



An Analytical Numerical Method for Solving Fuzzy Fractional Volterra Integro-Differential Equations

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Abstract: The modeling of fuzzy fractional integro-differential equations is a very significant matter in engineering and applied sciences. This paper presents a novel treatment algorithm based on utilizing the fractional residual power series (FRPS) method to study and interpret the approximated solutions for a class of fuzzy fractional Volterra integro-differential equations of order $0 < \beta \leq 1$ which are subject to appropriate symmetric triangular fuzzy conditions under strongly generalized differentiability. The proposed algorithm relies upon the residual error concept and on the formula of generalized Taylor. The FRPS algorithm provides approximated solutions in parametric form with rapidly convergent fractional power series without linearization, limitation on the problem's nature, and sort of classification or perturbation. The fuzzy fractional derivatives are described via the Caputo fuzzy H-differentiable. The ability, effectiveness, and simplicity of the proposed technique are demonstrated by testing two applications. Graphical and numerical results reveal the symmetry between the lower and upper *r*-cut representations of the fuzzy solution and satisfy the convex symmetric triangular fuzzy number. Notably, the symmetric fuzzy solutions on a focus of their core and support refer to a sense of proportion, harmony, and balance. The obtained results reveal that the FRPS scheme is simple, straightforward, accurate and convenient to solve different forms of fuzzy fractional differential equations.

Keywords: fuzzy fractional Volterra integro-differential equations; Caputo fractional derivative; fractional residual power series

1. Introduction

Fuzzy theory of fractional differential and integro-differential equations is a new and important branch of fuzzy mathematics. It has ample applications due to the fact that many practical problems in industrial engineering, computer science, physics, artificial intelligence, and operations research may be converted to uncertain process problems of fractional order. The topic of fuzzy fractional integro-differential equations (FFIDEs) has gained the attention of researchers in recent times because it is considered a powerful tool by which to present vague parameters and to handle with their dynamical systems in natural fuzzy environments. Indeed, it has a great significance in the fuzzy analysis theory and its applications in fuzzy control models, artificial intelligence, quantum optics, measure theory, and atmosphere, etc. [1–4]. In several cases, information about the real-life problems included is always pervaded with uncertainty. This uncertainty results from several factors, such as measurement errors, deficient data or if the constraint conditions are determined. So, it is necessary



to have some mathematical tools to understand this uncertainty. Consequently, to form a convenient and applicable algorithm is important to achieve a mathematical structure that would suitably process FFIDEs and solve them.

Most FFIDE problems cannot be solved analytically, and hence, finding good approximate solutions using numerical methods will be very valuable. Recently, numerous scholars have devoted their interest to studying and investigating solutions to FFIDEs utilizing different numerical and analytical techniques; these solutions include the Fuzzy Laplace transforms technique [5], two-dimensional Legendre wavelet technique [6], Adomian decomposition technique [7], variational iteration technique [8], and the fitted reproducing kernel Hilbert space technique [9]. Besides that, other scholars have shown an interest in the existence and uniqueness of the solutions for FDEs. (For more details, see [10–14].) Applications of the RPS scheme are extensive and numerous, especially for the simulation of models of integer order. Such approaches have recently been developed as a powerful numerical tool for treating different problems of arbitrary order. From a methodological point of view, the Volterra integro-differential equations considered in this study under uncertainty concerned with fractional derivatives are simply generalizations of classical forms, provided that $\beta = 1$, which have various uses in physics and engineering, including in dynamical systems, nonlinear propagation of a traveling wave, damped nonlinear string, electronics, and telecommunications, etc.

The present work aims to expand the applications of the fractional residual power series (FRPS) technique to determine approximated solutions for a class of fuzzy fractional Volterra integro-differential equations (FFVIDEs) subject to certain fuzzy initial conditions in the following form:

$$D_{a^{+}}^{\beta}y(x) + \int_{a}^{x}\varphi(x,t)y(t)dt = g(x), \ x \ge a, \ 0 < \beta \le 1,$$
(1)

with the fuzzy initial conditions

$$y(a) = y_0 \tag{2}$$

where λ is a parameter, $g : [a, b] \to \mathbb{R}_{\mathcal{F}}$ is a continuous fuzzy-valued function, $\varphi(x, t)$ is a continuous crisp arbitrary kernel function, $D_{a^+}^{\beta}$ is the fuzzy fractional derivative in Caputo sense, $y_0 \in \mathbb{R}_{\mathcal{F}}$ and y(x) is unknown analytical fuzzy function to be determined. Throughout this paper, $\mathbb{R}_{\mathcal{F}}$ stands for the set of all fuzzy numbers on the real line \mathbb{R} .

The FRPS technique developed in [19] is considered an easy and applicable tool to create a power series solution for strongly linear and nonlinear equations without being linearized, discretized, or exposed to perturbation [20–27]. This technique is featured by the following characteristics: firstly, the method provides the solutions in Taylor expansions; therefore, the exact solutions will be available when the solutions are polynomials. Secondly, the solutions along with their derivatives can be applied for each arbitrary point in the given interval. Thirdly, the method does not require modifications while converting from the lower to the higher order. Consequently, this method can be easily and directly applied to the given system by selecting an appropriate value for the initial guesses/approximations. Fourthly, the FRPS technique needs minor computational requirements with less time and more accuracy.

The remainder of the current paper is structured as follows: In the next section, some essential notations, definitions, and results relating to fuzzy calculus and fuzzy fractional calculus are shown. The process to solve fuzzy FVIDEs is discussed in Section 3. In Section 4, the construction of solutions using the FRPS algorithm is presented. Numerical examples will be performed to show the capability, potentiality and simplicity of the method. The last section of the current paper is a conclusion.

2. Overview of Fuzzy Calculus and Fuzzy Fractional Calculus

In the current section, the essential notations, definitions and the basic results relating to fuzzy calculus and fuzzy fractional calculus are presented. In general, a fuzzy number ρ is a fuzzy subset of

 \mathbb{R} with normal, convex, and upper semi-continuous membership function of bounded support. For more details, refer to [13,28–34].

Definition 1. [28] A fuzzy number ρ is a mapping such that $\rho : \mathbb{R} \to [0, 1]$ with the following properties:

- 1. ρ is fuzzy convex, that is, $\rho(\lambda s + (1 \lambda)t) \ge \min\{\rho(s), \rho(t)\}$ for all $s, t \in \mathbb{R}, \lambda \in [0, 1]$.
- 2. ρ is normal, that is, $\exists s_* \in \mathbb{R}$ for which $\rho(s_*) = 1$.
- 3. ρ is upper-semi continuous, that is, $\rho(s_*) \ge \lim_{s \to s^+} \rho(s)$ for any $s_* \in \mathbb{R}$.
- 4. $supp(\rho) = \{s \in \mathbb{R} : \rho(s) > 0\}$ is the support of ρ , and $\overline{\{s \in \mathbb{R} : \rho(s) > 0\}}$ is compact, where $\overline{\{*\}}$ denotes the closure of a subset.

The parametric form or the *r*-cut representation of a fuzzy number $\rho \in \mathbb{R}_{\mathcal{F}}$, is defined as: $[\rho]^r = \{s \in \mathbb{R} : \rho(s) \ge r\}$, if $r \in (0, 1]$, and $[\rho]^r = \overline{supp(\rho)}$, if r = 0. Clearly, the parametric form of ρ is closed and bounded interval $[\rho_{1r}, \rho_{2r}]$ in which ρ_{1r} is the lower *r*-cut representation of ρ , and ρ_{2r} is the upper *r*-cut representation of ρ . An equivalent parametric definition is also given in [13] as follows:

Definition 2. [28] A fuzzy number ρ in parametric form is a pair (ρ_1, ρ_2) of functions $\rho_1(r)$, $\rho_2(r)$, for $r \in [0, 1]$, which satisfy the following requirements:

- 1. $\rho_1(r)$ is a bounded non-decreasing left continuous for each $r \in (0, 1]$, and right continuous at r = 0.
- 2. $\rho_2(r)$ is a bounded non-increasing left continuous for each $r \in (0, 1]$, and right continuous at r = 0.
- 3. $\rho_1(r) \le \rho_2(r)$, for each $r \in [0, 1]$.

The metric structure of $\mathbb{R}_{\mathcal{F}}$ is defined by the Hausdorff distance mapping $\mathcal{D}_H : \mathbb{R}_{\mathcal{F}} \times \mathbb{R}_{\mathcal{F}} \to \mathbb{R}^+ \cup \{0\}$ such that $\mathcal{D}_H(\rho, \omega) = \sup_{0 \le r \le 1} \max\{|\rho_{1r} - \omega_{1r}|, |\rho_{2r} - \omega_{2r}|\}$, for arbitrary fuzzy numbers ρ and ω . The metric $(\mathbb{R}_{\mathcal{F}}, \mathcal{D}_H)$ has been proved in [30] as complete metric space.

The next definition explains the concept of strongly generalized differentiability, which was introduced by Bede and Gal in [31], to obtain solutions which have a decreasing length of their support, and hence, a decreasing level of uncertainty.

Definition 3. Let $y : (a, b) \to \mathbb{R}_{\mathcal{F}}$ and for fixed $x_0 \in (a, b)$. *y* is called a strongly generalized differentiable at x_0 , if there is an element $y'(x_0) \in \mathbb{R}_{\mathcal{F}}$ such that either:

- 1. The H-differences $y(x_0 + \xi) \ominus y(x_0)$, $y(x_0) \ominus y(x_0 \xi)$ exist, for each $\xi > 0$ sufficiently tends to 0 and $\lim_{\xi \to 0^+} \frac{y(x_0 + \xi) \ominus y(x_0)}{\xi} = y'(x_0) = \lim_{\xi \to 0^+} \frac{y(x_0) \ominus y(x_0 \xi)}{\xi},$
- 2. The H-differences $y(x_0) \ominus y(x_0 + \xi), y(x_0 \xi) \ominus y(x_0)$ exist, for each $\xi > 0$ sufficiently tends to 0 and $\lim_{\xi \to 0^+} \frac{y(x_0) \ominus y(x_0 + \xi)}{-\xi} = y'(x_0) = \lim_{\xi \to 0^+} \frac{y(x_0 - \xi) \ominus y(x_0)}{-\xi}.$

where the limit here is taken in the complete metric space $(\mathbb{R}_{\mathcal{F}}, \mathcal{D}_H)$.

Definition 4. Let $y : [a,b] \to \mathbb{R}_{\mathcal{F}}$. Then the function y is continuous at $x_0 \in [a,b]$ if for every $\varepsilon > 0$, $\exists \delta = \delta(x_0, \varepsilon) > 0$ such that $\mathcal{D}_H(y(x), y(x_0)) < \varepsilon$, for each $x \in [a,b]$, whenever $|x - x_0| < \delta$.

The concept of fuzzy integral functions was first presented in 1982 by Dubois and Prade. Since then, many approaches have been proposed, such as Riemann integral approach by Goetschel and Voxman [29] and Lebesgue-type approach by Kaleva [28]. In this article, we will use the Riemann integral approach, which is characterized by dealing with fuzzy-valued function integration.

Definition 5. [29] Let $y: \Omega \to \mathbb{R}_{\mathcal{F}}$ be a continuous fuzzy-valued function. For each partition $\wp = \{x_0^*, x_1^*, \dots, x_n^*\}$ of Ω and for arbitrary point $\eta_i \in [x_{i-1}^*, x_i^*], 1 \le i \le n$. Let $\Psi_{\wp} = \sum_{i=1}^n y_i(\eta_i)(x_i^* - x_{i-1}^*)$

and $\Delta = \max_{1 \le i \le n} |x_i^* - x_{i-1}^*|$. Then, the definite integral of y(x) over Ω is defined by $\int_{\Omega} y(x) dx = \lim_{\Delta \to 0} \Psi_{\wp}$ provided that the limit exists in the metric space $(\mathbb{R}_{\mathcal{F}}, \mathcal{D}_H)$.

The theorems below were proposed and studied by Chalco-Cano and Roman-Flores in [32] to assist us to convert the fuzzy fractional differential equations (FFDEs) into a system of ordinary fractional differential equations (OFDEs), ignoring the fuzzy setting approach.

Theorem 1. Suppose that $y : [a, b] \to \mathbb{R}_{\mathcal{F}}$, where $[y(x)]^r = [y_{1r}(x), y_{2r}(x)], r \in [0, 1]$,

- 1. If y is (1)-differentiable on [a,b], then y_{1r} and y_{2r} are two differentiable functions on [a,b], and $[D_1^1y(x)]^r = [y'_{1r}(x), y'_{2r}(x)]$,
- 2. If y is (2)-differentiable on [a,b], then y_{1r} and y_{2r} are two differentiable functions on [a,b], and $[D_2^1y(x)]^r = [y'_{2r}(x), y'_{1r}(x)].$

Theorem 2. Let $y : [a,b] \to \mathbb{R}_F$ be continuous fuzzy-valued function and put $[y(x)]^r = [y_{1r}(x), y_{2r}(x)]$ for each $r \in [0,1]$, then $\int_a^b y(x)dx$ exist, belong to \mathbb{R}_F , $y_{1r}(x)$ and $y_{2r}(x)$ are integrable functions on [a,b] and $\left[\int_a^b y(x)dx\right]^r = \left[\int_a^b y_{1r}(x)dx, \int_a^b y_{2r}(x)dx\right], r \in [0,1].$

Definition 6. Let $y: [a,b] \to \mathbb{R}_{\mathcal{F}}$ and $y \in C^{\mathcal{F}}[a,b] \cap L^{\mathcal{F}}[a,b]$. One can say y is Caputo fuzzy *H*-differentiable at x when $D_{a^+}^{\beta}y(x) = \frac{1}{\Gamma(1-\beta)} \int_a^x \frac{y'(\zeta)}{(x-\zeta)^{\beta}} d\zeta$ exists, where $0 < \beta \leq 1$. As well, we say that y is Caputo $[(1) - \beta]$ differentiable when y is (1)-differentiable and y is Caputo $[(2) - \beta]$ differentiable when y is (2)-differentiable, where $C^{\mathcal{F}}[a,b]$ and $L^{\mathcal{F}}[a,b]$ stand for the space of all continuous and Lebesque integrable fuzzy-valued functions on [a,b], respectively.

Theorem 3. Let $0 < \beta \le 1$ and $y \in C^{\mathcal{F}}[a, b]$. Then, for each $r \in [0, 1]$, the Caputo fuzzy fractional derivative exists on (a, b) such that

$$\begin{bmatrix} D_{a+}^{\beta} y(x) \end{bmatrix}^{r} = \begin{bmatrix} \frac{1}{\Gamma(1-\beta)} \int_{a}^{x} \frac{y_{1r}'(\zeta)}{(x-\zeta)^{\beta}} d\zeta , \frac{1}{\Gamma(1-\beta)} \int_{a}^{x} \frac{y_{2r}'(\zeta)}{(x-\zeta)^{\beta}} d\zeta \end{bmatrix} for (1)-differentiable,$$
$$\begin{bmatrix} D_{a+}^{\beta} y(x) \end{bmatrix}^{r} = \begin{bmatrix} \frac{1}{\Gamma(1-\beta)} \int_{a}^{x} \frac{y_{2r}'(\zeta)}{(x-\zeta)^{\beta}} d\zeta , \frac{1}{\Gamma(1-\beta)} \int_{a}^{x} \frac{y_{1r}'(\zeta)}{(x-\zeta)^{\beta}} d\zeta \end{bmatrix} for (2)-differentiable.$$

3. Formulation of Fuzzy Fractional Volterra IDEs

In the current section, the fuzzy fractional Volterra integro-differential equations (FFVIDEs) will be thoroughly studied using three main concepts, namely: strongly generalized differentiability, Caputo's H-differentiability and Riemann integrability, where the FFVIDEs are converted into corresponding system of crisp ordinary fractional Volterra integro-differential equations (OFVIDEs) for every differentiability type. The (FFVIDEs) will be appropriately solved if the initial value is a fuzzy number and the solution is a fuzzy function, and then the integral, as well as the derivative, should be individually considered as a fuzzy integral and fuzzy derivative. The formulation of the problem is considered the most significant part of this process. It is the determination process of the parametric form of *g*, the integrability type's selection, the differentiability type's selection, as well as the separation kernel of ϕ . Then, FFVIDEs (1) and (2) are framed as a set of crisp OFVIDEs; as a result, a new form of discretization will be used. Besides that, we assume that without loss of generality $\phi(x, t, y(t)) = \phi(x, t)y(t)$, so we can apply the FRPS technique to solve FFVIDEs (1) and (2).

Now, for all $r \in (0,1]$ and $a \le x \le b$, let the parametric form of the fuzzy functions g(x) and y(x), as $[g(x)]^r = [g_{1r}(x), g_{2r}(x)]$ and $[y(x)]^r = [y_{1r}(x), y_{2r}(x)]$, respectively, as well as $[y(a)]^r = [y_{1r}(x), y_{2r}(x)]$.

 $[y_{1r}(a), y_{2r}(a)] = [y_{0,1r}, y_{0,2r}]$. Hence, one can write the FFVIDEs (1) and (2) in the *r*-cut representation as follows:

$$\left[D_{a+}^{\beta}y(x)\right]^{r} + \lambda \int_{a}^{x} [\phi(x,t,y(t))]^{r} dt = [g(x)]^{r},$$
(3)

where the *r*-cut representation of the function, $[\phi(x,t,y(t))]^r$ is given by: $[\phi(x,t,y(t))]^r = [\phi_{1r}(x,t,y_{1r}(t),y_{2r}(t)),\phi_{2r}(x,t,y_{1r}(t),y_{2r}(t))]$, in which

$$\phi_{1r}(x,t,y_{1r}(t),y_{2r}(t)) = \begin{cases} \varphi(x,t) \ y_{1r}(t), \ \varphi(x,t) \ge 0\\ \varphi(x,t) \ y_{2r}(t), \ \varphi(x,t) < 0 \end{cases} \\ \phi_{2r}(x,t,y_{1r}(t),y_{2r}(t)) = \begin{cases} \varphi(x,t) \ y_{2r}(t), \ \varphi(x,t) \ge 0\\ \varphi(x,t) \ y_{2r}(t), \ \varphi(x,t) \ge 0\\ \varphi(x,t) \ y_{1r}(t), \ \varphi(x,t) < 0 \end{cases}$$

The (*n*)-solution of fuzzy FVIDEs (1) and (2) is a function $y : [a, b] \to \mathbb{R}_F$ that has Caputo $[(n) - \beta]$ -differentiable and satisfies the FFVIDEs (1) and (2). To compute it, we perform the next algorithm.

Algorithm 1: To obtain the (n)-solution of the FFVIDEs (1.1), there are two cases that will be discussed as follows:

Case 1: If y(x) is Caputo [(1)- β]-differentiable, we convert the FFVIDEs (1) and (2) to the following OFVIDEs system:

$$D_{a^{+}}^{\beta} y_{1r}(x) + \lambda \int_{a}^{x} \varphi(x,t) y_{1r}(t) dt = g_{1r}(x) D_{a^{+}}^{\beta} y_{2r}(x) + \lambda \int_{a}^{x} \varphi(x,t) y_{2r}(t) dt = g_{2r}(x),$$
(4)

with initial conditions

$$y_{1r}(a) = y_{0,1r}$$
 and $y_{2r}(a) = y_{0,2r}$ (5)

Then, do the following steps:

- Step 1: Solve the system (4) and (5) for $y_{1r}(x)$ and $y_{2r}(x)$.
- Step 2: Ensure that $[y_{1r}(x), y_{2r}(x)]$ and $\left[D_{a^+}^{\beta}y_{1r}(x), D_{a^+}^{\beta}y_{2r}(x)\right]$ are valid level sets on [a, b] or on a partial interval in [a, b].
- Step 3: Construct a (1)-differentiable solution y(x) whose *r*-cut representation is $[y_{1r}(x), y_{2r}(x)]$.

Case 2: If y(x) is Caputo [(2)- β]-differentiable, we convert the FFVIDEs (1) and (2) to the following OFVIDEs system:

$$D_{a+}^{\beta} y_{1r}(x) + \lambda \int_{a}^{x} \varphi(x,t) y_{2r}(t) dt = g_{2r}(x),$$

$$D_{a+}^{\beta} y_{2r}(x) + \lambda \int_{a}^{x} \varphi(x,t) y_{1r}(t) dt = g_{1r}(x),$$
(6)

with initial conditions

$$y_{1r}(a) = y_{0,1r}$$
 and $y_{2r}(a) = y_{0,2r}$. (7)

Then, do the following steps:

- Step 1: Solve the system (6) and (7) for $y_{1r}(x)$ and $y_{2r}(x)$.
- Step 2: Ensure that $[y_{1r}(x), y_{2r}(x)]$ and $\left[D_{a^+}^{\beta}y_{2r}(x), D_{a^+}^{\beta}y_{1r}(x)\right]$ are valid level sets on [a, b] or on a partial interval in [a, b].
- Step 3: Construct a (2)-differentiable solution y(x) whose *r*-cut representation is $[y_{1r}(x), y_{2r}(x)]$.

The previous formulation of FFVIDEs (1) and (2) along with Theorem 1 shows us how to deal with the numerical solutions of FFVIDEs. The original FFVIDEs can be converted into a system of OFVIDEs equivalently. As a consequence of this, we can employ the numerical approaches directly to solve the system OFVIDEs obtained without the need for reformulation in the fuzzy setting.

4. Description of the FRPS Technique

In the present section, we show the procedure of FRPS algorithm in order to study and construct analytic-numeric approximated solutions for FFVIDEs (1) and (2) through substituting the expansion of its fractional power series (FPS) among its truncated residual functions. In view of that, the resultant equation helps us derive a recursion formula for the coefficients' computation, where the FPS expansion's coefficients can be computed recursively through recurrent fractional differentiating of the truncated residual function.

Definition 7. [22] A fractional power series (FPS) representation at x_0 has the following form

$$\sum_{n=0}^{\infty} c_n (x-x_0)^{n\beta} = c_0 + c_1 (x-x_0)^{\beta} + c_2 (x-x_0)^{2\beta} + \dots$$

where $0 \le m - 1 < \beta \le m$, $x \ge x_0$ and c_n 's are the coefficients of the series.

Theorem 4. [22] Suppose that f has the following FPS representation at x_0

$$f(x) = \sum_{n=0}^{\infty} c_n (x - x_0)^{n\beta}.$$

where $f(x) \in C[x_0, x_0 + R)$ and $D_{x_0}^{n\beta} f(x) \in C(x_0, x_0 + R)$ for n = 0, 1, 2, ..., then the coefficients c_n will be in the form $c_n = \frac{D_{x_0}^{n\beta} f(x_0)}{\Gamma(1+n\beta)}$ such that $D_{x_0}^{n\beta} = D_{x_0}^{\beta} \cdot D_{x_0}^{\beta} \cdot ... \cdot D_{x_0}^{\beta}$ (*n*-times).

Conveniently, to obtain the (n)-solution of FFVIDEs (1) and (2), we will explain the fashion to determine (1)-solution equivalent to the solution for the system of OFVIDEs (4) and (5). Further, the same manner can be applied to construct (2)-solution. To reach our purpose, assume that the approximated solutions of OFVIDEs (4) and (5) at $x_0 = 0$ have the following form:

$$y_{1r}(x) = \sum_{n=0}^{\infty} c_n \frac{x^{n\beta}}{\Gamma(n\beta+1)},$$

$$y_{2r}(x) = \sum_{n=0}^{\infty} d_n \frac{x^{n\beta}}{\Gamma(n\beta+1)}.$$
(8)

Since $y_{1r}(x)$ and $y_{2r}(x)$ satisfy the initial condition (5), then $y_{1r}(0) = y_{0,1r} = c_0$ and $y_{2r}(0) = y_{0,2r} = d_0$ will be the initial guesses for (5), so the series solutions can be written as

$$y_{1r}(x) = c_0 + \sum_{n=1}^{\infty} c_n \frac{x^{n\beta}}{\Gamma(n\beta+1)},$$

$$y_{2r}(x) = d_0 + \sum_{n=1}^{\infty} d_n \frac{x^{n\beta}}{\Gamma(n\beta+1)}.$$
(9)

Further, we can approximate $y_{1r}(x)$ and $y_{2r}(x)$ by the following *k*th-truncated series solutions:

$$y_{k,1r}(x) = c_0 + \sum_{n=1}^k c_n \frac{x^{n\beta}}{\Gamma(n\beta+1)},$$

$$y_{k,2r}(x) = d_0 + \sum_{n=1}^k d_n \frac{x^{n\beta}}{\Gamma(n\beta+1)}.$$
(10)

Define the so-called *k*th-residual functions $Res_{k,1r}$ and $Res_{k,2r}$, for k = 1, 2, 3, ...,

$$Res_{k,1r}(x) = D_{0+}^{\beta} y_{k,1r}(x) + \lambda \int_{0}^{x} \varphi(x,t) y_{k,1r}(t) dt - g_{1r}(x),$$

$$Res_{k,2r}(x) = D_{0+}^{\beta} y_{k,2r}(x) + \lambda \int_{0}^{x} \varphi(x,t) y_{k,2r}(t) dt - g_{2r}(x).$$
(11)

and the following residual functions

$$Res_{1r}(x) = \lim_{k \to \infty} Res_{k,1r}(x) = D_{0+}^{\beta} y_{1r}(x) + \lambda \int_{0}^{x} \varphi(x,t) y_{1r}(t) dt - g_{1r}(x),$$

$$Res_{2r}(x) = \lim_{k \to \infty} Res_{k,2r}(x) = D_{0+}^{\beta} y_{2r}(x) + \lambda \int_{0}^{x} \varphi(x,t) y_{2r}(t) dt - g_{2r}(x).$$
(12)

Clear that, $Res_{nr}(x) = 0$, for n = 1, 2 and for each $x \ge 0$, which leads to $D_{0^+}^{(m-1)\beta}Res_{nr}(x) = 0$. Also, we have $D_{0^+}^{(m-1)\beta}Res_{nr}(0) = D_{0^+}^{(m-1)\beta}Res_{k,nr}(0) = 0$, for each m = 0, 1, 2, ..., k. However, $D_{0^+}^{(k-1)\beta}Res_{k,nr}(0) = 0$ holds for n = 1, 2.

According to applying FRPS technique to find the 1st-unknown coefficients c_1 and d_1 , substitute the 1st-approximated solutions $y_{1,1r}(x) = c_0 + c_1 \frac{x^{\beta}}{\Gamma(\beta+1)}$ and $y_{1,2r}(x) = d_0 + d_1 \frac{x^{\beta}}{\Gamma(\beta+1)}$ into the 1st residual functions $Res_{1,1r}(x)$ and $Res_{1,2r}(x)$ of (12) such that

$$\begin{aligned} \operatorname{Res}_{1,1r}(x) &= D_{0^+}^{\beta} y_{1,1r}(x) + \lambda \int_0^x \varphi(x,t) y_{1,1r}(t) dt - g_{1r}(x), \\ &= c_1 + \lambda \int_a^x \varphi(x,t) \left(c_0 + c_1 \frac{t^{\beta}}{\Gamma(\beta+1)} \right) dt - g_{1r}(x), \\ \operatorname{Res}_{1,2r}(x) &= D_{0^+}^{\beta} y_{1,2r}(x) + \lambda \int_0^x \varphi(x,t) y_{1,2r}(t) dt - g_{2r}(x), \\ &= d_1 + \lambda \int_a^x \varphi(x,t) \left(d_0 + d_1 \frac{t^{\beta}}{\Gamma(\beta+1)} \right) dt - g_{2r}(x). \end{aligned}$$
(13)

Using the facts $Res_{1,1r}(0) = Res_{1,2r}(0) = 0$, yields

$$c_{1} = \left(\frac{g_{1r}(x) - \lambda c_{0} \int_{0}^{x} \varphi(x, t) dt}{1 + \frac{\lambda}{\Gamma(\beta+1)} \int_{0}^{x} t^{\beta} \varphi(x, t) dt}\right)_{x=0} \text{ and } d_{1} = \left(\frac{g_{2r}(x) - \lambda d_{0} \int_{0}^{x} \varphi(x, t) dt}{1 + \frac{\lambda}{\Gamma(\beta+1)} \int_{0}^{x} t^{\beta} \varphi(x, t) dt}\right)_{x=0}.$$
 (14)

Again, to determine the 2nd-unknown coefficients c_2 and d_2 , substitute the 2nd-approximated solutions $y_{2,1r}(x) = c_0 + c_1 \frac{x^{\beta}}{\Gamma(\beta+1)} + c_2 \frac{x^{2\beta}}{\Gamma(2\beta+1)}$ and $y_{2,2r}(x) = d_0 + d_1 \frac{x^{\beta}}{\Gamma(\beta+1)} + d_2 \frac{x^{2\beta}}{\Gamma(2\beta+1)}$ into the 2nd-residual functions $Res_{2,1r}(x)$ and $Res_{2,2r}(x)$ of (11) such that

$$\begin{aligned} \operatorname{Res}_{2,1r}(x) &= D_{0+}^{\beta} y_{2,1r}(x) + \lambda \int_{0}^{x} \varphi(x,t) y_{2,1r}(t) dt - g_{1r}(x),\\ \operatorname{Res}_{2,2r}(x) &= D_{0+}^{\beta} y_{2,2r}(x) + \lambda \int_{0}^{x} \varphi(x,t) y_{2,2r}(t) dt - g_{2r}(x). \end{aligned}$$
(15)

Then, by applying the fractional derivative $D_{0^+}^{\beta}$ on both sides of $Res_{2,1r}(x)$ and $Res_{2,2r}(x)$, as well using the facts $D_{0^+}^{\beta} Res_{2,1r}(0) = D_{0^+}^{\beta} Res_{2,2r}(0) = 0$, the values of c_2 and d_2 will be given by

$$c_{2} = \begin{pmatrix} \frac{D_{0^{+}}^{\beta} g_{1r}(x) - \lambda \int_{0}^{x} \left(c_{0} + c_{1} \frac{t^{\beta}}{\Gamma(\beta+1)} \right) D_{0^{+}}^{\beta} \varphi(x,t) dt}{1 + \frac{\lambda}{\Gamma(2\beta+1)} \int_{0}^{x} t^{2\beta} D_{0^{+}}^{\beta} \varphi(x,t) dt} \end{pmatrix}_{x=0},$$

$$d_{2} = \begin{pmatrix} \frac{D_{0^{+}}^{\beta} g_{2r}(x) - \lambda \int_{0}^{x} \left(d_{0} + d_{1} \frac{t^{\beta}}{\Gamma(\beta+1)} \right) D_{0^{+}}^{\beta} \varphi(x,t) dt}{1 + \frac{\lambda}{\Gamma(2\beta+1)} \int_{0}^{x} t^{2\beta} D_{0^{+}}^{\beta} \varphi(x,t) dt} \end{pmatrix}_{x=0}.$$
(16)

In the same way for the 3rd-unknown coefficients, c_3 and d_3 , substitute the 3rd-approximated solutions $y_{3,1r}(x) = c_0 + \sum_{n=1}^{3} c_n \frac{x^{n\beta}}{\Gamma(n\beta+1)}$ and $y_{3,2r}(x) = d_0 + \sum_{n=1}^{3} d_n \frac{x^{n\beta}}{\Gamma(n\beta+1)}$ into the 3rd-residual functions $Res_{3,1r}(x)$ and $Res_{3,2r}(x)$ of (11) and then by computing $D_{0^+}^{2\beta} Res_{3,1r}(x)$ and $D_{0^+}^{2\beta} Res_{3,2r}(x)$ and using the facts $D_{0^+}^{2\beta} Res_{3,1r}(0) = D_{0^+}^{2\beta} Res_{3,2r}(0) = 0$, the coefficients, c_3 and d_3 will be given such that

$$c_{3} = \left(\frac{D_{0^{+}}^{2\beta} g_{1r}(x) - \lambda \int_{0}^{x} \left(c_{0} + c_{1} \frac{t^{\beta}}{\Gamma(\beta+1)} + c_{2} \frac{t^{2\beta}}{\Gamma(2\beta+1)}\right) D_{0^{+}}^{2\beta} \varphi(x,t)dt}{1 + \frac{\lambda}{\Gamma(3\beta+1)} \int_{0}^{x} t^{3\beta} D_{0^{+}}^{2\beta} \varphi(x,t)dt}\right)_{x=0}, \qquad (17)$$

$$d_{3} = \left(\frac{D_{0^{+}}^{2\beta} g_{2r}(x) - \lambda \int_{0}^{x} \left(d_{0} + d_{1} \frac{t^{\beta}}{\Gamma(\beta+1)} + d_{2} \frac{t^{2\beta}}{\Gamma(2\beta+1)}\right) D_{0^{+}}^{2\beta} \varphi(x,t)dt}{1 + \frac{\lambda}{\Gamma(3\beta+1)} \int_{0}^{x} t^{3\beta} D_{0^{+}}^{2\beta} \varphi(x,t)dt}\right)_{x=0}.$$

The process can be repeated, as can the coefficients, until an arbitrary order of the FPS solution for OFVIDEs (4) and (5) is obtained.

5. Applications and Simulations

The dynamic behavior for fractional systems has gained a lot of prominence over the past few years, mainly because fractional operators have become excellent mathematical tools in modeling many real-life problems, helping us understand the mathematical structure and memory effect. The solution of fractional integro-differential equations, in the Volterra sense, is very important to describe the behavior of linear and non-linear physical systems, in particular, the dynamics of nuclear reactors, and systems which are harmonically excited, or to calculate the probabilistic response of randomly-excited analytical models and so forth. As a matter of terminology, the Volterra series refers to a functional expansion of a dynamic, nonlinear, and time-invariant functional. This section tests two FFIDEs of Volterra type in order to demonstrate the efficiency, accuracy, and applicability of the present novel approach. Here, all necessary calculations and analyses are done using Mathematica 10.

Example 1. Consider the following FFIDE of Volterra type

$$D_{0^{+}}^{\beta}y(x) = [r+1, 2-r]\left(1+x^{\beta}\right) + \frac{1}{\Gamma(\beta)}\int_{0}^{x}(x-t)^{\beta-1}y(t)dt, \ 0 < \beta \le 1, \ x \in [0,1],$$
(18)

with the fuzzy initial condition

$$y(0) = 0.$$
 (19)

Based on the type of differentiability, fuzzy FVIDEs (18) and (19) can be converted to one of the following systems:

Case1: Under Caputo [(1)- β]-differentiability, the system of OFVIDEs corresponding to Caputo [(1)- β]-differentiable is

$$D_{0+}^{\beta}y_{1r}(x) = (r+1)(1+x^{\beta}) + \frac{1}{\Gamma(\beta)}\int_{0}^{x}(x-t)^{\beta-1}y_{1r}(t)dt,$$

$$D_{0+}^{\beta}y_{2r}(x) = (2-r)(1+x^{\beta}) + \frac{1}{\Gamma(\beta)}\int_{0}^{x}(x-t)^{\beta-1}y_{2r}(t)dt,$$
(20)

with the initial conditions

$$y_{1r}(0) = 0, \ y_{2r}(0) = 0.$$
 (21)

If $\beta = 1$, then the exact solutions of OFVIDEs (20) and (21) are given by

$$[y(x)]^{r} = [r+1, 2-r](e^{x}-1).$$
⁽²²⁾

Accordingly, the last description of FRPS algorithm, starting with $y_{0,1r}(0) = y_{0,2r}(0) = 0$, then the *k*th-approximated solutions for the system (20) and (21) are given by

$$y_{k,1r}(x) = \sum_{n=1}^{k} c_n \frac{x^{n\beta}}{\Gamma(n\beta+1)}, y_{k,2r}(x) = \sum_{n=1}^{k} d_n \frac{x^{n\beta}}{\Gamma(n\beta+1)}.$$
(23)

Consequently, the *k*th-residual functions $Res_{k,1r}$, and $Res_{k,2r}$ for (20) will be

$$Res_{k,1r}(x) = D_{0^+}^{\beta} y_{k,1r}(x) - \frac{1}{\Gamma(\beta)} \int_0^x (x-t)^{\beta-1} y_{k,1r}(t) dt - (r+1)(1+x^{\beta}),$$

$$Res_{k,2r}(x) = D_{0^+}^{\beta} y_{k,2r}(x) - \frac{1}{\Gamma(\beta)} \int_0^x (x-t)^{\beta-1} y_{k,2r}(t) dt - (2-r)(1+x^{\beta}).$$
(24)

The coefficients of the FRPS approximate solutions for the system (20) and (21) can be found in Appendix A.

To demonstrate the agreement between the lower and upper bound of the (1)-approximated solutions, the 7th-FRPS approximated solutions of Example 1, case 1 with different values of β and r = 0.5, are shown in Table 1.

β_i	7th-FRPS Approximated Solutions
$\frac{1}{4}$	$y_7(x) = \frac{3\Gamma(1/4)\sqrt{x}}{4\sqrt{\pi}} + \frac{3\Gamma(1/4)x}{8} + \frac{\Gamma(1/4)x^{3/2}}{2\sqrt{\pi}} + \frac{3x^{1/4}}{2\Gamma(5/4)} + \frac{3x^{3/4}}{2\Gamma(7/4)} + \frac{3x^{5/4}}{2\Gamma(9/4)} + \frac{3x^{7/4}}{2\Gamma(11/4)}$
$\frac{1}{2}$	$y_7(x) = rac{3\sqrt{x}}{\sqrt{\pi}} + rac{3\sqrt{\pi}x}{4} + rac{2x^{3/2}}{\sqrt{\pi}} + rac{3\sqrt{\pi}x^2}{8} + rac{4x^{5/2}}{5\sqrt{\pi}} + rac{\sqrt{\pi}x^3}{8} + rac{8x^{7/2}}{35\sqrt{\pi}}$
$\frac{3}{4}$	$y_7(x) = \frac{3\Gamma(3/4)x^{3/2}}{2\sqrt{\pi}} + \frac{3\Gamma(3/4)x^3}{16} + \frac{4\Gamma(3/4)x^{9/2}}{105\sqrt{\pi}} + \frac{3x^{3/4}}{2\Gamma(7/4)} + \frac{3x^{9/4}}{2\Gamma(13/4)} + \frac{3x^{15/4}}{2\Gamma(19/4)} + \frac{3x^{21/4}}{2\Gamma(25/4)}$
1	$y_7(x) = \frac{3}{2}x + \frac{3}{4}x^2 + \frac{1}{4}x^3 + \frac{1}{16}x^4 + \frac{1}{80}x^5 + \frac{1}{480}x^6 + \frac{1}{3360}x^7$

Table 1. The (1)-approximated solution of Example 1, case 1 for different values of β with r = 0.5.

Case2: Under Caputo $[(2)-\beta]$ -differentiability, the system of OFVIDEs corresponding to Caputo $[(2)-\beta]$ -differentiable is

$$D_{0+}^{\beta}y_{1r}(x) = (r+1)(1+x^{\beta}) + \frac{1}{\Gamma(\beta)} \int_{0}^{x} (x-t)^{\beta-1}y_{2r}(t)dt,$$

$$D_{0+}^{\beta}y_{2r}(x) = (2-r)(1+x^{\beta}) + \frac{1}{\Gamma(\beta)} \int_{0}^{x} (x-t)^{\beta-1}y_{1r}(t)dt,$$
(25)

with the initial conditions

$$y_{1r}(0) = 0, \ y_{2r}(0) = 0.$$
 (26)

If $\beta = 1$, then the exact solutions of OFVIDEs (25) and (26) are given by

$$[y(x)]^{r} = \frac{3}{2}e^{x} - [2 - r, r + 1] + \frac{1}{2}[1 - 2r, 2r - 1](\cos x - \sin x).$$
⁽²⁷⁾

To apply the FRPS technique, suppose that the *k*th-truncated series solutions of $y_{1r}(x)$ and $y_{2r}(x)$ for the system (25) and (26) about $x_0 = 0$ have the following form:

$$y_{k,1r}(x) = \sum_{n=1}^{k} c_n \frac{x^{n\beta}}{\Gamma(n\beta+1)},$$

$$y_{k,2r}(x) = \sum_{n=1}^{k} d_n \frac{x^{n\beta}}{\Gamma(n\beta+1)}.$$
(28)

Apparently, the *k*th-residual functions $Res_{k,1r}$, and $Res_{k,2r}$ for (25) will be

$$Res_{k,1r}(x) = D_{0^+}^{\beta} y_{k,1r}(x) - \frac{1}{\Gamma(\beta)} \int_0^x (x-t)^{\beta-1} y_{k,2r}(t) dt - (r+1)(1+x^{\beta}),$$

$$Res_{k,2r}(x) = D_{0^+}^{\beta} y_{k,2r}(x) - \frac{1}{\Gamma(\beta)} \int_0^x (x-t)^{\beta-1} y_{k,1r}(t) dt - (2-r)(1+x^{\beta}).$$
(29)

The coefficients of the FRPS approximate solutions for the system (25) and (26) can be found in Appendix A.

In Table 2, the 7th-FRPS approximated solutions of Example 1, case 2 with different values of β and r = 0.5 are computed.

Table 2. The (2)-approximated solution of Example 5.1, case 2 for different values of β with r = 0.5.

β_i	7th-FRPS Approximated Solutions
$\frac{1}{4}$	$y_7(x) = \frac{3\Gamma(1/4)\sqrt{x}}{4\sqrt{\pi}} + \frac{3\Gamma(1/4)x}{8} + \frac{\Gamma(1/4)x^{3/2}}{2\sqrt{\pi}} + \frac{3x^{1/4}}{2\Gamma(5/4)} + \frac{3x^{3/4}}{2\Gamma(7/4)} + \frac{3x^{5/4}}{2\Gamma(9/4)} + \frac{3x^{7/4}}{2\Gamma(11/4)}$
$\frac{1}{2}$	$y_7(x) = rac{3\sqrt{x}}{\sqrt{\pi}} + rac{3\sqrt{\pi}x}{4} + rac{2x^{3/2}}{\sqrt{\pi}} + rac{3\sqrt{\pi}x^2}{8} + rac{4x^{5/2}}{5\sqrt{\pi}} + rac{\sqrt{\pi}x^3}{8} + rac{8x^{7/2}}{35\sqrt{\pi}}$
$\frac{3}{4}$	$y_7(x) = \frac{3\Gamma(3/4)x^{3/2}}{2\sqrt{\pi}} + \frac{3\Gamma(3/4)x^3}{16} + \frac{4\Gamma(3/4)x^{9/2}}{105\sqrt{\pi}} + \frac{3x^{3/4}}{2\Gamma(7/4)} + \frac{3x^{9/4}}{2\Gamma(13/4)} + \frac{3x^{15/4}}{2\Gamma(19/4)} + \frac{3x^{21/4}}{2\Gamma(25/4)}$
1	$y_7(x) = \frac{3}{2}x + \frac{3}{4}x^2 + \frac{1}{4}x^3 + \frac{1}{16}x^4 + \frac{1}{80}x^5 + \frac{1}{480}x^6 + \frac{1}{3360}x^7$

Next, the absolute errors for Example 1, at $\beta = 1$, and n = 10, have been obtained in Tables 3 and 4 with different values of *r* and step size 0.2 on [0, 1]. Obviously, from these tables, it can be observed that the FRPS-approximated solutions are in high agreement with the exact solutions.

$y_{1r}(x)$					
x_i	r = 0	r = 0.5	r = 1		
0.2	$5.273559366 imes 10^{-16}$	$7.216449660 imes 10^{-16}$	$1.054711873 \times 10^{-15}$		
0.4	$1.086908341 imes 10^{-12}$	$1.630362511 imes 10^{-12}$	$2.173816682 imes 10^{-12}$		
0.6	$9.565170878 imes 10^{-11}$	$1.434776741 imes 10^{-10}$	$1.913034175 imes 10^{-10}$		
0.8	$2.304785251 \times 10^{-9}$	$3.457177877 imes 10^{-9}$	$4.609570503 \times 10^{-9}$		
$y_{2r}(x)$					
x_i	r = 0	r = 0.5	<i>r</i> = 1		
0.2	$1.054711873 imes 10^{-15}$	$7.216449660 imes 10^{-16}$	$5.273559366 imes 10^{-16}$		
0.4	$2.173816682 imes 10^{-12}$	$1.630362511 imes 10^{-12}$	$1.086908341 \times 10^{-12}$		
0.6	$1.913034175 imes 10^{-10}$	$1.434776741 imes 10^{-10}$	$9.565170877 imes 10^{-11}$		
0.8	$4.609570503 \times 10^{-9}$	$3.457177877 imes 10^{-9}$	$2.304785251 \times 10^{-9}$		

Table 3. Absolute errors for Example 1, case 1, at $\beta = 1$ and n = 10.

Table 4. Absolute errors for Example 1, case 2, at $\beta = 1$ and n = 10.

$y_{1r}(x)$					
x _i	r = 0	<i>r</i> = 0.5	<i>r</i> = 1		
0.2	$1.137978600 \times 10^{-15}$	$8.326672685 imes 10^{-16}$	$4.996003611 \times 10^{-16}$		
0.4	$2.172595439 imes 10^{-12}$	$1.630362512 imes 10^{-12}$	$1.088018564 imes 10^{-12}$		
0.6	$1.910848146 imes 10^{-10}$	$1.434776742 imes 10^{-10}$	$9.587064476 imes 10^{-11}$		
0.8	$4.600237524 \times 10^{-9}$	$3.457178099 imes 10^{-9}$	$2.314118674 \times 10^{-9}$		
$y_{2r}(x)$					
x_i	r = 0	r = 0.5	<i>r</i> = 1		
0.2	$5.551115123 imes 10^{-16}$	$8.326672685 imes 10^{-16}$	$1.193489751 \times 10^{-15}$		
0.4	$1.088018564 imes 10^{-12}$	$1.630362512 imes 10^{-12}$	$2.172595437 imes 10^{-12}$		
0.6	$9.587064476 imes 10^{-11}$	$1.434776742 imes 10^{-10}$	$1.910848146 imes 10^{-10}$		
0.8	$2.314118674 \times 10^{-9}$	$3.457178099 \times 10^{-9}$	$4.600237524 \times 10^{-9}$		

To show the fuzzy behavior of the proposed algorithm, the core and support of fuzzy (*m*)-approximated solutions, m = 1, 2, and its Caputo derivative at $\beta = 1$ of Example 1, are plotted in Figures 1 and 2, where $core(y(x)) = \{\tau \in \mathbb{R} : y(x)(\tau) = 1\}$, and $supp(y(x)) = \{\tau \in \mathbb{R} : y(x)(\tau) \ge 0\}$.



Figure 1. (a) The core and the support of fuzzy (1)-approximated solutions under Caputo $[(1)-\beta]$ -differentiable; (b) The core and the support of derivative of fuzzy (1)-approximated solution under Caputo $[(1)-\beta]$ -differentiable, at $\beta = 1$ of Example 1: gray support and red core.



Figure 2. (a) The core and the support of fuzzy (2)-approximated solutions under Caputo $[(2)-\beta]$ -differentiable; (b) The core and the support of fuzzy (2)-approximated Caputo derivatives solution under Caputo $[(2)-\beta]$ -differentiable, at $\beta = 1$ of Example 1: gray support and red core.

Example 2. Consider the following FFIDE of Volterra type

$$D_{0^{+}}^{\beta}y(x) = [r-1, 1-r] + \int_{0}^{x}y(t)dt, \ 0 < \beta \le 1, \ x \in [0,1],$$
(30)

with the fuzzy initial condition

$$y(0) = 0.$$
 (31)

Based on the type of differentiability, fuzzy FVIDEs (30) and (31) can be converted to one of the following systems:

Case 1: Under Caputo $[(1)-\beta]$ -differentiability, the system of OFVIDEs corresponding to Caputo $[(1)-\beta]$ -differentiable is

$$D_{0^+}^{\beta} y_{1r}(x) = (r-1) + \int_0^x y_{1r}(t) dt,$$

$$D_{0^+}^{\beta} y_{2r}(x) = (1-r) + \int_0^x y_{2r}(t) dt,$$
(32)

with the fuzzy initial condition

$$y_{1r}(0) = 0, y_{2r}(0) = 0.$$
 (33)

If $\beta = 1$, then the exact solution of OFVIDEs (32) and (33) is given by

$$[y(x)]^{r} = [r - 1, 1 - r]sinh(x).$$
(34)

By utilizing the FRPS algorithm as presented previously, beginning with $y_{0,1r} = y_{1r}(0) = 0$, $y_{0,2r} = y_{2r}(0) = 0$, and depending on Equation (10), the *k*th-FRPS approximated solutions $y_{k,1r}(x)$ and $y_{k,2r}(x)$ for the system (32) and (33) are given by

$$y_{k,1r}(x) = \sum_{n=1}^{k} c_n \frac{x^{n\beta}}{\Gamma(n\beta+1)},$$

$$y_{k,2r}(x) = \sum_{n=1}^{k} d_n \frac{x^{n\beta}}{\Gamma(n\beta+1)}.$$
(35)

Consequently, the *k*th-residual functions $Res_{k,1r}$, and $Res_{k,2r}$ for (32) will be

0

$$Res_{k,1r}(x) = D_{0^+}^{\rho} y_{k,1r}(x) - \int_0^x y_{k,1r}(t)dt - (r-1),$$

$$Res_{k,2r}(x) = D_{0^+}^{\beta} y_{k,2r}(x) - \int_0^x y_{k,2r}(t)dt - (1-r).$$
(36)

The coefficients of the FRPS approximate solutions for the system (32) and (33) can be found in Appendix B.

Case 2: Under Caputo [(2)- β]-differentiability, the system of OFVIDEs corresponding to Caputo [(2)- β]-differentiable is

$$D_{0^+}^{\beta} y_{1r}(x) = (1-r) + \int_0^x y_{2r}(t) dt,$$

$$D_{0^+}^{\beta} y_{2r}(x) = (r-1) + \int_0^x y_{1r}(t) dt,$$
(37)

with the initial conditions

$$y_{1r}(0) = 0, \ y_{2r}(0) = 0.$$
 (38)

If $\beta = 1$, then the exact solutions of OFVIDEs (38) and (39) are given by

$$[y(x)]^r = [1 - r, r - 1]\sin(x).$$
(39)

In view of the description for FRPS technique and starting with $y_{0,1r} = y_{1r}(0) = 0$, and $y_{0,2r} = y_{2r}(0) = 0$, then the *k*th-residual functions of Equation (37) will be as follows

$$Res_{k,1r}(x) = D_{0^+}^{\beta} y_{k,1r}(x) - \int_0^x y_{k,2r}(t) dt - (1-r),$$

$$Res_{k,2r}(x) = D_{0^+}^{\beta} y_{k,2r}(x) - \int_0^x y_{k,1r}(t) dt - (r-1).$$
(40)

where $y_{k,1r}(x)$ and $y_{k,2r}(x)$ are given by

$$y_{k,1r}(x) = \sum_{n=1}^{k} c_n \frac{x^{n\beta}}{\Gamma(n\beta+1)},$$

$$y_{k,2r}(x) = \sum_{n=1}^{k} d_n \frac{x^{n\beta}}{\Gamma(n\beta+1)}.$$
(41)

The coefficients of the FRPS approximate solutions for the system (37) and (38) can be found in Appendix B.

To show the accuracy of the FRPS technique, numerical results for Example 2 at $n = 10, r \in \{0.5, 0.75\}$ with some selected grid points in [0, 1] are given in Tables 5 and 6 with different values of β .

Table 5. Numerical results for Example 2, case 1, with different values of β .

$y_{1r}(x)$					
r _i	x_i	$\beta = 1$	$\beta = 0.9$	$\beta = 0.8$	$\beta = 0.7$
0.5	0.2	-0.100668001	-0.123692685	-0.151695235	-0.186264438
	0.4	-0.205376163	-0.238161466	-0.277064940	-0.324760477
0.5	0.6	-0.318326791	-0.359432909	-0.408753265	-0.470283639
	0.8	-0.444052990	-0.494515208	-0.556205023	-0.634532156
	0.2	-0.050334001	-0.061846342	-0.075847617	-0.093132219
0.75	0.4	-0.102688081	-0.119080733	-0.138532470	-0.162380238
0.75	0.6	-0.159163396	-0.179716454	-0.204376633	-0.235141819
	0.8	-0.222026495	-0.247257604	-0.278102512	-0.317266078
$y_{2r}(x)$					
r _i	x_i	$\beta = 1$	$\beta = 0.9$	$\beta = 0.8$	$\beta = 0.7$
	0.2	0.100668001	0.123692685	0.151695235	0.186264438
0 5	0.4	0.205376163	0.238161466	0.277064940	0.324760477
0.5	0.6	0.318326791	0.359432909	0.408753265	0.470283639
	0.8	0.444052990	0.494515208	0.556205023	0.634532156
	0.2	0.050334001	0.061846342	0.075847617	0.093132219
0.75	0.4	0.102688081	0.119080733	0.138532470	0.162380238
0.75	0.6	0.159163396	0.179716454	0.204376633	0.235141819
	0.8	0.222026495	0.247257604	0.278102512	0.317266078

$y_{1r}(x)$					
r _i	x_i	$\beta = 1$	$\beta = 0.9$	$\beta = 0.8$	$\beta = 0.7$
	0.2	0.099334665	0.120583966	0.144646654	0.170765057
	0.4	0.194709171	0.217958708	0.239847027	0.258218270
0.5	0.6	0.282321238	0.299033752	0.310147377	0.313819870
	0.8	0.358678047	0.363060372	0.359026685	0.346425845
	0.2	0.049667333	0.060291983	0.072323327	0.085382529
0.75	0.4	0.097354586	0.108979354	0.119923514	0.129109135
0.75	0.6	0.141160618	0.149516876	0.155073688	0.156909935
	0.8	0.179339023	0.181530186	0.179513342	0.173212923
			$y_{2r}(x)$		
r _i	x_i	$\beta = 1$	$\beta = 0.9$	$\beta = 0.8$	$\beta = 0.7$
	0.2	-0.099334665	-0.120583966	-0.144646654	-0.170765057
0 5	0.4	-0.194709171	-0.217958708	-0.239847027	-0.258218270
0.5	0.6	-0.282321238	-0.299033752	-0.310147377	-0.313819870
	0.8	-0.358678047	-0.363060372	-0.359026685	-0.346425845
0.75	0.2	-0.049667333	-0.060291983	-0.072323327	-0.085382529
	0.4	-0.097354586	-0.108979354	-0.119923514	-0.129109135
	0.6	-0.141160618	-0.149516876	-0.155073688	-0.156909935
	0.8	-0.179339023	-0.181530186	-0.179513342	-0.173212923

Table 6. Numerical results for Example 2, case 2, with different values of β .

For the purpose of comparison, the absolute errors of $y_{1r}(x)$ and $y_{2r}(x)$ of Example 2, case 1, by using the FRPS method and Haar Wavelet (HW) method [35], for n = 8, with fixed value of $\beta = 1$ are given in Table 7. From this table, it can be observed that our method provides us with accurate approximated solutions to OFVIDEs (32) and (33).

$y_{1r}(x)$					
x_i	FRPS Method	HW Method			
0.1	$2.76167 imes 10^{-15}$	4.205×10^{-6}			
0.2	$1.41145 imes 10^{-12}$	$5.305 imes10^{-6}$			
0.3	$5.42854 imes 10^{-11}$	$2.07 imes10^{-6}$			
$y_{2r}(x)$					
x_i	FRPS Method	HW Method			
0.1	$2.76167 imes 10^{-15}$	2.876×10^{-6}			
0.2	$1.41145 imes 10^{-12}$	$1.836 imes10^{-6}$			
0.3	$5.42854 imes 10^{-11}$	1.295×10^{-6}			

Table 7. Comparisons of absolute errors of Example 2, case 1.

¹ Results of HW method referred in [35].

To show the fuzzy behavior of the proposed algorithm, the exact and 10th-FRPS approximated solutions of Example 2, case1 and case 2, are plotted in Figure 3. The plots of *r*-cut representation of exact and FRPS approximated solutions for Example 2, case 1 and case 2, are plotted in Figure 4 at $\beta = 1$, n = 10 and $r \in \{0, 0.25, 0.5, 0.75, 1\}$.



Figure 3. (a) Surface plot exact solution, case 1; (b) Surface plot of 10th-FRPS approximated solutions, case 1; (c) Surface plot exact solution, case 2; (d) Surface plot of 10th-FRPS approximated solutions, case 2, of Example 2 at $\beta = 1$, for all $t \in [0, 1]$ and $r \in [0, 1]$: (yellow and blue are the upper and lower solution, respectively).



Figure 4. (a) Plots of *r*-cut representations of exact and $\varphi_{10,1r}(t)$, of Example 2, case 1; (b) Plots of *r*-cut representations of exact and $\varphi_{10,2r}(t)$, of Example 2, case 2, for $\beta = 1, t \in [0, 1]$ with different values of *r*. in parametric form: red r = 0, dashed blue r = 0.25, dashed green r = 0.5, darker red-dashed r = 0.75, blue r = 1.

6. Conclusions

In this paper, we have successfully used the FRPS technique to construct and investigate fuzzy approximated solutions for a class of fuzzy fractional Volterra integro-differential equations of order $0 < \beta \leq 1$, with appropriate fuzzy initial conditions under strongly generalized differentiability. This method is effectively applied without being exposed to any restriction such as conversion, discretization or perturbation. The methodology of the solution basically depends on constructing the residual function and employing the generalized Taylor formula under Caputo sense. Two illustrative examples are given to validate the capability and performance of our algorithm. The numerical results

obtained via FRPS algorithm have shown that this technique is an easy, powerful tool which can effectively solve different types of fuzzy fractional integro-differential equations.

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Appendix A

The coefficients of the FRPS approximate solutions for the system (20) and (21): to obtain the value of the coefficients c_1 and d_1 , substitute 1st approximated solutions $y_{1,1r}(x)$ and $y_{2,1r}(x)$ of (23) into $Res_{1,1r}(x)$ and $Res_{1,2r}(x)$, to get, $Res_{1,1r}(x) = -(r+1)(1+x^{\beta}) + c_1(1-\frac{x^{2\beta}}{\Gamma(2\beta+1)})$, and $Res_{1,2r}(x) = -(r+1)(1+x^{\beta}) + c_1(1-\frac{x^{2\beta}}{\Gamma(2\beta+1)})$. $(2-r)(1+x^{\beta}) + d_1(1-\frac{x^{2\beta}}{\Gamma(2\beta+1)})$. Then, by using the facts $Res_{1,1r}(0) = Res_{1,2r}(0) = 0$, yields $c_1 = r + 1, d_1 = 2 - r$. Therefore, the 1st-FRPS approximated solutions of system (20) and (21) are given by $y_{1,1r}(x) = (r+1)\frac{x^{\beta}}{\Gamma(\beta+1)}$ and $y_{1,2r}(x) = (2-r)\frac{x^{\beta}}{\Gamma(\beta+1)}$. Again, to determine the 2nd unknown coefficients c_2 and d_2 , we have $Res_{2,1r}(x) = (1 + x^{2\beta}) = 1$.

 $-(r+1)(1+x^{\beta}) + c_1\left(1 - \frac{x^{2\beta}}{\Gamma(2\beta+1)}\right) + c_2x^{\beta}\left(\frac{1}{\Gamma(\beta+1)} - \frac{x^{2\beta}}{\Gamma(3\beta+1)}\right), \text{ and } Res_{2,2r}(x) = (2-r)(1+x^{\beta}) + c_2x^{\beta}\left(\frac{1}{\Gamma(\beta+1)} - \frac{x^{2\beta}}{\Gamma(2\beta+1)}\right)$ $d_1\left(1-\frac{x^{2\beta}}{\Gamma(2\beta+1)}\right)+d_2x^{\beta}\left(\frac{1}{\Gamma(\beta+1)}-\frac{x^{2\beta}}{\Gamma(3\beta+1)}\right)$. Then, through applying the operator $D_{0^+}^{\beta}$ on the both sides of $Res_{2,1r}(x)$, and $Res_{2,2r}(x)$, we have $D_{0^+}^{\beta}Res_{2,1r}(x) = -(r+1)\beta\Gamma(\beta) - c_1\frac{x^{\beta}}{\Gamma(\beta+1)} + c_2\left(1 - \frac{x^{2\beta}}{\Gamma(2\beta+1)}\right)$,

b) $\operatorname{Res}_{2,1r}(x)$, and $\operatorname{Res}_{2,2r}(x)$, we have $D_{0+}\operatorname{Res}_{2,1r}(x) = -(r+1)\beta\Gamma(\beta) - c_1\frac{\Gamma(\beta+1)}{\Gamma(\beta+1)} + c_2\left(1 - \frac{\Gamma(2\beta+1)}{\Gamma(2\beta+1)}\right)$, and $D_{0+}^{\beta}\operatorname{Res}_{2,2r}(x) = (-2+r)\beta\Gamma(\beta) - d_1\frac{x^{\beta}}{\Gamma(1+\beta)} + d_2\left(1 - \frac{x^{2\beta}}{\Gamma(2\beta+1)}\right)$. Finally, by solving the resulting fractional equations at x = 0, one can get $c_2 = (r+1)\beta\Gamma(\beta)$, $d_2 = (2-r)\beta\Gamma(\beta)$. Hence, $y_{2,1r}(x) = (r+1)\left(\frac{x^{\beta}}{\Gamma(\beta+1)} + \frac{\beta\Gamma(\beta)x^{2\beta}}{\Gamma(2\beta+1)}\right)$ and $y_{2,2r}(x) = (2-r)\left(\frac{x^{\beta}}{\Gamma(\beta+1)} + \frac{\beta\Gamma(\beta)x^{2\beta}}{\Gamma(2\beta+1)}\right)$. Likewise, for the 3rd unknown coefficients, c_3 and d_3 , write $y_{3,1r}(x)$ and $y_{3,2r}(x)$ into 3rd residual functions of (24), to conclude that $\operatorname{Res}_{3,1r}(x) = -(r+1)\left(1 + x^{\beta}\right) + c_1 + \frac{c_2x^{\beta}}{\Gamma(2\beta+1)} - \frac{c_2x^{3\beta}}{\Gamma(3\beta+1)} - \frac{c_2x^{3\beta}}{\Gamma(2\beta+1)}$. Thereafter, evaluate $D_{0+}^{2\beta}$ of $\operatorname{Res}_{3,1r}(x)$, and $\operatorname{Res}_{3,2r}(x)$, to get $D_{0+}^{2\beta}\operatorname{Res}_{3,1r}(x) = -c_1 - \frac{c_2x^{\beta}}{\Gamma(\beta+1)} + \frac{c_$ $c_{3}\left(1-\frac{x^{2\beta}}{\Gamma(2\beta+1)}\right), \text{ and } D_{0^{+}}^{2\beta}Res_{3,2r}(x) = -d_{1} - \frac{d_{2}x^{\beta}}{\Gamma(\beta+1)} + d_{3}\left(1-\frac{x^{2\beta}}{\Gamma(2\beta+1)}\right). \text{ Then, based on the fact} \\ D_{0^{+}}^{2\beta}Res_{3,1r}(0) = D_{0^{+}}^{2\beta}Res_{3,2r}(0) = 0, \text{ will yield } c_{3} = r+1, d_{3} = 2-r. \text{ Thus, } y_{3,1r}(x) = (r+1)\left(\frac{x^{\beta}}{\Gamma(\beta+1)} + \frac{\beta\Gamma(\beta)x^{2\beta}}{\Gamma(2\beta+1)} + \frac{x^{3\beta}}{\Gamma(3\beta+1)}\right) \text{ and } y_{3,2r}(x) = (2-r)\left(\frac{x^{\beta}}{\Gamma(\beta+1)} + \frac{\beta\Gamma(\beta)x^{2\beta}}{\Gamma(2\beta+1)} + \frac{x^{3\beta}}{\Gamma(3\beta+1)}\right).$

Using the same argument and the fact $D_{0+}^{(k-1)\beta}Res_{k,1r}(0) = D_{0+}^{(k-1)\beta}Res_{k,2r}(0) = 0$, for k = 4, one can get $c_4 = (r+1)\beta\Gamma(\beta)$, $d_4 = (2-r)\beta\Gamma(\beta)$ and hence the 4th-FRPS approximated solutions of system (20) and (21) are given by $y_{4,1r}(x) = (r+1)\left(\frac{x^{\beta}}{\Gamma(\beta+1)} + \frac{\beta\Gamma(\beta)x^{2\beta}}{\Gamma(2\beta+1)} + \frac{x^{3\beta}}{\Gamma(3\beta+1)} + \frac{\beta\Gamma(\beta)x^{4\beta}}{\Gamma(4\beta+1)}\right)$, and $y_{4,2r}(x) = (2-r)\left(\frac{x^{\beta}}{\Gamma(\beta+1)} + \frac{\beta\Gamma(\beta)x^{2\beta}}{\Gamma(2\beta+1)} + \frac{x^{3\beta}}{\Gamma(2\beta+1)} + \frac{\beta\Gamma(\beta)x^{4\beta}}{\Gamma(2\beta+1)}\right)$. Moreover, the 6th-FRPS approximated solutions of system (20) and (21) are given by

$$\begin{split} y_{6,1r}(x) &= (r+1) \Big(\frac{1}{\Gamma(\beta+1)} x^{\beta} + \frac{\beta\Gamma(\beta)}{\Gamma(2\beta+1)} x^{2\beta} + \frac{1}{\Gamma(3\beta+1)} x^{3\beta} + \frac{\beta\Gamma(\beta)}{\Gamma(4\beta+1)} x^{4\beta} + \frac{1}{\Gamma(5\beta+1)} x^{5\beta} + \frac{\beta\Gamma(\beta)}{\Gamma(63\beta+1)} x^{6\beta} \Big), \\ y_{6,2r}(x) &= (2-r) \Big(\frac{1}{\Gamma(\beta+1)} x^{\beta} + \frac{\beta\Gamma(\beta)}{\Gamma(2\beta+1)} x^{2\beta} + \frac{1}{\Gamma(3\beta+1)} x^{3\beta} + \frac{\beta\Gamma(\beta)}{\Gamma(4\beta+1)} x^{4\beta} + \frac{1}{\Gamma(5\beta+1)} x^{5\beta} + \frac{\beta\Gamma(\beta)}{\Gamma(6\beta+1)} x^{6\beta} \Big). \end{split}$$

Therefore, at $\beta = 1$, the approximated solutions of OFVIDEs (20) and (21) can be written as:

$$y_{1r}(x) = \lim_{k \to \infty} y_{k,1r}(x) = (r+1) \left(x + \frac{x^2}{2} + \frac{x^3}{6} + \frac{x^4}{24} + \frac{x^5}{120} + \frac{x^6}{720} + \dots \right),$$

$$y_{2r}(x) = \lim_{k \to \infty} y_{k,2r}(x) = (2-r)\left(x + \frac{x^2}{2} + \frac{x^3}{6} + \frac{x^4}{24} + \frac{x^5}{120} + \frac{x^6}{720} + \dots\right).$$

which coincides precisely with the Taylor series expansion of the exact solutions $[y(x)]^r$ = $[r+1, 2-r](e^x-1).$

The coefficients of the FRPS approximate solutions for the system (25) and (26): To obtain the value of the coefficients c_n and d_n , n = 1, 2, ..., k, in expansion (28), solve the algebraic system in c_n and d_n that obtained by the fact $D_{0^+}^{(k-1)\beta} Res_{k,1r}(0) = D_{0^+}^{(k-1)\beta} Res_{k,2r}(0) = 0, 0 < \beta \le 1, k = 1, 2, 3, \dots$ Following the procedure of FRPS-algorithm, the first few coefficients c_n and d_n are

$$c_{1} = r + 1, d_{1} = 2 - r,$$

$$c_{2} = (r + 1)\beta\Gamma(\beta), d_{2} = (2 - r)\beta\Gamma(\beta),$$

$$c_{3} = r + 1, d_{3} = 2 - r,$$

$$c_{4} = (2 - r)\beta\Gamma(\beta), d_{4} = (r + 1)\beta\Gamma(\beta),$$

$$c_{5} = r + 1, d_{5} = 2 - r, \dots \text{ and so on.}$$

Continue with this procedure to get the 6th-FRPS approximated solutions of (25) and (26) as

$$y_{6,1r}(x) = \frac{(r+1)}{\Gamma(\beta+1)} x^{\beta} + \frac{(r+1)\beta\Gamma(\beta)}{\Gamma(2\beta+1)} x^{2\beta} + \frac{(2-r)}{\Gamma(3\beta+1)} x^{3\beta} + \frac{(2-r)\beta\Gamma(\beta)}{\Gamma(4\beta+1)} x^{4\beta} + \frac{(r+1)}{\Gamma(5\beta+1)} x^{5\beta} + \frac{(r+1)\beta\Gamma(\beta)}{\Gamma(6\beta+1)} x^{6\beta},$$

$$y_{6,2r}(x) = \frac{(2-r)}{\Gamma(\beta+1)} x^{\beta} + \frac{(2-r)\beta\Gamma(\beta)}{\Gamma(2\beta+1)} x^{2\beta} + \frac{(r+1)}{\Gamma(3\beta+1)} x^{3\beta} + \frac{(r+1)\beta\Gamma(\beta)}{\Gamma(4\beta+1)} x^{4\beta} + \frac{(2-r)}{\Gamma(5\beta+1)} x^{5\beta} + \frac{(2-r)\beta\Gamma(\beta)}{\Gamma(6\beta+1)} x^{6\beta}.$$

Consequently, the approximated solutions of (25) and (26) at $\beta = 1$, can be written as

$$y_{1r}(x) = \lim_{k \to \infty} y_{k,1r}(x) = \left((r+1)x + \frac{(r+1)}{2}x^2 + \frac{(2-r)}{6}x^3 + \frac{(2-r)}{24}x^4 + \frac{(r+1)}{120}x^5 + \frac{(r+1)}{720}x^6 + \dots \right),$$

$$y_{2r}(x) = \lim_{k \to \infty} y_{k,2r}(x) = \left((2-r)x + \frac{(2-r)}{2}x^2 + \frac{(r+1)}{6}x^3 + \frac{(r+1)}{24}x^4 + \frac{(2-r)}{120}x^5 + \frac{(2-r)}{720}x^6 + \dots \right).$$

which agreement well with the Taylor series expansion of the exact solutions $[y(x)]^r = \frac{3}{2}e^x - \frac{1}{2}e^x$ $[2-r, r+1] + \frac{1}{2}[1-2r, 2r-1](\cos x - \sin x).$

Appendix **B**

The FRPS approximate solutions of system (32) and (33) can be obtained by determining the unknown coefficients c_n and d_n of expansion (35).

Anyway, to determine c_1 and d_1 , let k = 1, in Equation (35), then substitute $y_{1,1r}(x) = c_1 \frac{x^{\beta}}{\Gamma(\beta+1)}$ and $y_{2,1r}(x) = d_1 \frac{x^{\beta}}{\Gamma(\beta+1)}$, into 1st-residual functions of Equation (36), that is, $Res_{1,1r}(x) = D_{0^+}^{\beta} \left(c_1 \frac{x^{\beta}}{\Gamma(\beta+1)} \right) - c_1 \frac{x^{\beta}}{\Gamma(\beta+1)}$ $\int_{0}^{x} \frac{c_{1}t^{\beta}}{\Gamma(\beta+1)} dt - (r-1) = 1 - r + c_{1} \left(1 - \frac{x^{2\beta}}{\Gamma(2\beta+1)}\right), \text{ and } \operatorname{Res}_{1,2r}(x) = D_{0^{+}}^{\beta} \left(d_{1} \frac{x^{\beta}}{\Gamma(\beta+1)}\right) - \int_{0}^{x} \frac{d_{1}t^{\beta}}{\Gamma(\beta+1)} dt - (1-r) = r - 1 + d_{1} \left(1 - \frac{x^{2\beta}}{\Gamma(2\beta+1)}\right).$ Then, by using the facts $\operatorname{Res}_{1,1r}(0) = \operatorname{Res}_{1,2r}(0) = 0$, yields $c_{1} = r - 1, d_{1} = 1 - r$. Therefore, the 1st-FRPS approximated solutions of system (33) and (34) is given by using the facts $r = r - 1, d_{1} = 1 - r$. by $y_{1,1r}(x) = (r-1)\frac{x^{\beta}}{\Gamma(\beta+1)}$, and $y_{1,2r}(x) = (1-r)\frac{x^{\beta}}{\Gamma(\beta+1)}$.

To obtain the 2nd unknown coefficients c_2 and d_2 , we have $Res_{2,1r}(x) = r - 1 + c_1\left(1 - \frac{x^{2\beta}}{\Gamma(2\beta+1)}\right) + c_2 x^{\beta} \left(\frac{1}{\Gamma(\beta+1)} - \frac{x^{2\beta}}{\Gamma(3\beta+1)}\right)$, and $Res_{2,2r}(x) = 1 - r + d_1 \left(1 - \frac{x^{2\beta}}{\Gamma(2\beta+1)}\right) + d_2 x^{\beta} \left(\frac{1}{\Gamma(\beta+1)} - \frac{x^{2\beta}}{\Gamma(3\beta+1)}\right)$. Through utilizing the fact $D_{0^+}^{\beta} Res_{2,1r}(0) = D_{0^+}^{\beta} Res_{2,2r}(0) = 0$, one can get $c_2 = 0$, $d_2 = 0$. Hence, $y_{2,1r}(x) = (r-1)\frac{x^{\beta}}{\Gamma(\beta+1)}$, and $y_{2,2r}(x) = (1-r)\frac{x^{\beta}}{\Gamma(\beta+1)}$.

Likewise, for the 3rd unknown coefficients, c_3 and d_3 , write $y_{3,1r}(x)$ and $y_{3,2r}(x)$ into 3rd residual functions of Equation (36), to get $Res_{3,1r}(x) = 1 - r + c_1 + \frac{c_2 x^{\beta}}{\Gamma(\beta+1)} - \frac{c_2 x^{3\beta}}{\Gamma(3\beta+1)} - \frac{c_3 x^{4\beta}}{\Gamma(4\beta+1)} + \frac{(-c_1+c_3)x^{2\beta}}{\Gamma(2\beta+1)}$, and $Res_{3,2r}(x) = r - 1 + d_1 + \frac{d_2 x^{\beta}}{\Gamma(\beta+1)} - \frac{d_2 x^{3\beta}}{\Gamma(3\beta+1)} - \frac{d_3 x^{4\beta}}{\Gamma(4\beta+1)} + \frac{(-d_1+d_3)x^{2\beta}}{\Gamma(2\beta+1)}$. According to

utilizing the 5th residual functions $Res_{5,1r}(x)$, $Res_{5,2r}(x)$ and the fact $D_{0^+}^{4\beta}Res_{5,1r}(0) = D_{0^+}^{4\beta}Res_{5,2r}(0) = 0$, such that $D_{0^+}^{4\beta}Res_{5,1r}(x) = -c_3 - \frac{c_4x^{\beta}}{\Gamma(\beta+1)} + c_5\left(1 - \frac{x^{2\beta}}{\Gamma(2\beta+1)}\right)$ and $D_{0^+}^{4\beta}Res_{5,2r}(x) = -d_3 - \frac{d_4x^{\beta}}{\Gamma(\beta+1)} + c_5\left(1 - \frac{x^{2\beta}}{\Gamma(2\beta+1)}\right)$ $d_5\left(1 - \frac{x^{2\beta}}{\Gamma(2\beta+1)}\right)$. So, $c_5 = r - 1$, $d_5 = 1 - r$, and further $y_{5,1r}(x) = (r - 1)\left(\frac{x^{\beta}}{\Gamma(\beta+1)} + \frac{x^{3\beta}}{\Gamma(3\beta+1)} + \frac{x^{5\beta}}{\Gamma(5\beta+1)}\right)$, and $y_{5,2r}(x) = (1-r) \left(\frac{x^{\beta}}{\Gamma(\beta+1)} + \frac{x^{3\beta}}{\Gamma(3\beta+1)} + \frac{x^{5\beta}}{\Gamma(5\beta+1)} \right)$. Moreover, based upon the fact $D_{0^+}^{(k-1)\beta} Res_{k,1r}(0) = D_{0^+}^{(k-1)\beta} Res_{k,2r}(0) = 0, k = 5, 6, \dots, 10$, the

10th-FRPS approximated solutions of system (32) and (33) are given by

$$y_{10,1r}(x) = (r-1) \left(\frac{x^{\beta}}{\Gamma(\beta+1)} + \frac{x^{3\beta}}{\Gamma(3\beta+1)} + \frac{x^{5\beta}}{\Gamma(5\beta+1)} + \frac{x^{7\beta}}{\Gamma(7\beta+1)} + \frac{x^{9\beta}}{\Gamma(9\beta+1)} \right),$$

$$y_{10,2r}(x) = (1-r) \left(\frac{x^{\beta}}{\Gamma(\beta+1)} + \frac{x^{3\beta}}{\Gamma(3\beta+1)} + \frac{x^{5\beta}}{\Gamma(5\beta+1)} + \frac{x^{7\beta}}{\Gamma(7\beta+1)} + \frac{x^{9\beta}}{\Gamma(9\beta+1)} \right).$$

For $\beta = 1$, the approximated solutions of OFVIDEs (32) and (33) can be written in the form

$$y_{1r}(x) = \lim_{k \to \infty} y_{k,1r}(x) = (r-1)\left(x + \frac{x^3}{6} + \frac{x^5}{120} + \frac{x^7}{5040} + \frac{x^9}{362880} + \dots\right),$$
$$y_{2r}(x) = \lim_{k \to \infty} y_{k,2r}(x) = (1-r)\left(x + \frac{x^3}{6} + \frac{x^5}{120} + \frac{x^7}{5040} + \frac{x^9}{362880} + \dots\right).$$

which coincides precisely with Taylor expansion for the exact solutions $y_{1r}(x) = (r - 1) \sin h(x)$, and $y_{2r}(x) = (r-1) \sin h(x).$

The coefficients of the FRPS approximate solutions for the system (37) and (38): To obtain the value of the coefficients c_n and d_n , n = 1, 2, ..., k, in expansion (41), do the following manner:

Through Equations (40) and (41), put k = 1, we have $Res_{1,1r}(x) = D_{0^+}^{\beta} \left(c_1 \frac{x^{\beta}}{\Gamma(\beta+1)} \right) - \int_0^x \frac{d_1 x^{\beta}}{\Gamma(\beta+1)} dt - (1-r) = r - 1 + c_1 - d_1 \left(1 - \frac{x^{2\beta}}{\Gamma(2\beta+1)} \right)$, and $Res_{1,2r}(x) = D_{0^+}^{\beta} \left(d_1 \frac{x^{\beta}}{\Gamma(\beta+1)} \right) - \int_0^x \frac{c_1 x^{\beta}}{\Gamma(\beta+1)} dt - (r-1) = (1-r) + c_1 - d_1 \left(1 - \frac{x^{2\beta}}{\Gamma(2\beta+1)} \right)$, and $Res_{1,2r}(x) = D_{0^+}^{\beta} \left(d_1 \frac{x^{\beta}}{\Gamma(\beta+1)} \right) - \int_0^x \frac{c_1 x^{\beta}}{\Gamma(\beta+1)} dt - (r-1) = (1-r) + c_1 - d_1 \left(1 - \frac{x^{2\beta}}{\Gamma(2\beta+1)} \right)$. $1 - r - c_1 \left(1 - \frac{x^{2\beta}}{\Gamma(2\beta+1)}\right) + d_1$. Then, we solve $Res_{1,1r}(0) = Res_{1,2r}(0) = 0$, it gives $c_1 = 1 - r$, $d_1 = r - 1$. So, the 1st-FRPS approximated solutions of system (38) and (39) are given by $y_{1,1r}(x) = (1-r)\frac{x^{\beta}}{\Gamma(\beta+1)}$, and $y_{1,2r}(x) = (r-1) \frac{x^{\beta}}{\Gamma(\beta+1)}$.

Similarly, for k = 2, and based on the fact $D_{0^+}^{\beta} \operatorname{Res}_{2,1r}(0) = D_{0^+}^{\beta} \operatorname{Res}_{2,2r}(0) = 0$, to get $c_2 = 0$, $d_2 = 0$. Thus, $y_{2,1r}(x) = (1-r)\frac{x^{\beta}}{\Gamma(\beta+1)}$, and $y_{2,2r}(x) = (r-1)\frac{x^{\beta}}{\Gamma(\beta+1)}$. To get the 3rd-FRPS approximated solutions, consider k = 3 in Equations (40) and (41) to get $\operatorname{Res}_{3,1r}(x) = r - 1 + c_1 + \frac{c_2x^{\beta}}{\Gamma(\beta+1)} + \frac{(c_3-d_1)x^{2\beta}}{\Gamma(2\beta+1)} - \frac{d_2x^{3\beta}}{\Gamma(3\beta+1)} - \frac{d_3x^{4\beta}}{\Gamma(4\beta+1)}$, and $\operatorname{Res}_{3,2r}(x) = 1 - r + d_1 + \frac{d_2x^{\beta}}{\Gamma(\beta+1)} - \frac{c_2x^{3\beta}}{\Gamma(2\beta+1)} - \frac{c_3x^{4\beta}}{\Gamma(2\beta+1)} + \frac{(-c_1+d_3)x^{2\beta}}{\Gamma(2\beta+1)}$. Thereafter, computing 2 β th-Caputo fractional derivative of $Res_{3,1r}$ and $Res_{3,2r}$, i.e. $D_{0^+}^{2\beta}Res_{3,1r}(x) = c_3 - d_1 + x^{\beta} \left(-\frac{d_2}{\Gamma(\beta+1)} - \frac{x^{\beta}d_3}{\Gamma(2\beta+1)} \right)$, and $D_{0^+}^{2\beta}Res_{3,2r}(x) = 0$ $-c_{1} + d_{3} - \frac{c_{2}x^{\beta}}{\Gamma(\beta+1)} - \frac{c_{3}x^{\beta}}{\Gamma(2\beta+1)}.$ Lastly, by solving the obtained fractional equations at x = 0, and considering the values of c_{1} , d_{1} , c_{2} and d_{2} from previous steps, we get $c_{3} = r - 1$, $d_{3} = 1 - r$. Hence, $y_{3,1r}(x) = \frac{(1-r)x^{\beta}}{\Gamma(\beta+1)} + \frac{(r-1)x^{3\beta}}{\Gamma(3\beta+1)}$, and $y_{3,2r}(x) = \frac{(r-1)x^{\beta}}{\Gamma(\beta+1)} + \frac{(1-r)x^{3\beta}}{\Gamma(3\beta+1)}.$

Continue with this fashion for k = 4, and depending on the fact $D_{0^+}^{3\beta} Res_{4,1r}(0) = D_{0^+}^{3\beta} Res_{4,2r}(0) = 0$, will yield $c_4 = 0$, $d_4 = 0$, and hence $y_{4,1r}(x) = \frac{(1-r)x^{\beta}}{\Gamma(\beta+1)} + \frac{(r-1)x^{3\beta}}{\Gamma(3\beta+1)}$, and $y_{4,2r}(x) = \frac{(r-1)x^{\beta}}{\Gamma(\beta+1)} + \frac{(1-r)x^{3\beta}}{\Gamma(3\beta+1)}$. Next, for k = 5, the 5th-FRPS approximated solutions can be constructed by considering the

5th-residual functions of Equation (40) and based on the fact $D_{0^+}^{4\beta}Res_{5,1r}(0) = D_{0^+}^{4\beta}Res_{5,2r}(0) = 0$, such that $D_{0^+}^{4\beta}Res_{5,1r}(x) = c_5 - d_3 - \frac{d_4x^{\beta}}{\Gamma(\beta+1)} - \frac{d_5x^{2\beta}}{\Gamma(2\beta+1)}$ and $D_{0^+}^{4\beta}Res_{5,2r}(x) = d_5 - c_3 - \frac{c_4x^{\beta}}{\Gamma(\beta+1)} - \frac{c_5x^{2\beta}}{\Gamma(2\beta+1)}$. Then, by solving the resultant fractional equations at x = 0, and taking into account the values of c_3, d_3, c_4 and d_4 , from previous steps, gives $c_5 = 1 - r$, $d_5 = r - 1$, as well $y_{5,1r}(x) = \frac{(1-r)x^{\beta}}{\Gamma(\beta+1)} + \frac{(r-1)x^{3\beta}}{\Gamma(3\beta+1)} + \frac{(1-r)x^{5\beta}}{\Gamma(5\beta+1)}$, and $y_{5,2r}(x) = \frac{(r-1)x^{\beta}}{\Gamma(\beta+1)} + \frac{(1-r)x^{3\beta}}{\Gamma(3\beta+1)} + \frac{(r-1)x^{5\beta}}{\Gamma(5\beta+1)}$. Furthermore, through utilizing the fact $D_{0^+}^{(k-1)\beta} Res_{k,1r}(0) = D_{0^+}^{(k-1)\beta} Res_{k,2r}(0) = 0$, $k = 6, 7, \dots, 10$, the 10th-FRPS approximated solutions of system (38) and (39) can be written as

$$y_{10,1r}(x) = \frac{(1-r)x^{\beta}}{\Gamma(\beta+1)} + \frac{(r-1)x^{3\beta}}{\Gamma(3\beta+1)} + \frac{(1-r)x^{5\beta}}{\Gamma(5\beta+1)} + \frac{(r-1)x^{7\beta}}{\Gamma(7\beta+1)} + \frac{(1-r)x^{9\beta}}{\Gamma(9\beta+1)}.$$
$$y_{10,2r}(x) = \frac{(r-1)x^{\beta}}{\Gamma(\beta+1)} + \frac{(1-r)x^{3\beta}}{\Gamma(3\beta+1)} + \frac{(r-1)x^{5\beta}}{\Gamma(5\beta+1)} + \frac{(1-r)x^{7\beta}}{\Gamma(7\beta+1)} + \frac{(r-1)x^{9\beta}}{\Gamma(9\beta+1)}.$$

Consequently, the approximated solutions of system (37) and (38) have general form which are coinciding well with the exact solutions for $\beta = 1$, such that

$$y_{1r}(x) = \lim_{k \to \infty} y_{k,1r}(x) = (1-r)x + \frac{(r-1)x^3}{6} + \frac{(1-r)x^5}{120} + \frac{(r-1)x^7}{5040} + \frac{(1-r)x^9}{362880} + \dots = (1-r)\sin x,$$

$$y_{2r}(x) = \lim_{k \to \infty} y_{k,2r}(x) = (r-1)x + \frac{(1-r)x^3}{6} + \frac{(r-1)x^5}{120} + \frac{(1-r)x^7}{5040} + \frac{(r-1)x^9}{362880} + \dots = (r-1)\sin x.$$

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