



Correction Correction: Hussain et al. Passive Electro-Optical Tracking of Resident Space Objects for Distributed Satellite Systems Autonomous Navigation. *Remote Sens.* 2023, 15, 1714

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Text Correction

There was an error in the original publication [1]. The thruster specifications are incorrect. A correction has been made to Results and Discussions in Section 5.3. Trajectory Optimization for collision avoidance.

It should be: It is assumed that the spacecraft that performs the orbit-raising manoeuvre is equipped with Nano Avionics EPSSC1 [95], which can generate a thrust of 1 N with a specific impulse of 213 seconds.

References

There was an error in reference 95, Electric Ion Space Propulsion Systems and Thrusters. Available online: https://www.space-propulsion.com/spacecraft-propulsion/propulsion-systems/electric-propulsion/index.html (accessed on 18 August 2022). It should be Cube-Sat Propulsion System EPSS, NanoAvionics. Available online: https://nanoavionics.com/cubesat-components/cubesat-propulsion-system-epss/ (accessed 2 January 2023). With this correction, the order of some references has been adjusted accordingly.

The authors state that the scientific conclusions are unaffected. This correction was approved by the Academic Editor. The original publication has also been updated.

Reference

 Hussain, K.F.; Thangavel, K.; Gardi, A.; Sabatini, R. Passive Electro-Optical Tracking of Resident Space Objects for Distributed Satellite Systems Autonomous Navigation. *Remote Sens.* 2023, 15, 1714. [CrossRef]

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