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A New Dynamic Model to Predict Transient and Steady State PV Temperatures Taking into Account the Environmental Conditions

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Abstract: Photovoltaic (PV) cell and module temperature profiles, T_c and T_{pv} , respectively, developed under solar irradiance were predicted and measured both at transient and steady state conditions. The predicted and measured T_c or T_{pv} covered both a bare c-Si PV cell, by SOLARTEC, at laboratory conditions using a solar light simulator, as well as various c-Si and pc-Si modules (SM55, Bioenergy 195W, Energy Solutions 125W) operating in field conditions. The time constants, τ , of the T_c and T_{pv} profiles were determined by the proposed model and calculated using the experimentally obtained profiles for both the bare PV cell and PV modules. For model validation, the predicted steady state and transient temperature profiles were compared with experimental ones and also with those generated from other models. The effect of the ambient temperature, T_a , wind speed, v_w , and the solar irradiance, I_T , on the model performance, as well as of the mounting geometries, was investigated and incorporated in the prediction model. The predicted temperatures had the best matching to the measured ones in comparison to those from six other models. The model developed is applicable to any geographical site and environmental conditions.

Keywords: PV cell temperature; transient profiles; time constant; steady state; wind velocity; environmental effects

1. Introduction

The photovoltaic (PV) temperature is a significant factor which affects the PV module performance through its effect on the PV cell electric characteristics, analytically presented in PV cell textbooks. Correspondingly, we speak about the PV module temperature, T_{pv} , and the PV cell temperature, T_c , which are equal provided the cells of the module are healthy and experience the same environmental conditions. It is of much interest to develop reliable models to predict T_{pv} , and the PV performance, through prediction of the power output $P_m(t)$, when the module operates under any configuration and field conditions. Various mathematical expressions have been proposed and validated on their reliability to predict steady state T_{pv} [1–9], as to be discussed in detail later in this paper or transient T_{pv} profiles, [10–14] with good accuracy under any field conditions and for Building Integrated Photovoltaic (BIPV) configurations [15–19]. Those T_{pv} prediction models are grouped in: explicit models described in [1–7], usually physics based theoretical models which try to incorporate the environmental parameters, mainly, solar irradiance on the PV plane I_T , wind velocity v_w , wind direction, heat transfer from the PV to the environment, and radiation exchanges between PV and environment:

a. Implicit models which use various algorithms and regression analysis to produce formulae to predict T_{pv} through quantities which depend on T_{pv} , as reviewed in [3,20].

b. Theoretical based semi-empirical models, a mixture of Physics based processes elaborated on implicit functions, which through regression analysis incorporate the environmental conditions and develop expressions to predict T_{pv} including geometrical factors like PV module inclination, sun-tracking systems, BIPV [6,8,21].

c. Approaches based on Artificial Neural Networks (ANN) [5,10,22].

An assessment of the T_{pv} prediction models discloses that those which have incorporated the radiation exchanges and the air flow regimes, where heat extraction off the modules is affected specifically, provide values closer to the measured ones [6,7,23–25]. A comparison among the models is necessary as to conclude on the conditions T_{pv} is predicted effectively and consistently. It is, therefore, necessary to compare T_{pv} models extensively to examine their validity in any PV configuration as the ones studied in [20,26–29].

A time dependent temperature profile is developed in a PV cell when under solar irradiance, I_T , [8,30]. The latter is the main factor contributing to the development of the temperature profile in which the ambient temperature T_a and the wind speed play a role too. This profile has a straight relationship with I_T at low Concentration Ratio, C, conditions, with C < 4, where $C = I_T/10^3 \ W/m^2$, and a strong dependence on the wind speed, v_w ; that is, $T_c(t; I_T, v_w)$. $T_c(t)$ depends, also, on the cell structure and the material composition of its layers. Figure 1 shows a section of a PV cell with its characteristic layers which govern the heat conduction causing an effect on the time constant, τ , of the temperature profiles. $T_c(t)$ or $T_{pv}(t)$, either the PV module is heated or cooled due to changes in the environmental conditions, is described through an exponential term, $exp(-t/\tau)$, as discussed in Sections 2 and 3.

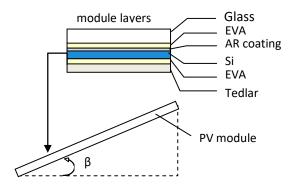


Figure 1. A schematic section of a photovoltaic (PV) module with its characteristic layers. EVA: Ethylene-vinyl Acetate, ARC: Anti-reflective Coating.

The PV cell electric characteristics, short circuit current I_{sc} , open circuit voltage V_{oc} depend on $T_c(t)$ and on I_T according to (1) and (2). The prediction of $T_c(t)$ by the model analytically outlined in this paper and the equations below [1,11], may lead to an excellent $V_{oc}(t)$ and $I_{sc}(t)$ profile prediction under any operating conditions.

$$V_{oc}(I_T, T_c) = V_{oc}(I_{T,ref}, T_{c,ref}) + \frac{n \cdot k}{q} \cdot T_c \cdot (lnI_T - lnI_{T,ref}) + \frac{dV_{oc}}{dT_c} (T_c - T_{c,ref})$$
 (1)

$$I_{sc}(I_{T},T_{c}) = \frac{I_{T}}{I_{T,ref}}I_{ph}(I_{T,ref},T_{c,ref}) - I_{o}\bigg(exp\bigg(\frac{I_{sc}(I_{T},T_{c})\cdot R_{s}}{n\cdot k\cdot T_{c}/q}\bigg) - 1\bigg) - \frac{I_{sc}(I_{T},T_{c})\cdot R_{s}}{R_{sh}} \tag{2}$$

Equation (1) has a form outlined in more detail in [1] and explains the $V_{oc}(t)$ vs. T_c behavior from the very early stage of the transient profile, where it is not a straight line. The fact that $T_c(t)$ is affected by v_w , may be used as simple recover agent for both I_{sc} , V_{oc} and P_m . The degree of the T_c effect depends indirectly on the PV cell size, especially as I_T increases, [31]. This is related to the module internal resistance, R_s and thus due to Joule effect P_m decreases as I_T increases, beyond a critical value.

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To reduce the deviations between predicted and measured values of the PV power output $P_m(t)$, it is necessary that the model provides accurate $T_c(t)$ results. This is the objective of this research project whose final outcome is a formula built on theoretical background and regression analysis and predicts T_{pv} under any environmental conditions. The predicted T_{pv} values provide the correction required for an accurate estimation of the PV power output which is necessary for online monitoring, control and diagnostic purposes in PV installations.

2. Tpv Prediction Models for Steady State and Transient Conditions

 $T_c(t)$ or $T_{pv}(t)$ may be obtained theoretically by building the Energy Balance Equation (EBE) for any PV cell or module with conversion efficiency η_c and incident solar radiation I_T . A fraction $\eta_c I_T dt$ of the intensity of the global solar radiation on the cell is converted into electricity, while the rest $(1 - \eta_c)I_Tdt$ is converted into heat, assuming a negligible reflection. The heat propagates to both sides front and back, whereof it is transferred to the environment by convection, with coefficients $h_{c,f}$ and h_{c,b} for the front and back side, respectively, and by infrared (IR) radiated heat with coefficients $h_{r,f}$ and $h_{r,b}$ for the front and back side respectively. The coefficients $h_{c,f}$, $h_{c,b}$, $h_{r,f}$, and $h_{r,b}$ depend on the surface conditions, geometry and the thermal and environmental conditions that the PV cell operates. Therefore, all possible factors related to the mode of heat transfer from the cell surface to the environment must be considered, either it is natural flow, forced flow, or mixed; the type of the air flow, laminar or turbulent; also, the wind velocity and its angle of incidence relative to the PV cell plane. The formulae to estimate the coefficients $h_{r,f}$, $h_{r,b}$, $h_{c,f}$ and $h_{c,b}$ for any of the above conditions are elaborated and discussed critically in [23,32–34]. Typical values of the physico-thermal properties of the cell components with their usual dimensions are provided in Table 1 which was developed based on data from [17,35,36]. These data are required to estimate the resistance due to conduction within the cell, the mass heat capacity (mc), and the $T_c(t)$ or $T_{pv}(t)$ time constant, τ .

Table 1. Characteristic, average values of the thickness δx , conductivity k, density ρ , specific heat capacity c_p , mass heat capacity mc and thermal resistance R_k normalised to surface area, for the PV cell components.

Material	δx (m)	K (W/mK)	ρ (kg/m ³)	c _p (J/kgK)	$(mc = \rho c_p A_c \delta x)/A_c$ (J/Km^2)	$R_{k} = \delta x/kA_{c}$ (K/W)
Glass *	0.003-0.004	1.0-1.4	2500-3000	500	4500	3×10^{-3}
ARC	100×10^{-9}	32	2400	691	0.165	3.13×10^{-9}
EVA	250×10^{-6}	0.35	960	2090	502	714×10^{-6}
Cell	225×10^{-6}	148	2330	677	355	1.52×10^{-6}
EVA	250×10^{-6}	0.35	960	2090	502	714×10^{-6}
Tedlar **	0.0001	0.2	1200	1000-1760	150	5×10^{-4}

^{*} Glass c_p ranges from 600–750 J/kgK based on its composition; ** Tedlar/PET/Tedlar (TPT) or Tedlar/PET/Ethylen primer (TPE), surface density 380–480 g/m², thickness = 0.3–0.4 mm, Tedlar c_p = 1760 J/kgK for UV screening glass. The c_p of TPT or TPE is almost the same as of the Tedlar.

Figure 2 shows the coefficient $f = f(t; I_T, v_w)$ given by Equations (3) and (4) vs. the hour in a mid-day of March with v_w and I_T as parameters, determined both for the fixed inclination (FIX) and double-axis sun tracking (ST) PV systems. Coefficient f and T_{pv} are given by the expressions, [12,21,37].

$$T_{pv} = T_a + fI_T \tag{3}$$

$$F = [(\tau \alpha) - \eta_c]/[U_f + U_b]$$
(4)

The strong effect of v_w on f is shown in Figure 2 where for an increase in v_w from 1 to 3.3 m/s, f decreases by 28.5% in the ST to 46.6% in the FIX. In absolute values, f changed by 0.01 for the ST and 0.02 m²K/W for FIX. Based on these results and Equation (3), the T_{pv} generally follows the f profile. The heat losses coefficients from the front and back PV sides, U_f and U_b respectively are represented by U_{g-a} and U_{b-a} respectively according to:

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$$U_{g-a} = h_{c,f} + h_{r,f} (5)$$

$$U_{b-a} = h_{c,b} + h_{r,b} (6)$$

The PV module temperature in the front side, T_g , is generally higher than T_b at the back at steady state conditions by 2–3 °C [16]. However, this figure may not be taken for granted and might be even reversed as it depends on the PV cell structural details, the specific heat capacity of each one of the cell components, their thickness, conductivity, and emissivity coefficients ε_g and ε_b of the PV glass cover and backsheet respectively, as well as the v_w along with its angle of incidence on the module, either windward or leeward [23].

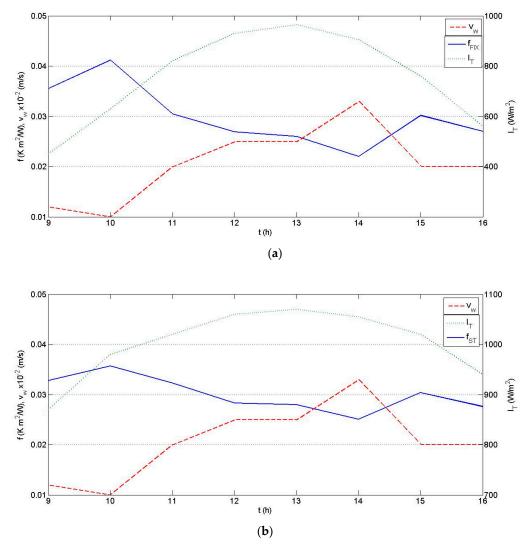


Figure 2. f versus t as determined for the mid-day of March with parameters v_w and I_T . The strong impact of v_w on f is obvious. (a) Corresponds to the FIX PV system and (b) to the sun tracking (ST) one.

2.1. Steady State T_{pv} Prediction Models

The steady state T_{pv} or T_c may be estimated by using formulas derived in this work and others proposed in [1–7]. Usually, there is no discrimination between T_c with the T_f or T_g and the T_b , which stand for the cell, glass, and back cover PV temperatures, respectively. Those temperatures will be analytically determined by the model proposed in Section 2.2. They differ to each other depending on the PV cell structure, PV cell type, the thermo-physical properties and the mounting e.g., for Building Adapted Photovoltaics (BAPV), PV thermal (PV/T) [37–41].

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Various Formulae for the T_{pv} Prediction at Steady State Conditions:

$$T_{pv} = T_a + f(v_w; \eta_{pv})I_T$$
(7)

f may be expressed as a function of v_w , and $\delta \eta_{pv}$ according to the model proposed, Equations (8)–(10),

$$f = f(v_w; \eta_{pv}) = f(v_w)(1 - \delta \eta_{pv}/(1 - \eta_{pv,m}))$$
(8)

 $\delta\eta_{pv}=\eta_{pv}-\eta_{pv,m}$ where, $\eta_{pv,m}$ is the PV efficiency at the average conditions, ($T_a=20^{\circ}C$, $I_T=800~W/m^2$), during the experiments carried out and which are used as reference. The regression analysis of one year's monitored data (I_T , T_a , T_{pv} , v_w) from a pc-Si PV (Energy Solutions 125 W_p module) generator gave for $f(v_w;\eta_{pv})$ a quadratic v_w function multiplied with a correction function standing for the change in η_{pv} due to deviations of the environmental conditions from the average values mentioned above.

$$f(v_w; \eta_{pv}) = (a + bv_w + cv_w^2) (1 - \delta \eta_{pv} / (1 - \eta_{pv,m}))$$
 (the proposed model) (9)

a, b, and c values when the PV module is at open rack conditions are given in (10)

$$f(v_w; \eta_{pv}) = (0.0381 - 0.00428v_w + 0.000196v_w^2)(1 - \delta\eta_{pv}/(1 - \eta_{pv,m}))$$
(10)

$$T_{pv} = T_a + I_T/(U_o + U_1 v_w)$$
 model [2] (11)

 U_o takes values from 23.5 to 26.5 W/m² K, with an average 25.5 W/m² K; U_1 takes values from 6.25 to 7.68 W/m² K, with an average 6.84 W/m² K.

$$T_c = T_a + I_T \exp(a + bv_w) \qquad \text{model [1]}$$

a and b are provided in Table 2, below.

Table 2. Values of the parameters a and b. Data from [1].

Type of Module	Mount	a *	b *	
Glass-cell-polymer sheet	Open rack	-3.56	-0.0750	
Glass-cell-polymer sheet	Insulated back	-2.81	-0.0455	

^{*} for values of a and b for different type of modules and configurations, see [1].

The $(T_{pv} - T_a)/I_T$ equal to f, Equation (7), was fitted onto a quadratic function given by (13),

$$f \times 10^3 = 0.0712 v_w^2 - 2.411 v_w + 32.96 \text{ for } v_w < 18 \text{ m/s with } v_w \text{ at } 10 \text{ m}$$
 model [7] (13)

 T_{pv} is then estimated from $T_{pv} = T_a + fI_T$

$$T_{pv} = 0.943T_a + 0.028I_T - 1.528v_w + 4.3$$
 model [5] (14)

$$T_c = T_a + \omega(0.32/(8.91 + 2v_F)) I_T$$
 $v_F = v_W/0.67$ model [3]

where ω = 1, according to [3], as this paper addresses free standing PV. The v_F = $v_{w,p}$ which is the parallel component of v_w on the PV plane

$$T_{c} = [U_{pv} \cdot T_{a} + I_{T}[((\tau \alpha) - \eta_{r}) - \mu T_{r}]/(U_{pv} - \mu I_{T})$$
 model [4]

where, $\mu = 0.05\%/^{\circ}C$, $T_r = 25~^{\circ}C$ and η_r is the reference efficiency of the PV cell or module.

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2.2. The Proposed Prediction Model for the Transient Profile $T_c(t)$ or Generally, $T_{vv}(t)$

To obtain theoretically the $T_c(t)$ profile the following set of energy balance equations is developed for the characteristic PV module components, that is, glass, cell and back sheet,

$$(mc)_{c}dT_{c}/dt = A_{c}[((\tau\alpha) - \eta_{c})I_{T} - U_{c-g}(T_{c} - T_{g}) - U_{c-b}(T_{c} - T_{b})]$$
(17)

$$(mc)_{g}dT_{g}/dt = A_{c}[U_{c-g}(T_{c} - T_{g}) - U_{g-a}(T_{g} - T_{a})]$$
(18)

$$(mc)_b dT_b / dt = A_c [U_{c-b} (T_c - T_b) - U_{b-a} (T_b - T_a)]$$
(19)

where:

$$U_{c-g} = 1/R_{c-g} = 1/(\delta x_{Cell}/2k_{Cell} + \delta x_{ARC}/k_{ARC} + \delta x_{EVA}/k_{EVA} + \delta x_{Glass}/k_{Glass})$$

$$U_{c-b} = 1/R_{c-b} = 1/(\delta x_{Cell}/2k_{Cell} + \delta x_{EVA}/k_{EVA} + \delta x_{Tedlar}/k_{Tedlar})$$

The corresponding values of the above properties are shown in Table 1.

For the case of a bare PV cell the optical factor $(\tau\alpha)$ in (17) is nearly equal to 1, and the U_{g-a} and U_{b-a} for the front and back side were assumed to be equal. This is acceptable in case the PV cell is positioned at vertical and there is no wind on the cell. Hence, T_g and T_b in this case are equal to a very good approximation. Based on the continuity of the heat flow from the cell to the environment the following formula holds, too,

$$U_{c-a}(T_c - T_a) = U_{g-a}(T_g - T_a) + U_{b-a}(T_b - T_a)$$
(20)

Equation (21) gives the heat flow from the cell to the glass cover which equals the one from the front, i.e., glass cover to the environment and Equation (22) from the cell to the back cover and the back cover to the environment.

$$U_{c-g}(T_c - T_g) = U_{g-a}(T_g - T_a)$$
(21)

$$U_{c-b}(T_c - T_b) = U_{b-a}(T_b - T_a)$$
(22)

The derivatives dT_g/dt and dT_c/dt with respect to dT_b/dt are derived from (20)–(22),

$$dT_{c}/dt = [(U_{c-b} + U_{b-a})/U_{c-b}]dT_{b}/dt$$
 (23)

$$dT_g/dt = [U_{c-g}/(U_{c-g} + U_{g-a})]dT_c/dt = [U_{c-g}/(U_{c-g} + U_{g-a})][(U_{c-b} + U_{b-a})/U_{c-b}]dT_b/dt \quad (24)$$

Adding (17)–(19), using (20)–(24), rearranging the terms and making the proper substitutions, the following 2 groups of relationships are obtained as in Sections 2.2.1 and 2.2.2 and lead to the estimation of $T_c(t)$ and $T_b(t)$.

2.2.1. The Relationships to Determine $T_c(t)$

$$dT_{c}/dt = A_{c}[((\tau \alpha) - \eta_{c})I_{T} - U_{c-a}(T_{c} - T_{a})]/(mc)_{ef} = F_{1} - F_{2}(U)(T_{c} - T_{a})$$
(25)

$$(mc)_{ef} = (mc)_c + ((mc)_{EVA} + (mc)_g)[U_{c-g}/(U_{c-g} + U_{g-a})] + ((mc)_{EVA} + (mc)_b)[U_{c-b}/(U_{c-b} + U_{b-a})]$$
(26)

$$F_2(U) = A_c U_{c-a} / (mc)_{ef}$$
 (27)

$$F_1 = A_c((\tau \alpha) - \eta_c)I_T/(mc)_{ef}$$
(28)

2.2.2. The Relationships to Determine $T_b(t)$

$$dT_b/dt = F_1 - F_2(U)(T_b - T_a)$$
(29)

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$$(mc)_{ef} = ((mc)_b + (mc)_{EVA}) + (mc)_c[(U_{c-b} + U_{b-a})/U_{c-b}] + ((mc)_{EVA} + (mc)_g)[(U_{c-g}/(U_{c-g} + U_{g-a}))]$$

$$[(U_{c-b} + U_{b-a})/U_{c-b}]$$

$$(30)$$

In this subsection, F_1 and $F_2(U)$ are given by:

$$F_1 = A_c((\tau \alpha) - \eta_c)I_T/(mc)_{ef}$$
(31)

$$F_2(U) = A_c[U_{b-a} + U_{g-a}[(1 + (U_{b-a}/U_{c-b}))/(1 + (U_{g-a}/U_{c-g}))]]/(mc)_{ef}$$
(32)

Based on (29), $T_b(t)$ is provided by the algorithmic expression below, which is part of the model proposed:

$$[F_1 - F_2(U)(T_b(t + \delta t) - T_a)]/[F_1 - F_2(U)(T_b(t) - T_a)] = \exp(-\delta t/\tau)$$
(33)

 $T_b(t+\delta t)$ is the PV backside temperature at time interval $t+\delta t$, and $T_b(t)$ at time t. Time intervals δt may be equal to a practical time unit. Equation (33) allows for introducing $I_T(t+\delta t)$ and $I_T(t)$ to Equation (31) and for using $v_w(t)$ to estimate U_{g-a} and U_{b-a} from equations in [23] taking into account the environmental conditions in that time interval $[t, t+\delta t]$ and introducing the values to (32). For the $T_c(t)$ the same expression is used where instead of T_b is T_c and the factors $F_2(U)$ and $(mc)_{ef}$ are given in Section 2.2.1. In all cases, the time constant of the PV module temperature profile (τ) is given by:

$$\tau = 1/F_2(U) \tag{34}$$

For the estimation of the time constants, τ_b , τ_g , τ_c appropriate (mc)_{ef} and $F_2(U)$ are used in (34). $F_2(U)$ for the $T_b(t)$ prediction tends to:

$$F_2(U) = A_c(U_{b-a} + U_{g-a})/(mc)_{ef}$$
 (35)

provided that U_{c-g} and U_{c-b} have high values compared to U_{b-a} and U_{g-a} and for $U_{b-a} = U_{g-a}$

$$F_2(U) = 2A_c U_{b-a} / (mc)_{ef} = U_{b-a} / ((\rho c)_{ef} L_c)$$
(36)

Hence, in simplified cases the time constant, τ , of the $T_c(t)$ profile is given by:

$$\tau = (\rho c)_{ef} L_c / U_{b-a} \tag{37}$$

The $(\rho c)_{ef}$ for the c-Si cell is taken from Table 1 data and is estimated by the sum of the products of the density and the specific heat capacity of every component of the PV cell. L_c is the characteristic length of the cell for the heat propagation process from inside the cell to outside, which is equal to the ratio of the PV cell volume (V) over its total surface. In this case, L_c due to the very small cell thickness is equal to the half of the PV cell thickness. In such simplified cases, recurrence formulae like in [11] are used, while Equations (23)–(32) are opted to get accurate $T_c(t)$, $T_b(t)$ and $T_f(t)$ prediction under any environmental conditions. From Equations (34)–(37) becomes clear that τ increases with $(mc)_{ef}$ that is, with the glass and back sheet thickness, which mostly contribute to $(mc)_{ef}$ and inversely decreases with v_w (see Figure 2) or with the friction of air flow on the PV back side due to U_f and U_b increase.

3. Results

3.1. The Experimental Set Up

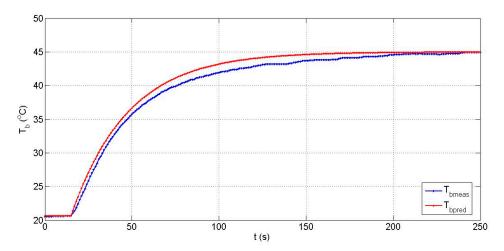
The experimental set up includes a Data Acquisition System, a solar simulator model Solar Light 16S-300-002 Class A Air Mass 1.5 emission spectrum, as well as the simulation model to predict $T_{pv}(t)$, $V_{oc}(t)$ and $I_{sc}(t)$. Also, thin diameter Cu-Const thermocouples attached at the PV cell or module back side to monitor $T_b(t)$, a Pt 100 for the ambient temperature and a series of c-Si bare cells and several

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c-Si and pc-Si modules mounted on FIX and ST frames installed at free environment. According to the data acquisition system used in the experiments data were collected and recorded every 1 s.

3.2. Predicted and Measured Transient $T_h(t)$ Profiles for Bare c-Si Cells

Figure 3 shows the measured and predicted profile of a SOLARTEC $2.5 \times 2.5 \text{ cm}^2$ c-Si part of a cell under $I_T = 10^3 \text{ W/m}^2$ at controlled environmental conditions in the laboratory, by using Equations (33)–(36). The deviation between the measured $T_{b,meas}(t)$ and predicted $T_{b,pred}(t)$ values is less than 3% throughout the transient period. Thus, the theoretical and experimental τ values for the bare cell are practically the same as discussed below. The time constant, τ, was predicted from the expression $(mc)_{ef}/(U_f + U_b)$, given in Equations (34) and (35). The $(mc)_{ef}$ normalized to the bare cell surface is equal to 857 J/m² K based on Table 1 data. The appropriate equations from [23] gave $U_f = U_b = 11.5-12 \text{ W/m}^2 \text{ K}$ at air free flow for T_b in the range 20–50 °C and 16–20 °C indoor temperature and therefore, τ was determined in the range of 35.7–37.3 s compared to the experimental 37.1 s, which was estimated by fitting the function $T_b(t) = a - b \cdot \exp(-t/\tau)$ on the $T_b(t)$ measured values. The deviation of the theoretical τ from the experimental one was less than 3.8%. The predicted $T_{b,pred}(t)$ were introduced into (1) to obtain $V_{oc}(t)$, as in Figure 4, where predicted and experimentally determined V_{oc}(t) are shown. A maximum difference of 6 mV is observed at the saturation time period of 5τ to 6τ . This corresponds to 1.1% deviation between measured and predicted values. It is noted that the $V_{oc}(t)$ time constant, was determined experimentally, as done with the $T_b(t)$, by fitting an exponential function on the data.



 $\textbf{Figure 3.} \ \ \text{Predicted} \ \ T_{b,pred}(t) \ \text{and measured} \ \ T_{b,meas}(t) \ \text{profiles of a c-Si bare cell in controlled laboratory conditions}.$

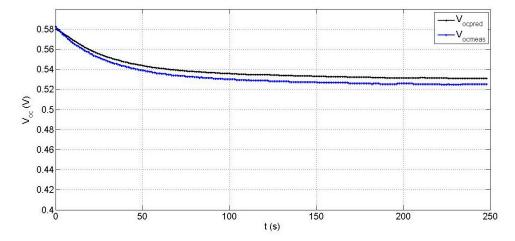


Figure 4. Predicted $V_{oc,pred}(t)$ and measured $V_{oc,meas}(t)$ profiles for a bare c-Si cell in controlled laboratory conditions.

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According to (1) the τ of $V_{oc}(t)$ is the same with the $T_b(t)$ time constant determined from the curve analysis of Figure 3, equal to 37.1 s. Fitting the function $a+b\cdot exp(-t/\tau)$ on the measured $V_{oc}(t)$ the result was $\tau=37.2$ s. Similarly, a good practical estimation of τ is obtained from the $V_{oc}(t)$ curve, Figure 4, using the value of 6τ at saturation which is in the range of 215–225 s/6 = 35.8–37.5 s. From (1) the sign of the derivative of $T_{pv}(t)$ is opposite to the corresponding of $V_{oc}(t)$.

3.3. Predicted and Measured Transient $T_h(t)$ Profiles and Time Constants, τ , for PV Modules

The improved set of the abovementioned iterative relationships which provide transient profiles, end up to the steady state value,

$$T_b = T_a + ((\tau \alpha) - \eta_{pv})I_T/(U_f + U_b)$$
 (38)

 T_b obtained from (38) lies very close to T_{pv} at saturation predicted in the previous section, provided that proper values for η_{pv} and (U_f+U_b) are substituted in the above expression. For $(\tau\alpha)=0.91$ (bare cell) $\eta_{pv}=0.15$ (manufacturer value), $(U_f+U_b)=24$ W/m 2 K, as above, and $T_a=16$ °C, Equation (38) gives $T_b=47.6$ °C compared to the 44.8 °C predicted, i.e., a 5.8% deviation.

Figure 5 gives measured $T_b(t)$ of a PV module Bioenergy 195W. τ was experimentally determined by the curve fitting analysis and found equal to τ = 316.7 s. For the theoretical prediction of τ , the total heat losses coefficient at field conditions with low v_w was given above equal to 24 W/m² K. According to the values from Table 1, the (mc)_{ef} normalized to surface A_c for this module, with 3.2 mm glass and PET back sheet of 0.4mm, is estimated in the range of 6760–7720 depending on the c_p of the glass cover. Hence, τ = [6760–7720]:24 = 281.7–321.6 s. In fact, the experimental τ lies inside the domain of the theoretically predicted τ values.

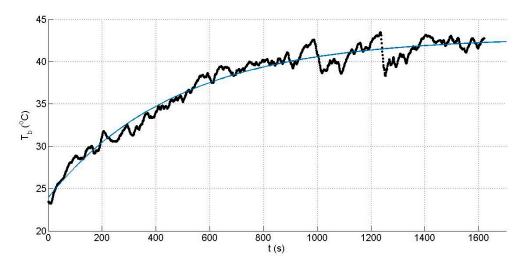


Figure 5. T_b(t) profile for a c-Si Bioenergy 195W PV module in field conditions.

Figure 6 shows the $T_b(t)$ profile of an SM55 module inclined over a window as shadow hanger and power generator, too. The expression $F(x) = A(1 - \exp(-Bx)) + C$ was fitted on the data, (upper curve) with $R^2 = 0.959$, and gave $\tau = 306.2$ s while the predicted value was determined by setting (mc)_{ef} 6760 J/m² K (considered for the lower size SM55) and 23–24 W/m² K for the heat losses coefficient. Thus, τ lies in the range 281.7–293.9 s with a deviation of its average from the experimental <6%. However, the wind speed increases at around 1100 s and steady state temperature reached earlier, see lower curve in Figure 6, where the final time constant due to the wind increase shortened τ to 235.7 s, according to the curve analysis. Using (39) [4], a theoretical estimate of τ , is obtained.

$$U = h_{c,f} + h_{c,b} = 11.34 + 7.73v \tag{39}$$

which for average wind speed during the experiments v=1~m/s, as the PV module, operating as a shadow hanger, was in wind protected zone, $U=19.07~W/m^2~K$. Adding $10~W/m^2~K$ for $h_{r,f}+h_{r,b}$ then, $U_{pv}=29.07~W/m^2~K$ and hence, $\tau=6760/29.07=232.5~s$ which is a very good prediction. That shows the strong effect of v_w on PV performance.

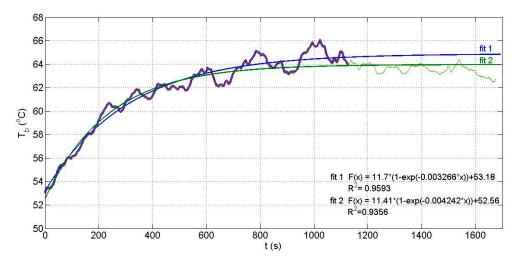


Figure 6. T_b(t) profile SM55 module placed inclined over a window in a Building Adapted Photovoltaics (BAPV) configuration.

3.4. Predicted Steady State $T_b(t)$ Values and Comparison with Measured Data and Results from other Models: Validation of the Proposed Model

The steady state T_b and the f values of pc-Si PV modules operating in field conditions in FIX and ST mounting were experimentally determined and theoretically predicted. The experiments for both FIX and ST PV systems were carried out in months of different environmental conditions, January and July. T_b and f were predicted by:

- a. the simulation model elaborated and proposed in this article, Equation (10), and
- b. formulae provided from the other models [1-5,7].

Those f and T_{pv} values were compared with the experimentally determined ones, shown in Table 3.

Table 3. Comparison of predicted by this model $(T_c - T_a)$ for morning–noon–afternoon hours in a mid-day of July with the measured values from the FIX and ST and those calculated using models [1–5].

Hour	Mod	el [1]	Mod	el [2]	Mod	el [4]	Mod	el [3]	This I	Model	Mod	el [5]	Meas	ured *
	F	ST	F	ST	F	ST	F	ST	F	ST	F	ST	F	ST
10	12.9	24	11.4	21.3	10.15	18.8	11.25	21.0	13.6	25.3	12.5	24.1	14.0	23.0
12	20.5	27.3	19.9	26.5	16.25	26.9	20.0	26.6	23.3	27.1	20.4	27.2	23.5	27.3
14	23.2	28.2	22.2	27.1	19	22.2	22.3	27.2	24.1	28.5	22.9	28.0	24.0	29.0
16	16.7	24	13	18.7	12.75	18.55	12.52	18.05	16.5	24	15.4	23.8	17	23

^{*} The fixed inclination (FIX) and ST systems were installed at free environment.

In addition, Table 4 gives the f values predicted by this model, (10), and also by the known models [1–5,7] during the hours in a mid-day of July and January. In the application presented T_a , v_w and I_T change during the day and the two PV generators sun-tracker and fixed inclination system having identical modules were used. Hence, the tests included two different PV mountings and varying environmental conditions.

Table 4. The predicted by this model f values compared with those calculated using models [1–5,7] and the experimentally determined ones, for various hours of a mid-day of January and July under various environmental conditions, I_T and v_w . Both cases of FIX and ST PV systems were considered.

Hour/Type	I _T	$T_c - T_a$	$\mathbf{v}_{\mathbf{w}}$	fexp *	f_{model}	Model [2]	Model [7]	Model [1]	Model [5]	Model [4]	Model [3]
14 h/7/FIX	840	24.5	2.0	0.0291	0.0303	0.0255	0.0305	0.0245	0.0285	0.0276	0.0278
11 h/7/FIX	623	17	3.8	0.0272	0.0267	0.0195	0.0248	0.0215	0.0227	0.0203	0.0202
16 h/7/ST	970	23	4.2	0.0237	0.0235	0.0184	0.0240	0.0208	0.0237	0.0196	0.0185
16 h/7/FIX	680	16	4.2	0.0235	0.0236	0.0184	0.0240	0.0208	0.0227	0.0220	0.0185
12 h/1/ST	1050	35	1.0	0.0335	0.0340	0.0309	0.0307	0.0264	0.0305	0.0366	0.0300
14 h/1/ST	1020	30.5	2.5	0.0299	0.0286	0.0235	0.0273	0.0236	0.0284	0.0266	0.0264
14 h/1/FIX	800	26.5	2.5	0.0330	0.0340	0.0235	0.0273	0.0236	0.0286	0.0250	0.0264
13 h/1/ST	1080	34.5	1.5	0.0318	0.0337	0.0280	0.0295	0.0254	0.0290	0.0332	0.0322
13 h/1/FIX	860	30.5	1.5	0.0355	0.0330	0.0280	0.0295	0.0254	0.0316	0.0330	0.0322
8 h/7/ST	625	19	1.2	0.0304	0.0318	0.0297	0.0302	0.0260	0.0295	0.0360	0.0343

^{*} f_{exp} is the f value determined from $(T_b - T_a)/I_T$ measured during the day by a monitoring system.

It is clear from Table 3 that the proposed model has an overall higher prediction performance over the other models. For this, a statistical analysis on both Tables data provides the consistency and the prediction quality of the models, as shown in Figure 7.

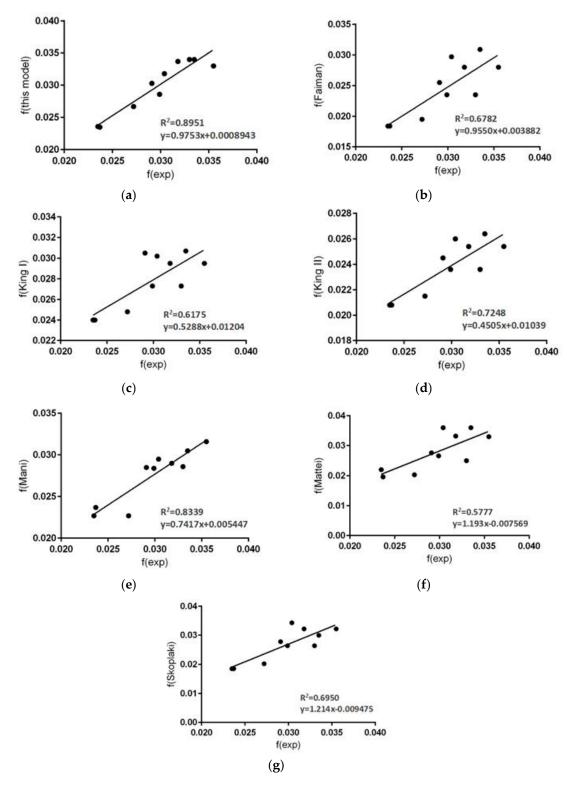


Figure 7. Results from a regression analysis of predicted f values versus the experimentally determined f values where f is predicted by (a) the proposed model, (b) model [2], (c) model [1], (d) model [7], (e) model [5], (f) model [4], and (g) model [3].

From the results deployed in Tables 3 and 4 it is clear that the proposed model predicts f and T_{pv} for FIX and ST configurations systematically very close to the experimentally determined values with deviation less than 4%. The predicted values from models [1–5,7] experience a larger dispersion disclosed by the determination coefficient, R^2 , while their deviations may in general reach up to 15%. In general, the models which do not provide correction due to the effect of I_T , I_T on I_T exhibit higher deviation compared to this model. Figure 7a–g show the predicted by this model and the models [1–5,7] I_T values versus the experimental ones. The model proposed exhibits the least dispersion of data and is nearer to the best theoretical line.

4. Discussion

The measured T_b(t) values either for the bare PV cell or the PV modules were best fitted on the function $a(1 - \exp(t/\tau_{Tc}))$, with a coefficient of determination always >0.998, which provided for the τ_{Tc} . $T_b(t)$ and τ were also predicted theoretically from Equations (29)–(34) accounting for the environmental conditions. The predicted T_b values for a cell deviated by <3% from the measured ones. Both depend on I_T, v_w and the PV geometrical and physico-chemical characteristics, as in Table 1. The dependence on I_T creeps in through the heat transfer coefficients as U_{g-a} and U_{b-a} increase with the $T_{\text{b}},$ which in turn increases with $I_{\text{T}}.$ A formula proposed to predict τ_{Tc} directly based on Equations (37) and (39) gave very good results, which deviated by <5% from the experimental value. Using more accurate expressions for the U_f and U_b as proposed by the authors in [23], would result in much smaller deviations between the predicted and experimental values but would raise the algorithmic complexity of the model which requires the use of many theoretical expressions to accurately simulate T_{pv} as analyzed in [23,24], rather than the mixed type compact model proposed here which was the aim of the current work. For the bare c-Si τ_{Tc} was found equal to 35.8 s-37.1 s for $I_T = 10^3 \text{ W/m}^2$, while for c-Si and pc-Si PV modules the τ_{Tc} value was around 4.5–5.5 min. For v_w higher than 1–2 m/s, τ decreased to 2–2.5 min. This is explained through Equations (32) and (34) where the effect of environmental conditions is expressed through the total effect of U_{b-a} and U_{g-a} which inversely affects τ . Note that U_{c-b} and U_{c-g} are much larger than U_{b-a} and U_{g-a} respectively and therefore the ratio $(1 + (U_{b-a}/U_{c-b}))/(1 + (U_{g-a}/U_{c-g}))$ tends to 1. Therefore, the effect of the characteristics of the layers of the module on the time constant is expressed mainly through (mc)ef in Equations (32) and (34), which proportionally affects τ . For example, the effect of the EVA encapsulant alone is significant as may be estimated using Equation (30) for the modules used in the study the EVA has 15% contribution in the module (mc)_{ef} value, leading to a larger time constant (by 15%) and more pronounced transient phenomena.

The predicted $T_c(t)$ was used to predict $V_{oc}(t)$. The result was in excellent agreement with the experimental values for $I_T = 10^3 \text{ W/m}^2$. The time constants, τ_{Voc} , of the theoretically developed $V_{oc}(t)$ profiles by using (1) lie very close to the experimentally determined ones. The transient prediction model is easily handled even for I_T and v_w changing during monitoring. The introduction of the $I_T(t)$ and $v_w(t)$ values into the algorithm, Equations (31)–(33), is done using their average values in each time unit. The recorded steady state T_b values during the hours of the mid-day of 2 climatically opposite months, July and January, were compared with the predicted values. An excellent agreement was confirmed and the diagram of the predicted by this model f values versus experimental ones was of higher quality compared to the other models. It is important to underline that the constants a, b, c in Equations (9) and (10) were derived by regression analysis of data taken from the operation of 7 years old pc-Si modules. Therefore, an ageing correction, of +7 years \times 0.85%/year = +6% must be added in the predicted f values obtained from the other models [1–3,7], provided that those models were developed using brand new PV modules. Thus, a good improvement will be achieved in their prediction performance. Finally, it is emphasized that the experimentally determined *f* and T_b values used in the validation test were excluded from the data used in the regression analysis to build the $f(v_w)$ quadratic formula.

The model developed applies to free standing PV modules or cells in any environmental conditions. It is based on c-Si PV modules but could be easily adapted to flat plate PV modules of other types as long as the properties of Table 1 are enriched for the layers and composition of these types. The model would need to be adapted for PV modules inclined before windows and BIPV as it concerns the view factor and the convection coefficients. The steady state model takes into account wind velocity but not wind direction, while module inclination is not considered. These can be integrated into the model through U_f and U_b as in [23] and will be presented in future work.

5. Conclusions

A new model to predict the steady state PV cell or module temperature, T_{pv} or T_b with a version to predict the transient temperature profiles was elaborated, presented, and validated. The model is based on a quadratic v_w function multiplied with a correction function accounting for the change in η_{pv} due to the deviation of the environmental conditions from their average values taken as reference. An excellent agreement under any environmental conditions was confirmed between predicted and recorded PV module T_b values, deviation <3%, in comparison with other 6 known models. The model performed better than any other one. Accurate PV temperature prediction is especially important considering its significant effect on PV power output, with a typical value for the temperature coefficient of P_m of $-0.5\%/^{\circ}C$. Considering that a range of 5–25% reduction in power output is normally expected from the nominal value for 1000 W/m² incident irradiance due to PV temperature alone, accurate prediction of PV temperature can assist in adequate control measures, monitoring and diagnostic procedures to be taken in practical situations of PV installations.

Finally, a mathematical algorithmic expression was developed to predict the transient $T_b(t)$, $T_g(t)$, $T_c(t)$. The time constant of the $T_b(t)$ profiles for the PV modules theoretically derived and experimentally determined deviated by less than 5%. The accuracy can be further increased with a more analytical determination of U_f and U_b as in [23]. The transient model provided also a simple expression for the steady state T_b whose deviation from the theoretical and experimental values was less than 5.8%. The transient $T_b(t)$ profile produced by the model followed closely the measured T_b data, as was shown in many cases examined in a bare c-Si cell and also in 3 c-Si and pc-Si PV modules. The compact model developed is applicable to any geographical site and environmental conditions.

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Nomenclature

ANN	Artificial Neural Networks	$U_f = U_{g-a}$	Heat losses coefficients due to convection and IR radiation at the front side of the PV module (W/m 2 K), equal to $h_{c,f} + h_{r,f}$
BAPV	Building Adapted Photovoltaics	V _{oc}	Open circuit voltage in a PV cell or module (V)
BIPV	Building Integrated Photovoltaics	h _{c,f}	Heat convection coefficient from PV glass to air
EBE	Energy Balance Equation	h _{r,f}	Radiative heat coefficient from the front PV side $(W/m^2 K)$
FIX	Fixed inclination PV installation	h _{c,b}	Heat convection coefficient from PV back surface to air $(W/m^2 K)$

Global solar radiation intensity on the tilted PV plane (W/m^2)	h _{r,b}	Radiative heat coefficient from the PV back side to environment $(W/m^2 K)$
It is the I_T equal to $10^3 \ W/m^2$	k _i	Thermal conductivity of cell layer i (W/mK)
The photo-current of the PV cell (A)	(mc)	Mass heat capacity (J/K)
Short circuit current from a PV cell or module (A)	n	The ideality factor of the PV cell diode
PV power output at MPP at time t (W)	v_{w}	Wind velocity (m/s)
Sun-tracking system	δx	Cell layer thickness (m)
PV module temperature, PV semiconductor temperature, PV front side and PV back side temperatures, respectively	$\varepsilon_{\mathrm{pv}},\varepsilon_{\mathrm{b}}$	Emissivity coefficients of the PV glass and back surface, respectively
PV glass cover temperature = T_f (°C)	η _c ,η _{pv} , η _{pv,m}	PV cell and module efficiency, PV module efficiency at average environmental conditions
Ambient temperature (K)	ρ	Density (kg/m ³)
Heat losses coefficients due to convection and IR radiation at the back side of the PV module (W/m^2 K), equal to $h_{c,b} + h_{r,b}$	τ	Time constant of the PV module or cell temperature profile
The overall heat losses coefficient from a PV (W/ m^2 K), equal to $U_f + U_b$	(τα)	Transmittance-absorptance product
	tilted PV plane (W/m²) It is the I_T equal to 10^3 W/m² The photo-current of the PV cell (A) Short circuit current from a PV cell or module (A) PV power output at MPP at time t (W) Sun-tracking system PV module temperature, PV semiconductor temperature, PV front side and PV back side temperatures, respectively PV glass cover temperature = T_f (°C) Ambient temperature (K) Heat losses coefficients due to convection and IR radiation at the back side of the PV module (W/m² K), equal to $h_{c,b} + h_{r,b}$ The overall heat losses coefficient from	tilted PV plane (W/m²) $h_{r,b}$ It is the I_T equal to 10^3 W/m² k_i The photo-current of the PV cell (A) (mc) Short circuit current from a PV cell or module (A) n PV power output at MPP at time t (W) n Sun-tracking system n Sun-tracking system n PV module temperature, PV semiconductor temperature, PV front side and PV back side temperatures, respectively PV glass cover temperature = n Ambient temperature (K) n Heat losses coefficients due to convection and IR radiation at the back side of the PV module (W/m² K), equal to n n n n n n n n

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