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Conservation Prioritization in a Tiger Landscape: Is Umbrella Species Enough?

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Abstract: Conservation approaches in tiger landscapes have focused on single species and their habitat. Further, the limited extent of the existing protected area network in India lacks representativeness, habitat connectivity, and integration in the larger landscape. Our objective was to identify sites important for connected tiger habitat and biodiversity potential in the Greater Panna Landscape, central India. Further, we aimed to set targets at the landscape level for conservation and prioritize these sites within each district in the landscape as specific management/conservation zones. We used earth observation data to derive an index of biodiversity potential. Marxan was used to identify sites that met tiger and biodiversity conservation targets with minimum costs. We found that to protect 50% of the tiger habitat with connectivity, 20% of the landscape area must be conserved. To conserve 100% of high biodiversity potential, 50% moderate biodiversity potential, and 25% low biodiversity potential, 55% of the landscape area must be conserved. To represent both tiger habitat and biodiversity, 62% of the total landscape area requires conservation or restoration intervention. The prioritized zones can prove significant for hierarchical decision making, involving multiple stakeholders in the landscape, including other tiger range areas.

Keywords: Marxan; systematic conservation planning; integrated landscape management; central India; protected area; targets; spatial prioritization; decision making



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1. Introduction

Protected areas (PAs) are among the important strategies of target-based conservation approaches [1]. The PA network in India covers 5.03% of the geographical area and includes national parks, wildlife sanctuaries, community reserves, and conservation reserves [2]. PAs have made a significant contribution to the conservation of biodiversity in India [3]. A significant contribution to this network is made by the Tiger Reserve Network (often combines existing PAs—national parks, wildlife sanctuaries, and reserve forests), which covers ~2% of the geographical area of the country. Since the beginning of the Project Tiger in 1973, Tigers (*Panthera tigris*) have played the role of both flagship and umbrella species and aided forest conservation through enhanced legal protection under Wildlife (Protection) Act, 1972 [4–8]. Tiger reserves instantiate the integration of forest and wildlife conservation since tiger conservation relies on the quality of forest cover and characteristics of surrounding forest landscape such as landscape connectivity, prey population, and intensity of human disturbance. For tigers and large carnivores, their large body size, large home ranges, dispersal as an important life-history trait, endangered status, etc. fulfill some of the common agreed-upon characteristics of umbrella species [9–11]. The practical

effectiveness of the umbrella species approach, in general, has been tested in a few studies, and there have been different experiences globally [12–15]. Its utility as a conservation tool has not been empirically tested in the case of tigers, but the umbrella species approach has been found to be more effective in selecting biologically important areas, as opposed to randomly selecting habitat patches for conservation [15], in addition to its higher efficacy in other cases to determine the size and type of habitats to protect [16].

The effectiveness of conservation efforts through PAs also depends on representativeness, connectivity, and integration of PAs in the larger landscape (Aichi Target 11) [1]. With fewer functional corridors connecting PAs in India, the surrounding human-use matrix plays an important role in the dispersal and movement of animals [17,18]. For the success of these species in the PAs, they must be surrounded by sustainably managed landscapes, mimicking an adaptive mosaic [19–21]. Further, PAs are not immune to downgrading, downsizing, degazettement, or other management issues [22,23]. The proposed Ken–Betwa Link Canal Project (KBLCP) in the central Indian landscape, for example, will submerge 90 km² area and will also impact the connectivity with another 105 km² of the core tiger habitat area of Panna Tiger Reserve (PTR) on the western side of the Ken River. Given the fact that PTR has recovered from a state of functional extinction of the tiger population in the recent past, the current and future management including human–wildlife interface issues ought to be seen and managed from these pragmatic perspectives. The issues concerning PTR and the surrounding areas that can be termed as “Greater Panna Landscape” (GPL), require an integrated landscape approach to ensure biodiversity conservation and well-being of the people in the long term. Therefore, we explore the idea for an integrated landscape management plan for this landscape further in this study, which originated as a part of the process for KBLCP.

GPL, centered around PTR in central India, is an important tiger habitat, with the latter as the major source population. It is a heterogeneous landscape—a mosaic of agriculture and forest. Conservation efforts have so far followed the top-down approach through protected area designation and intensive management within the PAs. While forest and wildlife conservation are intertwined and inseparable, they are often planned in silos through forest working plans, wildlife management plans, and tiger conservation plans, which makes it difficult to set comprehensive and inclusive conservation goals. For example, the surrounding forest patches and riverine ecosystems are important for dispersing tigers but also for other taxa such as the vultures and gharials (*Gavialis gangeticus*) [24,25]

PTR is now more known for the “fall and rise of the tiger” due to local extinction and subsequent successful reintroduction of the tiger. The Tiger population in the PTR during the 1980s was reported to be around 20 and remained in the range of 25–30 until 2000. Tiger number continued to decline, became functionally extinct by 2008, and it subsequently lost all its tigers in early 2009 [26]. To revive the tiger population, a concerted effort through a comprehensive recovery program was implemented by the Madhya Pradesh State Forest Department, supported by the Wildlife Institute of India (WII) and National Tiger Conservation Authority (NTCA), beginning in 2009 and continuing up till June 2021. From three translocated individuals in 2009 and subsequently another four over the years [27], the tiger population grew rapidly and reached beyond the estimated carrying capacity to the current population of around 60 individuals (as of 2021), much beyond the historically recorded number for the reserve. With the growing population, tigers have naturally dispersed from PTR and into the surrounding landscape, with an estimated 37 dispersal events. Therefore, the conservation of these tigers must be considered on the landscape scale.

Setting targets and prioritizing areas for tiger conservation has historically followed a species-centric approach at global, regional, and local scales. Conservation planning initiatives at the global level prioritized several representative tiger habitats across the tiger range countries through initiatives such as “A Framework for Identifying High-Priority Areas and Actions for the Conservation of Tigers in the Wild” (also known as TCU 1.0), and it identified tiger conservation units in different bioregions [28]. Habitat integrity, poaching

pressure, and population status were the three key criteria in this ecological approach. A second version that was more objective and data-driven was “Setting Priorities for the Conservation and Recovery of Wild Tigers: 2005–2015” (also known as TCL 2.0), and it delineated tiger conservation landscapes [29]. Setting such priority areas and targets for conservation allowed focused allocation of resources to safeguard the inviolate areas and habitat protection with representation and redundancy. Tiger conservation planning at the national and regional level has also followed a similar ecological approach for identifying priority areas, for example, in Nepal and the Terai Arc landscape in India [30–32] assuming the umbrella effect of tiger species. Prioritization of conservation areas using this popular but somewhat controversial umbrella species approach [15] can be problematic in landscapes with several species of conservation importance [33]. Decision making and management with a focus on one species do not consider the differential impact of landscape change on the other species [34]. Further, habitat selection at a finer scale can be different for different species occupying the same region [35]. Therefore, a multiscale and multispecies conservation approach is essential.

Landscape approaches often involve assessment and planning at multiple scales [17,36–39]. At the landscape scale, connectivity for tigers, satellite cores, and stepping stones are important features to preserve, in addition to the biophysical features within the landscape [17,40]. For example, cliffs and deep gorges are the characteristic topographic features of GPL and are important for the conservation of vultures [24]. At finer scales, for example at the stand level, species richness, diversity, and nesting sites are some of the important features to preserve. Conservation of these features can be carried out through spatial prioritization by setting conservation targets. Based on the availability of data and objectives, past studies have set targets for features such as natural areas, species richness and diversity, geological and topographical features, vegetation types, and ecosystem services [41–45]. Data availability for species and their habitat is an important challenge to this approach, which can be overcome by earth observation data, which play important roles in computing taxonomic and environmental surrogates for conservation features in areas with no or insufficient field data [46–50].

GPL has been envisioned to protect and consolidate forest patches and biodiversity-rich areas around the PTR taking a landscape approach to wildlife conservation (National Wildlife Action Plan, 2017–2031). It was also envisioned to facilitate the conservation of the tiger in a metapopulation framework while conserving other focal species such as crocodiles and vultures, as well as the overall biodiversity of the area. In this study, we used earth-observation-based environmental surrogates (biodiversity potential) and habitat connectivity for tiger species to identify sites within the GPL that meet the broad conservation targets for the landscape using a reserve selection tool Marxan [51,52]. We further prioritized these identified sites by creating specific management/conservation zones based on various combinations of tiger habitat and biodiversity potential areas identified at five levels. The prioritization maps generated through this assessment can be used as baselines for stakeholder engagement and appropriate conservation practice in each district and can encourage the deliberative process of negotiations at the village, district, and landscape levels. This also allows the implementation framework to be integrated with the five-stage multilevel planning framework in India. In this context, our study offers a unique perspective on conservation prioritization, compared with other similar studies globally [53–55].

2. Materials and Methods

2.1. Study Area

The study was conducted in the Greater Panna Landscape in central India (Figure 1). The landscape was defined using the administrative boundary of 11 districts of 2 states—Uttar Pradesh and Madhya Pradesh. The extent of the landscape was decided by the extent of contiguous forest patches and protected areas around the Panna Tiger Reserve. It extends between 81°53′25.70″ E to 78°17′12.56″ E longitude and 24°53′13.77″ N to 24°14′4.78″ N

that conservation feature (Supplementary Information, Table S1). The objective function can be written as in Equation (1).

$$\text{Score of the configuration being tested} = (\Sigma \text{ Cost of PUs}) + (\text{BLM} \times \Sigma \text{ Boundary length}) + (\text{SPF} \times \text{Penalty incurred for unmet targets}) \quad (1)$$

2.2.2. Planning Area and Planning Units

For the present assessment, the planning area was the GPL. The landscape shapefile was created by merging the district polygons. The analysis was carried out using PUs of square grid cells of 4 km × 4 km for tiger and 2 km × 2 km for biodiversity potential. Each PU was assigned a unique identification number, availability status for conservation, and cost associated with conservation. Traditionally, each planning unit is assigned a status as either “conserved” or “excluded” or “available” (Supplementary Information, Table S1). All the units were assigned the status “available”. In this landscape, existing mining and industrial sites were the major sites of exclusion, apart from the human settlements. We did not exclude the existing mining and industrial sites at this stage because these can be potential restoration sites depending upon their scale of operation, impact, and production period. In addition, we did not assign conserved status to protected areas because assigning “conserved” status meant that no more restoration or management effort will be required in these sites. In reality, the areas within the administrative boundaries of PA require some form of management interventions from time to time.

2.2.3. Conservation Features and Targets

We used five conservation features, i.e., tiger structural habitat (forest and scrub) and biodiversity potential classes (low, moderate, high). With 27% of forest area already under protection, we set targets for an overall 50% of forests and 50% of scrub to be conserved for tiger conservation. Similarly, to represent other taxa, we used a surrogate index that represented habitat diversity and therefore acted as a proxy for biodiversity potential. We set a target to conserve 100% of high biodiversity potential areas, 50% of moderate biodiversity potential areas, and 25% of low biodiversity potential areas in the landscape.

2.2.4. Tiger Habitat

We used a forest cover map (Forest Survey of India, 2014) available in raster format at 100 m spatial resolution. It had six classes—namely, very dense forest, moderately dense forest, open forest, scrub, water, and non-forest. The forest classes were merged to finally obtain four classes—forest, scrub, water, and non-forest. We reassigned the reservoirs to the non-forest class. Pixel clumps smaller than one km² were removed, and a “boundary clean” filter was applied to avoid slivers in the vectorized habitat shapefile. The vectorized habitat shapefile was used as input to compute connectivity in the later stage.

2.2.5. Biodiversity Potential

A grid-based approach was adopted to assess the potential of biodiversity in GPL. A composite of systematic indicators encompassing topographic, biological, and anthropogenic factors was used to synthesize a cumulative biodiversity potential index. Based on the literature, ecological significance, and expert discussion, a total of seven indicators were finalized for assessment. These indicators included elevation, normalized difference vegetation index (NDVI), normalized difference water index (NDWI), drainage system, land cover, forest cover, and human footprint. These indicators were derived from different remotely sensed datasets (Table 1). In the absence of data for the current year, the most recent data available for the study area were used. The results of the assessment were presented in the form of a cumulative biodiversity potential value/index.

Table 1. Earth observation data products used in the computation of variables for biodiversity potential.

Data Layers (Data Type)	Spatial Resolution	Source	Rationale	References
Elevation (Continuous)	30 m	ASTER	Topography influences regional biodiversity by generating environmental gradients and determining the pattern of vegetation productivity and species distributions. It helps in the identification of plateaus, cliffs, and gorges.	[58,59]
Forest Cover 2015 (Categorical)	24 m	Forest Survey of India	Land cover maps provide direct and indirect indices of biodiversity and can differentiate broad plant communities.	[47,60,61]
Land Use/Land Cover Data 2015–16 (Categorical)	54 m	NRSC, ISRO		
NDVI–Annual Mean 2015 (Continuous)	30 m	Landsat-8 OLI	Vegetation productivity is directly linked to biodiversity and can identify the regional hotspots of biodiversity. Areas with high productivity have a greater concentration of species and higher species diversity, compared with areas with low productivity.	[62–64]
Human Footprint 2012 (Continuous)	1 km	Last of the Wild [65]	Disturbances from natural and human factors alter the landscape structure and functioning of ecosystems, which, in turn, impacts biodiversity and species distributions.	[66,67]
NDWI- Annual Mean 2015 (Continuous)	30 m	Landsat-8 OLI	NDWI highlights the surface water bodies, which represent the terrestrial aquatic habitats at the landscape scale.	Study specific
River Drainage (Vector Line)	-	Hydrosheds [68]	The drainage network accounts for gaps in the NDWI data, especially in the case of smaller streams and dry riverbeds.	Study specific

The annual mean for bands of Landsat-8 OLI was computed for available image collection in 2015 after masking cloudy pixels in Google Earth Engine. These bands were then used to compute NDVI and NDWI. The datasets were clipped for the study area and preprocessed using reprojection, resampling, and rescaling techniques. The NDVI layer was processed to include only vegetation (values > 0 were retained, values < 0 were converted to 0). NDWI layer was also similarly rescaled to include only water areas (NDWI values > 0 were retained). The land use land cover layer was reclassified, and similar classes were grouped. For example, all types of forests including plantations were grouped into a single class. The forest cover layer was reclassified into two classes—forest and non-forest. The elevation layer was used to derive slope information, and the slope layer was further reclassified into 10-degree interval classes. The human footprint and drainage data were used directly in the analyses. All analyses were performed in ESRI ArcMap 10.2.

Since the datasets had different spatial resolutions, a uniform and systemic grid size of 2 km × 2 km was selected for GPL for further assessments. Data values were assembled at this common grid size (Table 2). A total of 12 (final set) indicators were derived from the seven indicators mentioned above, and for every grid cell, the value of these indicators was estimated.

Table 2. Rank and weight score assigned to the variables used in the computation of biodiversity potential.

Indicators	Normalization (0–1)	Rank Assigned	Weight Score
Elevation (standard deviation)	Low to High	6	0.04
Slope (diversity)	Low to High	1	0.14
NDVI (mean)	Low to High	2	0.12
NDVI (standard deviation)	Low to High	2	0.12
NDWI (mean)	Low to High	5	0.06
NDWI (standard deviation)	Low to High	5	0.06
Land use land cover (diversity)	Low to High	3	0.10
Stream length	Low to High	7	0.02
Stream diversity	Low to High	5	0.06
Human footprint (mean)	High to Low (1–0)	4	0.08
Human footprint (standard deviation)	High to Low (1–0)	4	0.08
Patch density (mean)	Low to High to Low	3	0.10

Each of the indicators was then standardized on a 0 to 1 scale using a minimum–maximum standardization technique. Human footprint indicators were scaled from 1 to 0. For patch density values, the “low to moderate” values were scaled from 0 to 1, while the “moderate to high” values were scaled from 1 to 0. A weighted sum of all the 12 indicators was estimated for every 2 km × 2 km grid cell to obtain the biodiversity potential values. This resulted in each grid cell having a value ranging from 0 to 1, with 0 indicating low biodiversity potential and 1 indicating high biodiversity potential. The biodiversity values were then clustered into three classes—namely, high, medium, and low biodiversity potential areas, using Jenk’s Natural Breaks algorithm in ArcMap. The biodiversity potential index thus synthesized represented a comprehensive measure of the status of biodiversity in each 4 km² grid of the GPL.

2.2.6. Field Data Collection

Species richness of vegetation and mammals was assessed for evaluation of their representation in the biodiversity potential classes. These two taxonomic groups are proven to have strong correlations with the richness and diversity of other taxa such as arthropods, birds, and herpetofauna at regional scales [69–71]. Further remotely sensed vegetation indices can also explain mammal diversity and distribution [72]. For sampling, we did not preselect a set of species for sampling but attempted to record any plant species present in the landscape that were limited to division “Angiospermae”. Similarly, targeted any animal species that could be recorded using camera traps, which were limited to class “Mammalia”. The study area was divided into nested hierarchical grids of 8 km, 4 km, and 2 km, and sampling was distributed in the 2 km grids, with multiple spatial replicates for each of the larger grids, ensuring sampling representation across the landscape, covering all spatial heterogeneity. In GPL, grids (4 km²) were selected based on the proportion of forest cover within each forest division, while in PTR, almost every 4 km² grid was sampled. Sampling grids were systematically chosen based on habitat availability, i.e., the presence of forest cover in the grids was considered necessary for sampling. Other criteria for grid selection included avoiding areas that were not suitable for deploying camera traps due to inaccessibility issues (tough terrain, lack of forest roads or trails suitable for camera trap deployment, etc.). In human-dominated landscapes, or areas outside PAs, deployment of camera traps is also challenging due to human activities, which cause data loss due to stealing, misplacing, or damaging of cameras. Hence, to avoid data loss, we refrained

from placing camera traps in those sensitive areas. Since the entire area has been covered systematically involving hierarchical design, ensuring representation for larger grids, we were able to avoid any sampling bias. Additionally, the landscape, although heterogenous, has similar habitat features across the region, and the sample size was large enough to resolve any bias in the outcome.

For vegetation assessment, a transect of 1 km was walked in each selected 4 km² grid (Supplementary Information, Figure S1). Species richness of trees, shrubs, and ground vegetation (herb and grasses) was recorded within quadrats of size 100 m², 25 m², and 1 m², respectively. For each transect, there were five sampling locations, each 250 m apart. Camera traps were used for mammal species richness. Within PTR, single-sided camera traps were installed in each 2 km² grid (1.4 km × 1.4 km) as per the protocol of All India Tiger Estimation [73], while within the rest of the GPL, camera traps were installed on both sides of the trails, in each selected 4 km² grid at suitable locations. A total of 830 grids (4 km²) were sampled in GPL (177 grids in PTR and 653 grids in the remaining GPL), representing 5960 sampling points (4150 for vegetation and 1810 for mammal). Field guides were used for the identification of vegetation and mammals [74–77]. No plant materials were preserved or stored during sampling. All of the richness-related data were scaled to 4 km² grids.

We calculated the species richness for trees, shrubs, herbs, carnivores (order Carnivora), herbivores (order Artiodactyla), primates (order Primates), rodents (order Rodentia) within the low, moderate, and high biodiversity potential classes by aggregating for each taxon. We used the Shapiro–Wilk test to test the normality of data and the Kruskal–Wallis test to statistically test if the field measured species richness explained the biodiversity potential classes. The null hypothesis was set as “There is no statistically significant difference between the three biodiversity potential classes” and the alternate hypothesis as “There is a statistically significant difference between the three biodiversity potential classes”. Since we used biodiversity potential classes for prioritization in this study, we used a multinomial logistic regression model to test if the field measured species richness could predict the biodiversity potential. Biodiversity potential classes were taken as a categorical dependent variable and species richness of trees, shrubs, herbs, carnivores, herbivores, primates, rodents, total mammal richness, total vegetation richness, and total richness were taken as continuous independent covariates. The class “low biodiversity potential” was set as a reference. A two-tailed z-test was performed, and p values were calculated. All statistical analyses were carried out in R (Version 1.4.1103). Packages “nnet” and “MASS” were used [78].

2.3. Spatial Prioritization

2.3.1. Prioritization for Tiger Habitat

For the prioritization of tiger habitat, we incorporated structural landscape connectivity and included the connectivity data as a spatial dependency. Connectivity was computed using habitat shapefile using the least-cost path method within Marxan Connect GUI [51]. A square resistance matrix was created based on expert knowledge for computing the least-cost path connectivity matrix (Supplementary Information, Table S2). The connectivity values were used to calculate new boundary values for each planning unit pair. Other Marxan input files were created in QGIS 3.10 using the plugin Conservation Land-Use Zoning software (CLUZ) [52]. Different boundary length modifier (BLM) values were tested (0, 50, 75, and 100) in Marxan Connect for the effect on the configuration of planning units selected. A value of 100 was used for the selection of planning unit configuration produced the least number of scattered planning units in the best solution. Sensitivity to species penalty factor (SPF) was tested using values 0 and 1000. SPF of 0 was assigned to each conservation feature, as the results did not differ between these two extremes. Other parameters were similarly selected after an initial pilot run and comparison of output with dispersal patterns of the tigers in the landscape. The sum of human footprint values from

the raster file was transferred to the planning units and used as the cost of PUs. Using target values as described earlier, Marxan was run with 100000 iterations and 100 runs.

2.3.2. Prioritization for the Biodiversity Potential

To prioritize biodiversity potential, we used square planning units of size $2\text{ km} \times 2\text{ km}$ and targets, as mentioned previously. We tested BLM values between 0 and 0.00001, with exponential increments, and their influence on the configuration of the best solution. Different BLM values resulted in a different configuration of reserve network, with higher values resulting in a more compact network. An appropriate reserve selection, in this case, was a balance between contiguous, clumped patches, and widely scattered PUs. Therefore, we selected a configuration that spread out over different administrative units to allow for effective allocation of funds and management. An SPF of 10 was assigned to each conservation feature. Marxan was run with 1,000,000 iterations, 100 runs, and BLM 0.00001.

Marxan output was obtained as “best solution” and “selection frequency scores” (Supplementary Information, Table S1). The distribution of PUs in the Marxan solution was visualized for 10 decile classes of selection frequency. Using the PUs in the best solution for tiger habitat and biodiversity potential, various combinations based on biodiversity potential classes were created. These combinations were then placed into five priority categories.

3. Results

3.1. Biodiversity Potential

Biodiversity potential scores ranged from 0.086 to 0.535 for 12,492 grids of size 4 km^2 (including small partially clipped grids at the edge of landscape boundary) (Figure 2). The low biodiversity potential class had 4674 (37.41%) grids ($2\text{ km} \times 2\text{ km}$), the moderate biodiversity potential class had 3931 (31.46%) grids, and the high biodiversity potential class had 3887 grids (38.11%) (Figure 2). Most of the low biodiversity potential PUs were in the agriculture areas, and high biodiversity potential PUs were in forest areas.

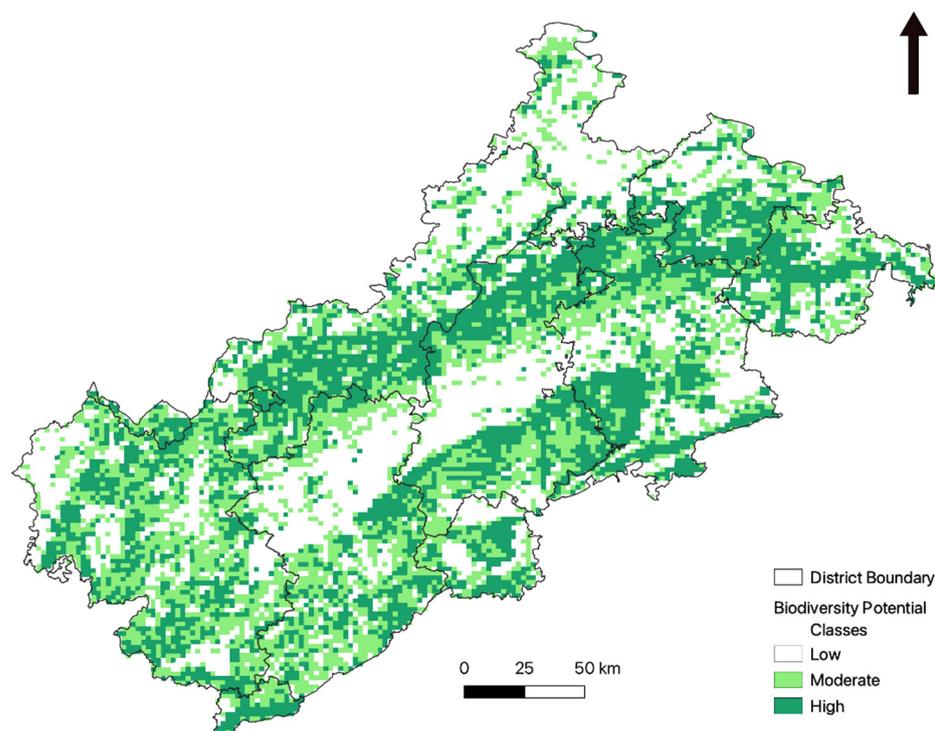


Figure 2. Spatial distribution of biodiversity potential classes in Panna Landscape.

A total of 32 species of mammal and 355 species of vegetation were recorded during field sampling. Field measured species richness for different taxa was found to increase with the increase in biodiversity potential, except for herbivores, primates, and rodents, which have fewer species and are also present throughout the landscape. Kruskal–Wallis test using all taxa (data in Table 3) showed no statistically significant difference (chi-squared = 2.538, $df = 2$, $p = 0.281$, 95% confidence interval) between the three biodiversity potential classes. However, a statistically significant difference (chi-squared = 7.758, $df = 2$, p -value = 0.021) was noted if the species richness for herbivores, primates, and rodents was removed.

Table 3. Field measured species richness in biodiversity potential classes.

Field Measured Species Richness	Biodiversity Potential		
	Low	Moderate	High
Trees	13	59	79
Shrubs	7	20	28
Herbs	6	75	113
Carnivores	13	17	18
Herbivores	8	9	9
Primates	2	2	2
Rodents	3	3	3

The multinomial logistic regression and z-test found all of the variables to be statistically significant except for rodent richness in the moderate biodiversity potential category (Supplementary Information, Table S3). The overall classification accuracy in predicting the biodiversity potential classes using field species richness data was 65.1%. It was observed that most of the misclassifications were between the moderate and high biodiversity potential classes and together represented 93.37%, reflecting that the surrogate approach to define biodiversity potentials has empirical support to classify the area of low with the rest of the classes.

3.2. Prioritization for Tiger Habitat and Biodiversity Potential

For tiger habitat, 610 (18.85%) PUs out of 3236 available PUs were selected in the best solution (Table 4, Figure 3). This constitutes 9345.03 km² area (18.87% of the landscape). For biodiversity potential, overall, 6963 (55.73%) PUs out of available 12,492 units were selected (Table 4, Figure 3). This constitutes an area of 27,315.09 km² (55.15% area of the landscape). Further within biodiversity potential, 1122 PUs were selected with low biodiversity potential, 1954 PUs with moderate biodiversity potential, and 3887 PUs with high biodiversity potential (Table 4). An area of 4201.15 km² (8.48% of the landscape area) was selected with low biodiversity potential, 7702.19 km² (15.55% of the landscape area) of moderate, and 15,411.75 km² (31.12% of the landscape area) of the area falls within the existing protected areas. As a whole, this configuration would conserve 29,260.12 km² area (59.08% of the geographical area of the GPL).

Table 4. Planning units selected for prioritization for each conservation feature.

	Tiger Habitat	Biodiversity Potential			
		Overall	Low	Moderate	High
Total Pus *	3236	12492	4674	3931	3887
PUs in best solution *	610	6963	1122	1954	3887
Area in best solution (km ²)	9345.03	27,315.09	4201.15	7702.19	15,411.75

* It includes clipped grid cells /PUs at the edge of the landscape.

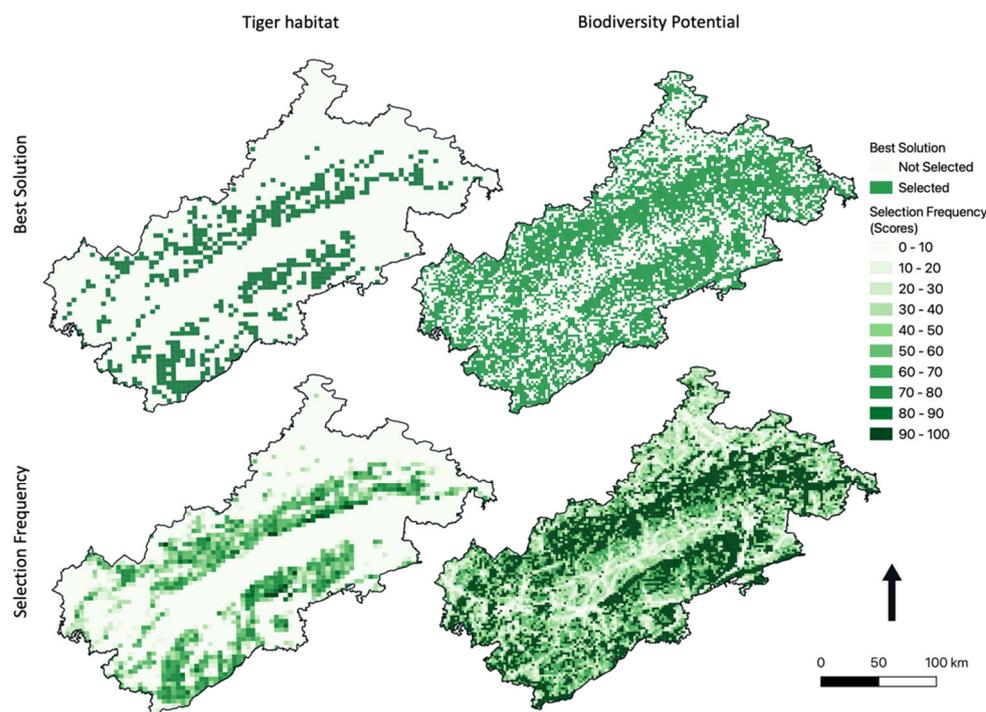


Figure 3. Marxan solution as best solution and selection frequency scores for tiger habitat and biodiversity potential.

3.3. Cost and Selection Frequency

In terms of the cost of planning units for tiger habitat, the majority of planning units were selected within a narrow range of 200 to 400 (Figure 4a), while for biodiversity potential, we observed selection of PUs with a cost greater than 50 and a decline in SF scores with increasing cost (Figure 4b). In terms of tiger habitat, the selection frequency scores of the selected PUs spanned over the entire range of classes, i.e., from 0–10 to 90–100 (Figure 4c). The majority of PUs had an SF score between 70 and 80, which means that they were selected in the best solution in 70 to 80 runs out of 100 runs. For biodiversity potential, the target for high biodiversity was met in the top decile of SF scores with a total of 3887 PUs (Figure 4d). For moderate biodiversity potential, the target was achieved at the fifth decile of SF scores (50–60). For low biodiversity potential, the target was met in the seventh decile of SF scores (30–40). Therefore, the selection of PUs having SF scores greater than 50 will only achieve targets for high and moderate biodiversity potential.

3.4. Priority Areas for Conservation

We obtained eight unique combinations of priorities with tiger and biodiversity potential—namely, (1) tiger only, (2) tiger and high biodiversity potential, (3) tiger and moderate biodiversity potential, (4) tiger and low biodiversity potential, (5) only high biodiversity potential, (6) only moderate biodiversity potential, (7) only low biodiversity potential, and (8) not selected for tiger or biodiversity potential. We merged these eight categories to obtain six categories as (1) priority I (tiger and high biodiversity potential); (2) priority II (tiger and moderate biodiversity potential; only high biodiversity potential); (3) priority III (only tiger; tiger and low biodiversity potential); (4) priority IV (only moderate biodiversity potential); (5) priority V (only low biodiversity potential), and (6) not prioritized (Figure 5). We further recommended management actions for these zones ranging from strict protection to community-based conservation and restoration (Table 5).

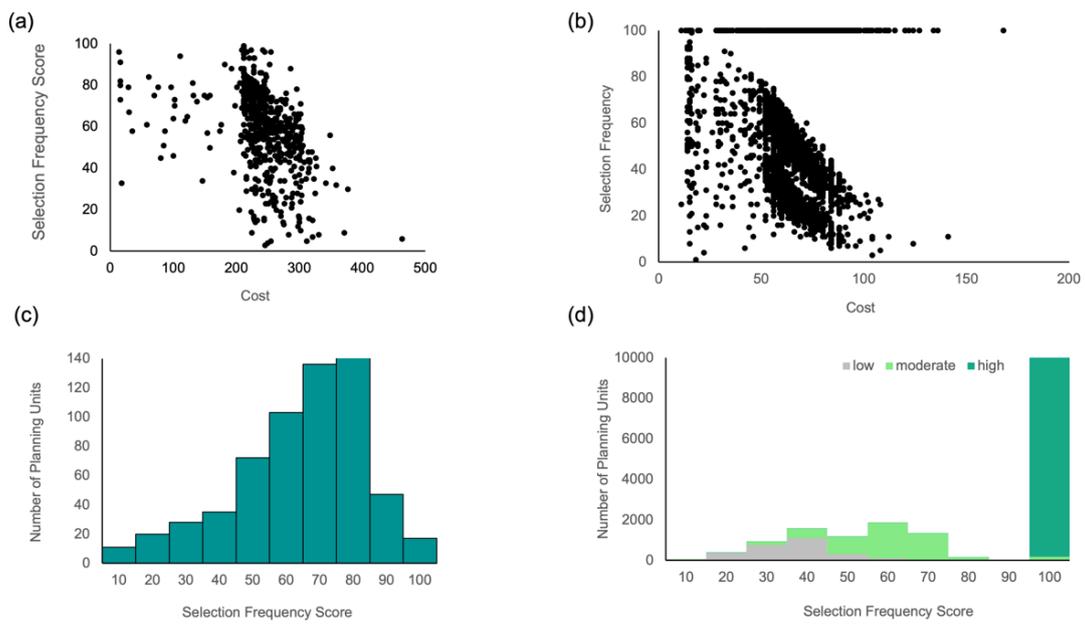


Figure 4. Distribution of planning units among different selection frequency scores for (a) tiger habitat and (b) biodiversity potential. Selection frequency versus the cost of planning units for (c) tiger habitat and (d) biodiversity potential.

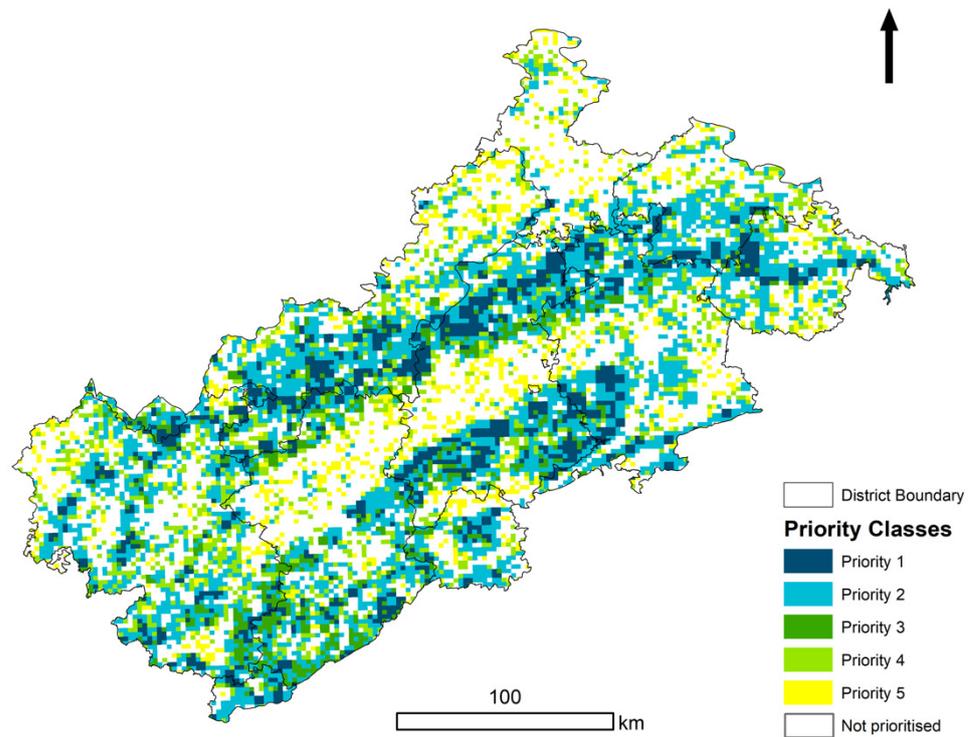


Figure 5. Priority areas for conservation in Panna Landscape.

Table 5. Priority levels and recommended action for different zones based on biodiversity potential and tiger habitat.

Priority Level	Description	Recommended Action
Priority I	Prioritized for Tiger AND high biodiversity potential	Inviolate and no-go areas
Priority II	Prioritized for Tiger AND moderate biodiversity potential OR only high biodiversity potential	Protection measures
Priority III	Prioritized for Tiger AND low biodiversity potential OR prioritized only for tiger	Protection measures and population augmentation for different taxa
Priority IV	Prioritized only for moderate biodiversity potential	Protection, population augmentation for different taxa, and restoration
Priority V	Prioritized only for low biodiversity potential	Social forestry and Restoration

District Panna held the maximum area under priority I, followed by Chhatarpur, Sagar, and others (Table 6). Sagar held the maximum area under priority II, followed by Satna, Chhatarpur, and others. Damoh held the maximum area under priority III, followed by Sagar, Panna, and others. Sagar held the maximum area under priority IV, followed by Chhatarpur, Damoh, and others. Panna held the maximum area under priority V, followed by Sagar, Damoh, and others. District Sagar also held the maximum area under the non-prioritized category.

Table 6. District-wise area (in km²) distribution for different priority regions of conservation.

District	Priority I	Priority II	Priority III	Priority IV	Priority V	Not Prioritized
Banda	19.613	346.463	0.638	243.858	411.078	2010.290
Chhatarpur	694.261	1799.758	258.014	786.011	657.140	2243.568
Chitrakoot	180.034	1008.221	17.365	398.756	219.070	1247.074
Damoh	531.414	1617.270	760.210	776.400	558.192	2777.839
Katni	127.875	484.473	82.768	148.514	170.046	587.091
Lalitpur	79.757	119.893	51.146	48.160	2.373	55.605
Narsinghpur	90.846	218.972	37.652	37.313	5.331	102.288
Panna	1325.439	1770.633	490.718	569.252	633.776	2018.931
Rewa	261.602	869.606	51.371	394.478	271.766	1119.092
Sagar	729.060	2467.751	503.496	1451.900	592.063	3423.288
Satna	673.965	2169.288	202.842	672.608	452.927	2491.929

4. Discussion

4.1. Accounting for Biodiversity

We undertook a biodiversity-centric approach by integrating biodiversity potential into the tiger conservation framework at the landscape scale, taking human footprint as a constraint. As species distribution and abundance status were available for a few protected areas and fewer taxa in the landscape [79], we opted for a coarse filter approach [80–82], and therefore, we set targets for land cover type and a surrogate measure for biodiversity potential. An advantage of this method is that the species or taxa bias can be avoided [82], and it is more representative encompassing various habitat features and taxa than covered

by fewer protected areas. Additionally, incorporating connectivity in the prioritization of tiger habitat allowed the inclusion of ecological processes (e.g., dispersal) instead of purely structural habitat information.

Biodiversity is a complex encapsulation of the structure, function, distribution, traits, and composition of all living things at different scales, and measuring and monitoring biodiversity are equally complex [83]. Methodological frameworks used for landscape-level characterization of biodiversity have a similar hypothesis that biological richness is a function of variables such as disturbance, biogeographical setting of the landscape, structural habitat, and terrain complexity [84–86]. In recent decades, remote sensing techniques have been used widely to acquire synoptic data that are explicit and can be collected at multiple spatiotemporal scales [38,84–86]. Environmental variables and indicators derived from remotely sensed imagery can provide distinct information specific to biodiversity and its richness [87]. Satellite-derived biodiversity indicators such as topography, land cover, and vegetation (vegetation productivity) have been used in the last few decades to assess biodiversity [88–92]. These studies confirmed that these indicators were efficient in predicting the species richness in different habitat types with high accuracies (sometimes >90%). Duro et al. [93] recommended four broad categories of key indicators—namely, topography, land cover, vegetation (vegetation productivity), and disturbance for national biodiversity monitoring in Canada, based solely on remote sensing datasets.

In our study, we used ecological, biophysical, and anthropogenic variables to account for habitat variability and, therefore, representation of most taxa in the landscape, which is similar to other studies mentioned above. A notable difference, however, was that we chose to use field-measured species richness for testing representation of the biodiversity potential classes, rather than using species richness data as input to compute the biodiversity potential. The primary reason was that we wanted to develop a simple method that can be replicated across the country using open access and freely available datasets. Nonetheless, we observed that field-measured species richness was able to explain biodiversity potential classes. The classification accuracy was 65%, which is mainly due to the fuzzy nature of these classes, and it increased to ~93% upon merging the moderate and high classes. We acknowledge that biotic and abiotic conditions are subject to change with time, and the availability of new or better data in the future can improve decision making. In such situations, this framework can be adapted to include the new information. Therefore, this index is intended to be used as an indicator and not an absolute measure of biodiversity.

4.2. Landscape and Jurisdictional Approaches

The integrated landscape approach (or landscape approach) to conservation and development is a long-term engagement that attempts to achieve the balance between multiple goals, involving diverse stakeholders that address conflicts in land use [94]. It extends beyond traditional management practices and addresses the complex social, political, and environmental challenges associated with sustainable use of land [95]. For example, integrated landscape approaches have been used in Indonesia to achieve sustainability and conservation goals [96]. Similarly, jurisdictional approaches define landscape by policy-relevant boundaries and apply policies and practices at these jurisdictional scales to halt deforestation and degradation [97,98]. Jurisdictional approaches offer both advantages and challenges in implementing landscapes, but their success or failure is yet to be observed, as they are comparatively newer [97]. Nonetheless, jurisdictional approaches are relevant in the case of countries where decision making occurs at multiple levels, for example, in India, Ghana, etc. [97,99]. On the other hand, the landscape approach has been widely advocated despite the lack of empirical data that would prove its effectiveness [94]. Similarly, a study by McIntosh et al. [100] highlighted that the literature on systematic conservation planning is dominated by methodological studies, with fewer examples of implementation and outcomes.

The approach used in our study allows a mix of both landscape and jurisdictional approaches, with context-specific implementation targeted for each district. Further, the sys-

tematic conservation planning framework offers an objective method that can be repeated for each district at finer scales keeping the “big picture” of landscape targets as a guiding post. With the area under each priority level highlighted for each district in the landscape, fine-scale data at the district level can be used to create district-level plans. This can involve local communities in decision making and address specific issues at the local scale. For example, local knowledge on biodiversity can guide the designation of community reserves and the selection of tree species for plantation under compensatory afforestation (CAMPA) and agroforestry initiatives. Similarly, for eco-tourism and nature-based livelihood options, several local factors such as education and socioeconomics can be taken into consideration.

4.3. Policy vs. Evidence-Based Targets for Conservation

Setting clear goals and objectives is an integral part of the framework of systematic conservation planning and prioritization [101]. This is achieved by setting targets that allow the progress to be measured against a benchmark [67]. However, tools such as Marxan cannot answer questions related to the extent to which a site should be protected, and what proportion of a feature or species must be conserved. In the history of conservation planning, targets have been found to range from policy-driven to evidence-based where policy-driven targets have little to no scientific grounding, and evidence-based targets are based on measures such as habitat suitability of the species or area requirement for the population viability [102]. Targets that address representation, resiliency, and redundancy add much-needed biological grounding to somewhat “arbitrary” policy-driven and analytical targets [103,104]. Large carnivores bring an important perspective to the conservation targets by playing the role of umbrella species [105]. For the current land-use change, they have been found to work as surrogates for several other threatened species of birds, amphibians, mammals, and reptiles [106]. However, a 17% target will not be sufficient to represent all the carnivores equally and will require a target of 21% and 24% for the current and future land-use change scenario, respectively [107]. Therefore, by setting targets of 50% for tiger habitat, we were able to avoid the arbitrariness of the targets.

4.4. What Will Priority Levels Mean for Protection and Conservation?

Based on the priority level, we suggest management or conservation actions be implemented for each priority level. Priority I areas that are important for both tiger and biodiversity can be declared inviolate areas, with the least human disturbance. These areas must then be non-negotiable for any proposed development project, as they interfere with tiger dispersal and future natural colonization. Priority II area will require enhanced protection since this is contiguous with priority I area. The protection can be offered by the local communities living in the vicinity with support from the forest department. Priority III area holds significance for tigers but has low biodiversity potential. Therefore, these sites can be targeted for restoration based on local population estimates. Priority IV area holds moderate biodiversity potential and, therefore, must focus on protection and restoration activities. Priority V area largely coincides with the agricultural areas and has low biodiversity potential. Private land conservation area approaches [108], organic farming, or agroforestry initiatives are possible in these sites to restore ecosystem services [109,110].

The priority levels will work as blueprints for the entire landscape and will be effective only when recommended actions are implemented. For example, priority I sites will have no effect on conservation if the contiguous priority II areas are highly disturbed. Further, there will be a need for effective collaborative partnerships and mutual learning between managers of the districts and the PAs [92]. A network theory approach can be extremely useful in this context as the GPL implements its conservation strategy in the future [111]. Additionally, it must be noted that the recommended actions will look very different in agriculture dominant and forest dominant districts. There cannot be a one-size-fits-all approach within the landscape. Each district has different issues and different species composition and, therefore, requires a different stakeholder engagement process at the district and village levels. At the level of each district, integrated district management plans must

be made to incorporate conservation strategies. These strategies can vary from community reserves, sacred groves, social forestry, organic farming, or private land conservation areas depending on the land use and socioeconomics. Recently, organic farming, agroforestry, and other nature-based solutions are proving crucial in conserving biodiversity and adding new evidence to achieve sustainable development and conservation goals [108,109,111]. With three-fourths of the population involved in the agriculture sector and millions of people living around protected areas, developing countries such as India require unified approaches to meet the national and global commitments made for biodiversity conservation and human well-being.

4.5. Opportunities

Setting targets for biodiversity alone is not sufficient for conservation [21]. It requires a balanced approach between ecological, social, and economic aspects of the landscape. Biodiversity conservation, especially for large carnivores, is affected by the nature of human–wildlife relationships (e.g., traditional values) and socioeconomics of the landscape [112–115]. These relationships and people’s perception toward wildlife and conservation are often driven by factors that vary with scale (e.g., at household and village level) but also across and between landscapes [112,113,116,117]. Therefore, more efforts are required to understand these relationships and integrate them into planning at the local scale [114]. Further, this analysis can benefit from the availability of detailed socio-economic cost data and ecosystem service supply maps in the landscape, as utilized in other studies [118].

5. Conclusions

Conservation of tigers is an international priority but also a complex and challenging task [3], particularly when conservation overlaps with livelihood and development goals in the spatial context. As India is observing an increase in tiger population, we advocate the need to consider other taxa in conservation plans and adopt a more integrated approach in tiger landscapes. Acknowledging the fact that empirical data on the status of biodiversity will always be limited, the biodiversity potential index using open-source earth observation data can account for general patterns of biodiversity potential and reflect the restoration opportunities. Significantly, the field-measured species richness for representative taxa could explain the biodiversity potential across the landscape. Marxan, a decision-making tool for conservation management, allowed objectively selecting sites in a framework that can be adapted to changing landscape characteristics (e.g., land use, human population, policies) incorporating umbrella species and other biodiversity components. Given the spatially explicit outcome, stakeholder engagement for setting conservation targets can be plausible. Further, the area under each priority level in different districts of the landscape can be used for long-term land-use policy and integrated development actions. The methodological framework can be scaled up to other regions across India and used in other tiger range countries for land managers and decision makers to allocate resources that are often limited in developing countries.

Supplementary Materials: The following supporting information can be downloaded at: <https://www.mdpi.com/article/10.3390/land11030371/s1>. Table S1: Description of terms used in this study, Table S2: Resistance matrix used for calculation of connectivity with the least cost path method, Table S3: Coefficients, standard error, and p values for logistic regression and z-test, Table S4: Confusion matrix for multinomial logistic regression model, Figure S1: Distribution of field sampling points in the landscape.

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Data Availability Statement: The data used in this study are open source and can be freely downloaded from respective sources. Other data can be accessed from the corresponding author upon reasonable request.

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