



## **Collaborative Robotics and Adaptive Machines**

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Deadline for manuscript  
submissions:

**closed (31 March 2023)**

### **Message from the Guest Editor**

The Special Issue will cover topics in the context of recent advances and future trends in collaborative robotics and adaptive machines including, but are not limited to the following:

- Collaboration modeling and collaboration dynamics
- Intelligent control strategies especially adaptive and predictive controls
- Artificial intelligence, machine learning, and vision-based algorithms
- Subtasks allocation and scheduling optimization
- Autonomy, team fluency, mixed initiatives, and mutual trust
- Bio-inspiration in human-robot or robot-robot collaboration
- Transparency, engagement, communication, safety, and efficiency
- Mechanisms and interface design, and passive compliance
- Security in collaborative robotics
- Task and motion planning in constrained spaces
- Collaboration or symbiosis in the forms of cyber-physical system (CPS) and internet of robotic things (IoRT)
- Ambient, embedded and cloud-based intelligence, and adaptive robotic ecology
- Collaborations in/with heterogeneous realities (e.g., real robot–virtual human collaboration)





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There are, in addition, unique features of this journal: Manuscripts regarding research proposals and research ideas will be particularly welcomed; Electronic files or software regarding the full details of the calculation and experimental procedure - if unable to be published in a normal way can be deposited as supplementary material.

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