



Article Analysis, Design, and Implementation of Improved LLC Resonant Transformer for Efficiency Enhancement

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Abstract: In battery charging applications, the charger changes its output voltage in a wide range during the charging process. This makes the design of LLC converters difficult to be optimized between the efficiency and the gain range. In this paper, an improved resonant transformer is presented for LLC resonant converter charger to improve the gain adjustment and charger efficiency. The resonant inductance and magnetizing inductance are integrated in the designed LLC transformer, and the magnetizing inductance can be adjusted dynamically with the change of output voltage and load, which is realized by a switch-controlled inductor (SCI) parallel to the secondary winding of transformer. The proposed transformer has 22.4% reduction in losses under full load conditions compared to conventional solutions. Moreover, the conduction loss and switching loss of LLC resonant tank are reduced by dynamically adjusting the magnetizing inductance, which improves the comprehensive efficiency of the whole charging process. The proposed transformer design is verified on a 720 W prototype.

Keywords: LLC resonant converter; resonant transformer; fringing effect; adjustable magnetizing inductance; efficiency

1. Introduction

LLC resonant converter has been widely used in electric vehicle battery chargers, flat panel television (TV), and photovoltaic (PV) system due to its high-power density and high conversion efficiency [1–4]. For now, it has become one of the most concerned DC/DC converters.

In constant output voltage applications, LLC resonant converter can achieve high efficiency. However, there are many challenges for LLC resonant converter in the charger applications which requires a wide output voltage adjustment range [5]. It requires a small magnetizing inductance to obtain a wide output voltage adjustment range, but it can lead to increased conduction loss and switching loss as well as efficiency reduction [6]. The magnetizing inductance is usually integrated in LLC resonant transformer. The usual structure of magnetic integrated LLC transformer is as shown in Figure 1, the leakage layer is set between the primary winding and secondary winding. The required resonant inductance is obtained by using stray flux and the magnetizing inductance is achieved by inserting an appropriate air-gap in the magnetic circuit [7,8]. The transformer with that structure has high integration and low cost and has been widely used in converters with power level from dozens to hundreds of watts.



Figure 1. Structure of conventional LLC transformer and leakage flux effect on the windings.

As the core device of LLC resonant converter, the transformer plays a critical role in converter's efficiency, volume, power density, and reliability. However, the whole loss of the LLC resonant transformer has a much higher percentage than that of phase-shift full-bridge transformer in the same power [9]. One of the main reasons is that the air gap in the magnetic core of LLC resonant transformer causes fringing effect, leading to an increase in the equivalent resistance of windings near the air gap, and the transformer inner temperature rise distributed imbalance. The other reason is that the small magnetizing inductance leads to increased conduction loss and switching loss of the LLC resonant converter, so the light-load efficiency is lower.

In order to improve the efficiency of LLC transformer, different improvement designs are proposed. In [10], a novel shape magnetic core is used to achieve the integration of two LLC transformers. In [11], a magneto plated wire is used to effectively decrease the winding loss caused by the proximity effect when working in high frequency. In [12], the integration of resonant inductance required is achieved by inserting a layer of flexible magnetic material between the primary and secondary windings. The designs proposed by [10-12] have high integration, but without regard for the fringing effect, so they are more suitable for low power applications. In [13], the copper loss of the Litz wire caused by the air gap is analyzed, and the influence of the fringing effect is weakened by using multiple small air gaps in series, but this increases the cost and difficulty of transformer production. In [7], a design method of LLC resonant transformer is presented, and the current density in the conductor near the air gap is simulated. In [14], the optimal design method of the transformer in conventional LLC resonant converter is extended to the design and application of flat panel transformer, and a complete design scheme and a detailed application method are given. In [7,14], the fringing effect is mentioned, but the influence of the effect is not analyzed and the solution is not given. In [15], the relationship between the temperature rise and the switch frequency as well as the winding number of the LLC resonant transformer are discussed, and a combination of two smaller transformers is used instead of one larger transformer to reduce the temperature rise. Matrix transformer is used to achieve a higher output power in [16]. However, with the increase of power, the matrix transformer which consists of too many transformers will lead the system more complex. In [17,18], to reduce the influence of the fringing effect, the distance between the winding and the air gap is increased by making changes of the winding structure, which leads to the increase in difficulty of processing windings.

To improve the light-load efficiency, the transformers in [19,20] are designed with variable magnetizing inductance. In [19], by using utilizing a step-gap in the core column, a larger magnetizing inductance is obtained at light load, and it decreases at heavy load, but the variety of magnetizing inductance is non-linear and uncontrollable. In [20], a bidirectional power switch is used to achieve the parallel operation of two transformers. When under heavy load, the switch turn-on, two transformers primary side work in parallel, the magnetizing inductance of resonant tank is small, and can satisfy the gain demand required in the initial stage of charging. When under light load, the switch turns off, only one transformer works, the magnetizing inductance of resonant tank is large, and the conduction loss and switching loss of primary side decrease. However, the resonant inductance cannot be integrated

into the transformer, the magnetizing inductance can only be changed between two fixed values, and when under light load, only one transformer works and the other is vacant.

Aiming to address the design problems of the conventional LLC transformer caused by the large influence of the fringing effect and the unchangeable magnetizing inductance, this paper presents a design for the integrated LLC resonant transformer. The magnetizing inductance does not need to be obtained by inserting air gap, so the fringing effect of the transformer is small. Moreover, the magnetizing inductance can be dynamically adjusted by a SCI parallel to the secondary winding of the transformer. This can not only improve the efficiency and the temperature rise of the transformer but also optimize the comprehensive efficiency of the LLC resonant converter during the whole charging process.

This paper includes following aspects. Section 2 analyzes the conventional integrated LLC resonant transformer. Section 3 presents the proposed design scheme, analysis of magnetic flux in the transformer core and the application circuit. Section 4 gives the calculation formula and design procedure of the transformer. Section 5 shows the experimental results of a 720 W LLC resonant converter. The conclusion is given in the last section.

2. Analysis of Conventional LLC Transformer

In high-power applications, the fringing effect near the air gap leads to a significant increase in the current density of the windings near the air gap, resulting in an apparent increase in the partial temperature rise and copper loss of the transformer [7]. To analyze the influence of fringing effect, finite element analysis (FEA) simulation is carried out by using Maxwell software. Figure 2 illustrates the simulation of fringing effect at 100 kHz. It can be seen the current density of the copper conductor near the air gap is about 70% higher than that away from the air gap, so the copper loss of this part is significantly increased. The increased copper loss results in the conspicuous regional temperature rise near the air gap. The simulation also shows that the fringing effect has a significant impact near the air gap, and the affected range increases with the increase of transformer power from the center of the air gap.



Figure 2. High frequency fringing effect near the air gap.

After the winding turns and air gap size of the transformer are determined, the transformer magnetizing inductance is a fixed value. Choosing small magnetizing inductance to obtain sufficient output voltage gain will result in increased conduction loss and switching loss of the LLC resonant converter.

The simulation results show that the induced magnetic flux increases in pace with the increase of the transformer power and input voltage, the area influenced by the air gap expand accordingly. In order to reduce the fringing effect, it is needed to increase distance d of leakage layer, as shown in Figure 1. However, the increasing d causes the available area of the core window decrease, under the

same diameter and turns, the layer *p* of transformer winding is increase. According to the Dowell's formula as below, this effect can lead to a significant increase in proximity loss.

$$\frac{R_{ac}}{R_{dc}} = \Delta \left[\frac{\sinh 2\Delta + \sin 2\Delta}{\cosh 2\Delta - \cos 2\Delta} + \frac{2(p^2 - 1)}{3} \frac{\sinh \Delta - \sin \Delta}{\cosh \Delta + \cos \Delta} \right]$$
(1)

where, *p* is the number of transformer windings layers, Δ is the ratio of the winding layer thickness *d* of the skin depth δ_0 .

To integrate the resonant inductance into the transformer, the primary winding and the secondary winding cannot use 'sandwich' method, which is used in full-bridge phase-shifting transformer to decrease the proximity loss. Therefore, at high frequency condition, use Litz wire to decrease the impact of the proximity effect and the skin effect.

In summary, the fringing effect, proximity effect, and the increase of the conduction loss and switching loss caused by small magnetizing inductance are main factors affect the transformer efficiency.

3. Analysis of Improved LLC Resonant Transformer

In order to promote the efficiency, an improved LLC transformer design is presented.

3.1. Main Structure

The structure of proposed LLC resonant transformer is shown in Figure 3, which has the following characteristics. (1) The skeleton adopts double groove structure, thus primary winding and secondary winding are wound respectively in two grooves. Therefore, the resonant inductance is still integrated in the transformer. (2) The air gap is not inserted in the magnetic circuit, so there is nearly no leakage flux, the intensive windings in the transformer is almost not affected by the fringing effect. (3) The thickness *d* of the middle leakage layer can be small, which does not occupy the space of the windings and improves the utilization rate of the core window, reducing the proximity effect.



Figure 3. Main structure of proposed transformer.

The fringing effect simulations comparison is shown in Figure 4. It can be seen that the conductor current density near the air gap of the proposed transformer is greatly reduced, and the conduction loss is effectively decreased, so the internal temperature rise can be improved.



Figure 4. Fringing effect comparison: (a) Conventional scheme; (b) Proposed scheme.

However, the proposed transformer almost has no air gap, and the equivalent magnetic permeability of the magnetic core is large. Hence, its magnetizing inductance is much larger than that of conventional LLC transformer with air gap, which cannot satisfy the LLC resonant tank demand. For this reason, a SCI is parallel to the secondary winding to achieve the magnetizing inductance adjustment, as shown in Figure 5, Co is the output filter capacitor, and R_L is the load.



Figure 5. Switch controlled inductor parallel to secondary winding of transformer.

3.2. Switch Controlled Inductor (SCI)

The SCI in Figure 5 adopts series type [21], and its circuit structure and working waveforms are shown in Figure 6. The SCI consists of linear inductance *La* and two control switches *Ta* and *Tb*. The voltage e_{AB} added to the both sides of SCI is the transformer secondary winding voltage close to square wave. V_{Ta} and V_{Tb} are the drive signal of switch devices *Ta* and *Tb* respectively, and their frequencies are equal to the operating frequency of the LLC resonant converter. The current flowing through the SCI is i_{AB} . δ is the phase angle of the switch drive signal. The working principle of SCI in a switch period is analyzed as follows.

At t_0 , when the secondary winding voltage e_{AB} is positive polarity and Ta is turn-off, the inductor current flow through SCI is zero. At t_1 , the drive signal makes Ta turning on and Tb turning off, and i_{AB} increases linearly from zero. Therefore, Ta turns on at zero current and Tb turn off at zero current. At t_2 , when the polar of e_{AB} reverses, the inductor current i_{AB} reaches a maximum and then begins to decrease linearly. At t_3 , the inductor current i_{AB} decreases to zero. Because of the reverse blocking of Tb, i_{AB} remains zero until t_4 . Therefore, Ta realizes zero current turn-off and Tb realizes zero current turn-on. The opposite direction is the same. Since the conduction resistance of Ta and Tb is very small, the switching loss and conduction loss of switch devices Ta and Tb are relatively small.



Figure 6. Topology and waveforms of SCI.

The equivalent inductance of SCI can be obtained from [22] as Equation (2)

$$L_{SCI} = \frac{L_a}{2 - (2\delta - \sin 2\delta)/\pi} \tag{2}$$

According to Equation (2), when the phase angle of switch drive signal ranges between $\pi/2$ and π , the equivalent switch-controlled inductance L_{SCI} ranges between La and ∞ . The relationship curve between inductance ratio L_{SCI}/L_a and the phase angle of switch drive signal is shown in Figure 7. It can be found the circuit shown in Figure 5 can be equivalent to an inductance which can be adjusted from La to ∞ .



Figure 7. Equivalent inductance of SCI.

3.3. Equivalent Circuit of Resonant Tank and Magnetic Field Analysis

The equivalent circuit of LLC resonant tank for secondary winding parallel SCI is shown in Figure 8. where C_r is the resonant capacitance, L_r is the resonant inductance and L_{m-ini} is the large magnetizing inductance integrated in transformer, as shown in Equation (3).

$$L_{m-ini} = \frac{\mu_{eff} \cdot N_p^2 \cdot A_c}{l_c}$$
(3)

where μ_{eff} is the equivalent magnetic permeability of the magnetic circuit approximately equal to the relative permeability of the core material μ_r . N_p is the turns of primary winding, A_c is the cross-section area of the magnetic core, l_c is the magnetic circuit length. Since $\mu_{eff} \approx \mu_r$, the value of L_{m-ini} is large as result of the large relative permeability of the core material.



Figure 8. Equivalent circuit of the proposed LLC resonant tank.

Setting *a* is the ratio of the transformer, and $a^2 \cdot L_{SCI}$ is the primary equivalent inductance reflected by the SCI. *Re* is the equivalent load impedance, and R_{load} is the load resistance. The magnetizing inductance in the resonant tank can be expressed as Equation (4).

$$L_{m-eq} = L_{m-ini} \bigg| \bigg| a^2 \cdot L_{SCI} \tag{4}$$

$$R_e = \frac{8}{\pi^2} \cdot a^2 \cdot R_{load} \tag{5}$$

Due to the adjusted value of L_{SCI} driven by δ , so the inductance $a^2 \cdot L_{SCI}$ in Equation (4) can be represented as an adjustable inductance. Therefore, the equivalent magnetizing inductance L_{m-eq} can also be adjusted by changing δ .

As shown in Figure 8, when the resonant tank is transferring energy to secondary side, the resonant frequency is f_r .

$$f_r = \frac{1}{2\pi\sqrt{L_r C_r}}\tag{6}$$

Otherwise, the magnetizing inductance L_{m-eq} participates in resonant, and the resonant frequency is Equation (7).

$$f'_{r} = \frac{1}{2\pi \sqrt{(L_{r} + L_{m-eq})C_{r}}}$$
(7)

Inner magnetic flux analysis of the transformer is shown in Figure 9. The primary side is on the left, and the secondary side is on the right. The flux ϕ_p and ϕ_s in the magnetic core established respectively by the primary resonant current i_p and the secondary current i_s cancel each other. Meanwhile, the flux ϕ_{Lm-eq} and ϕ_{AB} in the magnetic core established respectively by the magnetizing current i_{Lm-eq} and the SCI current i_{AB} cancel each other. It follows that, the transformer does not store energy, and the inductive energy storage required by LLC half-bridge switch for zero voltage switching (ZVS) is completed by SCI.



Figure 9. Magnetic flux in the core of transformer.

3.4. LLC Resonant Converter Charger Application

The application of the proposed transformer in LLC resonant converter charger is shown in Figure 10, and the secondary side adopts a full-bridge rectifier. The resonant tank consists of C_r , L_r , and L_{m-eq} .



Figure 10. Proposed resonant transformer applied to LLC resonant converter charger.

The ratio of the equivalent magnetizing inductance to resonant inductance is defined as Equation (8).

$$k = \frac{L_{m-eq}}{L_r} \tag{8}$$

$$Q = \frac{\sqrt{L_r/C_r} \cdot \pi^2}{8 \cdot a^2 \cdot R_{load}} \tag{9}$$

In Equation (9), Q is the quality factor. Under constant L_r , C_r , and a, Q is only related to load. Under the same load (Q value), the voltage gain curves with different k are shown in Figure 11. The horizontal axis is the normalized frequency, which is the ratio of working frequency f_s to resonant frequency f_r , and the vertical axis is DC voltage gain. It can be seen that in the same frequency range, a resonant tank with smaller k can get a larger output voltage regulating range. Moreover, under the condition of fixed resonant inductance L_r , the proposed transformer can regulate L_{m-eq} to adjust k, so that it can dynamically adjust the voltage gain of LLC resonant converter in the charging process according to the corresponding demand.



Figure 11. Gain curves with different *k* value.

Furthermore, the simplified typical battery charging curve is shown in Figure 12. The charging process can be divided to three stages: constant current charging, constant power charging, and constant voltage charging. The output power becomes very small at the charging end.

$$Q = \frac{\sqrt{L_r/C_r} \cdot \pi^2 \cdot I_o}{8 \cdot a^2 \cdot V_o} \tag{10}$$

At the initial stage of charging, the charger current I_0 is large, and the output voltage V_0 is relatively small. At the latter stage of charging, the output voltage V_0 is relatively high and the output current I_0 is small. According to Equation (10), the Q value should be large at the initial stage of charging. With the charging process carrying on, the Q value decreases. Figure 13 gives several gain curves of k value in the charging process. The shaded area (ZVS region) in Figure 13 is the work areas of LLC resonant converter. Usually, the operating frequency of LLC resonant converter is set as the resonant frequency with the maximum output power (point A in Figure 12), since the LLC converter can get highest efficiency [22].



Figure 13. Change of gain curve during charging process.

0.8

1.0

 f_{n}

1.2

1.4

0.8

0.6

Therefore, the operating frequency of the constant current charging stage in Figure 12 is located at the right of the resonant frequency ($f_n = 1$) in Figure 13. The primary switching device of LLC resonant converter works in the ZVS conduction state, but the turn-off loss increases with the increase of frequency and the secondary rectifier diode loses ZCS characteristic. Therefore, in this area, the operating frequency can be set as close as possible to the resonant frequency. As shown in Figure 13, the curve corresponding to a smaller K value is closer to the resonant frequency point (the frequency range is smaller with same gain range). When charging process enters constant power stage, the LLC resonant converter works at the left of the resonant frequency point. The primary switch of LLC resonant converter can realize ZVS conduction, and the secondary rectifier diode can realize ZCS turn-off, which can achieve better efficiency. With the decrease of operating frequency, the smaller K value leads to the increased resonant tank magnetizing current, conduction loss as well as turn-off loss. Especially, when at light load, the proportion of conduction loss in the whole loss increases and reduces

overall efficiency. Therefore, with the decrease of output power and the increase of output voltage, the magnetizing inductance should gradually increase (*k* value gradually increases). In the conventional scheme, the K value is constant after the magnetizing inductance is selected. However, the proposed transformer can make the LLC resonant converter change its equivalent magnetizing inductance according to load and output voltage during the whole charging process, so that the gain characteristic, circulation loss, and switching loss of LLC resonant tank can be optimized via programming.

4. Design Methodology

4.1. Electrical Design Considerations

A: Selection of magnetizing inductance

The maximum magnetizing inductance to realize ZVS under idle condition is L_{m1} , and the maximum value to ensure the maximum gain at the lowest frequency is L_{m2} . The final value of the magnetizing inductance should satisfy the above two requirements at the same time. Hence, the smaller one between L_{m1} and L_{m2} can be chosen. If L_{m1} is greater than L_{m2} , the dead time t_{dead} should be appropriately reduced [23], as shown in Equation (11).

$$\begin{cases} L_{m1} = \frac{t_{dead} \cdot a \cdot V_{o(\min)} \cdot \left(\frac{T_{s(\min)}}{4} - \frac{t_{dead}}{2}\right)}{C_{HB} \cdot V_{in(\max)}} \\ L_{m2} = L_r \cdot \frac{\pi^2}{4} \cdot \frac{1 - \frac{1}{G_{DC(\max)}}}{f_r \cdot T_{s(\max)} - 1} \\ L_{m-eq} = \min(L_{m1}, L_{m2}) \end{cases}$$
(11)

where $G_{DC(max)}$ is the maximum DC gain, and C_{HB} is the total equivalent capacitance of the H bridge.

B: Selection of minimum resonant inductance

The minimum resonant inductance should limit the maximum output current under short circuit when working at the highest frequency.

$$L_{r(\min)} = \frac{a \cdot V_{in(norm)} \cdot V_{o(norm)}}{8f_{s(\max)} \cdot P_o}$$
(12)

C: Selection of resonant capacitance

After L_r is selected, the resonant capacitance can be obtained by Equation (13).

$$C_r = \frac{1}{\left(2\pi \cdot f_r\right)^2 L_r} \tag{13}$$

4.2. Transformer Loss and Thermal Design Considerations

The loss of transformer includes core loss and winding loss.

A: Core loss

The core loss and core loss can be calculated by Steinmetz formula.

$$P_{fe} = V_c K_c f^{\alpha} B_{\max}{}^{\beta} \tag{14}$$

where V_c is the core volume, K_c is the typical value. α and β are provided by core manufacturer or obtained by loss curve.

B: Winding loss

The winding loss include DC loss and AC loss. The current through the winding can be calculated as below.

The current through the primary winding i_r is the sum of i_p and i_{Lm-eq} , and the current through secondary winding is the sum of i_s and i_{AB} . The expressions of the peak current through primary winding is I_{r-peak} with the RMS value I_{r-rms} , and the peak magnetizing current $I_{Lm-peak}$ are [7]

$$I_{r-peak} = \sqrt{\left(\frac{\pi \cdot I_o}{2af_n}\right)^2 + \left(\frac{aV_o}{4f_r L_{m-eq}}\right)^2}$$
(15)

$$I_{Lm-peak} = \frac{aV_o}{4L_{m-eq}f_r} \tag{16}$$

$$I_{r-rms} = \sqrt{\frac{a^2 V_o^2 T_r^2 (2T_s - T_r)}{32L_m^2 T_s} + \frac{\pi^2 I_o^2 T_s^2}{8a^2 T_r^2}}$$
(17)

where T_s and T_r are the switching period and resonant period respectively, V_o and I_o are the output voltage and output current, respectively.

By using Equation (18), the RMS value of the current though secondary winding can be obtained.

$$\dot{a}_{s_rms} = \sqrt{\frac{2 \cdot \int_0^{\frac{T_r}{2}} (aI_{r_peak} \sin[\omega_r t + \phi] + \frac{a^2 V_o}{4L_m f_r} - \frac{a^2 V_o}{L_m} t)^2 dt}{T_r}}$$
(18)

where $\omega_r = 2\pi f_r$, $\phi = \arctan\left(-\frac{a^2 R_L f_s}{\omega_r L_m f_r}\right)$.

The DC copper loss is calculated as below.

$$P_{cu} = R_{p-rms}I^{2}_{r-rms} + R_{s-rms}I^{2}_{s-rms}$$
(19)

The AC impedance of winding can be got from Equation (1).

C: Temperature rise consideration

The maximum loss is determined by the core thermal resistance and the permissible temperature increase.

$$P_{L_{max}} \approx \frac{\Delta T}{R_{\theta}} \tag{20}$$

where R_{θ} is the thermal resistance of the core provided by manufacturer or obtained from empirical data, h_c is thermal conductivity, and A_t is the surface area of transformer.

$$R_{\theta} = \frac{1}{h_{\rm c}A_t} \tag{21}$$

4.3. Transformer Design Considerations

Under the premise of minimize core loss and winding loss, the design purpose of a transformer is to transfer energy from input side to output side by electromagnetic induction. The optimization result can be boiled down to one conclusion: iron loss is equal to copper loss [23]. The transformer design method is related to the best magnetic induction intensity and temperature rise of magnetic core and is limited by the maximum permissible power loss.

A: Core selection

The appropriate core is up to A_p value. A_p is the product of core window area W_a and core cross-section area A_c , as Equation (22).

$$A_p = \left(\frac{\sqrt{2\sum VA}}{K_v f_s B_o k_f K_t \sqrt{k_u \Delta T}}\right)^{\frac{8}{7}}$$
(22)

where, $\sum VA$ is the sum of each windings rated VA values, $K_v = 4.44$, f_s is the operating frequency, B_o is the best magnetic induction intensity value, $K_t = 48.2 \times 103$, k_f is the core lamination factor, A_m is the effective sectional area of magnetic circuit.

The best magnetic induction intensity B_o is given by Equation (23).

$$B_{o} = \frac{\left(h_{c}k_{a}\Delta T\right)^{\frac{2}{3}}}{2^{\frac{2}{3}}\left(\rho_{w}k_{w}k_{u}\right)^{\frac{1}{12}}\left(k_{c}K_{C}f^{\alpha}\right)^{\frac{7}{12}}}\left(\frac{K_{v}fk_{f}k_{u}}{\Sigma VA}\right)^{\frac{1}{6}}$$
(23)

where, h_c is the thermal convection transfer coefficient with typical value 10, and k_a , k_c , and k_w are dimensionless constants with the typical values $k_a = 40$, $k_c = 5.6$, $k_w = 10$. K_C , α are the material parameters, ρ_w is the wire resistivity.

B: Calculation of transformer winding turns and turns ratio

The winding turns can be calculated by Equation (24).

$$N = \frac{V_{rms}}{K_v f B_{\max} A_m} \tag{24}$$

where V_{rms} is the wingding terminal voltage, A_m is the core cross-section area, B_{max} is the smaller one between B_o and B_{sat} . B_o is usually smaller than B_{sat} at the high frequency condition.

The turns ratio can be calculated by Equation (25). where, V_d is the conduction voltage drop of the secondary rectifier diode.

$$a = \frac{V_{in(norm)}}{2(V_{o(\min)} + V_d)}$$
(25)

C: Transformer wire diameter selection

The current density J_0 in the wire should satisfy the temperature rise requirement under the whole power loss.

$$J_0 = K_t \frac{\sqrt{\Delta T}}{\sqrt{k_u (1+\gamma)}} \tag{26}$$

The calculation of wire sectional area A_w is Equation (27).

$$A_w = \frac{I_{rms}}{J_0} \tag{27}$$

D: Determination of inductance La

According to Equation (2) and Figure 7, the switch-controlled inductance L_{SCI} can be adjusted in a wide range. When $\alpha = \pi/2$, $L_{SCI} = La$. While the *k* value of LLC resonant tank obtains a minimum value k_{\min} as Equation (28) According to Equation (4).

$$L_a = \frac{k_{\min} \cdot L_r \cdot L_{m-ini}}{a^2 (L_{m-ini} - k_{\min} \cdot L_r)}$$
(28)

5. Experimental Verification

5.1. Design Specification

An LLC resonant DC/DC converter with 720 W output power is designed, its input voltage is 390 VDC and output voltage is 60 VDC–96 VDC with maximum output current is 8 A. The resonant frequency is 85 kHz. According to Equation (12), the resonant inductance L_r should be greater than 44 µH and set as 50 µH. According to Equation (13), the resonant capacitance C_r is 70 nF. According to Equation (24), the transformer turns ratio a = 2:1. According to Equation (28), k_{\min} is 3, L_{\min} is 1 mH and La = 44 µH.

The design requirement is shown in Table 1, the RMS value of resonant current, the peak magnetizing current and the RMS value of secondary current are calculated by Equations (15)–(18). The core window utilization factor k_u is 0.55.

Symbol	Description	Value
Po	Output power	760 W
f_s	Switching frequency	50 k–300 kHz
f_{r1}	Resonant frequency	85 kHz
L_a	Magnetizing inductance	44 μΗ
L_r	Resonant inductance	50 µH
а	Turns ratio	2:1
ΔT	Temperature rise	70 °C
T_a	Ambient temperature	40 °C
I_{r-rms}	Resonant rms current	4.53 A
$I_{Lm-veak}$	Magnetizing peak current	1.26 A
I_{s-rms}	Secondary rms current	9.1 A
I_{AB-rms}	SCI current	2 A
$\sum VA$	The total rated VA values of windings	1466.3 VA

Table 1.	Design	Specification.
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5.2. Transformer Parameters

The ferrite core is used for the high switch frequency. $B_o = 0.1$ T is calculated by Equation (23), $A_p = 2.5$ cm⁴ is calculated by Equation (22), the ETD44 magnetic core is chosen. The magnetic material is the N87 from EPCOS company, the parameters of this material are given in Table 2, and the parameters of core and winding are given in Table 3. The saturation flux density of this material is 0.4 T. By Equation (24), the transformer secondary turns can be calculated as $Ns = 11.9 \approx 12$. The primary turns number is 24.

Fable 2. Material Specifications (Epcos N87)).
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Symbol	Description	Value
K _c	Steinmetz parameter	16.9
α	Steinmetz parameter	1.25
β	Steinmetz parameter	2.35
B _{sat}	Saturation magnetic flux	0.4 T
k _u	Window utilization factor	0.55
A_m	Effective magnetic circuit sectional area	213 mm ²
γ	Ratio of core loss to winding loss	1

Symbol	Description	Value
A _c	Cross-section area	1.73 cm ²
l_c	Magnetic path length	10.3 cm
W_a	Window area	2.78 cm^2
A_p	Area product parameter	4.81 cm^4
V_c	Volume of core	17.70 cm^3
MLT	Mean length of a turn	7.77 cm
k _f	Core stacking factor	1.0
ρ_{20}	Copper resistivity (20 °C)	1.72 μΩ·cm
α_{20}	Constant	0.00393

Table 3. Core and Winding Parameters.

The current density can be obtained by Equation (26) as 344 A/cm^2 , and the wire sectional area of the primary winding is 0.0132 cm² from Equation (27). Considering the wire skin effect at high frequency, the skin depth is

$$\lambda_0 = \frac{66}{\sqrt{f_s}} \tag{29}$$

It is set as $\lambda_0 = 0.226$ mm and the specification parameters are shown in Table 4. The DC resistance of primary winding is 120.3 $\mu\Omega/cm$ (20 °C).

Table 4. Core and Winding Parameters.

AWG	Sectional Area	Resistivity	Diameter
24	0.2047 mm ²	842.1 $\mu\Omega/cm$	0.51 mm

To reduce the secondary proximity effect, the Litz wire of 0.15 mm \times 110 mm is chosen. The equivalent electric conduction area is 1.95 mm², the current density is 464 A/cm², and the primary DC internal resistance is 89.2 $\mu\Omega$ /cm (20 °C).

The DC internal resistance of each winding can be obtained with temperature correction as

$$R_{cu-dc} = N \cdot MLT \cdot \rho_w \cdot [1 + \alpha_{20}(T_{\max} - 20 \ ^\circ \text{C})]$$
(30)

where T_{max} is the maximum temperature.

Considering the wire skin effect at high frequency, the skin effect factor is calculated by

$$\frac{R_{ac-pri}}{R_{dc-pri}} = 1 + \frac{(r_o/\delta_0)^4}{48 + 0.8(r_o/\delta_0)^4} = 1.019$$
(31)

where, r_0 . is the radius of wire and $r_0 = 0.255$ mm.

The influence of the proximity effect of the secondary winding is calculated by

$$\Delta_s = \frac{d_s}{\delta_0} = \frac{0.15}{0.26} = 0.577, \qquad p_s = 4 \tag{32}$$

where, d_s is the diameter of wire. The ratio of secondary AC resistance and DC resistance is $R_{ac_S}/R_{dc_S} = 1.2$. Power loss and the efficiency of transformer are shown in Table 5. It is worth noting the efficiency of the transformer is calculated under the condition of resonant frequency and full power.

Symbol	Description	Value	
P_{max}	Allowed Maximum power loss	4.9 W	
$P_{cu dc}$	DC winding loss	1.56 W	
P_{cu_ac}	AC winding loss	1.74 W	
P_{fe}	Core loss	1.94 W	
$\dot{P_{La}}$	The loss of SCI	1.1 W	
P_{tol}	Total loss	4.78 W	
η	Transformer efficiency	99.37%	

Table 5. Loss Calculations.

5.3. Experimental Results

The designed transformer is applied to 720 W LLC resonant converter charger. The experimental waveforms under different operating conditions are given in Figure 14. The operating waveform of LLC resonant converter at the initial stage of constant current charging is given in Figure 14a. The output power is 608 W and the operating frequency is 98.1 kHz, which is higher than the resonant frequency. The phase-shifting angle of the SCI is $\alpha = \pi/2$, and the current of the SCI branch i_{AB} is triangular wave. At this time, the magnetizing inductance of the resonant tank is small, the K value is also small, which helps reducing the switching frequency range.



Figure 14. Cont.



Figure 14. Experimental waveforms. (a) Constant Current Stage with $V_o = 76$ V and $I_o = 8$ A ($\alpha = 0.5\pi$); (b) Constant Power Stage with $V_o = 90$ V and $I_o = 8$ A ($\alpha = 0.67\pi$); (c) Constant Voltage Stage with $V_o = 96$ V and $I_o = 2.5$ A ($\alpha = 0.79\pi$).

Figure 14b shows the working waveform of LLC resonant converter at the constant power charging stage. The output power is 720 W and the operating frequency is 84.8 kHz, near the resonant frequency. The phase-shifting angle of the switch-controlled inductor is $\alpha \approx 0.67\pi$, and the magnetizing current of the transformer is relatively decreased, which reduces the conduction loss.

Figure 14c shows the working waveform of LLC resonant converter at constant voltage charging stage. The output power is 240 W, the operating frequency is 70.2 kHz, which is lower than the resonant frequency, and the output power is smaller. The phase-shifting angle of the switch-controlled inductor is $\alpha \approx 0.79\pi$, the magnetizing current of the transformer is decreased further and the light load efficiency is improve effectively.

The experiment results comparison of the transformer temperature after operating under a full load for 1 h is shown in Figure 15. The temperature rise of the proposed transformer is 65.2 °C. Experiments show that the transformer works in an ideal temperature rise range. In addition, the conventional transformer with air gap is applied to the same resonator circuit, the transformer retaining wall interval *d* is 4.3 mm, the temperature rise is measured as 83.8 °C. Moreover, the temperature rise of the secondary winding near the air-gap is the highest, which is 14.9 °C higher than the proposed transformer.



Figure 15. Temperature rise comparison. (a) The conventional scheme; (b) The proposed scheme.

Corresponding to Figure 14, the measured loss of the proposed transformer under 100%, 80%, and 33% loads are compared with those of the conventional LLC transformer, as shown in Figure 16. Experimental results show that the proposed design scheme is more efficient to reduce the temperature rise of magnetic components.



Figure 16. Measured loss comparison.

Figure 17 shows the efficiency comparison between the proposed LLC resonant converter charger and the conventional LLC resonant converter charger (k = 5) in the whole charging process. At the left of point A, the operating frequency is higher than resonant frequency. The proposed transformer magnetizing inductance can be dynamically adjusted, which not only improves the efficiency of the transformer itself, but also effectively reduces the conduction loss and switching loss of the LLC resonant converter. Hence, the comprehensive efficiency can be improved.



Figure 17. Efficiency comparison in the whole charging process.

6. Conclusions

Aiming at the relatively low efficiency problem of the conventional integrated transformer in LLC resonant converter, a controlled magnetizing inductance resonant transformer suitable for high power LLC resonant converter is proposed. The proposed transformer mainly removes the influence of fringing effect, improving the efficiency of the transformer, and the temperature rise of transformer. The experimental results show that the temperature rise of the transformer is reduced by 14.9 °C compared with the conventional scheme. Moreover, according to the change of charging process (output voltage and equivalent load impedance changes), the magnetizing inductance of proposed transformer can be dynamically adjusted to reduce the conduction loss and switching loss of the LLC resonant converter. Therefore, the comprehensive efficiency of the whole charging process can be improved further, especially at the initial charging stage and at the charging end (light load).

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