

Article

Prediction Performance of an Artificial Neural Network Model for the Amount of Cooling Energy Consumption in Hotel Rooms

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Abstract: This study was conducted to develop an artificial neural network (ANN)-based prediction model that can calculate the amount of cooling energy during the setback period of accommodation buildings. By comparing the amount of energy needed for diverse setback temperatures, the most energy-efficient optimal setback temperature could be found and applied in the thermal control logic. Three major processes that used the numerical simulation method were conducted for the development and optimization of an ANN model and for the testing of its prediction performance, respectively. First, the structure and learning method of the initial ANN model was determined to predict the amount of cooling energy consumption during the setback period. Then, the initial structure and learning methods of the ANN model were optimized using parametrical analysis to compare its prediction accuracy levels. Finally, the performance tests of the optimized model proved its prediction accuracy with the lower coefficient of variation of the root mean square errors (CVRMSEs) of the simulated results and the predicted results under generally accepted levels. In conclusion, the proposed ANN model proved its potential to be applied to the thermal control logic for setting up the most energy-efficient setback temperature.

Keywords: setback temperature; cooling energy consumption; artificial neural network; predictive and adaptive controls; accommodation

1. Introduction

With the period in which people spend their daily life in an indoor space having increased to 90%, the proper conditioning of the indoor environment quality (IEQ) has become a significant factor of the quality of life of the occupants [1]. The IEQ is associated with diverse components such as the thermal quality, light quality, air quality, and acoustic quality. In addition to the importance of providing the proper IEQ, these components are also deeply related to the building energy efficiency, environmental impact, and economic benefits.

Thermal quality (TQ) is one of the key components of the creation of a proper IEQ. The indoor thermal quality is complexly dependent on various thermal factors such as the indoor temperature, humidity, mean radiant temperature, and air velocity. These factors are affected by the heat transfer between the indoor and outdoor spaces, and by the indoor heat generation. Heat transfer consists of heat conduction and convection through building envelopes and solar radiation. In addition, indoor heat is generated by the occupants, lighting fixtures, and equipment. Proper planning of buildings can effectively control the amount of heat transfer and indoor heat generation [2–4].

Moreover, the thermal quality and the energy efficiency of buildings are closely correlated with the operating strategy of thermal control systems. Proper operation of heating, ventilating, and air conditioning systems (HVACs) can provide comfortable temperature and humidity conditions, and can enhance energy efficiency, which would reduce CO₂ generation that will decrease environmental damage [5].

Numerous studies have been conducted to propose a better control strategy for thermal systems. Among these efforts, artificial intelligence (AI), which is the study and design of intelligent agents that perceive their surrounding environment and take actions to maximize its chances of success, has been increasingly applied in the thermal control algorithm. AI can be successfully applied to the science and engineering of making intelligent machines. Thus, it can be defined as theories or methods that increase the potential of systems or logics to be used successfully based on their intelligent and smart works [1].

An artificial neural network (ANN) is a type of artificial intelligence. It is a computational model that uses the biological processes in the human brain [6]. Its advantage is that it does not require complex knowledge of system dynamics and can be successfully applied to non-linear systems or systems with unclear dynamics [1]. Based on the two major processes—(i) the feed-forward process for calculating the output from a series of inputs, and (ii) the back-propagation process for iterative self-learning—it was found that the predictive and adaptive controls of the systems are feasible.

The superiority of the ANN-based models over the existing mathematical models, such as of the proportional-integral-derivative (PID) models or regression models, has been widely proven [7]. The ANN model presented the more accurate prediction results for the heating and cooling loads [8–10] and energy consumption [11–17]. The ANN model successfully predicted the thermal comfort level as well as indoor temperature conditions [18–20]. In addition, after using the ANN model in the building thermal controls, the indoor thermal environment was more comfortably conditioned based on the

reduced overcooling and overheating, and the amount of energy consumption of the heating and cooling systems was significantly reduced [20–32].

Similar to other types of buildings, the thermal environment in accommodation buildings and its controls also need to be prudently managed to provide thermal comfort to the occupants and to improve the energy efficiency of systems. Despite these similar requirements, hotel rooms have two distinctive features. First, their indoor space is generally unoccupied at daytime and occupied at nighttime. Thus, thermal comfort is not an important factor at daytime, when the room is empty. Second, energy efficiency may not be among the occupant's concerns. Normally, the occupant pays the designated lodging charge without an extra fee for indoor thermal conditioning. The occupant may operate the heating and cooling systems in excess of their required degree. For example, general hotel users do not recognize the necessity of the setback application or the proper setback temperature of heating and cooling systems.

Thus, an active management process is required for the proper operation of thermal control systems in accommodation. The optimal setback temperature for heating and cooling systems needs to be considered in the expert system for improving energy efficiency. From this aspect, this study aimed at proposing an artificial neural network (ANN) model that can predict the amount of cooling energy needed during the setback period for various setback temperatures. The proposed ANN model calculates the amount of cooling energy during the unoccupied period for the diverse degrees of setback temperature of the cooling system. The optimal setback temperature, which consumed the least amount of cooling energy, can be applied as the most energy-efficient strategy.

The proposed ANN model in this study will be applied to the control logic which will be developed in the future study. With the use of the optimal setback temperature in the control logic, energy efficiency in accommodation buildings is expected to be improved.

2. Development of a Prediction Model

A logic framework for indoor thermal control systems, which can deliver indoor thermal comfort and building energy efficiency in a synthetic manner, has been proposed by Moon and Kim [1]. For improving the thermal comfort and building energy efficiency, the set-point and setback temperatures were mentioned to be optimally determined using the prediction models such as ANN.

Three major processes, as shown in Figure 1, were performed in this study for the development of an ANN-based prediction model. The first process involved the organizing of the initial model. In this process, the input, hidden and output neurons, initial number of hidden layers, and learning methods were determined. The second process optimizes the initial values of the ANN model such as the number of hidden layers and the learning methods to produce more stable and accurate outputs. The third step evaluates the prediction performance of the optimized ANN model. The accuracy of the prediction results of the ANN model was analyzed by comparing the predicted values with the numerically simulated values. The proven prediction accuracy of the ANN model showed its potential to be successfully applied to the control logic.

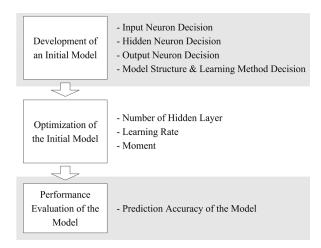


Figure 1. Development process of the prediction model.

2.1. Development of the Initial Model

The composition of the initial ANN model is shown in Figure 2 and summarized in Table 1. MATLAB (Matrix Laboratory) [30] and its neural network toolbox were used to develop the initial ANN model. The input variables for the prediction of the output variable, which is the amount of cooling energy consumption during the setback period (ENSETBACK, kWh), were composed of the setback temperature (TEMPSETBACK, °C), outdoor air temperature (TEMPout, °C), average outdoor air temperature from an hour earlier to the last control cycle (TEMPOUT, AVE, nStep-60~nStep-1, °C), average outdoor air temperature from two hours earlier to an hour earlier (TEMPout, AVE, nStep-120~nStep-61, °C), average outdoor air temperature from three hours earlier to two hours earlier (TEMPOUT, AVE, nStep-180~nStep-121, °C), outdoor earlier air temperature from four hours earlier to three hours average (TEMP_{OUT, AVE, nStep-240~nStep-181}, °C), average outdoor air temperature from five hours earlier to four hours earlier (TEMPOUT, AVE, nStep-300~nStep-241, °C), average outdoor air temperature from six hours earlier to five hours earlier (TEMP_{OUT, AVE, nStep-360~nStep-301}, °C), and daytime setback period (EN_{SETBACK}, minutes).

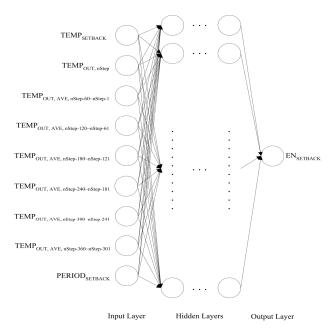


Figure 2. Structure of the initial ANN model.

	Parameters	Components and values		
		Number of neurons: 9		
		i) TEMP _{SETBACK} ii) TEMP _{OUT, nStep} iii) TEMP _{OUT, AVE, nStep-60~nStep-1}		
	Input layer	iv) TEMP _{OUT, AVE, nStep-120~nStep-61}		
Structure	input layer	v) TEMP _{OUT, AVE, n} Step-180~nStep-121		
		vi) TEMP _{OUT, AVE, nStep-240~nStep-181}		
		vii) TEMP _{OUT, AVE, nStep-300~nStep-241}		
		viii) TEMP _{OUT, AVE, nStep-360~nStep-301}		
		ix) PERIOD _{SETBACK}		
		Number of neurons: 19 using		
	Hidden layer	$N_h = 2N_i + 1$ [11,33]		
		Number of hidden Layer: 1		
	Output layer	Number of neuron: 1		
	Guiput layer	i) EN _{setback}		
Transfer function	Hidden neurons	Tangent sigmoid		
	Output neurons	Pure linear		
т д і	Goal	0.01 kWh (mean square error)		
	Epoch	1,000 times		
	Learning rate	0.6 [34]		
	Moment	0.4 [34]		
raining method	Algorithm	Levenberg-marquardt [1,35–37]		
	Number of data sats	196 using		
	Number of data sets	$N_d = (N_h - (N_i + N_o)/2)^2 [12]$		
	Data management technique	Sliding-window method		

Table 1. Composition of the initial prediction model.

The relationship between the setback temperature and the amount of energy consumption, as well as between the setback period and the amount of energy consumption, had been proven in the previous study [38]. The current and past outdoor temperatures also showed a significant relationship with the amount of energy consumption for thermal conditioning in buildings. The input values for each neuron were normalized between 0 and 1 using Equation 1. The normalized values were represented as 23 to 40 °C for TEMP_{SETBACK}, -20 to 40 °C for TEMP_{OUT} and TEMP_{AVE}, and 0 to 10 hours for PERIOD_{SETBACK}.

$$(VAL_{ACT}-VAL_{MIN}) / (VAL_{MAX}-VAL_{MIN})$$
(1)

The amount of cooling energy consumption (ENSETBACK) from the ANN model indicated the summation of the cooling energy during the setback period and the cooling energy needed to restore the indoor temperature to the normal set-point temperature. For example, when the setback temperature is 30 °C during the setback period and the normal set-point temperature is 23 °C, the cooling system will condition the indoor temperature to keep it at 30 °C during the setback period. To achieve this, a certain amount of cooling energy will be consumed. Moreover, when the setback period ends the set-point temperature returns to normal. For a certain period, the cooling system needs

to work to restore the indoor temperature to 23 °C. This is the cooling energy required to normalize the indoor temperature. Since the cooling energy for the restoration was increased when the setback temperature was higher, the optimal setback temperature must be determined to reduce the overall cooling energy consumption.

The number of hidden layers was initially determined as 1, and the number of hidden neurons, as 19, using the equation in Table 1. For the transfer functions, tangent-sigmoid and pure linear functions were used for the hidden and output neurons, respectively. In addition, a 0.0 minute goal, 1000 times epoch, 0.6 learning rate, 0.4 moment, and the Levenberg-Marquardt algorithm were used for the model training. The optimal number of hidden layers, learning rate, and moment were found in the optimization process.

A total of 196 data sets for initial training were collected based on the equation in Table 1, and the sliding-window method was used to manage the training data sets. In addition, 100 data sets for model optimization and 100 data sets for performance evaluation were prepared. Data sets for model training and evaluation were numerically collected incorporating and MATLAB (Matrix Laboratory) software [39] and TRNSYS (Transient Systems Simulation) [40].

Nine identical modules were modeled for data collection, and the data sets were collected from a module at their center, as shown in Figure 3. Figure 4 shows the modeling result of the test building. The features of the test location, dimensions, envelope insulation, infiltration rate, internal gain, and applied system are summarized in Table 2. The cooling system in the 56a-TRNFlow component was not confined to have a specific type. Instead, the method and capacity of the heat removal from the space were determined as convective and 8901 kJ/hr, respectively. The roles of seven types of components of TRNSYS software are summarized in Table 3.

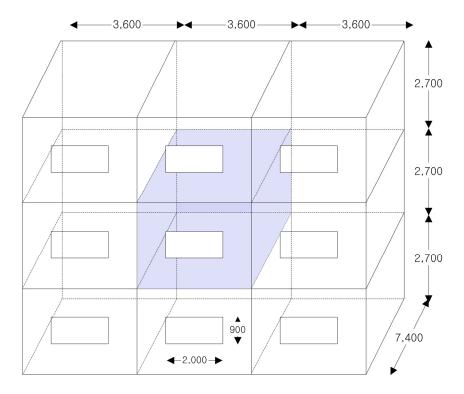


Figure 3. Test building (unit: mm).

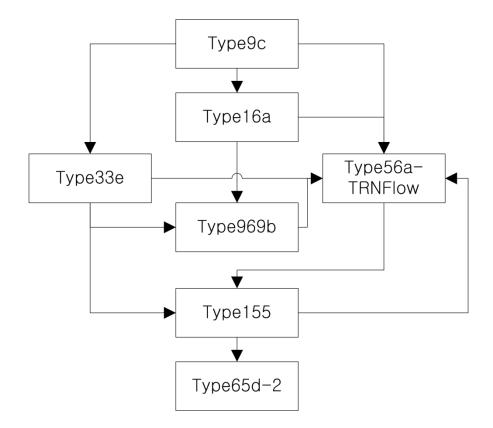


Figure 4. Composition of the simulation model.

Components		Contents				
	Location and weather data	Seoul, South Kroea (latitude: 37.56°N, longitude: 126.98°E) and TMY2				
Site	Climate conditions	Hot and humid in summer: 23.5 °C of air temperature and 72.7% of relative humidity from June to September in average Cold in winter: 1.7 °C of air temperature and 59.1% of relative humidity from November to February in average				
	Module	26.64 m^2 3.6 m wide × 7.4 m deep × 2.7 m high				
Dimension -	Window	1.8 m^2 2.0 m wide × 0.9 m high				
Envelope	Exterior walls	2.801				
insulation [m ² K /W]	Interior walls, roof and floor	0.492				
[41]	Windows	0.353				
Infiltration rate [41]		0.7 ACH				
Internal gain		1 occupant with seated, light work, typing 1 computer and printer 5 W/m ² lighting fixtures				
Applied system [42]		Convective cooling: 8901 kJ/hr heat removal				

Components	Roles			
Туре9с	Reading the TMY2 weather file			
	Transferring the weather data to the Type16a, Type33e, and Type56a-TRNFlow			
Type16a	Calculating the amount of solar radiation on the test building surface			
	Transferring the data to Type69b			
Tpe69b	Calculating the sky temperature			
	Transferring the data to the Type56a-TRNFlow			
Truno 22 o	Calculating the outdoor dew-point temperature			
Туре33е	Transferring the data to Type69b			
True 5 Co. TDNE love	Calculating the indoor temperature of the test building			
Type56a-TRNFlow	Transferring the data to Type 155			
T 155	Connecting the MATBAL and ANN models			
Type155	Producing training data sets			
Type65d-2	Producing the output file			

Table 3. Roles of the TRNSYS components.

Data sets for training, optimization, and evaluation were collected during the cooling season from June 01 to September 30. Different degrees of TEMP_{SETBACK} from 23 °C to 40 °C were applied to obtain the EN_{SETBACK}. The PERIOD_{SETBACK} was fixed 10 hours assuming the unoccupied period was from 8:00 to 18:00. Thus, a variety of EN_{SETBACK} according to the change of TEMP_{SETBACK} was collected for model training, optimization, and evaluation. Examples of data sets, which are composed of a series of input variables and one output variable, are presented in Table 4.

	1					
Data sets		1	2	3	4	5
	TEMD	0.00	0.00	0.00	0.00	0.00
	TEMPSETBACK	(23.00)	(23.00)	(23.00)	(23.00)	(23.00)
	TEMPOUT, nStep	0.65	0.67	0.66	0.70	0.68
	I LIVIF OUT, nStep	(19.07)	(20.15)	(19.65)	(21.78)	(20.72)
	TEMD	0.64	0.65	0.65	0.68	0.66
	TEMPOUT, AVE, nStep-60~nStep-1	(18.29)	(19.28)	(19.10)	(21.01)	(19.70)
	TEMD	0.64	0.63	0.63	0.66	0.63
	TEMPOUT, AVE, nStep-120~nStep-61	(18.17)	(17.54)	(18.04)	(19.47)	(17.70)
Input components (actual value in	TEM	0.65	0.60	0.62	0.63	0.60
parenthesis, °C for TEMP and minutes for PERIOD)	TEMPOUT, AVE, nStep-180~nStep-121	(18.89)	(15.83)	(16.99)	(17.96)	(15.73)
minutes for PERIOD)	TEMD	0.66	0.59	0.61	0.63	0.59
	TEMPOUT, AVE, nStep-240~nStep-181	(19.62)	(15.51)	(16.58)	(17.90)	(15.19)
		0.67	0.60	0.61	0.64	0.59
	TEMPOUT, AVE, nStep-300~nStep-241	(20.34)	(15.97)	(16.54)	(18.66)	(15.49)
	TEMD	0.68	0.61	0.61	0.66	0.60
	TEMP _{OUT} , AVE, nStep-360~nStep-301	(21.06)	(16.45)	(16.53)	(19.43)	(15.82)
	DEDIOD	1.00	1.00	1.00	1.00	1.00
	PERIODsetback	(600)	(600)	(600)	(600)	(600)
Output component, minutes	ENI	126.00	192.00	157.00	146.00	172.00
(actual value in parenthesis, kWh)	ENsetback	(5.19)	(7.91)	(6.47)	(6.02)	(7.09)

Table 4. Composition of the training data sets.

2.2. Optimization of the Initial Model

To produce more accurate and stable prediction results from the prediction model, the structure and the training methods of the initial ANN model were optimized using a parametrical optimization process based on the method used in the previous study [2,34,43].

The numbers of hidden learning rates and moments were sequentially optimized. When the first component (*i.e.*, the number of hidden layers) was used with a target variable to be optimized, the other components (*i.e.*, the learning rate and moment) were fixed as the initial values. After the optimal value of the first component was determined, the next component (*i.e.*, the learning rate) was optimized. In this case, the first component (*i.e.*, the number of hidden layers) was fixed as the optimal value, and the last component (*i.e.*, the moment) was fixed as the initial value. This process was conducted until the optimal value of the last component (*i.e.*, the moment) was found. The parametrical values used to optimize each component are summarized in Table 5.

One hundred data sets were collected for the ANN model optimization from the identical simulation model explained in Section 2.1. The coefficient of variation of the root mean square errors (CVRMSEs) (Equation 2) of the predicted values (Si) and the simulated values (Mi) were calculated for each parametrical value. The value that produced the smallest CVRMSE was determined as the optimal value of each component.

Components to be optimized			Par	ametr	ical va	lues to	o be te	sted		
Number of hidden layer	1	2	3	4	5	6	7	8	9	10
Learning rate	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0
Moment	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0
$CVRMSE = \sqrt{\frac{\sum_{i=1}^{n} (Mi - Si)^{2}}{n}} / Mavr \times 100$										

Table 5. Parametrically tested values for optimizing the ANN components.

2.3. Performance Evaluation of the Optimized ANN Model

The prediction performance of the optimized ANN model was tested using the 100 data sets. Through the comparison of the CVRMSEs of the predicted (Si) and simulated (Mi) amounts of cooling energy, the prediction accuracy and stability of the developed ANN model was validated. This validity will support the applicability of the proposed ANN model to the thermal control logic for improving building energy efficiency.

3. Results Analysis

3.1. Initial Model and Optimization

The performance of the initial model was statistically investigated using the analysis of variance (ANOVA) test and the mean squared errors (MSE) between the collected data from simulation and the predicted data from the ANN model for the amount of heat removal during the unoccupied period. For 100 cases, the R² between simulated values and predicted values was 0.4886 as shown in Figure 5

and summarized in Table 6, and the MSE was 0.768 kWh². Based on this initial model, the optimization process was conducted for more accurate and stable prediction.

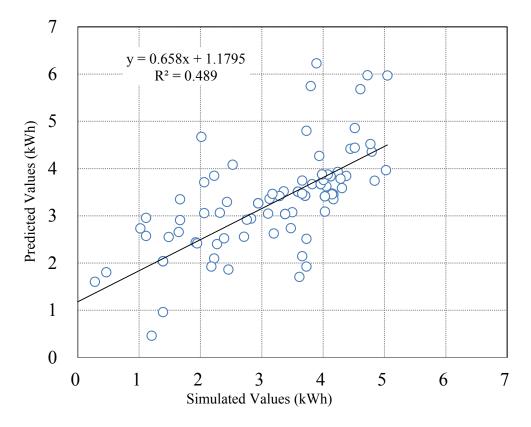


Figure 5. Relationship between the simulated values and the predicted values for the amount of heat removal during the unoccupied period.

Independent	Unstandardized coefficients		t	Significance.	ANOVA			
variables –	В	Std. error	_		R2	F(1, 54)	Significance.	
Predicted Values	0.658	0.068	9.677	< 0.001	0.489	93.642	< 0.001	

Table 6. ANOVA test result between the simulated values and the predicted values.

The comparison results for the prediction accuracy of the ANN models, which had different values for the structure and learning method, were compared for determining optimal ANN model as shown in Figures 6–8. The accuracy was compared with the difference between the predicted values from the ANN model (S_i) and the simulated values (M_i).

In the first step for finding the optimal number of hidden layers, the least CVRMSE between S_i and M_i was produced with three hidden layers, as presented in Figure 6. At this step, the learning rate and moment were fixed as initially determined at 0.6 and 0.4, respectively. The CVRMSE (%) ranged from 27.72% to 76.02% for the one to 10 hidden layers. The least value, when the ANN model used three hidden layers, was 27.72%, whereas the initial model with one hidden layer produced a much higher value: 41.14%. Thus, the modified ANN model was changed to have three hidden layers.

In the second step for determining the optimal value of the learning rate, the learning rate was parametrically changed from 0.1 to 1.0, as shown in Figure 7. The number of hidden layers was set as

three, as found in the previous step, and the moment was fixed at its initial value of 0.4. The CVRMSE values ranged from 27.72% to 42.27%. The lowest value was presented when the initial value of the learning rate (0.6) was applied. Thus, the learning rate of the ANN model was not revised to 0.6.

The third step was conducted to find the optimal value of the moment. Identical to the previous step, the moment was parametrically changed from 0.1 to 1.0, as shown in Figure 8. At this step, the number of hidden layers and the learning rate were fixed at the optimal values of 3 and 0.6, respectively. The CVRMSE ranged from 22.77% to 43.91%, and the lowest value was produced from a model with a moment of 0.2. The amount of MBE was 22.77%. Thus, the optimal model was determined to have a moment of 0.2. Based on the three steps conducted for finding the optimal structure and learning methods of the ANN, it was decided that the optimal ANN model has three hidden layers, a 0.6 learning rate, and a moment of 0.2.

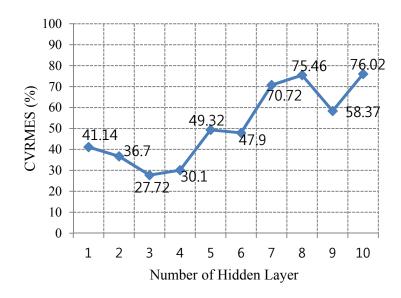


Figure 6. Mean bias error (MBE) by a different number of hidden layers.

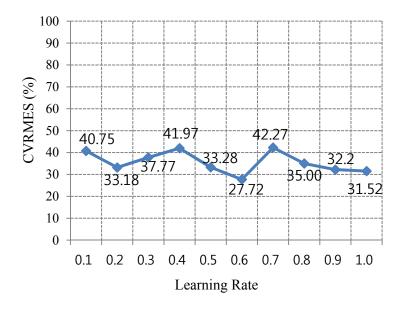


Figure 7. MBE by a different learning rate.

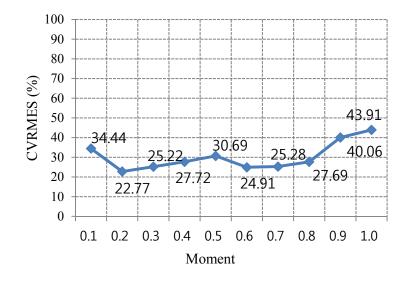


Figure 8. MBE by a different moment.

3.2. Performance of the Optimized Model

The performance of the optimized ANN model was evaluated according to its prediction accuracy. For the evaluation, data sets from the simulation model explained in Section 2.1 were required to be checked. Figure 9 shows the relationship between the setback temperature and the amount of heat removal by the cooling system. As the higher setback temperature was applied during the unoccupied period, the amount of heat removal was decreased. When the setback temperatures were over 30 °C, the amounts of heat removal were all close to 0.0 kWh, which means the indoor temperature did not reach the degree requiring cooling operation. Thus, for the performance evaluation of the ANN model, the data sets were collected for cases when the setback temperatures between 23 °C and 30 °C were applied.

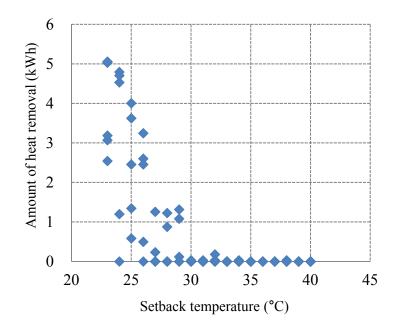


Figure 9. Relationship between the setback temperature and the amount of heat removal.

The amount of heat removal was vastly different for the same setback temperature. For example, the amount varied from 0 to around 5 kWh for the same 20 °C setback temperature. This phenomenon was due to the different outdoor temperature conditions. For a day when the current and past outdoor temperatures were higher, a larger amount of heat removal was required. Thus, the outdoor temperature conditions of the current control cycle and the past cycles were used as input variables.

The simulated data (M_i) were compared with the predicted data from the ANN model (S_i). As shown in Figure 10, the predicted data from the ANN model (red-solid-line) had a pattern similar to that of the simulated data from the simulation model (blue-dot-line). The y-value of the chart refers to the amount of cooling energy during the setback period.

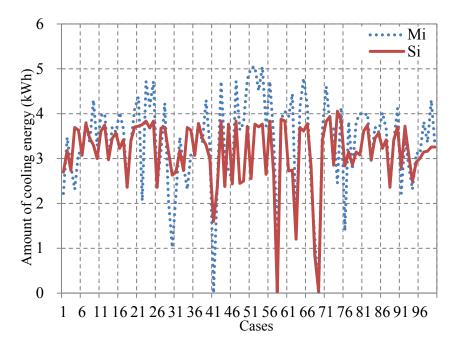


Figure 10. Comparison of the simulated results with the prediction results.

For the 100 cases, the average difference between the simulated and predicted results was 0.57 kWh, which was 17.07% of the average cooling energy of the simulation. The difference ranged from 2.47 kWh to 0.01 kWh. The CVRMSE was 21.32% for the 100 cases. Based on the proposal in the previous study of around 25% as a statistically meaningful value for supporting the applicability of the model [44], the prediction accuracy of the ANN model in this study was validated with a 17.07% average difference and a 21.32% CVRMSE. Thus, the ANN model showed the potential for successful application to the thermal control logic for employing the most energy-efficient setback temperature.

4. Conclusions

This study was conducted to develop an artificial neural network (ANN)-based prediction model that can calculate the amount of cooling energy needed during the setback period of accommodation buildings. By comparing the amounts of energy needed for diverse setback temperatures, the most energy-efficient optimal setback temperature was found and could be applied in the thermal control logic. Three major processes took place for developing and optimizing the ANN model, and for testing its prediction performance, respectively. The findings are summarized as follows.

(1) The initial ANN model for predicting the amount of cooling energy needed was developed to have nine input neurons, which were strongly related to the output neuron, 19 hidden neurons, one hidden layer, and one output neuron. In addition, a 0.6 learning rate and a moment of 0.4 were used for the learning methods;

(2) Through the optimization process using the parametrical analysis of the prediction performance of the initial ANN model, the model was modified to have three hidden layers, a 0.6 learning rate, and a moment of 0.2, which presented the lowest CVRMSE value between the simulated results (M_i) and the predicted results (S_i);

(3) The performance tests of the optimized ANN model showed that it presented a lower CVRMSE value under the generally accepted levels. Thus, the prediction accuracy of the developed ANN model was proven, so when the model is applied to the thermal control logic, the most energy-efficient setback temperature is expected to be used.

From the development and evaluation process, the optimized ANN model in this study presented its prediction accuracy and potentials applicable to the control logic. A further study is required for developing the thermal control logic after applying the proposed ANN model and for testing its performance. The performance tests need to be conducted by applying the model to real buildings and to the numerical computer simulation method. Using the extensive data analysis from the real building and computer simulation, the stability of the model such as an over-fitting problem will be thoroughly investigated, and based on which, the applicability of the proposed model will be supported. In addition, the ANN model and the thermal control logic will be developed to cover the heating system. After the application of the predictive and adaptive control logics, the indoor thermal environment of accommodation buildings is expected to be conditioned more energy-efficiently.

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Author Contributions

All authors participated in preparing the research from the beginning to ends, such as establishing research design, method and analysis. All authors discussed and finalized the analysis results to prepare manuscript according to the progress of research.

Conflicts of Interest

The authors declare no conflict of interest.

Nomenclature:

TEMPSETBACK	setback temperature, °C				
TEMPOUT, nStep	outdoor air temperature in the current control cycle, °C				
TEMPOUT, AVE, nStep-60~nStep-1	average outdoor air temperature from nStep-60 to nStep-1, °C				
TEMPOUT, AVE, nStep-120~nStep-61	average outdoor air temperature from nStep-120 to nStep-61, °C				
TEMPOUT, AVE, nStep-180~nStep-121	average outdoor air temperature from nStep-180 to nStep-121, °C				
TEMPOUT, AVE, nStep-240~nStep-181	average outdoor air temperature from nStep-240 to nStep-181, °C				
TEMPOUT, AVE, nStep-300~nStep-241	average outdoor air temperature from nStep-300 to nStep-241, °C				
TEMPOUT, AVE, nStep-360~nStep-301	average outdoor air temperature from nStep-360 to nStep-301, °C				
PERIODsetback	setback period during the daytime, minutes				
ENsetback	predicted amount of cooling energy consumption during the setback				
EINSEIBACK	period, kWh				
Ni	number of neurons in the input layer				
Nh	number of neurons in the hidden layer				
No	number of neurons in the output layer				
VALACT	actual value of each input variable				
VAL _{MIN}	minimal value of each input variable				
VAL _{MAX}	maximal value of each input variable				
Si	value predicted by the ANN model				
Mi	numerically simulated value				
Mave	average of M _i				
n	number of cases				

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