

Generating Geometric Patterns Using Complex Polynomials and Iterative Schemes

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Abstract: Iterative procedures have been proved as a milestone in the generation of fractals. This paper presents a novel approach for generating and visualizing fractals, specifically Mandelbrot and Julia sets, by utilizing complex polynomials of the form $Q_C(p) = ap^n + mp + c$, where $n \geq 2$. It establishes escape criteria that play a vital role in generating these sets and provides escape time results using different iterative schemes. In addition, the study includes the visualization of graphical images of Julia and Mandelbrot sets, revealing distinct patterns. Furthermore, the study also explores the impact of parameters on the deviation of dynamics, color, and appearance of fractals.

Keywords: iteration; fixed points; fractals

MSC: 47H10; 47J25



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1. Introduction

Complex graphics have drawn significant attention in the field of current research due to their captivating visual appeal, intricate nature, and repetitive patterns. Fractals are frequently seen in nature because they provide an appropriate explanation for a variety of natural phenomena, such as leaf patterns, tree branches, lightning, clouds, crystals, and many more. They play a vital role in examining various natural or biological structures, including microbial cultures. The exploration of fractals has become an intriguing area of study due to their captivating quality of self-replication. A fractal can be described as “an intricate mathematical shape that exhibits repeating patterns or structures, regardless of the level of magnification”.

The exploration of fractals began in the early twentieth century, as French mathematicians Gaston Maurice Julia and Pierre Joseph Louis Fatou endeavored to develop a systematic understanding of the complex function $Q_C(p) = p^2 + c$, where p is a complex variable and c is a complex number (for a detailed background and discussion, the readers are referred to [1–3]). In 1918, Julia [4] succeeded in iterating this function but faced challenges in visualizing it. Subsequently, in 1919, Fatou [5] initiated the investigation of Julia (abbreviated as $J.$) sets, leading to the designation of its complement as the Fatou set. The behavior of the function on the Fatou set demonstrates regularity, whereas on the $J.$ set, it exhibits chaotic behavior. Later, around 1980, Benoit B. Mandelbrot, a Polish-born French–American mathematician [6], visualized the $J.$ set and scrutinized its attributes. He coined the term “fractals” to describe these intricate graphs and earned the title of the “father of fractal geometry”. He observed that the $J.$ sets exhibit distinct characteristics for different values of the parameter c . Furthermore, through the interchange of the positions of p and c , he introduced a novel set called the Mandelbrot (abbreviated as $M.$) set, comprising

the parameters c for which the corresponding J . set remains connected. Conversely, in the J . set, the investigation revolves around the behavior of iterates for every value of p . In 1987, Lakhtakia et al. [7] extended this concept by employing $Q_{\mathbb{C}}(p) = p^n + c$, where $n \in \mathbb{N}$, and in 1989, Crowe et al. [8] visualized complex graphs for $p^2 + c$ and introduced the concept of anti- J . and anti- M . sets to explore their connected structures. In 2000, Rochon [9] studied a more generalized form of the M . set, which exists within a bicomplex plane. In 2008, some other generalized structures, namely, the superior J . and M . sets, for a general complex polynomial were analyzed by Negi et al. [10,11]. Various authors have employed diverse iterative techniques to create fractals. The exploration of the M . and J . sets has incorporated quadratic [12,13], cubic [14,15], and higher-degree polynomials [16] using the Picard orbit, which involves a one-step iteration process.

In 2004, Rani and Kumar [17,18] employed the one-step Mann iterative process to create superior J . and M . sets for complex polynomials of the n th degree, characterized by the form $Q_{\mathbb{C}}(p) = p^n + c$. In 2010, Rana et al. [19] and Chauhan et al. [20] expanded on this work by investigating a two-step Ishikawa iteration method to generate comparatively superior J . and M . sets. Through this approach, the authors identified unique J . and M . sets utilizing the Ishikawa orbit. Following this, in 2014, Rani et al. [21] delved into the three-step Noor iteration process for the construction of J . and M . sets. Subsequently, in 2015, Kang et al. [22,23] employed modified Ishikawa processes and S -iteration techniques to explore comparatively superior M . sets, as well as tricorns and multicorns. Furthermore, in 2016, Kumari et al. [24] uncovered generalizations of J . and M . sets applicable to quadratic, cubic, and higher-degree polynomials. They utilized a four-step iterative approach that surpasses the speed of the Picard, Mann, and S -iteration methods. In 2020, Abbas et al. [25] employed a three-step iterative process to produce J . and M . sets for complex polynomials of the n th degree, characterized by the form $Q_{\mathbb{C}}(p) = p^n + mp + r$. In 2022, Kumari et al. [26] introduced a methodology for visualizing M . and J . sets for complex polynomials expressed as $W(p) = p^n + mp + r$; $n \geq 2$, where $m, r \in \mathbb{C}$. They also devised a viscosity approximation method to generate biomorphs for any complex function.

Fascinated by the captivating images of fractals and intrigued to explore their generation using new polynomials, the main motivation behind the presented contribution was to delve into the potential of utilizing complex polynomials to create visually appealing fractal patterns. The current article explores various well-known iterations, some basic definitions, and a general escape criterion for the J . and M . sets in Section 2. Furthermore, Section 3 presents an analysis utilizing the iterative schemes proposed by Picard–Ishikawa [25] and Kalsoom et al. [27], incorporating a new polynomial, and establishing escape criteria to determine the escape radius for this process. In Sections 4 and 5, the construction of J . and M . sets, respectively, is illustrated using the escape criterion technique, accompanied by their visual representation. The subsequent section, Section 6, delves into a discussion on the M . sets generated by the Kalsoom et al. and Picard–Ishikawa iteration schemes. Finally, Section 7 serves as the conclusion, summarizing the findings and outlining potential directions for future study. While fractal generation using complex polynomials has shown encouraging potential, it is important to consider limitations or challenges that may affect the applicability and effectiveness of the proposed method. The research may not have compared the performance of the proposed method with different existing iterative schemes and polynomials. As a result, it is challenging to assess its superiority over alternative approaches.

2. Materials and Methods

In this section, some iterations and the definitions of J . and M . sets, as well as the link between them, are given. Both sets are developed by dynamical systems and may exhibit fractal behavior. The following nomenclature is used throughout the paper:

$Q_{\mathbb{C}}$	Complex polynomial
p, q, r, t	Complex variables
μ, ν, ω, m, c	Complex parameters

Definition 1. Let $Q_{\mathbb{C}} : \mathbb{C} \rightarrow \mathbb{C}$ and $p_0 \in \mathbb{C}$. Then

- The Picard orbit [12] is a sequence $\{p_i\}$ that is given by

$$p_{i+1} = Q_{\mathbb{C}}(p_i), \quad \text{for } i \geq 0.$$

- The Mann iterative method [28] is defined as

$$p_{i+1} = (1 - \mu)p_i + \mu Q_{\mathbb{C}}(p_i),$$

where $i = 0, 1, 2, \dots$ and $\mu \in (0, 1]$.

- The Ishikawa iterative method [29] is defined as

$$\begin{cases} p_{i+1} = (1 - \mu)p_i + \mu Q_{\mathbb{C}}(q_i), \\ q_i = (1 - \nu)p_i + \nu Q_{\mathbb{C}}(p_i), \end{cases}.$$

where $i = 0, 1, 2, \dots$ and $\mu, \nu \in (0, 1]$.

- The Noor iterative method [30] is defined as

$$\begin{cases} p_{i+1} = (1 - \mu)p_i + \mu Q_{\mathbb{C}}(q_i), \\ q_i = (1 - \nu)Q_{\mathbb{C}}(p_i) + \nu Q_{\mathbb{C}}(r_i), \\ r_i = (1 - \omega)Q_{\mathbb{C}}(p_i) + \omega Q_{\mathbb{C}}(p_i), \end{cases}.$$

where $i = 0, 1, 2, \dots$ and $\mu, \nu, \omega \in (0, 1]$.

- The S-orbit [31] is a sequence p_i that is given by

$$\begin{cases} p_{i+1} = (1 - \mu)p_i + \mu Q_{\mathbb{C}}(q_i), \\ q_i = (1 - \nu)p_i + \nu Q_{\mathbb{C}}(p_i), \end{cases}.$$

where $i = 0, 1, 2, \dots$ and $\mu, \nu \in (0, 1]$.

- The Picard–Ishikawa [25] orbit is a sequence p_i that is given by

$$\begin{cases} p_{i+1} = (1 - \mu)q_i + \mu Q_{\mathbb{C}}(q_i), \\ q_i = Q_{\mathbb{C}}(r_i), \\ r_i = Q_{\mathbb{C}}(t_i), \\ t_i = (1 - \nu)p_i + \nu Q_{\mathbb{C}}(p_i), \end{cases} \tag{1}$$

where $i = 0, 1, 2, \dots$ and $\mu, \nu, \omega \in (0, 1]$.

- The Kalsoom et al. [27]–type orbit, centered around any $p_0 \in \mathbb{C}$, is a sequence $\{p_i\}$ defined by

$$\begin{cases} p_{i+1} = Q_{\mathbb{C}}(t_i) \\ t_i = (1 - \mu)Q_{\mathbb{C}}(p_i) + \mu Q_{\mathbb{C}}(q_i) \\ q_i = (1 - \nu)r_i + \nu Q_{\mathbb{C}}(r_i), \\ r_i = (1 - \omega)p_i + \omega Q_{\mathbb{C}}(p_i), \end{cases} \tag{2}$$

where $i = 0, 1, 2, \dots$ and $\mu, \nu, \omega \in (0, 1]$.

Definition 2 ([32]). Let $Q_{\mathbb{C}}$ be any complex polynomial of the degree $n \geq 2$. Let K_Q be the set of points in \mathbb{C} whose orbits do not converge to the point at infinity, that is,

$$K_Q = \{p \in \mathbb{C} : \{|Q_{\mathbb{C}}^i(p)|\}_{i=0}^{\infty} \text{ is bounded}\}.$$

K_Q is called the filled J. set of the polynomial $Q_{\mathbb{C}}$. The set of boundary points of K_Q is called the simple J. set.

Definition 3 ([25]). Let $Q_{\mathbb{C}}$ be any complex polynomial of the degree $n \geq 2$. The M. set M consists of all parameters c for which the filled J. set of $Q_{\mathbb{C}}$ is connected; that is,

$$M = \{c \in \mathbb{C} : J_{Q_{\mathbb{C}}} \text{ is connected}\}.$$

Equivalently, the M . set can be defined as follows [33]:

$$M = \{c \in \mathbb{C} : \{|Q_c^n(0)|\} \rightarrow \infty \text{ as } n \rightarrow \infty\}.$$

Tingen [34] explained the following basic definitions in his doctoral dissertation.

Definition 4. A dynamical system is a rule, $Q_{\mathbb{C}} : \mathbb{C} \rightarrow \mathbb{C}$, which determines the present state of our system in terms of past states. The actual dynamics of the system are found in the behavior of the points $p_0 = Q_{\mathbb{C}}^n(p_0)$ under the iteration of $Q_{\mathbb{C}}$, where $n = 0, 1, 2, \dots$.

Definition 5. Iterating a function means evaluating it repeatedly, each time using the previous application’s output as the input for the next. This is the same as typing a number into a calculator and then continually pressing a function key like “sin” or “cos”. Mathematically, this is the process of repeatedly composing the function with itself. We write it as, for a function $Q_{\mathbb{C}}$, $Q_{\mathbb{C}}^2(p)$ is the second iterate of $Q_{\mathbb{C}}$, namely, $Q_{\mathbb{C}}(Q_{\mathbb{C}}(p))$; $Q_{\mathbb{C}}^3(p)$ is the third iterate $Q_{\mathbb{C}}(Q_{\mathbb{C}}(Q_{\mathbb{C}}(p)))$; and in general, $Q_{\mathbb{C}}^n(p)$ is the n -fold composition of $Q_{\mathbb{C}}$ with itself.

Definition 6. The orbit of p_0 under $Q_{\mathbb{C}}$ is the sequence of the points $p_0, p_1 = Q_{\mathbb{C}}(p_0), p_2 = Q_{\mathbb{C}}^2(p_0), \dots, p_n = Q_{\mathbb{C}}^n(p_0), \dots$, where $p_0 \in \mathbb{C}$. The point p_0 is called the seed of the orbit.

Definition 7. An element $p_0 \in \mathbb{C}$ is a fixed point of $Q_{\mathbb{C}} : \mathbb{C} \rightarrow \mathbb{C}$ if $Q_{\mathbb{C}}(p_0) = p_0$.

Tingen [34] also explained the fixed point. A fixed point has different behaviors. These behaviors are defined as follows:

Definition 8. Suppose p_0 is the fixed point of $Q_{\mathbb{C}}$. Then p_0 is an attracting fixed point if $|Q'_{\mathbb{C}}(p_0)| < 1$. The point p_0 is a repelling fixed point if $|Q'_{\mathbb{C}}(p_0)| > 1$. Finally, if $|Q'_{\mathbb{C}}(p_0)| = 1$, the fixed point is called neutral or indifferent.

The general escape criterion for the J . and Mandelbrot sets is as follows:

Theorem 1 ([12]). For $Q_c(p) = p^2 + c$, where $p, c \in \mathbb{C}$. If there exists $i \geq 0$ such that

$$|Q_c^i(p)| > \max\{|c|, 2\},$$

then $Q_c^i(p) \rightarrow \infty$ as $i \rightarrow \infty$.

The phrase $\max\{|c|, 2\}$ is also referred to as the “escape radius”. After each iteration, it is converging within the escape radius. With an increase in the number of iterations, our figures become more detailed. When it comes to visualizing fractals, the escape radius is crucial because it is a vital key to run the algorithm.

3. Convergence Results

In this section, we use Kalsoom et al. [27] and Picard–Ishikawa [25] iterative schemes with a new polynomial $Q_{\mathbb{C}}(p) = ap^n + mp + c$ and prove some escape criteria to obtain the escape radius for this process. Algorithms 1 and 2 for creating J . and M . sets cannot run without the use of an escape criterion. For the higher polynomial $Q_{\mathbb{C}}(p) = ap^n + mp + c$, where $a, m, c \in \mathbb{C}$, the following is the outcome.

Theorem 2. Assume that $|p_0| - 2\mu|q_0||a(p_0^{n-1} + p_0^{n-2}q_0 + \dots + p_0q_0^{n-2} + q_0^{n-1}) + m| \geq |c| > \max\left\{\left(\frac{2(1+|m|)}{\mu|a|}\right)^{\frac{1}{n-1}}, \left(\frac{2(1+|m|)}{\nu|a|}\right)^{\frac{1}{n-1}}, \left(\frac{2(1+|m|)}{\omega|a|}\right)^{\frac{1}{n-1}}\right\}$, $\mu, \nu, \omega \in (0, 1), a \neq 0$. Define $\{p_i\}_{i \in \mathbb{N}}$ as in (2), where p_0, q_0, r_0 , and t_0 are the initial points of p_i, q_i, r_i , and t_i , respectively. Then, $|p_i| \rightarrow \infty$ as $i \rightarrow \infty$.

Proof. As $Q_{\mathbb{C}}(p) = ap^n + mp + c$, from (2), we have the following:

$$|r_i| = |(1 - \omega)p_i + \omega Q_{\mathbb{C}}(p_i)|.$$

For $i = 0$, we have the following:

$$\begin{aligned}
 |r_0| &= |(1 - \omega)p_0 + \omega Q_{\mathbb{C}}(p_0)| \\
 &= |(1 - \omega)p_0 + \omega(ap_0^n + mp_0 + c)| \\
 &\geq |\omega ap_0^n + (1 - \omega)p_0 + \omega mp_0| - |\omega c| \\
 &\geq |\omega ap_0^n| - |(1 - \omega)p_0| - |\omega mp_0| - \omega |c| \\
 &> |\omega ap_0^n| - |p_0| + \omega |p_0| - |\omega mp_0| - \omega |p_0| \\
 &\geq |\omega ap_0^n| - |p_0| - |\omega mp_0| \\
 &\geq |p|(\omega |a| |p_0^{n-1}| - (1 + \omega |m|)).
 \end{aligned}$$

Since $\omega \leq 1$, we obtain $-(1 + \omega |m|) > -(1 + |m|)$, which implies the following:

$$|r_0| > |p_0|(\omega |a| |p_0^{n-1}| - (1 + |m|)).$$

Therefore,

$$|r_0| > |p_0| \left(\frac{\omega |a| |p_0^{n-1}|}{1 + |m|} - 1 \right).$$

From our supposition, $|p_0| > \max \left\{ \left(\frac{2(1+|m|)}{\mu|a|} \right)^{\frac{1}{n-1}}, \left(\frac{2(1+|m|)}{\nu|a|} \right)^{\frac{1}{n-1}}, \left(\frac{2(1+|m|)}{\omega|a|} \right)^{\frac{1}{n-1}} \right\}$, we obtain $\left(\frac{\omega |a| |p_0^{n-1}|}{1 + |m|} - 1 \right) > 1$. Therefore,

$$|r_0| > |p_0|. \tag{3}$$

For the second step of the iteration, we have $|q_0| = |(1 - \nu)r_0 + \nu Q_{\mathbb{C}}(r_0)| = |(1 - \nu)r_0 + \nu(ar_0^n + mr_0 + c)|$. By using the same method as above, we obtain the following:

$$|q_0| > |p_0| \left(\frac{\nu |a| |p_0^{n-1}|}{1 + |m|} - 1 \right) > |p_0|.$$

Moreover, from (2), we have the following:

$$|t_i| = |(1 - \mu)Q_{\mathbb{C}}(p_i) + \mu Q_{\mathbb{C}}(q_i)|$$

For $i = 0$, we obtain the following:

$$\begin{aligned}
 |t_0| &= |(1 - \mu)Q_{\mathbb{C}}(p_0) + \mu Q_{\mathbb{C}}(q_0)| \\
 &= |(1 - \mu)(ap_0^n + mp_0 + c) + \mu(aq_0^n + mq_0 + c)| \\
 &= |ap_0^n + mp_0 + c - \mu(a(p_0^n - q_0^n) + m(p_0 - q_0))| \\
 &= |ap_0^n + mp_0 + c - \mu(p_0 - q_0)(a(p_0^{n-1} + p_0^{n-2}q_0 + \dots + p_0q_0^{n-2} + q_0^{n-1}) + m)| \\
 &\geq |ap_0^n + mp_0| - |c| - \mu |p_0 - q_0| |a(p_0^{n-1} + p_0^{n-2}q_0 + \dots + p_0q_0^{n-2} + q_0^{n-1}) + m| \\
 &\geq |ap_0^n + mp_0| - |c| - \mu(|p_0| + |q_0|) |a(p_0^{n-1} + p_0^{n-2}q_0 + \dots + p_0q_0^{n-2} + q_0^{n-1}) + m| \\
 &> |ap_0^n + mp_0| - |c| - 2\mu |q_0| |a(p_0^{n-1} + p_0^{n-2}q_0 + \dots + p_0q_0^{n-2} + q_0^{n-1}) + m| \\
 &> |ap_0^n + mp_0| - |p_0| + 2\mu |q_0| |a(p_0^{n-1} + p_0^{n-2}q_0 + \dots + p_0q_0^{n-2} + q_0^{n-1}) + m| - \\
 &\quad 2\mu |q_0| |a(p_0^{n-1} + p_0^{n-2}q_0 + \dots + p_0q_0^{n-2} + q_0^{n-1}) + m|
 \end{aligned}$$

$$\begin{aligned}
 &\geq \mu|a||p_0^n| - |m||p_0| - |p_0| \\
 &\geq |p_0|(\mu|a||p_0^{n-1}| - (1 + |m|)) \\
 &\geq |p_0|(1 + |m|)\left(\frac{\mu|a||p_0^{n-1}|}{1 + |m|} - 1\right).
 \end{aligned}$$

Therefore,

$$|t_0| > |p_0|\left(\frac{\mu|a||p_0^{n-1}|}{1 + |m|} - 1\right).$$

From our supposition, $|p_0| > \max\left\{\left(\frac{2(1+|m|)}{\mu|a|}\right)^{\frac{1}{n-1}}, \left(\frac{2(1+|m|)}{\nu|a|}\right)^{\frac{1}{n-1}}, \left(\frac{2(1+|m|)}{\omega|a|}\right)^{\frac{1}{n-1}}\right\}$, we obtain $\left(\frac{\mu|a||p_0^{n-1}|}{1+|m|} - 1\right) > 1$. Consequently,

$$|t_0| > |p_0|. \tag{4}$$

Now, we have the following:

$$\begin{aligned}
 |p_1| &= |Q_C(t_0)| \\
 &= |at_0^n + mt_0 + c| \\
 &\geq |at_0^n + mt_0| - |c| \\
 &\geq \mu|a||t_0^n| - |m||t_0| - |t_0| \\
 &\geq |t_0|(\mu|a||t_0^{n-1}| - (1 + |m|))
 \end{aligned}$$

$$|p_1| \geq |p_0|\left(\frac{\mu|a||p_0^{n-1}|}{1 + |m|} - 1\right).$$

From the hypothesis of the theorem, we have $|p_0| > \left(\frac{2(1+|m|)}{\mu|a|}\right)^{\frac{1}{n-1}}$.

This implies that $\left(\frac{\mu|a||p_0^{n-1}|}{1+|m|} - 1\right) > 1$. Hence, there exists $\epsilon > 0$ such that

$$\left(\frac{\mu|a||p_0^{n-1}|}{1 + |m|} - 1\right) > 1 + \epsilon.$$

Therefore,

$$|p_1| > (1 + \epsilon)|p_0|.$$

In particular, $|p_1| > |p_0|$. Continuing in the same manner, we obtain the following:

$$|p_i| > (1 + \epsilon)^i |p_0|.$$

Hence, $|p_i| \rightarrow \infty$ as $i \rightarrow \infty$. \square

Escape Criterion 1. Suppose that $|p_i| > \max\left\{|c|, \left(\frac{2(1+|m|)}{\mu|a|}\right)^{\frac{1}{n-1}}, \left(\frac{2(1+|m|)}{\nu|a|}\right)^{\frac{1}{n-1}}, \left(\frac{2(1+|m|)}{\omega|a|}\right)^{\frac{1}{n-1}}\right\}$, where $\mu, \nu, \omega \in (0, 1]$. Then, for $i \in \mathbb{N}$, $|p_i| \rightarrow \infty$ as $i \rightarrow \infty$.

Theorem 3. Assume that $|p_0| \geq |c| > \max\left\{\left(\frac{2(1+|m|)}{\mu|a|}\right)^{\frac{1}{n-1}}, \left(\frac{2(1+|m|)}{\nu|a|}\right)^{\frac{1}{n-1}}\right\}$, with $n \geq 2$ and $\mu, \nu \in (0, 1]$. Define $\{p_i\}_{i \in \mathbb{N}}$ as in (1), where p_0, q_0, r_0 , and t_0 are the initial points of p_i, q_i, r_i , and t_i , respectively. Then, $|p_i| \rightarrow \infty$ as $i \rightarrow \infty$.

Proof. As $Q_{\mathbb{C}}(p) = ap^n + mp + c$, from (1), we obtain the following:

$$|t_i| = |(1 - \nu)p_i + \nu Q_{\mathbb{C}}(p_i)|$$

For $i = 0$, we obtain the following:

$$\begin{aligned} |t_0| &= |(1 - \nu)p_0 + \nu Q_{\mathbb{C}}(p_0)| \\ &= |(1 - \nu)p_0 + \nu(ap_0^n + mp_0 + c)| \\ &\geq |\nu ap_0^n + \nu mp_0| - (1 - \nu)|p_0| - \nu|c| \\ &\geq |\nu ap_0^n| - |\nu mp_0| - |p_0| + \nu|p_0| - \nu|p_0| \\ &\geq \nu|a||p_0^n| - |m||p_0| - |p_0|. \end{aligned}$$

Therefore,

$$|t_0| \geq |p_0| \left(\frac{\nu|a||p_0^{n-1}|}{1 + |m|} - 1 \right). \tag{5}$$

The assumption, $|p_0| > \max\left\{ \left(\frac{2(1+|m|)}{\mu|a|} \right)^{\frac{1}{n-1}}, \left(\frac{2(1+|m|)}{\nu|a|} \right)^{\frac{1}{n-1}} \right\}$, implies the following:

$$\left(\frac{\nu|a||p_0^{n-1}|}{1 + |m|} - 1 \right) > 1. \tag{6}$$

By using (6), we obtain the following:

$$|t_0| > |p_0|. \tag{7}$$

By (1), we have the following:

$$\begin{aligned} |r_0| &= |Q_{\mathbb{C}}(t_0)| \\ &= |at_0^n + mt_0 + c| \\ &\geq |at_0^n + mt_0| - |c|. \end{aligned}$$

As $\nu \leq 1$, from (7) and supposition $|p_0| \geq |c|$, we obtain the following:

$$\begin{aligned} |r_0| &\geq |at_0^n + mt_0| - |p_0| \\ &\geq \nu|a||t_0^n| - |m||t_0| - |t_0| \\ &\geq |t_0|(\nu|a||t_0^{n-1}| - (1 + |m|)); \end{aligned}$$

further, it implies the following:

$$|r_0| \geq |t_0| \left(\frac{\nu|a||t_0^{n-1}|}{(1 + |m|)} - 1 \right).$$

Now, by (6) and (7), we have the following:

$$\left(\frac{\nu|a||t_0^{n-1}|}{1 + |m|} - 1 \right) \geq \left(\frac{\nu|a||p_0^{n-1}|}{1 + |m|} - 1 \right) > 1. \tag{8}$$

Hence,

$$|r_0| > |p_0|. \tag{9}$$

Moreover, using the same method as before, we obtain the following:

$$|q_0| \geq |p_0| \left(\frac{\nu|a||p_0^{n-1}|}{1+|m|} - 1 \right) > |p_0|,$$

which implies

$$|q_0| > |p_0|. \tag{10}$$

Last step of the iteration:

$$\begin{aligned} |p_1| &= |(1-\mu)q_0 + \mu Q_{\mathbb{C}}(q_0)| \\ &= |(1-\mu)q_0 + \mu(aq_0^n + mq_0 + c)|. \end{aligned}$$

The assumption $|p_0| \geq |c|$ (10) and $\mu \leq 1$ yield the following:

$$\begin{aligned} |p_1| &\geq |(1-\mu)q_0 + \mu(aq_0^n + mq_0)| - \mu|c| \\ &\geq \mu|a||q_0^n| - (1+\mu|m|)|q_0| \\ &\geq |q_0|(\mu|a||q_0^{n-1}| - (1+\mu|m|)) \\ &\geq |p_0| \left(\frac{\mu|a||p_0^{n-1}|}{1+|m|} - 1 \right). \end{aligned}$$

Since $|p_0| > \left(\frac{2(1+|m|)}{\mu|a|}\right)^{\frac{1}{n-1}}$, which yields $\left(\frac{\mu|a||p_0^{n-1}|}{1+|m|} - 1\right) > 1$. Thus, there is a positive number $\epsilon > 0$ such that

$$\left(\frac{\mu|a||p_0^{n-1}|}{1+|m|} - 1\right) > 1 + \epsilon.$$

It follows from above that

$$|p_1| > (1 + \epsilon)|p_0|$$

Particularly, we have the following:

$$|p_1| > |p_0|.$$

Continuing in the same manner yields the following:

$$|p_i| > (1 + \epsilon)^i |p_0|.$$

Therefore, $|p_i| \rightarrow \infty$ as $i \rightarrow \infty$. \square

Escape Criterion 2. Assume that $|p_i| > \max\left\{ |c|, \left(\frac{2(1+|m|)}{\mu|a|}\right)^{\frac{1}{n-1}}, \left(\frac{2(1+|m|)}{\nu|a|}\right)^{\frac{1}{n-1}} \right\}$, with $n \geq 2$ and $\mu, \nu \in (0, 1]$. Then, $|p_i| \rightarrow \infty$ as $i \rightarrow \infty$.

Algorithm 1 Generation of J . set.

Input: $Q_{\mathbb{C}} : \mathbb{C} \rightarrow \mathbb{C}$ —complex polynomial, $A \subset \mathbb{C}$ —area, N —maximum number of iterations, $\mu, \nu, \omega \in (0, 1]$ —involved parameters, colormap $[0 \dots M - 1]$ —colormap with M colors.

Output: J . set for the area A .

```

1: R = Escape radius
2: for  $p_0 \in A$  do
3:    $i = 0$ 
4:   while  $i \leq N$  do
5:     Proposed iterative method
6:     if  $|p_{i+1}| > R$  then
7:       break
8:     end if
9:      $i = i + 1$ 
10:  end while
11:   $m = \lfloor (M - 1) \frac{i}{N} \rfloor$ 
12:  color  $p_0$  with colormap  $[m]$ 
13: end for

```

Algorithm 2 Generation of M . set.

Input: $Q_{\mathbb{C}} : \mathbb{C} \rightarrow \mathbb{C}$ —complex polynomial, $A \subset \mathbb{C}$ —area, N —maximum number of iterations, $\mu, \nu, \omega \in (0, 1]$ —involved parameters, colormap $[0 \dots M - 1]$ — colormap with M colors.

Output: M . set for the area A .

```

1: for  $c \in A$  do
2:   R = Escape radius
3:    $i = 0$ 
4:    $p_0 =$  critical point of  $Q_{\mathbb{C}}$ 
5:   while  $i \leq N$  do
6:     Proposed iterative method
7:     if  $|p_{i+1}| > R$  then
8:       break
9:     end if
10:     $i = i + 1$ 
11:  end while
12:   $m = \lfloor (M - 1) \frac{i}{N} \rfloor$ 
13:  color  $c$  with colormap  $[m]$ 
14: end for

```

4. Visualization of J . Sets

Authors have utilized a variety of methods to create fractals in the literature. Distance estimator [35], escape criterion [36], and potential function algorithms [37,38] are some common fractal visualization techniques. In this section, we use the escape criterion technique to construct J . sets. The escape time algorithm will continue executing the function until the value of the function exceeds the certain escape radius. The procedure generates two sets, one consisting of points where the orbits do not escape to infinity, i.e., J . set, and the other consisting of points where the orbits do escape to infinity, i.e., Fatou domains. Furthermore, we show J . sets at various n and input parameter values. We develop a number of new fractals with diverse mathematical shapes that are captivating. Due to changing input parameters, we observe the clear variation of colors and the shape of fractals.

4.1. Generation of J . Sets in Kalsoom et al. Iteration

Algorithm 1 is the pseudocode for the creation of J . sets.

We show quadratic, cubic, and higher-degree J . sets in a Kalsoom at al.–type orbit for the complex polynomial $Q_C(p) = ap^n + mp + c$.

1. For Figure 1, the polynomial $Q_C(p) = (0.02 - 1.04i)p^2 + (0.08 - 0.07i)p + (-0.1 + 0.17i)$ and $A = [-2.5, 2.5]^2$ is considered. We can observe that the J . sets in Figure 1a,b are spread and stretched, while the J . sets in Figure 1c,d are dense and tightly packed. Additionally, two connected and two disconnected J . sets are shown. It can easily be seen that Figure 1 resembles the shape of clouds.
2. In Figure 2, the polynomial $Q_C(p) = (1.2 + 1.01i)p^3 + (0.027 + 0.08i)p + (0.17 + 0.45i)$ and $A = [-1.5, 1.5]^2$ is considered. We have comparable shapes, but the colors differ significantly. Additionally, Figure 2a,b depict the disconnectivity of orbits of the J . sets, while Figure 2c,d exhibit connectivity among their orbits.
3. For Figure 3, the polynomial $Q_C(p) = (0.2 + 1.01i)p^{15} + (0.2 + 0.12i)p + (0.35 + 0.557i)$ and $A = [-2.3, 2.3]^2$ is considered.

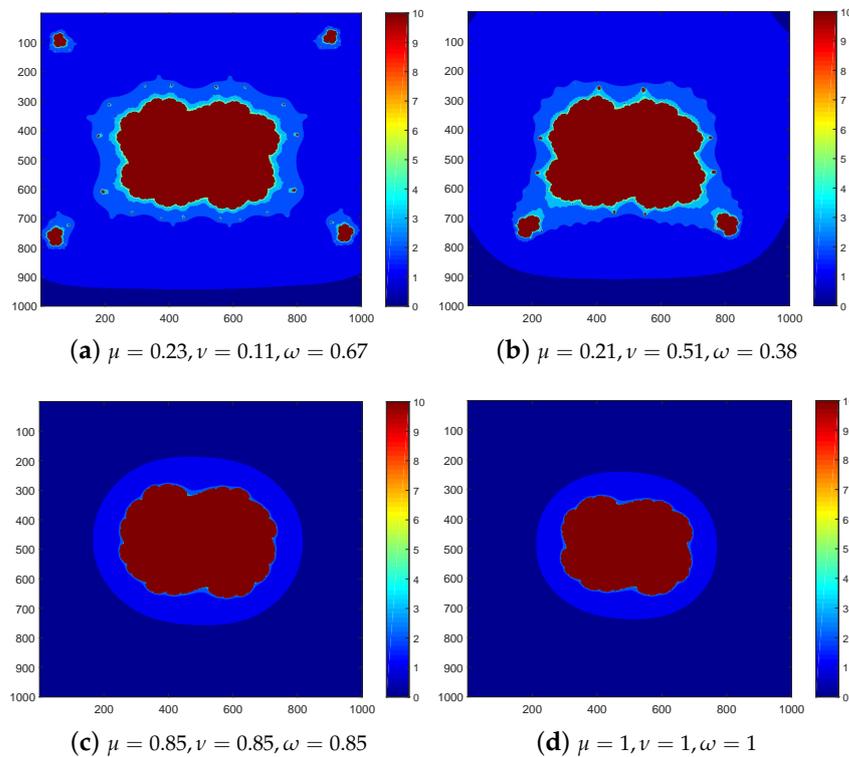


Figure 1. J . sets of $Q_C(p) = ap^n + mp + c$ with $n = 2$.

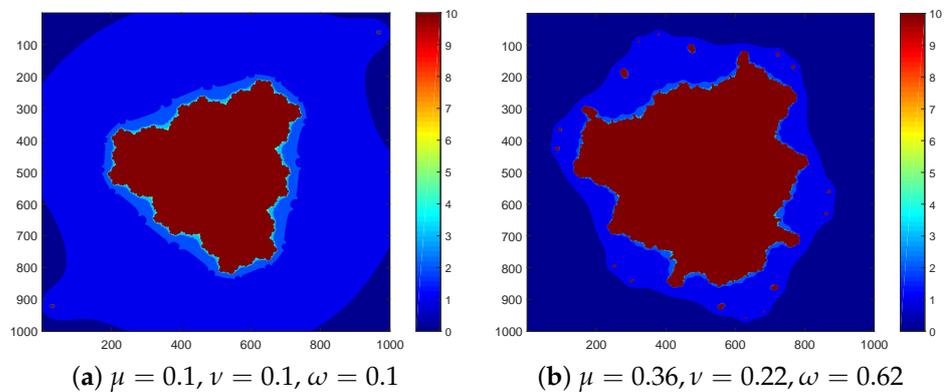


Figure 2. Cont.

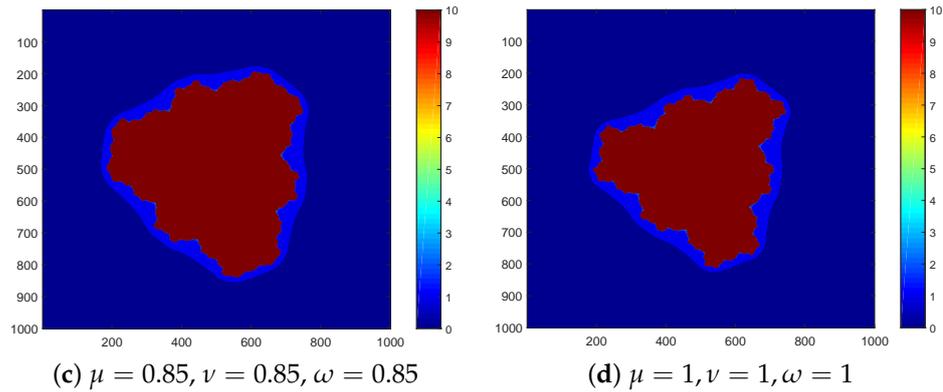


Figure 2. J . sets of $Q_C(p) = ap^n + mp + c$ with $n = 3$.

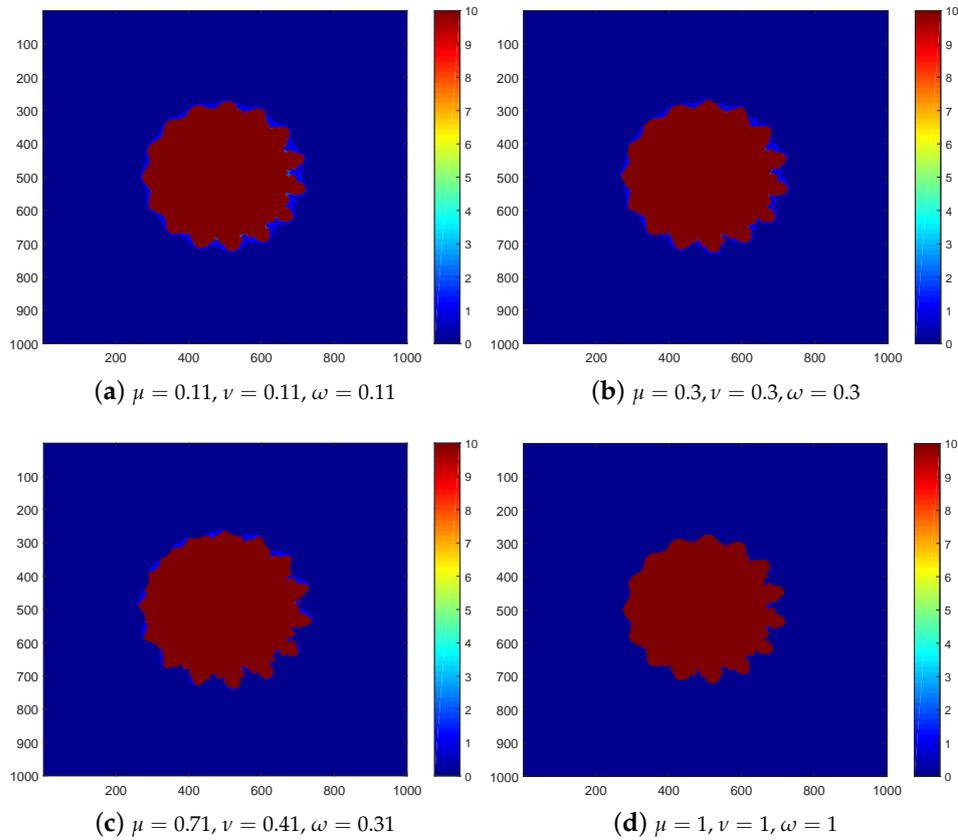


Figure 3. J . sets of $Q_C(P) = ap^n + mp + c$ with $n = 15$.

4.2. Generation of J . Sets in Picard–Ishikawa Iteration

We show quadratic, cubic, and higher-degree J . sets in a Picard–Ishikawa–type orbit for the complex polynomial $Q_C(p) = ap^n + mp + c$.

1. For Figure 4, the polynomial $Q_C(p) = (0.02 - 1.04i)p^2 + (0.08 - 0.07i)p + (-0.1 + 0.17i)$ and $A = [-2.5, 2.5]^2$ is considered. We can observe that the shape in Figure 4a provides a disconnected J . set, while Figure 4b–d give connected J . sets. We can also observe that the lower the value of parameters is, the bigger the set shape changes. For $\mu = 0.23$ and $\nu = 0.11$, the difference in shapes is significant.
2. For Figure 5, the polynomial $Q_C(p) = (1.2 + 1.01i)p^3 + (0.027 + 0.08i)p + (0.17 + 0.45i)$ and $A = [-1.5, 1.5]^2$ is considered. Although our shapes are identical, there is a significant color difference.
3. In Figure 6, the polynomial $Q_C(p) = (0.2 + 1.01i)p^{15} + (0.2 + 0.12i)p + (0.35 + 0.557i)$ and $A = [-2.3, 2.3]^2$ is considered.

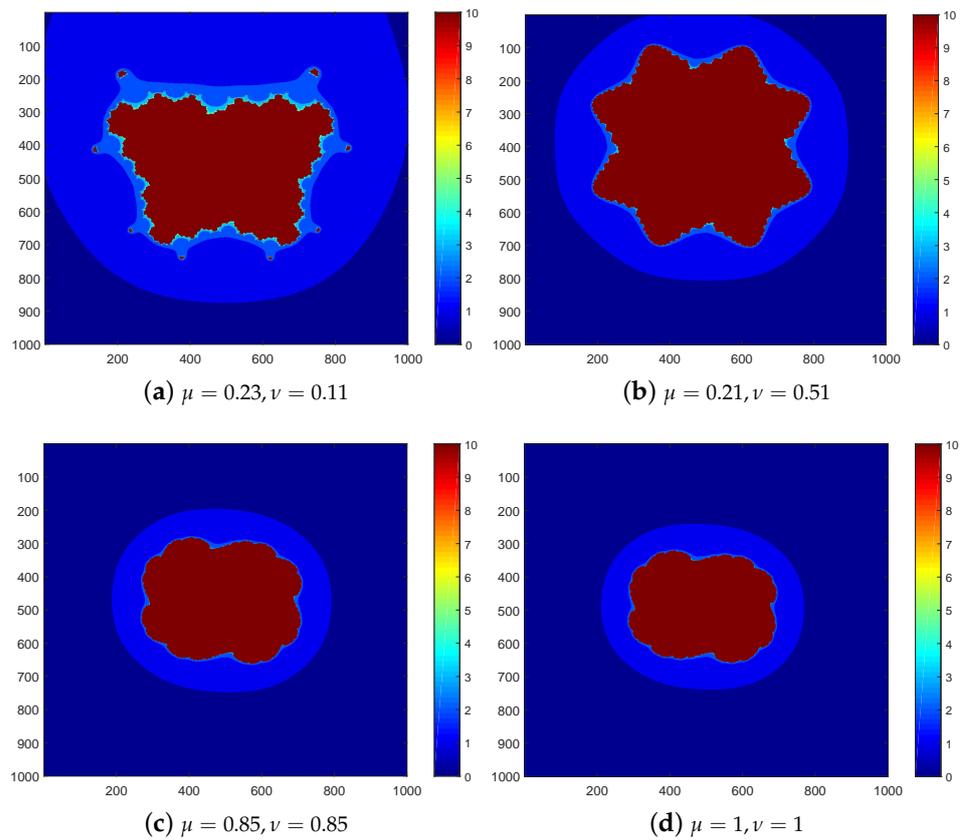


Figure 4. J -sets of $Q_C(p) = ap^n + mp + c$ of with $n = 2$.

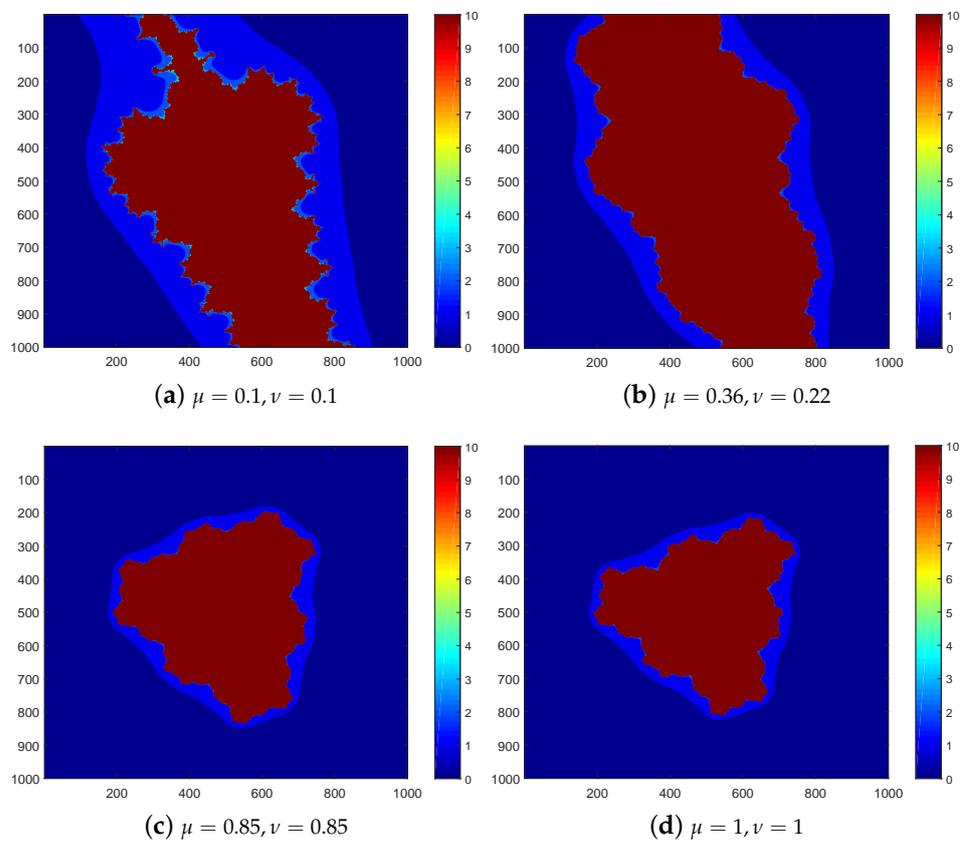


Figure 5. J -sets of $Q_C(p) = ap^n + mp + c$ of with $n = 3$.

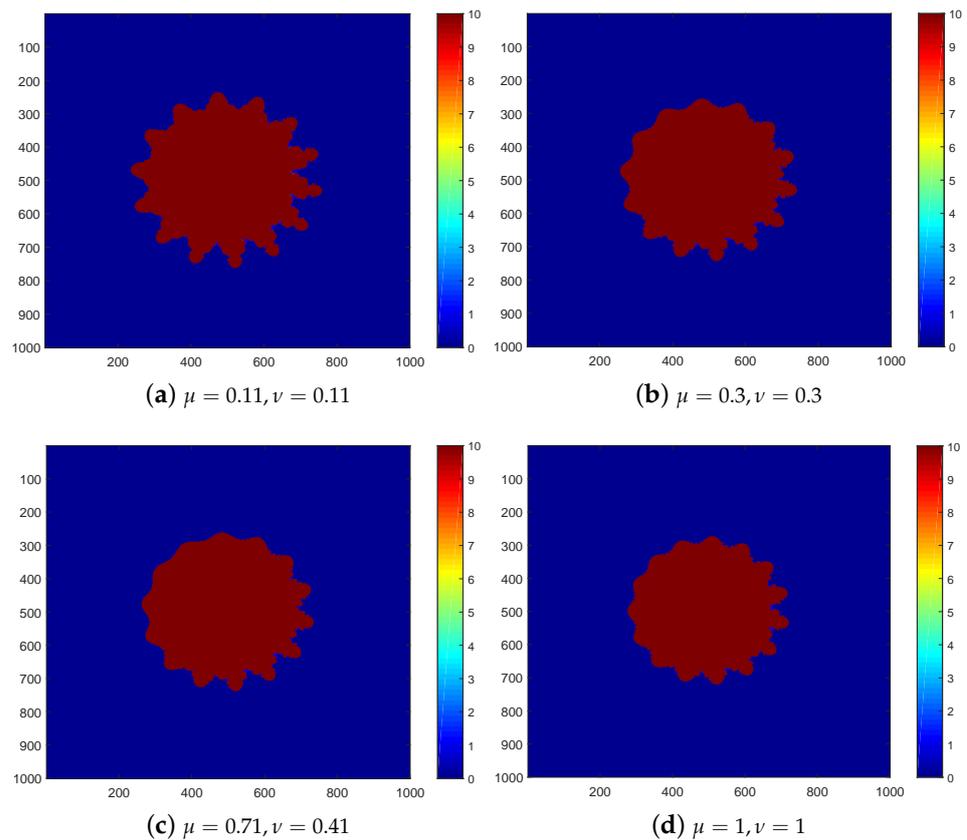


Figure 6. J . sets of $Q_{\mathbb{C}}(p) = ap^n + mp + c$ of with $n = 15$.

5. Visualization of M . Sets

In this section, we delve into the visual representation of M . sets, showcasing their intricate structures. By manipulating the input parameters, we witness the emergence of vibrant colors and the transformation of the fractal’s shape, leading to a captivating visual experience.

For our exploration of M . sets, we utilize the escape criterion technique. The result of this process is the generation of two sets: one comprising points where the orbits remain bounded, forming the M . set, and the other consisting of points where the orbits escape to infinity, creating the background.

5.1. Generation of M . Sets

Algorithm 2 is the pseudocode for the creation of M . sets.

We show quadratic, cubic, and higher-degree M . sets in a Kalsoom at al.–type orbit for the complex polynomial $Q_{\mathbb{C}}(p) = ap^n + mp + c$.

1. For Figure 7, we input $A = [-2.5, 2.5]^2$ and observe that the images are similar to a traditional M . set. The main body includes several bulbs of various sizes, but magnifying any picture bulb reveals the form of the entire image. All the M . sets in Figure 7 have downward faces and symmetry about the y -axis.
2. For Figure 8, we input $A = [-2, 2]^2$, and it shows that each picture has two cardioids, two large bulbs, and four small bulbs and preserves symmetry about diagonals.
3. For Figure 9, we input $A = [-2.3, 2.3]^2$, and we perceive that a clear color variation is involved. Figure 9c covers more area as compared with Figure 9d.

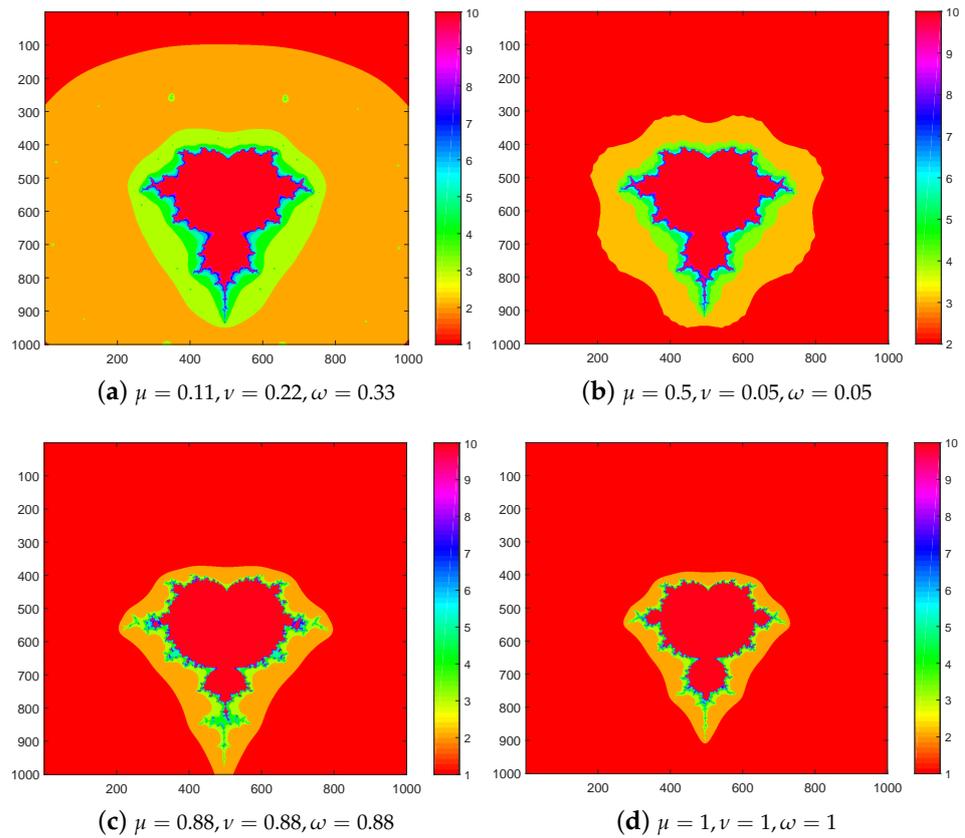


Figure 7. M. sets of $Q_{\mathbb{C}}(p) = ap^n + mp + c$ with $n = 2$.

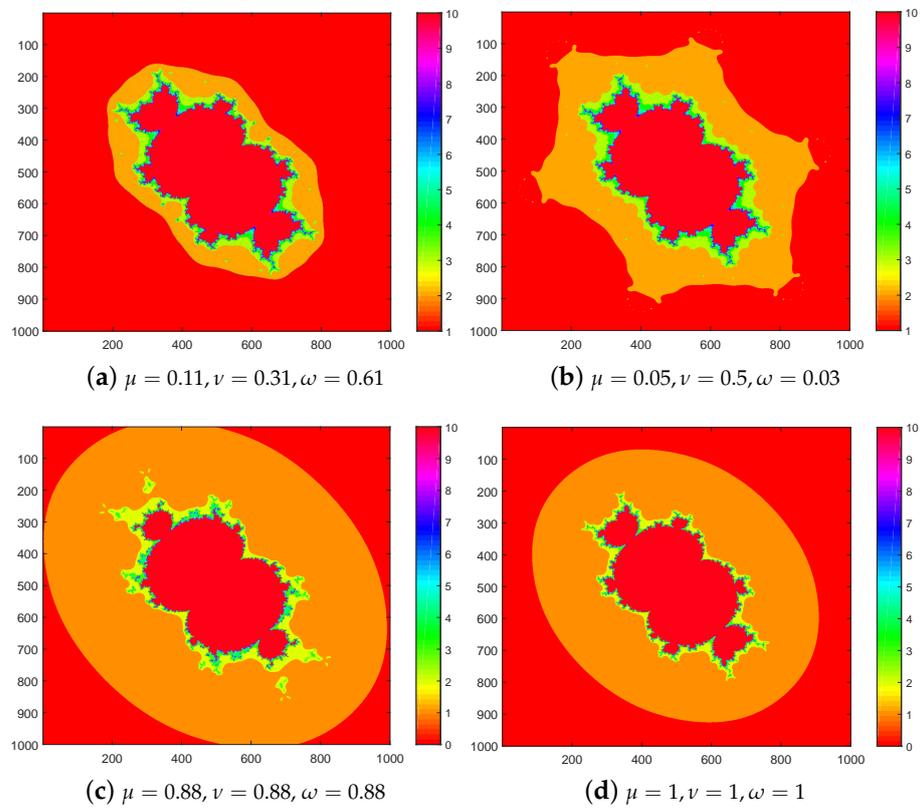


Figure 8. M. sets of $Q_{\mathbb{C}}(p) = ap^n + mp + c$ with $n = 3$.

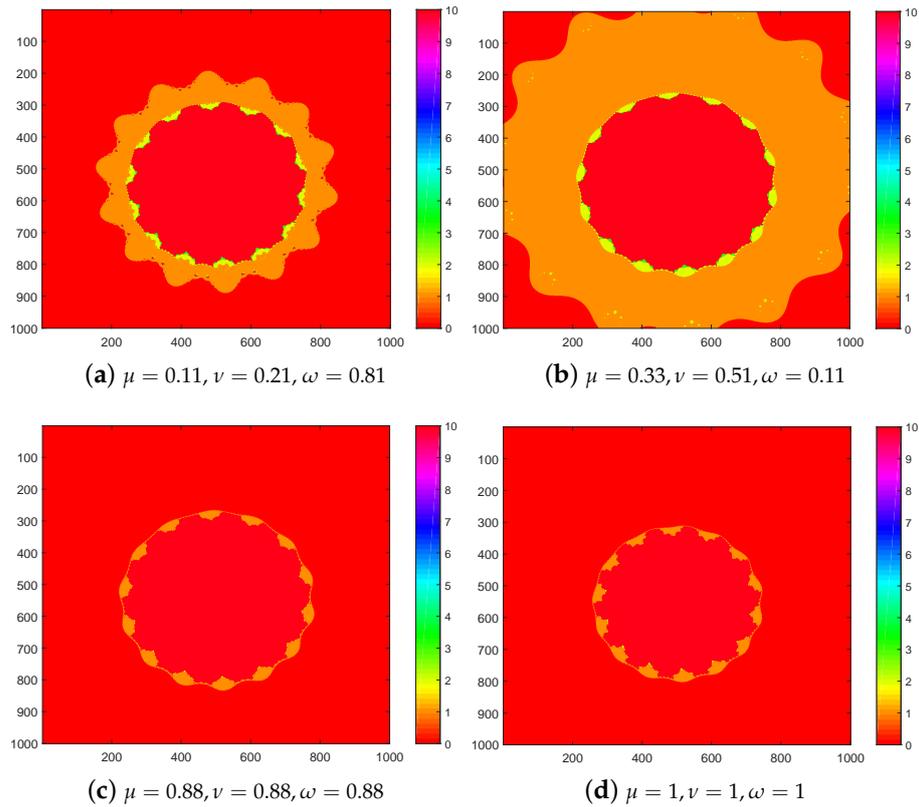


Figure 9. $M.$ sets of $Q_{\mathbb{C}}(p) = ap^n + mp + c$ with $n = 15$.

5.2. Generation of $M.$ Sets in Picard–Ishikawa Iteration

We show quadratic, cubic, and higher-degree $M.$ sets in a Picard–Ishikawa–type orbit for the complex polynomial $Q_{\mathbb{C}}(p) = ap^n + mp + c$.

1. For Figure 10, we input $A = [-2.5, 2.5]^2$ and observe that the images are similar to a traditional $M.$ set. The main body includes several bulbs of various sizes, but magnifying any picture bulb reveals the form of the entire image. Figure 10a–d have downward faces and symmetry about the y -axis. Notice that the pattern in Figure 10a is stretched and the bulb is broader, but the shapes in Figure 10c,d are compact and have a defined bulb.
2. For Figure 11, we input $A = [-2, 2]^2$, and it shows that each picture has two cardioids, two large bulbs, and four small bulbs and preserves symmetry along both diagonals.
3. For Figure 12, we input $A = [-2.3, 2.3]^2$, and we perceive that shapes are the same, but there is variability in colors. Figure 12c covers more area as compared with Figure 12d.

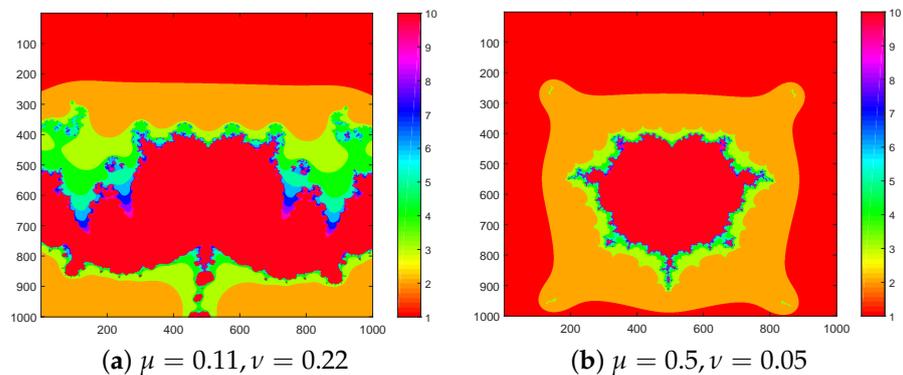


Figure 10. Cont.

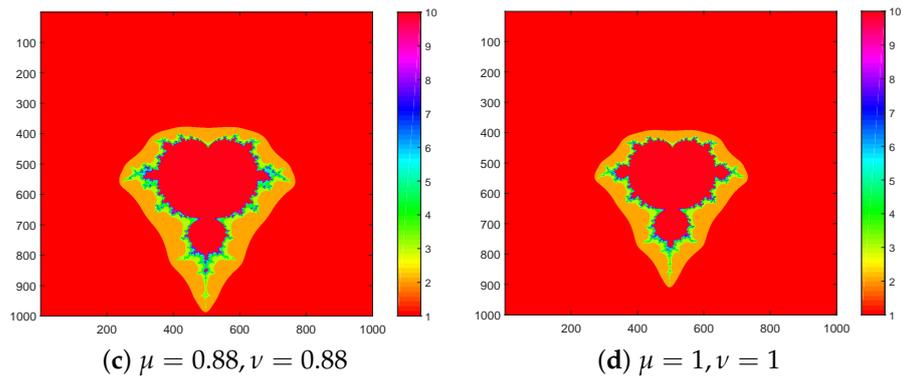


Figure 10. $M.$ sets for $Q_C(p) = ap^n + mp + c$ with $n = 2$.

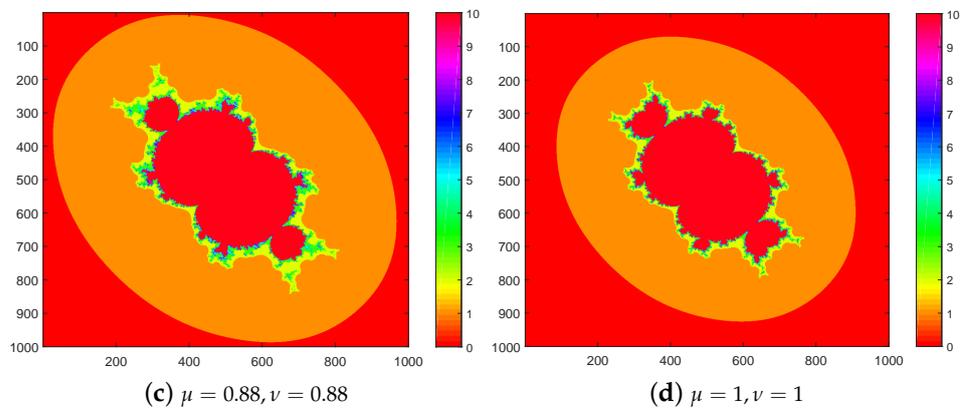
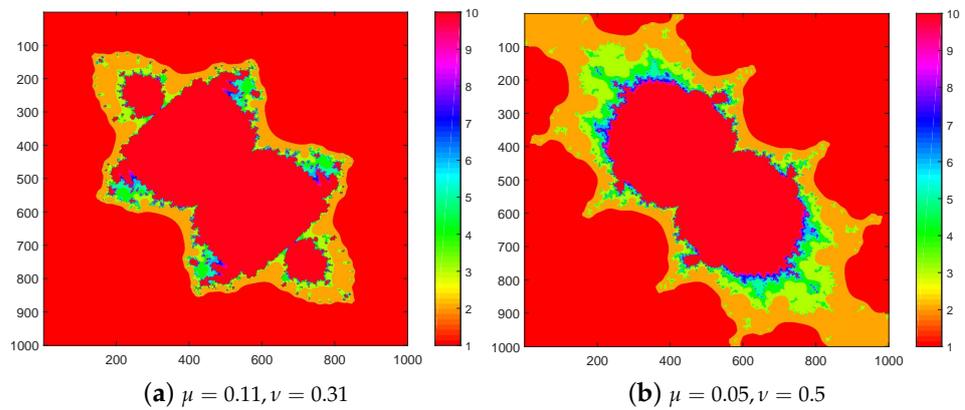


Figure 11. $M.$ sets for $Q_C(p) = ap^n + mp + c$ with $n = 3$.

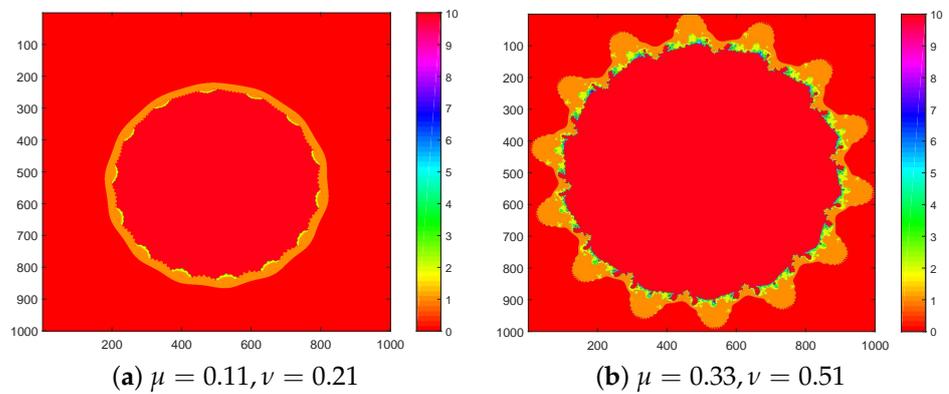


Figure 12. *Cont.*

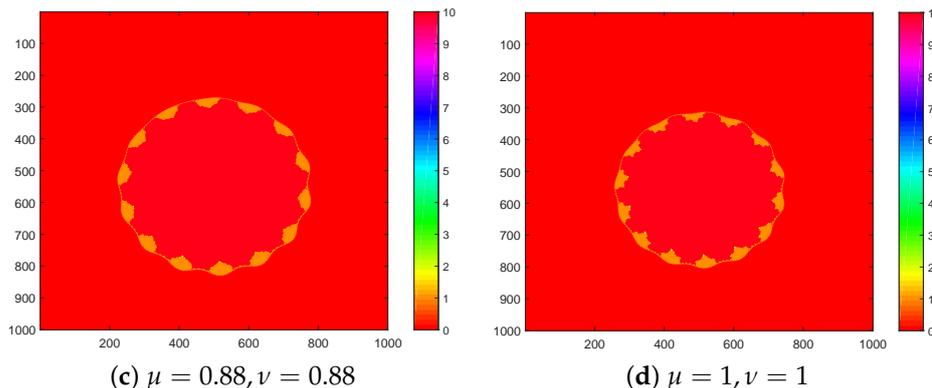


Figure 12. M . sets for $Q_C(p) = ap^n + mp + c$ with $n = 15$.

6. Discussion on the M . Sets Generated by Kalsoom et al. and Picard–Ishikawa Iteration Schemes

We have generated M . sets with Kalsoom et al. and Picard–Ishikawa iteration schemes. We checked the graphical behaviors of both iterations. For comparison, we took two M . sets, first, with Kalsoom et al. iteration and, second, with Picard–Ishikawa iteration and perceive that the results with Kalsoom et al. iteration are better than Picard–Ishikawa because they are in more compact form. For Figure 13a,b, we input the same area and the values of the parameters but obtained different results. Figure 13a shows that the shape of the M . set by using Kalsoom et al. iteration is compact with a defined bulb, and Figure 13b shows that the shape of the M . set by using Picard–Ishikawa iteration is stretched and the bulb is wider. The added value of the method presented in this research lies in the utilization of both Kalsoom et al. iteration and Picard–Ishikawa iteration. With Kalsoom et al. iteration, we achieve the shape of the traditional M . set even at lower μ values of the parameter. On the other hand, with Picard–Ishikawa iteration, we need to use higher values to obtain traditional M . sets.

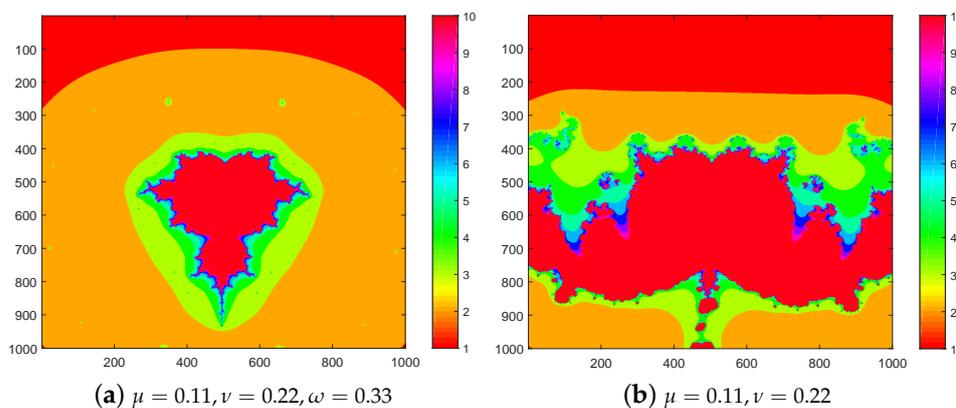


Figure 13. $A = [-2.5, 2.5]^2$.

7. Conclusions

In this article, different iteration processes and color maps have been employed to generate J . and M . sets. The utilization of these sets can be helpful to those interested in the automatic generation of visually appealing images. Escape criteria for the n th-degree polynomial to generate the said sets via Kalsoom et al. and Picard–Ishikawa iteration schemes with the polynomial $Q_C(p) = ap^n + mp + c$ have been proven. Additionally, new fractals for complex functions that are distinctly different from those introduced earlier have been obtained. Interesting J . and M . sets have been achieved by using different values of μ, ν, ω . A few examples of complex quadratic, cubic, and n th-degree polynomials have been presented. While the paper presents escape criteria that have proven effective

in generating fractals, exploring alternative escape criteria could offer new perspectives on the generation process. Investigating different escape conditions and their impact on the resulting fractals could be a fascinating direction for future research. Moreover, this study can be extended to explore fractals beyond M and J sets. Investigating other fractal families, such as Multibrot sets, Biomorphs, or Barnsley fern, and applying the developed iterative procedures to generate and visualize these fractals would open new paths for further exploration in the field.

Open Problem: Can the results demonstrated in this paper be extended to include exponential and multivariate polynomials using any other iteration scheme?

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