



Article

# Smooth Information Criterion for Regularized Estimation of Item Response Models

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Abstract: Item response theory (IRT) models are frequently used to analyze multivariate categorical data from questionnaires or cognitive test data. In order to reduce the model complexity in item response models, regularized estimation is now widely applied, adding a nondifferentiable penalty function like the LASSO or the SCAD penalty to the log-likelihood function in the optimization function. In most applications, regularized estimation repeatedly estimates the IRT model on a grid of regularization parameters  $\lambda$ . The final model is selected for the parameter that minimizes the Akaike or Bayesian information criterion (AIC or BIC). In recent work, it has been proposed to directly minimize a smooth approximation of the AIC or the BIC for regularized estimation. This approach circumvents the repeated estimation of the IRT model. To this end, the computation time is substantially reduced. The adequacy of the new approach is demonstrated by three simulation studies focusing on regularized estimation for IRT models with differential item functioning, multidimensional IRT models with cross-loadings, and the mixed Rasch/two-parameter logistic IRT model. It was found from the simulation studies that the computationally less demanding direct optimization based on the smooth variants of AIC and BIC had comparable or improved performance compared to the ordinarily employed repeated regularized estimation based on AIC or BIC.

**Keywords:** regularized estimation; item response models; smooth information criterion; differential item functioning; multidimensional item response model; Rasch model; SCAD penalty



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## 1. Introduction

Item response theory (IRT; [1–5]) modeling is a class of statistical models that analyze discrete multivariate data. In these models, a vector  $\mathbf{X} = (X_1, \dots, X_I)$  of I discrete variables  $X_i$  ( $i = 1, \dots, I$ ; also referred to as items) is summarized by a unidimensional or multidimensional factor variable  $\theta$ . In this article, we confine ourselves to dichotomous random variables  $X_i \in \{0,1\}$ .

The multivariate distribution for the vector  $X \in \{0,1\}^{I}$  in the IRT model is defined as

$$P(X = x; \gamma) = \int \prod_{i=1}^{I} P(X_i = x_i | \theta; \gamma_i) f(\theta; \beta) d\theta , \qquad (1)$$

where  $\mathbf{\gamma} = (\gamma_1, \dots, \gamma_I, \boldsymbol{\beta})$  is the vector of model parameters. The vector  $\mathbf{\gamma}_i$  contains item parameters of item i, while  $\boldsymbol{\beta}$  parametrizes the density f of the factor variable  $\boldsymbol{\theta}$ . Note that (1) includes a local independence assumption. That is, the items  $X_i$  are conditionally independent given the factor variable  $\boldsymbol{\theta}$ . The function  $\boldsymbol{\theta} \mapsto P(X_i = x_i | \boldsymbol{\theta}; \boldsymbol{\gamma}_i)$  is also referred to as the item response function (IRF; [6–8]). The two-parameter logistic (2PL) model [9] uses the IRF  $\boldsymbol{\theta} \mapsto \Psi(a_i \boldsymbol{\theta} - b_i)$ , where  $\Psi$  denotes the logistic distribution function.

Algorithms **2024**, 17, 153 2 of 17

Now, assume that N independent replications of X are available. The parameter vector  $\gamma$  from these observations  $x_1, \ldots, x_N$  can be estimated by minimizing the negative log-likelihood function

$$l(\mathbf{\gamma}) = -\sum_{n=1}^{N} \log P(X = \mathbf{x}_n; \mathbf{\gamma}), \qquad (2)$$

where the parameter vector  $\mathbf{\gamma} = (\gamma_1, \dots, \gamma_H)$  contains H components that have to be estimated.

In various applications, the IRT model (1) is not identified or includes too many parameters, making the interpretation difficult. To this end, some sparsity structure [10] on model parameters  $\gamma$  is imposed. Regularized estimation as a machine learning technique is employed in IRT models to make estimation feasible [11–13]. More formally, sparsity structure on  $\gamma$  is imposed by replacing the negative log-likelihood function with a negative regularized log-likelihood function

$$l_{\text{reg}}(\gamma;\lambda) = l(\gamma) + N \sum_{h=1}^{H} \iota_h \mathcal{P}(\gamma_h, \lambda) , \qquad (3)$$

where  $\iota_h$  is an indicator variable for the parameter  $\gamma_h$  that takes values 0 or 1. The indicator  $\iota_h$  equals 1 if  $\gamma_h$  is regularized (i.e., the sparsity structure assumption applies to this parameter), while it is 0 if  $\gamma_h$  should not be regularized. Let  $H_1 = \sum_{h=1}^H \iota_h$  be the number of regularized parameters and  $H_0 = H - H_1$  is the number of nonregularized model parameters. The regularized negative log-likelihood function  $l_{\text{reg}}$  defined in (3) includes a penalty function  $\mathcal P$  that decodes the assumptions about sparsity. For a scalar parameter x, the least absolute shrinkage and selection operator (LASSO; [14]) penalty is a popular penalty function used in regularization, and it is defined as

$$\mathcal{P}_{\text{LASSO}}(x,\lambda) = \lambda |x| \,, \tag{4}$$

where  $\lambda$  is a nonnegative regularization parameter that controls the extent of sparsity in the obtained parameter estimate. It is well-known that the LASSO penalty introduces bias in estimated parameters. To circumvent this issue, the smoothly clipped absolute deviation (SCAD; [15]) penalty has been proposed.

$$\mathcal{P}_{\text{SCAD}}(x,\lambda) = \begin{cases} \lambda |x| & \text{if } |x| < \lambda \\ -(x^2 - 2a\lambda|x|^2 + \lambda^2)(2(a-1))^{-1} & \text{if } \lambda \le |x| \le a\lambda \\ (a+1)\lambda^2 & \text{if } |x| > a\lambda \end{cases}$$
(5)

In many studies, the recommended value of a=3.7 (see [15]) has been adopted (e.g., [10,16]). Note that  $\mathcal{P}_{SCAD}$  has the property of the LASSO penalty around zero, but has zero derivatives for x values that strongly differ from zero.

A parameter estimate  $\hat{\gamma}$  of the regularized IRT model is defined as an estimator defined as the minimizer of  $l_{\rm reg}$ 

$$\widehat{\mathbf{\gamma}}(\lambda) = \underset{\mathbf{\gamma}}{\operatorname{arg\,min}} \ l_{\operatorname{reg}}(\mathbf{\gamma}; \lambda) \ .$$
 (6)

Note that the penalty function  $\mathcal{P}$  involves a fixed tuning parameter  $\lambda$ . Hence, the parameter estimate  $\widehat{\gamma}(\lambda)$  depends on  $\lambda$ . A crucial issue of the LASSO and the SCAD penalty functions is that they are nondifferentiable functions because the function  $x\mapsto |x|$  is nondifferentiable. Hence, particular estimation techniques for nondifferentiable optimization problems must be applied [14,17,18]. As an alternative, the nondifferentiable optimization function can be replaced by a differentiable approximation [19–22]. For example, the absolute value function  $x\mapsto |x|$  in the SCAD penalty can be replaced with  $x\mapsto \sqrt{x^2+\varepsilon}$  for a sufficiently small  $\varepsilon$  such as  $\varepsilon=0.001$ . Using differentiable approximations has the advantage that ordinary gradient-based optimizers can be utilized.

Algorithms **2024**, 17, 153 3 of 17

In practice, the estimation of the regularized IRT model is carried out on a grid of T values of  $\lambda$  in a grid  $\Lambda = \{\lambda_1, \ldots, \lambda_T\}$ . For each value of the tuning parameter  $\lambda_t$ , a parameter estimate  $\widehat{\gamma}(\lambda_t)$  is obtained. A final parameter estimate  $\widehat{\gamma}$  is obtained by minimizing an information criterion

$$IC(\widehat{\gamma}(\lambda)) = 2l(\widehat{\gamma}(\lambda)) + K_N \left( H_0 + \sum_{h=1}^H \iota_h \mathbf{1}(\widehat{\gamma}_h(\lambda) \neq 0) \right), \tag{7}$$

where the factor  $K_N$  is chosen as  $K_N = 2$  for the Akaike information criterion (AIC; [23]) and  $K_N = \log N$  for the Bayesian information criterion (BIC; [24]) (see [25]).

If the regularized likelihood function is evaluated with differentiable approximations, there are no regularized parameters that exactly equal zero (in contrast to special-purpose optimizers for regularized estimation; [17]). Hence, estimated parameters  $\gamma_h$  are counted as zero if they do not exceed a fixed threshold  $\tau$  (such as 0.001, 0.01, or 0.02) in its absolute value. Hence, the approximated information criterion is computed as

$$IC(\widehat{\gamma}(\lambda)) = 2l(\widehat{\gamma}(\lambda)) + K_N \left( H_0 + \sum_{h=1}^H \iota_h \mathbf{1}(|\widehat{\gamma}_h(\lambda)| > \tau) \right). \tag{8}$$

The final estimator of  $\gamma$  is defined as

$$\widehat{\gamma}_{IC} = \widehat{\gamma}(\widehat{\lambda}_{opt}) \text{ with } \widehat{\lambda}_{opt} = \underset{\lambda \in \Lambda}{\text{arg min }} IC(\widehat{\gamma}(\lambda)). \tag{9}$$

Depending on the chosen value of  $K_N$ , the regularized parameter estimate can be based on the AIC and BIC.

The ordinary estimation approach to regularized estimation described above has the computational disadvantage that it requires a sequential fitting of models on the grid  $\Lambda$ of the regularization parameter  $\lambda$ . This approach is referred to as an indirect optimization approach because it first minimizes a criterion function (i.e., the regularized likelihood function) with respect to  $\gamma$  for a fixed value of  $\lambda$  and optimizes a second criterion (i.e., the AIC or BIC) in the second step. O'Neill and Burke [26] proposed an estimation approach to regularized estimation that directly minimizes a smooth version of the BIC (i.e., smooth Bayesian information criterion, SBIC) for regression models. This direct estimation approach has been successfully implemented for structural equation models [21,27]. For these models, the optimization based on SBIC had similar, if not better, performance than the ordinary estimation of regularized models based on the AIC and BIC. In this paper, we explore whether the smooth information criteria SBIC and the smooth Akaike information criterion (SAIC) also hold promise for various applications in IRT models. Using a computationally cheaper alternative for regularized estimation is probably even more important for IRT models than for structural equation models because IRT models are more difficult to estimate and more computationally demanding. To the best of our knowledge, this is the first attempt at using smoothed information criteria in IRT models.

The rest of this paper is structured as follows. The optimization using smooth information criteria is outlined in Section 2. Afterward, three applications of regularized IRT models are investigated in three simulation studies. Section 3 presents Simulation Study 1, which studies regularized estimation for differential item functioning. Section 4 presents Simulation Study 2, which investigates the regularized estimation of multidimensional IRT models. The last Simulation Study 3 in Section 5 is devoted to regularized estimation of the mixed Rasch/2PL model. Finally, this study closes with a discussion in Section 6.

Algorithms **2024**, 17, 153 4 of 17

#### 2. Smooth Information Criterion

In theory, a parameter estimate  $\hat{\gamma}$  for  $\gamma$  of the IRT model may be obtained by directly minimizing an information criterion

$$\widehat{\mathbf{\gamma}} = \underset{\mathbf{\gamma}}{\operatorname{arg\,min}} \left\{ 2l(\mathbf{\gamma}) + K_N \left( H_0 + \sum_{h=1}^H \iota_h \mathbf{1}(\mathbf{\gamma}_h \neq 0) \right) \right\}. \tag{10}$$

The optimization function in (10) can be interpreted as a regularized log-likelihood function with an  $L_0$  penalty [28,29]. Obviously, the indicator function 1 in (10) counts the number of regularized parameters that differ from zero. Researchers O'Neill and Burke [26] proposed substituting the indicator function with a suitable differentiable approximation  $\mathcal{N}_{\varepsilon}$ . To this end, a smooth information criterion, such as the SAIC and the SBIC, is obtained. In more detail, the differentiable approximation  $\mathcal{N}_{\varepsilon}$  for 1 is defined as

$$\mathcal{N}_{\varepsilon}(x) = \frac{x^2}{x^2 + \varepsilon} \,, \tag{11}$$

where  $\varepsilon > 0$  is a sufficiently small tuning parameter, such as  $\varepsilon = 0.001$ . The function  $\mathcal{N}_{\varepsilon}$  takes values close to zero for x arguments close to 0 and approaches 1 if |x| moves away from 0. A smoothed information criterion  $SIC(\gamma)$  (abbreviated as SIC) can be defined as

$$SIC(\gamma) = 2l(\gamma) + K_N \left( H_0 + \sum_{h=1}^{H} \iota_h \mathcal{N}_{\varepsilon}(\gamma_h) \right).$$
 (12)

We obtain the SAIC for the choices of  $K_N$  in (12) of  $K_N = 2$  and the SBIC for  $K_N = \log(N)$ . Hence, the minimization problem (10) can be replaced by

$$\widehat{\mathbf{\gamma}} = \arg\min_{\mathbf{\gamma}} SIC(\mathbf{\gamma}) = \arg\min_{\mathbf{\gamma}} \left\{ 2l(\mathbf{\gamma}) + K_N \left( H_0 + \sum_{h=1}^H \iota_h \mathcal{N}_{\varepsilon}(\mathbf{\gamma}_h) \right) \right\}. \tag{13}$$

The optimization function in (13) directly minimizes a smoothed version of the information criterion.

#### 3. Simulation Study 1: Differential Item Functioning

In the first Simulation Study 1, the assessment of differential item functioning (DIF; [30–32]) is considered as an example. DIF occurs in datasets with multiple groups if item parameters are not invariant (i.e., they are not equal) across groups. In this study, the case of two groups in the unidimensional 2PL model is treated. The IRF is given by

$$P(X_i = 1 | G = g, \theta) = \Psi(a_i \theta - b_i - \delta_i \mathbf{1}(G = 2)) \text{ for } g = 1, 2, \tag{14}$$

where  $\delta_i$  indicates the DIF in item intercepts, which is also referred to as uniform DIF. The item parameters of item  $X_i$  are given by  $\gamma_i = (a_i, b_i, \delta_i)$ . The mean and the standard deviation of  $\theta$  in the first group are fixed for identification reasons to 0 and 1, respectively. Then, the mean  $\mu_2$  and the standard deviation  $\sigma_2$  of  $\theta$  in the second group can be estimated.

It has been pointed out that additional assumptions about DIF effects  $\delta_i$  must be imposed for model identification [33–35]. Assuming a sparsity structure on the DIF effects may be one plausible option. To this end, DIF effects  $\delta_i$  ( $i=1,\ldots,l$ ) are regularized in the optimization based on the regularized log-likelihood function (3) or the minimization of the SIC (13). Regularized estimation of DIF in IRT models has been widely discussed in the literature [36–42].

## 3.1. Method

In this simulation study, we use a data-generating model (DGM) similar to the one used in the simulation study in [38]. The factor variable  $\theta$  was assumed to be univariate

Algorithms **2024**, 17, 153 5 of 17

normally distributed. We fixed the mean  $\mu_1$  and the standard deviation  $\sigma_1$  of the factor variable  $\theta$  in the first group to 0 and 1, respectively. The factor variable  $\theta$  had a mean  $\mu_2$  of 0.5 and a standard deviation  $\sigma_2$  of 0.8 in the second group. In total, I=25 items were used in this simulation study.

We now describe the item parameters used for the IRF defined in (14). The common item discriminations  $a_i$  of the 25 items were chosen as 1.3, 1.4, 1.5, 1.7, 1.6, 1.3, 1.4, 1.5, 1.7, 1.6, 1.3, 1.4, 1.5, 1.7, 1.6, 1.3, 1.4, 1.5, 1.7, and 1.6. The item difficulties  $b_i$  were chosen as -0.8, 0.4, 1.2, 2.0, -2.0, -0.8, 0.4, 1.2, 2.0, -2.0, -0.8, 0.4, 1.2, 2.0, -2.0, -0.8, 0.4, 1.2, 2.0, -2.0, -0.8, 0.4, 1.2, 2.0, and -2.0. The DIF effects  $\delta_i$  were zero for the first 15 items. Items 16 to 25 had non-zero DIF effects.

In the condition of small DIF effects (see [38]), we chose  $\delta_i$  values of -0.60, 0.60, -0.65, 0.70, 0.65, -0.70, 0.60, -0.65, 0.70, and -0.65 for Items 16 to 25. In the condition of large DIF effects, we multiplied these effects by 2. These two conditions are referred to as balanced DIF conditions because the DIF effects  $\delta_i$  average to zero. In line with other studies, we also considered unbalanced DIF [43], in which we took absolute DIF effects in the small DIF and large DIF conditions. In the unbalanced DIF conditions, all DIF effects  $\delta_i$  were assumed positive and did not average to zero. The item parameters can also be found at https://osf.io/ykew6 (accessed on 2 April 2024).

Moreover, we varied the sample size N in this simulation study by 500, 1000, and 2000. There were N/2 subjects in each of the two groups.

The regularized 2PL model with DIF was estimated with the regularized likelihood function using the SCAD penalty on a nonequidistant grid of 37  $\lambda$  values between 0.0001 and 1 (see the R simulation code at https://osf.io/ykew6; accessed on 2 April 2024). We approximated the nondifferentiable SCAD penalty function by its differentiable approximating function using the tuning  $\varepsilon=0.001$ . We saved parameter estimates that minimized AIC and BIC. Item parameters that did not exceed the threshold  $\tau=0.02$  in its absolute value were regularized. In the direct minimization of SAIC and SBIC, we tried the values 0.01, 0.001, and 0.0001 of the tuning parameters  $\varepsilon$ . It was found that  $\varepsilon=0.001$  performed best, which is the reason why we only reported this solution.

As the outcome of the simulation study, we studied (average) absolute bias and (average) root mean square error (RMSE) of model parameter estimates as well as type-I error rates and power rates. Absolute bias and RMSE were computed for estimates of distribution parameters  $\mu_2$  and  $\sigma_2$ . Moreover, absolute bias and RMSE were computed for all estimates of DIF effects  $\delta_i$ . Formally, let  $\gamma_h$  be the hth parameter ( $h = 1, \ldots, H$ ) in the model parameter vector  $\gamma$ . Let  $\widehat{\gamma}_{hr}$  be the parameter estimate of  $\gamma_h$  in replication r ( $r = 1, \ldots, R$ ). The absolute bias (abias) of the parameter estimate  $\widehat{\gamma}_h$  was computed as

$$abias(\widehat{\gamma}_h) = \left| \frac{1}{R} \sum_{r=1}^{R} \widehat{\gamma}_{hr} - \gamma_h \right|.$$
 (15)

The RMSE was computed as

$$RMSE(\widehat{\gamma}_h) = \sqrt{\frac{1}{R} \sum_{r=1}^{R} (\widehat{\gamma}_{hr} - \gamma_h)^2}.$$
 (16)

The average absolute bias and average RMSE were computed for DIF effects with true values of 0 (i.e., DIF effects for Items 1 to 15; non-DIF items) and for DIF effects different from 0 (i.e., DIF effects for Items 16 to 25; DIF items). The (average) type-I error rates was assessed for non-DIF items as the proportion of events in which an estimated DIF effect differed from zero (i.e., it exceeded the threshold  $\tau=0.02$  in its absolute value). The (average) power rates were determined for DIF items accordingly. More formally, the type-I error rate or power rate (abbreviated as "rate" in (17)) was determined by

$$rate(\widehat{\gamma}_h) = 100 \cdot \frac{1}{R} \sum_{r=1}^{R} \mathbf{1}(|\widehat{\gamma}_{hr}| > \tau) . \tag{17}$$

Algorithms **2024**, 17, 153 6 of 17

Absolute bias values smaller than 0.03 were classified as acceptable in this simulation study. Moreover, type-I error rates smaller than 10.0 and power rates larger than 80.0 were seen as satisfactory.

In total, R = 750 replications were conducted in each of the 2 (small vs. large DIF)  $\times$  2 (balanced vs. unbalanced DIF)  $\times$  3 (sample size) = 12 cells of the simulation study. The entire simulation study was conducted with the R [44] statistical software. The estimation of the regularized IRT model was carried out using the sirt::xxirt() function in the R package sirt [45]. Replication material for the simulation study can be found at https://osf.io/ykew6 (accessed on 2 April 2024).

## 3.2. Results

Table 1 displays the average absolute bias and the average RMSE of model parameters as a function of the extent of DIF and sample size N for balanced and unbalanced DIF. It turned out that the mean  $\mu_2$  and the standard deviation  $\sigma_2$  of the second group were unbiasedly estimated in the balanced DIF condition. Moreover, while DIF effects for non-DIF items were unbiasedly estimated, DIF effects were biased for moderate sample sizes (i.e., for N=500 and 1000). In general, there was a similar behavior of regularized estimation based on AIC and BIC compared to its smooth competitors SAIC and SBIC. However, smooth information criteria had some advantages in smaller samples with respect to the RMSE. Note that SAIC was the frontrunner in all balanced DIF conditions regarding the RMSE of the estimate of  $\mu_2$ .

**Table 1.** Simulation Study 1: (Average) absolute bias and average root mean square error (RMSE) of model parameters as a function of the extent of differential item functioning (DIF) and sample size *N* for balanced and unbalanced DIF.

			(	(Average) A	bsolute Bias	<u> </u>		(Average	e) RMSE	
Par	DIF	N	AIC	SAIC	BIC	SBIC	AIC	SAIC	BIC	SBIC
			Balanced D	IF						
Ш	small	500 1000 2000	0.001 0.002 0.001	0.004 0.000 0.001	0.000 0.001 0.000	0.003 0.001 0.000	0.104 0.069 0.048	0.090 0.064 0.046	0.113 0.075 0.046	0.104 0.070 0.047
$\mu_2$	large	500 1000 2000	0.005 0.003 0.002	0.000 0.004 0.001	0.007 0.001 0.002	0.004 0.001 0.002	0.101 0.071 0.050	0.093 0.066 0.049	0.096 0.067 0.049	0.098 0.068 0.049
$\sigma_2$	small	500 1000 2000	0.002 0.001 0.001	0.002 0.001 0.001	0.007 0.002 0.001	0.001 0.001 0.002	0.071 0.046 0.032	0.070 0.046 0.032	0.070 0.046 0.032	0.070 0.046 0.032
02	large	500 1000 2000	0.003 0.002 0.001	0.001 0.003 0.001	0.000 0.002 0.001	0.002 0.002 0.001	0.068 0.045 0.035	0.067 0.044 0.035	0.067 0.044 0.035	0.067 0.044 0.035
$\delta_i$	small	500 1000 2000	0.006 0.005 0.002	0.006 0.003 0.002	0.003 0.002 0.001	0.004 0.002 0.001	0.216 0.139 0.098	0.187 0.113 0.073	0.108 0.061 0.032	0.148 0.069 0.028
(no DIF)	large	500 1000 2000	0.003 0.006 0.006	0.005 0.004 0.002	0.003 0.001 0.001	0.002 0.002 0.001	0.201 0.140 0.098	0.188 0.115 0.073	0.082 0.047 0.031	0.142 0.067 0.030
$\delta_i$	small	500 1000 2000	0.025 0.006 0.003	0.024 0.008 0.003	<b>0.182 0.062</b> 0.010	<b>0.077 0.041</b> 0.011	0.349 0.211 0.137	0.330 0.213 0.135	0.496 0.315 0.155	0.398 0.276 0.157
(DIF)	large	500 1000 2000	0.026 0.017 0.007	0.024 0.017 0.004	0.022 0.015 0.004	0.022 0.015 0.003	0.311 0.212 0.149	0.302 0.207 0.146	0.340 0.210 0.146	0.311 0.208 0.146

Algorithms **2024**, 17, 153 7 of 17

Table 1. Cont.

				(Average) A	bsolute Bias	 S	(Average) RMSE				
Par	DIF	N	AIC	SAIC	BIC	SBIC	AIC	SAIC	BIC	SBIC	
			Unbalance	d DIF							
		500	0.093	0.099	0.115	0.091	0.157	0.139	0.163	0.144	
	small	1000	0.050	0.047	0.049	0.033	0.111	0.087	0.110	0.085	
$\mu_2$		2000	0.025	0.008	0.013	0.004	0.069	0.048	0.072	0.048	
μ2		500	0.053	0.072	0.024	0.020	0.145	0.122	0.143	0.100	
	large	1000	0.024	0.030	0.003	0.002	0.084	0.076	0.077	0.068	
		2000	0.004	0.012	0.001	0.000	0.053	0.059	0.048	0.048	
		500	0.004	0.004	0.001	0.003	0.067	0.067	0.067	0.067	
	small	1000	0.000	0.000	0.001	0.000	0.048	0.048	0.048	0.048	
Œ		2000	0.000	0.000	0.001	0.000	0.032	0.031	0.031	0.031	
$\sigma_2$		500	0.000	0.001	0.000	0.001	0.065	0.065	0.064	0.065	
	large	1000	0.000	0.001	0.001	0.000	0.046	0.046	0.045	0.045	
	Ü	2000	0.001	0.002	0.001	0.001	0.031	0.032	0.031	0.032	
		500	0.114	0.108	0.035	0.062	0.296	0.251	0.170	0.207	
	small	1000	0.072	0.055	0.028	0.016	0.207	0.150	0.143	0.095	
$\delta_i$		2000	0.037	0.013	0.015	0.001	0.122	0.079	0.098	0.023	
(no DIF)		500	0.079	0.114	0.032	0.030	0.255	0.236	0.206	0.144	
	large	1000	0.038	0.051	0.005	0.003	0.133	0.145	0.072	0.065	
	O	2000	0.010	0.025	0.001	0.001	0.055	0.107	0.023	0.030	
		500	0.185	0.221	0.399	0.262	0.405	0.409	0.553	0.462	
	small	1000	0.089	0.111	0.158	0.117	0.270	0.285	0.368	0.319	
$\delta_i$	0111011	2000	0.036	0.010	0.020	0.010	0.167	0.135	0.179	0.151	
(DIF)		500	0.075	0.112	0.037	0.029	0.339	0.312	0.354	0.303	
	large	1000	0.036	0.050	0.005	0.004	0.212	0.199	0.207	0.196	
	Ü	2000	0.011	0.020	0.004	0.004	0.138	0.144	0.137	0.138	

Note. Par = parameter;  $\mu_2$  = mean of  $\theta$  in second group;  $\sigma_2$  = standard deviation of  $\theta$  in second group;  $\delta_i$  (no DIF) = DIF parameters with zero population values;  $\delta_i$  (DIF) = DIF parameters with non-zero population values; Absolute bias values larger than 0.03 are printed in bold font.

In the unbalanced DIF condition, estimated group means and DIF effects were generally biased. However, the bias decreased with increased sample size and was smaller with large instead of small DIF effects. SBIC was the frontrunner on five out of six conditions for estimates of  $\mu_2$  with respect to the RMSE. Only for N=500 and small DIF, SAIC outperformed the other estimators.

Table 2 presents average type-I error and power rates for DIF effects of non-DIF and DIF items. It is evident that AIC and SAIC had inflated type-I error rates. Moreover, BIC and SBIC had acceptable type-I error rates. However, SBIC had an inflated type-I error rate for N=500 in the unbalanced DIF condition with a small DIF. Overall, the power rates of regularized estimators AIC and BIC performed similarly to their smooth alternatives SAIC and SBIC. However, SBIC slightly outperformed BIC in terms of power rates.

Algorithms **2024**, 17, 153 8 of 17

			Type-I E	rror Rate	Power Rate				
DIF	N	AIC	SAIC	BIC	SBIC	AIC	SAIC	BIC	SBIC
		Balanced DI	F						
	500	17.0	13.7	2.1	6.2	83.6	85.8	52.7	73.3
small	1000	14.4	8.2	1.4	2.1	97.0	96.1	81.5	87.3
	2000	14.4	6.2	0.7	0.5	99.9	99.8	97.6	97.5
	500	15.3	14.2	1.2	5.8	99.7	99.8	97.5	99.4
large	1000	15.0	9.0	0.8	2.0	100	100	99.9	100
Ü	2000	14.5	6.2	0.6	0.6	100	100	100	100
		Unbalanced	DIF						
	500	25.8	23.8	4.8	11.3	68.9	65.6	30.6	54.0
small	1000	21.0	15.8	5.1	3.7	89.4	85.4	71.3	79.9
	2000	13.6	9.1	2.7	0.4	97.7	99.6	95.9	98.1
	500	14.5	28.9	3.4	6.3	98.0	99.0	96.7	98.9
large	1000	9.6	22.4	0.6	2.0	99.8	100	99.7	100

0.3

**Table 2.** Simulation Study 1: Type-I error rate and power rate for DIF effects  $\delta_i$  as a function of the extent of differential item functioning (DIF) and sample size N for balanced and unbalanced DIF.

Note. Type-I error rates larger than 10.0 and power rates smaller than 80.0 are printed in bold font.

# 4. Simulation Study 2: Multidimensional Logistic Item Response Model

0.6

In this Simulation Study 2, the multidimensional logistic IRT model [46] with cross-loadings is studied. That is, each item  $X_i$  is allocated to a primary dimension  $\theta_d$ . However, it could be that this item also loads on other dimensions than the primary dimension (i.e., the target factor variable). Formally, the IRF of the multidimensional logistic IRT model is given by

100

$$P(X_i = 1 | \boldsymbol{\theta}) = \Psi\left(\sum_{d=1}^{D} a_{id} \theta_d - b_i\right), \tag{18}$$

100

100

100

where  $\theta = (\theta_1, \dots, \theta_D)$ . All item discriminations  $a_{id}$  are regularized in the estimation, except those that load on the primary dimension. The means and standard deviations of factor variables  $\theta_d$  are fixed at 0 and 1 for identification reasons, respectively. The correlations between the dimensions can be estimated.

The regularized estimation of this model has been discussed in Refs. [47–49]. To ensure the identifiability of the model parameter, a sparse loading structure for item discriminations  $a_{id}$  is imposed. That is, most item discriminations are (approximately) zero in the DGM. Only a few loadings are allowed to differ from 0. Notably, regularized estimation of factor models can be regarded as an alternative to rotation methods in exploratory factor analysis [50,51].

#### 4.1. Method

2000

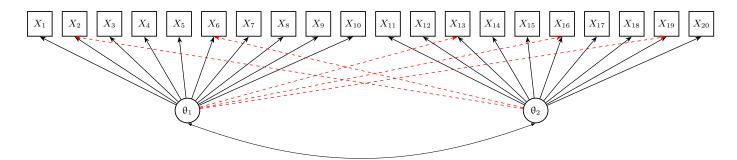
3.4

21.5

In this simulation study, we used a DGM with I=20 items and D=2 factor variables  $\theta_1$  and  $\theta_2$ . The first 10 items loaded on the first dimension, while Items 11 to 20 loaded on the second dimension. The factor variable  $(\theta_1,\theta_2)$  was bivariate normally distributed with standardized normally distributed components and a fixed correlation  $\rho$  of 0.5.

Moreover, we specified five cross-loadings. Items 2 and 6 had a cross-loading of size  $\delta$  on the second dimension, while Items 13, 16, and 19 had a cross-loading of size  $\delta$  on the first dimension. The DGM is visualized in Figure 1. In more detail, the loading matrix A that contains the item discriminations  $a_{id}$  (see (18)) is given by

Algorithms **2024**, 17, 153 9 of 17



**Figure 1.** Simulation Study 2: Data-generating model with I = 20 items  $X_i$  (i = 1, ..., 20) and two factor variables  $\theta_1$  and  $\theta_2$ . Cross-loadings are depicted by red dashed lines.

$$A = \begin{pmatrix} 0.6 & 0 \\ 0.8 & \delta \\ 1.0 & 0 \\ 1.4 & 0 \\ 1.2 & 0 \\ 0.6 & \delta \\ 0.8 & 0 \\ 1.0 & 0 \\ 1.4 & 0 \\ 1.2 & 0 \\ 0 & 0.6 \\ 0 & 0.8 \\ \delta & 1.0 \\ 0 & 1.4 \\ 0 & 1.2 \\ \delta & 0.6 \\ 0 & 0.8 \\ 0 & 1.0 \\ \delta & 1.4 \\ 0 & 1.2 \end{pmatrix} . \tag{19}$$

The size of the cross-loading  $\delta$  was chosen as 0.3, indicating a small cross-loading), or 0.5, indicating a large cross-loading. The item difficulties  $b_i$  (see (18)) of the 20 items were -0.8, 0.4, 1.2, 2.0, -2.0, -0.8, 0.4, 1.2, 2.0, -2.0, -0.8, 0.4, 1.2, 2.0, -2.0, -0.8, 0.4, 1.2, 2.0, and -2.0. The item parameters can also be found at https://osf.io/ykew6 (accessed on 2 April 2024).

We varied the sample size N as 500, 1000, and 2000, which may be interpreted as a small, moderate, and large sample size.

Like in Simulation Study 1, we compared the performance of regularized estimation based on AIC and BIC with the smooth alternatives SAIC and SBIC. A nonequidistant grid of 37  $\lambda$  values between 0.0001 and 1 was chosen (see the R simulation code at https://osf.io/ykew6; accessed on 2 April 2024). The optimization functions were specified with the same tuning parameters for differentiable approximations as in Simulation Study 1 (see Section 3.1). (Average) absolute bias and (average) RMSE of model parameters, as well as type-I error rates and power rates for cross-loadings, were assessed for the four estimation methods.

In total, R = 750 replications were conducted in each of the 2 (small vs. large cross-loadings)  $\times$  3 (sample size) = 6 cells of the simulation study. The whole simulation study was conducted using the statistical software R [44]. The estimation of the regularized multidimensional logistic IRT model was carried out using the sirt::xxirt() function in

Algorithms **2024**, 17, 153 10 of 17

the R package sirt [45]. Replication material for this simulation study can also be found at https://osf.io/ykew6 (accessed on 2 April 2024).

## 4.2. Results

Table 3 reports the (average) absolute bias and (average) RMSE of estimated model parameters. It turned out that the factor correlation  $\rho$  was biased for small and moderate sample sizes of N=500 and N=1000. The bias was reduced with larger cross-loadings in large sample sizes. However, a notable bias was even present for a large sample size N=2000 if the BIC or SBIC was used. However, AIC and SAIC outperformed the other criteria for estimates of  $\rho$  with respect to bias and RMSE. Interestingly, the RMSE of SAIC was substantially smaller compared to AIC for the factor correlation  $\rho$ , as well as for true zero cross-loadings (i.e., rows "CL=0" in Table 3) and non-zero cross-loadings (i.e., rows " $CL\neq0$ " in Table 3).

**Table 3.** Simulation Study 2: (Average) absolute bias and average root mean square error (RMSE) of model parameters as a function of the size of cross-loadings and sample size *N*.

				Absolu	te Bias			RMSE			
Par	CL	N	AIC	SAIC	BIC	SBIC	AIC	SAIC	BIC	SBIC	
		500	0.064	0.054	0.104	0.070	0.151	0.102	0.134	0.110	
	small	1000	0.040	0.070	0.088	0.085	0.157	0.096	0.124	0.104	
0		2000	0.015	0.018	0.059	0.065	0.077	0.052	0.082	0.081	
ρ	500	0.055	0.062	0.136	0.073	0.167	0.109	0.179	0.117		
	large	1000	0.029	0.054	0.074	0.057	0.144	0.100	0.124	0.099	
	_	2000	0.010	0.014	0.016	0.014	0.062	0.047	0.058	0.051	
		500	0.041	0.016	0.015	0.008	0.243	0.113	0.130	0.095	
	small	1000	0.025	0.028	0.008	0.014	0.188	0.119	0.092	0.088	
CL = 0		2000	0.011	0.006	0.006	0.003	0.102	0.062	0.049	0.034	
CL = 0		500	0.044	0.016	0.024	0.011	0.282	0.119	0.181	0.109	
	large	1000	0.027	0.028	0.013	0.015	0.183	0.127	0.096	0.095	
	_	2000	0.009	0.009	0.005	0.002	0.094	0.067	0.049	0.030	
		500	0.102	0.141	0.238	0.177	0.287	0.287	0.306	0.296	
	small	1000	0.075	0.118	0.211	0.192	0.237	0.235	0.288	0.273	
$CL \neq 0$		2000	0.021	0.033	0.132	0.154	0.140	0.146	0.231	0.243	
		500	0.078	0.130	0.295	0.166	0.341	0.353	0.452	0.379	
	large	1000	0.036	0.066	0.151	0.107	0.228	0.245	0.336	0.291	
	<u> </u>	2000	0.011	0.009	0.025	0.028	0.123	0.116	0.161	0.161	

Note. Par = parameter;  $\rho$  = correlation between factors  $\theta_1$  and  $\theta_2$ ; CL=0 = cross-loading with zero population value;  $CL\neq 0$  = cross-loading with non-zero population value;; Absolute bias values larger than 0.03 are printed in bold font.

Table 4 shows type-I error rates and power rates of estimated cross-loadings. It is evident that AIC had inflated type-I error rates, while type-I error rates of SAIC, BIC, and SBIC were acceptable. Importantly, there were low power rates for BIC and SBIC, in particular for small cross-loadings. The SAIC estimation method may be preferred if the goal is detecting non-zero cross-loadings.

			Type-I E	rror Rate		Power Rate				
CL	N	AIC	SAIC	BIC	SBIC	AIC	SAIC	BIC	SBIC	
	500	16.7	5.1	2.1	2.5	41.2	30.6	9.4	22.4	
small	1000	18.7	8.8	2.0	3.2	58.0	46.5	17.9	24.3	
	2000	15.1	6.2	1.7	0.7	86.5	82.4	44.0	38.3	
	500	18.5	4.8	3.1	2.8	68.5	59.5	27.3	52.0	
large	1000	17.0	10.0	2.5	3.2	87.4	81.0	59.2	70.6	
J	2000	13.3	7.8	1.3	0.7	98.6	98.7	92.3	92.6	

**Table 4.** Simulation Study 2: Type-I error rate and power rate for cross-loadings as a function of the size of cross-loadings and sample size *N*.

Note. CL = size of cross-loadings; Type-I error rates larger than 10.0 and power rates smaller than 80.0 are printed in bold font.

## 5. Simulation Study 3: Mixed Rasch/2PL Model

Recently, a mixed Rasch/2PL model [52] (see also [53]) received some attention. The idea of this unidimensional IRT model is to find items that conform to the Rasch model [54], while there can be a subset of items that follow the more complex 2PL model [9]. The IRF of this model is given by

$$P(X_i = 1|\theta) = \Psi(\exp(\alpha_i)\theta - b_i). \tag{20}$$

Note that the IRF in (20) is just a reparametrized 2PL model with item discriminations  $a_i = \exp(\alpha_i)$ . Hence,  $\alpha_i = \log(a_i)$  are the logarithms of item discriminations  $a_i$ . The case  $\alpha_i = 0$  corresponds to the Rasch model because  $a_i = \exp(\alpha_i) = 1$ , while  $\alpha_i \neq 0$  results in item discriminations  $a_i$  different from 1. The mean of the factor variable  $\theta$  is fixed to 0, while the standard deviation  $\sigma$  should be estimated.

In order to achieve identifiability of the model parameters, a sparsity structure of the logarithms of item discriminations  $\alpha_i$  is imposed. Hence, the majority of items is assumed to follow the Rasch model. Again, the sparsity structure is directly implemented in a regularized estimation of the mixed Rasch/2PL model.

# 5.1. Method

In this simulation study, we used I = 20 items for the DGM of the mixed Rasch/2PL model. The factor variable  $\theta$  was assumed to be normally distributed with a zero mean and a standard deviation  $\sigma = 1.2$ . The item difficulties  $b_i$  (see the IRF in (20)) of the 20 items were chosen as -0.8, 0.4, 1.2, 2.0, -2.0, -0.8, 0.4, 1.2, 2.0, -2.0, -0.8, 0.4, 1.2, 2.0, -2.0, -0.8, 0.4, 1.2, 2.0, and -2.0. The first 14 items followed the Rasch model (i.e.,  $\alpha_i = 0$ for i = 1, ..., 15). Items 15 to 20 followed the 2PL model and had  $\alpha_i$  values that equaled  $-\delta$ ,  $\delta$ ,  $-\delta$ ,  $\delta$ , and  $-\delta$ . The size of  $\delta$  controlled the deviation from the Rasch model. We either chose  $\delta$  as  $\log(1.4) = 0.336$  and  $\log(2) = 0.693$ , indicating small and large deviations from the Rasch model. Moreover, we manipulated the direction of the deviation from the Rasch model. While the previously described conditions had  $\alpha_i$  that canceled out on average and resulted in a balanced deviation from the Rasch model (i.e., there was an equal number of items that are smaller and larger than 1, respectively), we also specified an unbalanced deviation from the Rasch model in which Items 15 to 20 all had the value  $\delta$ . In this condition, we also studied small (i.e.,  $\delta = 0.336$ ) and large (i.e.,  $\delta = 0.693$ ) deviations from the Rasch model. Hence, in the case of unbalanced deviations from the Rasch model, items had either discriminations of 1 or larger than 1. The item parameters can also be found at https://osf.io/ykew6 (accessed on 2 April 2024).

Like in the other two simulation studies, we varied the sample size N as 500, 1000, and 2000.

Again, like in Simulation Study 1 and Simulation Study 2, we compared the performance of regularized estimation based on AIC and BIC with the smooth alternatives SAIC and SBIC. A nonequidistant grid of 33  $\lambda$  values between 0.001 and 1 was chosen (see the R simulation code at https://osf.io/ykew6; accessed on 2 April 2024). The optimization

functions were specified with the same tuning parameters for differentiable approximations as in Simulation Study 1 (see Section 3.1). (Average) absolute bias and (average) RMSE of model parameters  $\sigma$  and  $\alpha_i$  ( $i=1,\ldots,I$ ), as well as type-I error rates and power rates for logarithms of item discriminations, were assessed.

Overall, R = 750 replications were conducted in each of the 2 (small vs. large deviations)  $\times$  2 (balanced vs. unbalanced deviations)  $\times$  3 (sample size) = 12 cells of the simulation study. This simulation study was also executed using the statistical software R [44]. Like in the other two simulation studies, the regularized multidimensional logistic IRT model was estimated using the sirt::xxirt() function in the R package sirt [45]. Replication material for this simulation study can also be found at https://osf.io/ykew6 (accessed on 2 April 2024).

#### 5.2. Results

Table 5 contains the (average) absolute bias and (average) RMSE for the estimated model parameters. Notably, there was a different pattern of findings in the conditions of balanced and unbalanced deviations from the Rasch model. In general, SAIC performed well for the estimation of  $\sigma$ , except for small balanced deviations from the Rasch model with a sample size of N=500. In most of the conditions, estimation based on SBIC performed similarly, if not better, than BIC for the estimation of  $\sigma$  in terms of RMSE.

**Table 5.** Simulation Study 3: (Average) absolute bias and average root mean square error (RMSE) of model parameters as a function of the sample size *N* and the size and the extent and direction of deviations from the Rasch model

			(	(Average) A	bsolute Bias	5		(Average	e) RMSE	
Par	Dev	N	AIC	SAIC	BIC	SBIC	AIC	SAIC	BIC	SBIC
			Balanced de	viations from	the Rasch m	odel				
σ	small	500 1000 2000	0.053 0.062 0.109	<b>0.038</b> 0.005 0.001	0.004 0.012 0.025	0.010 0.004 0.009	0.099 0.107 0.167	0.082 0.054 0.032	0.070 0.051 0.044	0.072 0.056 0.037
J	large	500 1000 2000	0.018 0.016 0.007	0.014 0.002 0.000	0.004 0.002 0.000	0.006 0.002 0.000	0.069 0.050 0.035	0.065 0.044 0.033	0.064 0.041 0.030	0.064 0.041 0.030
$\alpha_i = 0$	small	500 1000 2000	0.035 0.048 0.096	0.017 0.003 0.001	0.001 0.002 0.003	0.002 0.001 0.000	0.124 0.119 0.166	0.091 0.060 0.042	0.048 0.027 0.023	0.047 0.020 0.003
$\alpha_l = 0$	large	500 1000 2000	0.018 0.017 0.007	0.012 0.003 0.001	0.002 0.001 0.000	0.002 0.000 0.000	0.101 0.066 0.033	0.082 0.058 0.040	0.046 0.023 0.010	0.044 0.014 0.003
$lpha_i  eq 0$	small	500 1000 2000	0.071 0.081 0.120	<b>0.070</b> 0.024 0.003	0.127 0.075 0.072	0.137 0.101 0.045	0.224 0.184 0.199	0.239 0.154 0.085	0.283 0.212 0.159	0.289 0.237 0.156
	large	500 1000 2000	0.014 0.019 0.004	0.017 0.006 0.004	0.015 0.006 0.003	0.018 0.008 0.004	0.207 0.139 0.095	0.215 0.136 0.095	0.230 0.138 0.093	0.231 0.143 0.094
				l deviations fi						
σ	small	500 1000 2000	0.008 0.015 0.011	<b>0.032</b> 0.008 0.003	0.084 0.028 0.002	<b>0.083 0.055</b> 0.015	0.076 0.051 0.036	0.081 0.050 0.032	0.110 0.061 0.031	0.109 0.078 0.040
	large	500 1000 2000	0.001 0.005 0.002	0.001 0.001 0.003	0.001 0.000 0.002	0.001 0.001 0.002	0.069 0.046 0.034	0.062 0.043 0.032	0.061 0.040 0.030	0.060 0.040 0.029

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				(Average) Al	bsolute Bia	6	(Average) RMSE				
Par	Dev	N	AIC	SAIC	BIC	SBIC	AIC	SAIC	BIC	SBIC	
small $lpha_i=0$ large	small	500 1000	0.009 0.014	0.005 0.003	0.008 0.002	0.004 0.001	0.099 0.068	0.078 0.056	0.057 0.027	0.047 0.019	
	large	2000 500 1000	0.010 0.003 0.004	0.002 0.003 0.001	0.001 0.001 0.001	0.000 0.001 0.000	0.044 0.105 0.069	0.042 0.079 0.053	0.015 0.046 0.025	0.005 0.041 0.013	
$\alpha_1 \neq 0$	small	2000 500 1000 2000	0.003 0.029 0.012 0.012	0.001 <b>0.069</b> 0.014 0.001	0.001 0.194 0.069 0.002	0.000 0.205 0.145 0.037	0.047 0.180 0.103 0.068	0.039 0.207 0.116 0.067	0.014 0.281 0.182 0.075	0.002 0.289 0.240 0.129	
$\alpha_i \neq 0$	large	500 1000 2000	0.008 0.011 0.003	0.006 0.007 0.003	0.007 0.006 0.003	0.005 0.006 0.003	0.129 0.091 0.062	0.126 0.089 0.061	0.127 0.089 0.061	0.127 0.089 0.061	

Note. Par = parameter; Dev = size of deviation from the Rasch model;  $\sigma$  = standard deviation of factor variable  $\theta$ ;  $\alpha_i = 0$  = logarithm of item discriminations with zero population value;  $\alpha_i \neq 0$  = logarithm of item discriminations with non-zero population value;; Absolute bias values larger than 0.03 are printed in bold font.

Table 6 displays type-I error rates and power rates for estimated logarithms of item discriminations. In contrast to the estimation based on the AIC, SAIC had acceptable type-I error rates. Moreover, power rates for detecting deviations from the Rasch model were much higher for SAIC then BIC or SBIC.

**Table 6.** Simulation Study 3: Type-I error rate and power rate for logarithm of item discriminations as a function of the sample size N and the size and the extent and direction of deviations from the Rasch model.

			Type-I E	rror Rate		Power Rate				
Dev	N	AIC	SAIC	BIC	SBIC	AIC	SAIC	BIC	SBIC	
		Balanced dev	viations from th	e Rasch mode	l					
	500	14.6	7.7	1.3	1.2	68.8	61.6	40.6	39.6	
small	1000	18.5	6.5	0.7	0.3	77.6	85.5	63.6	55.9	
	2000	36.4	7.7	0.6	0.0	78.8	98.7	75.5	79.8	
	500	11.4	6.6	1.3	1.2	97.9	95.8	93.8	93.6	
large	1000	9.3	6.6	0.6	0.2	99.7	99.8	99.4	98.9	
Ü	2000	4.4	7.4	0.1	0.0	100	100	100	100	
		Unbalanced	deviations from	the Rasch mo	odel					
	500	11.4	5.7	1.8	1.1	80.4	69.5	30.9	29.9	
small	1000	10.8	5.9	0.8	0.3	97.9	94.0	72.5	50.9	
	2000	8.3	7.7	0.4	0.1	99.9	99.9	98.2	87.3	
	500	13.7	5.9	1.2	1.0	100	100	99.9	99.9	
large	1000	12.1	5.8	0.7	0.2	100	100	100	100	
ŭ	2000	10.9	7.3	0.4	0.0	100	100	100	100	

Note. Dev = size of deviation from the Rasch model; Type-I error rates larger than 10.0 and power rates smaller than 80.0 are printed in bold font.

# 6. Discussion

In this article, we compared the ordinarily employed indirect regularized estimation based on a grid of regularization parameters  $\lambda$  with a subsequent discrete minimization of AIC and BIC with a direct minimization of smooth information criteria SAIC and SBIC [26] for the estimation of regularized item response models. It turned out that the direct SIC-based estimation methods resulted in comparable, in many cases, or better performance than the indirect regularization estimation methods based on AIC and BIC.

This is remarkable because SIC-based minimization is computationally much simpler, and ordinary gradient-based optimization routines can be utilized.

We studied the performance of SAIC and SBIC in three simulation studies that focus on differential item functioning, (semi-)exploratory multidimensional IRT models, and model choice between the Rasch model and the 2PL model. These three cases frequently appear in applications of regularized IRT models, which is why we chose these settings for our work.

In this article, we confined ourselves to analyzing dichotomous item responses and continuous factor variables. Future research could investigate the application of these techniques to polytomous item response, count item response data [55], or cognitive diagnostic models that involve multivariate binary factor variables [56]. More generally, smooth information criteria can be used in all modeling approaches that involve regularized estimation. In the field of econometrics or social science, possible applications could be (generalized) linear regression models [57], regularized panel models [58], or regularized estimation for analyzing heterogeneous treatment effects [59].

Notably, we did not investigate the estimation of standard errors in this article. Future research may investigate this with an application of the Huber–White variance estimation formula [60,61] applied to the subset of parameters that resulted in non-zero values [62].

Finally, two different targets in the analysis of item response models should be distinguished in regularized estimation. First, the selection or detection of non-zero effects like cross-loadings or DIF effects may be the focus. For this goal, model selection based on information criteria can prove helpful in order to control type-I error rates. Second, if the focus lies on structural parameters (such as group means or factor correlations), choosing a parsimonious model that tries to penalize the number of estimated parameters, like in information criteria, may not be beneficial in terms of bias and variability of structural parameters [21]. It can be advantageous to use a sufficiently small regularization parameter  $\lambda$  to ensure the empirical identifiability of the model but not to focus on effect selection if structural parameters are of interest [63]. In this sense, sparsity in effects is imposed in a defensive way.

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**Data Availability Statement:** Supplementary material for the simulation studies can be found at https://osf.io/ykew6 (accessed on 2 April 2024).

Conflicts of Interest: The authors declare no conflicts of interest.

## Abbreviations

The following abbreviations are used in this manuscript:

2PL two-parameter logistic
AIC Akaike information criterion
BIC Bayesian information criterion
DGM data-generating model
DIF differential item functioning
IRF item response function
IRT item response theory

LASSO least absolute shrinkage and selection operator

ML maximum likelihood RMSE root mean square error

SAIC smooth Akaike information criterion SBIC smooth Bayesian information criterion SCAD smoothly clipped absolute deviation SIC smooth information criterion Algorithms **2024**, 17, 153 15 of 17

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