

## Article

# Design and Analysis of a 35 GHz Rectenna System for Wireless Power Transfer to an Unmanned Air Vehicle

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**Abstract:** In this article, the concept of a 22-kW microwave-powered unmanned aerial vehicle is presented. Its system architecture is analyzed and modeled for wirelessly transferring microwave power to the flying UAVs. The microwave system transmitting power at a 35 GHz frequency was found to be suitable for low-cost and compact architectures. The size of the transmitting and receiving systems are optimized to 108 m<sup>2</sup> and 90 m<sup>2</sup>, respectively. A linearly polarized 4 × 2 rectangular microstrip patch antenna array has been designed and simulated to obtain a high gain, high directivity, and high efficiency in order to satisfy the power transfer requirements. The numerically simulated gain, directivity, and efficiency of the proposed patch antenna array are 13.4 dBi, 14 dBi, and 85%, respectively. Finally, a rectifying system (rectenna) is optimized using the Agilent advanced design system (ADS) software as a microwave power receiving system. The proposed rectenna at the core of the system has an efficiency profile of more than 80% for an RF input power range of 9 to 18 dBm. Moreover, the RF-to-DC conversion efficiency and DC output voltage of the proposed rectenna are 80% and 3.5 V, respectively, for a 10 dBm input power at 35 GHz with a load of 1500 Ω.



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**Keywords:** UAV; microwave power transmission; patch antenna array; rectenna; millimeter-wave rectifier; Schottky diode; RF to DC conversion; voltage doubler; wireless power transfer

## 1. Introduction

Unmanned aircraft and drones are employed for applications related to intelligence, surveillance, and reconnaissance (ISR) gathering that are not putting human life in danger [1–3]. Unmanned air vehicles (UAVs) using advanced technologies such as global positioning systems (GPS) and wireless communications offer new business opportunities [4]. Nowadays, UAVs are widely used including fields such as broadcast coverage, search and rescue missions, scientific research, disaster monitoring, crime prevention, radiation observation, and so on. They can act as a platform for telecommunication services, i.e., mobile radio or TV broadcasting in rural locations at the regional level [5–8].

Electric aircraft has drawn attention as a possible candidate for UAVs applications. They have several advantages over the conventional gasoline-based airplane. An electric aircraft can use an electric motor that can be 95% efficient instead of the 18–23% efficiency of regular combustion engines. It is more reliable, light in weight, safe, low-cost, and quieter. Finally, it has zero carbon emissions, which is environmentally friendly.

The concept of wireless power transmission (WPT) via microwave is not new; research projects are conducted worldwide for cost-effective and highly efficient system design, which have multiple applications in different areas. In the 1960s, W.C Brown [9,10] initiated a microwave power transmission (MPT) research program wherein significant progress was made [11–13]. These previous attempts report on an MPT system consisting of two sections: a transmitting antenna (Tx), and a receiving antenna or rectifying antenna (Rx). In the Tx section, DC power is converted to microwave power by a microwave oscillator, i.e., magnetron or klystron. The microwave power radiates to the free space towards the Rx.

The Rx section receives microwave power and reverts it back to DC voltage. In 1963, W.C. Brown conducted an experiment in which he could capture 100 W of RF power with an output efficiency of 26% at 2.45 GHz from a distance of 5.48 m [11,14]. He then investigated the possibility of feeding wireless power to a flying helicopter. Shortly after, he and his team developed a 55% efficient rectifying antenna; consequently, his team successfully demonstrated the first microwave-powered helicopter that could reach an altitude of fifty feet [15]. By 1975, W.C. Brown and his team, while working on a NASA project, built the largest WPT made of a 26 m diameter parabolic antenna transmitting to a rectenna array size of 3.4 m × 7.2 m. The distance between the Tx antenna and Rx rectenna was 1 mile and the Rx side receive 30 kW of DC power with an efficiency of 82.5% [16]. In 1987, SHARP Canada conducted an MPT project that aimed at demonstrating a fuel-free airplane. They transmitted a 10 kW microwave signal at 2.45 GHz to an aircraft at a flying altitude of 150 m [17]. Many Japanese researchers have investigated and carried out fuel-free airplane MPT research in the 1980s using a 2.45 GHz RF carrier [18–21]. Some significant experiments including MINIX [18] and ISY-METS [19] were executed by Hiroshi Matsumoto’s team in 1983 and 1993, respectively. In MINIX and ISY-METS, a magnetron microwave transmitter generating an 800 W output at 2.45 GHz was used.

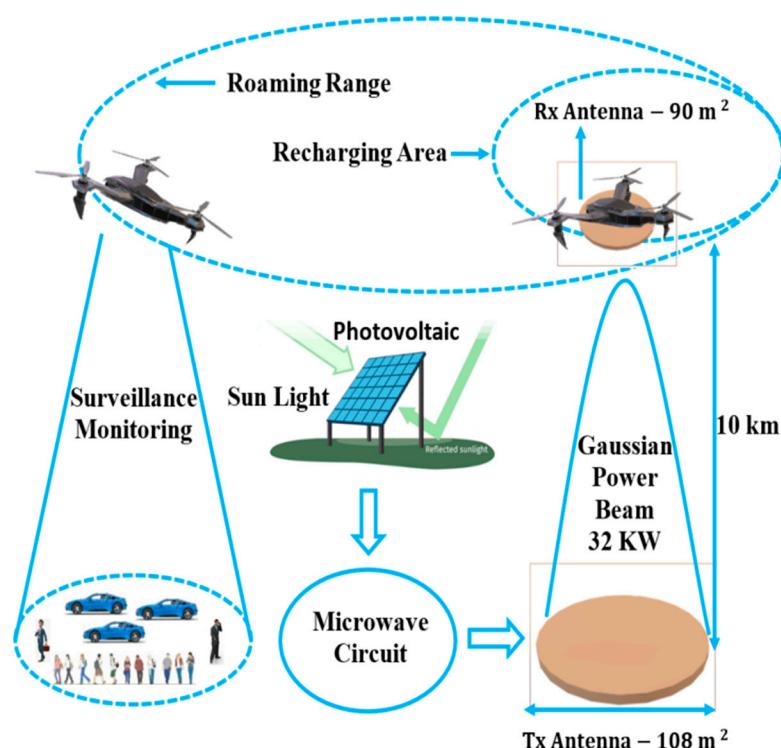
Many researchers reported different antennas employed in the design of rectennas such as microstrip patch, co-planer patch, dipole, spiral antennas, and so on [22–26]. To receive more power at the rectenna side, a high-gain antenna is preferable for WPT applications. A single antenna element is not compatible with WPT applications because it has low gain. To overcome this problem, using an array of micro-antennas is an interesting solution since it can supply more RF power [25]. Many high-frequency rectenna arrays have been reported, specifically below 10 GHz, i.e., 2.45 GHz and 5.8 GHz [27,28]. On the other hand, only a few millimeter-wave (24, 35, and 94 GHz) rectenna designs have been reported so far [29–33]. Most of them focused on wireless energy harvesting, which is suitable for low-power applications. The obvious advantages of millimeter-wave rectennas over microwave rectennas are their compact antenna size and higher overall system efficiency for long-distance transmission [25]. Very limited attention has been given to millimeter-wave frequencies WPT to UAVs systems. The potential offered by the importance of a millimeter-wave rectenna operating at 35 GHz has motivated the present work. This paper presents a 22-kW microwave power transfer to a UAV flying at a distance of 10 km. The key technologies that comprise this system are analyzed, estimated, and designed. All the results presented in this work are numerically simulated. The remainder of this paper is organized as follows: Section 2 describes an efficient overall system architecture based on MPT working at 35 GHz suitable for a compact system that could be implemented at a low cost. The MPT system’s key components, i.e., Tx, Rx, and beam efficiency parameters, are optimized in Sections 3 and 4, respectively. Section 5 describes a 4 × 2 rectangular patch antenna array considering the low cost and high production capacity. In Section 6, an efficient rectifying system is conceived using the Agilent advanced design system (ADS). Conclusions drawn from this work are presented in Section 7.

## 2. Remotely Powered Unmanned Air Vehicles

A key problem with conventional UAV is the limited amount of energy that can be stored onboard [34,35]. In order to increase the mission roaming range, the amount of energy stored needs to be increased at the expense of increased battery weight. One way to counter this problem is by supplying power remotely during the flight enabling recharge during the mission. Additionally, using microwave energy transmission allows the transfer over several kilometers and extends at the same time the roaming range. The most significant advantage of microwave power transmission technology is the capability for long-distance non-contact power transmission [11]. Wireless power transfer using microwaves is now a mature technology, and it can be utilized for efficient remotely powered UAV systems.

## 2.1. Proposed System Architecture

Pioneer works in that field were initiated many years ago by SHARP [17], wherein a high-altitude microwave-powered airplane was considered as a platform for relaying telecommunication signals. The idea includes a large ground antenna transferring microwave power to fuel-free airplanes at an altitude of 21 km [14–21]. This microwave power captured by the rectenna mounted under the airplane is converted into usable DC power to run the electric motor. Sharp has performed both theoretical and experimental analysis in this project, and the ISM frequency of 2.45 GHz was used [17]. Here, we proposed a microwave-powered UAV, at a transmitting distance of 10 km from the ground station. The transmitting distance can be varied according to the power demand. The proposed system architecture is shown in Figure 1. In this project, the MGM Compro electric propulsion system is adopted using a brushless DC motor with an embedded controller. It has maximum ratings in continuous power, voltage, torque, and revolution of 22 kW, 120 V, 100 Nm, and 8000 RPM, respectively. The UAVs can fly to the surveillance or monitoring area beyond the WPT range using its installed battery power of 120 V and 200 Ah. When the battery power goes down below a certain threshold, the UAV flies back within the WPT range (rechargeable area) for recharging. Several UAVs could use the same WPT ground station [1]. The ground station Tx antenna transmits power to the Rx rectenna mounted under the UAV while flying in the recharging area.



**Figure 1.** Proposed system architecture for microwave wireless power transmission.

The beam direction of the transmitted signal is determined by a pilot signal tracking method [36]. A large Tx and Rx antenna system is required with higher transmission efficiency for the successful MPT. Therefore, phase synchronization becomes an important issue among the unit. Hence, beam steering can be applied in each unit to solve the phase error. When the UAV changes its direction, the direction of the main lobe of the radiation pattern is changed in the Tx system in order to follow the UAV. The wingspan and length of the UAV are 10 m and 9 m, respectively. Therefore, the maximum antenna area on the UAV is  $90 \text{ m}^2$ . Given this antenna size, a maximum power,  $P_T$ , of 27 kW can be transmitted according to the equation:

$$P_T = P_d \times A_{eff} \quad (1)$$

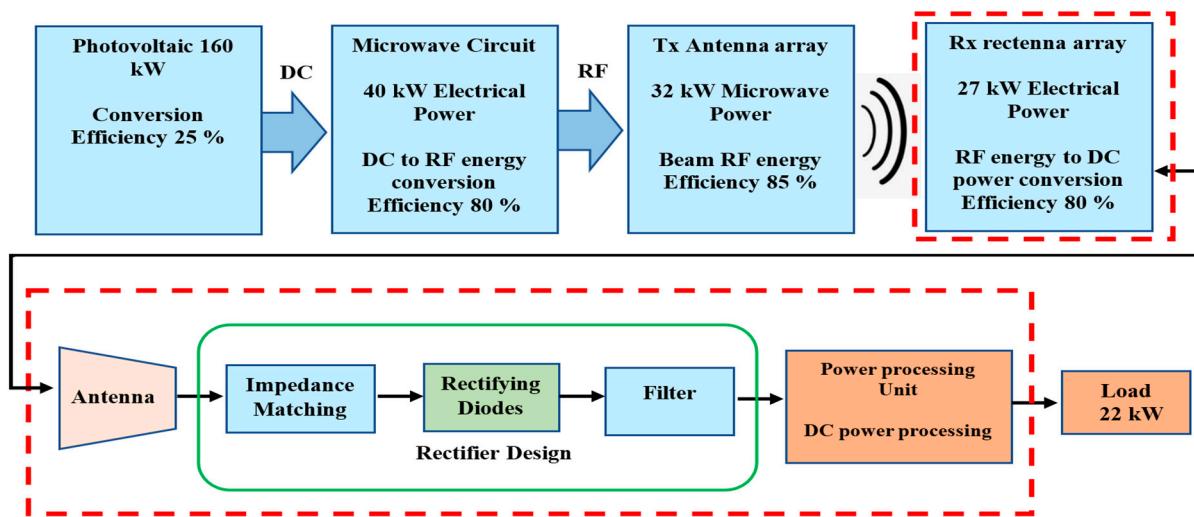
where  $P_d$  is the beam power density safety limit for microwave on earth atmosphere set to  $300 \text{ W/m}^2$  [37], and  $A_{\text{eff}}$  is the antenna effective area. The impact of the Rx antenna on the UAV's aerodynamics is not considered here as it is beyond the scope of this paper. However, a major redesign of the aircraft could be required.

## 2.2. Selection of the 35 GHz Transmission Frequency

In point-to-point microwave power transfer, the first step is selecting a suitable frequency in the microwave band. Hence, industrial, scientific, and medical (ISM) frequency bands of 2.45 GHz, 5.8 GHz, and 24.5 GHz are recommended for MPTs [38,39]. On the other hand, the Tx antenna and Rx rectenna dimension increase with the transmitting distance. As a result, for long-distance power transmission, the dimensions of the transmitter and the receiver would be very large and costly for the ISM frequency bands. To decrease the antenna dimensions and to lower the cost, higher frequencies, i.e., 35, 61, and 94 GHz, are preferable. Among them, the 35 GHz frequency is chosen for MPT in this research. This frequency window decreases the Tx antenna and the Rx rectenna dimension while keeping a transmission efficiency in the order of more than 90% [40]. Atmospheric absorption loss is also low at this frequency window [41].

## 3. Microwave Wireless Power Transmission

There are many key issues for deploying microwave-powered UAVs. Wireless power transfer for a distance of more than 10 km is a challenging task; the Gaussian beamforming technique must be used for efficient transmission [11,42]. A 32-kW microwave UAV power flow diagram is shown in Figure 2. In this proposed system, photovoltaic arrays transform solar power into electrical power (DC). The high voltage DC power is then supplied to a microwave generator, i.e., a magnetron that delivers the transferred microwave power [43]. The beam formation is achievable using a phased array antenna [44,45]. The receiving microwave antenna connected with the rectifier changes the high-frequency microwave power back to electrical DC power [46]. In this model, a solar array is required for collecting 160 kW of solar insolation at a power density of  $1000 \text{ W/m}^2$  and produces 40 kW DC power (25% conversion efficiency). Considering a DC-to-microwave conversion efficiency of 80% [47,48], 32 kW microwave power would be transmitted from the ground Tx antenna. Here, our target is to design a suitable rectenna to power the 22-kW electrical propeller onboard the UAV.



**Figure 2.** Microwave power transmission system block diagram.

### Microwave Wireless Power Transmission Equations

Equation (2) shows the Friis' relationship for transmitted signal within the far-field Fraunhofer zone.

$$P_R = P_T G_T \left( \frac{\lambda}{4\pi D} \right)^2 G_R = \frac{A_t A_r}{\lambda^2 D^2} P_T \quad (2)$$

where  $P_T$  and  $P_R$  are transmitted and received power,  $G_T$  and  $G_R$  are the gain, and  $A_t$  and  $A_r$  are the effective surface area of the Tx antenna and Rx rectenna, respectively.  $D$  is the separation between the Tx antenna and the Rx rectenna and  $\lambda$  is the transmitted wavelength. This transmission equation is not applicable for long-distance, point-to-point power transfer because, in the Fraunhofer zone, the beam power density decreases as the square of the distance between the Tx and the Rx antennas. As a consequence, full dispersion occurs [38]. In order to obtain efficient power at the receiving antenna, a near-field zone needs to be considered, wherein the beam power density remains constant with respect to distance, and the dispersion is also negligible [11,38]. G. Goubau and W.C. Brown showed the relationship between wireless beam power transfer efficiency and beam power transmission parameter for near field conditions in Equations (3) and (4) [11,42].

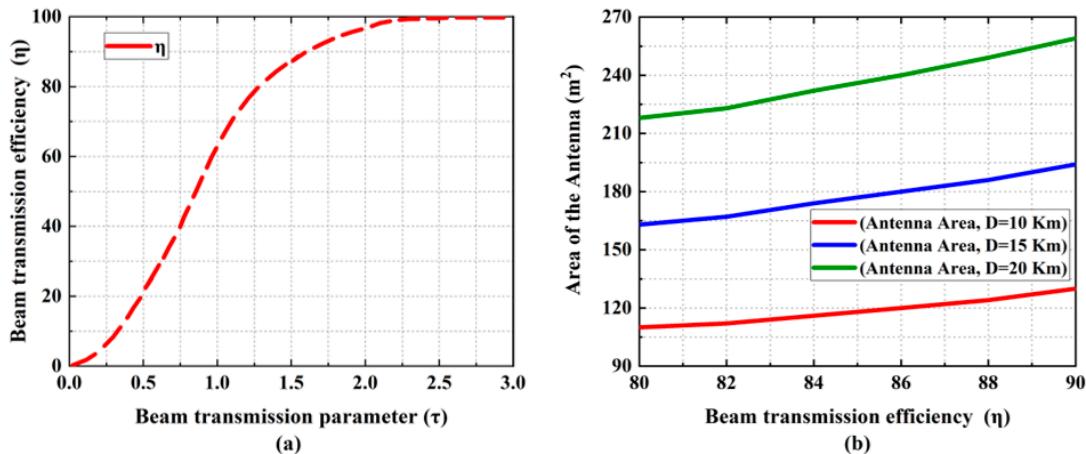
$$\frac{A_t A_r}{\lambda^2 D^2} = \tau^2 \quad (3)$$

where  $\tau$  is the beam transmission parameter.

Then, the beam transmission efficiency is given by:

$$\eta_{beam} = 1 - e^{-\tau^2} \quad (4)$$

Figure 3a shows the beam transmission efficiency as a function of the beam transmission parameter  $\tau$ . According to Figure 3a, a 100% beam transmission efficiency is achievable at a transmission parameter of 2.5 [16,17]. Figure 3b shows the Tx antenna aperture variation as a function of the beam efficiency and the transmission distance, as obtained from Equations (3) and (4). As expected, a larger antenna area is required for long-distance power transmission and higher beam transfer efficiency, assuming  $A_r A_t$ .



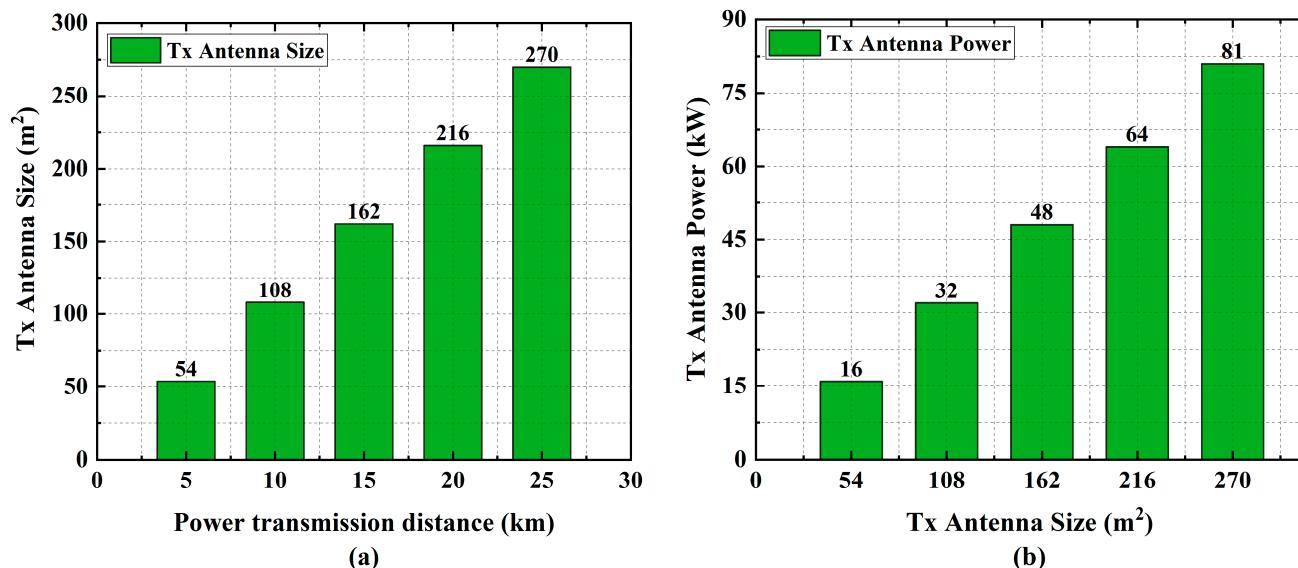
**Figure 3.** (a) Beam transmission efficiency as a function of the beam transmission parameter  $\tau$  for optimum power-density distribution across the transmitting antenna's aperture [11,38] and (b) Tx antenna aperture variation as a function of beam efficiency and transmission distance.

#### 4. Tx Antenna Area Calculation for Different Power Level

Knowing the Tx antenna dimension, it is then possible to calculate the power transmission capacity of the Tx antenna and the power receiving capacity of the Rx rectenna using Equation (1). First, the area of the Tx antenna needs to be calculated using Equations (3) and (4) and considering a 10 km transmission distance at 35 GHz signal frequency. In that case, if we consider a reasonable beam transmission efficiency of 80%, we obtain  $\tau = 1.26$ , which allows us to extract the required antennas' area ( $A_r A_t$ ), using the same calculation method as the one used of the Tx antenna size. Different power transmission distances are shown in Figure 4a. For the desired 10 km power transmission distance,  $A_r A_t = 108 \text{ m}^2$  is found, which is the minimum size required to maintain near-field conditions. The Tx antenna power capacity variation with the size is given in Figure 4b; it can be noticed here that an antenna size of  $108 \text{ m}^2$  is able to transmit 32 kW of power according to Equation (1).

Now, using Equation (1), it is possible to calculate the maximum power transmission capacity of the Tx antenna. For instance, when the Tx antenna area is  $108 \text{ m}^2$  and the beam power density is  $300 \text{ W/m}^2$  [37], given the safety and security limits, the maximum power transmission capacity of the Tx antenna is 32 kW. If the area of the antenna increases, then it can transmit more power and more distance as well, as shown in Figure 4b. The area of the selected UAV is  $90 \text{ m}^2$  and a rectenna of the same size can receive 27 kW RF power and convert it to usable DC power to feed the electric motor of the propeller.

A comparison with previous MPT work is presented in Table 1. With the advancement in microwave technology, the operating frequency can be increased for a cost-effective and highly efficient MPT system.



**Figure 4.** (a) Area of the Tx antenna with different power transmission distance considering Friis' near field equation for a beam transmission efficiency of 80%. (b) Maximum power transmission capacity of the Tx antenna with respect to the area considering a Tx antenna size of  $108 \text{ m}^2$ .

**Table 1.** Comparison of the previous MPT for various frequencies.

Source-Agency	Frequency (GHz)	Tx/Rx Diameter (m)	Transmission Power (kW)	Transmission Distance (m)	Received Power (kW)
Raytheon's Spencer Lab-1964 [15]	2.45	3	0.65	3–5	15
NASA-1975 [16]	2.45	26	5.6	320	34
SHARP-1987 [17]	2.45	85	30	500–1000	21,000
SHARP-1987 [17]	2.45	4.5	1	10	150
NICT-1995 [34]	2.45	3	3.4	5	1.9
IHI Aerospace Co., 2015 [35]	5.8	2	0.8	10	58
JAXA-2001 [37]	5.8	1000	3400	$1.3 \times 10^6$	$36 \times 10^6$
Kansai Electric Power Co., 1994 [43]	2.45	3	3.8	5	42
KAIST 2018 [49]	2.45	1	0.5	0.25	1
Sichuan University 2019 [50]	5.8	1	1	0.5	10
<b>This Work</b>	<b>35</b>	<b>11.7</b>	<b>10.7</b>	<b>32</b>	<b>10,000</b>
					<b>27</b>

## 5. Design and Simulation of Microstrip Patch Antenna Array

A high gain and high directivity antenna is required for MPT applications. Moreover, an array of antennas has more gain and directivity compared to a single antenna. Therefore, an array of patch antennas is selected for the project. Patch antennas have excellent radiation characteristics and are easier to design and fabricate. In addition, they are light in weight, compact, have a low fabrication cost, and have small dimensions.

### 5.1. 4 × 2 Patch Antenna Array Design

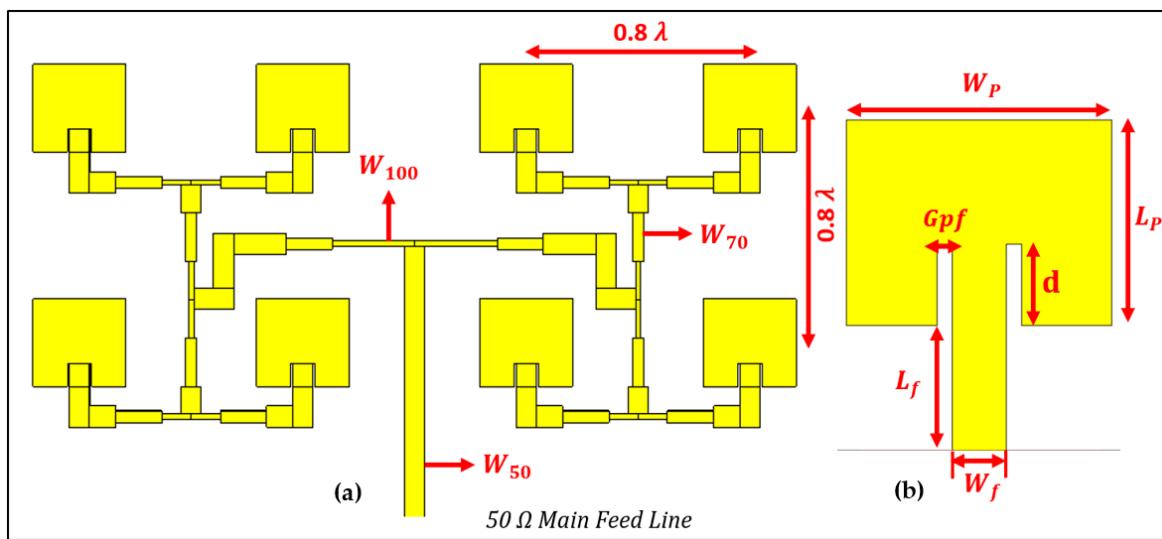
The geometry of the proposed  $4 \times 2$  patch antenna array is shown in Figure 5. The proposed antenna is designed on a RT-Duroid substrate with a thickness of 0.254 mm, a dielectric constant of 2.2, and a loss tangent of 0.0004 to 0.0009. Copper is selected as the top and bottom conductor layers because of its low cost and high conductivity. The copper thickness is 0.0035 mm. The bottom conductor can work either as an RF ground or a reflection plane.

The design and simulation of the microstrip patch antenna array are carried out using the corporate feed network since the incident power can be distributed equally to each antenna element from a single power port. The  $4 \times 2$  microstrip patch antenna arrays are designed and optimized with the software tool CST Studio Suite.

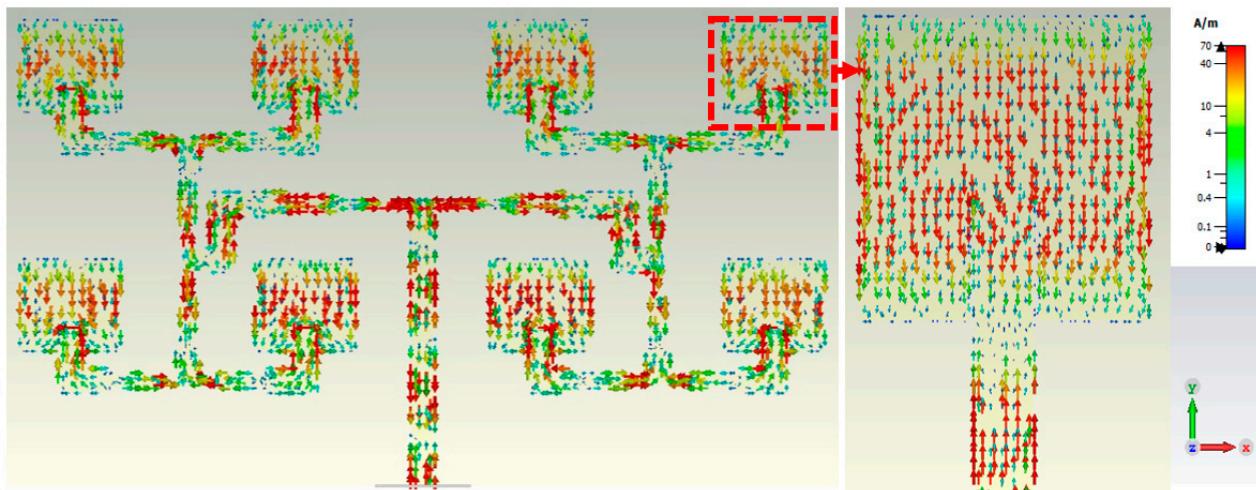
### 5.2. Results and Discussion

At 35 GHz, the surface current flow of a  $4 \times 2$  patch antenna array is shown in Figure 6. The designed antenna is linearly polarized and found to be suitable for point-to-point power transfer. The return loss of the designed patch antenna array is shown in Figure 7a. This antenna resonates well at a desired 35 GHz center frequency with a reflection coefficient value of  $-33$  dB. The bandwidth of the antenna at  $-10$  dB is 0.7 GHz. The ratio of maximum and a minimum standing wave is called VSWR. Figure 7b shows a VSWR of 1.06 at the center frequency of 35 GHz. Hence, the designed  $4 \times 2$  patch antenna array can transfer high power.

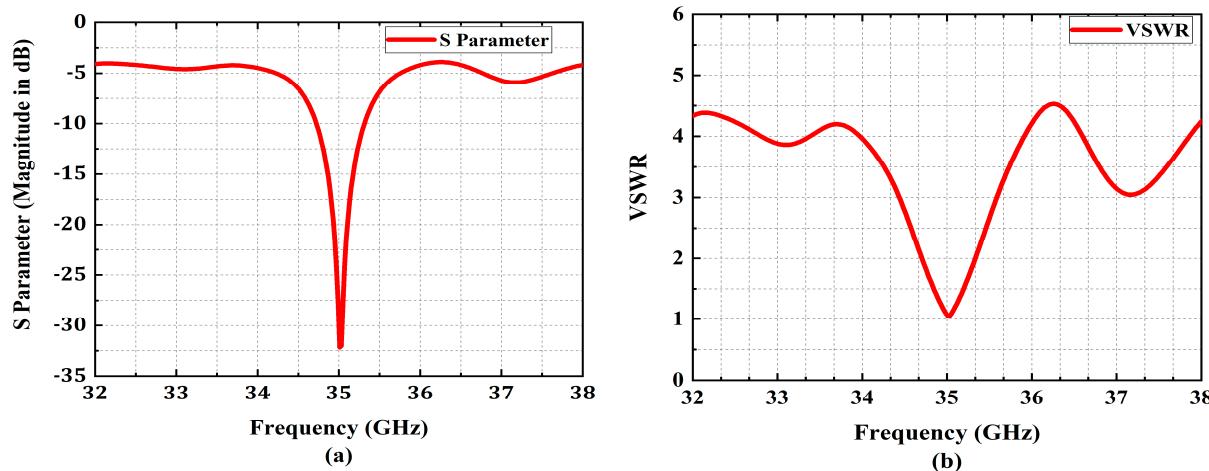
Figure 8a shows the radiation pattern of the  $4 \times 2$  antenna array. The intensity of the color corresponds to the energy level. The maximum energy is passing through the main lobe, and it has the highest gain and directivity. Figure 8b shows the 2D polar plot of the radiation diagram. The gain and directivity at 0 degree of the  $4 \times 2$  antenna are 13.4 dBi and 14 dBi respectively, whereas the side lobes are less than  $-11$  dBi. Hence, we can claim that the designed  $4 \times 2$  antenna array has satisfactory features for an MPT. The designed  $4 \times 2$  microstrip patch antenna array has an efficiency of 85%, as shown in Figure 9.



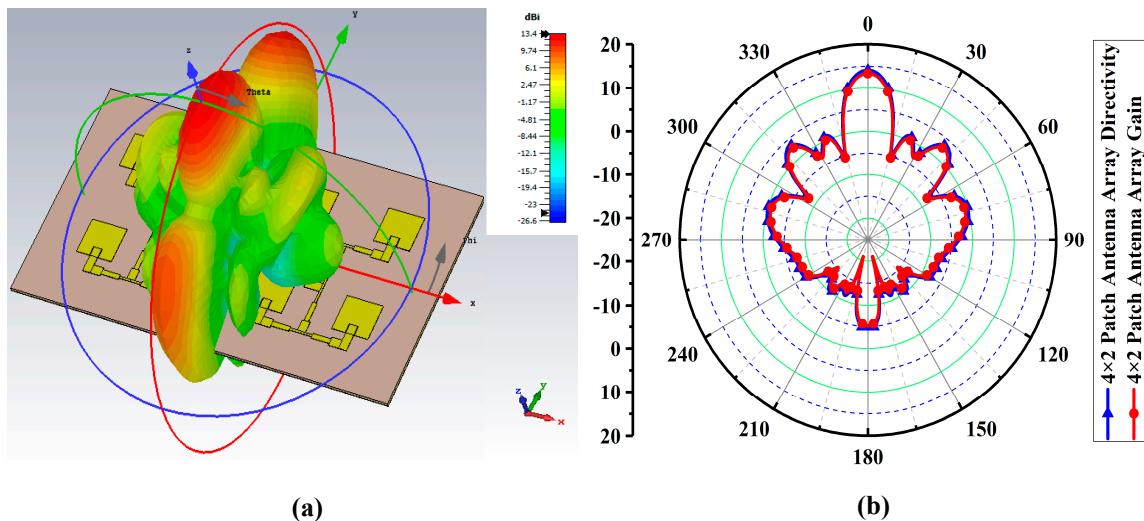
**Figure 5.** (a) Illustration of antenna elements with  $0.8 \lambda$  horizontal and  $0.8 \lambda$  vertical spacing in a  $4 \times 2$  patch antenna array with corporate feed, widths of  $50 \Omega$  ( $W_{50}$ ),  $70.71 \Omega$  ( $W_{70,71}$ ) and  $100 \Omega$  ( $W_{100}$ ) transmission lines are  $0.8$  mm,  $0.45$  mm, and  $0.25$  mm, respectively. (b) Unit element antenna parameter are:  $W_p = 3.4$  mm,  $L_p = 2.7$  mm,  $W_f = 0.8$  mm,  $L_f = 1.6$  mm,  $d = 1.07$  mm and  $Gpf = 0.1$  mm.



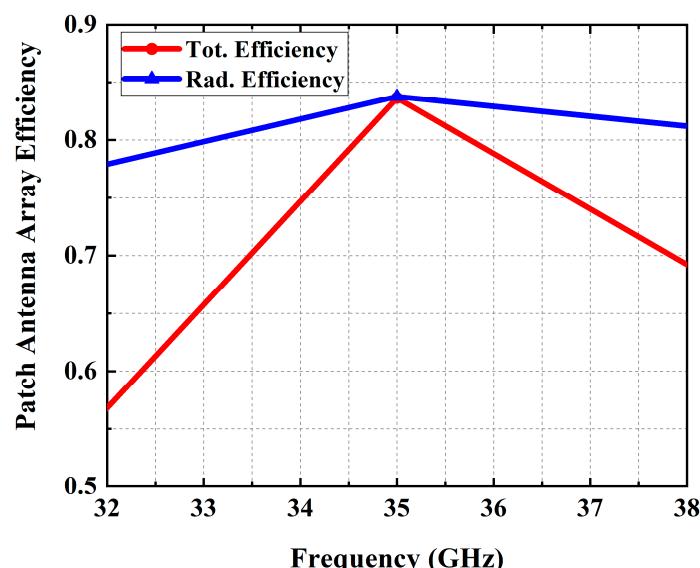
**Figure 6.** Surface currents plot of the  $4 \times 2$  patch antenna array at  $35$  GHz.



**Figure 7.** (a) Return loss and (b) voltage standing wave ratio (VSWR) of a  $4 \times 2$  patch antenna array.



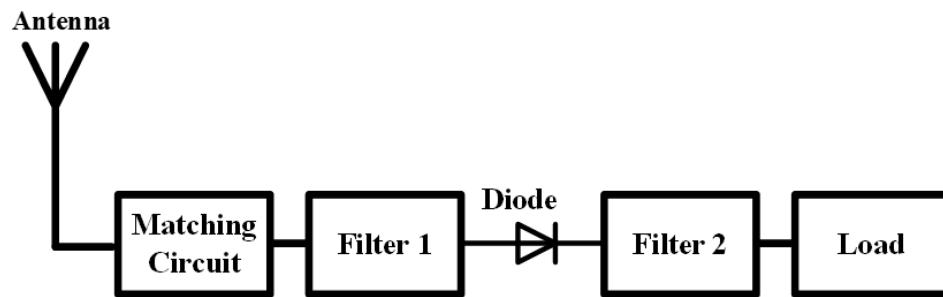
**Figure 8.** Radiation pattern of the proposed patch antenna array (a) 3D view of a  $4 \times 2$  array and (b) 2D polar view of a  $4 \times 2$  array.



**Figure 9.** Efficiency of  $4 \times 2$  patch antenna array.

## 6. Design and Optimization of Rectifying Circuit

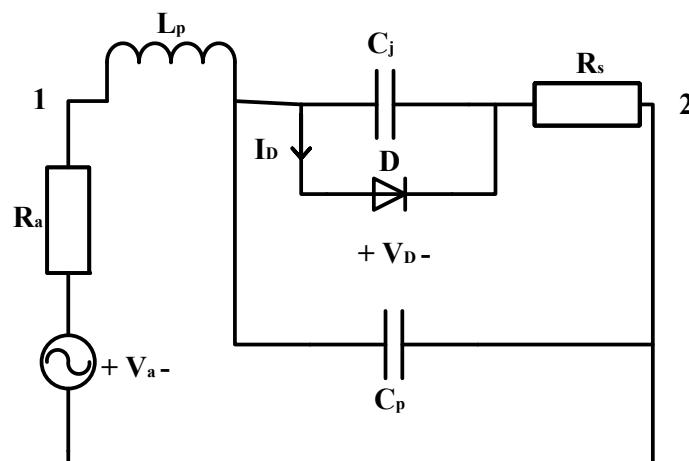
A rectenna typically consists of an antenna, a diode, a matching circuit, and a resistive load ( $R_L$ ) connected to the end of the circuit to collect the DC power, as shown in Figure 10. It has various topologies based on the diode orientation such as series [51–53], shunt [54,55], voltage doubler, and bridge rectifier [56,57]. A voltage doubler rectifier topology is selected for this project in order to achieve a higher RF to DC conversion efficiency.



**Figure 10.** Block diagram of conventional rectenna.

### 6.1. Equivalent Circuit Model of a Schottky Diode

The Schottky diode is a nonlinear device, as proved analytically in [58–60] and verified in [61,62]. The circuit analysis presented in [61] is a standard technique that is quick, precise, and reliable for calculating the input impedance of the packaged Schottky diode as a function of the operating frequency and input power levels. The Schottky diode equivalent circuit model is shown in Figure 11. Here,  $C_j$  is the junction capacitance, and  $C_p$  and  $L_p$  are the parasitic packaging capacitance and inductance, respectively.  $D$  is the ideal diode,  $V_a$  is an RF voltage source, and  $R_a$  is the internal resistance of the source and series resistance  $R_s$ .



**Figure 11.** Simplified circuit model of a diode [58–63].

In Figure 11, Kirchhoff's current and voltage laws are used to determine the voltage  $V_D$  and current  $I_D$  across the diode  $D$ . These found values are further used to determine the impedance of the rectifier. A voltage source with a single frequency  $f_0$  as input,  $V_a = |V_a| \cos(2\pi f_0 t)$ , is used as shown in Figure 11. The electrical behavior of this circuit can be described with the following expressions, found by applying Kirchhoff's relations:

$$V_a = I_a R_a + L_p \frac{\partial I_a}{\partial t} + V_{C_p} \quad (5)$$

$$V_{C_p} = V_D + V_{R_s} \quad (6)$$

$$V_{R_s} = R_s (I_{C_j} + I_D) \quad (7)$$

$$I_{C_j} = C_j \frac{\partial V_D}{\partial t} \quad (8)$$

$$I_D = I_s (e^{\alpha V_D} - 1) \quad (9)$$

so that,

$$\frac{\partial V_D}{\partial t} = \frac{1}{R_s C_j} \left\{ \psi \left( \frac{\partial I_a}{\partial t} \right) - R_s I_s (e^{\alpha V_D} - 1) \right\} \quad (10)$$

where,

$$\psi \left( \frac{\partial I_a}{\partial t} \right) = V_a - R_a I_a - V_D - L_p \frac{\partial I_a}{\partial t}, \alpha = \frac{q}{nKT}$$

$\frac{q}{KT}$  is the thermal voltage and  $n$  is the ideality factor. The above differential Equation (10) has been solved with the fourth-order Runge–Kutta method and the voltage  $V_D$  across the diode,  $D$ , is calculated. Furthermore, Equation (9) is used to determine the current  $I_D$  flowing through the diode. After the evaluation of  $V_D$  and  $I_D$ , the input impedance of the diode  $D$  is found using Ohm's law:

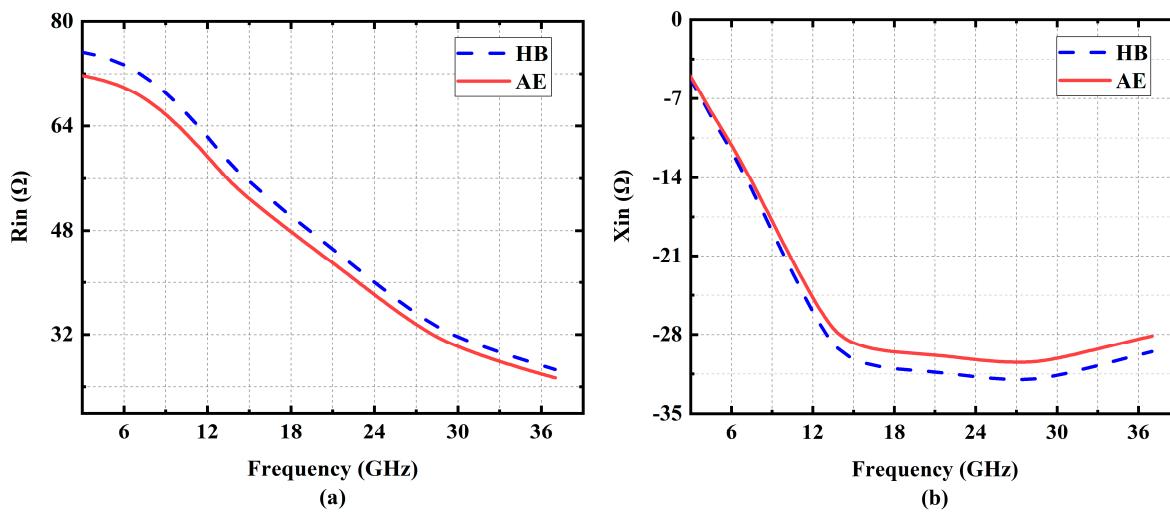
$$Z_D = \frac{V_D}{I_D} \quad (11)$$

#### Harmonic Balance (HB) Simulation Validation

The Spice model parameters of the MA4E1317 diode are found in [59,63], where the ideality factor  $N = 1.5$ , the grading coefficient  $M = 0.5$ , the saturation current  $I_s = 100 \text{ nA}$ , the series resistance  $R_s = 4 \Omega$ , the junction capacitance  $C_{jo} = 0.02 \text{ pF}$ , the parasitic capacitance  $C_p = 0.025 \text{ pF}$ , parasitic inductance  $L_p = 0.05 \text{ nH}$ , the reverse breakdown voltage  $V_{br} = 7 \text{ V}$ , and the forward voltage  $V_f = 0.6 \text{ V}$ , at forward current  $I_f = 1 \text{ mA}$ . Using the values of Spice parameters, the input impedance of the Schottky diode  $Z_{in}$  including its series resistance and packaging parasitics is calculated. To verify the accuracy of the equivalent circuit model, the Schottky diode MA4E1317 ADS harmonic balance simulation model will be compared. The input impedance versus frequency for different power levels is calculated with the aid of the equivalent circuit model and is compared with harmonic balance simulation results.

Figure 12a,b shows the impedance of the rectifier as calculated by using ADS harmonic balance simulations and the presented analytical expressions (AE). Figure 12 also shows the real and imaginary parts of the input impedance versus frequency at an input power level of 10 dBm.

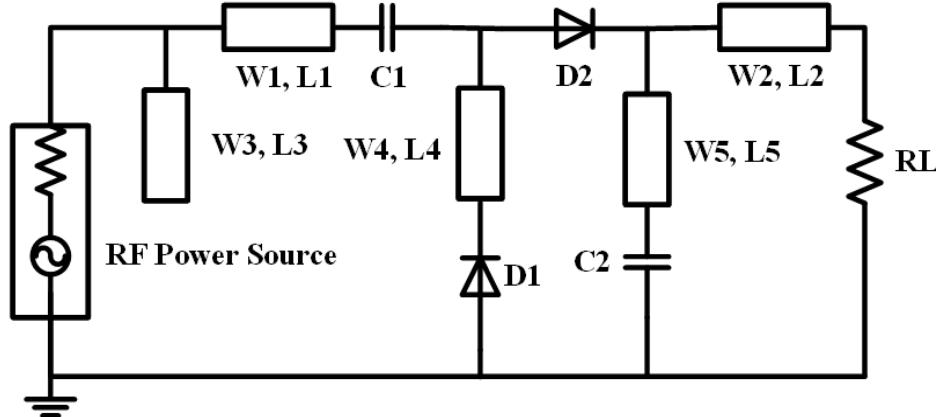
It is shown in Figure 12 that the equivalent circuit model can predict the impedance of the rectifier with a relative difference of less than 10% for the real and imaginary parts of the input impedance. The input impedance is again calculated using ADS harmonic balance simulations and the equivalent circuit model. It is shown in the figures that the results of the analytical equations are matching the results obtained using harmonic balance simulations.



**Figure 12.** Real and imaginary parts of the input impedance of the Schottky diode MA4E1317 versus frequency for a maximum available power level of 10 dBm calculated using the analytical equation (AE) and harmonic balance (HB) simulations.  $R_a = 50 \Omega$ , (a) Real impedance as a function of frequency, (b) Imaginary impedance as a function of frequency.

### 6.2. Rectifying Circuit Configuration

The geometrical structure of the proposed rectifying circuit operating at 35 GHz is shown in Figure 13. The rectifying circuit is designed on RT-Duroid substrate thickness of 0.254 mm, a relative dielectric constant of 2.2, and a loss tangent of 0.0004 to 0.0009.

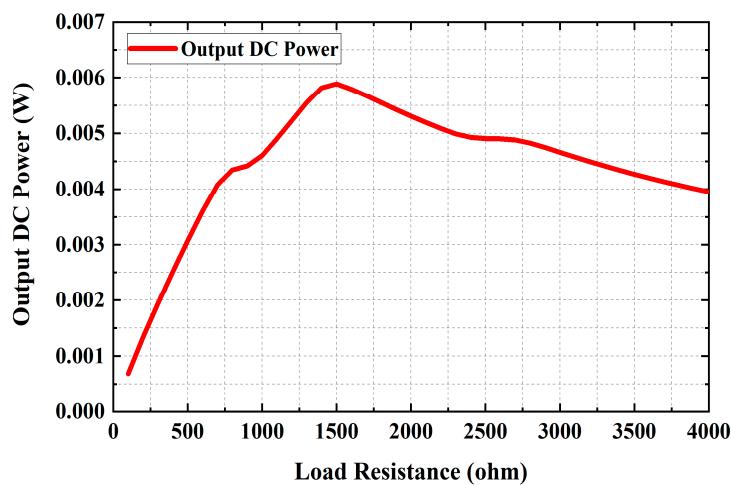


**Figure 13.** Circuit configuration of the proposed rectenna. The parameters are  $L_1 = L_2 = 1.57$  mm,  $L_3 = 0.97$  mm,  $L_4 = 0.37$  mm,  $L_5 = 0.34$  mm,  $W_1 = W_2 = W_3 = 0.776$  mm,  $W_4 = 0.3$  mm,  $W_5 = 0.28$  mm,  $C_1 = C_2 = 100$  pF, and  $R_L = 1500 \Omega$ .

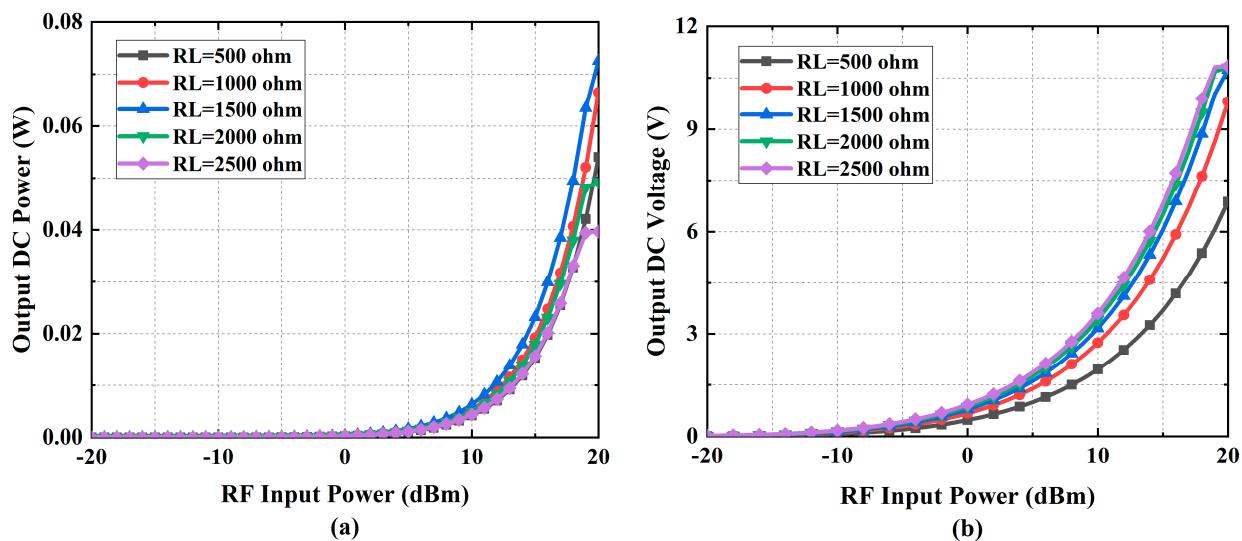
The rectifying nonlinear circuit simulation is performed in Advance Design System (ADS) Harmonics Balance (HB) simulator. A 10 dBm input RF power was considered for the simulation. The circuit parameters are first calculated, and then the software ADS Optim toolbox with optimization-type genetic and iteration 500 can be utilized to optimize those parameters. After optimization, the parameters found are given in the Figure 13 caption.

### 6.3. Results and Discussion

The output DC power changing across the different load resistors is shown in Figure 14. The maximum output DC power is obtained at  $1500 \Omega$ . Figure 15 exhibits the DC output power (a) and voltage (b) as a function of the input RF power with different load resistances ( $R_L$ ). At the desired input power of 10 dBm, a maximum 0.0065 W DC power and 3.1 V are achieved with an operating frequency of 35 GHz across the  $1500 \Omega$  load resistance.



**Figure 14.** Output power variation with different values of load resistance.

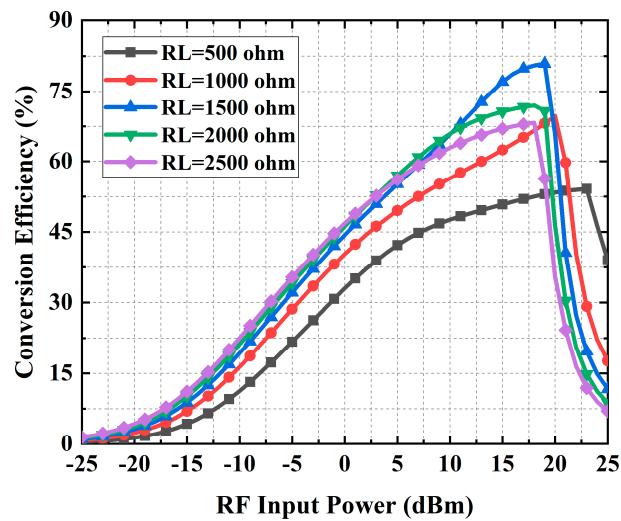


**Figure 15.** (a) Output DC power and (b) Output DC voltage as a function of the input power for different load resistance.

Figure 16 shows the RF-to-DC conversion efficiency with various load resistances and different RF input power levels at the selected 35 GHz frequency. The figure depicts that the maximum efficiency of 82% is observed at 19 dBm input power with a  $1500\ \Omega$  load resistance, whereas, at our desired power level of 10 dBm, an efficiency of 65% is achieved. However, the maximum efficiency was expected to be at 10 dBm input power; the reason behind this undesired behavior might be the impedance mismatch between the source power and the rectifier circuit. The RF-to-DC conversion efficiency of the rectenna can be determined using the following equation:

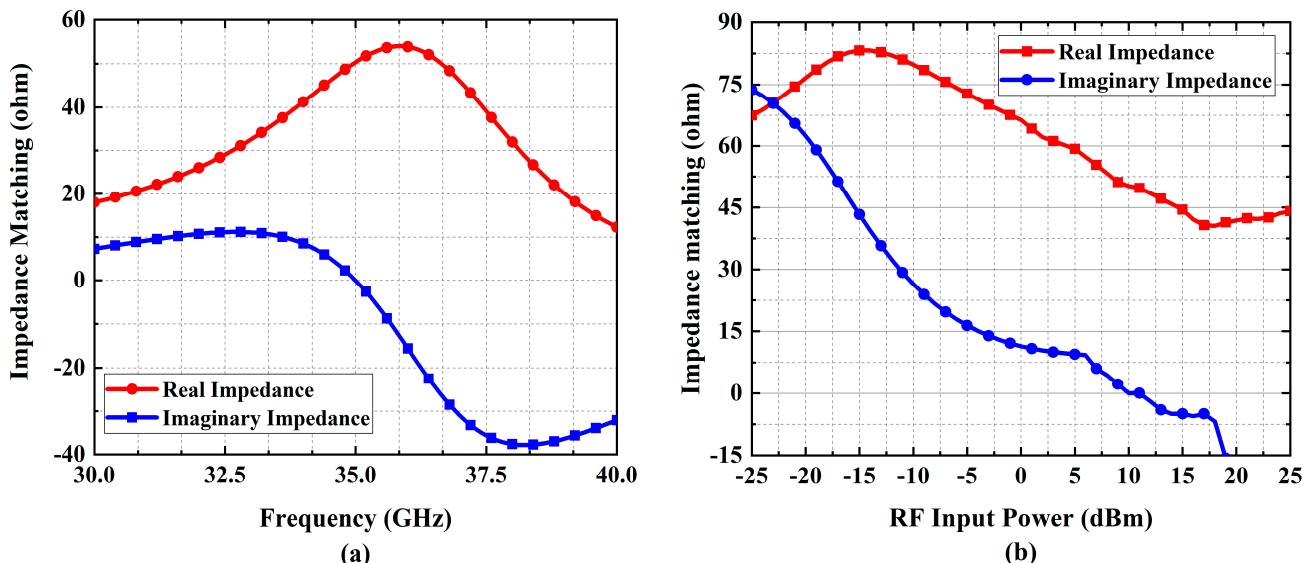
$$\eta = \frac{V_{out}^2}{P_{in} R_L} \times 100\% \quad (12)$$

where  $V_{out}$  is the output DC voltage,  $R_L$  is the load resistance, and  $P_{in}$  is the input RF power.



**Figure 16.** Conversion efficiency of the designed rectenna as a function of the input power for different load resistance.

The ADS Smith chart tool is then utilized to match the impedance at 35 GHz frequency with 10 dBm input power. The source power impedance is  $50\ \Omega$  and the rectifier impedance can be determined by the commercial software ADS [64–66]. The rectifier input impedance's real and imaginary value variation with frequency (GHz) and input power (dBm) are provided in Figure 17a,b, respectively. The impedance is matched to a  $50\ \Omega$  load at the selected 35 GHz frequency.



**Figure 17.** Rectifier circuit impedance matching (a) variation with frequency and (b) variation with input power.

After impedance matching (IM), the output DC power and voltage are improved; consequently, the RF-to-DC conversion efficiency is also improved. A comparison between the proposed rectenna with and without impedance matching is presented in Figure 18. The rectenna without IM has a maximum efficiency of 82% at 19 dBm. The proposed rectenna has a plateau in the efficiency curve at an RF input power range of 9 to 18 dBm, and the average efficiency is greater than 80% in that range. Table 2 compares the efficiency of the proposed rectenna with related works. The reported 80% is higher than all other identified prior works.

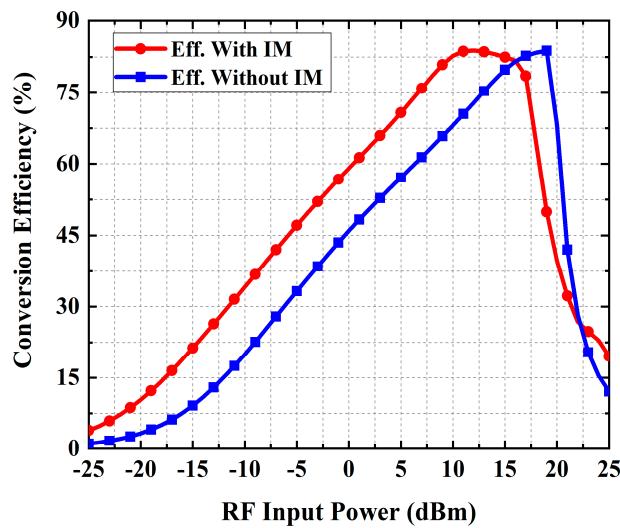


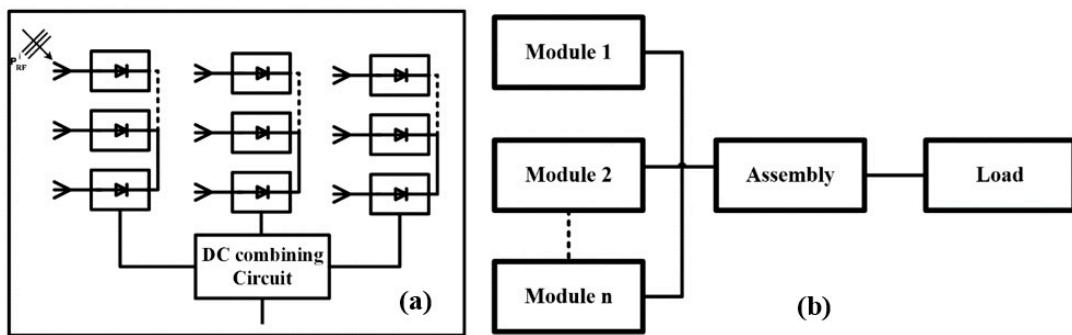
Figure 18. Conversion efficiency as a function of the RF input power.

Table 2. Efficiency comparison of various rectennas.

Source	Frequency (GHz)	Results	Rectifier Element	RF Power Level for Maximum Efficiency (dBm)	Maximum Efficiency (%)
Chiou H. et al. [32]	94	Experiment	0.13-mm CMOS	20	37
Ladan S. et al. [46]	35	Experiment	Schottky MA4E1317	13	34
Ladan S. et al. [63]	24	Simulation	Schottky MA4E1317	12	78
Awais Q. et al. [67]	2.45	Experiment	Schottky HSMS 2850	5	68
Zhang Q.Q. et al. [68]	5.8	Experiment	Schottky BAT15-03W	8.2	69
Shinohara N. et al. [69]	24	Experiment	Schottky MADS-01317	21	54
Mavaddat A. et al. [70]	35	Experiment	Schottky MA4E1317	8.5	67
Chen Q. et al. [71]	35	Experiment	Schottky Diode	19	68.5
This Work	35	Simulation	Schottky MA4E1317	9–18	80

#### 6.4. Large Area Power Collection

This work considers an onboard rectenna that could benefit from mass production, easy interconnections, and integration with power electronics circuitry. The power capacity of a single rectenna is low; therefore, to fulfill the high power demand, there is a requirement for series and parallel combinations. In previous works [72,73], it has been shown that series connection offer more power losses than parallel connections, so optimum connection of series/parallel is required for maximum power transfer; otherwise, losses will be high and will contribute to heating issues. Additionally, supplying maximum power for battery charging of the UAV is a challenging task. It is due to the fact that energy storage units such as rechargeable batteries or supercapacitors do not have the voltage/current characteristics of a resistor. This problem can be solved by using a cost-effective and efficient resistance emulation technique as proposed in [74]. First, a module will be developed with optimum rectenna array connection and integrated power circuitry. To determine the optimum module size, power simulation, thermal modeling and simulation will be performed. ADS has an integrated circuit and EM solver (co-simulation) and thermal solver (path-wave) that can be found suitable to determine the optimum module size. The onboard design will be assembled to form a module. Furthermore, these modules combine power and form an assembly to supply the maximum power to the load, as shown in Figure 19.



**Figure 19.** Schematics of the investigated rectenna array configurations. P is the incident RF power on the antennas. Rectenna module consists of optimum series-parallel connections with (a) DC combining circuit (b) power delivery.

The designed  $4 \times 2$  antenna is directly attached to a rectifier circuit in a single rectenna. The effective area of the designed  $4 \times 2$  antenna is  $0.000128 \text{ m}^2$ , which can transmit or receive  $38.4 \text{ mW}$  for RF power at a density of  $300 \text{ W/m}^2$  according to Equation (1). A suitable combination of 74,000 rectenna elements can effectively feed a  $22 \text{ kW}$  electrical engine, assuming, a rectenna RF-DC conversion efficiency of 80% and an array efficiency of 85%.

According to our system described in Section 2, an Rx antenna area of  $90 \text{ m}^2$  can accommodate 74,000 rectenna elements. The UAV is handling high power that is wirelessly transmitted via microwave while maintaining a lower operating temperature has proven effective in preventing power loss as well as component degradation. The thermal problem can be countered by applying a suitable cooling method, and then the thermal management systems are analyzed in [75].

## 7. Conclusions

The concept of efficiently transmitting  $22 \text{ kW}$  of DC power to a UAV using microwave over a distance of 10 km has been presented. The underlying system architecture of UAVs is based on a  $35 \text{ GHz}$  microwave signal that allows reducing the antenna size while keeping a high transfer efficiency over long distances. An array of microstrip patch antennas is adopted for the transmitting system. It is composed of  $4 \times 2$  rectangular microstrip patches that have been optimized using a CST tool. The numerically simulated gain, directivity, and efficiency of the proposed  $4 \times 2$  microstrip patch antenna are  $13.4 \text{ dBi}$ ,  $14 \text{ dBi}$ , and 85%, respectively. The optimized value of Tx areas and beam efficiency are, respectively,  $108 \text{ m}^2$  and 80% to transmit microwave power efficiently at a frequency of  $35 \text{ GHz}$ . Finally, to receive the microwave power, the Rx areas are optimized to  $90 \text{ m}^2$  and a rectenna is designed employing the Agilent advanced design system (ADS) software. The proposed rectenna has an efficiency of over 80% for an RF input power range of 9 to  $18 \text{ dBm}$  and a DC output voltage of  $3.5 \text{ V}$  for a  $10 \text{ dBm}$  input power at  $35 \text{ GHz}$ , feeding a load of  $1500 \Omega$ .

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