

where  $i(X_x)\omega^p$  denote the interior product of the vector  $X_x$  by the two-form  $\omega^p$ . Therefore,

$$C_x(\omega^p) = \{X_x \in T_x M \mid i(X_x)\omega^p = 0\}$$

**Definition 1.** We say that  $(\omega^1, ..., \omega^k; E)$  is a k-symplectic structure on M, if the following conditions are satisfied [28]:

- 1. The two-forms  $\omega^1, \ldots, \omega^k$  are closed;
- 2. The system  $\{\omega^1, \ldots, \omega^k\}$  is nondegenerate, that is,

$$C_x(\omega^1)\cap\cdots\cap C_x(\omega^k)=\{0\}$$

*for every*  $x \in M$ *;* 

3. The system  $\{\omega^1, \ldots, \omega^k\}$  is vanishing on the tangent vectors to the foliation  $\mathfrak{F}$ , that is,

 $\omega^p(X,Y) = 0$  for all  $X, Y \in \Gamma(E)$  and  $p = 1, \dots, k$ .

**Example 1.** Canonical k-symplectic structure on  $\mathbb{R}^{n(k+1)}$  [28]: Consider the real space  $\mathbb{R}^{n(k+1)}$  endowed with its Cartesian coordinates  $(x^{pi}, y^i)_{1 \le p \le k, 1 \le i \le n}$ . Let E be the sub-bundle of  $T\mathbb{R}^{n(k+1)}$  defined by the equations:

$$dy^1 = 0, \ldots, dy^n = 0$$

and let  $\omega^p (p = 1, ..., k)$  be the differential two-forms on M given by:

$$\omega^p = \sum_{i=1}^n dx^{pi} \wedge dy^i.$$

 $(\omega^1, \ldots, \omega^k; E)$  defines a k-symplectic structure on  $\mathbb{R}^{n(k+1)}$  called the canonical k-symplectic structure of  $\mathbb{R}^{n(k+1)}$ . This structure induces a natural k-symplectic structure on the torus  $\mathbb{T}^{n(k+1)}$ .

2.2. k-Symplectic Affine Manifolds

Let *M* be a *k*-symplectic manifold of dimension n(k + 1).

**Definition 2** ([28]). We say that *M* is an affine k-symplectic manifold if the Darboux atlas  $\mathfrak{A}$  confers upon *M* a structure of a locally affine manifold.

Let  $Gp(k, n; \mathbb{R})$  be the group of all affine transformations of  $\mathbb{R}^{n(k+1)}$  preserving the canonical *k*-symplectic structure of  $\mathbb{R}^{n(k+1)}$ . The group  $Gp(k, n; \mathbb{R})$  is the set of all affine transformations:

$$X \longmapsto AX + B$$

of  $\mathbb{R}^{n(k+1)}$  such that A belongs to the k-symplectic group  $Sp(k, n; \mathbb{R})$ .

**Proposition 1** ([28]). Let *M* be a complete connected affine k-symplectic manifold of dimension n(k+1). Then, *M* is just a quotient  $\mathbb{R}^{n(k+1)}/\Gamma$  and with a fundamental group  $\Gamma$ :

$$M = \mathbb{R}^{n(k+1)} / \Gamma, \quad \pi_1(M) = \Gamma,$$

where  $\Gamma$  is a subgroup of  $Gp(k, n; \mathbb{R})$  acting freely and properly discontinuously on  $\mathbb{R}^{n(k+1)}$ .

2.3. Case Where  $\mathfrak{F}$  Is of Codimension One

Let  $Hp(k, n; \mathbb{R})$  [28] be the group of all matrices:

$\begin{pmatrix} I_n & A_1 & C_1 \end{pmatrix}$	
· : :	
0 $I_n A_k C_k$	:
$0 \cdots 0 I_n B$	
$igl( 0 \cdots 0 0 1 )$	)

where  $I_n$  is the unit matrix of rank,  $n, A_1, \dots, A_k$  are  $n \times n$  real symmetric matrices, and  $C_1, \dots, C_k, B$  are column vectors of length n. We denote by (A, B, C) the matrices of the previous form where  $A = (A_1, \dots, A_k), C = (C_1, \dots, C_k)$ .

**Proposition 2** ([28]). If *M* is a complete connected affine *k*-symplectic manifold of dimension k + 1, then *M* is a quotient  $\mathbb{R}^{k+1}/\Gamma$  with a fundamental group  $\Gamma$ :

$$M = \mathbb{R}^{k+1} / \Gamma, \quad \pi_1(M) = \Gamma,$$

where  $\Gamma$  is a subgroup of  $Hp(k, 1; \mathbb{R})$  acting freely and properly discontinuously on  $\mathbb{R}^{k+1}$ .

#### 3. Main Results

Based on the propositions above, we construct an infinite family of *k*-symplectic manifolds of dimension three by constructing a family of subgroups of  $Hp(2, 1; \mathbb{Z})$ , which act freely and properly discontinuously on  $\mathbb{R}^3$ .

3.1. Subgroups of  $Hp(2, 1; \mathbb{Z})$  Acting without a Fixed Point

The group  $Hp(2, 1; \mathbb{Z})$  is formed by the matrices of the form:

$$\begin{pmatrix} 1 & 0 & a_1 & c_1 \\ 0 & 1 & a_2 & c_2 \\ 0 & 0 & 1 & b \\ 0 & 0 & 0 & 1 \end{pmatrix}$$
(1)

where  $a_1, a_2, b, c_1, c_2 \in \mathbb{Z}$ .

We denote by (A, b, C) the matrices of Type (1) where  $A = (a_1; a_2), C = (c_1; c_2) \in \mathbb{Z}^2$ , and  $b \in \mathbb{Z}$ .

For all  $g = (A, b, C), g' = (A', b', C') \in Hp(2, 1; \mathbb{Z})$ , we have:

$$gg' = (A + A', b + b', b'A + C + C')$$

 $g^k = (kA, kb, P_k bA + kC)$ 

where  $k \in \mathbb{Z}$  and  $P_k = \frac{k(k-1)}{2}$ .

$$g^{-1} = (-A, -b, bA - C)$$
  
 $[g, g'] = (0, 0, b'A - bA').$ 

Let  $\Gamma$  be a subgroup of  $Hp(2,1;\mathbb{Z})$  and  $\Gamma_0$  a subgroup of  $\Gamma$  defined by:  $\Gamma_0 = \{(A, b, C) \in \Gamma \mid b = 0\}.$ 

 $\Gamma_0$  is a free Abelian subgroup of the additive group formed by the triplets: (*A*,0,*C*), where A,C  $\in \mathbb{Z}^2$ .

Therefore, the rank of  $\Gamma_0$  is less than or equal to four.

3.1.1. Case Where  $\Gamma_0 = \{0\}$ 

It results from the definition of  $\Gamma_0$  that: For all  $g = (A, b, C) \in \Gamma$ , we have  $b \neq 0$  or A = C = 0. Let  $g_1 = (A^1, b_1, C^1)$ ,  $g_2 = (A^2, b_2, C^2) \in \Gamma$  with  $b_1, b_2 \in \mathbb{Z}^*$ . The component *b* of the element  $g_1^{b_2}g_2^{-b_1}$  is zero. Hence,  $g_1^{b_2} = g_2^{b_1}$ . Therefore,  $g_2^{b_1}$  is in the subgroup  $< g_1 >$  of  $\Gamma$  generated by  $g_1$ :

$$g_2^{v_1} \in < g_1 >.$$

**Proposition 3.** Γ *is a monogenous subgroup.* 

**Proof.** Suppose that  $\Gamma$  is not reduced to  $\{0\}$ ; we consider g = (A, b, C) an element of  $\Gamma$  with  $b \neq 0$ .

Let *E* be the set:

$$E = \{ b \in \mathbb{N}^* \mid \exists g \in \Gamma \text{ where } g = (A, b, C) \}.$$

*E* is a nonempty subset of  $\mathbb{N}^*$ , so it admits a least element denoted  $b_1$ . We consider an element  $g_1 = (A^1, b_1, C^1)$  of  $\Gamma$  corresponding to  $b_1$ , and we prove that  $\Gamma$  is generated by  $g_1$ :

$$\Gamma = \langle g_1 \rangle.$$

Let  $g_2 = (A^2, b_2, C^2)$  be an element of  $\Gamma$  such that  $b_2 \neq 0$ ; we prove first that  $b_1$  divides  $b_2$ . We can suppose that  $b_2 > 0$ . We suppose the opposite ( $b_1$  does not divide  $b_2$ ).

For  $b = b_1 \wedge b_2$ , we have:  $0 < b < b_1$ , and by the Bezout identity: there exist  $u, v \in \mathbb{Z}$  such that:  $ub_1 + vb_2 = b$ .

Therefore:

$$g_1^u g_2^v = (A'', ub_1 + vb_2 = b, C'') \in \Gamma$$

and this contradicts that  $b_1$  is the least element in *E*.

Hence,  $b_1$  divides  $b_2$ ,.

Consequently: there exists  $m \in \mathbb{Z}$  such that  $b_2 = mb_1$ .

The component *b* of the element  $g = g_2 g_1^{-m}$  is zero.

Consequently:  $g = i_d \Longrightarrow g_2 = g_1^m$ , which proves that  $\Gamma = \langle g_1 \rangle$ .  $\Box$ 

3.1.2. Case Where the Rank ( $\Gamma_0$ ) = 1

We suppose that  $\Gamma_0$  is generated by an element  $g_0 = (A^0, 0, C^0)$  supposed without a fixed point and different from (0;0;0).

**Remark 1.** (1) The following properties are equivalent: (*i*)  $\Gamma_0$  acts without a fixed point on  $\mathbb{R}^3$ ;

- (*ii*)  $C^0 \notin \mathbb{R}.A^0$ ;
- (iii) If  $A^1 \neq 0 \Rightarrow \det(C^1, A^1) \neq 0$ .
- (2) For all  $(A, 0, C) \in \Gamma_0$ , we have:  $C = 0 \Longrightarrow A = 0$ ;
- (3) For all  $g = (A, b, C) \in \Gamma$ , we have:  $(b = 0 \Longrightarrow \exists n \in \mathbb{Z}: g = g_0^n)$ .

**Proposition 4.** We have that  $\Gamma = \Gamma_0$  or  $\Gamma$  admits two generators  $\Gamma = \langle g_0, g_1 \rangle$ , where  $g_1 = (A^1, b_1, C^1)$  with  $b_1 \neq 0$ .

**Proof.** If  $\Gamma$  strictly contains  $\Gamma_0$ , then it contains at least an element g = (A, b, C) with  $b \neq 0$ . Let *E* be the set:

$$E = \{b \in \mathbb{N}^* \mid \exists g \in \Gamma : g = (A, b, C)\}.$$

*E* is a nonempty subset of  $\mathbb{N}^*$ , so it admits a least element denoted  $b_1$ . We consider an element  $g_1 = (A^1, b_1, C^1)$  of  $\Gamma$ .

We have:  $b_1$  divides b; so there is an  $m \in \mathbb{Z}$  such that:  $b = mb_1$ . The component b of the element  $gg_1^{-m}$  is zero. Then, there exists  $n \in \mathbb{Z}$ : $gg_1^{-m} = g_0^n$ , hence  $g = g_0^n g_1^m$ . Consequently,  $\Gamma = \langle g, g_1 \rangle$ .  $\Box$ 

**Proposition 5.**  $\Gamma$  acts without a fixed point on  $\mathbb{R}^3$ .

**Proof.** Let  $g = (A, b, C) \in \Gamma$ ; the relative integers A, b, C are respectively written in the forms:

$$A = (\sum_{i=1}^{n} \lambda_{i})A^{0} + (\sum_{i=1}^{n} \mu_{i})A^{1}.$$
  

$$b = (\sum_{i=1}^{n} \mu_{i})b_{1}.$$
  

$$C = (\sum_{k=1}^{n} (\sum_{j=1}^{k} \lambda_{j})\mu_{k})b_{1}A^{0} + P_{\sum_{i=1}^{n} \mu_{i}}b_{1}A^{1} + (\sum_{i=1}^{n} \lambda_{i})C^{0} + (\sum_{i=1}^{n} \mu_{i})C^{1} \text{ where } n \in \mathbb{N}, \lambda_{i}, \mu_{j} \in \mathbb{Z}.$$

and i = 0, 1, ..., n.

If *g* admits a fixed point, then:  $\sum_{i=1}^{n} \mu_i = 0$ , and there exists  $q \in \mathbb{Q}$  such that:

$$\left(\sum_{k=1}^{n} \left(\sum_{j=1}^{k} \lambda_{j}\right) \mu_{k}\right) b_{1} A^{0} + \left(\sum_{i=1}^{n} \lambda_{i}\right) C^{0} = q\left(\sum_{i=1}^{n} \lambda_{i}\right) A^{0}.$$
  
If  $A^{0} = 0$ , then  $\left(\sum_{i=1}^{n} \lambda_{i}\right) C^{0} = 0.$   
 $C^{0} \neq 0$ , so:  $\sum_{i=1}^{n} \lambda_{i} = 0$ , and consequently,  $g = (0,0,0).$   
In this particular case, we obtain an Abelian group isomorphic to  $\mathbb{Z}^{2}.$   
If  $A^{0} \neq 0$ , then  $\left(\sum_{i=1}^{n} \lambda_{i}\right) \det(C^{0}, A^{0}) = 0.$   
 $\det(C^{0}, A^{0}) \neq 0$ , so  $\sum_{i=1}^{n} \lambda_{i} = 0.$   
Consequently,  $g = (0,0,0).$ 

3.1.3. Case Where Rank  $(\Gamma_0) = 2$ 

We suppose that  $\Gamma_0$  is generated by two elements:  $g_0 = (A^0, 0, C^0)$  and  $g_1 = (A^1, 0, C^1)$  both not equal to (0, 0, 0).

If  $\Gamma$  acts without a fixed point on  $\mathbb{R}^3$ , then:

- (i)  $A^0 \neq 0 \Longrightarrow \det(A^0, C^{\hat{0}}) \neq 0;$
- (ii)  $A^1 \neq 0 \Longrightarrow \det(A^1, C^1) \neq 0;$
- (iii)  $\det(C^1, C^0) \neq 0$ .

We prove Assertion (iii).

If det( $C^1$ ,  $C^0$ ) = 0, then there exists  $n,m\in\mathbb{Z}^*$  such that:  $nC^0 + mC^1 = 0$ . We can suppose that *n* and *m* are coprime.

The element  $g_0^n g_1^{-m} = (nA^0 - mA^1, 0, 0)$  belongs to  $\Gamma_0$ , which has a fixed point. Hence,  $g_0^n g_1^{-m} = id$ .

Let  $u, v \in \mathbb{Z}$ , which satisfy: un + vm = 1, and  $g_2 = g_0^v g_1^u \in \Gamma_0$ . We have:

$$g_2^m = g_0^{vm} g_1^{um} = g_0^{vm} g_0^{un} = g_0^{un+vm} = g_0$$

and:

$$g_2^n = g_0^{vn} g_1^{un} = g_1^{vm} g_1^{un} = g_1^{un+vm} = g_1$$

which shows that  $\Gamma_0$  is monogenous and generated by the element  $g_2$ .

Then, we come back to the case 3.1.2.

**Proposition 6.** We either have  $\Gamma = \Gamma_0$  or  $\Gamma$  is a free group with three generators  $g_0, g_1$ , and  $g_2$ with  $g_2 = (A^2, b_2, C^2)$  and  $b_2 \neq 0$ .

**Proof.** If  $\Gamma$  strictly contains  $\Gamma_0$ , then  $\Gamma$  contains an element  $g_2 = (A^2, b_2, C^2)$ , where  $b_2$  is the least element of the subset:  $E = \{b \in \mathbb{N}^* \mid \exists g \in \Gamma \text{ where } g = (A, b, C)\}.$ 

Let  $g = (A, b, C) \in \Gamma$  where  $b \neq 0$ .

As in 3.1.2., we prove that  $b_2$  divides b.

We denote by *m* an element of  $\mathbb{Z}$  such that:  $b = mb_1$ .

The element  $gg_2^{-m}$  of  $\Gamma$  is written in the form (A'', 0, C''). Consequently,  $gg_2^{-m} \in \Gamma_0$ , which proves that g belongs to the free group  $\langle g_0, g_1, g_2 \rangle$ generated by  $g_0, g_1, g_2$ .

Hence,  $\Gamma = \langle g, g_1, g_2 \rangle$ .  $\Box$ 

We are now looking for a characterization of the group  $\Gamma$ , which acts without fixed points on  $\mathbb{R}^3$ .

We denote by  $D_1 = \det(A^1, A^0)$ ,  $D_2 = \det(A^0, C^0)$  and,  $D_3 = \det(C^1, A^0)$ . (1) Case where  $D_2 = 0$ :

If  $A^0 = A^1 = 0$ , then  $\Gamma$  contains only the translations: it is isomorphic to  $\mathbb{Z}^2$  or  $\mathbb{Z}^3$ , for consequence  $\Gamma$  acts on  $\mathbb{R}^3$  without a fixed point.

The case where  $A^0 = 0$  and  $A^1 \neq 0$  will be discussed in the case where  $D_2 \neq 0$ ;

(2) Case where  $D_2 \neq 0$  and  $D_1 = 0$ :

If  $D_1 = 0$ , then there exists  $m \in \mathbb{Q}$  such that  $A^1 = mA^0$ ;

(i) We suppose that m = 0. In this case, an element g = (A, b, C) of  $\Gamma$  is written in the forms:

$$A = (\sum_{i=1}^{n} \lambda_i) A^0 + (\sum_{i=1}^{n} \theta_i) A^2.$$
$$b = (\sum_{i=1}^{n} \theta_i) b_2.$$

$$C = \left(\sum_{k=1}^{n} \left(\sum_{j=1}^{k} \lambda_{j}\right)\theta_{k}\right)b_{2}A^{0} + P_{\sum_{i=1}^{n} \theta_{i}}b_{2}A^{2} + \left(\sum_{i=1}^{n} \lambda_{i}\right)C^{0} + \left(\sum_{i=1}^{n} \mu_{i}\right)C^{1} + \left(\sum_{i=1}^{n} \theta_{i}\right)C^{2}$$

where  $n \in \mathbb{N}, \lambda_i, \mu_i, \theta_i \in \mathbb{Z}$  and i = 0, 1, ..., n;

(i.1)  $D_3 = 0$ :

In this case, we have:  $C^1 = \lambda A^0$ ,  $\lambda \in \mathbb{Q}$ .

If *g* has a fixed point, then:

$$(*) \quad (\sum_{i=1}^{n} \theta_i) = 0,$$

(\*\*)  $\exists q \in \mathbb{Q}$  such that C = qA. The condition (\*\*) is written:

$$\sum_{k=1}^{n} \left( \left(\sum_{j=1}^{k} \lambda_{j}\right) b_{2} \theta_{k} + \lambda \mu_{k} \right) A_{1}^{0} + \left(\sum_{i=1}^{n} \lambda_{i}\right) C_{1}^{0} = q \left(\sum_{i=1}^{n} \lambda_{i}\right) A_{1}^{0}.$$

$$\sum_{k=1}^{n} \left( \left(\sum_{j=1}^{k} \lambda_{j}\right) b_{2} \theta_{k} + \lambda \mu_{k} \right) A_{2}^{0} + \left(\sum_{i=1}^{n} \lambda_{i}\right) C_{2}^{0} = q \left(\sum_{i=1}^{n} \lambda_{i}\right) A_{2}^{0}$$
and then,  $\left(\sum_{i=1}^{n} \lambda_{i}\right) D_{2} = 0.$ 
Hence,  $\left(\sum_{i=1}^{n} \lambda_{i}\right) = 0$ 
We deduce that if  $D_{i} = 0$  and  $m = 0$  then  $\Gamma$  acts without a fixed point of

We deduce that: if  $D_3 = 0$  and m = 0, then  $\Gamma$  acts without a fixed point on  $\mathbb{R}^3$ ; (i.2)  $D_3 \neq 0$ :

We will see in (the case where  $m \neq 0$ ) that  $\Gamma$  acts without a fixed point if and only if  $D_3 = mD_2$ .

We can also see (1) of remak12;

(ii) We suppose that  $m \neq 0$ . In this case, we have:

**Proposition 7.** The group  $\Gamma$  acts without a fixed point on  $\mathbb{R}^3$  if and only if  $D_3 = mD_2$ .

**Proof.** If  $D_3 = mD_2$ , then  $\Gamma$  is generated by:

 $g_0 = (A^0, 0, C^0), g_1 = (mA^0, 0, C^1)$  and  $g_2 = (A^2, b_2, C^2)$  with  $b_2 \neq 0$ . Every element g = (A, b, C) of  $\Gamma$  is written in the form:

$$A = \left(\left(\sum_{i=1}^{n} \lambda_{i}\right) + m\left(\sum_{i=1}^{n} \mu_{i}\right)\right)A^{0} + \left(\sum_{i=1}^{n} \theta_{i}\right)A^{2}.$$
$$b = \left(\sum_{i=1}^{n} \theta_{i}\right)b_{2}.$$

$$C = (\sum_{k=1}^{n} (\sum_{j=1}^{k} (\lambda_j + m\mu_j)\theta_k)b_2A^0 + P_{\sum_{i=1}^{n} \theta_i}b_2A^2 + (\sum_{i=1}^{n} \lambda_i)C^0 + (\sum_{i=1}^{n} \mu_i)C^1 + (\sum_{i=1}^{n} \theta_i)C^2$$

where  $n \in \mathbb{N}, \lambda_i, \mu_i, \theta_i \in \mathbb{Z}$  and i = 0, 1, ..., n.

We suppose that  $g \neq (0, 0, 0)$ .

If g admits a fixed point, then:  $\left(\sum_{i=1}^{n} \theta_{i}\right) = 0 \text{ and } \sum_{j=1}^{k} (\lambda_{j} + m\mu_{j}) \neq 0,$ and there exists  $q \in \mathbb{Q}^{*}$  such that: C = qA. It follows that:  $\left(\sum_{i=1}^{n} \lambda_{i}\right)D_{2} + \left(\sum_{i=1}^{n} \mu_{i}\right)D_{3} = \left(\sum_{j=1}^{k} (\lambda_{j} + m\mu_{j})\right)D_{2} = 0.$   $D_{2} \neq 0$ , then:  $\left(\sum_{j=1}^{k} (\lambda_{j} + m\mu_{j})\right) = 0.$ Hence, g = (0, 0, 0), which is absurd. As a consequence,  $\Gamma$  acts without being fixed on  $\mathbb{R}^{3}$ .

Conversely, we suppose that  $D_3 \neq mD_2$ .

An element g of  $\Gamma$  not equal to (0,0,0) has a fixed point if and only if there exist:  $\lambda_1, \ldots, \lambda_n, \mu_1, \ldots, \mu_n \in \mathbb{Z}$ , such that the system:

$$\begin{cases} (\sum_{i=1}^{n} \lambda_i) + m(\sum_{i=1}^{n} \mu_i) \neq 0\\ (\sum_{i=1}^{n} \lambda_i) D_2 + (\sum_{i=1}^{n} \mu_i) D_3 = 0 \end{cases}$$
(2)

is satisfied.

There are many integers  $\lambda_1, \ldots, \lambda_n, \mu_1, \ldots, \mu_n \in \mathbb{Z}$  such that:

 $\delta_{i}(\sum_{i=1}^{n} \mu_{i}) \in \mathbb{Z}^{*}, (\sum_{i=1}^{n} \mu_{i}) = \delta D \text{ and } (\sum_{i=1}^{n} \lambda_{i}) = -\delta D_{3}, \text{ and in these conditions, we have:}$  $(\sum_{i=1}^{n} \lambda_{i}) + m(\sum_{i=1}^{n} \mu_{i}) = \delta(mD_{2} - D_{3}) \neq 0 \text{ and } (\sum_{i=1}^{n} \lambda_{i})D_{2} + (\sum_{i=1}^{n} \mu_{i})D_{3} = 0.$ Consequently,  $\Gamma$  has a fixed point on  $\mathbb{R}^3$ .  $\Box$ 

**Remark 2.** (1) In the case where m = 0 and  $D_3 \neq 0$ , the system (2) becomes:

$$\begin{cases} (\sum_{i=1}^{n} \lambda_i) \neq 0\\ (\sum_{i=1}^{n} \lambda_i) D_2 + (\sum_{i=1}^{n} \mu_i) D_3 = 0 \end{cases}$$
(3)

*There exists*  $\lambda_1 \ldots, \lambda_n, \theta_1, \ldots, \theta_n \in \mathbb{Z}$  *satisfying* (3); *hence,* (i.2)  $D_3 \neq 0$ ; (2)  $\Gamma_0$  *is a normal subgroup in*  $\Gamma$ *, isomorphic to*  $\mathbb{Z} \times \mathbb{Z}$ *;* (3) For  $D_3 = mD_2$ , we have  $A^0 = (C^1 - mC^0) \frac{D_2}{\det(C^0, C^1)}$ .

(3) Case where  $D_2 \neq 0$  and  $D_1 \neq 0$ :

In this case, the group  $\Gamma$  admits fixed points.

Let  $\lambda_0$ ,  $\lambda_1$ ,  $\mu_1$ ,  $\mu_2$ ,  $\theta_1$ ,  $\theta_2$ ,  $\delta \in \mathbb{Z}$  such that:

$$\theta_1 + \theta_2 = 1$$
,  $\delta D_2 \in \mathbb{Z}^*$ ,  $\mu_1 = -\mu_0 = -\delta D_2$  and  $\lambda_0 + \lambda_1 = -\delta b_2 D_1$ 

The element:  $g = g_0^{\lambda_0} g_1^{\mu_0} g_2^{\theta_0} g_0^{\lambda_1} g_1^{\mu_1} g_2^{\theta_1}$  is different from (0,0,0) and admits a fixed point.

# 3.1.4. Case Where the Rank of $\Gamma_0$ Is at Least 3

In these conditions,  $\Gamma_0$  contains three elements  $g_0 = (A^0, 0, C^0), g_1 = (mA^0, 0, C^1)$ , and  $g_2 = (A^2, 0, C^2)$ , which are independent of the  $\mathbb{Z}$ -module  $\Gamma_0$ .

Otherwise, we can find three nonvanishing integers  $\lambda$ ,  $\mu$ ,  $\theta$ , such that:  $\lambda C^0 + \mu C^1 + \theta C^2$ = 0 and  $\lambda A^0 + \mu A^1 + \theta A^2 \neq 0$ .

 $g_0, g_1, g_2$  are free in the  $\mathbb{Z}$ -module  $\Gamma_0$ . The element  $g_0^{\lambda} g_1^{\mu} g_2^{\theta} = (\lambda A^0 + \mu A^1 + \theta A^2, 0, 0)$  has a fixed point. The study above is summed up by the following proposition:

**Proposition 8.** *The subgroups*  $\Gamma$  *of*  $Hp(2, 1; \mathbb{Z})$  *of the type:* 

 $\Gamma = \langle (A^0, 0, C^0), (mA^0, 0, C^1), (A^2, b_2, C^2) \rangle$  with  $A^0, C^0, C^1, A^2, C^2 \in \mathbb{Z}^2$  and  $b_2 \in \mathbb{N}^*$ satisfying:

 $det(C^0, C^1) \neq 0, D_3 = mD_2$ 

and their subgroups are all subgroups of  $Hp(2, 1; \mathbb{Z})$  acting without a fixed point on  $\mathbb{R}^3$ .  $(D_2 \text{ and } D_3 \text{ denote respectively the determinants } det(A^0, C^0) \text{ and } det(A^0, C^1).)$ 

3.2. An Infinite Family of Compact Complete and Locally Affine k-Symplectic Manifolds of Dimension 3

**Proposition 9.** The subgroups  $\Gamma$  of  $Hp(2, 1; \mathbb{Z})$  of the type:

 $\Gamma = \langle (A^0, 0, C^0), (mA^0, 0, C^1), (A^2, b_2, C^2) \rangle$  with  $A^0, C^0, C^1, A^2, C^2 \in \mathbb{Z}^2$  and  $b_2 \in \mathbb{N}^*$ , which satisfy:  $det(C^0, C^1) \neq 0$ ,  $D_3 = mD_2$ , and their subgroups, act freely and properly discontinuously without a fixed point on  $\mathbb{R}^3$ .

**Proof.** We prove that  $\Gamma$  acts properly discontinuously on  $\mathbb{R}^3$ .

If  $A^0 = 0$ , the group  $\Gamma$  contains only translations; as the vectors  $(0, C^0), (0, C^1)$  and  $(b_2, C^2)$  are independent, the quotient space is isomorphic to the torus  $\mathbb{T}^3$ .

We suppose now that  $A^0 \neq 0$ :

(a) Let us first prove that any point of  $\mathbb{R}^3$  admits an open neighborhood *U* such that the set  $\{g \in \Gamma \mid g(U) \cap U \neq \phi\}$  is finite.

Let  $a_0 \in \mathbb{Z}$  and  $b_0 \in \mathbb{N}^*$  such that:  $m = \frac{a_0}{b_0}$  and  $M_0$  a point of  $\mathbb{R}^3$  of coordinates  $(x_0, y_0, z_0).$ 

We pose  $\varepsilon = Min(\frac{1}{4b_2b_0}, \frac{|D_2|}{4b_0(|A_1^0|+|A_2^0|)})$  and  $U_0$  the open ball of center  $M_0$  and radius  $\varepsilon$ for the norm: ||(x, y, z)|| = sup(|x|, |y|, |z|).

Let *g* be an element of  $\Gamma$  satisfying  $g(U) \cap U \neq \phi$ ; there exists a point  $M = (x, y, z) \in \mathbb{R}^3$ such that *M* and g(M) are in *U*.

For (x', y', z') = g(M), we must have: ( $\star$ )  $|x' - x| < 2\varepsilon$ ,  $|y' - y| < 2\varepsilon$  and  $|z' - z| < 2\varepsilon$ .

Recall that the element g = (A, b, C) of  $\Gamma$  is written in the form (A, b, C) with:

$$A = \left( \left(\sum_{i=1}^{n} \lambda_i\right) + m\left(\sum_{i=1}^{n} \mu_i\right) \right) A^0 + \left(\sum_{i=1}^{n} \theta_i\right) A^2,$$
$$b = \left(\sum_{i=1}^{n} \theta_i\right) b_2,$$

$$C = \left(\sum_{k=1}^{n} \left(\sum_{j=1}^{k} (\lambda_{j} + m\mu_{j})\theta_{k}\right)b_{2}A^{0} + P_{\sum_{i=1}^{n}\theta_{i}}b_{2}A^{2} + \left(\sum_{i=1}^{n} \lambda_{i}\right)C^{0} + \left(\sum_{i=1}^{n} \mu_{i}\right)C^{1} + \left(\sum_{i=1}^{n} \theta_{i}\right)C^{2}$$

where  $n \in \mathbb{N}, \lambda_i, \mu_i, \theta_i \in \mathbb{Z}$ , and i = 0, 1, ..., n. By hypothesis, we have:

$$\begin{aligned} |z'-z| &= |(\sum_{i=1}^{n} \theta_i)b_2| < 2\varepsilon < 1 \text{ with } (\sum_{i=1}^{n} \theta_i)b_2 \in \mathbb{Z} \text{ with } b_2 \neq 0, \text{ then } |(\sum_{i=1}^{n} \theta_i)| = 0 \\ \text{The components } x'-x \text{ and } y'-y \text{ become:} \\ x'-x &= ((\sum_{i=1}^{n} \lambda_i) + m(\sum_{i=1}^{n} \mu_i)) zS_1^0 + (\sum_{k=1}^{n} (\sum_{j=1}^{k} (\lambda_j + m\mu_j)\theta_k)b_2A_1^0 + (\sum_{i=1}^{n} \lambda_i)C_1^0 + (\sum_{i=1}^{n} \mu_i)C_1^1 \\ y'-y &= ((\sum_{i=1}^{n} \lambda_i) + m(\sum_{i=1}^{n} \mu_i)) zS_2^0 + (\sum_{k=1}^{n} (\sum_{j=1}^{k} (\lambda_j + m\mu_j)\theta_k)b_2A_2^0 + (\sum_{i=1}^{n} \lambda_i)C_2^0 + (\sum_{i=1}^{n} \mu_i)C_2^1. \\ \text{The inequalities: } |x'-x| < 2\varepsilon, |y'-y| < 2\varepsilon \text{ imply that:} \\ |A_2^0(x'-x) - A_1^0(y'-y)| \leq 2\varepsilon (|A_1^0| + |A_2^0|). \end{aligned}$$

$$|(\sum_{i=1}^{n} \lambda_{i})det(A^{0}, C^{0}) + (\sum_{i=1}^{n} \mu_{i})det(A^{0}, C^{1})| = |(\sum_{i=1}^{n} \lambda_{i}) + m(\sum_{i=1}^{n} \mu_{i})| |D_{2}| \le 2\varepsilon(|A_{1}^{0}| + |A_{2}^{0}|)$$

Consequently,  $|(\sum_{i=1}^{n} \lambda_i) + m(\sum_{i=1}^{n} \mu_i)| b_0$  is an integer satisfying:  $|(\sum_{i=1}^{n} \lambda_i) + m(\sum_{i=1}^{n} \mu_i)| b_0 \le 2\varepsilon(|A_1^0| + |A_1^0|)b_0 / |D_2| < \frac{1}{2}.$ Hence,  $|(\sum_{i=1}^{n} \lambda_i) + m(\sum_{i=1}^{n} \mu_i)| = 0$ It follows that  $b_0 | x' - x |$  and  $b_0 | y' - y |$  are positive integers less than 1, so they

are equal to zero.

Consequently, g = (0, 0, 0), and this proves that:

$$\{g \in \Gamma \mid g(U) \cap U \neq \phi\} = \{I_d\};$$

(b) First, we prove that  $\Gamma$  acts properly on  $\mathbb{R}^3$ : for any compact subset *K* of  $\mathbb{R}^3$ , the set:

$$\{g \in G \mid g(K) \cap K \neq \phi\}$$

is finite.

Let  $M_1 = (x_1, y_1, z_1)$ , *K* be a compact subset of  $\mathbb{R}^3$  and a real number R > 0 such that *K* is contained in the open ball  $B(M_1, R)$  of center  $M_1$  and radius *R*.

The following sets are finite:

$$S_1 = \{ \mu \in \mathbb{Z} : | \ \mu b_2 \mid < R \}.$$

$$S_{2} = \{\lambda + m\theta : | \lambda + m\theta | < 2R(|A_{1}^{0}| + |A_{2}^{0}|) \text{ where } \lambda, \theta \in \mathbb{Z}\}.$$
  
$$S_{3}^{i} = \{(\lambda + m\theta)z_{1}A_{i}^{0} + \mu C_{i}^{2} + u : | (\lambda + m\theta)z_{1}A_{i}^{0} + \mu C_{i}^{2} + u | < R\},$$

where  $(\lambda + m\theta) \in S_2, \mu \in S_1, u \in \mathbb{Z}$ , and i = 1, 2.

It follows that the set  $\Gamma(M_1) \cap K$  is finite; then,  $\Gamma$  acts properly on  $\mathbb{R}^3$ .

We recall the following theorem:

Theorem [29]: Let G be a discrete group acting continuously on a locally compact topological space E. Each orbit is closed and discrete in E, and the space of orbits E/G is a Hausdorff space.

By this theorem, it follows, in particular, that any points  $M_1 = (x_1, y_1, z_1)$  and  $M_2 = (x_2, y_2, z_2)$  of  $\mathbb{R}^3$  not equivalent by  $\Gamma$  admit two open neighborhoods  $U_1$  and  $U_2$ such that:  $\Gamma(U_1) \cap U_2 = \phi$ , which proves the proposition.  $\Box$ 

## 4. Conclusions

**Proposition 10.** For all  $A^0$ ,  $C^0$ ,  $C^1$ ,  $A^2$ ,  $C^2 \in \mathbb{Z}^2$  and  $b \in \mathbb{Z}$  satisfying:

 $b_2 \neq 0$ ,  $det(C^0, C^1) \neq 0$  and  $D_3 = mD_2$ , we denote by  $M(A^0, C^0, C^1, b_2)$  the quotient manifold:

$$M(A^{0}, C^{0}, C^{1}, b_{2}) = \mathbb{R}^{3} / \langle (A^{0}, 0, C^{0}), (mA^{0}, 0, C^{1}), (A^{2}, b_{2}, C^{2}) \rangle$$

Then:

-The quotient  $M(A^0, C^0, C^1, b_2)$  is a locally affine, compact, and complete 2-symplectic manifold whose fundamental domain is the parallelepiped built on the vectors:

 $(C^{0}, 0), (C^{1}, 0) and (C^{2}, b_{2});$ 

-The fundamental group is given by:

$$\pi_1(M(A^0, C^0, C^1, b_2)) = \langle (A^0, 0, C^0), (mA^0, 0, C^1), (A^2, b_2, C^2) \rangle;$$

-The manifold  $M(A^0, C^0, C^1, b_2)$  is homeomorphic to the torus  $\mathbb{T}^3$  if and only if  $A^0 = 0$ .

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