





# Numerical Investigation of the Effect of Variable Baffle Spacing on the Thermal Performance of a Shell and Tube Heat Exchanger

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Abstract: In this present study, numerical and theoretical analysis were both used to investigate the effect of the variable baffle spacing on the thermal characteristics of a small shell and tube heat exchanger. The numerical study was performed by using a three dimensional computational fluid dynamics (CFD) method and the computations were performed under steady-state conditions. We employed five different cases where the first had equal baffle spacing and the others had variable ones considering different configurations for balancing the pressure drop on the shell side. Theoretical calculations were run using the Bell-Delaware and Kern methods which are the most commonly used methods in the available literature. We show that the thermal performance of a shell and tube heat exchanger can be improved by evaluating together the results of the CFD and Bell-Delaware methods. From the numerical results, we can say that variable spacing with centered baffle spacing scheme can be proposed as an alternative shell side construction layout compared to an equal baffle spacing scheme. The numerical results were in good agreement with the theoretical data in the available literature.

Keywords: heat exchanger; baffle spacing; CFD

# 1. Introduction

Heat exchangers are devices made for efficient heat transfer from one zone to another in order to transfer energy and they are widely used in different industries like the automotive, heating, ventilation and air conditioning (HVAC), chemical and food industry and so on [1,2]. The shell and tube heat exchanger is an indirect contact type heat exchanger and there are considerable reasons to prefer the shell and tube heat exchanger, such as relatively simple manufacturing, multi-purpose applicability, robust geometry construction, easy maintenance, etc. Certain standards and correlations proposed by the Tubular Exchanger Manufacturers Association (TEMA) have to be considered when a well-designed shell and tube heat exchanger is desired for industrial applications. In the shell and tube heat exchanger there are two main fluid flows, one fluid flow that goes through the tubes while the other flows on the shell side [3-5]. In a baffled shell and tube heat exchanger, the baffles are used for different reasons such as providing support for tubes, obtaining a desirable fluid velocity to be maintained for the shell-side fluid flow, and preventing the tubes from vibrating. They also direct the shell side flow to enhance the heat transfer coefficient but their usage conversely produces an increased pressure drop [6]. Therefore, their dimensions and locations have to be optimized or they have to be replaced with the other types which have better heat transfer efficiency and lower pressure drops [7–10]. There are numerous studies on the impact of the baffle cut, number of baffles, baffle type, etc. on the thermal performance of the shell and tube heat exchanger in the available literature, however there is a limited amount of research on the effect of variable baffle spacing schemes on the heat transfer rate and pressure drop of a small shell and tube heat exchanger. Baffle spacing is one of the most important parameters used in the design of shell and tube heat exchangers. Closer spacing causes a higher heat transfer rate and pressure drop. On the other hand, a higher baffle spacing reduces both the heat transfer rate and pressure drop [11]. In this study, we investigated the impact of variable baffle spacing on the thermal characteristics of a shell and tube heat exchanger. As the default shell and tube heat exchanger an E shell type was selected which is the most commonly used due to its low cost and simplicity. The shell and tube heat exchanger used in this study had one shell and one pass with 19 tubes and seven baffles. In theoretical calculations for predicting the overall heat transfer coefficient, the convective heat transfer coefficients for the shell and tube sides are needed. On the tube side, well known correlations have to be selected according to the flow conditions. On the other hand, the shell side analysis is more complex than the tube side one because of several additional parameters that affect the shell side flow. On the shell side of the heat exchanger, the Kern and Bell-Delaware methods are the common methods used in the literature to calculate the heat transfer coefficient and pressure drop. Comparing these two methods, the Kern method is also only suitable for preliminary sizing whereas the Bell-Delaware method is a very detailed method that takes into account the effects of various leakage and bypass streams on the shell side. The Bell-Delaware method gives also the most reliable results for the shell side analysis [1,12,13]. However, while all these theoretical calculations indicate the deficiencies of shell side design in general these methods do not give any information about the location of these weaknesses. On the other hand, a well designed and built computational fluid dynamics (CFD) numerical model can be a useful tool to obtain the flow and heat transfer characteristics of a shell and tube heat exchanger. The CFD method with these common correlations can be utilized to get the appropriate flow and heat transfer characteristics taking into account the desired heat transfer rate and pressure drop. The CFD method can be used both in the rating and iteratively in the sizing of heat exchangers [14]. On the other hand, to get a successful CFD simulation for a detailed heat exchanger model, in the numerical computations, we chose a small shell and tube heat exchanger to evaluate the effect of variable baffle spacing on the heat transfer coefficient and also pressure drop that can be compared with the correlation-based ones.

#### 2. Materials and Methods

#### 2.1. Theoretical Study

The total heat transfer rate between two different fluid streams can be easily calculated by using Equations (1) and (2) under steady-state conditions assuming negligible heat transfer between the heat exchanger and its surroundings:

$$\mathbf{Q}_{\mathbf{h}} = \left( \dot{\mathbf{m}} \cdot \mathbf{c}_{\mathbf{p}} \right)_{\mathbf{h}} \cdot (\mathbf{T}_{\mathbf{h},1} - \mathbf{T}_{\mathbf{h},2}),\tag{1}$$

$$Q_{c} = \left(\dot{m} \cdot c_{p}\right)_{c} \cdot (T_{c,2} - T_{c,1}).$$
<sup>(2)</sup>

On the other hand the temperature difference in the heat exchanger varies with the location in both shell and tube sides. Thus, for the design process, the total heat transfer rate can be written by using logarithmic mean temperature difference (LMTD) shown in Equation (3):

$$Q = U \cdot A \cdot \Delta T_{lm}.$$
(3)

where  $U_f$  is the overall heat transfer coefficient described in Equation (5) considering fouling resistance, A is the total heat transfer area of a heat exchanger and the  $\Delta T_{lm}$  can be calculated as a function of inlet and outlet temperatures both of hot and cold fluids by using Equation (4):

$$\Delta T_{\rm lm} = \frac{\Delta T_1 - \Delta T_2}{\ln(\Delta T_1 / \Delta T_2)},\tag{4}$$

$$\frac{1}{U_{f}} = \frac{1}{h_{h}} + \frac{1}{h_{c}} + \frac{t}{k_{w}} + R_{f,h} + R_{f,c'}$$
(5)

$$\frac{1}{U} = \frac{d_o}{d_i} \cdot \frac{1}{h_i} + \frac{d_o \cdot \ln(d_o/d_i)}{2k} + \frac{1}{h_o}.$$
(6)

In this study, the fouling resistance is assumed negligible in theoretical calculations, thus Equation (5) can be rewritten for cylindrical geometries and the final form of the overall heat transfer coefficient based on the outer diameter of the tube which is used in this study is described in Equation (6) for clean surfaces. The use of Equation (6) requires the convective heat transfer coefficients for shell and tube sides. In this study, the shell side heat transfer coefficient and pressure drop for various baffle spacings were calculated by using the Kern and Bell-Delaware methods described below. The heat transfer coefficient of the tube side was calculated by using the appropriate correlation known as the Petukhov-Kirillov method and the flow was assumed as turbulent (Equations (7)–(10)):

$$\operatorname{Re} = \frac{\rho \cdot U_{\mathrm{m}} \cdot d_{\mathrm{i}}}{\mu} \tag{7}$$

Nu = 
$$\frac{(f/2) \cdot \text{Re} \cdot \text{Pr}}{1.07 + 12.7 \cdot (f/2)^{1/2} \cdot (\text{Pr}^{2/3} - 1)}$$
 (8)

$$f = (1.58 \ln Re - 3.28)^{-2}$$
(9)

$$h_{i} = \frac{Nu \cdot k}{d_{i}} \tag{10}$$

## 2.1.1. Shell Side Heat Transfer Coefficient and Pressure Drop Using the Kern Method

In the Kern method, all results are based on a constant baffle cut (Bc) ratio which is taken as 25% in this study. The shell side heat transfer coefficient can be calculated with the correlation suggested by Mc Adams and expressed by Equation (11), where  $h_o$  is the shell-side heat transfer coefficient, De is the equivalent diameter on the shell side and is calculated by using Equation (12) and  $G_s$  is the shell side mass velocity which is the ratio of mass flow rate to the bundle crossflow area at the center of the shell that can be calculated from Equation (13) [15]. The bundle crossflow area can be calculated using shell side inner diameter ( $D_s$ ), clearance between adjacent tubes (C), the distance between two successive baffles (B) and the pitch size ( $P_t$ ) (Equation (14)):

$$\frac{\mathbf{h}_{0} \cdot \mathbf{D}_{e}}{\mathbf{k}} = 0.36 \times \left(\frac{\mathbf{D}_{e} \cdot \mathbf{G}_{s}}{\mu}\right)^{0.55} \cdot \left(\frac{\mathbf{c}_{p} \cdot \mu}{\mathbf{k}}\right)^{1/3} \cdot \left(\frac{\mu_{b}}{\mu_{w}}\right)^{0.14},\tag{11}$$

$$D_{e} = \frac{4\left(\frac{P_{T}^{3}\sqrt{3}}{4} - \frac{\pi \cdot d_{o}^{2}}{8}\right)}{\frac{\pi \cdot d_{o}}{2}},$$
(12)

$$G_{\rm s} = \frac{\dot{\rm m}}{{\rm A}_{\rm s}},\tag{13}$$

$$A_{s} = \frac{D_{s} \cdot C \cdot B}{P_{T}}.$$
(14)

In this method, the pressure drop for the shell side can be calculated with Equation (15), where N<sub>b</sub> is the number of baffles,  $\phi_s$  is calculated from Equation (16) where  $\mu$  is the dynamic viscosity and the friction factor (f) for the shell side can be calculated from Equation (17) considering the range of the Reynolds number described:

$$\Delta \mathbf{p}_{s} = \frac{\mathbf{f} \cdot \mathbf{G}_{s}^{2} \cdot (\mathbf{N}_{b} + 1) \cdot \mathbf{D}_{s}}{2 \cdot \boldsymbol{\rho} \cdot \mathbf{D}_{e} \cdot \boldsymbol{\varphi}_{s}},\tag{15}$$

$$\phi_{\rm s} = (\mu_{\rm b}/\mu_{\rm w})^{0.14},\tag{16}$$

$$f = \exp(0.576 - 0.19 \ln(Re_s), \ 400 < Re_s = \frac{G_s \cdot D_e}{\mu} < 1 \times 10^6.$$
(17)

2.1.2. Shell Side Heat Transfer Coefficient and Pressure Drop Using the Bell-Delaware Method

The Bell-Delaware method is more complicated than the Kern method because of some additional parameters that are involved in the calculations. These parameters concern various leakages and bypass streams on the shell side and their effect on the shell side ideal heat transfer coefficient is described by Equation (18): The ideal heat transfer coefficient ( $h_{id}$ ) described in the Bell-Delaware method for pure crossflow in an ideal tube bank and is calculated from Equation (19), where  $J_i$  is Colburn j-factor and it can be found as a function of the shell side Reynolds number,  $A_s$  is the cross-flow area at the centerline of the shell for one cross-flow between two baffles.  $J_c$  is the correction factor for baffle cut and spacing,  $J_l$  is the correction factor for baffle leakage effects including tube-to-baffle and shell-to-baffle leakage,  $J_b$  is the correction factor for bundle bypassing effects and  $J_s$  is the correction factor for baffle leakage effects were not considered in the CFD model so the  $J_l$  factor was assumed as 1.  $J_s$  is a correction factor if the baffle spacing length is different in the inlet and outlet fluid zones. In this study, the value of this length was equal to each other for these zones, thus the  $J_s$  factor was assumed as 1. The details of this method can be found in [1]:

$$\mathbf{h}_{o} = \mathbf{h}_{id} \cdot \mathbf{J}_{c} \cdot \mathbf{J}_{l} \cdot \mathbf{J}_{b} \cdot \mathbf{J}_{s} \cdot \mathbf{J}_{r'}$$
(18)

$$h_{id} = j_i \cdot c_{p,s} \cdot \Phi\left(\frac{\dot{m}_s}{A_s}\right) \cdot \left(\frac{k_s}{c_{p,s} \cdot \mu_s}\right)^{2/3} \cdot \left(\frac{\mu_s}{\mu_{s,w}}\right)^{0.14}$$
(19)

For shell side Reynolds number we used Equation (20) where  $d_o$  is the outer diameter of a one tube and  $A_s$  is the crossflow bundle area described in Equation (14). The Reynolds number is computed to be about 2773, thus the shell side flow is assumed as turbulent:

$$\operatorname{Re}_{s} = \frac{\operatorname{d}_{o} \cdot G_{s}}{\mu_{s}}.$$
(20)

In this method the total pressure drop for the shell side ( $\Delta p_s$ ) is calculated considering entering and leaving ( $\Delta p_e$ ), internal cross-flow ( $\Delta p_c$ ) baffle window ( $\Delta p_w$ ) and the nozzle ( $\Delta p_n$ ) regions, the detailed information about these calculations can be found in references [16] and [17] (Equation (21)). These pressure drop regions are shown in Figure 1 for shell and tube heat exchangers in general:

$$\Delta p_{s} = \Delta p_{c} + \Delta p_{win} + \Delta p_{e} + \Delta p_{n}$$
<sup>(21)</sup>



Figure 1. Pressure drop regions in a shell and tube heat exchanger.

## 2.2. Numerical Study

## 2.2.1. CAD Model of the Heat Exchanger

We considered three different locations that can be taken as a reference point for the comparison of the thermal performance. These locations were selected at inlet, outlet and the center of the heat exchanger. This can be also examined in different configurations but five different baffle spacing schemes were selected for the numerical simulations to evaluate the effect of variable baffle spacing on the heat transfer characteristics in terms of using these reference locations.

In the first case the heat exchanger had equal baffle spacing length and the other cases it had a variable one. On the other hand, in the second case, the baffle spacing length decreases when approaching the center line of the heat exchanger. The third case had an opposite structure to the second case. For the fourth and fifth cases, a baffle spacing length which decreases from centerline to the inlet and outlet zones, respectively, was selected. These variable baffle spacing schemes and the dimensions are shown in Figures 2 and 3 and Table 1. We selected these five different schemes for the comparison of the numerical results in view of pressure drops and heat transfer rates.

The CAD model of the shell and tube heat exchanger is shown in Figure 4. The tube side had a triangular pitch layout and the dimensional properties of the shell and tube heat exchanger used in the numerical simulations are listed in Table 2.



Figure 2. The dimensions of baffle spacing lengths for all cases.



(e) Case-V: Outlet baffle spacing scheme

Figure 3. Baffle spacing scheme for all cases.

Spacing Length	Case-I (mm)	Case-II (mm)	Case-III (mm)	Case-IV (mm)	Case-V (mm)
L1	26.75	26.75	26.75	26.75	26.75
L2	26.75	41.25	16.00	16.00	38.50
L3	26.75	26.00	26.00	21.00	34.00
L4	26.75	16.00	41.25	26.00	31.00
L5	26.75	16.00	41.25	31.00	26.00
L6	26.75	26.00	26.00	34.00	21.00
L7	26.75	41.25	16.00	38.50	16.00
1.8	26.75	26.75	26.75	26.75	26.75

Table 1. The dimensions of baffle spacing lengths for all cases.



Figure 4. CAD model of the shell and tube heat exchanger used in this numerical study.

Shell Side Dimensions				
Shell internal diameter	44 mm			
Shell wall thickness	3 mm			
Baffle plate wall thickness	1 mm			
Number of baffle plates	7			
Tube Side Dimensions				
Tube internal diameter	4 mm			
Tube wall thickness	1 mm			
Effective tube length	221 mm			
Number of tubes in tube bundle	19			

Table 2. The dimensions of the shell side and tube side of the heat exchanger.

2.2.2. Mesh Structure and Boundary Conditions of Numerical Calculations for Shell and Tube Heat Exchanger

In the numerical calculations of all cases, the computational domain had eight fluid zones in the shell side for getting comparative numerical detailed results (Figure 5). The multi-zone approach was used to model the heat exchanger and all these zones had tetrahedral mesh elements due to the complexity of the CAD model. The number of total elements was about 6.0 million and the mesh should be well designed to resolve the important flow features which are dependent upon flow condition parameters.

In numerical calculations, mesh generation is very crucial for getting accurate predicted results and reducing the computation time [9,12,14,18,19]. The mesh structure of the surfaces of the computational domain and the section view of this domain are shown in Figure 6. Today, there are many computer software packages for flow field and heat transfer analysis. For the mesh generation and the numerical solution, the Ansys Fluent package software program was used. In this software flow and temperature fields were computed by a three dimensional CFD method. This software solves continuum, energy and transport equations numerically and the coupled algorithm was chosen for pressure-velocity

coupling, the k- $\varepsilon$  realizable model was used for turbulence modeling and this model was used for such calculations due to stability and precision of the numerical results in the available literature [6,12,18–22]. The governing equations for steady state conditions are shown below:

Conservation of mass :  $\nabla(\rho \cdot \vec{V}) = 0$ , (22)

x-momentum: 
$$\nabla(\rho u \overrightarrow{V}) = -\frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left( 2\mu \frac{\partial u}{\partial x} + \lambda divV \right) + \frac{\partial}{\partial y} \left[ \mu \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \right] + \frac{\partial}{\partial z} \left[ \mu \left( \frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right) \right],$$
 (23)

y-momentum: 
$$\nabla(\rho v \vec{V}) = \rho g_y - \frac{\partial p}{\partial y} + \frac{\partial}{\partial x} \left[ \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right] + \frac{\partial}{\partial y} \left[ 2\mu \frac{\partial v}{\partial y} + \lambda divV \right] + \frac{\partial}{\partial z} \left[ \mu \left( \frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right) \right],$$
 (24)

z-momentum: 
$$\nabla(\rho w \overrightarrow{V}) = -\frac{\partial p}{\partial z} + \frac{\partial}{\partial x} \left[ \mu \left( \frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right) \right] + \frac{\partial}{\partial y} \left[ \mu \left( \frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right) \right] + \frac{\partial}{\partial z} \left( 2\mu \frac{\partial w}{\partial z} + \lambda divV \right),$$
 (25)



Figure 5. Separated fluid zones on the shell side of the heat exchanger.



Figure 6. Mesh structure of the heat exchanger.

In Equation (22),  $\Phi$  is the dissipation function that can be calculated from:

$$\Phi = \mu \left[ 2 \left[ \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial z} \right)^2 \right] + \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right)^2 + \left( \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right)^2 \right] + \lambda \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)^2$$
(27)

All numerical calculations were performed under steady state conditions and in the numerical calculations, water was selected as both the shell and tube side fluid in the numerical model of the heat exchanger. The mass flow rates of the hot and cold water were set to 0.3 kg/s and 0.2 kg/s and the temperature values of these zones were set to 50 °C and 10 °C, respectively. The detailed solver settings and the boundary conditions used in this numerical study are shown in Table 3.

(26)

Solver Settings				
Solver	Pressure-based			
Time	Steady-state conditions			
Equations	Combined simulation of flow and energy			
Flow type	k-epsilon realizable turbulence model			
	Shell Side			
Supply temperature of cold water	10 °C			
Mass flow rate	$0.2  { m kg  s^{-1}}$			
Shell outer surfaces	Adiabatic conditions			
Outlet nozzle	Gauge pressure equals to 0 Pa			
	Tube-Side			
Supply temperature of hot water	50 °C			
Mass flow rate	$0.3 { m kg s^{-1}}$			
Outlet surfaces of the tube side	Gauge pressure equals to 0 Pa			
Thermal Propert	ties of Water at Mean Temperature			
Thermal conductivity	$0.6 \text{ W m}^{-1} \text{ K}^{-1}$			
Specific heat	Cold side: 4180 j kg <sup>-1</sup> K <sup>-1</sup> , Hot side: 4186.5 j kg <sup>-1</sup> K <sup>-1</sup>			
Density	998.2 kg m $^{-3}$			
Dynamic viscosity	$0.001003 \text{ kg m}^{-1} \text{ s}^{-1}$			

Table 3. Solver settings and boundary conditions used in the numerical simulations.

The flow chart of the numerical simulation used in this study is shown in Figure 7. In the first stage, 3D CFD analysis of a shell and tube heat exchanger was achieved by using a commercial CFD solver. When the entire fluid domain is modeled as a single continuum zone, the numerical data can be obtained only for this zone and getting the computed values of temperature, velocity and pressure between baffles becomes difficult. We used a multi-zone approach in which the entire fluid domain for CFD analysis was divided into sub-zones as shown in Figures 5 and 6. These sub-zones can helpful to get the numerical solution data between two successive fluid zones compared to the single zone. These sub-zones were used to obtain the thermal characteristics and pressure drop in an efficient way. In this content, we can easily say that multi-zone solution scheme including solid and fluid zones can be used to evaluate the heat transfer characteristics and pressure drop in a more detailed way compared to the single zone approach because the multi-zone approach enables one to investigate each fluid zone individually in view of the heat transfer coefficient, pressure drop, temperature and velocity distributions. On the other hand, this approach can be used to evaluate the results such as the weaknesses (different leakage flow paths, bypass streams for different flow zones, temperature and velocity distribution for each zone etc.) on the shell side for different operating conditions. Moreover, using a 3D CFD model, the effect of the main important parameters such as baffle spacing length and baffle cut on the heat transfer and pressure drop in shell side can be obtained easily in this stage.

The validation of the numerical results can be achieved by comparison with the theoretical results of common methods like the Kern and Bell-Delaware methods. Thus multi-zone CFD approach used together with common theoretical methods can be useful for getting better design solution considering the maximum pressure drop limit and desired heat transfer rate of the heat exchanger. The desired configuration based on the numerically obtained temperature and flow fields can be achieved iteratively and this numerical solution procedure is shown in Figure 7.

In the numerical calculations, the 3D model of the heat exchanger was obtained considering inlet and outlet plenums, whereas in the literature, some numerical investigations were performed by applying a constant mass flow rate for each tube individually and constant temperature boundary conditions were applied to the tube surfaces in general, but in this study, we also considered the effect of the velocity distribution of the inlet and outlet regions (plenum) on the flow inside the tubes and

the shell and tube side flows were both solved simultaneously with energy equations [5,12]. On the other hand, we also employed solid zones such as tube walls, shell body, baffles and inlet and outlet nozzles etc. to include conjugate heat transfer in this numerical study.



**Figure 7.** Flow chart of numerical method for the desired solution of the thermal analysis of a shell and tube heat exchanger suggested in this study.

## 3. Results and Discussion

For getting the comparative numerical results, we defined eight section planes in different zones (Figure 8). The first and end section planes are located at the mid-center of the nozzles and the other ones are located at the middle center of the each fluid zone. To evaluate the numerical data in terms of multi-zone approach, the each fluid zone had inlet and outlet faces, separately. These faces (window, inlet and outlet faces) are shown in Figure 9.



Figure 8. Schematic view of section planes defined for comparative results for shell side.



Figure 9. Window surfaces located between two adjacent fluid zones.

The predicted temperature values at these section planes are shown in Figures 10–14. The calculated maximum temperature difference was about 2.5 °C in the first section plane for all cases. On the other hand, the predicted temperature values increased with the z-coordinate and the maximum values were computed at the location which had dense baffle spacing construction because this structure leads to an increase in the predicted temperature values in these section planes. Thus we can say that heat transfer rate strictly depends on the baffle spacing length.

From the calculated temperature values at the middle center of the each fluid zone the temperature values were lower than the others for the region aligned with the window area for all cases in general (Figures 10–14). The maximum temperature difference between the first and end section planes were computed at about 9 °C for Case-I and Case-II. In these section planes, the calculated maximum temperature value was obtained for Case-II and it was computed about 23 °C at z = 0.173 m section plane which is located close to the middle plane of the heat exchanger. As a result of these numerical data, we can easily say that different baffle spacing scheme has a great effect on the temperature distribution of shell side and also the heat transfer rate. These results can be used for getting better designs in terms of heat transfer characteristics.



Figure 10. Prediction of temperature (°C) distribution at section planes defined in shell side (Case-I).

1.00e+01 1.23e+01	1.45e+01 1.68e+01	1.90e+01 2.13e+01	2.35e+01 2.50e+01
		14	
Z= 0.010 m (first-plane)	Z= 0.048 m	Z= 0.081 m	Z= 0.102 m
45 10 10 16.5	18.5	28 21 21 21 21 20 19.5	
Z= 0.118 m	Z= 0.139 m	Z= 0.173 m	Z= 0.211 m (end-plane)

Figure 11. Prediction of temperature (°C) distribution at section planes defined in shell side (Case-II).



Figure 12. Prediction of temperature (°C) distribution at section planes defined in shell side (Case-III).



Figure 13. Prediction of temperature (°C) distribution at section planes defined in shell side (Case-IV).



Figure 14. Prediction of temperature (°C) distribution at section planes defined in shell side (Case-V).

These computed numerical data for each zone is shown in Tables 4 and 5. From the obtained results, the calculated pressure drop changed between 893 Pa and 1210 Pa for each zone. Due to the assignation of zero gauge pressure for the outlet surface to obtain the relative pressure drop between inlet and outlet sections, the maximum pressure drop was calculated from win-7 to the cold outlet surfaces. One of the reasons for this situation is that, the contraction at the outlet nozzle leads to a higher pressure drop. The maximum pressure drop that occurred in a single fluid zone was calculated at about 1600 Pa for Case-II. However, in this case, this leads to an increase in temperature values and also the heat transfer rate compared to the Case-III, Case-IV and Case-V. On the other hand the temperature difference between the cold inlet and outlet surfaces was predicted at about 7.2 °C for Case-III, Case-IV and Case-V. This value was computed as 8.1 °C and 8.0 °C for Case-I and Case-II, respectively. Thus, Case-I and Case-II have similar thermal properties in view of heat transfer rate and the pressure drop was calculated to be nearly equal, but the pressure drop should be adopted considering the best design configuration by changing baffle spacing length for Case-II.

	C	ase-I	Ca	ase-II	Case-III	
Surface Name	Pressure (Pa)	Temperature (°C)	Pressure (Pa)	Temperature (°C)	Pressure (Pa)	Temperature (°C)
Cold-inlet	20,832	10.00	21,340	10.00	21,312	10.00
Win-1	19,622	11.78	20,194	11.83	20,128	11.50
Win-2	18,729	12.82	19,356	13.22	18,934	12.20
Win-3	17,588	13.91	18,243	14.13	17,756	13.20
Win-4	16,484	14.89	16,754	14.82	16,759	14.36
Win-5	15,361	15.86	15,183	15.43	15,768	15.41
Win-6	14,269	16.76	14,023	16.37	14,709	16.27
Win-7	13,147	17.63	12,986	17.49	13,230	16.67
Cold-outlet	0	18.11	0	17.98	0	17.16

Table 4. Computed temperature and pressure values at different surfaces (i).

The predicted heat transfer rates for each zone and total heat transfer rate for all cases are shown in Table 6. From the obtained numerical results, the calculated total heat transfer rates for Case-I and Case-II were about equal to 6.5 kW and these cases had similar properties in terms of thermal performance. The ratio of the total heat transfer rate to the computed heat transfer rate for Case-I was defined as a dimensionless number ( $R_h$ ) and this value was computed as 0.98. These results shown that Case-II which had variable spacing with centered baffle spacing scheme had similar thermal properties compared to Case-I but more experimental investigation about this scheme has to be performed considering practical problems. The predicted total heat transfer rates for Case-III, Case-IV and Case-V were about 5.9 kW, thus these baffle spacing schemes had lower thermal performance than the others. The minimum predicted heat transfer rate was obtained for Case-III and Case-V.

Surface Name	Ca	ase-IV	C	ase-V
Surface Mullie	Pressure (Pa)	Temperature (°C)	Pressure (Pa)	Temperature (°C)
Cold-inlet	20,907	10.00	21,196	10.00
Win-1	19,759	11.51	19,852	11.64
Win-2	18,602	12.22	19,021	12.83
Win-3	17,308	12.97	17,938	13.87
Win-4	16,195	13.83	16,944	14.71
Win-5	15,103	14.79	15,851	15.56
Win-6	14,125	15.77	14,661	16.24
Win-7	13,130	16.75	13,132	16.67
Cold-outlet	0	17.22	0	17.16

Table 5. Computed temperature and pressure values at different surfaces (ii).

Table 6. Predicted heat transfer rates on the	shell side for all cases.
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Shell Side Fluid Zones	CFD Results of Heat Transfer Rates for All Cases (Watt)					
Shell Shue Hulu Zones -	Case-I	Case-II	Case-III	Case-IV	Case-V	
Fluid zone-1	1460.59	1501.61	1230.83	1239.04	1345.71	
Fluid zone-2	853.38	1140.57	574.39	582.59	976.46	
Fluid zone-3	894.40	746.70	820.55	615.42	853.38	
Fluid zone-4	804.14	566.18	951.84	705.68	689.27	
Fluid zone-5	795.94	500.54	861.58	787.73	697.47	
Fluid zone-6	738.50	771.32	705.68	804.14	557.98	
Fluid zone-7	713.88	919.02	328.22	804.14	352.84	
Fluid zone-8	393.87	402.07	402.07	385.66	402.07	
Total	6654.69	6548.02	5875.17	5924.40	5875.17	
R <sub>h</sub>	1	0.98	0.88	0.89	0.88	

The computed overall heat transfer coefficients, the total heat transfer rates and pressure drops for all cases are shown in Table 7. For the pressure drop calculations, we only used the Bell-Delaware method because the Kern method is just suitable for initial sizing problems but the Bell-Delaware method estimates shell side heat transfer coefficients and pressure drops more precisely. The baffle cut ratio was selected as 25% which is the reference value of the Kern method. From the results given in Table 7, the computed overall heat transfer coefficient by using the Kern and CFD methods were calculated to be 2533 W·m<sup>-2</sup> K<sup>-1</sup> and 2347 W·m<sup>-2</sup> K<sup>-1</sup>, respectively, but this computed value was about 2270 W·m<sup>-2</sup> K<sup>-1</sup> from the Bell-Delaware method. In the CFD method, the effects of various leakage and bypass streams on the shell side were ignored, thus the computed value was higher than that one obtained from the Bell-Delaware method. The outlet temperature of the shell side, pressure drop and overall heat transfer rates for the shell and tube sides was nearly about 0.5 Watt, thus we can easily say that steady-state conditions were achieved for the CFD results. The calculated total pressure drop for Case-I was about 21 kPa and 18 kPa by using the CFD and Bell-Delaware methods, respectively.

Heat Transfer Characteristics							
Thermal properties		Case-I		Case-II	Case-III	Case-IV	Case-V
r r	CFD	Kern	Bell-Delaw	are	Cl	FD	
U (W m <sup>2</sup> K <sup>-1</sup> )	2533.06	2346.74	2269.00	2485.00	2175.54	2199.57	2177.83
Q <sub>cold</sub> (W)	6654.69	6164.72	5960.51	6548.02	5875.17	5924.40	5875.17
Q <sub>hot</sub> (W)	6654.18	6164.72	5960.51	6551.76	5871.48	5925.51	5876.63
Pressure Drop Calculations							
ΔP <sub>c</sub> (Pa)	CFD	Bell-D	elaware		Cl	FD	
	20,832	17,	,769	21,340	21,312	20,907	21,196

Table 7. Results of numerical and analytical calculations for all cases.

We also defined a horizontal plane parallel to flow direction in the middle center of the shell and tube heat exchanger and the calculated temperature distributions throughout the flow direction for all cases are shown in Figure 15. These results may be used to evaluate the heat transfer characteristics between the cold and hot fluid streams. As expected, the maximum temperature difference between the tube outer wall and the shell side fluid were predicted in the first fluid zone for all cases. This value decreased along the tubes and the minimum value was computed for the end zone. The higher temperature values were predicted in the second half of the heat exchanger and we can easily say that the baffle spacing length and scheme directly affected the temperature distribution in the center plane of the heat exchanger. The predicted velocity distribution in all fluid zones is shown in Figure 16 for all cases. The computed velocity value was obtained between  $1.1 \text{ m} \cdot \text{s}^{-1}$  and  $2.25 \text{ m} \cdot \text{s}^{-1}$  in general but the maximum value was computed about  $4.5 \text{ m} \cdot \text{s}^{-1}$  near the nozzle regions due to contraction in the inlet and outlet regions. The calculated mass average velocity values for all fluid zones are shown in Table 8. The predicted mass average velocity values varied between 0.4 m  $\cdot$  s<sup>-1</sup> and 2.25 m  $\cdot$  s<sup>-1</sup> in general, however the maximum calculated value was  $0.662 \text{ m} \cdot \text{s}^{-1}$  in fluid-zone 5 for Case-II due to effect of the dense baffle spacing scheme for that zone. The computed mass average velocity value in the first and end fluid zones was calculated at about  $0.6 \text{ m} \cdot \text{s}^{-1}$  and  $0.5 \text{ m} \cdot \text{s}^{-1}$ , respectively, for all cases. It can be observed that a decrease in baffle spacing length leads to higher velocity values and the heat transfer rate will be higher with increasing velocity values.

Shell Side Fluid Zones	Case-I	Case-II	Case-III	Case-IV	Case-V
Fluid zone-1	0.62	0.62	0.62	0.62	0.62
Fluid zone-2	0.44	0.37	0.61	0.60	0.37
Fluid zone-3	0.50	0.50	0.52	0.57	0.46
Fluid zone-4	0.50	0.65	0.41	0.52	0.46
Fluid zone-5	0.49	0.66	0.40	0.47	0.50
Fluid zone-6	0.50	0.52	0.50	0.44	0.55
Fluid zone-7	0.49	0.41	0.65	0.41	0.66
Fluid zone-8	0.58	0.57	0.59	0.57	0.59
Average	0.51	0.51	0.51	0.51	0.51

Table 8. CFD results of velocity distribution for each fluid zone (m/s).



Figure 15. Temperature distribution at the center plane of the heat exchanger (a) Case-I (b) Case-II (c) Case-III (d) Case-IV (e) Case-V.



**Figure 16.** Prediction of velocity (m s<sup>-1</sup>) distribution of shell side flow (**a**) Case-I (**b**) Case-II (**c**) Case-III (**d**) Case-IV (**e**) Case-V.

# 4. Conclusions

In this study, numerical and theoretical analysis were both used to investigate the effect of variable baffle spacing on the thermal characteristics of a small shell and tube heat exchanger. As a result of these numerical computations, we can say that correlation-based approaches indicate the deficiencies of a shell and tube heat exchanger but the location of these weaknesses is not used in any of these methods. By using a well designed and built multi-zone CFD model, the flow and heat transfer characteristics of a shell and tube heat exchanger can be changed and improved. Another important result is that the Case-I which had equal baffle spacing configuration had the smallest pressure drop and highest thermal performance among all the schemes. On the other hand, the predicted temperature difference between the cold inlet and outlet surfaces was about 8 °C for Case-I and Case-II. Thus,

we conclude that thermal performance of Case-II was close to that of Case-I but using the variable baffle spacing scheme in practical applications may cause difficulties such as manufacturing and maintenance problems, etc. More experimental investigations about this scheme have to be performed considering industrial applications. However, using a centered baffle spacing scheme leads to an increase in pressure drop and also the heat transfer rates, so design parameters have to be determined for the best configuration considering the maximum pressure drop limit and desired heat transfer rate of the heat exchanger. We can easily say that different baffle spacing schemes have a great effect on the temperature distribution of the shell side and also the heat transfer rate. These results can be used for getting the best design in terms of heat transfer characteristics of a shell and tube heat exchanger. Moreover, using the CFD model together with the correlation-based approaches not only indicates the weaknesses, but also predicts the location of the maximum pressure drop, variation of heat transfer rate and flow field and the effects of different baffle spacing schemes on the heat transfer characteristics of the shell and tube heat exchanger in a more detailed way. In this numerical study, the simulation results are compared with the results from the Kern and Bell-Delaware methods and the numerical results were in good agreement with the theoretical data, although in this study, the numerical data from the CFD solution were more compatible with the theoretical results calculated with the Kern method. However, more complicated parameters such as by-pass and leakage streams and various factors existing in the Bell-Delaware method leads to underestimated thermal performance results. We plan to investigate the transient thermal performance of a shell and tube heat exchanger in future studies considering different baffle spacing schemes and the other design configurations.

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Conflicts of Interest: The authors declare no conflicts of interest.

#### Nomenclature

А	total heat transfer rate area	[m <sup>2</sup> ]
As	bundle crossflow area	[m <sup>2</sup> ]
В	baffle spacing	[m]
cp	specific heat at constant pressure	$[J \cdot kg^{-1} \cdot K^{-1}]$
Ċ	clearance between adjacent tubes	[m]
di	tube inside diameter	[m]
do	tube outside diameter	[m]
De	equivalent diameter	[m]
Ds	shell inner diameter	[m]
f	friction factor	-
g	gravitational acceleration	$[m \cdot s^{-2}]$
Gs	mass velocity	$[\text{kg} \cdot \text{m}^{-2} \cdot \text{s}^{-1}]$
h	convection heat transfer coefficient	$[W \cdot m^{-2} \cdot K^{-1}]$
j <sub>i</sub>	Colbum j-factor for an ideal tube bank	-
J <sub>b</sub>	bundle bypass correction factor for heat transfer	-
J <sub>c</sub>	segmental baffle window correction factor for heat transfer	-
J <sub>1</sub>	baffle leakage correction factor for heat transfer	-
J <sub>r</sub>	laminar flow heat transfer correction factor	-
Js	heat transfer correction factor for unequal end baffle spacing	-
k	kinetic energy of turbulent fluctuations per unit mass	-
k	thermal conductivity	$[W \cdot m^{-1} \cdot K^{-1}]$
ṁ	mass flow rate	$[\text{kg}\cdot\text{s}^{-1}]$
N <sub>b</sub>	number of baffles	-
Nu	Nusselt number	-
t	thickness	[m]
Т	temperature	[K]

р	pressure	[Pa]
Pr	Prandl number	-
P <sub>T</sub>	pitch size	[m]
q	heat flux as a source term	$[W \cdot m^{-2}]$
Q	total heat transfer rate	[W]
R	fouling resistance	$[m^2 \cdot K \cdot W^{-1}]$
Re	Reynolds number	-
R <sub>h</sub>	Heat transfer ratio	-
u, v, w	velocity components	$[m \cdot s^{-1}]$
U	overall heat transfer coefficient	$[W \cdot m^{-2} \cdot K^{-1}]$
U <sub>f</sub>	overall heat transfer coefficient with fouilng	$[W \cdot m^{-2} \cdot K^{-1}]$
$\stackrel{\rightarrow}{\mathrm{V}}$	velocity vector	-
x, y, z	position coordinates	-
$\Delta p_s$	total shell side pressure drop	[Pa]
$\Delta p_e$	pressure drop in entering and leaving section	[Pa]
$\Delta p_c$	pressure drop in cross flow section	[Pa]
$\Delta p_{win}$	pressure drop in window section	[Pa]
$\Delta p_n$	pressure drop in nozzle region	[Pa]
λ	viscosity coefficient	-
ρ	density	[kg·m <sup>−3</sup> ]
τ	shear stress	$[N \cdot m^{-2}]$
$\phi_s$	viscosity correction factor for shell-side fluids	-
Φ	dissipation function	-
μ	dynamic viscosity	$[N \cdot s \cdot m^{-2}]$
μb	viscosity evaluated at the bulk mean temperature	$[N \cdot s \cdot m^{-2}]$
μw	viscosity evaluated at the wall temperature	$[N \cdot s \cdot m^{-2}]$
μs	shell fluid dynamic viscosity at average temperature	$[N \cdot s \cdot m^{-2}]$
μs,w	shell fluid dynamic viscosity at wall temperature	$[N \cdot s \cdot m^{-2}]$

## Subscript

b	bulk mean
c	cold
f	fouling factor
h	hot
i	inner
id	ideal
lm	logarithmic mean
m	mean
0	outer
s	shell
w	wall
$\Delta$	delta operator
$\nabla$	Laplacian operator

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