



Article A Framework for the Magnetic Dipole Effect on the Thixotropic Nanofluid Flow Past a Continuous Curved Stretched Surface

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Abstract: The magnetic dipole effect for thixotropic nanofluid with heat and mass transfer, as well as microorganism concentration past a curved stretching surface, is discussed. The flow is in a porous medium, which describes the Darcy–Forchheimer model. Through similarity transformations, the governing equations of the problem are transformed into non-linear ordinary differential equations, which are then processed using an efficient and powerful method known as the homotopy analysis method. All the embedded parameters are considered when analyzing the problem through solution. The dipole and porosity effects reduce the velocity, while the thixotropic nanofluid parameter increases the velocity. Through the dipole and radiation effects, the temperature is enhanced. The nanoparticles concentration increases as the Biot number and curvature, solutal, chemical reaction parameters increase, while it decreases with increasing Schmidt number. The microorganism motile density decreases as the Peclet and Lewis numbers increase. Streamlines demonstrate that the trapping on the curved stretched surface is uniform.

Keywords: magnetic dipole effect; thixotropic nanofluid; curved stretching surface; analytical solution

1. Introduction

Non-Newtonian fluid flows have already captivated the attention of researchers. These materials are used extensively in bioengineering, geophysics, pharmaceuticals, chemical and nuclear industries, polymer solutions, cosmetics, oil storage engineering, paper manufacturing, and other fields. Clearly, no single constitutive relationship can account for all non-Newtonian materials based on behavioral shear stresses. It is distinct from Newtonian and creeping viscous fluids [1]. As a result, several non-Newtonian fluid models have been proposed [2–5]. One such model is the thixotropic fluid model. The shear thinning fluid differs from the thixotropic fluid in that the shear thinning fluid has



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Copyright: © 2021 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). less viscosity and its shear rate increases over time, whereas the viscosity of a thixotropic fluid decreases with a constant shear rate. A few studies on thixotropic and non-Newtonian fluid models can be found in the references [6–21].

The suitability of the flow of porous media for a wide range of practical industrial applications, including crude oil extraction, food storage, fossil fuels, geothermal systems, porous insulation, packaged beds, petroleum technology and waste disposal, etc., has attracted considerable interest among scientists. Various models, such as Darcy–Forchheimer and Darcy and Brinkman, have been introduced in the literature. Researchers are interested in studying porous media models because of its importance. These models may be established in the light of Darcy's law, where the pressure gradient is directly related to the average velocity of the volume. Darcy's formula may be slow and porous with no effect of inertia, porosity variable, solid boundary or thermal dispersion. To achieve the desired accurate results, the presence of non-Darcian effects is crucial for the porous media analysis as discussed by Nield and Bejan [22]. These effects are presented by Forchheimer [23], with response of the square velocity term to the Darcian velocity term. Subsequently, Morris [24] coined the term "Forchheimer", applicable to the high Reynolds number. Kishan and Maripala [25] investigated the effects of viscous dissipation and thermophoresis analysis on the mixed convection in Darcy–Forchheimer MHD fluid via porous saturated media. Rauf et al. [26] investigated the thermal radiation viscous fluid flow in Darcy–Forchheimer porous space over a curved moving surface. Jagadha [27] studied the Darcy–Forchheimer mixed convection MHD boundary layer flow with viscous dissipation in nanofluid saturated with porous media.

The ferrofluids describe a specific category of magnetizable fluids with interesting effects that have a tremendous technological impact. The ferrofluid is often a single magnetic particle domain colloidal suspension with a size of approximately 10 nm. Aerodynamics and computer peripherals, avionics, cooling agents, crystal processing, filtration, fiber optics, loudspeakers, laser based operational devices, nuclear power plants, robotics, semiconductor processing, refrigeration, plastic drawing, etc. regularly use ferrofluids in a number of industrial applications. Like these innumerable applications, a number of studies of ferrofluids have been carried out by researchers and scientists. Andersson [28] investigated the ferrofluid with special effects of magnetic dipole. Hayat et al. [29] investigated the magnetic dipole effect on radiative ferromagnetic Williamson fluid flow. Some important studies in connection with ferrofluid are presented in the references [30–32].

For industrial, chemical applications and bio-engineering, such as drying, energy transport between desert coolers and cooling towers, food processing, production of polymers, evaporation, and metal work, the study of chemical reactions (productive/destructive) are essential for stretching surfaces. Extrusion on the stretched surface, heat transfer in the MHD stagnation point flow under the effect of chemical reactions and transpiration are analyzed by Mabood et al. [33]. Narayana and Babu [34] presented a study of MHD Jeffrey fluid flow with the chemical reaction effects over a stretching sheet numerically. Mixed peristaltic convective flow of Prandtl fluid to Hall current and chemical reaction effects is investigated by Hayat et al. [35]. Hayat et al. [36] studied the hydromagnetic flow of viscous fluid with chemical reaction and thermal radiation through a curved stretching sheet. The others relevent and stretching surfaces studies can be seen in the references [37–43].

Bioconvection is a common phenomenon that occurs in suspensions due to the upswimming of microorganisms that have a marginally higher density than water. When the upper surface of the suspensions becomes too dense due to microorganism proliferation, it becomes porous and microorganisms collapse, resulting in bioconvection. These microorganisms may exhibit gravitaxis, gyrotaxis, or oxytaxis. Supporting gyrotactic microorganisms for fluids aids in mass conversion, mixing micro-scales, and increasing fluid stability, particularly in micro-volumes. A number of researchers have investigated its various effects on fluid flow. Chamkha et al. [44] investigated the radiating effects on gyrotactic microorganisms on a vertical plate with fluid variability of temperature in natural bioconvection flow. Raju and Sandeep [45] proposed a mathematical model to study bioconvection through the use of non-linear chemical and thermal radiation in a rotational fluid. Hady et al. [46] studied the unsteady bioconvection thermal boundary layer flow in the presence of gyrotactic microorganisms on a stretching plate and a vertical cone in a porous medium. Recent investigations on bioconvection can be found in the references [47–56].

The current study discusses the magnetic dipole effect on thixotropic fluid with heat and mass transfer, as well as microorganism concentration passing through a curved stretching surface. The Darcy–Forchheimer model is used to describe the flow in a porous medium. Thermal radiation and viscous dissipation effects are also taken into consideration. Through appropriate similarity transformations, partial differential equations are transformed into ordinary differential equations and solved using a well-known technique, namely homotopy analysis method HAM [57–59]. Many researchers [40,47,60–63] have used HAM to solve their research problems. The results obtained are used to discuss graphically the effects of all the relevant parameters on all dimensionless profiles.

2. Methods

Two-dimensional hydrodynamic incompressible ferromagnetic thixotropic nanofluid past a stretched curved sheet under the influence of magnetic dipole is considered. xand y are used for curvilinear coordinates. The stretching surface is curled in a radius circle R'. Based on the linear velocity u = Ax (A is constant), the sheet is stretched in the x-direction and y-direction, which is transverse to x-direction. The magnetic field of strength B_0 is perpendicular to the flow direction. The surface is submerged in a non-Darcy porous medium. As the Reynolds number (due to a magnet) is smaller in the present problem, the electrical and induced magnetic fields are ignored. Convective heat and mass transfer conditions are observed. In addition, a chemical reaction of the first order is also considered.

In conjunction with the above assumptions, the boundary layer of the equations involved are governed by the following terms [7,26,27,29,30]

$$\frac{\partial\{(y+R')v\}}{\partial y} + R'\frac{\partial u}{\partial x} = 0,$$
(1)

$$\frac{u^2}{y+R'} = \frac{1}{\rho} \frac{\partial p}{\partial y'},\tag{2}$$

$$\rho\left(v\frac{\partial u}{\partial y} + \frac{R'u}{y+R'}\frac{\partial u}{\partial x} + \frac{uv}{y+R'}\right) = \frac{R'}{y+R'}\frac{\partial p}{\partial x} + \mu\left(\frac{\partial^2 u}{\partial y^2} - \frac{u}{(y+R')^2} + \frac{1}{y+R'}\frac{\partial u}{\partial y}\right)
- 6R_1\left(\frac{\partial u}{\partial y}\right)^2\left(\frac{\partial^2 u}{\partial y^2}\right) + 4R_2\left[\frac{\partial u}{\partial y}\frac{\partial^2 u}{\partial y^2}\left(u\frac{\partial^2 u}{\partial x\partial y} + v\frac{\partial^2 u}{\partial y^2}\right)
+ \left(\frac{\partial u}{\partial y}\right)^2\left(u\frac{\partial^3 u}{\partial x\partial y^2} + v\frac{\partial^3 u}{\partial y^3} + \frac{\partial u\partial^2 u}{\partial y\partial x\partial y} + \frac{\partial v\partial^2 u}{\partial y\partial y^2}\right)\right] - \frac{\mu S_1}{k_o}u - \frac{\rho C_b S_1}{\sqrt{k_o}}u^2 + \mu_o M\frac{\partial H}{\partial x},$$
(3)

$$(\rho c_p) \left(\frac{R'u}{y+R'} \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} \right) = \frac{k_T}{y+R'} \left[\frac{\partial T}{\partial y} + (y+R') \frac{\partial^2 T}{\partial y^2} \right] - 2\mu R_1 \left(\frac{\partial u}{\partial y} \right)^4 + 4\mu R_2 u \frac{\partial^2 u}{\partial x \partial y} \left(\frac{\partial u}{\partial y} \right)^3 + 4\mu R_2 v \frac{\partial^2 u}{\partial y^2} \left(\frac{\partial u}{\partial y} \right)^3 + \left(u \frac{\partial H}{\partial x} + v \frac{\partial H}{\partial y} \right) \mu_0 T \frac{\partial M}{\partial T} - \frac{k_T}{y+R'} \left(\frac{\partial q_r}{\partial y} (y+R') \right),$$
(4)

$$\frac{R'}{y+R'}u\frac{\partial C}{\partial x} + v\frac{\partial C}{\partial y} = \frac{D}{y+R'}\left(\frac{\partial C}{\partial y} + (y+R')\frac{\partial^2 C}{\partial y^2}\right) - K_c(C-C_{\infty}),\tag{5}$$

$$\left(\frac{R'}{y+R'}\right)u\frac{\partial N}{\partial x} + v\frac{\partial N}{\partial y} + \frac{bW_c}{C_w - C_\infty}\frac{\partial\left(N\frac{\partial C}{\partial y}\right)}{\partial y} = D_m\frac{\partial^2 N}{\partial y^2},\tag{6}$$

with boundary conditions

$$u = Ax = U_w(x), \quad v = 0, \quad -k_T \frac{\partial T}{\partial y} = h_1(T_w - T), \quad -D\frac{\partial C}{\partial y} = k_m(C_w - C), \quad N = N_w \quad at \quad y = 0, \tag{7}$$

$$u \to 0, \quad \frac{\partial u}{\partial y} \to 0, \quad v \to 0, \quad T \to T_{\infty}, \quad C \to C_{\infty}, \quad N \to N_{\infty}, \quad as \quad y \to \infty,$$
 (8)

where velocity components are (u,v) in the radial (*x*-direction) and transverse (*y*-direction), k_m is the mass transfer coefficient, h_1 is the convective heat transfer coefficient, R_1 and R_2 are the material constants, diffusion coefficient is *D*, constant fluid density is ρ , k_T is the thermal conductivity, σ is the electrical conductivity, k_o is permeability of porous medium, the effective dynamic viscosity is μ , magnetic permeability is μ_o , heat capacitance is (ρc_p) , first order chemical reaction parameter is K_c , microorganisms diffusion is D_m , speed of gyrotactic cell is W_c , *b* is the chemotaxis, C_b is the drag coefficient, S_1 is the porosity of porous medium, *T* is the temperature, *C* is the concentration, *N* is the gyrotactic microorganisms concentration, and C_{∞} , T_{∞} , and N_{∞} , respectively, stand for the nanoparticles concentration, temperature, and density of microorganisms far away from the surface.

Rosseland and Ozisik approximation allows to write the radiation heat flux q_r with σ^* Stenfan-Boltzman, and β_R mean absorption coefficient [64] as:

$$q_r = -\frac{4\sigma^*}{3\beta_R}\frac{\partial T^4}{\partial y} = -\frac{4T_\infty^3\sigma^*}{3\beta_R}\frac{\partial T}{\partial y}.$$
(9)

Magnetic Dipole

The characteristics of the magnetic field have an effect on the flow of ferrofluid due to the magnetic dipole. Magnetic dipole effects are recognized by the magnetic scalar potential Φ [29] shown in Equation (10)

$$\Phi = \frac{\gamma}{2\pi} \frac{x}{x^2 + (y+c)^2},$$
(10)

where γ stands for magnetic field strength at the source, *c* is the distance of the line currents from the leading edge. H_x and H_y are taken as the components of magnetic field as shown in Equations (11) and (12)

$$H_x = -\frac{\partial \Phi}{\partial x} = \frac{\gamma}{2\pi} \frac{x^2 - (y+c)^2}{[x^2 + (y+c)^2]^2},$$
(11)

$$H_y = -\frac{\partial \Phi}{\partial y} = \frac{\gamma}{2\pi} \frac{2x(y+c)}{[x^2 + (y+c)^2]^2}.$$
(12)

The magnetic field *H* is usually proportional to the components of magnetic field H_x and H_y , gradient along *x* and *y* directions respectively. It is therefore defined in Equation (13) as

$$H = \sqrt{H_x^2 + H_y^2}.$$
 (13)

It is considered that the temperature-dependent variation of magnetization M is linear as shown in Equation (14)

$$M = K_1(T - T_\infty),\tag{14}$$

where K_1 identifies the coefficient of the ferromagnetic. The physical schematic of the heated ferrofluid can be seen in Figure 1.



Figure 1. Schematic diagram of the problem.

Considering the following transformations [26], with ν as kinematic viscosity, *A* is constant:

$$u = Axf'(\zeta), \quad v = -\left(\frac{R'}{y+R'}\right)\sqrt{A\nu}f(\zeta), \quad p = \rho A^2 x^2 p(\zeta), \quad \zeta = y\sqrt{\frac{A}{\nu}},$$

$$\theta(\zeta) = \frac{T-T_{\infty}}{T_w - T_{\infty}}, \quad \phi(\zeta) = \frac{C-C_{\infty}}{C_w - C_{\infty}}, \quad \chi(\zeta) = \frac{N-N_{\infty}}{N_w - N_{\infty}}, \quad (15)$$

By the application of Equation (15), Equations (2)–(8) provide the following Equations (16), (18)–(25)

$$p' = \frac{f'^2}{\zeta + \alpha_1},\tag{16}$$

$$f''' - \left(\frac{\alpha_1}{\zeta + \alpha_1}\right) \left[ff'' - f'^2 + A_1 f' f \right] + Nn_1 f''^2 f''' + Nn_2 \left[f''^4 - \frac{\alpha_1}{\zeta + \alpha_1} \left(f'''^2 f f'' + f''^2 f f'''' \right) \right] - P_1 f' - L_i f'^2 + \frac{2\beta}{(\zeta + d)^4} \theta + 2 \left(\frac{\alpha_1}{\zeta + \alpha_1}\right) p = 0,$$
(17)

$$(1+Rd)\left(\theta''+\frac{\theta'}{(\zeta+\alpha_1)}\right) + Pr\left(\frac{\alpha_1}{\zeta+\alpha_1}\right)f\theta' + \frac{1}{3}PrNn_1Ecf''^4 + PrNn_1Ec\left[f'f''-ff'''\right] + \frac{2\beta\lambda(\theta-\epsilon)f}{(\zeta+d)^3} + \beta\lambda(\theta-\epsilon)\left[\frac{2f'}{(\zeta+d)^4} + \frac{4f}{(\zeta+d)^5}\right] = 0,$$

$$(18)$$

$$\phi'' + \frac{\phi'}{(\zeta + \alpha_1)} + \left(\frac{\alpha_1}{\zeta + \alpha_1}\right) Scf\phi' - \delta Sc\phi = 0,$$
(19)

$$\chi'' + Pe\left[\phi'\chi' + \phi''\chi + N_{\delta}\phi''\right] + Le\left(\frac{\alpha_1}{\zeta + \alpha_1}\right)f\chi' = 0.$$
⁽²⁰⁾

To eliminate the pressure term, integrating (16) to get p and replacing it, then (17) becomes

$$f''' - \left(\frac{\alpha_1}{\zeta + \alpha_1}\right) \left[ff'' - f'^2 + A_1 f' f \right] + Nn_1 f''^2 f''' + Nn_2 \left[f''^4 - \frac{\alpha_1}{\zeta + \alpha_1} \left(f'''^2 f f'' + f''^2 f f'''' \right) \right] - P_1 f' - L_i f'^2 + \frac{2\beta}{(\zeta + d)^4} \theta + \left(\frac{\alpha_1}{(\zeta + \alpha_1)^2}\right) (2ff'' - f'^2) = 0,$$
(21)

and the boundary conditions become

$$f'(0) = 1, f(0) = 0, f(\infty) = 0, f''(\infty) = 0,$$
(22)

$$\theta'(0) = -Bi_1[1 - \theta(0)], \theta(\infty) = 0,$$
(23)

$$\phi'(0) = -Bi_2[1 - \phi(0)], \phi(\infty) = 0, \tag{24}$$

$$\chi'(0) = 1, \, \chi(\infty) = 0, \tag{25}$$

where A_1 is the ratio of rate constants, α_1 is the curvature parameter, d is the dimensionless distance, Nn_1 and Nn_2 are the non-Newtonian parameters, β is the ferrohydrodynamic interaction parameter, heat dissipation parameter is λ , ε is the curie temperature, Prandtl number is Pr, radiation parameter is Rd, Eckert number is Ec, chemical reaction parameter is δ , the Schmidt number is Sc, local inertia parameter is Li, porosity parameter is P_1 , Lewis number is Pe, Lewis number is Le, thermal Biot number is Bi_1 and concentration Biot number is Bi_2 , which are defined by

$$A_{1} = \sqrt{\frac{\mu}{\rho A}}, \alpha_{1} = R'\sqrt{\frac{A}{\nu}}, Nn_{1} = \frac{4R_{2}A^{4}x^{2}}{\rho\nu^{2}}, Nn_{2} = \frac{-6R_{1}A^{4}x^{2}}{\rho\nu}, P_{1} = \frac{\mu S_{1}}{\rho Ak_{o}^{*}}, L_{i} = \frac{C_{b}S_{1}}{\sqrt{k_{o}^{*}}}, \\ \beta = \frac{\gamma\mu_{o}K_{1}\rho(T_{w} - T_{\infty})}{2\pi\mu^{2}}, Pr = \frac{\mu C_{P}}{k_{T}}, Ec = \frac{(Ax)^{2}}{C_{P}(T_{w} - T_{\infty})}, \lambda = \frac{A\mu^{2}}{\rho(T_{w} - T_{\infty})k_{T}}, d = \sqrt{\frac{Ac^{2}}{\nu}}, \\ \delta = \frac{AK_{c}}{\nu}, Rd = \frac{16\sigma^{*}T_{\infty}^{3}}{3k^{*}}, Sc = \frac{\nu}{D}, Pe = \frac{bW_{c}}{D_{m}}, Le = \frac{\nu}{D_{n}}, Bi_{1} = \frac{h_{1}}{k_{T}}\sqrt{\frac{\nu}{A}}, Bi_{2} = \frac{k_{m}}{k_{T}}\sqrt{\frac{\nu}{A}}, \\ \epsilon = \frac{T_{\infty}}{T_{\infty} - T_{w}}, N_{\delta} = \frac{N_{\infty}}{N_{w} - N_{\infty}}.$$
(26)

The quantities of interest, such as coefficient of skin friction, local Nusselt, Sherwood and local density numbers, are determined by

$$C_f = \frac{\tau_{yx}}{\rho(Ax)^2}, \ Nu_x = \frac{-xq_w}{k_T(T_w - T_\infty)}, \ Sh_x = \frac{-xq_m}{D(C_w - C_\infty)}, \ Sn_x = \frac{-xq_n}{D(N_w - N_\infty)},$$
(27)

where

$$\tau_{yx} = \mu u_y|_{y=0}, \ q_w = -k_T T_y|_{y=0} - \frac{4T_{\infty}^3 \sigma^*}{3\beta_R} \frac{\partial T}{\partial y}|_{y=0}, \ q_m = -DC_y|_{y=0}, \ q_n = D_m N_y|_{y=0}.$$
(28)

By putting values from Equation (28) in Equation (27), it is obtained that

$$C_{f} = \frac{1}{Re_{x}} \left(f''(0) - \frac{f'(0)}{\alpha_{1}} \right), \quad Nu = -Re_{x}^{0.5}(1 + Rd)\theta'(0),$$

$$Sh = -Re_{x}^{0.5}\phi'(0), \quad Sn = -Re_{x}^{0.5}\chi'(0).$$
(29)

3. HAM Solution

The initial guesses and the linear operators are taken as

$$f_0(\zeta) = A\zeta + (1-A)(1-e^{-\zeta}), \ \theta_0(\zeta) = \frac{Bi_1}{1+Bi_1}e^{-\zeta}, \ \phi_0(\zeta) = \frac{Bi_2}{1+Bi_2}e^{-\zeta}, \ \chi_0 = e^{-\zeta}.$$
 (30)

Equation (30) satisfies the properties as given below

$$L_{f}(E_{1} + E_{2}e^{\zeta} + E_{3}e^{-\zeta}) = 0, \quad L_{\theta}(E_{4}e^{\zeta} + E_{5}e^{-\zeta}) = 0,$$

$$L_{\phi}(E_{6}e^{\zeta} + E_{7}e^{-\zeta}) = 0, \quad L_{\chi}(E_{8}e^{\zeta} + E_{9}e^{-\zeta}) = 0, \quad (31)$$

where E_i (i = 1, ..., 9) indicates the arbitrary constants. The corresponding zeroth order form of the problems are

$$(1-q)L_{f}[f(\zeta,q) - f_{0}(\zeta)] = qh_{f}N_{f}[f(\zeta,q), \theta(\zeta,q)],$$

$$(1-q)L_{\theta}[\theta(\zeta,q) - \theta_{0}(\zeta)] = qh_{\theta}N_{\theta}[\theta(\zeta,q), f(\zeta,q)],$$

$$(1-q)L_{\phi}[\phi(\zeta,q) - \phi_{0}(\zeta)] = qh_{\phi}N_{\phi}[\phi(\zeta,q), f(\zeta,q)],$$

$$(1-q)L_{\chi}[\chi(\zeta,q) - \chi_{0}(\zeta)] = qh_{\chi}N_{\chi}[\chi(\zeta,q), \phi(\zeta,q), f(\zeta,q)],$$

(32)

$$f(0,q) = 0, f'(0,q) = 1, \ f'(\infty,q) = A, \ \theta'(0,q) = -Bi_1(1-\theta(0,q)), \ \theta(\infty,q) = 0,$$

$$\phi'(0,q) = -Bi_2(1-\phi(0,q)), \ \phi(\infty,q) = 0, \ \chi'(0,q) = 1, \ \chi(\infty,q) = 0,$$
(33)

$$\begin{split} \mathbf{N}_{f}[f(\zeta,q)] &= \frac{\partial^{3}f(\zeta,q)}{\partial\zeta^{3}} - \left(\frac{\alpha_{1}}{\zeta+\alpha_{1}}\right) \left[f(\zeta,q)\frac{\partial^{2}f(\zeta,q)}{\partial\zeta^{2}} - \left(\frac{\partial f(\zeta,q)}{\partial\zeta}\right)^{2} + A_{1}\frac{\partial f(\zeta,q)}{\partial\zeta}f(\zeta,q)\right] \\ &+ Nn_{1}\left(\frac{\partial^{2}f(\zeta,q)}{\partial\zeta^{2}}\right)^{2}\frac{\partial^{3}f(\zeta,q)}{\partial\zeta^{3}} + Nn_{2}\left[\left(\frac{\partial^{2}f(\zeta,q)}{\partial\zeta^{2}}\right)^{4} - \frac{\alpha_{1}}{\zeta+\alpha_{1}}\left(\left(\frac{\partial^{3}f(\zeta,q)}{\partial\zeta^{3}}\right)^{2}f(\zeta,q)\frac{\partial^{2}f(\zeta,q)}{\partial\zeta^{2}}\right) \\ &+ \left(\frac{\partial^{2}f(\zeta,q)}{\partial\zeta^{2}}\right)^{2}f(\zeta,q)\frac{\partial^{4}f(\zeta,q)}{\partial\zeta^{4}}\right) - P_{1}\frac{\partial f(\zeta,q)}{\partial\zeta} - L_{i}\left(\frac{\partial f(\zeta,q)}{\partial\zeta}\right)^{2} \\ &+ \frac{2\beta}{(\zeta+d)^{4}}\theta(\zeta,q) + \left(\frac{\alpha_{1}}{(\zeta+\alpha_{1})^{2}}\right)\left(2f(\zeta,q)\frac{\partial^{2}f(\zeta,q)}{\partial\zeta^{2}} - \left(\frac{\partial f(\zeta,q)}{\partial\zeta}\right)^{2}\right), \end{split}$$
(34)

$$\mathbf{N}_{\theta}[\theta(\zeta,q)] = (1+Rd) \left(\frac{\partial^{2}\theta(\zeta,q)}{\partial\zeta^{2}} + \frac{1}{(\zeta+\alpha_{1})} \frac{\partial\theta(\zeta,q)}{\partial\zeta} \right) + Pr\left(\frac{\alpha_{1}}{\zeta+\alpha_{1}}\right) f(\zeta,q) \frac{\partial\theta(\zeta,q)}{\partial\zeta} + \frac{1}{3} PrNn_{1} Ec \left(\frac{\partial^{2}f(\zeta,q)}{\partial\zeta^{2}} \right)^{4} + PrNn_{2} Ec \left[\frac{\partial f(\zeta,q)}{\partial\zeta} \frac{\partial^{2}f(\zeta,q)}{\partial\zeta^{2}} - f(\zeta,q) \frac{\partial^{3}f(\zeta,q)}{\partial\zeta^{3}} \right] + \frac{2\beta\lambda(\theta(\zeta,q)-\epsilon)f(\zeta,q)}{(\zeta+d)^{3}} + \beta\lambda(\theta-\epsilon) \left[\frac{2}{(\zeta+d)^{4}} \frac{\partial f(\zeta,q)}{\partial\zeta} + \frac{4f(\zeta,q)}{(\zeta+d)^{5}} \right],$$
(35)

$$\mathbf{N}_{\phi}[\phi(\zeta,q)] = \frac{\partial^2 \phi(\zeta,q)}{\partial \zeta^2} + \frac{1}{(\zeta+\alpha_1)} \frac{\partial \phi(\zeta,q)}{\partial \zeta} + \left(\frac{\alpha_1}{\zeta+\alpha_1}\right) Scf(\zeta,q) \frac{\partial \phi(\zeta,q)}{\partial \zeta} - \delta Sc\phi(\zeta,q), \tag{36}$$

$$\mathbf{N}_{\chi}[\chi(\zeta,q)] = \frac{\partial^{2}\chi(\zeta,q)}{\partial\zeta^{2}} + Pe\left[\frac{\partial\phi(\zeta,q)}{\partial\zeta}\frac{\partial\chi(\zeta,q)}{\partial\zeta} + \frac{\partial^{2}\phi(\zeta,q)}{\partial\zeta^{2}}\chi(\zeta,q) + N_{\delta}\frac{\partial^{2}\phi(\zeta,q)}{\partial\zeta^{2}}\right] + Le\left(\frac{\alpha_{1}}{\zeta+\alpha_{1}}\right)f(\zeta,q)\frac{\partial\phi(\zeta,q)}{\partial\zeta},$$
(37)

where $q \in [0, 1]$ is the embedding parameter while N_f , N_θ , N_ϕ , and N_χ are the nonlinear operators.

The *m*-th order deformation problems are as follows

$$L_{\theta}[\theta_m(\zeta, q) - \eta_m \theta_{m-1}(\zeta)] = h_{\theta} \mathcal{R}_{\theta, m}(\zeta), \tag{39}$$

$$\mathcal{L}_{\phi}[\phi_m(\zeta,q) - \eta_m \phi_{m-1}(\zeta)] = h_{\phi} \mathcal{R}_{\phi,m}(\zeta), \tag{40}$$

$$L_{\chi}[\chi_m(\zeta,q) - \eta_m\chi_{m-1}(\zeta)] = h_{\chi}\mathcal{R}_{\chi,m}(\zeta), \tag{41}$$

$$f_{m}(0) = f'_{m}(0) = f'_{m}(\infty) = 0,$$

$$\theta'_{m}(0) - Bi_{1}\theta_{m}(0) = \theta_{m}(\infty) = 0,$$

$$\phi'_{m}(0) - Bi_{2}\phi_{m}(0) = \phi_{m}(\infty) = 0,$$

$$\chi'_{m}(0) = \chi_{m}(0) = \chi_{m}(\infty) = 0,$$
(42)

$$\mathcal{R}_{f}^{m}(\zeta) = f_{m-1}^{\prime\prime\prime} - \left(\frac{\alpha_{1}}{\zeta + \alpha_{1}}\right) \left[\sum_{r=0}^{m-1} f_{m-1-r} f_{r}^{\prime\prime} - \sum_{r=0}^{m-1} f_{m-1-r}^{\prime} f_{r}^{\prime} + A_{1} \sum_{r=0}^{m-1} f_{m-1-r} f_{r}^{\prime}\right] \\ + Nn_{1} \sum_{r=0}^{m-1} \left(\sum_{k=0}^{r} f_{m-1-r}^{\prime\prime} f_{r-k}^{\prime\prime}\right) f_{k}^{\prime\prime\prime} + Nn_{2} \left[\sum_{r=0}^{m-1} \left(\sum_{k=0}^{r} \left(\sum_{p=0}^{k} f_{m-1-r}^{\prime\prime} f_{r-k}^{\prime\prime}\right) f_{k}^{\prime\prime}\right) - \frac{\alpha_{1}}{\zeta + \alpha_{1}} \left(\sum_{r=0}^{m-1} \left(\sum_{k=0}^{r} \left(\sum_{p=0}^{k} f_{m-1-r} f_{r-k}^{\prime\prime\prime}\right) f_{k-p}^{\prime\prime\prime}\right) f_{p}^{\prime\prime\prime}\right) \right] - P_{1} f_{m-1}^{\prime} - L_{i} \sum_{r=0}^{m-1} f_{m-1-r}^{\prime} f_{r}^{\prime} \\ + \frac{2\beta}{(\zeta + d)^{4}} \theta_{m-1} + \frac{\alpha_{1}}{(\zeta + \alpha_{1})^{2}} \left(2\sum_{r=0}^{m-1} f_{m-1-r} f_{r}^{\prime\prime} - \sum_{r=0}^{m-1} f_{m-1-r}^{\prime} f_{r}^{\prime}\right), \tag{43}$$

$$\mathcal{R}_{\theta}^{m}(\zeta) = \left(1 + Rd\right) \left(\theta_{m-1}^{\prime\prime} + \frac{\theta_{m-1}^{\prime}}{(\zeta + \alpha_{1})}\right) + Pr\left(\frac{\alpha_{1}}{\zeta + \alpha_{1}}\right) \sum_{r=0}^{m-1} f_{m-1-r}\theta_{r}^{\prime} \\ + \frac{1}{3} PrNn_{1}Ec \sum_{r=0}^{m-1} \left(\sum_{k=0}^{r} \left(\sum_{p=0}^{k} f_{m-1-r}^{\prime\prime} f_{r-k}^{\prime\prime}\right) f_{k-p}^{\prime\prime}\right) f_{p}^{\prime\prime} \\ + PrNn_{2}Ec \left[\sum_{r=0}^{m-1} f_{m-1-r}^{\prime} f_{r}^{\prime\prime} - \sum_{r=0}^{m-1} f_{m-1-r} f_{r}^{\prime\prime\prime}\right] + \frac{2\beta\lambda(\theta_{m-1} - \epsilon)f_{m-1}}{(\zeta + d)^{3}} \\ + \beta\lambda(\theta_{m-1} - \epsilon) \left[\frac{2f_{m-1}^{\prime}}{(\zeta + d)^{4}} + \frac{4f_{m-1}}{(\zeta + d)^{5}}\right],$$
(44)

$$\mathcal{R}_{\phi}^{m}(\zeta) = \phi_{m-1}^{\prime\prime} + \frac{\phi_{m-1}^{\prime}}{(\zeta + \alpha_{1})} + \left(\frac{\alpha_{1}}{\zeta + \alpha_{1}}\right) Sc \sum_{r=0}^{m-1} f_{m-1-r} \phi_{r}^{\prime} - \delta Sc \phi_{m-1}, \tag{45}$$

$$\mathcal{R}_{\chi}^{m}(\zeta) = \chi_{m-1}^{\prime\prime} + Pe\left[\sum_{r=0}^{m-1} \phi_{m-1-r}^{\prime} \chi_{r}^{\prime} + \sum_{r=0}^{m-1} \phi_{m-1-r}^{\prime\prime} \chi_{r} + N_{\delta} \phi_{m-1}^{\prime\prime}\right] + Le\left(\frac{\alpha_{1}}{\zeta + \alpha_{1}}\right) \sum_{r=0}^{m-1} f_{m-1-r} \chi_{r}^{\prime},$$
(46)

where

$$\eta_m = \begin{cases} 0, \text{ if } m \le 1\\ 1, \text{ if } m > 1. \end{cases}$$
(47)

The general solutions are given by

$$f_m(\zeta) = f_m^*(\zeta) + E_1 + E_2 e^{\zeta} + E_3 e^{-\zeta}, \tag{48}$$

$$\theta_m(\zeta) = \theta_m^*(\zeta) + E_4 e^{\zeta} + E_5 e^{-\zeta}, \tag{49}$$

$$\phi_m(\zeta) = \phi_m^*(\zeta) + E_6 e^{\zeta} + E_7 e^{-\zeta}, \tag{50}$$

$$\chi_m(\zeta) = \chi_m^*(\zeta) + E_8 e^{\zeta} + E_9 e^{-\zeta},$$
(51)

where $(f_m^*(\zeta), \theta_m^*(\zeta), \phi_m^*(\zeta), \chi_m^*(\zeta))$ are special solutions.

4. Convergence Analysis of the Homotopy Solution

The nonzero auxiliary parameters are involved in the homotopy solution. These parameters are extremely important in controlling and adjusting the convergence acquired by the homotopic series solutions. The *h*-curves at the 15th order of approximations are sketched to show the acceptable approximate region of convergence. Figure 2 depicts the region as falling within the ranges $-1.8 \le h_f \le 0.2, -2.5 \le h_\theta \le 0.8, -4.2 \le h_\phi \le 1.1, -0.4 \le h_\chi \le 0.4$. The values of parameters used are $A_1 = d = 1, \lambda = \beta = P_1 = Li = Sc = 0.3, \varepsilon = \delta = Ec = 0.1, Pe = Le = N_\delta = 0.2, Nn_1 = Nn_2 = 0.5, Pr = 6.8, Re = 0.7, \alpha_1 = Rd = Bi_1 = Bi_2 = 0.4$.



Figure 2. *h*-curves for $f(\zeta)$, $\theta(\zeta)$, $\phi(\zeta)$, $\chi(\zeta)$.

5. Discussion

The velocity behavior with the ferromagnetic hydrodynamic interaction parameter β can be seen in Figure 3. It demonstrates that the velocity decreases as β increases. Ideally, the resistance force known as Lorentz force [65] increases with the β increase, and the velocity field decreases. Figure 4 is used to investigate the effect of curvature parameter α_1 on the velocity profile. It is clearly shown in the figure that the velocity component decreases for larger α_1 . Figures 5 and 6 describe the effects of the thixotropic parameters Nn_1 and Nn_2 on the velocity profile. From these figures, it is observed that Nn_1 and Nn_2 result in an increase in fluid velocity. Ideally, Nn_1 and Nn_2 are associated with the properties of shear thinning, which show a time-dependent changes in viscosity. The higher the fluid under shear stress, the lower the viscosity of nanofluid, which will ultimately lead to an increase in fluid velocity. Figure 7 is used to present the velocity behavior with the porosity parameter P_1 . The presence of porous medium slows down the field of the flow, resulting in an increase in shear stress on the curved surface, and therefore the velocity profile shows a declining trend by increasing the values of P_1 . In contrast to the effect seen with P_{1i} change in local inertia parameter Li results in an increase in velocity as shown in Figure 8.

Figure 9 is used used to examine the effect of β on temperature. Here, temperature increases with higher values of β . The temperature profile behavior relating to the higher values of thermal Biot number Bi_1 is shown in Figure 10. The parameter Bi_1 significantly

promotes the temperature field in a positive manner attributable to the effective convective heat effects. It is also observed that there is no heat transfer at $Bi_1 = 0$. The effect of the heat dissipation parameter λ on temperature is shown in Figure 11. The temperature is a decreasing function of λ . Physically thermal conductivity of liquid decreases with larger λ , and therefore the temperature decreases. The Eckert number *Ec* attributes to the temperature profile is shown in Figure 12. For larger *Ec*, temperature and thermal boundary layer thickness were observed to be effected with the increase in *Ec.* In this phenomenon, the heat energy stored in the fluid is caused by friction forces that increase the temperature. The Curie temperature parameter ε effect on temperature profile is shown in Figure 13. The temperature decreases through larger values of ε . Thermal conductivity of the liquid increases with the larger ε . The effect of Prandtl number *Pr* on temperature profile is shown in Figure 14. The temperature distribution and thermal boundary layer are reduced by higher values of Pr, due to which thermal diffusion is reduced. In addition, fluids with a smaller values of *Pr* slowly decay compared to liquids with larger values of *Pr*. The effect of radiation parameter *Rd* on temperature profile is discussed in Figure 15. The increase in temperature curves with a larger boundary layer thickness is determined by an increase in Rd. Usually, mean absorption coefficient decays for higher estimation of *Rd* and diffusion flux occurs as a consequence of the temperature gradient, which therefore increases the temperature.

The effect of the concentration Biot number Bi_2 on the nanoparticles concentration profile is shown in Figure 16. In this case, the concentration is increased in response to increase in the Bi_2 values. Figure 17 shows the effect of the Sc on concentration profile. Since Sc is the ratio of momentum to mass diffusivity, the increase in Sc causes a decay in mass diffusivity, thus leading to a decrease in nanoparticles concentration. Figure 18 shows the effect of the curvature parameter α_1 on the nanoparticles concentration profile. The increase in the curvature parameter results in an increase in the concentration. Figure 19 shows the effect of the chemical reaction parameter δ on the concentration profile. The nanoparticles concentration is observed to increase for the higher estimates of δ . In fact, the consumption of reactive species rapidly declines as δ becomes larger.

Figure 20 shows the effect of Peclet number *Pe* on the microorganisms profile. There is a clear relationship between the reduced density of the microorganisms and the increase in *Pe*. The higher values of *Pe* indicate the minimum motile diffusivity. Figure 21 shows the impact of Lewis number *Le* on microorganisms concentration profile. The decrease in the concentration distribution is shown as the Lewis number increases, since it is inversely proportional to the mass diffusion.

The effect of the dimensionless variable ζ on the streamlines is shown in Figures 22 and 23. It is shown that the number of the trapped boluses increases as the values of ζ increase, and the streamlines have also been identified to be perpendicular to the surface. The increase in the ζ increases the shearing motion, which, in fact, results in a higher precession of the flow to the stretching surface.

Table 1 shows a numerical analysis of the skin friction coefficient for β , α_1 , P_1 , Li, Nn_1 , Nn_2 . It is discovered that the skin friction coefficient increases with the increasing values of β , P_1 , Li, Nn_2 , while a reverse trend is observed for α_1 and Nn_1 . Table 2 cross-checks the accurateness of the homotopic solution used in the present investigation. A comparison of skin friction coefficient for the different values of α_1 with the study [66] is shown for $P_1 = Li = \beta = A_1 = Nn_1 = Nn_2 = 0$ at $\zeta = 0$. Table 3 shows the numerical assessment of the local Nusselt number for various values of β , α_1 , λ , Pr, Rd, ε , Ec, Nn_1 , Nn_2 . It is observed that the local Nusselt number decreases with increasing values of β , α_1 , λ , Nn_1 . Table 4 shows the numerical values of the local Sherwood number for various values of α_1 , Sc, δ . It is observed that the local Sherwood number decreases with the increasing values of parameters. The tables clearly show that the current findings are completely consistent.



Figure 3. Impact of the ferrohydrodynamic interaction parameter β on velocity profile $f'(\zeta)$.



Figure 4. Impact of the curvature paraeter α_1 on velocity $f'(\zeta)$.



Figure 5. Impact of the non-Newtonian parameter Nn_1 on velocity $f'(\zeta)$.



Figure 6. Impact of the non-Newtonian parameter Nn_2 on velocity $f'(\zeta)$.



Figure 7. Impact of the porosity parameter P_1 on velocity $f'(\zeta)$.



Figure 8. Impact of the local inertia parameter *Li* on velocity $f'(\zeta)$.



Figure 9. Impact of the ferrohydrodynamic interaction parameter β on temperature $\theta(\zeta)$.



Figure 10. Impact of the thermal Biot number Bi_1 on temperature $\theta(\zeta)$.



Figure 11. Impact of the heat dissipation parameter λ on temperature $\theta(\zeta)$.



Figure 12. Impact of the Eckert number *Ec* on temperature $\theta(\zeta)$.



Figure 13. Impact of the curie temperature parameter ε on temperature $\theta(\zeta)$.



Figure 14. Impact of the Prandtl number *Pr* on temperature $\theta(\zeta)$.



Figure 15. Impact of the thermal radiation parameter *Rd* on temperature $\theta(\zeta)$.



Figure 16. Impact of the solutal Biot number Bi_2 on concentration $\phi(\zeta)$.



Figure 17. Impact of the Schmidt number *Sc* on concentration $\phi(\zeta)$.



Figure 18. Impact of the curvature parameter α_1 on concentration $\phi(\zeta)$.



Figure 19. Impact of the chemical reaction parameter δ on concentration $\phi(\zeta)$.



Figure 20. Impact of the Peclet number *Pe* on motile microorganism $\chi(\zeta)$.



Figure 21. Impact of the Lewis number *Le* on motile microorganism $\chi(\zeta)$.



Figure 22. Behavior of streamlines for $\zeta = 0.1$.



Figure 23. Behavior of streamlines for $\zeta = 0.3$.

β	α1	P_1	Li	Nn_1	Nn_2	$-C_f$
0.3	0.4	0.3	0.3	0.5	0.5	1.24238
0.7						1.24698
1.1						1.25158
	0.7					1.24467
	1.0					1.23511
	1.3					1.22220
		0.6				1.33715
		0.9				1.43382
		1.2				1.53241
			0.6			1.28757
			0.9			1.33233
			1.2			1.37976
				1.0		1.19970
				1.5		1.16111
				2.0		1.12627
					1.0	1.20631
					1.5	1.17235
					2.0	1.14041

Table 1. Numerical values of skin friction coefficient with varying values of the parameters β , α_1 , P_1 , Li, Nn_1 , Nn_2 .

Table 2. Comparative numerical values of the skin friction coefficient with published result with changing values of α_1 with $P_1 = Li = \beta = A_1 = Nn_1 = Nn_2 = 0$.

α1	Published Work [66]	Present Work
5	0.7577	0.7569
10	0.8735	0.8736
15	0.9357	0.9357

Table 3. Numerical values of Nusselt number with varying values of the parameters β , α_1 , λ , Pr, Rd, ε , Ec, Nn_1 , Nn_2 .

α1	λ	β	Pr	Rd	ε	Ec	Nn_1	Nn_2	Nu
0.4 0.7 1.0	0.3	0.3	6.8	0.4	0.1	0.1	0.5	0.5	0.331075 0.330973 0.330021
	0.8 1.3 1.8								0.332224 0.332115 0.332006
	1.0	0.7 1.1							0.332245 0.332158 0.222071
		1.5	6.9 10.0						0.333827 0.335319
			10.11	$\begin{array}{c} 0.6 \\ 0.8 \end{array}$					0.336809 0.379260 0.426063
				1.0	$0.4 \\ 0.7$				0.472745 0.332614 0.332896
					1.0	0.4			0.333177 0.334739 0.337145
						1.0	1.0		0.339552 0.332088
							1.5 2.0	1.0	0.331853 0.331625 0.333376
								1.5 2.0	$0.334405 \\ 0.335419$

α1	Sc	δ	Sh
0.4	0.3	0.1	0.23643
0.7			0.23658
1.0			0.23661
	0.8		0.23775
	1.3		0.238104
	1.8		0.238455
		0.5	0.238244
		0.9	0.239083
		1.3	0.239915

Table 4. Numerical values of Sherwood number with varying values of the parameters α_1 , *Sc*, δ .

6. Conclusions

The Darcy–Forchheimer hydromagnetic flow of thixotropic nanofluid through a curved stretching sheet with thermal radiation and chemical reaction in the presence of heat and mass transfer, gyrotactic microorganisms, and magnetic dipole is explored. The present study contributes to the findings set out below.

- The velocity decreases with increasing values of ferromagnetic parameter β and a curvature parameter α_1 , while it increases with increasing values of Nn_1 , Nn_2 and P_1 .
- The temperature increases with increasing values of *Ec*, *β*, and *Rd* and decays with increasing values of *Pr*.
- The nanoparticles concentration decreases with increasing values of Sc and δ, while it
 increases with increasing values of Bi₂ and α₁.
- The distribution of the microorganism is decreased with increasing values of *Pe* and *Le*.
- The non-Newtonian parameters *Nn*₁ and *Nn*₂ have the same decreasing effects on the skin friction coefficient, while *Nn*₁ decreases and *Nn*₂ increases the heat transfer rate.

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