





# Proceedings Ultrasonic Coupled Passive Wireless Oscillating Sensor System <sup>+</sup>

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**Abstract:** This paper presents, for the first time, an instrumentation technique for passively extracting a resonance frequency of a high-Q resonator across a wireless ultrasonic channel. As a first application, passive wireless measurement of temperature is presented along with a proof of concept of the wireless and passive operation of the device. Temperature resolution of 0.17 °C and a measurement range of 350 mm has been demonstrated.

**Keywords:** ultrasound; wireless sensor system; passive sensor node; temperature sensing oscillator; tuning fork resonator

#### 1. Introduction

Passive wireless sensing is an instrumentation technique that allows analog wireless measurement of a transducer element [1]. In the age of internet of things, this technology has a fair chance of transforming from the current niches of harsh environment industrial sensing to the mainstream market [2]. Conventional wireless communication based on electromagnetic wave propagation is ineffective in situations where the sensor-node is in a conductive enclosure, such as a Faraday cage, thus techniques based on ultrasonic propagation have been lately proposed [3].

The work presented here is an attempt to investigate a chipless approach by matching a tuning fork resonator with an ultrasonic transducer. First the concept of wireless interrogation of high-Q resonators is discussed, followed by a description of the experiment that tests the following hypothesis: Can ultrasonic transducers and crystal resonators be used as passive wireless sensors? This is then followed by a characterization of the sensor element and subsequent analysis of its performance.

#### 2. Concept for the Wireless Sensor System

Similar to wireless passive sensing using surface acoustic wave devices coupled to antennas [4], the approach presented here is based on a time domain separation of the transmitted and reflected signal. The wireless sensor system contains an excitation and receiving element with signal processing on the active part and a transceiver with an oscillating load on the passive sensor-node. The passive sensor-node consists of a resonator electrically connected to a radiating element, i.e., an ultrasonic transducer. Quality factor, the main figure of merit for a resonator in this application is defined as:

$$Q = \frac{\omega_0 W}{P}$$

where  $\omega_0$  is the resonance frequency, *W* is the energy stored in the resonator and *P* is the power dissipated. For resonators coupled with a radiating element, if the power dissipated to heat due to internal material and resistivity losses is low, the ringing time can be longer than environmental echoes, thus enabling a channel invariant measurement of the resonance frequency wirelessly.



Figure 1. Basic concept of a wireless readout of a resonance frequency using ultrasonic wave propagation.

External environmental factors like temperature influence material properties such as the stiffness tensor of a piezoelectric resonator. This causes a frequency shift of the resonant mode as explained by the harmonic perturbation theory. This effect can be used to measure temperature, passively over a wireless link and is demonstrated in Section 4.

#### 3. Proof of Concept

The main focus for the proof of concept lies on the passive extraction of a resonance frequency with wireless ultrasonic interrogation. Here, a temperature compensated quartz tuning fork resonator with a high-Q is used. A temperature sensing tuning fork resonator is presented later in this paper for the realization of the sensor system. The instrumentation setup is shown in Figure 2. The commercially available electronic components have a center frequency of 40 kHz and have been analyzed using a high precision impedance measurement.



**Figure 2.** Measurement setup with laboratory equipment for the proof of concept with a quartz tuning fork resonator.

A pulse width of 0.5 s is applied to the transmitter which results in a bandwidth of 2.4 Hz around the resonance. This causes the ringing of the high-Q resonator which allows for a time domain separation of Tx and Rx.

Figure 3 presents the measured time domain signal on the ultrasonic receiver. The excitation frequency decays after the burst in less than 2 ms and the high-Q resonator starts ringing in his

resonance frequency. The shift of frequency from the excitation to the resonance frequency proofs the presented concept.

A backscattered signal could be measured with a channel power of -36 dBmV over a distance of 350 mm with 100 ms burst at 2 V<sub>PP</sub> with and SNR of 10 dB.



**Figure 3.** Backscattered signal: (a) Excitation pulse width of 0.502 s and ringing of the high-Q factor resonator at resonance frequency with an envelope fit (red dashed) to the decay for Q factor calculation; (b) Shift from excitation frequency to resonance frequency.

#### 4. Sensor Characterization

As sensor a temperature sensing oscillator (TSXO) is used, implemented as tuning fork resonator. With its high-Q factor and low frequency in the kHz range it achieves long ringing times. For the measurement in figure 4 a temperature ramp from -30 °C to +90 °C is applied to the resonator in a climate chamber. It is interrogated using the burst mode technique and the temperature dependent resonance frequency is measured with a gated FFT in the unforced time frame, shown in Figure 3a as the red area. The excitation frequency is adjusted over the temperature ramp by setting it to the previously obtained resonance frequency completing the feedback chain of the presented digital-gated phased-locked loop [5].



**Figure 4.** (a) Characterization of the resonance frequency of the sensor element as function of the temperature with a quadratic fit (b) Residuals of the fitted curve in mHz.

The TSXO shows a quadratic temperature response with a sensitivity of -1.94 Hz/°C at 25 °C. The fitted curve has a value for R-squared of 1.0 and 4.3552 as norm of residuals with 1819 points. The parabola patterns in the residual plot suggest that the main reason for the residuals can be attributed to the quantization error of the temperature sensor used as reference with a resolution of 0.1 °C. The currently used FFT frequency bandwidth resolution of 0.34 Hz is limiting the

temperature resolution to 0.17 °C. As the Cramer Rao bound [6] is much lower, a better resolution for the temperature can be achieved.

### 5. Conclusions

This paper has presented, an instrumentation technique for extracting a resonance frequency of a high-Q resonator across a wireless ultrasonic channel. Passive wireless measurement of temperature is presented along with a proof of concept of the wireless and passive operation of the device. Temperature resolution of 0.17 °C and a measurement range of 350 mm has been demonstrated. It has been found that design and implementation of the presented system requires careful matching the resonance frequency and impedance between the transducer and the resonator. In addition, and depending on the noise levels of the environment, the Q factor of the resonator must be high (~100,000) for precise wireless extraction of the resonance frequency.

The novel wireless sensing technique presented in this contribution has significant potential applications with respect to measurements on moving parts, inside enclosed cavities and in submerged environments.

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