## Article

# Wide Load Range Capacitor Clamped ZVZCS Half Bridge Three-Level DC-DC Converter with Two Unsymmetrical Bi-directional Switches 

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#### Abstract

This paper presents a zero-voltage and zero-current switching (ZVZCS) capacitor-clamped half bridge (HB) three-level dc-dc converter (TLDC), which is well fit for high input voltage dc-dc industrial applications. The maximum voltage stress of the primary switches is limited by the flying capacitor and input capacitors, which is very close to $\mathrm{V}_{\mathrm{in}} / 2$. Two unsymmetrical bidirectional switches are used to replace two of the primary switches in a conventional capacitor-clamped HB TLDC, which ensure ZVZCS of the main switches in wide load range. The reverse direction MOSFETs in the unsymmetrical bidirectional switches have low on-state resistance and are controlled with soft-switching mode irrelevant to the load current. Therefore, the additional power loss can be omitted. The current of the flying capacitor is greatly reduced due to ZVZCS operation, which would result in a smaller volume flying capacitor and high system reliability. Furthermore, the current imbalance problem of the power devices is also well solved. The circuit, basic operation principles and some important technical analyses are discussed in this paper, and experimental results from a $1-\mathrm{kW}$ prototype are provided to evaluate the proposed converter.


Keywords: three-level dc-dc converter; ZVZCS; capacitor clamped; balanced current distribution

## 1. Introduction

Three-level (TL) dc-dc converters (TLDCs) can be widely used in plenty of existing and upcoming industrial applications, e.g., dc-dc converters for distributed power systems, micro-grids, renewable energy power systems, and electric vehicles [1-4]. The most outstanding attribute of TLDC is reduced voltage stress of the primary switches, and both dynamic and static voltages on the main switches can be confined below $\mathrm{V}_{\mathrm{in}} / 2$ by the clamping devices, such as clamping diodes or capacitors. After diode-clamped TLDC was proposed in 1992, several good studies on this topic have been carried out, which are new topologies, wide load range soft-switching techniques, reduced volume of passive components methods, and new control strategies [5-21]. Several TLDCs were proposed in Reference [5], and most existing TLDCs are invented based on these topologies. A secondary active reset zero-voltage and zero-current switching (ZVZCS) TLDC was reported in Reference [6], wherein an extra capacitor is added to the primary side to realize a phase-shift (PS) switching scheme. In Reference [6], the extra capacitor provides a zero-voltage switching (ZVS) quasi-resonant path for the outer switches and a secondary clamping circuit is adopted to provide zero-current switching (ZCS) for the inner switches. In Reference [7], a passive snubber is series-connected with the primary coil of the transformer to generate reset voltage of the primary current, and two diodes are used to prevent a negative primary current during the free-wheeling stages. Some other new TLDCs were reported in References [8-14], which have different attractive characteristics. To reduce the volume of the passive filter, lots of TLDCs with TL secondary-rectified voltage waveforms were proposed. In Reference [15], a hybrid TLDC
was proposed, which can generate TL secondary waveform before the output filter. A hybrid ZVZCS TLDC was proposed in Reference [16], which can achieve TL secondary rectified waveform as well as a wide soft switching load range. A ZVZCS TLDC with no primary clamping devices was proposed in Reference [17], which has a simpler primary structure. A TLDC with four switches was proposed, which has the minimum primary switches to generate a TL secondary-rectified waveform [18]. Other TLDCs with reduced volume of the output filter were reported in References [19,20]. To improve the reliability of TLDCs, some detailed analyses about current imbalanced problems of the primary components are investigated [21-23]. All mentioned references have made TLDCs more applicable.

Figure 1a shows a capacitor-clamped half bridge (HB)TLDC, and the four switches in Figure 1a are switched in the asymmetrical PWM (APWM) method to achieve balanced voltage on the input and flying capacitors. As depicted in Figure 1a, only one flying capacitor is parallel connected with HB cells, which would minimize the space of the circuit loop among $C_{i n 1}, C_{i n 2}$, and $Q_{1}$ to $Q_{4}$ in a real product. Hence, the parasitic inductance caused by this circuit loop would be small, which suppresses the voltage spike on the primary switches at turn-off instants. The voltage stress of the main switches is restricted by $\mathrm{C}_{\mathrm{s}}$, and this capacitor would absorb more energy stored in the parasitic inductances of the primary circuit. Therefore, all the primary switches can be well confined in the safe operation area (SOA). In addition, widely-used two-level HB power modules can be adopted in the proposed converter, which makes this topology more convenient for industrial users.


Figure 1. Capacitor-clamped HB TLDC and its key waveforms: (a) Circuit; (b) Key waveforms.
However, some drawbacks of the converter in Figure 1a should be overcome. First, as illustrated in Figure $1 \mathrm{~b}, i_{\mathrm{Q} 1}$ and $i_{\mathrm{Q} 2}$ are imbalanced due to an asymmetrical switching sequence, which causes some design obstacles for the power devices. Furthermore, with a decrease of the duty ratio, the imbalanced degree of the current distribution among $Q_{1}$ to $Q_{4}$ is more serious, which would affect the reliability of the converter. Second, the current distribution of $\mathrm{C}_{\mathrm{in} 1}$ and $\mathrm{C}_{\mathrm{in} 2}$ is also imbalanced, and the RMS value of $i_{\mathrm{Cin} 2}$ is clearly higher than that of $i_{\mathrm{Cin} 1}$ under a small duty ratio. High current stress leads high operation temperature, and it is well known that the life expectancy of film or an AL electrolytic capacitor is inversely proportional to the operation temperature. Therefore, the reliability of the converter would also be reduced. Third, $i_{p}$ flows through $C_{s}$ during the freewheeling stages, which would cause thermal problems of $C_{s}$. In addition, a large value capacitance of $C_{s}$ is required to minimize the voltage ripple on it, which increases the volume of $C_{s}$. Finally, $Q_{1}$ and $Q_{3}$ cannot achieve zero-voltage switching in a wide load range due to less energy reserved in $\mathrm{L}_{\mathrm{lk}}$. New capacitor-clamped TLDC without the above-mentioned drawbacks is an interesting problem.

This paper proposes a novel ZVZCS capacitor-clamped HB TLDC, which overcomes all abovementioned shortcomings. In addition, all above features can be achieved with a simple switching sequence. The outline of this paper is concluded as follows. In part 1, the circuit is described, and detailed analysis about the operation principle is presented. Some technique aspects are analyzed in part 2. In part 3, experimental results are provided and analyzed, and some brief conclusions are given in the final part.

## 2. Circuits and Principle of Operation

Figure 2 shows the proposed ZVZCS HB TLDC, and two unsymmetrical bi-directional switches are replaced by $\mathrm{Q}_{2}$ and $\mathrm{Q}_{4}$ in Figure 1a. The unsymmetrical bi-directional switches can conduct a bi-directional current with the same value and sustain different bi-directional voltage. After introducing the unsymmetrical bi-directional switches, the currents of $S_{2}$ and $S_{4}$ can be controlled as a positive value, negative value or zero freely. Consequently, the converter with APWM switching scheme can also achieve ZVZCS operation. The remaining circuit is identical to that of the converter in Figure 1a, which is not described in detail.


Figure 2. Proposed capacitor-clamped ZVZCS HB TLDC.
Figure 3 shows the waveforms of the proposed converter, and identical circuits over one-half switching period are given in Figure 4. To simplify the analysis, some assumptions are given: all components have ideal characteristics; $C_{i n 1}$ and $C_{i n 2}$ are the input capacitors with a certain value, which could reset $i_{\mathrm{p}}$ properly during the operation as well as transfer energy to the load; $\mathrm{S}_{k}$ is replaced by $\mathrm{Q}_{k \mathrm{P}}$ and $\mathrm{Q}_{k \mathrm{R}}$ in Figures 3 and $4 ; \Delta v_{\mathrm{Cin} 2}=\mathrm{V}_{\mathrm{in}} / 2-v_{\mathrm{Cin} 2}$; the current ripple of $\mathrm{L}_{\mathrm{o}}$ is neglected, and $i_{\mathrm{Lo}}$ is represented by $I_{0}$.


Figure 3. Key waveforms.


Figure 4. Identical circuits: (a) Mode 1; (b) Mode 2; (c) Mode 3; (d) Mode 4; (e) Mode 5; (f) Mode 6.
Mode 1 [Figure 4 a , before $t_{0}$ ]: $\mathrm{Q}_{1}$ and $\mathrm{Q}_{2 \mathrm{P}}$ are on; energy is transferred from the primary side to the load; $\mathrm{Q}_{2 \mathrm{R}}$ and $\mathrm{Q}_{4 \mathrm{R}}$ are also on, $\mathrm{D}_{\mathrm{o} 1}$ and $\mathrm{D}_{\mathrm{o} 4}$ are conducted. $v_{\text {Cin2 }}$ increases with the rate of

$$
\begin{equation*}
\frac{d v_{\mathrm{Cin} 2}}{d t}=\frac{\mathrm{I}_{\mathrm{o}}-k_{\mathrm{T}}\left|\dot{\mathrm{inn}}_{\mathrm{in}}\right|}{k_{\mathrm{T}} \mathrm{C}_{\mathrm{in} 1}}-\frac{\left|\dot{i}_{\mathrm{in}}\right|}{\mathrm{C}_{\mathrm{in} 2}} \tag{1}
\end{equation*}
$$

During this stage, $v_{\mathrm{p}}=\mathrm{V}_{\mathrm{in}} / 2-\Delta v_{\mathrm{Cin} 2} ; v_{\mathrm{re}}=\left(\mathrm{V}_{\mathrm{in}}-2 \Delta v_{\mathrm{Cin} 2}\right) / 2 k_{\mathrm{T}} ; i_{\mathrm{p}}=\mathrm{I}_{\mathrm{o}} / k_{\mathrm{T}} ; i_{\mathrm{Cin} 1}=\mathrm{I}_{\mathrm{o}} / k_{\mathrm{T}}-\left|i_{\text {in }}\right|, i_{\mathrm{Cin} 2}$ $=-\left|i_{\text {in }}\right| ; v_{\mathrm{Q} 3}=v_{\mathrm{Q} 4 \mathrm{P}}=\mathrm{V}_{\text {in }} / 2$. Although $\mathrm{Q}_{4 \mathrm{R}}$ is on, $i_{\mathrm{Q} 4 \mathrm{R}}$ is zero owing to $\mathrm{Q}_{4 \mathrm{P}}$ is off.

Mode 2 [Figure $4 \mathrm{~b}, t_{0}-t_{1}$ ]: At $t_{0}, \mathrm{Q}_{1}$ is off, and $v_{\mathrm{Q} 1}$ cannot change sharply due to $\mathrm{C}_{1} ; v_{\text {Cin2 }}$ increases, and reaches $V_{\text {Cin2max }}$ at the end of this mode. $i_{\mathrm{p}}=\mathrm{I}_{\mathrm{o}} / k_{\mathrm{T}}$, and charges $\mathrm{C}_{1}$ and discharges $\mathrm{C}_{4 \mathrm{P}}$ through $\mathrm{C}_{\mathrm{s}}$. This stage continues until $v_{\mathrm{C} 1}=\mathrm{V}_{\text {in }} / 2$ and $v_{\mathrm{C} 4 \mathrm{P}}=0 . i_{\mathrm{Cin} 1}=-\left|i_{\mathrm{in}}\right|, i_{\mathrm{Cin} 2}=-\mathrm{I}_{\mathrm{o}} / k_{\mathrm{T}}-\left|i_{\text {in }}\right| \cdot v_{\mathrm{Q} 3}$ is $v_{\mathrm{Cs}}$, which is identical to $\mathrm{V}_{\mathrm{in}} / 2 . v_{\mathrm{Q} 1}$ and $v_{\mathrm{Q} 4 \mathrm{P}}$ are smaller than $\mathrm{V}_{\mathrm{in}} / 2$.

Mode 3 [Figure $4 \mathrm{c}, t_{1}-t_{3}$ ]: At $t_{1}, \mathrm{D}_{4 \mathrm{P}}$ conducts naturally and $\mathrm{I}_{\mathrm{O}}$ is free-wheeled through secondary rectifier diodes. After $t_{1}, Q_{4 P}$ should be triggered on to ensure zero-voltage operation, and as proved in Figure $3, Q_{4 P}$ is on with zero-voltage at $t_{2} . Q_{2 R}$ is also turned off at $t_{2}$. As $\mathrm{D}_{2 R}$ conducts naturally, $\mathrm{Q}_{2 \mathrm{R}}$ can achieve zero-voltage turn-off. $v_{\mathrm{Cin} 2}$ is $\mathrm{V}_{\mathrm{Cin} 2 \mathrm{MAX}}$, and $\mathrm{V}_{\mathrm{Cin} 2 \mathrm{MAX}}-\mathrm{V}_{\mathrm{in}} / 2$ is fully applied to $\mathrm{L}_{\mathrm{lk}}$ to reset $i_{\mathrm{p}}$, and $i_{\mathrm{p}}$ is

$$
\begin{equation*}
i_{\mathrm{p}}(t)=\frac{\mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}}}-\frac{\mathrm{V}_{\mathrm{Cin} 2 \mathrm{MAX}}-\frac{\mathrm{V}_{\mathrm{in}}}{2}}{\mathrm{~L}_{\mathrm{lk}}}\left(t-t_{1}\right) \tag{2}
\end{equation*}
$$

When $i_{\mathrm{p}}$ is zero, this mode is finished, and the time is

$$
\begin{equation*}
\mathrm{T}_{31}=\frac{\mathrm{I}_{\mathrm{o}} \mathrm{~L}_{\mathrm{lk}}}{k_{\mathrm{T}}\left(\mathrm{~V}_{\mathrm{Cin} 2 \mathrm{MAX}}-\frac{\mathrm{V}_{\mathrm{in}}}{2}\right)} \tag{3}
\end{equation*}
$$

$i_{\mathrm{Cin} 1}$ is $-\left|i_{\mathrm{in}}\right|$ and $i_{\mathrm{Cin} 2}$ is $-\mathrm{I}_{\mathrm{o}} / k_{\mathrm{T}}-\left|i_{\mathrm{in}}\right| ; v_{\mathrm{Q} 3}=v_{\mathrm{Q} 1}=\mathrm{V}_{\mathrm{in}} / 2$.
Mode 4 [Figure $4 \mathrm{~d}, t_{3}-t_{4}$ ]: At $t_{3}, i_{\mathrm{p}}$ is zero, and $i_{\mathrm{p}}$ cannot change the conducting direction because of $\mathrm{D}_{2 \mathrm{R}}$. After $t_{3}, \mathrm{Q}_{2 \mathrm{P}}$ can achieve zero-current turned off. During this mode, $v_{\text {Cin2 }}$ in $\mathrm{V}_{\mathrm{Cin} 2 \max }$. $i_{\mathrm{Cin} 1}=$ $i_{\mathrm{Cin} 2}=-\left|i_{\mathrm{in}}\right| ; v_{\mathrm{Q} 3}=\mathrm{V}_{\mathrm{in}} / 2+\Delta v_{\mathrm{Cin} 2}$, and $v_{\mathrm{Q} 1}=\mathrm{V}_{\mathrm{in}} / 2-\Delta v_{\mathrm{Cin} 2}$.

Mode 5 [Figure $4 \mathrm{e}, t_{4}-t_{5}$ ]: At $t_{5}, \mathrm{Q}_{2 \mathrm{P}}$ is turned off with ZCS. $i_{\mathrm{Cin} 1}=i_{\mathrm{Cin} 2}=-\left|i_{\mathrm{in}}\right| ; v_{\mathrm{Q} 1}=v_{\mathrm{Q} 2}=\left(\mathrm{V}_{\mathrm{in}} / 2\right.$ $\left.-\left|\Delta v_{\mathrm{Cin} 2}\right|\right) / 2$, and $v_{\mathrm{Q} 3}=\mathrm{V}_{\mathrm{in}} / 2+\Delta v_{\mathrm{Cin} 2}$.

Mode 6 [Figure $4 \mathrm{f}, t_{5}-t_{6}$ ]: At $t_{5}, \mathrm{Q}_{3}$ is on, and $\mathrm{Q}_{3}$ can achieve ZCS due to the low increasing rate of $i_{\mathrm{p}} ; \mathrm{Q}_{2 \mathrm{R}}$ is also turn-on with ZCS owing to $\mathrm{Q}_{2 \mathrm{P}}$ is off. $\mathrm{Q}_{4 \mathrm{P}}$ has been turned on at $t_{2} ; i_{\mathrm{p}}$ increases linearly at the rate of

$$
\begin{equation*}
i_{\mathrm{p}}(t)=-\frac{\mathrm{V}_{\mathrm{CBLMAX}}}{\mathrm{~L}_{\mathrm{lk}}}\left(t-t_{5}\right) \tag{4}
\end{equation*}
$$

At the end of this interval, $i_{\mathrm{p}}$ is $-\mathrm{I}_{\mathrm{o}} / k_{\mathrm{T}}$, and the interval is

$$
\begin{equation*}
\mathrm{T}_{56}=\frac{\mathrm{L}_{\mathrm{lk}} \mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}} \mathrm{~V}_{\text {CBLMAX }}} \tag{5}
\end{equation*}
$$

At $t_{6}, i_{\mathrm{p}}$ is $-\mathrm{I}_{\mathrm{o}} / k_{\mathrm{T}}$. The proposed converter goes into the second half switching cycle and primarily powers the load. $v_{\mathrm{p}}=-\mathrm{V}_{\mathrm{in}} / 2+\Delta v_{\mathrm{Cin} 2} ; v_{\mathrm{re}}=-\left(\mathrm{V}_{\mathrm{in}}-2 \Delta v_{\mathrm{Cin} 2}\right) / 2 k_{\mathrm{T}} ; i_{\mathrm{p}}=-\mathrm{I}_{\mathrm{o}} / k_{\mathrm{T}} ; i_{\mathrm{Cin} 1}=-\left|i_{\mathrm{in}}\right|, i_{\mathrm{Cin} 2}=\mathrm{I}_{\mathrm{o}} / k_{\mathrm{T}}$ $-\left|i_{\text {in }}\right|$.

## 3. Technical Analysis

### 3.1. Soft Switching of $Q_{2 P}$ and $Q_{4 P}$

### 3.1.1. Turn-on Instants

$Q_{2 P}$ and $Q_{4 P}$ can achieve zero-voltage turn-on easily because large equivalent primary inductor can provide enough energy to discharge or charge the parasitic output capacitances of $Q_{1}, Q_{3}, Q_{2 P}$ and $Q_{4 \mathrm{P}}$. For example, to ensure ZVS of $\mathrm{Q}_{4 \mathrm{P}}$, the energy stored in the output inductor and the leakage inductor of the transformer should be

$$
\begin{equation*}
\frac{1}{2} \mathrm{~L}_{\mathrm{r}}\left(\frac{\mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}}}\right)^{2} \geq \frac{1}{2}\left(\mathrm{C}_{1}+\mathrm{C}_{4 \mathrm{P}}\right)\left(\frac{\mathrm{V}_{\text {in }}}{2}\right)^{2} \tag{6}
\end{equation*}
$$

where $L_{r}$ is the equivalent primary inductor at this instant, and the minimum load current to achieve ZVS is

$$
\begin{equation*}
\mathrm{I}_{\mathrm{o}, \min } \geq \frac{\mathrm{V}_{\mathrm{in}}}{2 k_{\mathrm{T}}} \sqrt{\frac{\left(\mathrm{C}_{1}+\mathrm{C}_{4 \mathrm{P}}\right)}{\mathrm{L}_{\mathrm{r}}}} \tag{7}
\end{equation*}
$$

### 3.1.2. Turn-off Instants

$\mathrm{Q}_{2 \mathrm{P}}$ and $\mathrm{Q}_{4 \mathrm{P}}$ are triggered off after $i_{\mathrm{p}}$ is reduced to zero. Hence, $\mathrm{Q}_{2 \mathrm{P}}$ and $\mathrm{Q}_{4 \mathrm{P}}$ can ensure ZCS in a wide load range. The reset time of $i_{p}$ is determined by (3), and $T_{\text {reset }}$ is the minimum time delay of the driving signals of $\mathrm{Q}_{2 \mathrm{P}}$ and $\mathrm{Q}_{4 \mathrm{P}}$. Therefore, to keep a safe zero-current turn-off, $\mathrm{T}_{\text {reset }}$ should be larger than the reset time of $i_{\mathrm{p}}$, and $\mathrm{C}_{\mathrm{in} 2}$ should be designed with following equation [17]

$$
\begin{equation*}
\mathrm{C}_{\mathrm{in} 2} \leq \frac{\left(\mathrm{T}_{\mathrm{s}}-2 \mathrm{~T}_{\text {reset }}\right) \mathrm{T}_{\text {reset }}}{4 \mathrm{~L}_{\mathrm{lk}}} \tag{8}
\end{equation*}
$$

Reduced $\mathrm{C}_{\mathrm{in} 2}$ could cause a large value of reset voltage of $i_{p}$, which can ensure safe ZCS operation. However, it may cause high OFF voltage on $D_{o 1}$ to $D_{04}, Q_{2 R}, Q_{4 R}$, and $Q_{3}$. Hence, there should be a trade-off between the ZCS condition and the OFF voltages on $D_{01}$ to $D_{04}, Q_{2 R}, Q_{4 R}$, and $Q_{3}$.

### 3.2. Soft Switching of $Q_{1}$ and $Q_{3}$

### 3.2.1. Turn-on Instants

When $Q_{1}$ and $Q_{3}$ are on, $i_{p}$ is still zero, and $i_{p}$ cannot vary sharply due to the fact that $L_{l k}$ limits the increasing rate. Consequently, $Q_{1}$ and $Q_{3}$ can obtain quasi $Z C S$ turn-on. To reduce the switching-on loss further, low driving resistors are preferred for $Q_{1}$ and $Q_{3}$.

### 3.2.2. Turn-off Instants

When $\mathrm{Q}_{1}$ and $\mathrm{Q}_{3}$ are off, $v_{\mathrm{Q} 1}$ and $v_{\mathrm{Q} 3}$ varies with low slope because $\mathrm{C}_{1}$ and $\mathrm{C}_{3}$. Consequently, $\mathrm{Q}_{1}$ and $Q_{3}$ can obtain quasi $Z V S$ operation. To minimize the power loss further, extra output capacitors of $Q_{1}$ and $Q_{3}$ could be added.

### 3.3. Soft Switching of $Q_{2 R}$ and $Q_{4 R}$

The identical circuit of $Q_{2 R}$ during the turn-off interval is shown in Figure 4c. As illustrated in Figure $3, \mathrm{D}_{2 \mathrm{R}}$ is already conducted before $t_{2}$, and $\mathrm{Q}_{2 R}$ is gated off at $t_{2}$. Hence, $\mathrm{Q}_{2 R}$ can be switched off with zero-voltage properly. The identical circuit of $Q_{2 R}$ during the turn-on period is shown in Figure 4 e . As depicted in Figure 3, $Q_{2 P}$ is already off before $t_{5}$ and $Q_{2 R}$ is gated on at $t_{5}$. Therefore, the turn-on power loss of $Q_{2 R}$ is zero. The soft switching condition of $Q_{4 R}$ is similar to that of $Q_{2 R}$, and detailed analysis is not presented in this paper.

### 3.4. Voltage Balance of the Primary Capacitors

### 3.4.1. Input Capacitors

With identical capacitance and symmetrical circuit structure, the initial voltage of $\mathrm{C}_{\mathrm{in} 1}$ and $\mathrm{C}_{\mathrm{in} 2}$ is $\mathrm{V}_{\mathrm{in}} / 2 . v_{\mathrm{Cin} 1}$ and $v_{\mathrm{Cin} 2}$ can be stable, owing to the fact that charging and discharging currents of these capacitors are balanced over one switching period. Corresponding waveforms are given in Figure 3, and identical circuits can be referenced in Figure 4. As the positive and negative pulses of the currents flowing through $C_{i n 1}$ and $C_{i n 2}$ are balanced over one switching period, the mid-point voltage of $C_{i n 1}$ and $\mathrm{C}_{\mathrm{in} 2}$ can be stable over one switching period.

### 3.4.2. Flying Capacitors

The initial voltage of $\mathrm{C}_{\mathrm{s}}$ is also $\mathrm{V}_{\mathrm{in}} / 2$ due to symmetrical circuit structure, and $v_{\mathrm{C}_{s}}$ can be stable owing to the fact that charging and discharging currents of $C_{S}$ are balanced over one switching period. Corresponding waveforms are given in Figure 3, and identical circuits can be referenced in Figure 4. The positive and negative pulses of the current flowing through $C_{s}$ are balanced over one switching period. Hence, $\mathrm{C}_{\mathrm{s}}$ can achieve stable voltage over one switching cycle.

### 3.5. Current Stress of the Primary Component

3.5.1. $\mathrm{S}_{2}$ and $\mathrm{S}_{4}$

The average value of $i_{S 2}$ and $i_{S 4}$ is

$$
\begin{equation*}
\mathrm{I}_{\mathrm{AVG}_{-} S_{2,4}}=\frac{\mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}}}\left(\frac{D}{2}-\frac{1}{2} \frac{\mathrm{~T}_{31}}{\mathrm{~T}_{\mathrm{s}}}\right) \tag{9}
\end{equation*}
$$

The RMS value of $i_{\mathrm{S} 2}$ and $i_{\mathrm{S} 4}$ is

$$
\begin{equation*}
\mathrm{I}_{R M S_{-} S_{2,4}} \approx \sqrt{\frac{1}{\mathrm{~T}_{s}} \int_{0}^{D \frac{\mathrm{~T}_{s}}{2}}\left(\frac{\mathrm{I}_{\mathrm{O}}}{k_{\mathrm{T}}}\right)^{2} d t+\frac{1}{\mathrm{~T}_{s}} \int_{0}^{\mathrm{T}_{31}}\left(\frac{\mathrm{I}_{\mathrm{O}}}{\mathrm{~T}_{31} k_{\mathrm{T}}}\right)^{2} t^{2} d t}=\frac{\mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}}} \sqrt{\frac{D}{2}+\frac{\mathrm{T}_{31}}{3 \mathrm{~T}_{s}}} \tag{10}
\end{equation*}
$$

3.5.2. $\mathrm{Q}_{1}$ and $\mathrm{Q}_{3}$

The average value of $i_{\mathrm{Q} 1}$ and $i_{\mathrm{Q} 3}$ is

$$
\begin{equation*}
\mathrm{I}_{\mathrm{AVG}} \mathrm{Q}_{1,3} \approx \frac{\mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}}} \frac{D}{2} \tag{11}
\end{equation*}
$$

The RMS value of $i_{\mathrm{Q} 1}$ and $i_{\mathrm{Q} 3}$ is

$$
\begin{equation*}
\mathrm{I}_{R M S_{-} Q_{1,3}} \approx \sqrt{\frac{1}{\mathrm{~T}_{s}} \int_{0}^{D \frac{\mathrm{~T}_{s}}{2}}\left(\frac{\mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}}}\right)^{2} d t}=\frac{\mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}}} \sqrt{\frac{D}{2}} \tag{12}
\end{equation*}
$$

3.5.3. $\mathrm{C}_{\mathrm{in} 1}$

The average current of $i_{\mathrm{Cin} 1}$ is zero. The time integral of the positive pulse of $i_{\mathrm{Cin} 1}$ is

$$
\begin{equation*}
\mathrm{I}_{p o s_{-} C_{\mathrm{in} 1}}=\int_{0}^{\frac{D \mathrm{~T}_{\mathrm{s}}}{2}}\left(\frac{\mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}}}-\left|i_{\mathrm{in}}\right|\right) d t=\left(\frac{\mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}}}-\left|i_{\mathrm{in}}\right|\right) \frac{D \mathrm{~T}_{s}}{2} \tag{13}
\end{equation*}
$$

The time integral of the negative pulse of $i_{\mathrm{Cin} 1}$ is

$$
\begin{equation*}
\mathrm{I}_{n e g_{-} C_{\mathrm{in} 1}}=\int_{\frac{D T_{s}}{2}}^{\mathrm{T}_{s}}\left|i_{\mathrm{in}}\right| d t=\left|i_{\mathrm{in}}\right|(2-D) \frac{\mathrm{T}_{s}}{2} \tag{14}
\end{equation*}
$$

To keep charge balance over one switching cycle, the average current of $i_{\text {Cin } 1}$ is zero. Hence, $\left|i_{\text {in }}\right|$ can be computed as

$$
\begin{equation*}
\left|i_{\text {in }}\right|=\frac{\mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}}} \frac{D}{2} \tag{15}
\end{equation*}
$$

The RMS value of $i_{\text {Cin1 }}$ is

$$
\begin{equation*}
\mathrm{I}_{R M S_{-} C_{\mathrm{in1} 1}} \approx \sqrt{\frac{1}{\mathrm{~T}_{s}} \int_{0}^{\frac{D \mathrm{~T}_{s}}{2}}\left(\frac{\mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}}}\right)^{2}\left(1-\frac{D}{2}\right)^{2} d t+\frac{1}{\mathrm{~T}_{s}} \int_{\frac{D \mathrm{~T}_{s}}{2}}^{\mathrm{T}_{s}}\left(\frac{\mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}}}\right)^{2}\left(\frac{D}{2}\right)^{2} d t}=\frac{\mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}}} \sqrt{\frac{D}{2}-\frac{D^{2}}{4}} \tag{16}
\end{equation*}
$$

3.5.4. $\mathrm{C}_{\mathrm{in} 2}$

The average current of $i_{\mathrm{Cin} 2}$ is zero. The RMS value of $i_{\mathrm{Cin} 2}$ can be computed according to Figure 3

$$
\begin{equation*}
\mathrm{I}_{R M S_{-} C_{\mathrm{in} 2}} \approx \frac{\mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}}} \sqrt{\frac{D}{2}-\frac{D^{2}}{4}+\frac{2 \mathrm{~T}_{31}}{3 \mathrm{~T}_{s}}} \tag{17}
\end{equation*}
$$

### 3.5.5. $\mathrm{C}_{\mathrm{s}}$

The average current of $i_{C s}$ is zero. The RMS value of $i_{C S}$ can be computed according to Figure 3

$$
\begin{equation*}
\mathrm{I}_{R M S_{-} C_{s}} \approx \frac{\mathrm{I}_{\mathrm{o}}}{k_{\mathrm{T}}} \sqrt{\frac{2 \mathrm{~T}_{31}}{3 \mathrm{~T}_{s}}} \tag{18}
\end{equation*}
$$

### 3.6. Comparison with the Conventional Capacitor Clamped TL dc-dc Converter

### 3.6.1. Main Switches

As illustrated in Figure 5a, the current difference between $Q_{1}$ and $Q_{2}$ of the converter in Figure 1a is inversely proportional to the duty ratio D , and when $\mathrm{D}=0.3$, the current of $\mathrm{Q}_{2}$ would be twice that of $Q_{1}$. Hence, the current distribution of the main switches of the converter in Figure 1a is imbalanced. Consequently, the current rating of $Q_{2}$ and $Q_{4}$ is much higher than that of $Q_{1}$ and $Q_{2}$. However, in the proposed converter, the primary switches have balanced and reduced current. As shown in Figure 5c, the current difference between $i_{Q 1}$ and $i_{Q 2 P}$ is around 0.01 per unit, which is mainly caused by the negative current pulse of $i_{Q 2 P}$. However, the RMS value of the negative pulse can be neglected due to the fact that the time of this pulse is very short. As the primary free-wheeling current is reset to zero, the current stress on the main switches in the proposed converter is also reduced. The maximum value of the off-voltage stress on $\mathrm{Q}_{3}$ is $\mathrm{V}_{\mathrm{in}} / 2+\Delta v_{\mathrm{Cin} 2}$, which is slightly higher than that of the converter in Figure 1a. However, as $\Delta v_{\text {Cin2 }}$ is usually small, which is not exceed 30 V . Hence, the increasing voltage stress on $Q_{3}$ can still be accepted.


Figure 5. Current of the primary switches: (a) $i_{\mathrm{Q} 1}$ and $i_{\mathrm{Q} 2}$ in Figure 1a; (b) $i_{\mathrm{Cin} 1}$ and $i_{\mathrm{Cin} 2}$ in Figure 1a; (c) $i_{\mathrm{Q} 1}$ and $i_{\mathrm{Q} 2 \mathrm{P}}$ in the proposed converter; (d) $i_{\mathrm{Cin} 1}$ and $i_{\mathrm{Cin} 2}$ in the proposed converter; (e) $i_{\mathrm{Cs}}$.

### 3.6.2. Primary Capacitors

As illustrated in Figure 5b, the current difference between $C_{i n 1}$ and $C_{i n 2}$ of the converter in Figure 1a is varied with the duty ratio $D$, and when $D=0.3$, the current of $C_{i n 2}$ would be twice that of $\mathrm{C}_{\mathrm{in} 1}$. Hence, the current distribution of the input capacitors of the converter in Figure 1a is imbalanced. Furthermore, the current rating of $C_{i n 2}$ is much higher than that of $C_{i n 1}$. However, in the proposed converter, the input capacitors have balanced and reduced current. As shown in Figure 5d, the current difference between $i_{\text {Cin1 }}$ and $i_{\text {Cin2 }}$ is around 0.01 per unit, which is mainly caused by the current pulses
during switching instants. However, the RMS value of these pulses can also be neglected due to fact that the times are very short. As $i_{p}$ during the free-wheeling stages is zero, the RMS value of $i_{C i n 1}$ and $i_{\mathrm{Cin} 2}$ in the proposed converter is also reduced. The current comparison of $\mathrm{C}_{\mathrm{s}}$ is provided in Figure 5e, and the RMS value of $i_{C s}$ in the proposed converter is obviously lower than $C_{s}$ in Figure 1. Hence, the required value of $C_{s}$ in the proposed converter is much lower than $C_{s}$ in Figure 1, which results in reduced volume of this capacitor.

### 3.6.3. Soft Switching Load Range

As proven in Table 1, the ZVS load range of $Q_{1}$ and $Q_{3}$ in Figure 1a is narrow owing to the fact that only low energy kept in $L_{l k}$ can be used to discharge or charge $C_{1}, C_{3}, C_{2 p}$, and $C_{4 p}$, which would lead to poor efficiency under light load condition. Hence, $C_{1}, C_{3}, C_{2 p}$, and $C_{4 p}$ in Figure 1a should be small to ensure $Z V S$ operation of $Q_{1}$ and $Q_{3}$. However, a large value of $C_{1}, C_{3}, C_{2 p}$, and $C_{4 p}$ is better for minimizing turn-off power loss of $Q_{1}$ and $Q_{3}$. Hence, the switching-off power loss of $Q_{1}$ to $Q_{3}$ in Figure 1a cannot be optimized.

Table 1. Soft switching of the main switches.

| Item | $\mathbf{Q}_{1}$ | $\mathbf{Q}_{\mathbf{2}}$ | $\mathbf{Q}_{\mathbf{3}}$ | $\mathbf{Q}_{4}$ |
| :---: | :---: | :---: | :---: | :---: |
| Proposed | ZCZVS, easy | ZVZCS, easy | ZCZVS, easy | ZVZCS, easy |
| Figure 1a | ZVS, hard | ZVS, easy | ZVS, hard | ZVS, easy |

As depicted in Figures 2-4, $Q_{2 P}$ and $Q_{4 P}$ in the proposed converter are turned-on with zero-voltage and off with zero-current; while, $Q_{1}$ and $Q_{3}$ are on with quasi-ZCS mode and off with quasi-ZVS mode. Hence, the soft-switching conditions of the primary switches in the proposed converter are not interconnected, and the switching-off power loss of $Q_{1}$ and $Q_{3}$ can be reduced without increasing the switching-on power loss.

### 3.7. Brief Comparison with Other Typical HB TLDCs

To evaluate the proposed converter further, some brief comparison is carried out in this part. The components comparison is shown in Table 2. Compared with classical HB TLDCs, the power devices with high voltage rating of the proposed converter are less than other converters. As allowed voltage ripple on the input capacitors is large, $C_{i n 1}$ and $C_{i n 2}$ in the proposed converter are small, which means reduced system volume and BOM cost. In Reference [7], an extra capacitor is required to generate the reset voltage of $i_{\mathrm{p}}$, and the number of capacitors of the converter in Reference [7] is highest.

Table 2. Components comparison.

| Converter | Power Devices <br> High Voltage | Power Devices <br> Low Voltage | Capacitors <br> Large Value | Capacitors <br> Small Value |
| :---: | :---: | :---: | :---: | :---: |
| Proposed | 4 | 2 | 0 | 3 |
| $[1]$ | 6 | 0 | 2 | 0 |
| $[6]$ | 6 | 1 | 2 | 1 |
| $[7]$ | 6 | 2 | 2 | 2 |

The performance comparison is depicted in Table 3. As two of the primary switches cannot ensure safe ZVS operation under light output current, the converter in Reference [1] has the worst soft-switching characteristics. As the switching-on power loss and switching-off power loss can be optimized at the same time, the proposed converter has the best soft switching characteristics among the four converters. The extra power devices in Reference [6] are operated in hard switching mode, which will reduce the efficiency. As $i_{p}$ is reduced to zero in the free-wheeling stages, the proposed converter and the converters in References [6,7] have small duty ratio loss. In addition, the current
stress of the primary components is large and uneven in the converter [1], owing to similar reasons as the converter in Figure 1a.

Table 3. Performance comparison.

| Converter | Soft Switching <br> Primary Switches | Soft Switching <br> Extra Power <br> Devices | Current Stress <br> Primary <br> Components | Duty Ratio Loss |
| :---: | :---: | :---: | :---: | :---: |
| Proposed | Good | Good | Small (even) | Small |
| $[1]$ | Worse | NA | Large (uneven) | Large |
| $[6]$ | Medium | Worse | Small (even) | Small |
| $[7]$ | Medium | Good | Small (even) | Small |

## 4. Experimental Results

The operation principle and characteristics of the proposed converter are proved by a $1-\mathrm{kW}$ experimental equipment, and some specifications of the experimental equipment are listed in Table 4. Figures 6-12 show the experimental results.

Figure 6 gives the primary voltage of the transformer, and $v_{p}$ changes with the same rate with $v_{\mathrm{Cin} 1}$ and $v_{\mathrm{Cin} 2}$ during the power-transferring stages. At the beginning of the free-wheeling stages, $v_{\mathrm{p}}$ provides enough and constant reset voltage of $i_{\mathrm{p}}$. As provided in Figure 7, $i_{\mathrm{p}}$ remains as zero during the free-wheeling stages, which ensures zero-current turn-off of $Q_{2 p}$ and $Q_{4 \mathrm{P}}$. In addition, the primary circulating current is nearly zero, which reduces the conduction loss. As proved in Figure 8, $\mathrm{C}_{\mathrm{in} 2}$ is charged or discharged by $i_{\mathrm{p}}$ during power-transfer stages, hence, $v_{\mathrm{Cin} 2}$ varies within the boundary of $\Delta v_{\text {Cin2 }}$ linearly with time. During free-wheeling stages, $v_{\mathrm{Cin} 2}$ is unchanged, owing to $i_{\mathrm{p}}$ remaining as zero. As shown in Figure $9, v_{\mathrm{Do1}}$ is also changed with the slope of $v_{\mathrm{p}} / k_{\mathrm{T}}$, and the voltage stress of $v_{\text {Do1 }}$ is increased.

Table 4. Specifications of the experimental equipment.

| Item | Parameter |
| :---: | :---: |
| $\mathrm{V}_{\text {in }}$ | $400 \mathrm{~V}-600 \mathrm{~V}$ |
| Rated $\mathrm{V}_{\mathrm{o}}$ | 200 V |
| Rated $\mathrm{I}_{\mathrm{o}}$ | 5 A |
| $f_{\mathrm{s}}$ | 100 kHz |
| $\mathrm{Q}_{1}, \mathrm{Q}_{3}, \mathrm{Q}_{2 \mathrm{p}}$ and $\mathrm{Q}_{4 \mathrm{p}}$ | $20 \mathrm{~A} / 600 \mathrm{~V}$ |
| $\mathrm{Q}_{2 \mathrm{R}}, \mathrm{Q}_{4 \mathrm{R}}$ | $20 \mathrm{~A} / 25 \mathrm{~V}$ |
| $\mathrm{D}_{\mathrm{o} 1}$ to $\mathrm{D}_{\mathrm{o} 4}$ | $20 \mathrm{~A} / 600 \mathrm{~V}$ |
| $k_{\mathrm{T}}$ | $1: 1.15$ |
| $\mathrm{C}_{\text {in } 1}, \mathrm{C}_{\text {in2 }}$ | $200 \mu \mathrm{~F}$ |
| $\mathrm{C}_{\mathrm{s}}$ | $1.5 \mu \mathrm{~F}$ |
| $\mathrm{~L}_{\mathrm{o}}$ | $20 \mu \mathrm{H} / 5 \mathrm{~A}$ |
| $\mathrm{C}_{\mathrm{o}}$ | $200 \mu \mathrm{~F}$ |



Figure 6. Waveform of $v_{p}$.


Figure 7. Waveform of $i_{p}$.


Figure 8. Waveform of $\Delta v_{\text {Cin2 }}$.


Figure 9. Waveform of $v_{D o 1}$.
The soft-switching characteristic of $Q_{2 P}$ is proved in Figure 10, and it is clear that $Q_{2 P}$ can achieve ZVZCS. Before the switch-on instant, $i_{\mathrm{Q} 2 \mathrm{P}}$ conducts in the reverse direction owing to the fact that $\mathrm{D}_{2 \mathrm{P}}$ is already on, hence, $Q_{2 p}$ is switched on with zero-voltage. Before the switching-off signal of $Q_{2 P}$ is coming, $i_{2 P}$ reduces to zero. Therefore, $\mathrm{Q}_{2 P}$ can achieve ZCS turn-off properly.
$v_{\mathrm{Q} 3}, i_{\mathrm{Q} 3}$ and $v_{\mathrm{GSQ} 3}$ are depicted in Figure 11, which proves $\mathrm{Q}_{3}$ is operated in ZCZVS. At the time of switching-on, $i_{\mathrm{Q} 3}$ cannot change sharply owing to the fact that $\mathrm{L}_{\mathrm{lk}}$ limits the changing rate of $i_{\mathrm{p}}$, thus, $\mathrm{Q}_{3}$ is switched with quasi-ZCS mode. At the time of switching-off, $v_{\mathrm{Q} 3}$ cannot change sharply owing to the fact that $C_{3}$ limits the changing rate; therefore, the switching-off power loss of $Q_{3}$ is also small. It should be pointed out that a large value of $C_{3}$ would not take great effect on ZVS turn-on of $Q_{3}$, which means both the turn-on and turn-off switching loss of $Q_{2 P}$ and $Q_{3}$ can be optimum. As proved in Figures 10 and 11, the voltage stress of $Q_{3}$ and $Q_{2 P}$ is confined close to $V_{i n} / 2$.

The efficiency comparison results are illustrated in Figure 12. In Figure 12a, the proposed converter has high efficiency under low output current condition owing to reduced switching power loss of the primary switches. Under high output current conditions, the efficiency of the proposed converter is also better due to the fact that switching-off power loss can be further reduced. In Figure 12b, when $I_{o}$ is constant, the efficiency of both converters is changed inversely proportional to $\mathrm{V}_{\mathrm{in}}$. In addition, the
efficiency of the proposed converter is decreased slowly owing to the fact that $V_{\text {in }}$ has a small effect on the soft switching condition of the primary switches.


Figure 10. Waveform of $v_{\mathrm{Q} 2 \mathrm{P}}$ and $i_{\mathrm{Q} 2 \mathrm{P}}$.


Figure 11. Waveform of $v_{\mathrm{Q} 3}, i_{\mathrm{Q} 3}$ and $v_{\mathrm{GSQ}}$.


Figure 12. Efficiency curves: (a) $V_{i n}=400 \mathrm{~V}, \mathrm{I}_{\mathrm{O}}$ is varied; (b) $\mathrm{I}_{\mathrm{O}}=4 \mathrm{~A}, \mathrm{~V}_{\text {in }}$ is varied.

## 5. Conclusions

A new ZVZCS capacitor-clamped HB TLDC with two unsymmetrical bidirectional switches is proposed and analyzed, and the experimental results can well support the theoretical analysis. After discussion, some obvious advantages of the proposed converter can be concluded, e.g., balanced and reduced current stress of the primary components, small and reduced volume of the clamping capacitor, wide load range soft-switching operation for both turn-on and turn-off instants and a simple switching scheme. The only drawback of the proposed converter is the off voltage of $Q_{3}$ is slightly higher than $V_{i n} / 2$.

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