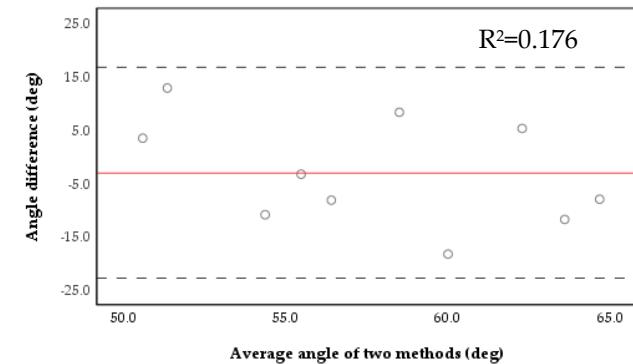
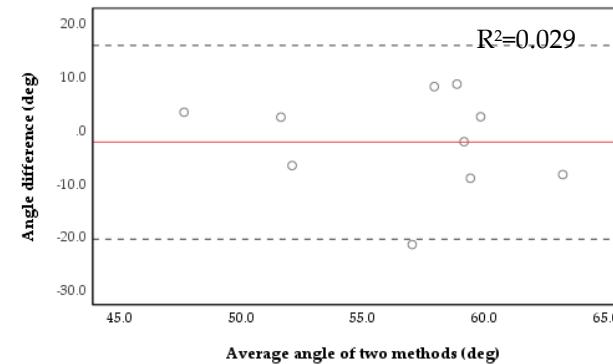
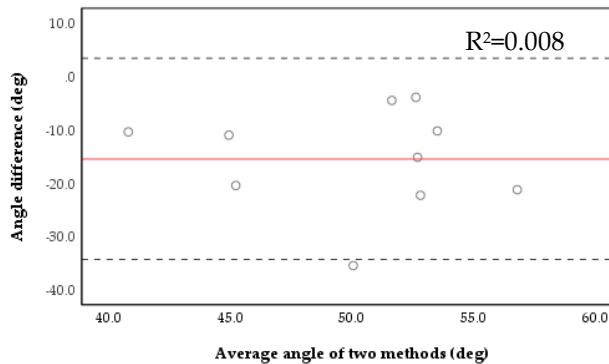
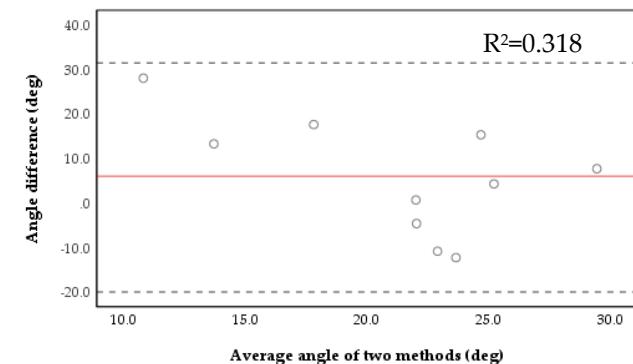
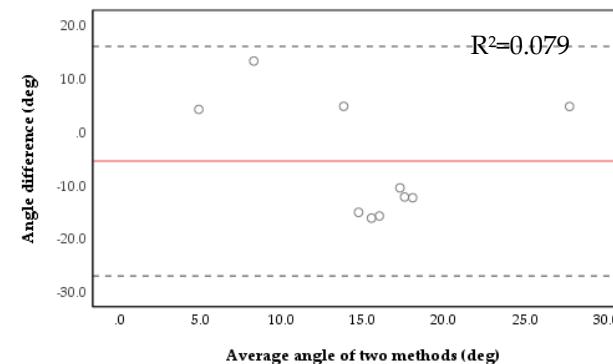
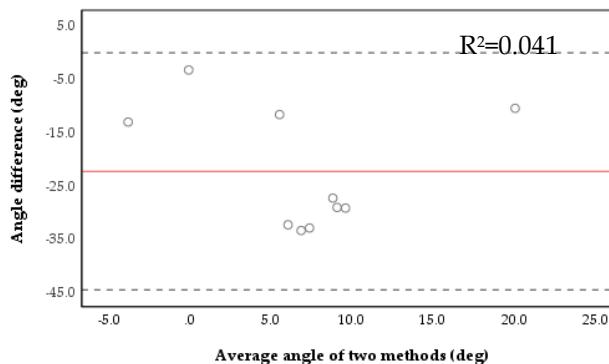


Supplementary Material – Bland-Altman plots for joint kinematics parameters during gait.

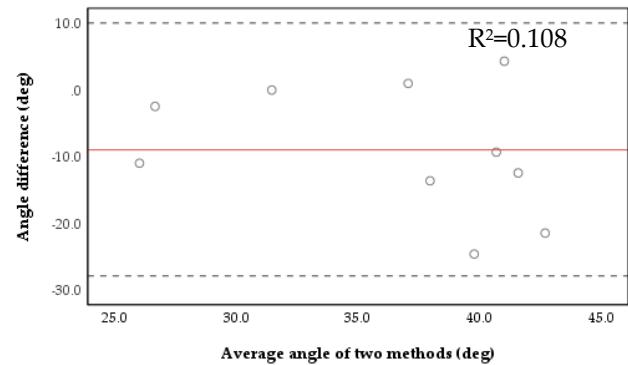
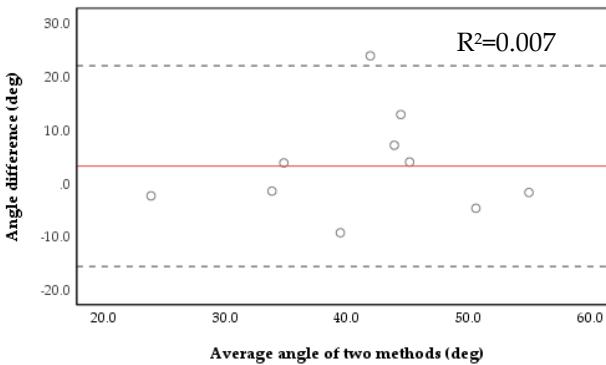
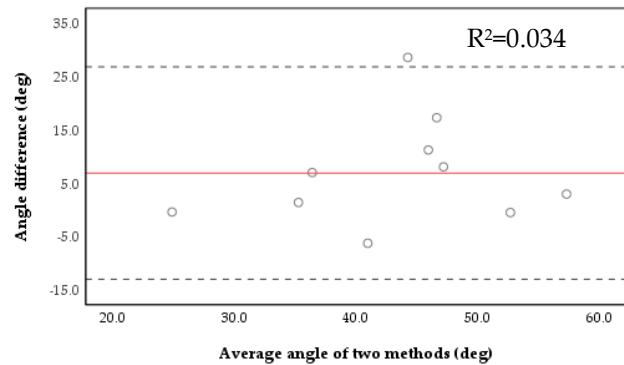
Maximum Hip flexion/extension angle



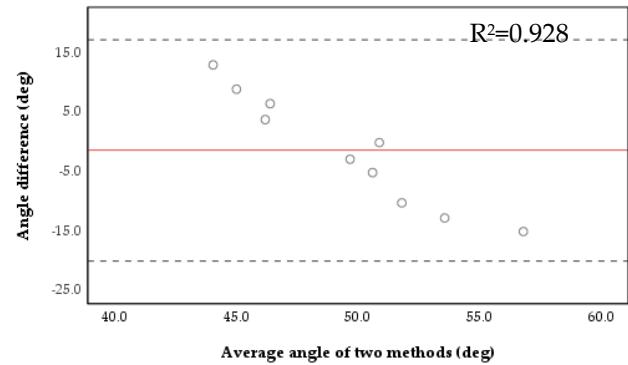
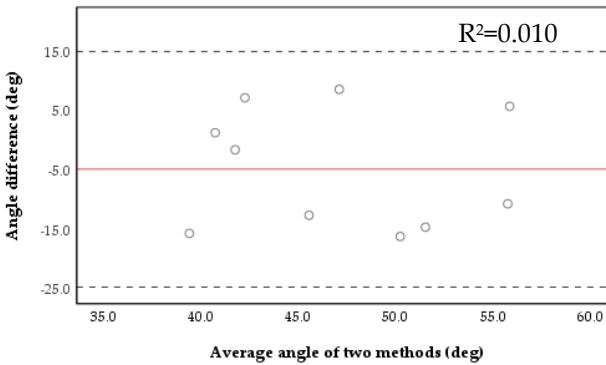
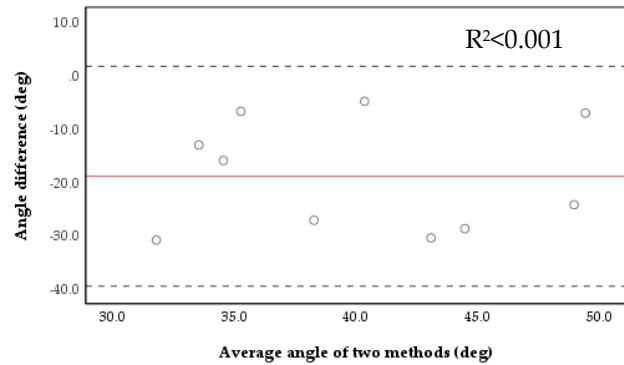
Minimum Hip flexion/extension angle



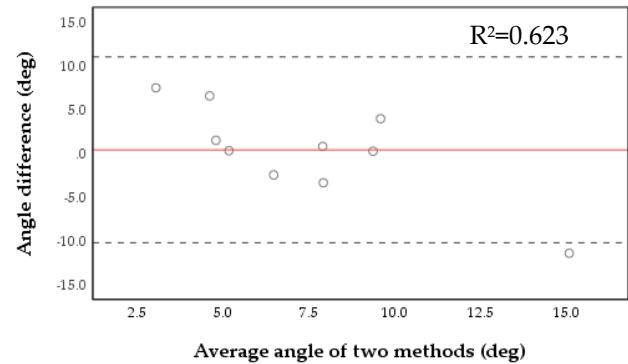
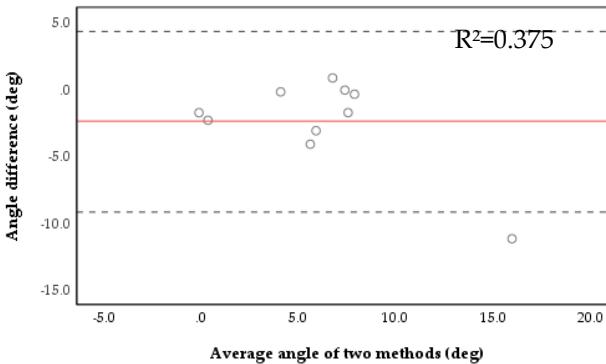
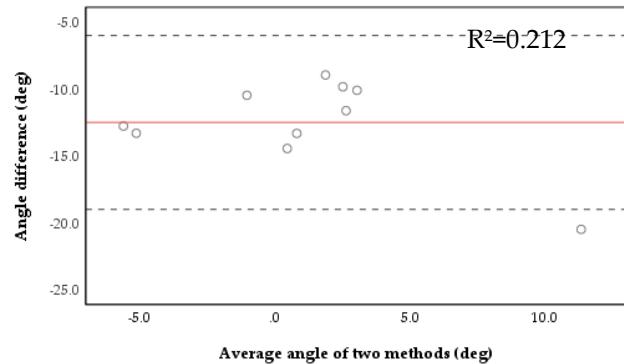
Hip flexion/extension ROM



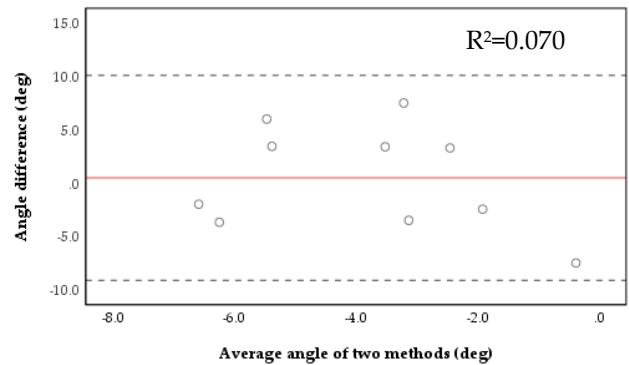
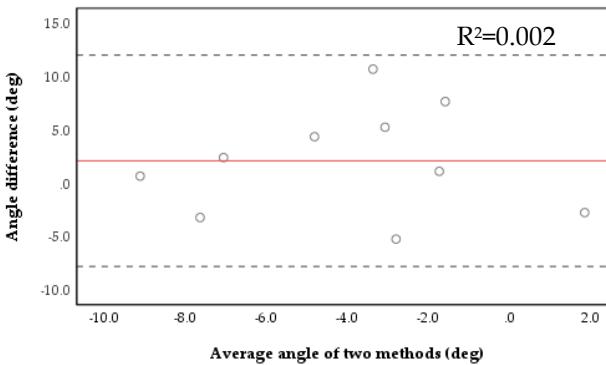
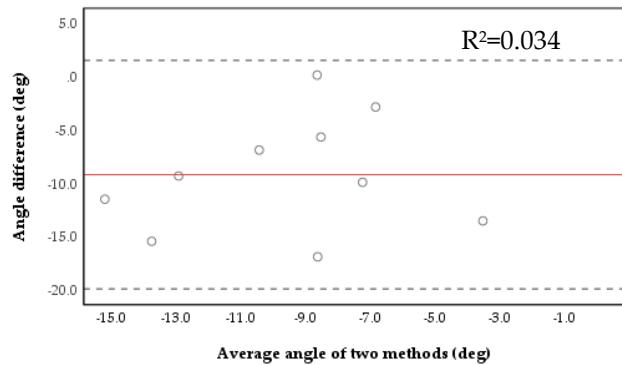
Hip flexion/extension at initial contact



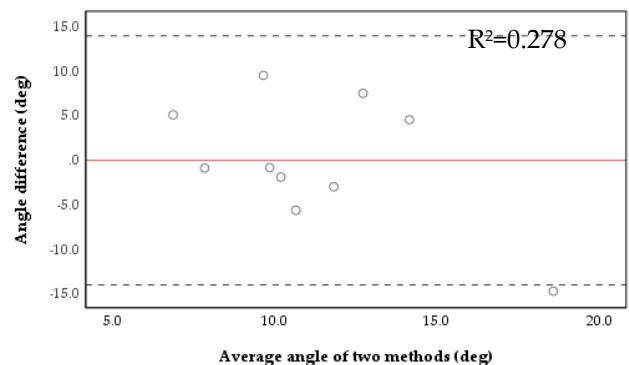
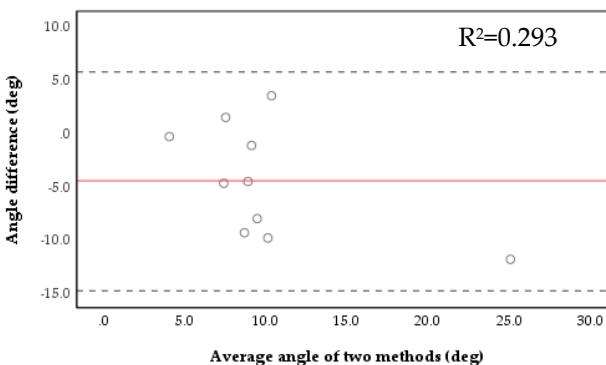
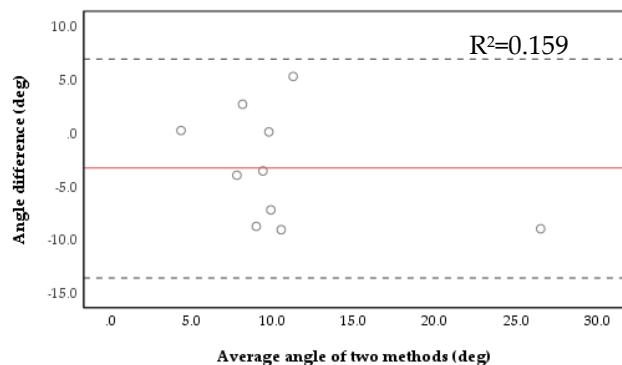
Maximum Hip adduction/abduction angle



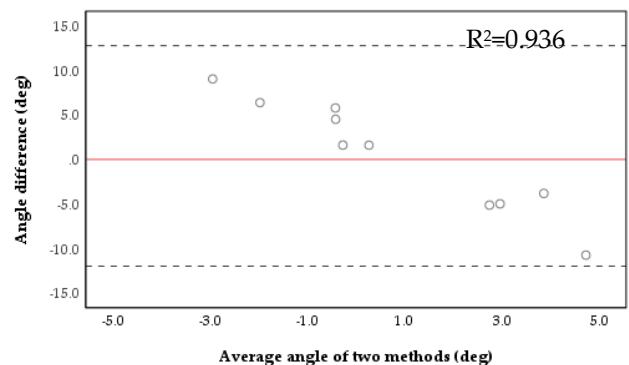
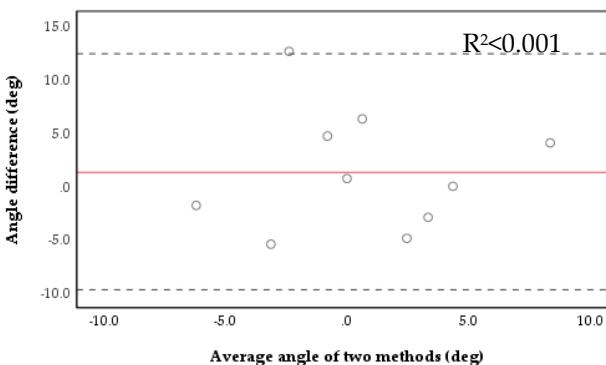
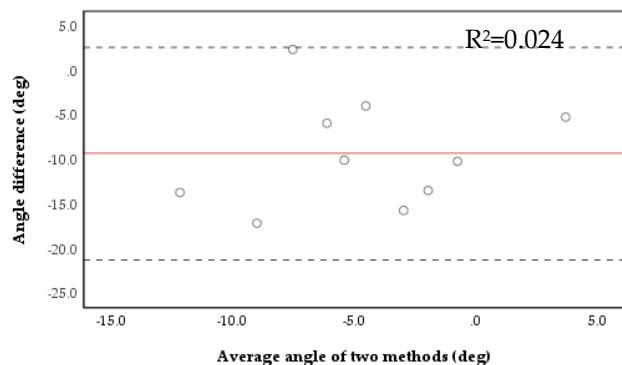
Minimum Hip adduction/abduction angle



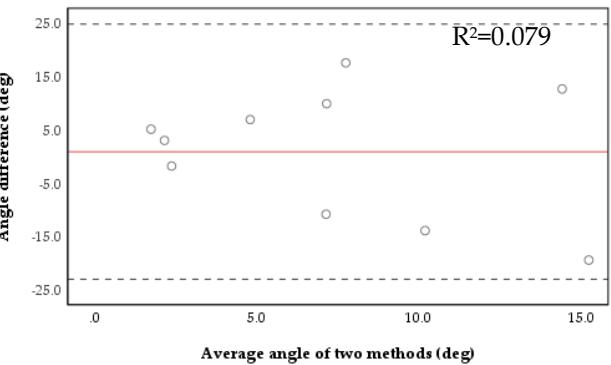
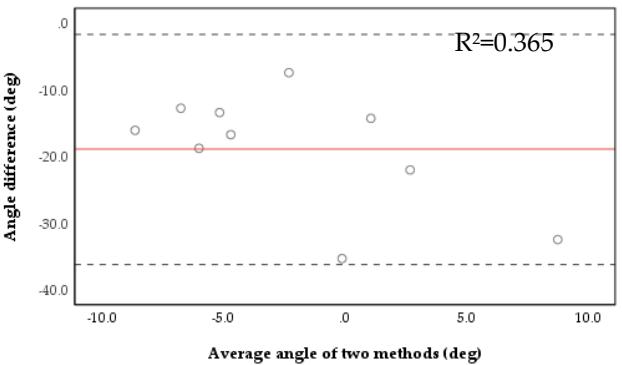
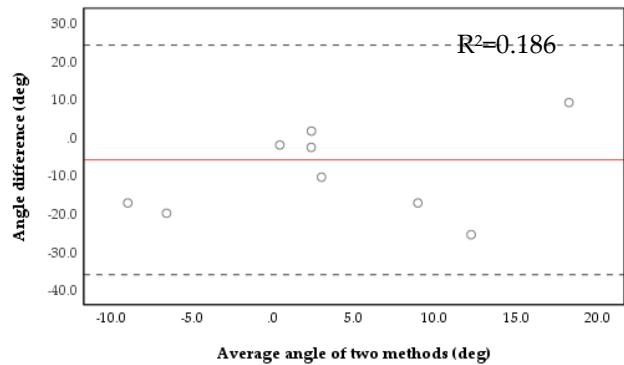
Hip adduction/abduction ROM



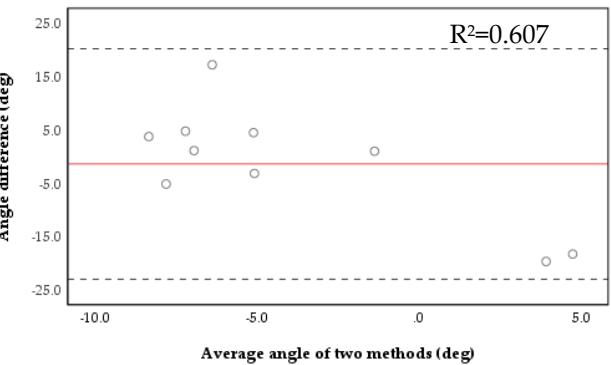
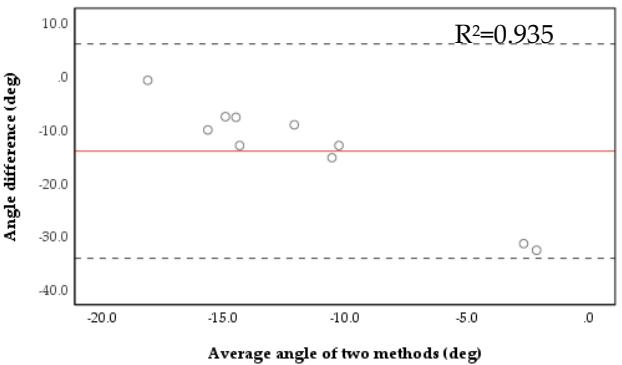
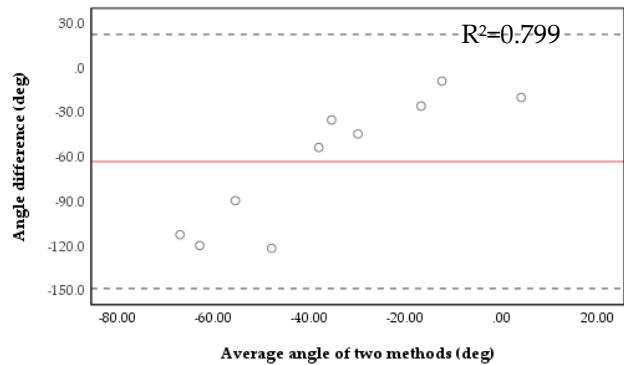
Hip adduction/abduction at initial contact



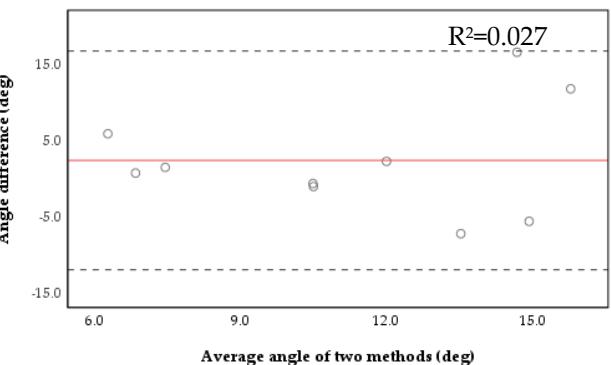
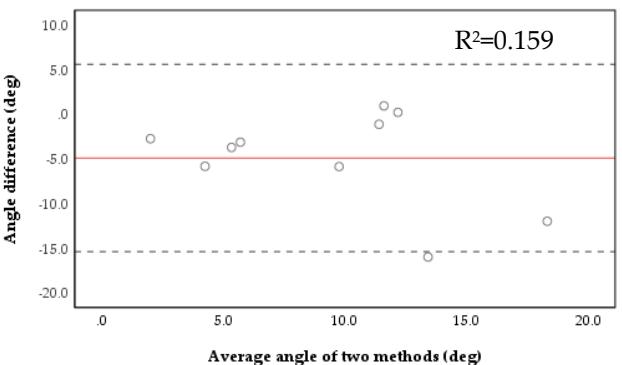
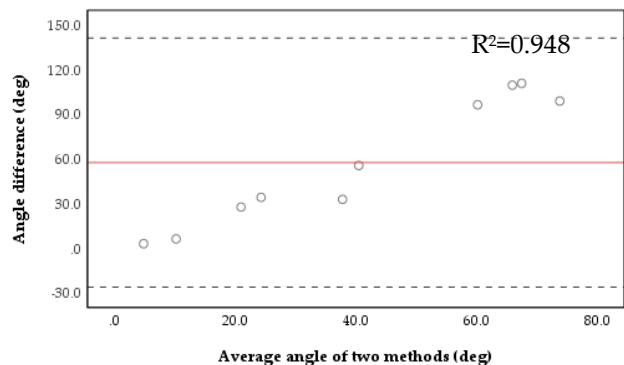
Maximum Hip internal/external rotation angle



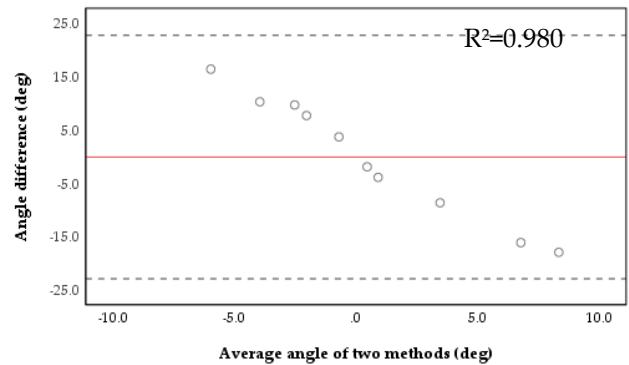
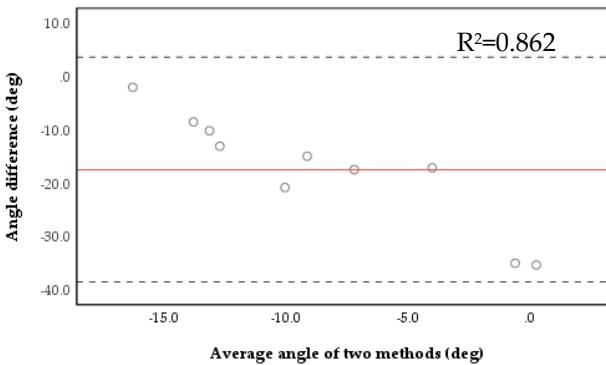
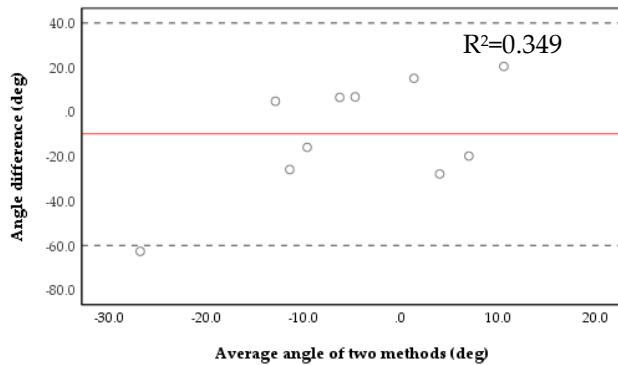
Minimum Hip internal/external rotation angle



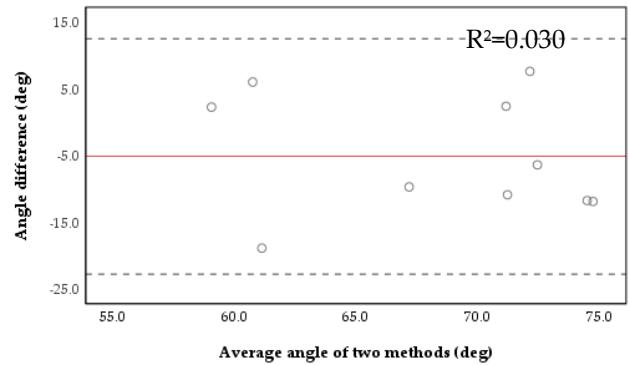
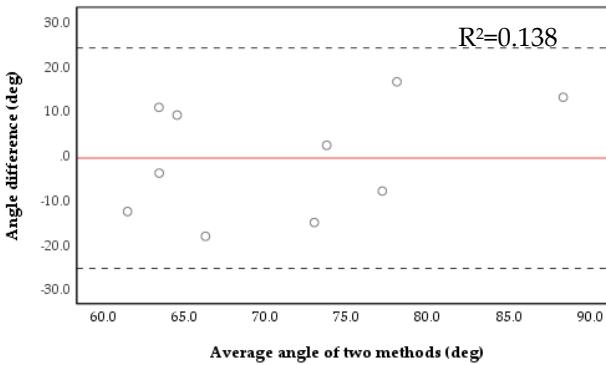
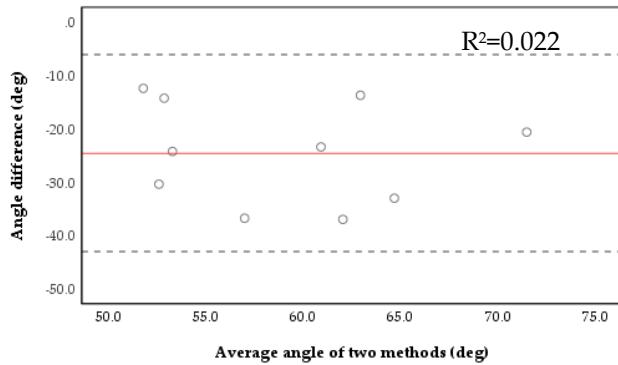
Hip internal/external rotation ROM



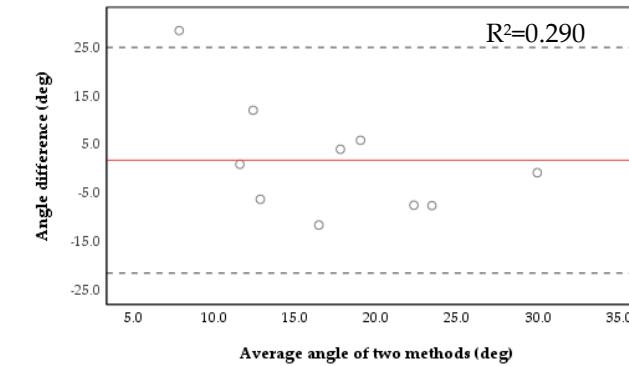
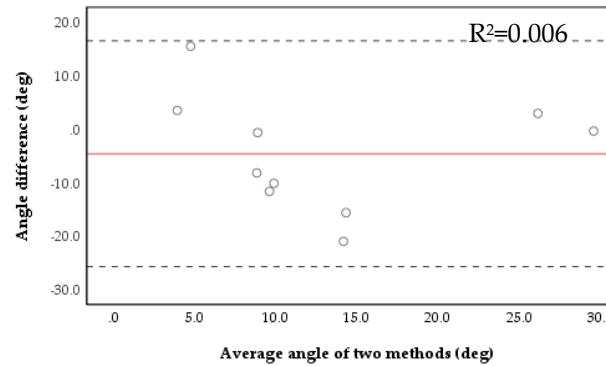
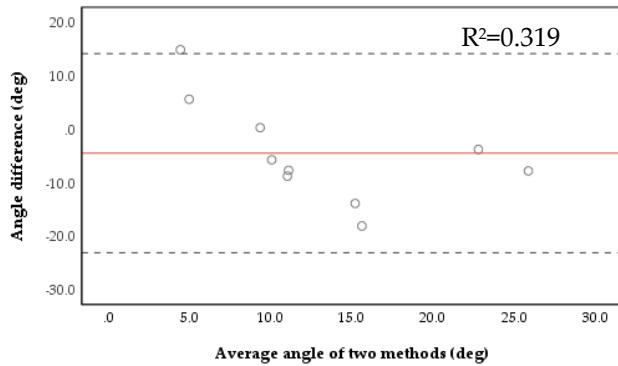
Hip internal/external rotation at initial contact



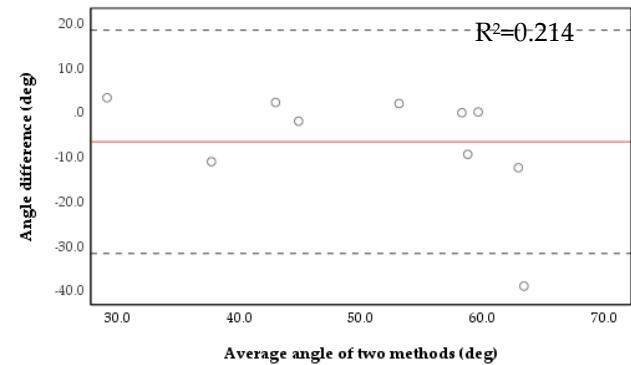
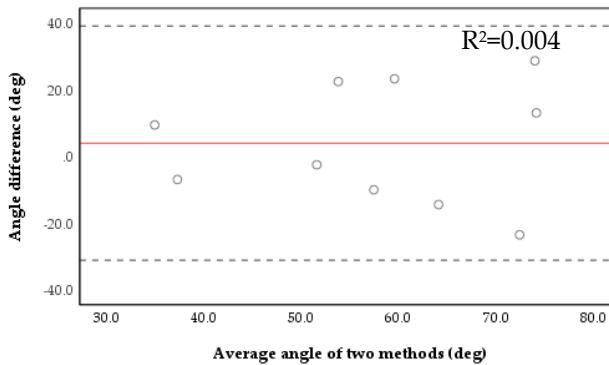
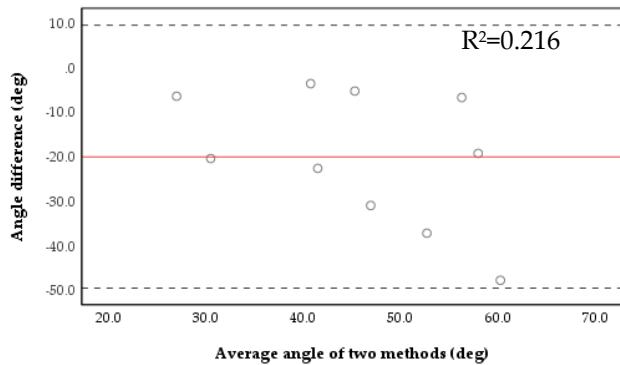
Maximum Knee flexion/extension angle



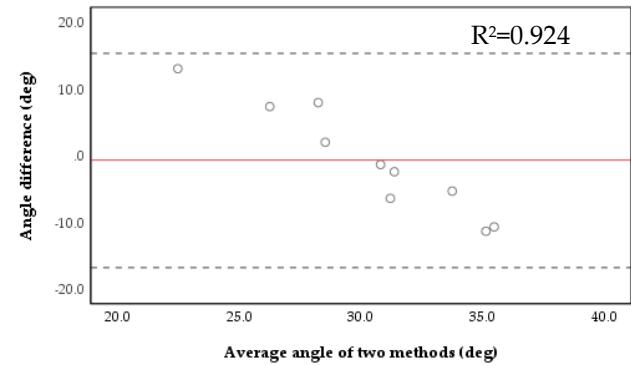
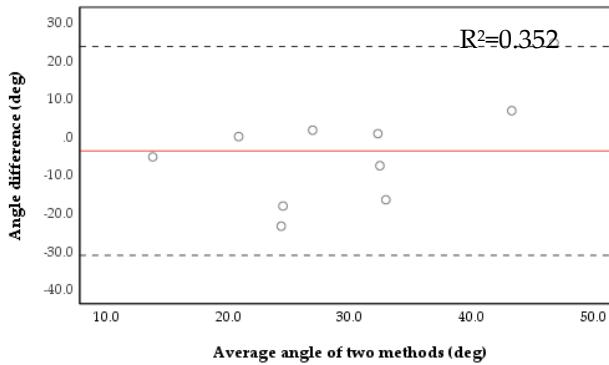
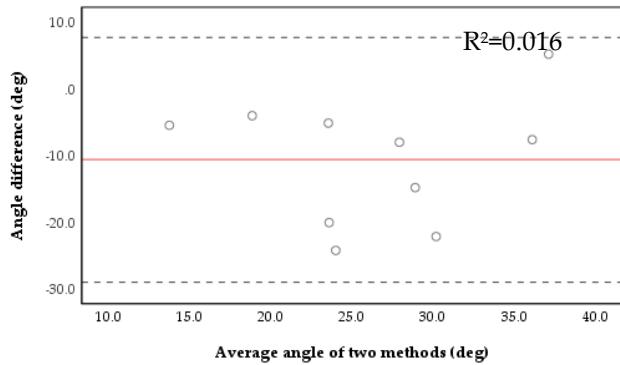
Minimum Knee flexion/extension angle



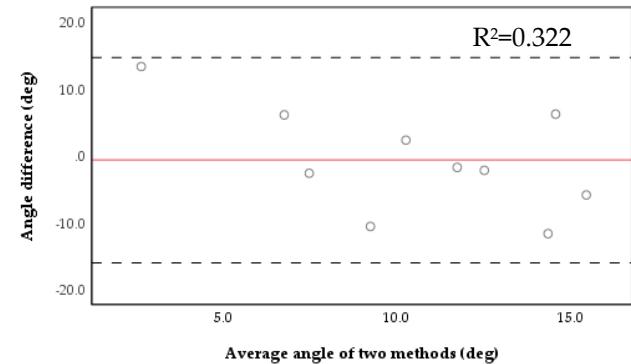
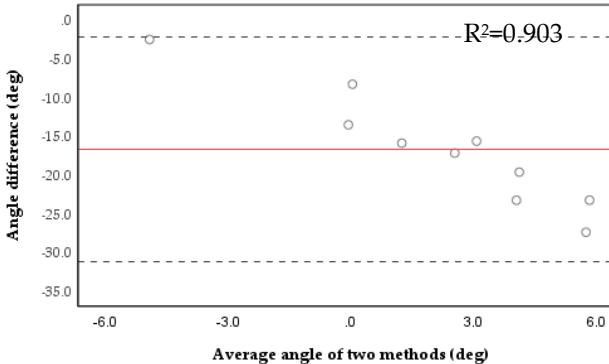
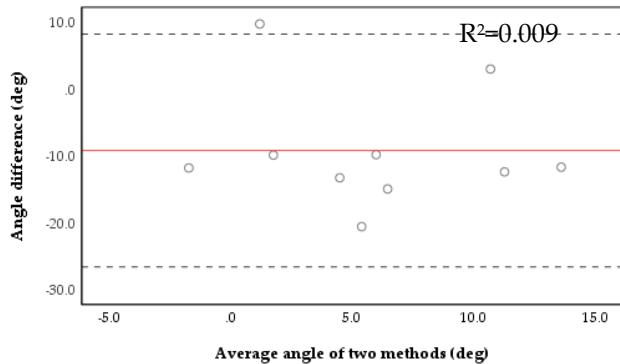
Knee flexion/extension ROM



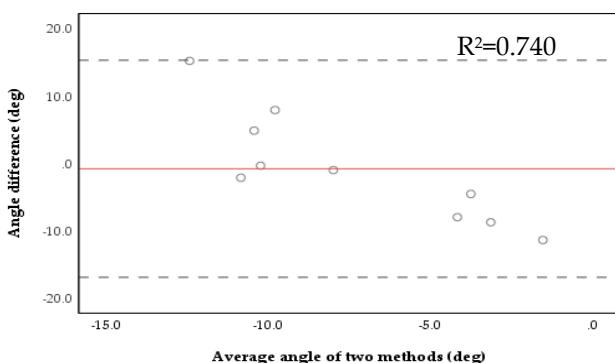
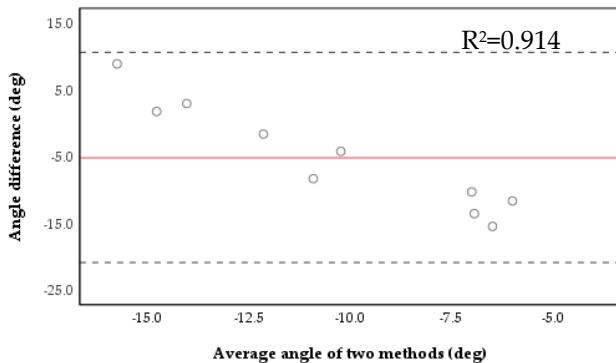
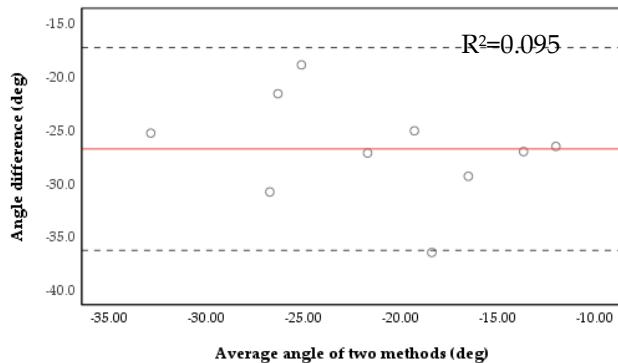
Knee flexion/extension angle at initial contact



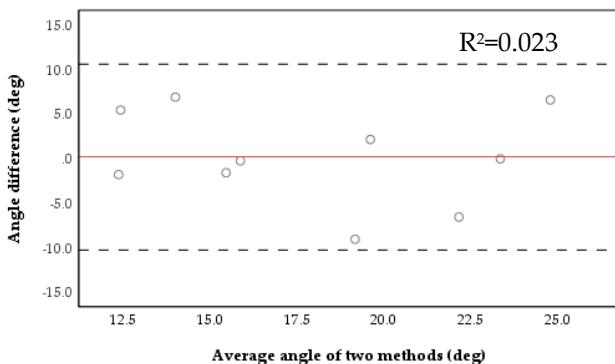
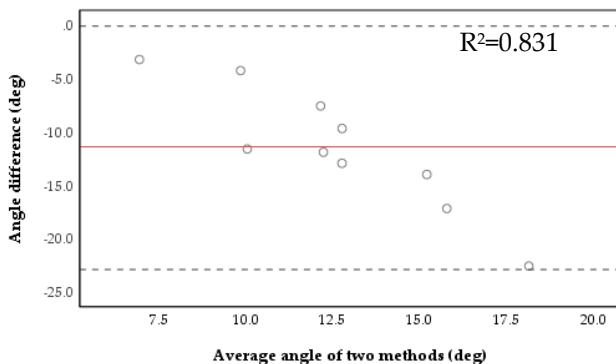
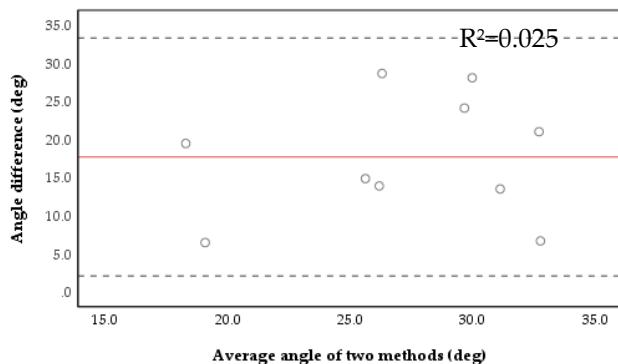
Maximum Ankle dorsiflexion/plantarflexion angle



Minimum Ankle dorsiflexion/plantarflexion angle



Ankle dorsiflexion/plantarflexion ROM



Ankle dorsiflexion/plantarflexion at initial contact

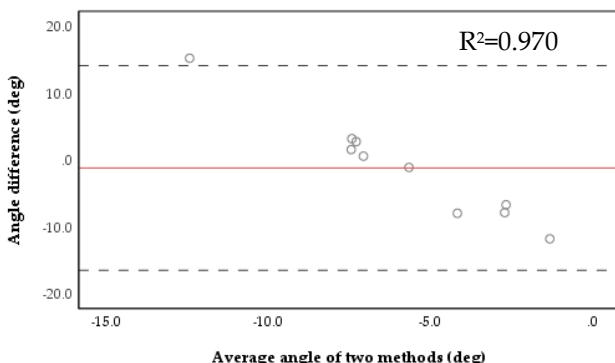
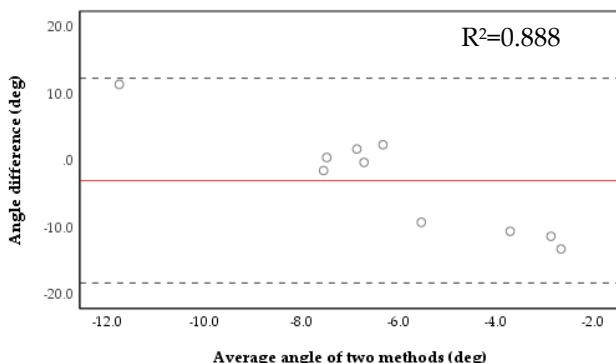
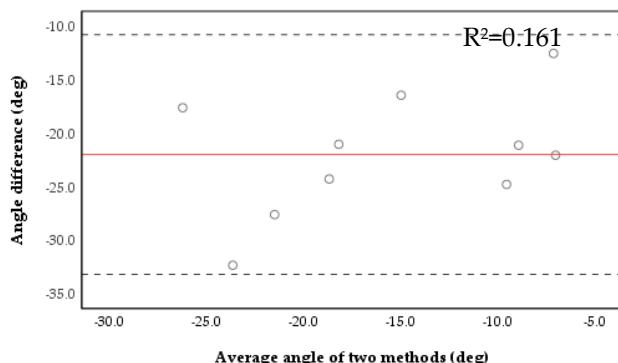


Figure 1S. Bland-Altman plots with 95% limits of agreement (LoA). X axes represents the angle means of two systems and the Y axes represents the mean of differences. The red line (middle one) represents the reference line at mean, and the two dashed lines represent the upper and lower limit of agreement. From left to right, the plots are measurement differences between "Kinect vs. Motion Analysis", "Kinect calibrated by linear regression vs. Motion Analysis" and "Kinect calibrated by LSTM vs Motion Analysis" respectively.

Table S1. Results of Bland-Altman analysis of agreement between joint kinematic parameter calculated from Kinect and Motion Analysis. Mean difference, limits of agreement (LoA), Lower LoA and Upper LoA are reported.

Kinematic parameter	Mean difference	LoA	Lower LoA	Upper LoA
Hip flexion/extension				
maximum	-15.5	18.8	-34.3	3.4
minimum	-22.4	22.2	-44.6	-0.2
ROM	6.9	19.9	-12.9	26.8
initial contact	-18.9	20.6	-39.5	1.7
Hip adduction/abduction				
maximum	-12.5	6.5	-19.0	-6.0
minimum	-9.2	10.7	-19.9	1.5
ROM	-3.3	10.2	-13.6	6.9
initial contact	-9.3	11.9	-21.3	2.6
Hip int/external rotation				
maximum	-5.9	30.1	-36.0	24.2
minimum	-63.4	85.7	-149.1	22.3
ROM	57.5	83.8	-26.3	141.3
initial contact	-9.8	49.8	-59.6	40.0
Knee flexion/extension				
maximum	-24.6	18.4	-43.0	-6.1
minimum	-4.5	18.6	-23.1	14.1
ROM	-20.1	29.5	-49.6	9.5
initial contact	-10.6	18.4	-29.0	7.7
Ankle dorsi/plantar flexion				
maximum	-9.2	17.4	-26.6	8.2
minimum	-26.8	9.5	-36.3	-17.3
ROM	17.7	15.6	2.1	33.3
initial contact	-22.0	11.2	-33.2	-10.8

Table S2. Results of Bland-Altman analysis of agreement between joint kinematic parameter calculated from Kinect (calibrated by linear regression method) and Motion Analysis. Mean difference, limits of agreement (LoA), Lower LoA and Upper LoA are reported.

Kinematic parameter	Mean difference	LoA	Lower LoA	Upper LoA
Hip flexion/extension				
maximum	-2.3	9.3	-20.5	15.8
minimum	-5.5	11.0	-27.0	16.0
ROM	3.2	9.6	-15.6	22.0
initial contact	-4.8	10.1	-24.7	15.0
Hip adduction/abduction				
maximum	-2.4	3.4	-9.2	4.3
minimum	2.1	5.0	-7.8	12.0
ROM	-4.5	5.2	-14.8	5.7
initial contact	1.3	5.6	-9.7	12.4
Hip int/external rotation				
maximum	-18.9	8.8	-36.2	-1.7
minimum	-14.0	10.3	-34.1	6.1
ROM	-4.9	5.4	-15.4	5.6
initial contact	-17.5	10.7	-38.5	3.6

Knee flexion/extension				
maximum	-0.6	12.7	-25.4	24.2
minimum	-4.6	10.8	-25.7	16.5
ROM	4.0	17.9	-31.1	39.1
initial contact	-3.8	14.0	-31.2	23.6
Ankle dorsi/plantar flexion				
maximum	-16.7	7.4	-31.2	-2.2
minimum	-5.2	8.0	-20.9	10.6
ROM	-11.5	5.8	-22.9	-0.1
initial contact	-3.1	7.8	-18.4	12.2

Table S3. Results of Bland-Altman analysis of agreement between joint kinematic parameter calculated from Kinect (calibrated by long short-term memory recurrent neural network) and Motion Analysis. Mean difference, limits of agreement (LoA), Lower LoA and Upper LoA are reported.

Kinematic parameter	Mean difference	LoA	Lower LoA	Upper LoA
Hip flexion/extension				
maximum	-3.1	10.1	-22.8	16.7
minimum	5.9	13.0	-19.6	31.5
ROM	-9.0	9.6	-27.9	9.9
initial contact	-1.6	9.5	-20.3	17.0
Hip adduction/abduction				
maximum	0.4	5.4	-10.2	11.0
minimum	0.5	4.9	-9.1	10.1
ROM	-0.1	7.1	-14.1	13.9
initial contact	0.4	6.3	-12.0	12.8
Hip int/external rotation				
maximum	0.9	12.2	-22.9	24.8
minimum	-1.4	11.0	-23.0	20.2
ROM	2.3	7.3	-12.0	16.6
initial contact	-0.1	11.6	-22.9	22.7
Knee flexion/extension				
maximum	-5.1	9.0	-22.8	12.5
minimum	1.6	11.8	-21.6	24.8
ROM	-6.7	12.8	-31.8	18.4
initial contact	-0.7	8.2	-16.8	15.3
Ankle dorsi/plantar flexion				
maximum	-0.6	7.8	-16.0	14.7
minimum	-0.8	8.2	-16.9	15.3
ROM	0.2	5.3	-10.3	10.6
initial contact	-1.2	7.8	-16.5	14.1