Energy Saving Design Technologies and Methodologies for a Hydraulic Press
Correction


Weijia Yang 1,2, Jiandong Yang 1,*, Wencheng Guo 1, Wei Zeng 1, Chao Wang 1, Linn Saarinen 2,3 and Per Norrlund 2,3

1 The State Key Laboratory of Water Resources and Hydropower Engineering Science, Wuhan University, Wuhan 430072, China; Weijia.Yang@Angstrom.uu.se (W.Y.); wench@whu.edu.cn (W.G.); wzeng@whu.edu.cn (W.Z.); wc699621@whu.edu.cn (C.W.)
2 Department of Engineering Sciences, Uppsala University, Uppsala SE-751 21, Sweden; Linn.Saarinen@vattenfall.com (L.S.); per.norrlund@vattenfall.com (P.N.)
3 Vattenfall R&D, Älvkarleby SE-814 26, Sweden
* Correspondence: jdyang@whu.edu.cn; Tel.: +86-27-6877-4375; Fax: +86-27-6877-2310

Received: 23 May 2016; Accepted: 30 May 2016; Published: 22 June 2016

The authors wish to make the following corrections to the published paper [1].

1. Equation (15) is replaced with:
\[ b_p K_d \frac{dy_{PID}}{dt}^2 + (1 + b_p K_p) \frac{dy_{PID}}{dt} + b_p K_i (y_{PID} - y_C) = - \left( K_d \frac{dx_f}{dt} + K_p \frac{dx_f}{dt} + K_i x_f \right) \]

2. Equation (16) is replaced with:
\[ e_p K_d \frac{d^2 x}{dt^2} + e_p K_p \frac{dx}{dt} + e_p K_i (x - p_C) + \frac{dy_{PID}}{dt} = - \left( K_d \frac{dx_f}{dt} + K_p \frac{dx_f}{dt} + K_i x_f \right) \]

3. Equation (17) is replaced with:
\[ b_p K_d \frac{d(y_{PID} - y_C)^2}{dt} + (1 + b_p K_p) \frac{d(y_{PID} - y_C)}{dt} + b_p K_i (y_{PID} - y_C) = 0 \]

4. Table 3 is replaced with:

<table>
<thead>
<tr>
<th>Control Mode</th>
<th>Equation</th>
<th>S1 Status</th>
<th>S2 Status</th>
<th>S3 Status</th>
</tr>
</thead>
<tbody>
<tr>
<td>Frequency control</td>
<td>(15)</td>
<td>1</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td></td>
<td>(16)</td>
<td>1</td>
<td>3</td>
<td>3</td>
</tr>
<tr>
<td>Opening control</td>
<td>(17)</td>
<td>2</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td></td>
<td>(18)</td>
<td>2</td>
<td>2</td>
<td>1</td>
</tr>
<tr>
<td>Power control</td>
<td>(19)</td>
<td>2</td>
<td>3</td>
<td>3</td>
</tr>
<tr>
<td></td>
<td>(20)</td>
<td>2</td>
<td>2</td>
<td>3</td>
</tr>
</tbody>
</table>

5. Figure 3 is replaced with:

![Graphical representation of the governor system in TOPSYS.](image)

**Figure 3.** Governor system in TOPSYS.

We apologize for any inconvenience caused to the readers by these changes. The manuscript will be updated and the original will remain available on the article webpage.

**Reference**


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