



Advanced Control and Multiobjective Optimization of Multiple Industrial Robots

Guest Editors:

Prof. Dr. Yanling Wei

School of Automation, Southeast University, Nanjing 210096, China

Prof. Dr. Jinjun Shan

Department of Earth and Space Science and Engineering, York University, 4700 Keele Street, Toronto, ON M3J 1P3, Canada

Prof. Dr. Hamid Reza Karimi

Department of Mechanical Engineering, Politecnico di Milano, Via La Masa 1, 20156 Milan, Italy

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Message from the Guest Editors

Dear Colleagues,

With the integration of mechanical, information, electronics, control, intelligence, and other interdisciplinary studies, industrial robotic applications are becoming increasingly complex in both theoretical and practical aspects. Multiple industrial robots (MIRs) have been growing increasingly in various applications in recent years. The main motivation for employing MIRs is that they can be used to increase system effectiveness. With respect to a single autonomous robot or a team of noncooperating robots, MIRs can better perform a mission in terms of time and quality and can achieve tasks not executable by a single robot or can take advantage of distributed sensing and actuation. A wider spatial area can also be covered more efficiently if more robots are deployed, and heterogeneous capabilities can be distributed across the team without having to dramatically change the payload (and thus price) of individual robots.

The contributions to this Special Issue are expected to provide the latest results in collective analysis, estimation, optimization, coordinated control, and intelligent control of complex MIRs.





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Editor-in-Chief

Prof. Dr. Flavio Canavero

Department of Electronics and
Telecommunications,
Politecnico di Torino, 10129
Torino, Italy

Message from the Editor-in-Chief

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Electronics Editorial Office
MDPI, St. Alban-Anlage 66
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