Power Stabilization Strategy of Random Access Loads in Electric Vehicles Wireless Charging System at Traffic Lights

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Abstract: An opportunity wireless charging system for electric vehicles when they stop and wait at traffic lights is proposed in this paper. In order to solve the serious power fluctuation caused by random access loads, this study presents a power stabilization strategy based on counting the number of electric vehicles in a designated area, including counting method, power source voltage adjustment strategy and choice of counting points. Firstly, the circuit model of a wireless power system with multi-loads is built and the equation of each load is obtained. Secondly, after the counting method of electric vehicles is stated, the voltage adjustment strategy, based on the number of electric vehicles when the system is at a steady state, is set out. Then, the counting points are chosen according to power curves when the voltage adjustment strategy is adopted. Finally, an experimental prototype is implemented to verify the power stabilization strategy. The experimental results show that, with the application of this strategy, the charging power is stabilized with the fluctuation of no more than 5% when loads access randomly.

Keywords: opportunity wireless charging system; electric vehicles; power stabilization strategy

1. Introduction

With the rapid development of battery technology, from the hybrid electric vehicle (HEV) to the battery electric vehicle (BEV), the automobile is gradually moving away from dependence on fossil fuels. However the energy density and the speed of energy supply a battery possesses are far lower than those of petrol [1]. As a result, the electric vehicle (EV) is characterized by inconvenient and frequent charging, a bulky battery pack and limited driving range.

In order to remove the need for the charging cable, researchers have investigated EV static wireless charging (EVSWC) technology when an EV stops at the assigned position. Compared with the cable charging method, the EVSWC system is more convenient and can avoid electric sparks and worn circuits. The studies of EVSWC technology mainly cover efficient high-frequency inverters in primary side, effective high-frequency rectifiers in secondary side, electromagnetic couplers with high lateral misalignment tolerance, novel compensation circuits in both primary side and secondary one, and interoperability of different EV wireless charging equipment. The design and implementation of a wireless power transfer battery charger for an electric city car is presented in [2]. A 2 kW 700 mm-diameter pad, with a horizontal radial tolerance of 130 mm with a 200 mm air gap, was constructed and tested in [3]. A double D (DD) coil and a unipolar coil are selected for the
study in [4]. In [5], a compensated coil is integrated into the main coil structure, and a system with the proposed integration method is able to transfer 3.0 kW with an efficiency of 95.5% at an air gap of 150 mm. The series LC (SLC) resonant and the hybrid series-parallel (LCL) resonant full-bridge inverter topologies used for wireless electric vehicle (EV) charging are comparatively studied in [6]. The interoperability between different systems of contactless EV battery static charging by means of inductive coupling is investigated in [7].

Furthermore, to solve the issues of bulky battery and limited driving range, and to develop new energy storage devices with higher energy density, researchers have put forward the EV dynamic wireless charging technology (EVDWC), which can supply electricity for a running EV. EVs tend to have a limited driving range because of the restricted number of battery. With the application of dynamic wireless charging technology, EVs can be powered wirelessly while running. As a result, the size of the battery will decrease and in theory the car could even run without battery. A typical EVDWC system consists of the wireless power transmission unit, electric automobile unit and coordinated control unit [8]. The primary structures of EVDWC systems can be divided into a single long coil structure and a multiple short-segmented coil structure. The researches about systems with a single long coil structure mainly focus on modeling methods, novel coil structures and electromagnetic radiation elimination methods. A system with a single long coil structure is modeled on Laplace phasor transform in [9]. Hao et al. [10] build the approximate dynamic model of EVDWC system with LCL-T structure by using the generalized state-space averaging method. The research team at the University of Auckland proposes a three-phase wireless power transmission structure for EVDWC [11]. Researchers in KAIST (Korea Advanced Institute of Science and Technology) devote themselves to designing the coils structures of primary and secondary sides [8] and finding the electromagnetic radiation elimination methods [12]. Compared to a system with a single long coil structure, a system with a multiple short-segmented coil structure depends on EV positioning technology and switching control method of multiple primary coils. Bertoluzza et al. [13] investigate the coupling characteristics of double D (DD) coils with different dimensions in a short-segmented coil structure system. In [14], an efficiency of 92.5% at an output power of 5 kW is achieved with the application of a double-coupled configuration in a short-segmented wireless charging system for EV. An EVDWC system with a simultaneous two-transmitter method is proposed to obtain constant power supply in [15]. Kibok et al. [16] investigate characteristics of the received power changing with the position of the secondary coil in EVDWC systems with multiple short-segmented coils.

Because of many factors including existing technology and relevant policies about road reconstruction, there are still many problems to be solved before promoting the practical application of EVDWC systems in a short timeframe [17]. However, we can turn our attention to road junctions at traffic lights and build an opportunity wireless charging system for electric vehicles there. This opportunity wireless charging system at traffic lights is a combination of EVSWC and EVDWC. EVs can enter the waiting area that is also the opportunity wireless charging area and be charged conveniently while they wait for the traffic lights. This method contributes to enlarging driving range and is the basis of a whole-road EVDWC system.

Unlike the existing EVSWC system, the EV wireless charging system at traffic lights will need to solve two main problems. Firstly, due to the fact that waiting time cannot be very long (usually between 30 s and 100 s), the rate of the charging power is expected to need to be several kilowatts so that charge the battery in a short time. According to advanced EVDWC technology, the system can generate a high rate of charging power [8]. Another problem caused by the random access loads in the system is studied in this paper: On the one hand, if the power source voltage is constant, the access process of a new load will lead to a decline of charging power in the previous loads. On the other hand, if the voltage is adjusted regardless of the position of the random access load, the previous loads are threatened by an unbearably high rate of charging power. The issue of random access loads in EV wireless charging system received little attention. This paper focuses on a power stabilization strategy to deal with the issue of random access loads in EV wireless charging systems at traffic
lights. The detection method of EVs is necessary but not a key research point in this paper. In [18], a combination of vertically and horizontally oriented magnetic sensing coils is arranged to provide a signal that is used to control the steering of a driverless passenger vehicle. A three-coil detection system is proposed to detect the approaching EV in [19].

In Section 2, an opportunity EV wireless charging system at traffic lights is outlined. In Section 3, a circuit model of a wireless power transmission system with one primary coil and multi secondary coils is built. Equations of the received power of every load are then obtained. In Section 4, the power stabilization strategy is proposed, including counting method, power source voltage adjustment on the basis of the number of EVs when the system is at a steady state and choice of the counting points. In Section 5, the experimental prototype with the application of the power stabilization strategy is built and the theoretical analysis is verified by the experimental results.

2. Overview of Opportunity EV Wireless Charging System at Traffic Lights

The single long rectangular primary coil is installed under the lane at the traffic lights. When the traffic light is red, the EV can be charged wirelessly and conveniently when the EV is detected in the effective wireless charging area. The principle of the opportunity EV wireless charging system at traffic lights proposed in this paper is shown as Figure 1.

![Figure 1. Principle of the opportunity electric vehicle (EV) wireless charging system.](image)

The primary side of the proposed system consists of a traffic light information unit, EV counter information unit, control unit, high-frequency inverter, and the primary coil with compensation circuit. The secondary side includes the secondary coil with compensation circuit, rectification and voltage regulation unit, and the load. The communication mode of information of traffic lights is one-way communication in order to avoid influences on the traffic light system. The control unit combines the traffic lights information and the counter information, and also controls the DC voltage of the high-frequency inverter. The energy is transferred wirelessly through the electromagnetic coupling between the primary and secondary coils. The structure diagram of the opportunity EV wireless charging system is shown in Figure 2. In order to solve the issue of low electricity quality, at least two aspects should be dealt with in practical application. Firstly, a front-end power factor corrector (PFC) stage should be installed in front of the rectifier and the high-frequency inverter in order to handle the reactive burden. Secondly, the dc-link capacitor should also be installed between the rectifier and the high-frequency inverter in order to handle the ripple current.
The opportunity EV wireless charging system at traffic lights is a complex system with many issues to be investigated. In order to focus on the power fluctuation caused by the random access loads, theoretical analysis is carried out and a control strategy is proposed under the following hypotheses:

(i) The actual implementation of obtaining the information of traffic lights and the detection method of EVs are not mentioned in this paper.
(ii) When the traffic light is red and the EV is about to enter the effective wireless charging area, the EV is assumed to need charging and can be wireless charged.
(iii) When the traffic light turns green, the whole system turns off. Namely, all EVs quit simultaneously at that time.
(iv) The parameters of secondary coils in each EV are identical. The load characteristics are supposed to be identical too. In this paper, the actual load, including rectifier and battery, is simplified as the AC equivalent resistive load, which can be directly connected with the secondary coil. The differences of load characteristics caused by different batteries can be eliminated by using impedance conversion technology. At the preliminary stage of our research, we mainly focus on the wireless charging system for EVs with the same power level. In the future, we will deal with EVs of different power levels in the proposed system.
(v) On the one hand, most of the energy is transferred wirelessly through the fundamental square wave from the high-frequency inverter. On the other hand, the harmonics cause slight extra loss in primary side. Since the harmonic components count for a slight part in inverter output voltage, the loss caused by the harmonics is far less than that caused by the fundamental component. So the power source can be assumed to be ideal high-frequency sinusoidal in theoretical analysis.

3. System Modelling and Analysis

The circuit model of the proposed opportunity EV wireless charging system at traffic lights is displayed in Figure 3. The primary side and the secondary side are compensated with the resonant capacitors. \( U_{in} \) and \( R_{in} \) represent the voltage and the internal resistance of the high-frequency power source respectively. \( R_p, L_p, \) and \( C_p \) represent the resistance, the inductance and the compensation capacitor of the primary coil respectively. The number of loads in system is \( n \). \( R_{sk}, L_{sk} \) and \( C_{sk} \) denote the resistance, the inductance and the compensation capacitor of the \( k \)th \((1 \leq k \leq n)\) secondary coil respectively. \( R_{lk} \) is the \( k \)th load. \( M_{lk} \) represents the mutual inductance between the \( k \)th secondary coil and the primary coil. \( M_{ij} \) is the mutual inductance between the \( i \)th \((1 \leq i < n)\) secondary coil and the \( j \)th \((i < j \leq n)\) secondary coil.
On the basis of Kirchhoff’s voltage law, the model in Figure 3 is built by

\[
\begin{bmatrix}
I_p \\
I_{s1} \\
\vdots \\
I_{sk} \\
\vdots \\
I_{stn}
\end{bmatrix}
= \begin{bmatrix}
U_{in} \\
0 \\
\vdots \\
0 \\
\vdots \\
0
\end{bmatrix}
\]

(1)

where \( I_p \) is the current of the primary circuit, \( I_{sk} \) is the current of the \( k \)th secondary circuit, and \( Z \) is the impedance matrix of the system.

\[
Z = \begin{bmatrix}
Z_{00} & Z_{01} & \cdots & Z_{0k} & \cdots & Z_{0n} \\
Z_{10} & Z_{11} & \cdots & Z_{1k} & \cdots & Z_{1n} \\
\vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\
Z_{k0} & Z_{k1} & \cdots & Z_{kk} & \cdots & Z_{kn} \\
\vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\
Z_{n0} & Z_{n1} & \cdots & Z_{nk} & \cdots & Z_{nn}
\end{bmatrix}
\]

(2)

The non-diagonal element \( Z_{k0} = Z_{0k} = -j\omega M_{ks} \) and \( Z_{ij} = Z_{ji} = -j\omega M_{ij} \). The diagonal elements \( Z_{00} \) and \( Z_{kk} \) (\( 1 \leq k \leq n \)) represent the impedances of primary circuit and secondary circuits respectively, where \( Z_{00} = R_m + R_p + j\omega L_p + \frac{1}{j\omega C_p} \) and \( Z_{kk} = R_{lk} + R_{sk} + j\omega L_{sk} + \frac{1}{j\omega C_{sk}} \). \( \omega = 2\pi f \), and \( f \) is the working frequency.

Since the distance between two secondary coils is long enough in this system, the mutual inductance between two secondary coils can be ignored, namely, \( M_{ij} = 0 \). According to the hypotheses mentioned above, the inner resistance of every secondary coil is assumed to be \( R_s \) and each load is assumed to be \( R_L \). The working frequency is set to be the resonant frequency of every circuit, namely, \( j\omega L_p + \frac{1}{j\omega C_p} = 0 \) and \( j\omega L_{sk} + \frac{1}{j\omega C_{sk}} = 0 \). The impedance matrix, Equation (2), can be simplified as
The current in the primary circuit can be calculated as

\[
I_p = \frac{U_{in}}{(R_{in} + R_p) + \omega^2 (\sum_{i=1}^{n} \frac{M_{is}^2}{R_i + R_L})}
\]  

(4)

The current in the \(k\)th secondary circuit is

\[
I_{sk} = \frac{j \omega M_{ks} U_{in}}{(R_{in} + R_p) (R_s + R_L) + \omega^2 (\sum_{i=1}^{n} M_{is}^2)}
\]  

(5)

After the inner resistance of the power source is ignored, the received power of the \(k\)th load can be expressed as

\[
P_{outk} = I_{sk}^2 R_{lk} = \frac{\omega^2 M_{ks}^2 U_{in}^2 R_L}{\left[R_p (R_s + R_L) + \omega^2 (\sum_{i=1}^{n} M_{is}^2)\right]^2}
\]  

(6)

The diagram of mutual inductance calculation is shown in Figure 4. \(N_1\) and \(N_2\) represent the numbers of turns in primary coil and secondary coil respectively. \(\mu_0\) is the vacuum permeability and \(\mu_r\) is the relative permeability. \(I_p\) and \(I_{ks}\) are the current loops in the primary circuit and the \(k\)th secondary circuit respectively. \(dI_p\) and \(dI_{ks}\) are infinitesimal in the current loops respectively. \(R_k\) is the vector distance between \(dI_p\) and \(dI_{ks}\). The central coordinates of the primary coil and secondary coil are \(O_1(0, 0, 0)\) and \(O_2(x, 0, h)\) respectively, where \(x\) is the abscissa of the secondary coil center and \(h\) is the vertical height.

![Figure 4. The diagram of mutual inductance calculation.](image)

According to the Neummann formula, \(M_{ks}\) can be calculated as

\[
M_{ks} = \frac{N_1 N_2 \mu_0 \mu_r}{4\pi} \int_{I_p} \int_{I_{ks}} \frac{dI_p dI_{ks}}{R_k}
\]  

(7)

The curve of \(M_{ks}\) versus position variation of the secondary coil can be obtained as shown in Figure 5.
The effective wireless charging area is the area where the secondary coil can be located right above the primary coil. The lateral misalignment is not taken into account in this paper. As shown in Figure 5, the effective wireless charging area can be expressed as $x_1 \leq x \leq x_2$, where $x_1 = -(a_2 - a_1)/2$ and $x_2 = (a_2 - a_1)/2$. The received power changes little when the EV is in the effective charging area because the $M_{ks}$ does not change much there. On the other hand, the final stopping place of each EV is uncertain. Hence $M_{rms}$ (the Root Mean Square of $M_{ks}$) is chosen to express the mutual inductance in the effective wireless charging area approximately.

$$M_{rms} = \sqrt{\int_{x_1}^{x_2} M_{ks}^2 \, dx \over x_2 - x_1}$$

After Equation (8) is written into Equation (6), when the secondary coil is in the effective wireless charging area completely, the received power can be calculated as

$$P_{outk} = \frac{\omega^2 M_{rms}^2 U_{in}^2 R_L}{\left[R_p (R_s + R_L) + n\omega^2 M_{rms}^2\right]^2}$$

If $U_{in}$ always remains constant, it is difficult for $P_{outk}$ to maintain stability because $n$ is randomly changing. In order to reduce adverse effects that the random access of the new load has on the received power of previous loads, a power stabilization strategy, including counting the number of EVs, adjusting the power source voltage and choosing the counting points, is proposed in the following part. The received power of loads will be stabilized and the system’s adaptation to the random access load will be promoted with the application of this strategy.

4. Analysis and Control Strategy of Received Power Stabilization

4.1. Source Voltage Adjustment Strategy Based on Counting Loads when the System is at a Steady State

As the premise of the power stabilization strategy is based on step voltage adjustment, the counting method in the effective wireless charging area is shown in Figure 6. The tail counter and the head counter (such as the photoelectric counter and hall sensor counter) are installed in both ends of the effective wireless charging area. Since the effective wireless charging area is in the one-way lane, the number of EVs in the designated area $n$ can be expressed as

$$n = n_{\text{tail}} - n_{\text{head}}, n \geq 0$$

where $n_{\text{tail}}$ is the number of EVs passing the tail counter and $n_{\text{head}}$ is the number of EVs passing the head–tail counter.
The source voltage adjustment strategy based on the EV counting method is as follows. When \( n = 0 \), the voltage should be adjusted to \( U_{in(0)} = 0 \) \((n = 0)\). When \( n \geq 1 \), the received power can be stabilized around the expected value \( P_{out0} \) by voltage adjustments. According to Equation (9), power source voltage \( U_{in(n)} \) can be expressed as

\[
U_{in(n)} = \frac{\sqrt{P_{out0}} [R_p (R_s + R_L) + n \omega^2 M_{rms}^2]}{\sqrt{R_L \omega M_{rms}}} \quad (n \geq 1)
\]

which is equivalent to

\[
U_{in(n)} = \frac{\sqrt{P_{out0}} R_p (R_s + R_L)}{\sqrt{R_L \omega M_{rms}}} + n \frac{\sqrt{P_{out0}} \omega M_{rms}}{\sqrt{R_L}}
\]

which is rewritten as the following expression

\[
\begin{align*}
U_{in(n+1)} &= U_{in(n)} + \frac{\sqrt{P_{out0}} \omega M_{rms}}{\sqrt{R_L}} \\
U_{in(1)} &= \frac{\sqrt{P_{out0}} R_p (R_s + R_L)}{\sqrt{R_L \omega M_{rms}}} + \frac{\sqrt{P_{out0}} \omega M_{rms}}{\sqrt{R_L}}
\end{align*}
\]

where \( U_{in(k)} \) is the power source voltage when the number of loads in the effective wireless charging area is \( k \).

According to Expression (13), the voltage adjustment based on EVs counting method to stabilize the received power is as follows. When the first EV is detected, the power source voltage is

\[
U_{in(1)} = \frac{\sqrt{P_{out0}} R_p (R_s + R_L)}{\sqrt{R_L \omega M_{rms}}} + \frac{\sqrt{P_{out0}} \omega M_{rms}}{\sqrt{R_L}}.
\]

If the number of EVs is increased by one, the power source voltage is expected to be increased by \( \Delta U = \frac{\sqrt{P_{out0}} \omega M_{rms}}{\sqrt{R_L}} \).

This paper takes a four-load opportunity EV wireless charging system as an example. In fact, the number of loads should match the power supply transmitted by the grid. In the simulation study, the length and the width of the primary coil are 20 m and 0.9 m respectively. The number of turns of primary coil is six. The secondary coils are square and the length of the sides is 0.9 m. The number of turns of the secondary coils is seven. The vertical distance between the primary side and the secondary side is 0.20 m. Other parameters are shown in Table 1.

Table 1. System parameters.

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Note</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>( f )</td>
<td>Resonant frequency</td>
<td>85 kHz</td>
</tr>
<tr>
<td>( P_{out0} )</td>
<td>Expected power</td>
<td>10 kW</td>
</tr>
<tr>
<td>( R_p )</td>
<td>Primary coil resistance</td>
<td>1.5 ( \Omega )</td>
</tr>
<tr>
<td>( R_s )</td>
<td>Secondary coil resistance</td>
<td>0.2 ( \Omega )</td>
</tr>
<tr>
<td>( R_L )</td>
<td>Load resistance</td>
<td>50 ( \Omega )</td>
</tr>
</tbody>
</table>

The calculation result of \( M_{rms} \) is 23.4 \( \mu \)H, according to Equation (8). After the other parameters are put into Equation (13), the relationship between the power source voltage when system is at
a steady state and the number of loads can be obtained as shown in Figure 7. To be more specific, \( U_{\text{in}(1)} = 262 \, \text{V} \) and \( \Delta U = 177 \, \text{V} \).

4.2. The Strategy of Determining Counting Points Based on Bounded Domain of Received Power

In the opportunity EV wireless charging system at traffic lights, the mutual inductance is determined by the position of the tail counter when the power source voltage is about to adjust. The mutual inductance between the previous secondary coil and the primary coil is \( M_{k_0} = M_{\text{rms}} \), where \( 1 \leq k \leq n - 1 \) and those \( n - 1 \) secondary coils are in the effective wireless charging area. The mutual inductance between the \( n \)th secondary coil (new load) and the primary coil is expressed as \( M_{\text{ns}} \).

According to Equation (6), while the new load is entering the effective wireless charging area gradually, the received power of the previous loads can be expressed as

\[
P_{\text{outk}} = \frac{\omega^2 M_{\text{rms}}^2 U_{\text{in}(n)}^2 R_L}{\{ R_p (R_s + R_L) + \omega^2 [(n - 1) M_{\text{rms}}^2 + M_{\text{ns}}^2]\}^2} \quad (1 \leq k \leq n - 1) \tag{14}
\]

and the received power of the new \( n \)th load can be calculated as

\[
P_{\text{outn}} = \frac{\omega^2 M_{\text{ns}}^2 U_{\text{in}(n)}^2 R_L}{\{ R_p (R_s + R_L) + \omega^2 [(n - 1) M_{\text{rms}}^2 + M_{\text{ns}}^2]\}^2} \tag{15}
\]

When the \( n \)th coil is counted but not completely in the effective charging area, \( M_{\text{ns}} \) is a small value and the voltage is adjusted according to the increased EV number. Then \( P_{\text{outk}} \) will increase dramatically and exceed the expected range. In order to choose the optimal counting points, curves of the received power of each load versus position variation of the new load should be investigated. According to Equations (14) and (15), the curves of a one-load system, two-load system, three-load system and four-load system are shown respectively in Figure 8.

In the one-load system, the primary side will be in a state of overcurrent for a long time if the tail counter is installed far away from the effective charging area. As shown in Figure 8, the received power fluctuates with different rates as a result of the varying mutual inductance between primary side and secondary side. The fluctuation of the received power is assumed to be limited within 5% in this paper. The bounded domain of received power is displayed in Figure 8. The positions of the tail counter in each situation are the intersections of the power curves and the domain boundaries, namely, \( CP_a = -9.12 \, \text{m} \), \( CP_b = -8.76 \, \text{m} \), \( CP_c = -8.94 \, \text{m} \), \( CP_d = -9.00 \, \text{m} \). Finally, in order to meet the requirements simultaneously, the optimal position of the tail counter is chosen as \( CP_{\text{opt}} = -8.76 \, \text{m} \).
The head counter and the tail counter should be installed symmetrically. Hence, the optimal position of the head counter is chosen as \( x = 8.76 \) m.

![Graphs showing power curves and domain boundaries for different load systems.](image)

**Figure 8.** The curves of received power of each load versus position variation of new load: (a) one-load system; (b) two-load system; (c) three-load system; (d) four-load system.

To sum up, the power stabilization strategy in the opportunity EV wireless charging system at traffic lights can be concluded as follows. Firstly, the optimal counter positions are defined with the application of the theoretical analysis above. Then the number of loads in the effective wireless charging area is obtained on the basis of Equation (10). Finally, the power source voltage is adjusted according to Equation (13) and the received power can be stabilized in the bounded domain.

5. Experimental Verifications

The experimental prototype of an opportunity EV wireless charging system with four loads at most is proposed in Figure 9. The width and length of the rectangular primary coil are 0.15 m and 3.33 m respectively. The number of the turns is six. The secondary coils are square coils of seven turns and with a side of 0.15 m. The vertical distance between primary side and secondary side is 0.03 m. The inductance, the resistance and the compensation capacitor of the primary coil are 153.1 \( \mu \)H, 0.5 \( \Omega \) and 22 nF respectively. The inductance, the resistance and the compensation capacitor of the secondary coils are 20.4 \( \mu \)H, 0.1 \( \Omega \) and 168 nF respectively. Because of the manufacture of the coils and the capacitors with a fixed value, the working frequency is set to 87 kHz. In accordance with the theoretical analysis before, after the numerical simulation method, the power source voltage adjustment strategy is clarified as follows. The voltage is 5.0 V when only one load is detected and it increases by \( \Delta U = 3.5 \) V when a new load accesses. Furthermore, the tail counter position is determined as \( CP_{opt} = -1.45 \) m based on 5% bounded domain of received power. The head counter is omitted due to the symmetrical installment of the two counters.
In the experimental process, when the first load is located at the tail counter, the power source voltage is adjusted to \( U_{in(1)} = 5.0 \) V approximately. After changing the position of the first load and measuring the received power of it, the curve of received power versus position variation of the first load is shown in Figure 10a. When a new load is located at the tail counter, the voltage of power source increases by 3.5 V, namely, \( U_{in(2)} = 8.5 \) V, \( U_{in(3)} = 12.0 \) V and \( U_{in(2)} = 15.5 \) V. The other curves of received power versus position variation of the new access load are shown in Figure 10. According to the experimental results, the received power is around 10 W with fluctuation constrained in 5%. The voltage waveforms of the power source and the voltage waveforms of loads in systems with different load numbers when systems are at a steady state are shown in Figure 11. The voltages are measured with voltage probes (Tektronix TPP0500B, Beaverton, OR, USA).

Figure 9. The experimental prototype of the opportunity EV wireless charging system with four loads.

Figure 10. The experimental curves of received power versus position variation of the new access load: (a) one-load system; (b) two-load system; (c) three-load system; (d) four-load system.
Efficiency \( (W) \)

<table>
<thead>
<tr>
<th>Voltage ( V )</th>
<th>Voltage ( V )</th>
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<tbody>
<tr>
<td>10</td>
<td>10</td>
</tr>
<tr>
<td>15</td>
<td>15</td>
</tr>
<tr>
<td>20</td>
<td>20</td>
</tr>
</tbody>
</table>

The efficiency stack graph of systems with different load numbers when systems are at a steady state is shown in Figure 12. The efficiency increases with the increased load number.

Figure 12. The efficiency stack graph of systems with different load numbers.

The experimental prototype with low power rating is proposed to verify the theoretical research. The proposed power stabilization strategy is not influenced by the power rate. With the application of the power stabilization strategy proposed in this paper, the power source voltage is adjusted with the changing load number. The received power of loads is stabilized around 10 W and the power fluctuations are limited within 5%. Experimental results demonstrate the correctness of previous theoretical study.
6. Conclusions

This paper proposes an opportunity EV wireless charging system at traffic lights. However, due to the random access of EVs in this system, the constant power source voltage cannot meet the requirement of stable received power. In order to solve this issue, a power stabilization strategy of random access loads is proposed. Based on a model of a wireless power transfer system with one primary side and multiple loads, the relationship between received power and the number of loads is established. Then the adjustment strategy of the power source voltage is investigated with the application of the EV counting method. Furthermore, the counting points are chosen based on the voltage adjustment strategy and the bounded domain of received power. Finally, the power stabilization strategy of random access loads in the EV wireless charging system at traffic lights is validated by experiments.

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References


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