Fagus_sylvatica_8F

Processing Report

07 November 2018

Survey Data

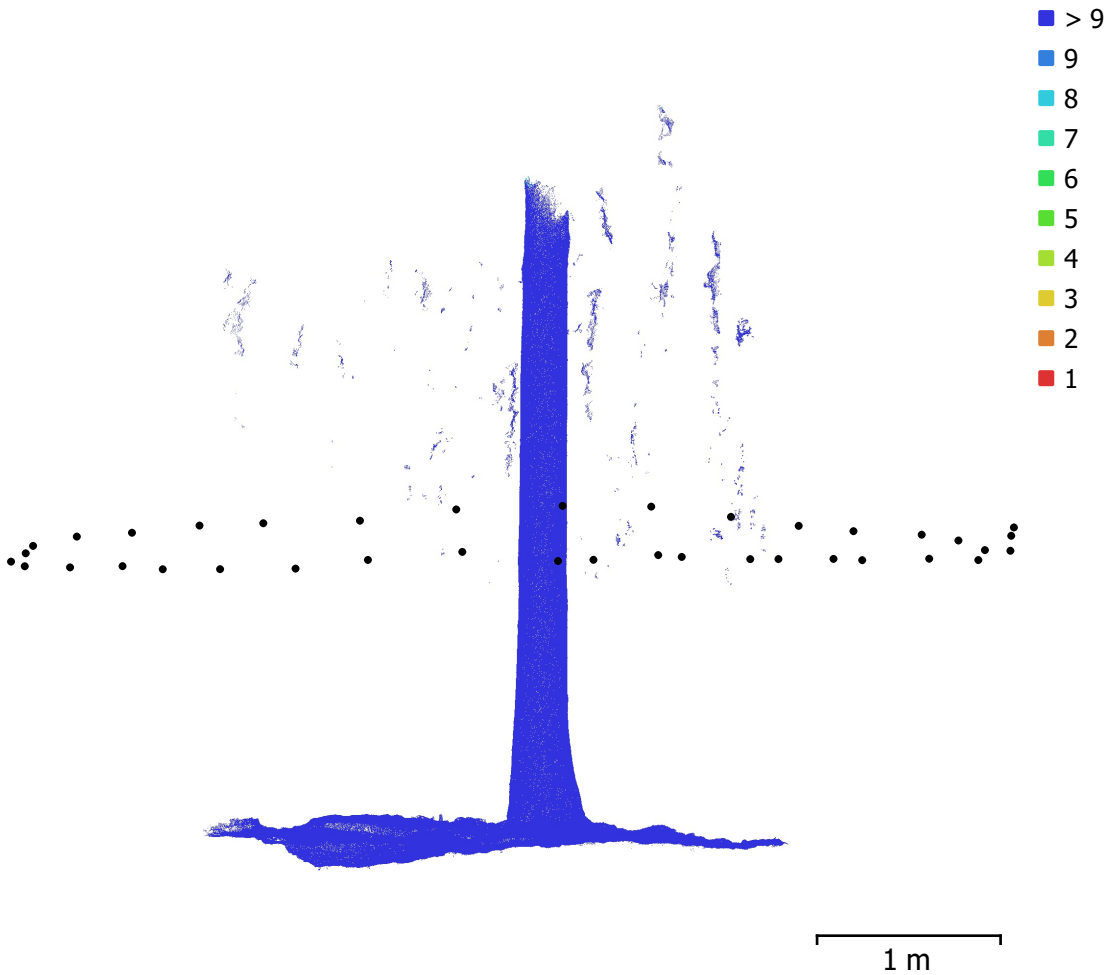

Fig. 1. Camera locations and image overlap.

Number of images:	38	Camera stations:	38
Flying altitude:	2.97 m	Tie points:	35,255
Ground resolution:	0.67 mm/pix	Projections:	81,325
Coverage area:	1.41 m²	Reprojection error:	0.46 pix

Camera Model	Resolution	Focal Length	Pixel Size	Precalibrated
Canon EOS 70D (15 mm)	5472 x 3648	15 mm	4.17 x 4.17 µm	No

Table 1. Cameras.

Camera Calibration

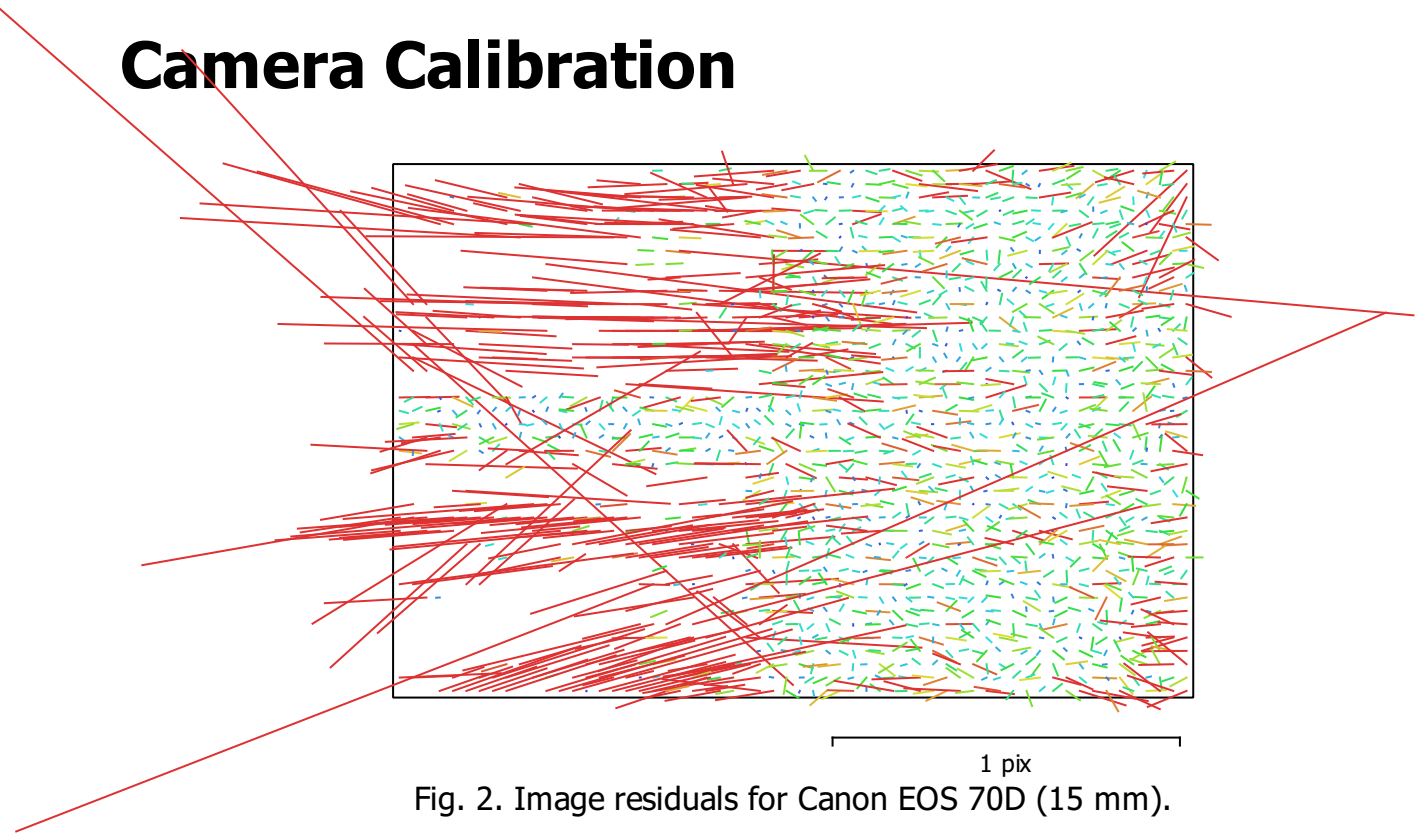

Fig. 2. Image residuals for Canon EOS 70D (15 mm).

Canon EOS 70D (15 mm)

38 images

Type	Resolution	Focal Length	Pixel Size
Fisheye	**5472 x 3648**	**15 mm**	**4.17 x 4.17 µm**

	Value	Error	F	K1	P1	P2
F	**3747.79**	0.21	1.00	-0.35	-0.19	-0.01
K1	**-0.034929**	6.9e-05		1.00	-0.25	0.01
P1	**0.000899673**	2.4e-05			1.00	0.07
P2	**-9.92376e-05**	1.1e-05				1.00

Table 2. Calibration coefficients and correlation matrix.

Ground Control Points

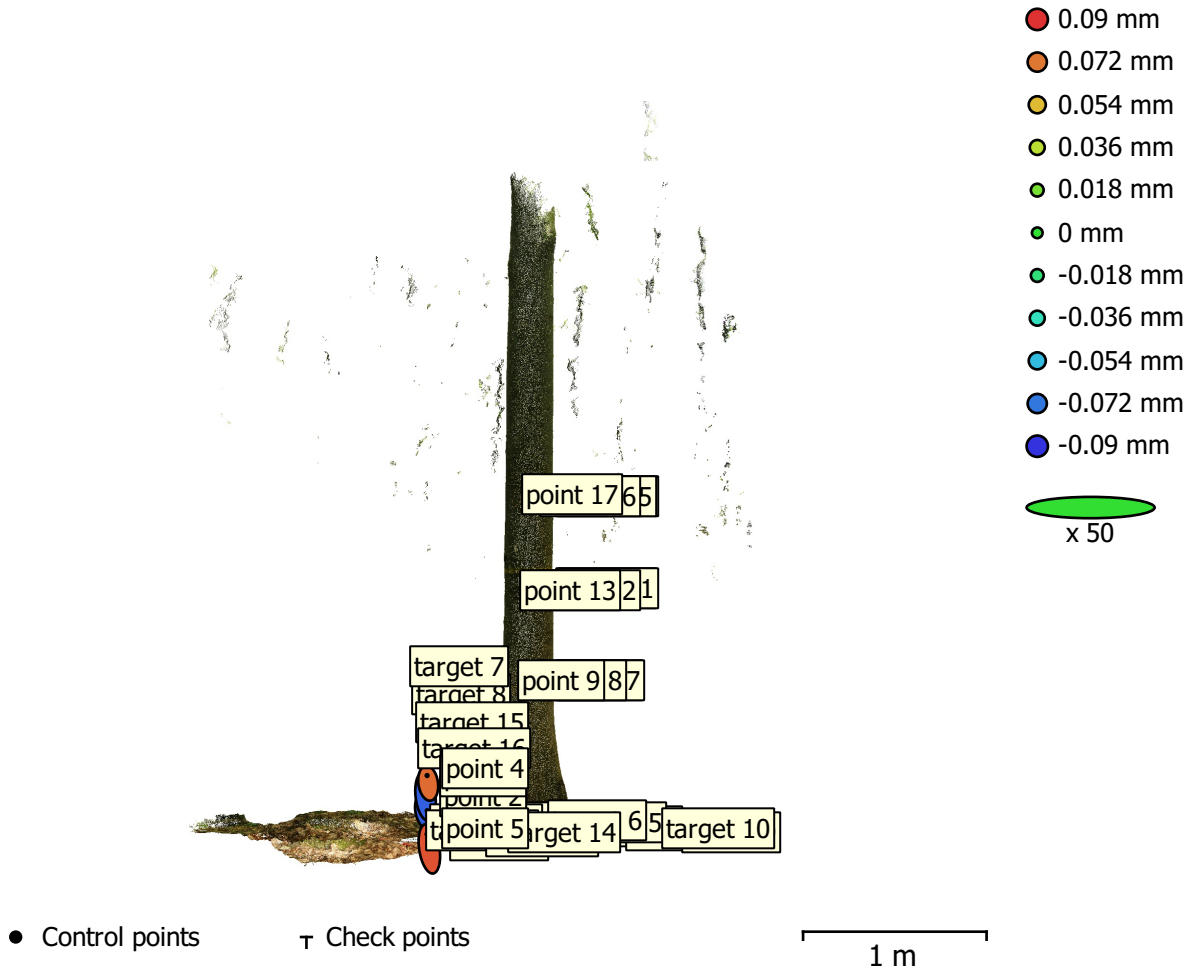

Fig. 3. GCP locations and error estimates.
Z error is represented by ellipse color. X,Y errors are represented by ellipse shape.
Estimated GCP locations are marked with a dot or crossing.

Count	X error (mm)	Y error (mm)	Z error (mm)	XY error (mm)	Total (mm)
4	0.379645	2.54093	0.0784396	2.56914	2.57034

Table 3. Control points RMSE.

Label	X error (mm)	Y error (mm)	Z error (mm)	Total (mm)	Image (pix)
point 2	0.369542	-1.76109	-0.0789117	1.80117	0.004 (38)
point 3	0.367191	-3.1142	-0.0778962	3.13674	0.004 (38)
point 4	-0.238478	1.68217	0.0750956	1.70065	0.004 (38)
point 5	-0.498255	3.19312	0.0817122	3.23279	0.004 (38)
Total	**0.379645**	**2.54093**	**0.0784396**	**2.57034**	**0.004**

Table 4. Control points.

Label	X error (mm)	Y error (mm)	Z error (mm)	Total (mm)	Image (pix)
target 1					0.636 (21)
target 2					0.463 (13)
target 3					0.549 (15)
target 4					0.482 (10)
target 5					0.533 (24)
target 6					0.624 (28)
target 8					1.585 (15)
target 9					0.822 (16)
target 10					0.532 (19)
target 11					0.243 (8)
target 12					0.553 (10)
target 13					0.365 (19)
target 14					0.369 (29)
target 15					0.968 (8)
target 16					1.265 (6)
target 7					0.004 (38)
point 6					0.004 (38)
point 7					0.004 (38)
point 8					0.004 (38)
point 9					0.004 (38)
point 10					0.004 (38)
point 11					0.004 (38)
point 12					0.004 (38)

Label	X error (mm)	Y error (mm)	Z error (mm)	Total (mm)	Image (pix)
point 13					0.004 (38)
point 14					0.004 (38)
point 15					0.004 (38)
point 16					0.004 (38)
point 17					0.004 (38)
Total					

Table 5. Check points.

Scale Bars

Label	Distance (m)	Error (m)
target 5_target 6	0.147883	-0.000116616
target 8_target 7	0.149016	0.00101642
target 9_target 10	0.147551	-0.000449195
target 11_target 12	0.14788	-0.000120024
target 13_target 14	0.147925	-7.51602e-05
target 15_target 16	0.147725	-0.00027523
Total		**0.000473337**

Table 6. Control scale bars.

Label	Distance (m)	Error (m)
point 2_point 5	0.0791823	
point 3_point 5	0.12775	
point 4_point 5	0.3194	
Total		

Table 7. Check scale bars.

Digital Elevation Model

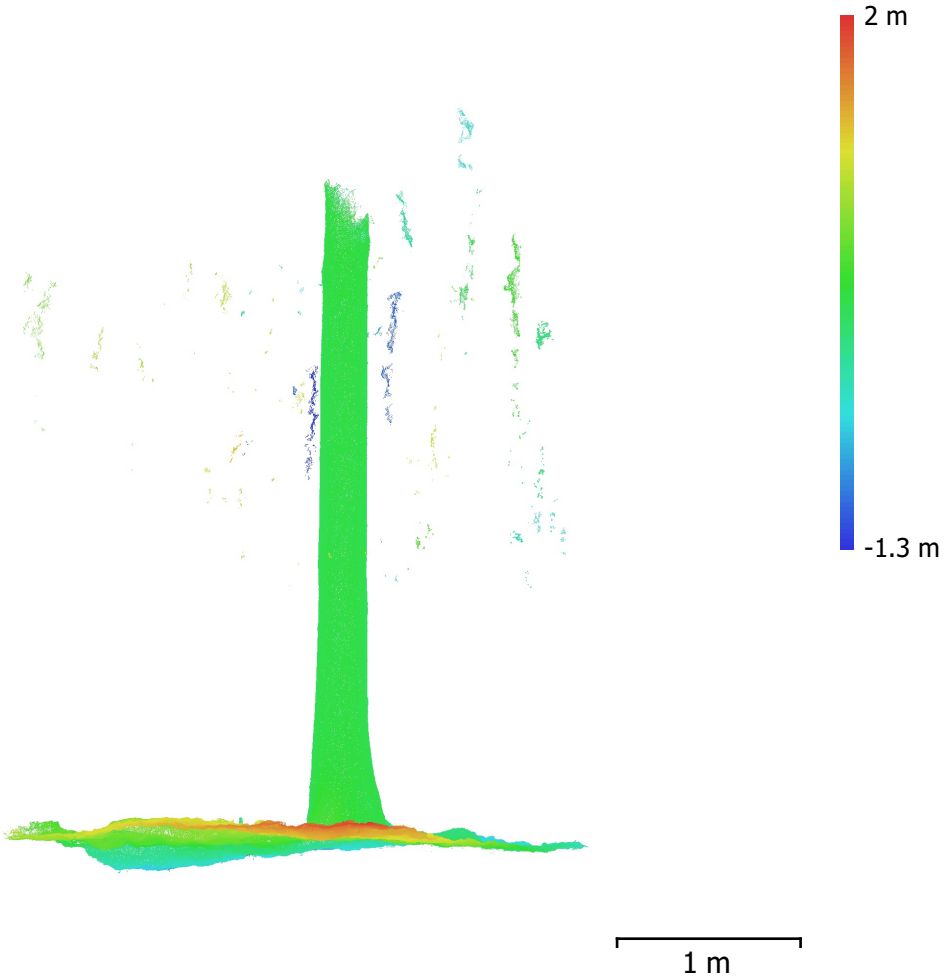

Fig. 4. Reconstructed digital elevation model.

Resolution:	unknown
Point density:	unknown

Processing Parameters

General	
Cameras	38
Aligned cameras	38
Markers	32
Scale bars	9
Coordinate system	Local Coordinates (m)
Rotation angles	Yaw, Pitch, Roll
Point Cloud	
Points	35,255 of 37,232
RMS reprojection error	0.0850793 (0.460276 pix)
Max reprojection error	0.257189 (15.1515 pix)
Mean key point size	4.41748 pix
Point colors	3 bands, uint8
Key points	No
Average tie point multiplicity	2.3606
Alignment parameters	
Accuracy	High
Generic preselection	Yes
Key point limit	40,000
Tie point limit	4,000
Adaptive camera model fitting	Yes
Matching time	4 minutes 33 seconds
Alignment time	14 seconds
Depth Maps	
Count	38
Reconstruction parameters	
Quality	Medium
Filtering mode	Aggressive
Processing time	41 minutes 58 seconds
Dense Point Cloud	
Points	1,731,200
Point colors	3 bands, uint8
Reconstruction parameters	
Quality	Medium
Depth filtering	Aggressive
Depth maps generation time	41 minutes 58 seconds
Dense cloud generation time	13 minutes 56 seconds
Software	
Version	1.4.4 build 6848
Platform	Windows 64