



# Article Combining Image-Based Phenotyping and Multivariate Analysis to Estimate Fruit Fresh Weight in Segregation Lines of Lowland Tomatoes

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Abstract: The fruit weight is an important guideline for breeders and farmers to increase marketable productions, although conventionally it requires destructive measurements. The combination of image-based phenotyping (IBP) approaches with multivariate analysis has the potential to further improve the line selection based on economical trait, like fruit weight. Therefore, this study aimed to evaluate the potential of image-derived phenotypic traits as proxies for individual fruits weight estimation using multivariate analysis. To this end, an IBP experimentation was carried out on five populations of low-land tomato. Specifically, the Mawar (M; 10 plants), Karina (K; 10 plants), and F2 generation cross (100 lines) samples were used to extract training data for the proposed estimation model, while data derived from M/K//K backcross population (35 lines) and F5 population (50 lines) plants were used for destructive and non-destructive validation, respectively. Several phenotypic traits were extracted from each imaged tomato fruit, including the slice and whole fruit area (FA), round (FR), width (FW), height (FH), and red (RI), green (GI) and blue index (BI), and used as inputs of a genetic- and multivariate-based method for non-destructively predicting its fresh weight (FFW). Based on this research, the whole FA has the greatest potential in predicting tomato FFW regardless to the analyzed cultivar. The relevant model exhibited high power in predicting FFW, as explained by R<sup>2</sup>-adjusted, R<sup>2</sup>-deviation and RMSE statistics obtained for calibration (81.30%, 0.20%, 3.14 g, respectively), destructive (69.80%, 0.90%, 4.46 g, respectively) and non-destructive validation (80.20%, 0.50%, 2.12 g, respectively). These results suggest the potential applicability of the proposed IBP approach in guiding field robots or machines for precision harvesting based on non-destructive estimations of fruit weight from image-derived area, thereby enhancing agricultural practices in lowland tomato cultivation.

**Keywords:** digital imaging; fruit prediction; non-destructive validation; regression analysis; *Solanum lycopersicum* 



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# 1. Introduction

Tomato is one of the most widely cultivated horticultural crops in the world [1]. The well-known health and nutritional benefits of tomato, namely vitamins C and E, carotenoids, phenolic compounds, sucrose, hexoses, citrate, malate and ascorbic acid, have led this fruit to be often present in the daily diet [1–3]. Such properties correlate with the increasing demand for tomatoes along with population growth [4,5]. However, the global warming experienced in recent years have caused tomatoes to suffer a decline in production and quality [6]. This is mainly dictated by alterations in the growing environment which favor more intense and frequent attacks by parasites and diseases, as well as increased competition phenomena with other crops [7–9]. Therefore, it is necessary to identify genotypes adaptable to warmer conditions, especially within global regions most expose to the effects of climate change (e.g., Tropics) [6,10,11]. In particular, the higher temperatures registered in the areas of Asian countries most suited to tomato cultivation (i.e., highlands) has stimulated interest in new varieties adaptable to the climatic conditions typical of lower altitudes [10]. Consequently, the selection of improved tomato cultivars through innovative and effective plant breeding programs is required to safeguard production standards at different altitudes.

Several genetic efforts have been conducted to increase tomato production and quality in the Asiatic lowlands [6,11–13]. Cross-breeding programs have allowed the identification of candidate varieties to generate offspring tomato lines better adaptable to new growth conditions, as previously reported for the Mawar (M) and the Karina (K) cultivars [13,14]. The Mawar variety is well adapted to lowland conditions for the production of fruits with a relatively large wavy shape and a high market value given by the richness in nutrients and antioxidants. On the other hand, Karina is a variety grown mainly in middle plains with round shaped fruits [13,15].

The results of crossing M and K varieties have been analyzed in depth regarding traits that have the potential to be used as selection criteria [13,14]. In several studies, the significance of fruit weight stands out as a key determinant in shaping the direction of selection, closely aligned with considerations of overall productivity [14,16–19]. Furthermore, in the hybridization of these two varieties, both the shape and weight of the fruit exhibit remarkable similarity [13,14]. Consequently, prioritizing the enhancement of fruit weight attributes emerges as a pivotal strategy in steering the course of selection progress. However, the assessment of tomato fruit weight primarily relies on destructive samplings, demanding considerable energy, time, and streamlined processes, especially when dealing with extensive populations [20–23]. In addition, inaccuracy during the handling process can adversely impact the fruit weight and, consequently, the breeding process [24,25]. Hence, a meticulous approach is imperative for accurately predicting the potential of segregating line populations. Image-based phenotyping (IBP) represents an effective technique for this purpose.

IBP is a digitalization approach in the 4.0 era, encompassing the accurate and nondestructive screening of imaged objects [24–29]. The precision of the analysis is dependent on the type of imaging sensors employed, including Red, Green and Blue (RGB) cameras, multispectral cameras, hyperspectral cameras, Light Detection and Ranging (LiDAR) cameras, and Magnetic Resonance Imaging (MRI) [28,29]. The higher spatial resolution of the camera sensor, the more comprehensive the data obtained, especially when integrated with automation and big data concepts, such as high-throughput phenotyping [28,30–34]. In this context, RGB cameras represent an affordable tool which can be used to indirectly obtain reliable information on the agronomic potential of plants and/or crops [27,29,35–38]. Therefore, phenotypic traits derived from RGB images can serve as inputs for models aimed at predicting tomato fruit weight. This approach not only helps breeders in selection programs but could also contribute to optimize the subsequent robotic harvesting process in the field.

Previous researches has focused on exploring the potential application of IBP techniques for analyzing both tomato fruits [26,38–40] and canopy [41,42]. Specifically, Nyalala et al. [26,38] highlighted the efficacy of IBP in non-destructively predicting tomato fruit weight. Although their results were satisfactory ( $1.47 \le RMSE \le 15.84$  g and  $0.92 \le R^2 \le 0.97$ ), it's important to note that the proposed predictive models are applicable exclusively to a specific tomato cultivar (i.e., cherry tomato) and lack generalizability to other larger-fruited varieties. Similarly, studies conducted by Taheri-Garavand et al. [43] and de Luna et al. [44] employed IBP for assessing fruit size and weight of specific tomato genotypes ( $R^2 \ge 0.90$ ), but their method was exclusively destructive. Therefore, evaluating the potential application of IBP for non-destructively predicting tomato fruit weight is an essential research topic, particularly in lowlands F2 lines characterized by high segregation complexity and large population sizes [6,45]. To ensure optimal generalizability, a systematic analysis of the image-derived traits is essential for identifying the appropriate inputs for the predictive model.

Multivariate analysis stands out as a solution for systematically determining potential predictive traits, as reported by [46–49]. This approach involves gathering all dimensions of an extensive crop data collection to be processed collectively, leading to a more straightforward interpretation [15,50,51]. Although several studies have employed multivariate analysis on image-derive phenotypic traits [37,38,52,53], the joint application of IBP and multivariate analysis in detecting tomato fruit fresh weight has not been extensively tested, particularly in segregated populations.

Building upon previous research efforts, this study aims to address the critical need for a generalized and non-destructive predictive model applicable to lowland tomato varieties. To this end, a multivariate approach was developed to systematically analyze image-derived phenotypic traits, providing a comprehensive understanding of the best predictor for tomato fruit fresh weight.

#### 2. Materials and Methods

#### 2.1. Plant Material and Growing Conditions

The research was conducted from January to May 2022 on the Mawar (M) variety, Karina (K) variety, and their respective crossbreed populations, including F2 and M/K//K backcross Additionally, an investigation into the F5 population was carried out in October 2023. Each parent was represented by 10 plant samples, while the F2 cross-segregation population consisted of 100 lines. In contrast, the backcross population and F5 populations were comprised of 35 lines and 50 lines, respectively. Field experiments were carried out at the Experimental Garden of the Faculty of Agriculture, Hasanuddin University, located in Tamalanrea District, Makassar City, South Sulawesi (Indonesia). The elevation of the location is 22.4 m above sea level.

Sowing was conducted using a planting medium comprising a blend of soil, burnt husks, and compost in a ratio of 2:1:1. The prepared planting medium was then placed in seedling trays and thoroughly saturated with water to ensure even distribution. Subsequently, tomato seeds were sown and treated with Furadan to mitigate potential disturbances or pest attacks. Seedlings maintenance involved daily watering, and after 7 days after sowing (DAS), Goodplant Ab mix fertilizer was applied at a concentration of 5 mL per 1 L. This fertilizer contains essential nutrients such as N Total (20.7%),  $P_2O_5$  (5.1%),  $K_2O$  (24.80%), MgO (5.1%), CaO (14.5%), S (8.9%), Fe (0.10%), Mn (0.05%), Cu (0.05%), B (0.03%), Zn (0.02%), and Mo (0.001%).

Upon reaching 30 DAS, transplanting was carried out into beds constructed with a width of 80 cm and a length of 2.5 m, spaced 30 cm apart, and with a height of 30 cm. The beds were covered with silver mulch and perforated according to the planting distance, specifically 50 cm between rows and 80 cm within rows. Watering was conducted twice daily, both in the morning and evening, until the soil achieves a consistently damp appearance. Replanting occurred 7–14 days after transplanting (DAT) for tomato seedlings exhibiting abnormal growth, wilting, or pest and disease infestations. In such cases, affected samples were replaced with new ones matching their genetic code. Plant fertilization was initiated at 7 DAT and subsequently applied weekly. Mutiara NPK (16:16:16) fertilizer,

at a concentration of 10 g/L of water, was used initially. During the generative phase, this was replaced with KNO<sub>3</sub> at a concentration of 5 g/L. Each plant received 200 mL of the fertilizer solution. Additionally, foliar fertilization was conducted using Gandasil D and Gandasil B during the vegetative and generative phase, respectively. Pruning involved the removal of small shoots in the leaf axils, directing the tomato's growth towards the main stem, while weeds hindering plant growth were manually removed in the planting area or treated with herbicide between the beds. The final maintenance stage involved controlling pests and diseases weekly. To this end, a combination of 2 cc/L of water of insecticide Curacron 500 EC and 2 g/L of water of fungicide Antracol 70 WP were alternated with Dhitane M-45 WP at a concentration of 2 g/L of water, replacing Antracol 70 WP to enhance efficacy. Pesticides were applied through surface spraying on the plants. Finally, periodic harvests, occurring up to three times over an 8-week span, were conducted to achieve optimal genetic potential in tomatoes, with the readiness for collection indicated by fruits displaying a reddish-yellow color.

# 2.2. Fruits Imaging and Traits Extraction

The detached tomato fruits were firstly weight on a precision scale for obtaining the weight of whole and sliced fresh fruit (FFW; g) and subsequently photographed at the Agronomy Department of Hasanuddin University (Indoensia) for phenotypic traits extraction. Five tomato samples were collected from all plants in each generation, except for F5, for which only two samples were directly photographed on the plant. In total, 875 photos were gathered for IBP analysis (Figure 1).

Specifically, each sample was placed onto a portable lightbox photography studio  $(50 \text{ cm} \times 50 \text{ cm} \times 50 \text{ cm})$  and illuminated with an 8-watt LED light against a white background to better distinguish the fruit shape. Taking photos in destructive concept is also arranged by placing the fruit in the best or widest position, so that the fruit has an optimal area to photograph. This is so that the photo can represent the true trait. A Canon® EF 28–135 mm f/3.5–5.6 commercial camera (Canon Inc., Tokyo, Japan) was fixed on the top-hole of the box ensuring a 90-degree vertical shooting. For each sample, 1 top-view RGB image was collected by setting the camera with 5.6 F-stop, 1/160 s exposure time, ISO 800 and no-flash mode. The scene also included a graduated ruler with markings every 1 mm as a reference scale to xy-metrically calibrate the image. Meanwhile, non-destructive shooting is done with a white background too. This aims to sharpen the ruler scale when taking photos of fruit directly in the field, so that the model could be optimize in prediction. In addition, non-destructive photography is also done by taking the best or widest angle of the target fruit in the field. This also aims to ensure that the model formed at the initial development stage can be optimized in predicting fruit fresh weight (FFW; g) as the primary trait.

Fiji® open-source software [54] was used to semi-automatically obtain phenotypic measurements from individual tomato scans, as similarly reported by Woolf et al. [55] and Ayenan et al. [56]. Firstly, the ruler markings were manually selected and used to calculate a scaling factor for obtaining absolute morphometric values. Subsequently, foreground objects (i.e., fruit) were segmented from the background pixels by applying a triangle thresholding method. In particular, the original RGB colorspace was automatically converted to a Hue, Saturation, Brightness (HSB) stack to emphasize spectral dissimilarities between vegetal and non-vegetal features. In the HSB model, H (0–360°) differentiates pure colors while S (0-100%) and B (0-100%) characterizes the shade and the overall brightness of the color, respectively, offering manipulable indicators for intuitive selection of foreground and background color-fingerprints. To this end, the HSB histogram of the whole stack was computed, and the ideal threshold (THR) automatically identified as the point of maximum distance between the histogram and the line connecting its peak to the farthest end [57]. Thus, the pixels outside THR were labelled as 0' (i.e., background), while the remaining points were coded as '1' (i.e., fruit). The original RGB image was superimposed to the resulted binary mask to retrieve solely the region of interest (ROI). Then, the ROI

was automatically analysed to measure the whole and slice fruit area (FA), round (FR), width (FW), height (FH), and red (RI), green (GI) and blue index (BI). Specifically, FA was obtained as the surface of all the selected pixel (cm<sup>2</sup>), FR was the length of the outside boundary of the ROI (cm), while FW and FH represented the maximum x- and y-axis length of a fitted ellipse (cm), respectively. Finally, RI, GI and BI were calculated as the average red-, blue- and green-channel value of all the ROI pixels. As the fruit's appearance was categorized into whole and sliced, a total of 14 image-based phenotyping traits per sample was extracted.





#### 2.3. Development of the Fruit Fresh Weight Estimation Model

The analysis of fruit-derived data involved an initial examination of genetic parameters (i.e., heritability analysis), wherein heritability values were categorized into three groups: high (>50%), medium (20–50%), and low (<20%) [58]. Subsequently, Pearson correlation analysis was conducted, and image-based phenotyping traits demonstrating a significant positive correlation proceeded to path and multiple regression analyses using the "agricolae" package in Rstudio<sup>®</sup> 3.6.3 [59]. The results were then subjected to secondary trait (i.e., phenotypic predictors) validation, encompassing the (i) analysis of selection intensity, (ii) genetic progress percentage, and (iii) effectiveness of secondary traits. The selected secondary traits were combined into a linear regression analysis model for FFW estimation [38,40,59]. Then, destructive and non-destructive data from the backcross M/K//K and F5 samples were used for validating the predicting mode. Such generations were chosen due to their optimal diversity, as they consistently exhibited robust segregation characteristics [60–62].

# 2.3.1. Selection Intensity and Genetic Progress Percentage

Selection intensity (*i*) represents the mean of the selected proportion in phenotypic standard deviations, enabling the comparison of the effectiveness of each selection when considered collectively (Equation (1)). Following previous researches [21,63], *i* was employed to assess the effectiveness of selected secondary traits.

$$=\frac{(x_i - \overline{x})}{\sqrt{SD}}\tag{1}$$

where  $x_i$  represents the average value of the *i*-th lines,  $\overline{x}$  is the general average value, and *SD* refers to the standard deviation.

i

The selection progress ( $\Delta G$ %) was included in the model evaluation process to gain more effective results (Equation (2)). Indeed, the  $\Delta G$ % explains the extent to which the mean value of the chosen population undergoes alteration upon continuation into the next generation [5,64,65]

$$\Delta G\% = \frac{(x_i - \overline{x}) \times h^2}{\overline{x}} \times 100\%$$
<sup>(2)</sup>

where  $h^2$  represents the heritability.

# 2.3.2. Effectiveness of Secondary Traits

The ultimate validation assessment involved the evaluation of the efficacy of secondary traits (Equation (3)). This analysis aims to discern the secondary trait's effectiveness in indirectly predicting the success of selection on the primary trait [66,67].

$$\frac{CR_x}{R_x} = r_g \times \frac{(i_y \times h_y)}{(i_x \times h_x)}$$
(3)

where  $CR_x/R_x$  is the effectiveness of secondary traits,  $r_g$  represents the genetic correlation between secondary and primary traits, while *y* indicates the secondary traits and *x* the primary trait.

#### 2.3.3. Model Sensitivity and Effectivness

The sensitivity and effectiveness of the developed model were further assessed through the analysis of confidence interval (CI), prediction interval (PI), determination value ( $R^2$ ; Equation (4)), determination adjustment value ( $R^2$ -adjusted; Equation (5)), and root mean square error (*RMSE*; Equation (6)).

CI and PI are statistics commonly used for evaluating models' sensitivity. CI indicates the accuracy of model estimates with a certain confidence level from samples, while PI explains the prediction range of a new object entering a population based on a regression analysis.  $R^2$  and adjusted  $R^2$  show how much the independent variable determines a proportion of the variance in the dependent variable. Adjusted  $R^2$  places more emphasis on penalizing the addition of independent variables, measuring the goodness of fit in forming a model [68,69]. Finally, *RMSE* serves as an error validation method typically conducted by assessing the average standard deviation or the disparity between predicted and actual outcomes [68].

$$R^2 = 1 - \frac{SS_{residual}}{SS_{total}} \tag{4}$$

$$Adjusted R^{2} = 1 - \frac{\frac{SS_{residual}}{(n-K)}}{\frac{SS_{total}}{(n-1)}}$$
(5)

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (X_i - Y_i)^2}$$
(6)

where *SS* is the sum square, *n* represents number of data, *K* refers to the number of parameters fit by the regression, while  $X_i$  and  $Y_i$  are the predicted and actual value, respectively.

#### 3. Results

The heritability results of each image-derived phenotypic trait are shown in Table 1. There was no statistically significant difference in the average values ( $\bar{x}$ ) across genotype backgrounds for all fruit image-based phenotyping (IBP) traits, including fruit fresh weight (FFW). Although Karina samples (parents) exhibited relatively higher FFW compared to other genotypes, this difference lacked statistical significance. In contrast, there were significant differences in the diversity of values among genotype backgrounds, with the F2 population displaying higher diversity than other samples ( $\sigma^2$ ). Notably, traits showing low- to medium-range heritability (H) included fruit fresh weight (34.44), whole fruit area (37.47), whole fruit roundness (27.79), whole fruit width (39.69), whole fruit height (43.73), whole blue index (31.96), wide fruit slices (26.39), area of fruit slices (29.76), height of fruit slices (45.64).

Table 1. Heritability results of all the analyzed phenotypic traits.

GB	S	FFW	WFA	WFR	WFW	WFH	WRI	WGI	WBI	SFA	SFR	SFW	SFH	SRI	SGI	SBI
K	$\frac{\overline{x}}{\sigma^2}$	20.71 5.71	9.33 1.98	0.89 0.04	3.53 0.48	3.39 0.27	125.72 26.35	44.43 14.59	33.87 11.74	9.84 2.69	0.94 0.02	3.60 0.54	3.43 0.46	118.87 25.16	47.26 15.86	29.62 12.59
М	$\frac{\overline{x}}{\sigma^2}$	18.26 5.98	8.90 2.66	0.71 0.11	3.94 0.49	2.97 0.51	114.24 12.27	44.09 9.97	30.24 5.89	6.95 1.79	0.92 0.04	3.94 0.49	3.75 0.36	114.24 12.27	44.09 9.97	30.24 5.89
F1	$\frac{\overline{x}}{\sigma^2}$	19.91 3.91	9.90 0.96	0.94 0.02	3.56 0.25	3.54 0.16	115.73 27.34	44.37 14.96	32.32 12.23	6.54 0.88	0.93 0.02	3.74 0.33	3.61 0.22	128.91 25.48	60.58 24.45	38.38 11.79
F2	$\frac{\overline{x}}{\sigma^2}$	17.32 7.93	8.49 2.98	0.84 0.08	3.56 0.68	3.12 0.56	114.35 22.54	40.49 15.83	31.75 14.63	5.93 2.43	0.93 0.03	3.53 0.64	3.41 0.64	121.95 22.95	50.99 18.96	33.25 12.50
V V V H	7Έ 7Ρ 7G Η	5.20 7.93 2.73 <b>34.44</b>	1.87 2.98 1.12 <b>37.47</b>	0.06 0.08 0.02 <b>27.79</b>	0.41 0.68 0.27 <b>39.69</b>	0.31 0.56 0.24 <b>43.73</b>	21.99 22.54 0.55 2.44	13.17 15.83 2.66 16.82	9.95 14.63 4.68 <b>31.96</b>	1.79 2.43 0.64 <b>26.39</b>	0.03 0.03 0.01 18.86	0.45 0.64 0.19 <b>29.76</b>	0.35 0.64 0.29 <b>45.64</b>	20.97 22.95 1.98 8.62	16.76 18.96 2.20 11.62	10.09 12.50 2.41 19.27

Notes: GB = genotype background, S = statistic ( $\bar{x}$  = average value;  $\sigma^2$  = population variance; VE = environmental variance; VP = phenotypic variance; VG = genetic variance; H = heritability), FFW = fruit fresh weight, WFA = whole fruit area, WFR = whole fruit round, WFW = whole fruit width, WFH = whole fruit height, WRI = whole red index, WGI = whole green index, WBI = whole blue index, SFA = slice fruit area, SFR = slice fruit round, SFW = slice fruit width, SFH = slice fruit height, SRI = slice red index, SGI = slice green index, SBI = slice blue index. The bold number shows moderate heritability.

Figure 2 displays the results of the correlation analysis among various image-derived phenotyping traits and destructively collected FFW. In general, the whole fruit height (0.68), slice fruit area (0.66), whole fruit area (0.73), slice fruit height (0.69), whole fruit width (0.71), and slice fruit width (0.68) showed a significant positive correlation both among the traits and with FFW. A significant positive correlation was also observed between the traits' red index, green index, and blue index in both whole and sliced fruits. Conversely, the whole fruit round negatively correlated with both whole (-0.33) and slice fruit width (-0.31).

The path analysis results revealed that whole fruit width (WFW) has a direct impact on fruit weight, with a coefficient of 0.6 (Table 2). This trait also exerted a substantial indirect influence on other phenotypic traits. In addition to WFW, fruit fresh weight was directly influenced by both whole fruit area and whole fruit height, each having a corresponding coefficient of 0.21. Conversely, the trait with the least direct influence resulted the wide fruit slice (-0.49).



**Figure 2.** Correlation analysis of all analyzed traits; a significant correlation at 5% error level is denoted by color and value, while a lack of significance is represented by blank cells; FW = fruit weight, WFA = whole fruit area, WFR = whole fruit round, WFW = whole fruit width, WFH = whole fruit height, WRI = whole red index, WGI = whole green index, WBI = whole blue index, SFA = slice fruit area, SFR = slice fruit round, SFW = slice fruit width, SFH = slice fruit height, SRI = slice red index, SGI = slice green index, SBI = slice blue index.

Trait	Direct		Correlation					
	Effect	WFA	WFW	WFH	SFA	SFW	SFH	- Correlation
WFA	0.21		0.54	0.19	0.13	-0.44	0.1	0.73
WFW	0.60	0.19		0.16	0.13	-0.47	0.1	0.71
WFH	0.21	0.19	0.47		0.12	-0.39	0.08	0.68
SFA	0.15	0.18	0.51	0.17		-0.44	0.09	0.66
SFW	-0.49	0.19	0.58	0.17	0.13		0.1	0.68
SFH	0.11	0.19	0.57	0.17	0.13	-0.47		0.69
total		0.94	2.67	0.86	0.63	-2.21	0.47	

Table 2. Path analysis of traits that remained positive toward results.

Notes: WFA = whole fruit area, WFW = whole fruit width, WFH = whole fruit height, SFA = slice fruit area, SFW = slice fruit width, SFH = slice fruit height.

Traits that exhibited positive correlations with FFW were then selected as inputs for the stepwise multiple regression analysis, leading to the development of an estimation model with a reasonably high determination value (0.544; Table 3). The model incorporates three traits for predicting FFW: intercept, whole fruit area (WFA), and WFW. However, upon single component analysis, solely the WFA emerged as significantly significant trait based on the student *t*-test.

Validation of secondary traits was carried out by the three genetic approaches showed in Table 4. When considering the intensity of selection through direct selection, the fruit fresh weight exhibited the highest intensity (4.09), followed by whole fruit area (4.06) and whole fruit width (0.90). In terms of selection intensity with indirect selection, the WFA resulted, instead, in a selection intensity of 3.66 for fruit weight, while the WFW yielded a lower value (3.53). Examining the percentage of selection progress through direct selection, FFW resulted in the highest progress (39.05%), followed by WFA (29.29%) and WFW (15.90%). Concerning selection progress through indirect selection, FFW showed a progress of 12.53% when selection is focused on the WFA. Conversely, when the focus shifted to the WFW, FFW demonstrated a lower selection intensity of 12.06%. Accordingly, the effectiveness of selection progress based on secondary traits revealed that the WFA has an effectiveness of 0.68 in representing FFW, while the WWF only reached a value of 0.32.

**Table 3.** Stepwise multiple regression analysis of traits that resulted positively correlated with the fruit fresh weight.

Parameters	Estimate	Std. Error	t Value	$\Pr(> t )$
(Intercept)	-4.9456	3.7527	-1.318	0.19071
WFA	1.2911	0.4217	3.062	0.00286 **
WFW	3.2015	1.8520	1.729	0.08711

Notes:  $R^2$ : 0.554, Adjusted  $R^2$ : 0.5446, \*\* significant effect at 1% error level, WFA = whole fruit area, WFW = whole fruit width.

Grouping	Traits	SG	S	i	$\Delta G$	$\Delta G\%$	(Cr/Rx)
Independent	WFW	4.45	0.90	1.81	0.57	15.90	
	WFA FFW	12.56 28.85	4.06 11.53	2.35 4.09	2.49 6.76	29.29 39.05	
Dependent -	WFA FFW	12.56 27.16	2.65 7.25	2.70 3.66	0.99 2.50	10.03 12.53	0.68
	WFW FFW	4.45 26.89	0.89 6.98	1.09 3.53	0.35 2.40	9.95 12.06	0.32

Table 4. Validation analysis of secondary traits using genetic approaches.

Notes: WFA = whole fruit area, WFW = whole fruit width, FFW = fruit fresh weight, SG = selected genotypes, S = selection differential, I = selection intensity,  $\Delta G$  = selection progress, Cr/Rx = effectiveness of secondary traits.

As shown in Figure 3 and Table 5, the derived model for estimating fruit fresh weight based on whole fruit area extracted from the training samples is expressed as:  $FFW = -4878 + 2619 \times WFA$ . Notably, only 3 points out of 110 total samples fell outside the confidence interval (CI) line, with the majority residing within the prediction interval (PI; Figure 3). In addition, the training model was characterized by high  $R^2$  and adjusted- $R^2$  values (81.5 and 81.3, respectively), with a reasonably low error (*RMSE* = 3.14 g; Table 3).



**Figure 3.** Development of the fruit fresh weight (FW\_F2; g) model based on the total whole fruit area (WFA; cm<sup>2</sup>) through regression analysis. Blue dots are lines from the population.

validation data.		

Data	n	<i>p</i> -Value	$R^2$	Adjusted-R <sup>2</sup>	<b>R<sup>2</sup>-Deviation</b>	RMSE	
Training	96	0.000	81.5	81.3	0.2	3.14	
Destructive Validation	30	0.000	70.7	69.8	0.9	4.46	
Non-destructive Validation	45	0.000	80.7	80.2	0.5	2.12	

Notes: n = number of genotypes,  $R^2$  = determination value, RMSE = root mean square error.

Table 5. Analysis of model sensitivity on training and

The model was validated by considering image-derived data from other populations, namely M/K//K backcross crosses and F5 population for destructive and non-destructive validation, respectively. Based on the destructive validation depicted in Figure 4, the whole fruit area exhibited a relatively high model determination value for FFW. This was further corroborated by the absence of samples outside the confidence interval (CI) area, although a few samples extended beyond the prediction interval (PI). Additionally, the robustness of this model was supported by the validation metrics, including  $R^2$ -Deviation and *RMSE*, which closely aligned with the training data at 0.9 and 4.46, respectively (Table 5). Similarly, non-destructive validation (Figure 5) demonstrated the high effectiveness of the WFA-driven model in predicting FFW. The determination was notably robust, further validated by  $R^2$ -Deviation (0.5) and *RMSE* (2.12 g) values comparable to the training data and destructive validation (Table 5).



**Figure 4.** Model destructive validation on M/K//K backcross population validation data. Blue dots are lines from the population.



**Figure 5.** Model non-destructive validation on F5 population validation data. Blue dots are lines from the population.

# 4. Discussion

The results of this study revealed noteworthy insights into the distribution of phenotypic traits along different lowland tomato varieties. Although the F2 population's mean values generally aligned closely with those of its parental counterparts and F1 generation, certain traits exhibited lower averages compared to other background genotypes. This discrepancy suggests that specific F2 genotypes manifest deficient scores in comparison to both parents and F1 line for specific traits. Nevertheless, it is imperative to recognize that the manifestation of phenotypes is not solely governed by the segregation process resulting from the cross. This is evident in the heritability values associated with fruit traits, which consistently fell within the low to medium range. Such results underscored the prevailing influence of environmental factors on the phenotypic expression of tomato fruit traits [6,70,71]. However, the moderate heritability observed in this study provided a valuable reference for the selection of image-derived phenotypic traits as proxies for fruit fresh weight (FFW). Notably, the application of the proposed image-based phenotyping (IBP) pipeline guaranteed the extraction of morphological variables with superior heritability compared to the principal trait (i.e., FFW). According to Acquaah [71], Lozada [67], and Fadhilah et al. [14], this result reflects the essential criterion for a valuable secondary trait to possess a superior heritability than the variable to be estimated. Consequently, the effective IBP-based measurement of secondary traits to estimate FFW in different segregation lines of lowland tomatoes emerges as a notable outcome of this research.

Within the framework of predictive models, the inclusion of numerous predictors unrelated to the primary trait could introduce considerable bias [69,72–74]. Indeed, while these additional data may seemingly enhance the estimation accuracy, their contributions often yield variations that lack substantial supplemental information in model development [71]. Therefore, a correlation analysis was performed to systematically minimize the inputs required for an accurate estimate of the FFW. Correlation is a commonly used approach for reducing the number of phenotypic traits that exhibit the potential to be candidates as predictors, as previously stated for maize [51], rice [54] and tomato [15,20,74–76]. Results highlighted specific phenotypic traits, namely whole fruit height (WFH), slice fruit area (SFA), whole fruit area (WFA), slice fruit height (SFH), whole fruit width (WFW), and slice fruit width (SFW), as optimal candidates for serving as predictors of the tomato fresh weight.

Aiming to identify the most powerful trait for accurately estimating the FFW, our study employed the convergence of stepwise multiple regression and path analysis, follow-

ing [46,59,75–77]. Accordingly, these methodologies complement each other, performing integrated roles [48,59]. Stepwise multiple regression represents a systematic and gradual reduction analysis which combines information from different variables [46,59,78]. This approach mitigates information loss that can occur when comparing one model with others [78], ensuring that the resulting model effectively encapsulates all relevant information derived from each selected independent variable. Nevertheless, stepwise multiple regression could not fully explain how individual independent variables influence the dependent variable. To address this limitation, path analysis can improve the understanding of how each independent variable contributes to the overall variance of the dependent variables [14,46,59,79], thus resulting essential to validate the established model [80,81]. Here, both analyses identified whole fruit area (WFA) and width (WFW) as potential secondary traits, with crosscheck results revealing a significant direct influence of WFW to the fruit fresh weight, followed by WFA and whole fruit height (WFH). However, the regression analysis presented varying results, emphasizing the importance of further validation to increase the level of confidence in the estimations [40,82–85].

In this context, the selection intensity [63,86,87], percentage of genetic progress [5,65,88] and the effectiveness of secondary traits [66,67,89] genetic approaches were applied to enhance the precision of identifying optimal predictor in segregating tomato populations. Previous researches consistently underscored the effective shared ability of such genetic methodologies to compare secondary traits, particularly in F2 populations [6,14,90,91]. In this study, despite WFW displaying higher direct influence and heritability values compared to whole fruit area WFA, this superiority was deemed genetically insufficient to consider WFW as a valuable predictor. Conversely, the WFA emerged as a reliable proxy of FFW. This result was consistently observed across various direct and indirect selection methods, highlighting the robust effectiveness of WFA in predicting the FFW within the proposed IBP framework. Such evidence aligns with the findings previously reported by various researchers on several plant species [24,27,37,92,93], including tomato [22,38–40].

The accuracy and robustness of the developed WFA-driven estimation model  $(FFW = -4878 + 2619 \times WFA)$  was both qualitatively and quantitatively ascertained. Moreover, the effective destructive and non-destructive validation of the estimates obtained in different tomato populations reinforced the generalization ability of the model  $(R^2 = 80.7\%, \text{Adjusted} \cdot R^2 = 80.2, \text{ and } RMSE = 2.12 \text{ g})$ . In this context, the proposed nondestructive pipeline achieved a similar or even greater accuracy of existing IBP destructive methods which were exclusively focused on estimating the fruit weight of a specific variety, with errors ranging from 1.27 g [26] to 15.84 g [38]. Encouragingly, the outcome of the nondestructive validation raises promising prospects for the model's effectiveness in directly evaluating tomato fruit weight within field conditions. Indeed, although the model may not accurately detect very light fruits (i.e., negative estimated values shown in Figure 5), this represents a negligible limitation for the workflow's applicability considering the size and weight standards of the marketable tomatoes at the harvest time. Accordingly, the proposed model could guide field robots or machines in the efficient harvesting of tomato fruits, ensuring the direct identification of those that do not meet market needs while still on the plant.

Nevertheless, the potentialities of this model invite further optimization through the incorporation of more advanced sensors (e.g., multispectral and/or hyperspectral cameras) or cutting-edge image-based phenotyping technologies (e.g., 3D-modeling). This could led to the comprehensive analysis of more complex phenotypic traits involved in the formation of the fruit weight and quality, as well as in predicting the effects of biotic and/or abiotic stressors on marketable tomato yield [29,33,94–96]. Consequently, the proposed pipeline could also serve as an efficient, straightforward, and rapid tool for breeding tomato varieties highly resilient to climate change in lowland areas.

# 5. Conclusions

In this study, multivariate analysis emerged as a highly efficacious approach for identifying pivotal image-derived phenotypic traits for predicting the final yield of lowland tomato segregation lines. Notably, the whole fruit area (WFA; cm<sup>2</sup>) displayed considerable potential in estimating single fruit fresh weight (FFW; g). The proposed model, expressed as  $FFW = -4878 + 2619 \times WFA$ , demonstrated robustness and generalizability. Indeed, methodological rigor characterizes the model's construction and validation, encompassing a comprehensive array of populations and validations, spanning both destructive and non-destructive paradigms. This model is therefore recommended for the proactive selection of tomato lines most adaptable to novel lowland environmental conditions, with envisioned utility in the realm of automated harvest robotics for discerning marketable fruits during harvesting operations.

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