

## Article

# Using SAR-Derived Vegetation Descriptors in a Water Cloud Model to Improve Soil Moisture Retrieval

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**Abstract:** The water cloud model (WCM) is a widely used radar backscatter model applied to SAR images to retrieve soil moisture over vegetated areas. The WCM needs vegetation descriptors to account for the impact of vegetation on SAR backscatter. The commonly used vegetation descriptors in WCM, such as Leaf Area Index (LAI) and Normalized Difference Vegetation Index (NDVI), are sometimes difficult to obtain due to the constraints in data availability in in-situ measurements or weather dependency in optical remote sensing. To improve soil moisture retrieval, this study investigates the feasibility of using all-weather SAR derived vegetation descriptors in WCM. The in-situ data observed at an agricultural crop region south of Winnipeg in Canada, RapidEye optical images and dual-polarized Radarsat-2 SAR images acquired in growing season were used for WCM model calibration and test. Vegetation descriptors studied include HV polarization backscattering coefficient ( $\sigma_{HV}^{\circ}$ ) and Radar Vegetation Index (RVI) derived from SAR imagery, and NDVI derived from optical imagery. The results show that  $\sigma_{HV}^{\circ}$  achieved similar results as NDVI but slightly better than RVI, with a root mean square error of  $0.069 \text{ m}^3/\text{m}^3$  and a correlation coefficient of 0.59 between the retrieved and observed soil moisture. The use of  $\sigma_{HV}^{\circ}$  can overcome the constraints of the commonly used vegetation descriptors and reduce additional data requirements (e.g., NDVI from optical sensors) in WCM, thus improving soil moisture retrieval and making WCM feasible for operational use.

**Keywords:** soil moisture; Radarsat-2; SAR; water-cloud model; vegetation descriptor

## 1. Introduction

Soil moisture plays a key role in the terrestrial water cycle. The retrieval of soil moisture over a large area is important in the modeling and assessing drought impact [1], evapotranspiration [2], and water budget [3,4]. With high temporal and spatial variations, soil moisture data over large areas is difficult to obtain from in situ networks. Radar has a high backscattering sensitivity to soil moisture due to the high contrast of the microwave dielectric constant ( $\epsilon$ ) between dry soil ( $\epsilon = 2\sim 3$ ) and water ( $\epsilon = 80$ ) [5]. It also has the advantage of observing the earth's surface day and night in all weather conditions. Therefore, radar remote sensing has the potential to measure soil moisture on a large scale at regular temporal intervals from space [6–10]. Over the past 30 years, considerable effort has been spent on using Synthetic Aperture Radar (SAR) imagery to retrieve soil moisture.

SAR incidence angle and polarization are important factors that affect soil moisture retrieval [5,8,11–14]. Radar backscatters normally decrease with increasing incidence angle [15,16]. The rate of decrease depends mostly on roughness conditions and land cover. Previous studies showed that SAR at low incidence angle is less sensitive to surface roughness [5,11–13,17] and vegetation [18,19] than at high incidence angle. Low incidence angles are thus optimal for soil moisture retrieval. The choice of polarizations also plays an important role in SAR-based soil moisture retrieval.

Single-polarization data is often used for soil moisture retrieval [5,11]. Several studies showed that HH polarization is more sensitive than HV to soil moisture but less sensitive than VV [13,20,21]. However some other studies disagreed. For example, Beaudoin et al. [22], Le Loan [23], and Baghdadi et al. [14] found that HH polarization is most relevant to soil moisture estimates. Moreover, the study by McNarin and Brisco [24] demonstrated that additional polarizations can provide more information content in a SAR dataset. For example, cross-polarized SAR images (HV or VH) are sensitive to crop structure within the total canopy volume and thus provide information that can be complementary to HH and VV imagery. Using multiple polarizations should, in theory, improve soil moisture estimation [25]. Improved soil moisture retrieval using multi-polarization SAR data was reported even under dense vegetation canopy [26,27]. It must be noted that Baghdadi et al. [28] found that the accuracy of the soil moisture estimation did not improve significantly ( $<0.01 \text{ cm}^3/\text{cm}^3$ ) for two bare soil sites when two polarizations (HH and HV) were used instead of only one polarization. There have been great interests to use full-polarized SAR data in soil moisture retrieval after the data is available [1,25,29] as it contains more information on the scattering objects than the single- and dual-polarization data. However, full-polarized SAR data has the disadvantage of narrow swath, which limits its applications in soil moisture retrieval over large areas. As such, dual-polarized SAR data is recommended for retrieving soil moisture over large areas because of its large swath width of up to 500 km (e.g., Radarsat-2 ScanSAR wide beam mode).

For the case without vegetation or with low vegetation cover, shorter wavelength SAR (especially X-band) is more sensitive to soil moisture and least sensitive to surface roughness than longer wavelength SAR [30–32]. For the presence of vegetation (especially dense vegetation), however, longer wavelength L-band, compared with the SAR X-band and C-band, is more suitable for soil moisture retrieval since it has stronger vegetation/soil penetration power and is less sensitive to vegetation canopy [9,33]. Unfortunately, currently, ALOS-2/PALSAR is the only long wavelength L-band SAR sensor currently in orbit. Since its data is limited, especially for regions outside Japan, the ALOS-2/PALSAR is significantly hampered for operational use in soil moisture retrieval. In contrast, Sentinel-1A, Sentinel-1B and Radarsat-2, which are C-band SAR satellites currently in orbit, can provide routine observations of Earth's surface over large areas. Radarsat Constellation Mission (RCM) with 4-days revisit interval will further expand current C-band SAR satellites' revisit capabilities (6-days for Sentinel-1A/B and 24-days for Radarsat-2). These capacities are promoting new scientific and operational perspectives, e.g., downscaling passive microwave soil moisture [34,35], in the retrieval of soil moisture continuously over large areas using C-band SAR imagery.

Soil moisture retrievals from C-band SAR are significantly affected by vegetation cover and surface roughness. A number of SAR backscatter models have been proposed to separate the backscattering contributions of soil and vegetation [6,14,36–39]. These models are generally categorised into three groups: theoretical, empirical, and semi-empirical. The theoretical models such as the Integral Equation Model (IEM) and the advanced IEM model [17,40,41] are complicated and require a large number of parameters. Baghdadi et al. [42–44] modified the IEM to reduce the IEM's input soil parameters from three to two [45]. On the other hand, the empirical models, e.g., Dubois model [46], are simple to develop but may have limitations in applicability for other sites due to their data and site dependency [6,47]. Recently Baghdadi et al. [31] improved the Dubois model for a reliable estimate of soil moisture. The semi-empirical models, e.g., Oh model [15] and Water Cloud Model (WCM) [48], start from a physical background and then use simulated or experimental datasets to simplify the theoretical backscattering models [8]. The WCM is often used in retrieving soil moisture and modelling of the scattering of vegetated areas for its simplicity [27]. In addition, the inversion techniques, including the Neural Network (NN) approach and the Change Detection (CD) method, are also used widely for soil moisture retrieval.

The neural network approach consists of a number of hidden neurons or nodes that work in parallel to convert data from an input vector to an output vector [9,48]. For soil moisture retrieval, the neural network is often trained using a synthetic database generated from SAR backscattering model

such as IEM, Oh, and WCM models [39,49,50] or WCM model combined with the IEM model [39,51]. Based on the NN approach, Santi et al. [52] retrieved soil moisture from ENVISAT/ASAR data with an Root Mean Square Error (RMSE) as low as  $0.023 \text{ m}^3/\text{m}^3$ . Paloscia et al. [39] trained a neural network by using a synthetic database of backscattering coefficients simulated from WCM model combined with IEM model for a wide range of soil moisture, surface roughness, and vegetation index. The inputs to the neural networks were the SAR data and NDVI. The approach doesn't need roughness measurements. They achieved results with RMSE between  $1.67 \text{ m}^3/\text{m}^3$  and  $6.68 \text{ m}^3/\text{m}^3$  over several areas in Italy, Australia, and Spain using Sentinel-1 SAR data, which were very much in line with GMES requirements (with RMSE generally  $<5 \text{ m}^3/\text{m}^3$ ). The change detection method is based on the near linear relationship between SAR backscatter and soil moisture. It assumes the effect of vegetation and surface roughness on observed backscatter are consistent between acquisitions. The advantage of this method is that it can retrieve soil moisture in the absence of prior information of the study area when multi-temporal SAR data is available. Based on this method, Gao et al. [48] retrieved soil moisture over a site in Urgell (Catalunya, Spain) from multi-temporal Sentinel-1/SAR data, which combined with optical Sentinel-2 data, with an RMSE as low as  $0.059 \text{ m}^3/\text{m}^3$ . Zribi et al. [53] achieved a better result with a RMSE of about  $0.035 \text{ m}^3/\text{m}^3$  in retrieving soil moisture over a semi-arid area using ASAR data. The Water Cloud Model (WCM), a simple semi-empirical backscatter model, can relate the backscattering coefficient (HH or VV polarizations) to soil properties (moisture and roughness) and vegetation properties (e.g., biomass, leaf area index) and thus it can be used to retrieve soil moisture from SAR imagery over densely vegetated areas [48]. Based on the WCM, Gherboudj et al. [27] retrieved soil moisture with an RMSE of 5.9% and 6.6% for two sites in crop fields from multi-polarized and multi-angular Radarsat-2 SAR data. Zribi et al. [54] achieved similar result (RMSE:  $\sim 0.06 \text{ m}^3/\text{m}^3$ ) in a semi-arid region from C-band ASAR data using the WCM. Kumar et al. [55] obtained a better soil moisture retrieval with an RMSE as low as  $0.0419 \text{ m}^3/\text{m}^3$  from C-band ASAR data by the use of LAI in the WCM as the vegetation descriptor. The WCM is used in this study for its simplicity.

The performance of the WCM for soil moisture retrieval depends on the characterization of surface roughness and vegetation. Obtaining accurate information about surface roughness is difficult. First, the in-situ measurement of the surface roughness is quite challenging [56]. Second, the SAR-based surface roughness retrievals (e.g., depolarization ratio method) are mainly developed for bare soil and are less efficient in the presence of a vegetation canopy [27]. In this study, the effect of surface roughness is accounted for by using multi-temporal data over the same field, as surface roughness has little change over a short time period especially for crop fields during the growing time period [57].

Various vegetation descriptors such as plant height, leaf area index (LAI), vegetation water content, and normalized difference vegetation index (NDVI) have been used in WCM [14,27,38,55]. These vegetation descriptors are calculated using data either from in-situ measurements or from optical satellite remote sensing. The use of in-situ data is difficult in operational applications because of the high cost and time consuming in data collections, especially in remote areas. The use of optical satellite data is often limited by weather conditions such as cloud and haze.

Recently, some advances have been made toward developing SAR parameters for characterizing vegetation canopies. For example, the radar vegetation index (RVI), which is computed as a ratio of the cross-polarization scattering to the total scattering, has been used to estimate the biomass and the water content of a wheat crop [58]. Kumar et al. [59] showed RVI as a better alternative to NDVI for monitoring soybean and cotton. In other studies, the HV backscattering coefficient ( $\sigma_{HV}^\circ$ ) was found to be very sensitive to the vegetation biomass [60,61] and correlated with LAI [62,63]. Using SAR data to characterize vegetation in the WCM for soil moisture retrieval could be much more effective and beneficial than using in situ and optical sensor-based vegetation descriptors, but few studies are available.

The objective of this study was to assess the WCM performance in soil moisture retrieval by using SAR-derived vegetation descriptors. Specifically, the SAR-derived  $\sigma_{HV}^\circ$  and RVI obtained from dual-polarized Radarsat-2 SAR imagery were tested using a simplified WCM. The NDVI derived from

RapidEye images was also used in the WCM for comparison. The goal of this study is to provide a practical tool for continuous mapping of soil moisture over large areas by future SAR missions such as RCM.

## 2. Methods

A simplified WCM was employed in this study to retrieve soil moisture. Assuming the effect of soil surface roughness on observed backscatter for a given site is consistent over a short period, in such a case, the temporal change in SAR backscattering only reflects the change of vegetation and soil moisture. Therefore the multi-temporal SAR data was used in the WCM for this study. Since the multi-temporal SAR imagery may be in different viewing geometries, an incidence angle normalization was conducted to make the SAR data radiometrically comparable. The RVI was then computed from these normalized SAR images. The accuracy of the retrieved soil moisture was evaluated by root mean square error (RMSE) and the Pearson correlation coefficient ( $R$ ). The detailed WCM description and data processing methods are given below.

### 2.1. A Simplified Water-Cloud Model (WCM)

The water-cloud model, initially developed by Attema and Ulaby [36], considers the vegetation canopy as a cloud containing water droplets randomly distributed within the canopy. It provides solutions for the backscattering coefficients for the vegetation canopy as well as the underlying soil [23,28]. The WCM for a given co-polarization (pp) is formulated as:

$$\sigma_{pp}^{\circ} = \sigma_{veg}^{\circ} + \tau^2 \sigma_{soil}^{\circ}, \quad (1)$$

where

$$\sigma_{veg}^{\circ} = AV_1 \cos \theta_i (1 - \tau^2), \quad (2)$$

$$\tau^2 = e^{-2BV_2 \sec \theta_i}, \quad (3)$$

where  $\sigma_{pp}^{\circ}$  (in power) is the observed canopy backscattering coefficient, which is represented as the sum of vegetation volume scattering  $\sigma_{veg}^{\circ}$  and the bare soil scattering  $\sigma_{soil}^{\circ}$ ,  $\tau^2$  is the two-way transmissivity of the vegetation,  $A$  and  $B$  are the model coefficients, and  $V_1$  and  $V_2$  are the vegetation descriptors. According to Bai and He [42], the WCM can be further simplified by expanding  $\tau^2$  through the Maclaurin series [64]:

$$\tau^2 = e^{-2BV_2 \sec \theta_i} = 1 - \frac{2BV_2}{\cos \theta_i} + \frac{2B^2 V_2^2}{\cos^2 \theta_i} + \dots, \quad (4)$$

Only the first two items are preserved in Equation (4). Combining Equations (1)–(4), the WCM is simplified as:

$$\sigma_{pp}^{\circ} = 2ABV_1^2 + \left(1 - \frac{2BV_2}{\cos \theta_i}\right) \sigma_{soil}^{\circ}, \quad (5)$$

The  $V_1$  and  $V_2$  are often reduced to a single vegetation descriptor  $V$  ( $V = V_1 = V_2$ ) in the WCM. As such, Equation (5) can be further simplified through variable substitution:

$$\sigma_{pp}^{\circ} = aV^2 + bV\sigma_{soil}^{\circ} + \sigma_{soil}^{\circ}, \quad (6)$$

in which  $a = 2AB$  and  $b = -2B/\cos \theta_i$  are the coefficients of the simplified WCM. Comparing to Equation (1), Equation (6) can simplify the computation of the unknown model coefficients [38].

The bare soil scattering  $\sigma_{soil}^{\circ}$  is represented by the function  $f(R, M_s)$  of surface roughness ( $R$ ) and soil moisture ( $M_s$ ). For a field especially an agriculture field during the crop growing time period,  $R$  is considered constant for a short period. In such a case, when multi-temporal SAR data is used over the

same field, the temporal change in bare soil scattering only reflects the change of soil moisture with time for a site, and the  $\sigma_{soil}^\circ$  has a linear relationship with  $M_s$ , which can be expressed as:

$$\sigma_{soil}^\circ(db) = cM_s + d, \quad (7)$$

where  $c$  can be considered as the sensitivity of SAR to soil moisture and  $d$  indicates the backscatter due to surface roughness. The parameters  $a$ ,  $b$ , and  $c$  for a specific vegetation are assumed to be constant for a specific time period and the parameter  $d$  varies with surface roughness. It must be noted that the backscattering coefficients in Equations (6) and (7) are given in *power* and *db* formats, respectively. When submitting Equation (7) to Equation (6), the unit conversion must be conducted to make the units of both equations are the same. As mentioned earlier in the Introduction, the  $V$  is often parameterized by LAI, vegetation water content, or NDVI estimated using in-situ or optical remote sensing data, and it is parameterized using HV backscattering and RVI from Radarsat-2 dual-polarization (HH + HV) imagery in this study.

## 2.2. Incidence Angle Normalization of SAR Imagery

Given a short time period, the amount of repeat pass SAR images may not be sufficient for fitting the WCM due to their low temporal resolutions. As a solution, all available SAR images were used to produce a time series dataset. These images may not be radiometrically comparable because they could be captured at different incidence angles (especially low incidence angles), which have a significant impact on radar backscatters [16]. For example, Oh et al. [15] showed that even as little as a  $5^\circ$  incidence angle can sometimes have  $\sim 3$  db difference in radar backscatters, which may correspond to about 15% soil moisture change when incidence angle was lower than  $35^\circ$ . As such, incidence angle normalization toward a single reference angle is required for the time series SAR images. For this purpose, several studies [65,66] used empirical regression approaches, which assume linear function of SAR backscatter to incidence angles. This kind of approaches is site- and sensor-specific. In this study, we normalized the SAR backscatters to a reference angle based on the theoretical model of Lambert's law:

$$\sigma^\circ(\theta_{ref}) = \frac{\cos^2(\theta_{ref})}{\cos^2(\theta_i)} \sigma^\circ(\theta_i), \quad (8)$$

where  $\sigma^\circ(\theta_i)$  is the incidence angular dependent radar backscatter,  $\theta_i$  and  $\theta_{ref}$  represent the local incidence angle and the reference incidence angle, respectively, and  $\sigma^\circ(\theta_{ref})$  is the normalized radar backscatter to a reference incidence angle  $\theta_{ref}$ . The Lambert's law assumes that the relationship between the incidence angle and amount of scattering per unit surface area follows the cosine law. This behaviour is typical for the middle range of incidence angles [67]. The model is simple but it was found to be reasonably representative for many types of terrains [65,66]. The model has been applied for agriculture land surfaces by many researchers [57,68–72].

## 2.3. Radar Vegetation Index (RVI)

The RVI is normally derived from quad-polarization SAR data using the equation proposed by Kim and Van Zyl [73]:

$$RVI_{quad} = \frac{8\sigma_{HV}^\circ}{\sigma_{HH}^\circ + \sigma_{VV}^\circ + 2\sigma_{HV}^\circ}, \quad (9)$$

where  $\sigma_{HH}^\circ$ ,  $\sigma_{HV}^\circ$ , and  $\sigma_{VV}^\circ$  are backscattering coefficients of HH, HV and VV polarizations, respectively. Since we use dual-polarization (HH + HV) SAR data for soil moisture retrieval, VV polarization data



is not available. Instead, we calculate the RVI from the dual-polarization SAR data for each Radarsat-2 image using the following equation as modified by Charbonneau et al. [74],

$$RVI = \frac{4\sigma_{HV}^{\circ}}{\sigma_{HH}^{\circ} + \sigma_{HV}^{\circ}}. \quad (10)$$

#### 2.4. Normalized Difference Vegetation Index (NDVI)

The NDVI is computed as the ratio of the difference and sum of the reflectance measurements acquired in the near infrared (NIR) and red spectral regions. It can be written as:

$$NDVI = \frac{\rho_{NIR} - \rho_{RED}}{\rho_{NIR} + \rho_{RED}}, \quad (11)$$

where  $\rho_{NIR}$  and  $\rho_{RED}$  are the reflectance at NIR and red spectral wavebands respectively.

#### 2.5. Model Evaluation

The model results for soil moisture are compared to in-situ measurements using the Pearson correlation coefficient ( $R$ ) and the Root Mean Square Error (RMSE) as given below:

$$R = \frac{\sum_{i=1}^n (Mso_i - \overline{Mso})(Msp_i - \overline{Msp})}{\sqrt{\sum_{i=1}^n (Mso_i - \overline{Mso})^2 \sum_{i=1}^n (Msp_i - \overline{Msp})^2}}, \quad (12)$$

$$RMSE = \sqrt{\frac{\sum_{i=1}^n (Msp_i - Mso_i)^2}{n}}, \quad (13)$$

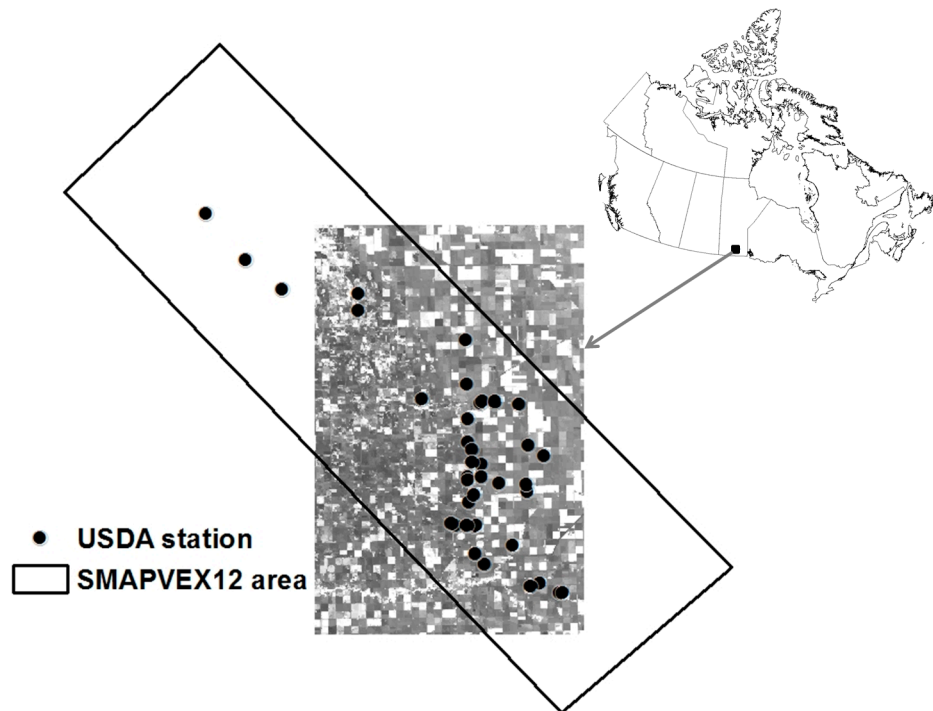
where  $Mso_i$  and  $Msp_i$  are the retrieved and in-situ soil moisture at site  $i$ , respectively.  $\overline{Mso}$  and  $\overline{Msp}$  are their corresponding mean values, and  $n$  is the total number of sample sites. In this study, the wide range of variability for in-situ soil moisture and LAI data and large time span over the growing season provided solid inputs for the model testing, validation and analysis. However, the difficulties and costs associated with field measurements at this scale largely constrained the size of the in situ datasets. To address this limitation, the Leave-One-Out-Cross-Validation (LOOCV) method was used for model evaluation [9]. In this method, one of the data samples was left out of each time for model evaluation and the remaining  $n - 1$  data samples were used to train the model. This resulted in a total of  $n$  models trained using the  $n - 1$  data samples. The results of the model evaluation can be obtained by computing  $R$  and RMSE using all unique sample estimation from each of the  $n$  models. One advantage of the LOOCV method over other traditional validation methods, e.g., splitting the dataset equally into one subset for training and one subset for validation, is that it can effectively reduce the impact of small amount of data samples. The result from this LOOCV evaluation is generally regarded as a more conservative estimate of the model performance than that trained on all samples [75].

### 3. Study Area and Datasets

#### 3.1. Study Area

Our study area was located in the SMAP Validation Experiment 2012 (SMAPVEX12) site [31] (Figure 1). The background image shows the coverage (30 km by 50 km) of our study region. It is an agricultural region (90% are crop fields) located in south of Winnipeg in Manitoba, Canada. The crop types include corn, soybean, canola, wheat, and pasture. The soil texture varies greatly across the study region providing a large range of soil moisture levels. Soil moisture, soil temperature, and other surface characteristics (vegetation, roughness, soil density, etc.) data were collected during a six-week field campaign in 2012 (7 June–17 July). Accompanying the field campaign, remotely sensed satellite and airborne data were acquired at a time close to the in-situ data collections. The remote sensing

data includes SMOS, AMSR-E, Radarsat-2, RapidEye, SPOT-4, DMC International Ltd. (DMCii) and Uninhabited Aerial Vehicle Synthetic Aperture Radar (UAVSAR). The crop map was produced from a supervised classification of imagery acquired by SPOT-4, DMCii, and Radarsat-2. The wealth of data collected during the intensive field campaign provided a good opportunity for developing and testing our soil moisture retrieval models. More detail information about the study region and the datasets can be found in McNarin et al. [76].



**Figure 1.** The location of the study area.

### 3.2. Data and Pre-Processing

Time series of Radarsat-2 (in single look complex (SLC) format) and RapidEye (in L1B format) images acquired during the SMAPVEX12 field campaign were used in this study. RapidEye refers to the constellation of five satellites, which provide daily-revisit high resolution (5 m) images. A RapidEye image has five spectral bands: Blue (440–510 nm), Green (520–590 nm), Red (630–690 nm), Red-Edge (690–730 nm), and Near-Infrared (760–880 nm). All the satellite images were obtained through Canada's National Earth Observation Data Framework (NEODF). There are a total of 12 Radarsat-2 scenes and seven RapidEye scenes of which details are given in Table 1. In addition, a 30 m resolution Shuttle Radar Topography Mission (SRTM) DEM data covering the study area was downloaded from <http://eros.usgs.gov> for orthorectifying the satellite images.

The SLC (single look complex) format data for the time series of Radarsat-2 images was first multi-looked. The digital number (DN) values of HH and HV polarizations were then converted to backscattering coefficients (denoted as  $\sigma^{\circ}_{HH}$  and  $\sigma^{\circ}_{HV}$ , respectively) in power format.  $\sigma^{\circ}_{HH}$  and  $\sigma^{\circ}_{HV}$  were then orthorectified in UTM projection with 20 m resolution by using the SRTM DEM data. While orthorectifying the images, the local incidence angle for each pixel was computed scene by scene. A  $5 \times 5$  enhanced Lee filter was applied to reduce speckle noise. All the processes were completed using the GAMMA Remote Sensing software. Table 1 shows that the incidence angles of the Radarsat-2 images vary from  $20^{\circ}$  to  $37^{\circ}$ . To make these images radiometrically comparable, we used Equation (8) to normalize the backscattering coefficients to a reference incidence angle of  $25^{\circ}$  since low incidence angle ( $<35^{\circ}$ ) is less sensitive to surface roughness [12,13]. The RVI images were then generated from these incidence angle normalized images by using Equation (10).

**Table 1.** The satellite images used in this study.

Acquisition Date (2012)	Flight Direction	Radarsat-2			RapidEye
		Mode	Polarizations	Incidence Angle	Acquisition Date (2012)
5 June	Descending	FQ3W	HH, HV, VH, VV	20.0–23.6°	4 June
6 June	Ascending	S3	HH, HV	30.4–37°	12 June
13 June	Ascending	FQ10W	HH, HV, VH, VV	28.4–31.6°	28 June
19 June	Descending	S3	HH, HV	30.4–37°	5 July
20 June	Ascending	FQ6W	HH, HV, VH, VV	23.7–27.2°	14 July
27 June	Ascending	FQ2W	HH, HV, VH, VV	19.7–22.7°	21 July
29 June	Descending	FQ3W	HH, HV, VH, VV	20.0–23.6°	27 July
30 June	Ascending	S3	HH, HV	30.4–37°	
7 July	Ascending	FQ10W	HH, HV, VH, VV	28.4–31.6°	
14 July	Ascending	FQ6W	HH, HV, VH, VV	23.7–27.2°	
21 July	Ascending	FQ2W	HH, HV, VH, VV	19.7–22.7°	
24 July	Ascending	S3	HH, HV	30.4–37°	

For the time series L1B RapidEye images, a series of preprocessing procedures were conducted using the PCI Geomatica software including the conversion of DN values to Top of Atmosphere (TOA) reflectance, atmospheric corrections for converting TOA reflectance to surface reflectance, and orthorectification. Finally, all the images represented surface reflectance in UTM projection with 20 m resolution. The NDVI images were then generated from these processed images by using Equation (11). Due to the differences of acquisition dates between Radarsat-2 imagery and RapidEye imagery (see Table 1), we used the B-Spline interpolation method to interpolate the NDVI images to generate time series NDVI images corresponding to the acquisition dates of Radarsat-2.

Considering that the in situ soil moisture data collected in the field campaign was only coincident with flight overpasses of the UAVSAR rather than the Radarsat-2, we used soil moisture measurements (0–5 cm) from the U.S. Department of Agriculture’s (USDA) stations, which were installed during the SMAPVEX12 campaign. The USDA datasets provided hourly calibrated soil moisture measurements from 4 June to 18 July 2012. For each station, only soil moisture recorded close (less than 30 min) to the acquisition time of Radarsat-2 imagery was used in this study. The soil surface roughness and LAI data measured during the SMAPVEX12 were also used for analysis. Each measurement of soil surface roughness and LAI represents a crop field where a USDA station was located. For most of the USDA stations, LAI were measured on 12, 13, 19, 20, 27, 29, and 30 June, and 6, 7, 13, and 14 July 2012. Since the dates of LAI measurements were different from the acquisition dates of Radarsat-2 imagery, the LAI measurements were also interpolated to match the acquisition dates of Radarsat-2 imagery using the B-Spline interpolation method, similar to that for NDVI. All the in-situ measurements were downloaded from <https://smapvex12.espaceweb.usherbrooke.ca> and were processed in ArcGIS shapefile format. More details about in-situ measurements can be found in McNairn et al. [75] or the above website.

As mentioned earlier, the effect of surface roughness can be eliminated by using multi-temporal data over the same field. However, soil surface roughness varies with the fields even having the same crop types. To make data as most as possible for analysis, we used the in-situ data with similar roughness in the WCM for each crop type. The soil moisture data were processed as follows. For each crop type, the USDA soil moisture stations with similar surface roughness are grouped. The group with the largest number of stations were selected for this study. For each selected soil moisture station, the time series of soil moisture ( $M_s$ ) and LAI measurements at the acquisition times of Radarsat-2 images, as well as the co-located  $3 \times 3$  pixel averaged Radarsat-2 backscatter coefficients ( $\sigma_{HH}^\circ$  and  $\sigma_{HV}^\circ$ ), RVI and RapidEye NDVI values, were extracted. Using a  $3 \times 3$  pixel averaged value to replace a single pixel value can reduce errors caused by co-registration errors between satellite images and soil moisture measurement sites. It is noted that the study was based on data representing each



specific in-situ measurement site and not the whole crop field. Table 2 lists the statistics of the selected soil moisture and LAI measurements for five crop types: soybean, canola, corn, wheat, and pasture. The root mean square (RMS) roughness values of the selected fields for each crop type are 0.31–0.42 cm (soybean), 1.31–1.33 cm (canola), 1.23–1.28 cm (corn), 1.27–1.29 cm (wheat), and 0.6–0.74 cm (pasture), which are also listed in Table 2.

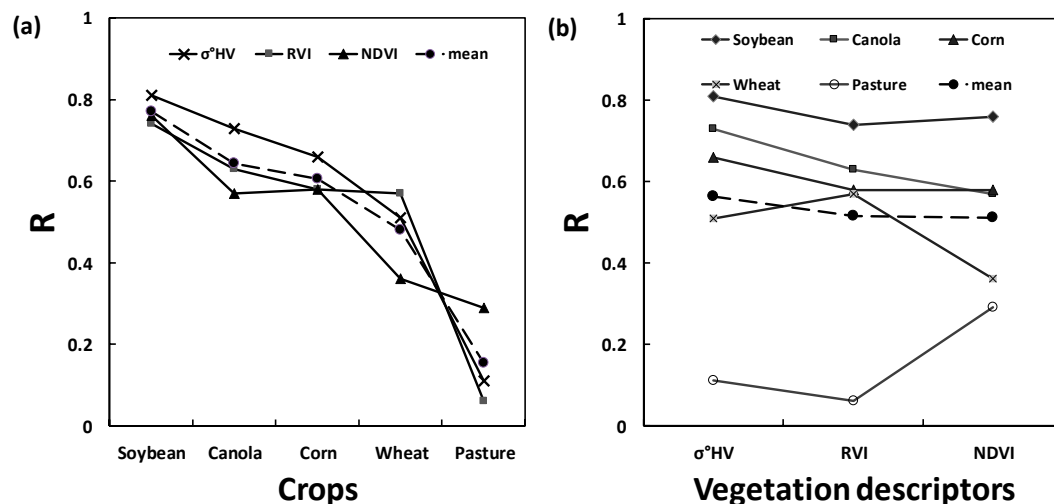
**Table 2.** The in-situ soil moisture (0–5 cm) and Leaf Area Index (LAI) data used in this study.

Crop Types	Soil Moisture (m <sup>3</sup> /m <sup>3</sup> )			LAI (m <sup>2</sup> /m <sup>2</sup> )			RMS * (cm)
	Range	Average	<i>n</i> *	Range	Average	<i>n</i>	
Soybean	0.155–0.467	0.317	26	0.11–2.43	0.92	18	0.31–0.42
Canola	0.042–0.419	0.24	27	0.31–6.33	3.12	18	1.31–1.33
Corn	0.122–0.354	0.211	23	0.09–3.92	1.04	21	1.23–1.28
Wheat	0.123–0.37	0.245	27	0.59–5.15	2.38	20	1.27–1.29
Pasture	0.0398–0.217	0.14	25	1.3–7.19	3.36	18	0.6–0.74

\* *n* is the number of in-situ measurements and RMS is the root mean square roughness.

#### 4. Results and Discussion

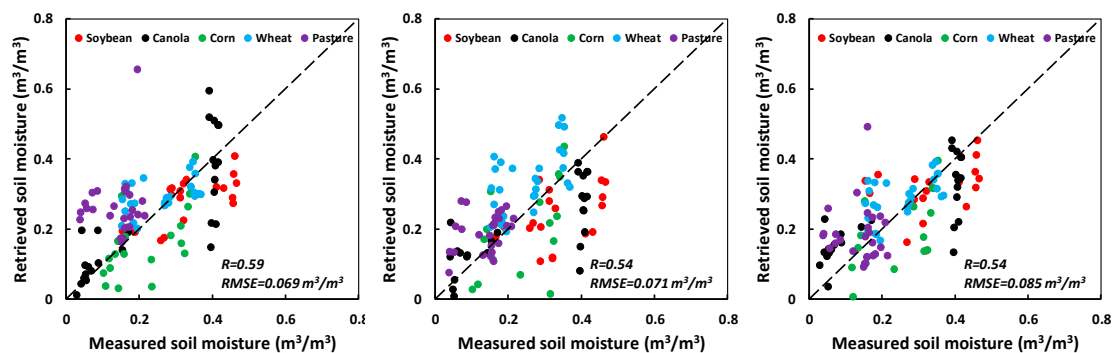
SAR backscatters are generally related to vegetation properties such as shape, height, size, and density, which vary with vegetation types [77]. Different vegetation types may present different behavior in WCM's calibrations [27,78,79]. In this study, therefore, the simplified WCM (Equation (6)) was applied to five different crop types: soybean, canola, pasture, wheat, and corn where  $\sigma_{HH}^{\circ}$  was used as the soil moisture retriever  $\sigma_{pp}^{\circ}$ . The  $\sigma_{HV}^{\circ}$ , RVI, and NDVI were separately used as the vegetation descriptor *V*. The WCM was calibrated for each crop type separately. The LOOCV method was used for the model evaluation. We calculated *R* values between the in-situ and modelled soil moisture for each crop type. Figure 2 show the plots of the *R* values for the five crop types. The results showed that the *R* values vary with crop types and vegetation descriptors.



**Figure 2.** The plots of *R* values of the retrieved and measured soil moisture against (a) crop types and (b) vegetation descriptors.

The soil moisture retrieval for soybean, canola, and corn generally showed higher *R* values than those for wheat and pasture for all the three vegetation descriptors (Figure 2a). Among the five crop types, soybean and pasture have the best and the worst soil moisture retrieval, respectively. These results are confirmed by the mean *R* values of the three vegetation descriptors. The soybean, canola, and corn have mean *R* values ranging from 0.61 to 0.77 while the wheat and pasture have mean *R*

values of 0.48 and 0.15, respectively. Figure 2b shows the mean  $R$  values for  $\sigma^{\circ}_{HV}$ , RVI, and NDVI are 0.57, 0.52, and 0.51. It also demonstrates that  $\sigma^{\circ}_{HV}$  used as the vegetation descriptor in the WCM gave slightly better soil moisture retrieval results than RVI and NDVI. The results are also confirmed by Figure 3, which shows the scatter plots with  $R$  values between the in-situ measured and model retrieved moisture together for all crop types. The  $R$  values for  $\sigma^{\circ}_{HV}$ , RVI, and NDVI are 0.59, 0.54, and 0.54, respectively. The values of RMSE between retrieved and in-situ soil moisture are  $0.069 \text{ m}^3/\text{m}^3$ ,  $0.085 \text{ m}^3/\text{m}^3$ , and  $0.071 \text{ m}^3/\text{m}^3$  for  $\sigma^{\circ}_{HV}$ , RVI, and NDVI, respectively. The results are similar to those in the literature for soil moisture retrieval for other crops from SAR data using the WCM [12,28]. Overall,  $\sigma^{\circ}_{HV}$  as the vegetation descriptor in the WCM shows similar accuracy as NDVI but slightly outperforms RVI for the retrieval of soil moisture. It worth mentioning that the in-situ LAI as the vegetation descriptor in the WCM achieved slightly better results ( $R = 0.8$  and  $\text{RMSE} = 0.067 \text{ m}^3/\text{m}^3$ ) than  $\sigma^{\circ}_{HV}$ . Nevertheless our study showed that the use of  $\sigma^{\circ}_{HV}$  can overcome the constraints of the commonly used vegetation descriptors (e.g., NDVI) in WCM such as data availability and weather dependency, thus improving soil moisture retrieval.

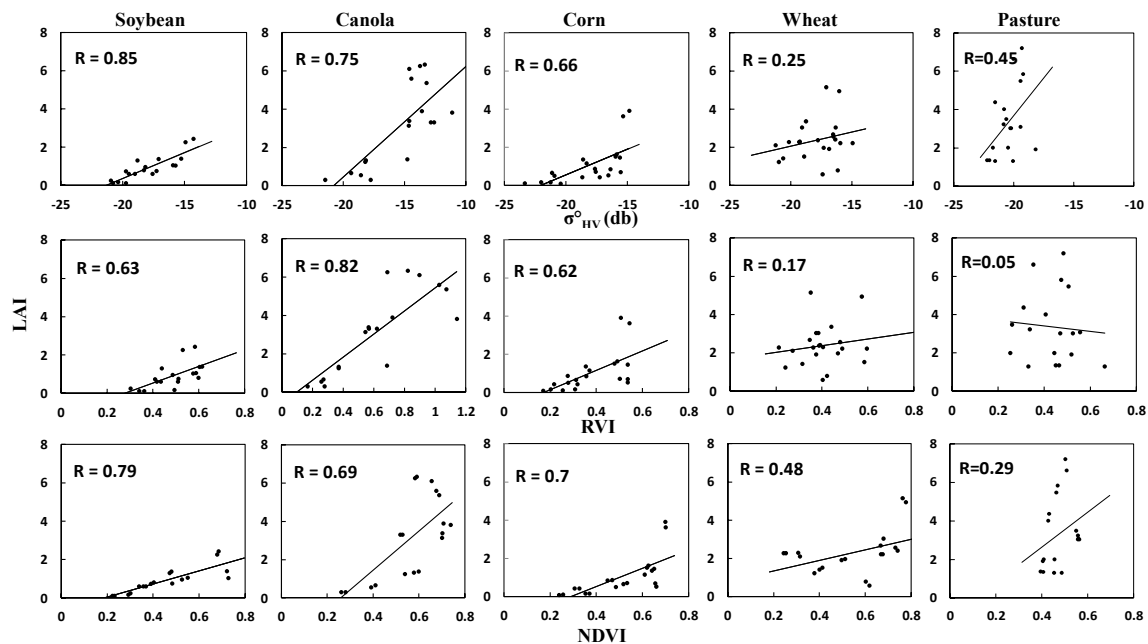


**Figure 3.** Plots of soil moisture measured from U.S. Department of Agriculture’s (USDA) stations and soil moisture retrieved from Radarsat-2 using (a) backscatters of HV polarization  $\sigma^{\circ}_{HV}$ , (b) RVI, and (c) NDVI in the WCM for all crops.

To further understand the results, we examined the relationships between the LAI and the vegetation descriptors for each crop type. Figure 4 shows the scatter plots of the LAI vs. the three vegetation descriptors of  $\sigma^{\circ}_{HV}$ , RVI, and NDVI. The  $R$  values between the LAI and the three vegetation descriptors were given in Figure 5. The results show that soybean, canola, and corn generally have better correlations ( $R$ ) between the LAI and three vegetation descriptors than wheat and pasture. Soybean, canola and corn have mean  $R$  values larger than 0.65 while wheat and pasture have mean  $R$  values around 0.3, which helps to explain the results shown in Figure 2a. The results indicate that the crops that have a stronger correlation between LAI and vegetation descriptors generally demonstrate better soil moisture retrievals when using the WCM.

Figure 4 show that for some crop types, e.g., wheat and pasture, the relationships between vegetation descriptors ( $\sigma^{\circ}_{HV}$ , RVI, and NDVI) are not good. Moreover, for some crop types, vegetation descriptors do not saturate with LAI. More specifically, for soybean, the  $\sigma^{\circ}_{HV}$  has a better sensitivity to LAI than RVI and NDVI. It could result in the more accurate soil moisture retrieval (with  $R = 0.81$ ). Canola shows LAI values ranging from  $0.3 \text{ m}^2/\text{m}^2$  to  $6.3 \text{ m}^2/\text{m}^2$  with a mean value of 3.12 (Table 2). All three vegetation descriptors present a good relationship with LAI, but  $\sigma^{\circ}_{HV}$  and RVI are more sensitive to LAI than NDVI, which is saturated at a LAI of around  $2.0 \text{ m}^2/\text{m}^2$  as shown in Figure 4. This could be the reason why NDVI as the vegetation descriptor in the WCM achieves less accurate soil moisture retrievals ( $R = 0.57$ ) than  $\sigma^{\circ}_{HV}$  and RVI. For corn, the three vegetation descriptors show good linear relationships with LAI when LAI is less than  $2.0 \text{ m}^2/\text{m}^2$ , but they saturate quickly. Their similar relationships with LAI could lead to similar soil moisture estimations (Figure 2b). For wheat, all three vegetation descriptors saturate with LAI and have weak relationships with LAI, with NDVI showing

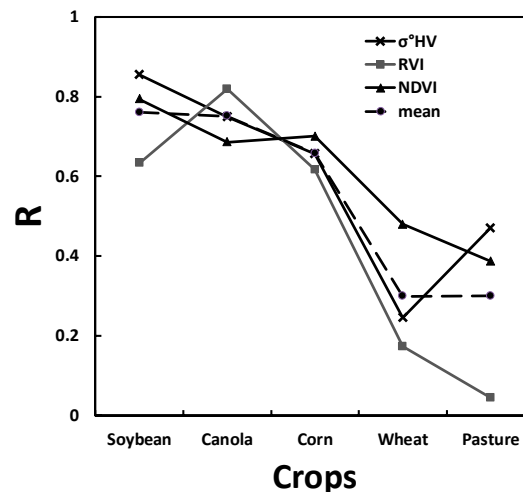
slightly better correlations than  $\sigma^{\circ}_{HV}$  and RVI. Some of the LAI having values between  $3.0 \text{ m}^2/\text{m}^2$  and  $5.0 \text{ m}^2/\text{m}^2$  (Figure 4) indicated some observations were in late growing stage of wheat with dense canopy, as a result, the penetration of SAR is in fact limited when vegetation canopy is dense. The three vegetation descriptors present similar soil moisture estimations (Figure 2b). We also tested LAI as the vegetation descriptor in the WCM. The LAI gives the values of 0.59 and  $0.07 \text{ m}^3/\text{m}^3$  for R and RMSE, separately. It shows that even LAI as the vegetation descriptor cannot significantly improve the result at this growing stage. However the estimation accuracies are still acceptable. The partial reason for the results is that NDVI and LAI are often influenced by vegetation water content [80], in addition, Kim et al. [58] also showed that RVI is highly correlated with vegetation water content in wheat. The vegetation water content could correlate with the soil moisture underneath the canopy. For pasture of which the LAI values ranged from  $2.0 \text{ m}^2/\text{m}^2$  to  $7.0 \text{ m}^2/\text{m}^2$  (Table 1), all three vegetation descriptors were saturated and had weak relationships with LAI ( $R = 0.47$  for  $\sigma^{\circ}_{HV}$ ,  $R = 0.04$  for RVI and  $R = 0.29$  for NDVI). However, NDVI leads to better soil moisture retrieval than  $\sigma^{\circ}_{HV}$  and RVI which needs to be explained by further studies. In general, Figure 4 shows the  $\sigma^{\circ}_{HV}$  became saturated at relatively higher LAI values and is more sensitive to LAI than RVI and NDVI for some crop types. The results are consistent with the studies of Paloscia [62], Simoes et al. [63], and Jiao et al. [81] which showed that  $\sigma^{\circ}_{HV}$  is related to LAI and vegetation biomass.



**Figure 4.** The plots of LAI against three vegetation descriptors:  $\sigma^{\circ}_{HV}$  (top row), RVI (middle row) and NDVI (bottom row) for each crop type.

Although,  $\sigma^{\circ}_{HV}$  is generally more sensitive to vegetation than NDVI and RVI, its backscatter still contains some soil moisture signals, which may introduce errors. However, this study shows, overall,  $\sigma^{\circ}_{HV}$  as the vegetation descriptor presents similar soil moisture estimation accuracy as NDVI and slightly outperforms RVI (Figure 3). Actually Baghdadi et al. showed that cross polarization is more sensitive to vegetation cover than to soil moisture and the soil contribution in cross polarization quickly becomes lower than the vegetation contribution. The sensitivity of cross polarization to soil moisture strongly decreases when both incidence angle and vegetation density increases. Therefore  $\sigma^{\circ}_{HV}$  only introduce errors when the WCM is applied to areas with less vegetation. Moreover, the sensitivity decreases when the soil moisture decreases. For example, the soil contribution becomes negligible for incidence angle higher than  $25^{\circ}$  from an NDVI of 0.27 and 0.39 for soil moisture with  $0.05 \text{ m}^3/\text{m}^3$  and  $0.10 \text{ m}^3/\text{m}^3$ , respectively [16]. The soil contribution in cross polarization to the total

signal is low in the case of well-developed vegetation cover. Moreover, in this study, 25% of in-situ data were collected when LAI was less than 1.0. Majority of the in-situ data has LAI larger than 1.0. The influence of soil contribution to HV backscatter on the soil moisture estimation is low in this study. The study also showed that  $\sigma^{\circ}_{HV}$  ( $R = 0.63$ ) achieved better soil moisture estimations than RVI ( $R = 0.53$ ) and NDVI (0.52) for LAI larger than 2.0 and vice versa for LAI less than 1.0 ( $R = 0.80, 0.86, 0.83$  for  $\sigma^{\circ}_{HV}$ , RVI and NDVI, separately).



**Figure 5.** The plots of  $R$  values between LAI and vegetation descriptors for crop types calculated from Figure 4.

As stated above, NDVI has a saturation point at lower LAI than  $\sigma^{\circ}_{HV}$  for some crop types. The reason could be that NDVI is a measure of vegetation greenness whereas  $\sigma^{\circ}_{HV}$  is a measure of volumetric scattering. In general, vegetation reaches the maximum greenness before it becomes matured volumetrically due to radar's penetration. Normally  $\sigma^{\circ}_{HV}$  and RVI have similar results in vegetation characterization [82]. The dispersion of  $\sigma^{\circ}_{HV}$  and RVI in this study may be related to the effect of crop planting directions. RVI was calculated only from HH and HV polarization in this study. A previous study [83] reported that the planting row orientations in a sugarcane field had an influence on the HH polarization but not on the HV polarization. In addition, it can be also noticed from Figure 3 that the retrieved soil moisture is overestimated for relatively dry sites ( $M_s < 0.25 \text{ m}^3 \text{ m}^{-3}$ ) and underestimated for wet sites ( $M_s > 0.25 \text{ m}^3 \text{ m}^{-3}$ ) due to the difference of penetration of SAR in dry and wet soils. In addition, the data we used in this study is from the SMAPVEX12, which is a six-week field campaign in 2012 (7 June–17 July). The database for some crop types may cover a limited period. It could be useful to test WCM for a vegetation growth cycle in future study.

Ideally, the Radarsat-2 data should be in the same viewing geometry. Since Radarsat-2 has a revisit time of 24 days, it is difficult to obtain enough repeat pass images within a short period for the analysis. Instead, we used all available Radarsat-2 data, which are in different modes and possess different incidence angles. To reduce the effect of SAR incidence angle, we normalized all Radarsat-2 images to a reference angle theoretical model of Lambert's law. However, it should be noted that the theoretical approach may not be the most appropriate one and could introduce errors [40]. The assessments of errors and different approaches are beyond the scope of this paper. Therefore, although an incidence angle normalization process was applied to these images to minimize the effect of different viewing geometries on SAR backscatters, the residual errors may still exist. The SAR imagery limitations can be improved after the RCM data become available. The RCM has a 4-day revisit time, which makes it possible to acquire sufficient repeat pass SAR images in a short period.

## 5. Conclusions

This study investigated the capability of using SAR-derived vegetation descriptors in a WCM for improving soil moisture retrieval over a vegetated area. Two vegetation descriptors,  $\sigma^{\circ}_{HV}$  and RVI, derived from Radarsat-2/SAR were studied. The results were compared to those obtained from using NDVI. The use of  $\sigma^{\circ}_{HV}$  in WCM achieved similar soil moisture retrieval as the use of NDVI but slightly better than the use of RVI. The RMSE between retrieved and observed soil moisture were  $0.069 \text{ m}^3/\text{m}^3$ ,  $0.085 \text{ m}^3/\text{m}^3$  and  $0.071 \text{ m}^3/\text{m}^3$  for  $\sigma^{\circ}_{HV}$ , RVI and NDVI, respectively. The corresponding  $R$  were 0.59, 0.54, and 0.54, respectively. The results can be explained from the relationships of the vegetation descriptors with LAI, which shows  $\sigma^{\circ}_{HV}$  saturates at relatively higher LAI values for some crop types and is generally more sensitive to vegetation than RVI and NDVI. Soil contribution in HV polarization brings an effect on the soil moisture estimation over areas with less vegetation but the effect is limit in this study. The small difference of RVI and  $\sigma^{\circ}_{HV}$  (or NDVI) in soil moisture retrieval indicates that RVI is also a relevant vegetation descriptor in the WCM. Moreover, the use of  $\sigma^{\circ}_{HV}$  or RVI in the WCM overcomes the dependency of WCM on in-situ or optical remote sensing data for deriving vegetation descriptors and further reduces additional data requirements for WCM, thus improves soil moisture retrieval. The study also indicates that the use of dual-polarized SAR images presents a practical way to retrieve soil moisture over a large area since the dual-polarized images can have a large swath width of up to 500 km (e.g., Radarsat-2 ScanSAR wide mode). The RCM will further enhance the capability with its rapid revisit and compact polarimetric (CP) configuration. The RCM CP is considered as a possible alternative of quad-polarized (QP) system but with wider image swath. Therefore the use of CP data in WCM could achieve a better soil moisture retrieval over a large area even under dense vegetation canopy.

**Author Contributions:** J.L. performed the experiment, analyzed the data, validated the results and wrote the manuscript. S.W. provided crucial guidance and support during the research, and revised the manuscript.

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