A New Combined Boost Converter with Improved Voltage Gain as a Battery-Powered Front-End Interface for Automotive Audio Amplifiers

Ching-Ming Lai 1, Yu-Huei Cheng 2,*, Jiashen Teh 3 and Yuan-Chih Lin 4

1 Department of Vehicle Engineering, National Taipei University of Technology, 1, Sec. 3, Chung-Hsiao E. Road, Taipei 106, Taiwan; pecmlai@gmail.com
2 Department of Information and Communication Engineering, Chaoyang University of Technology, Taichung 41349, Taiwan
3 School of Electrical and Electronic Engineering, Universiti Sains Malaysia, USM Engineering Campus, Nibong Tebal, Seberang Perai Selatan 14300, Penang, Malaysia; jiashenteh@usm.my
4 Department of Electrical Engineering, National Taiwan University, No. 1, Sec. 4, Roosevelt Rd., Taipei 106, Taiwan; gero.lin1980@gmail.com

* Correspondence: yuhuei.cheng@gmail.com; Tel.: +886-4-2332-3000 (ext. 7712)

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Abstract: High boost DC/DC voltage conversion is always indispensable in a power electronic interface of certain battery-powered electrical equipment. However, a conventional boost converter works for a wide duty cycle for such high voltage gain, which increases power consumption and has low reliability problems. In order to solve this issue, a new battery-powered combined boost converter with an interleaved structure consisting of two phases used in automotive audio amplifier is presented. The first phase uses a conventional boost converter; the second phase employs the inverted type. With this architecture, a higher boost voltage gain is able to be achieved. A derivation of the operating principles of the converter, analyses of its topology, as well as a closed-loop control designs are performed in this study. Furthermore, simulations and experiments are also performed using input voltage of 12 V for a 120 W circuit. A reasonable duty cycle is selected to reach output voltage of 60 V, which corresponds to static voltage gain of five. The converter achieves a maximum measured conversion efficiency of 98.7% and the full load efficiency of 89.1%.

Keywords: automotive audio amplifier; battery-powered; combined boost converter; voltage gain

1. Introduction

High boost DC/DC (direct current to direct current) voltage conversions are indispensable in a power electronic interface of certain low-voltage DC-powered electrical devices, including audio amplifiers [1–7], high intensity discharge (HID) lamps [8–14], uninterruptible power supplies (UPS) [15–19], and electric vehicle systems [20–32]. For such high voltage gain application, the conventional boost converter has to work for extremely wide duty cycle which increases power consumption and has low reliability problems [32,33]. In order to overcome these problems, several high boost converter DC/DC topologies have been presented. Franceschini et al. presented a DC/DC boost converter topology that is a full-bridge architecture using a three-phase transformer and is well suitable for high-power applications with battery supplies [5]. Zhao and Lee proposed a series of high efficiency, high boost DC/DC converters that apply diodes and coupling windings instead of active switches to achieve similar functions to active clamps [9,10]. In [11], Yang et al. presented a transformerless DC/DC converter that consists of a boost converter paralleled with an inverting boost and a floating diode-capacitor output rectifier. Though the voltage gain of the converter is
improved with the relative low-cost components, the input current ripple is large owing to the fact that
the active switches are controlled simultaneously by using one control signal. Divakar et al. introduced
a circuit that can eliminate one auxiliary winding and can reduce the voltage on the primary side
switch. Furthermore, with this circuit, the selection of switches with a lower rating is permitted [12].
Shahin et al. proposed a cascade DC/DC converter including interleaved boost converters with
two phases and three level series boost converters [23]. The efficiency and reliability of this solution
are low. In [24], a cascaded boost converter regulated the reasonable voltage gain with a common
pulse-width modulation (PWM) control. However, if a high voltage gain has to be offered, more power
switches and capacitors are actually necessary. In addition, although exceeding duty cycles can be
prevented, the input current ripple is large because of its single-phase operation makes the converter
not suitable for high current and low ripple applications. In order to further decrease the voltage
stress on active switches and electromagnetic interference (EMI), Lai presented a high boost converter
consisting of three-phase circuits by an auxiliary forward circuit [19]. However, the circuit structure
of this particular topology is costly and complex. Lai et al. also proposed a modular interleaved
boost converter that integrates a forward energy-delivering circuit with a voltage-doubler to realize a
high voltage gain, the reduced switch voltage and high efficiency for DC-microgrid applications [31].
The characteristic low ripple of the interleaved boost converter is responsible for the attention placed
on investigations into this technology [28–31]. Although many DC/DC converters offer high boost
voltage gain, they have the disadvantage of either requiring a complex circuit structure or considerable
higher costs for the bill of material (BOM). It is therefore difficult to manufacture these circuits in
a batch manner [32,33].

To provide an appropriate solution, in this study, we introduce a combined boost converter
topology. While the low ripple characteristics that benefit from interleaved structures, this simpler
and lower cost topology can also give an improved voltage gain when comparing to a conventional
interleaved boost converter with two phases. A partial study and analysis of a battery-powered
combined boost converter for automotive audio amplifiers was presented in [7], but only a brief concept
was described therein. By contrast, this paper introduces a detailed analysis of the operation of this new
topology and simulated and experimented results for all its modes of operation. Figure 1 shows the
studied audio amplifier architecture. In today’s automotive framework, galvanic isolation is no longer
required in automotive audio applications because the head unit of the amplifier’s signal and the
power supply of the amplifier share a power ground [4]. As with the post-amplifier, the pre-amplifier
is connected to a full-bridge class-D amplifier, which can output any voltage waveform to supply
the load. In the audio amplifier architecture studied, the loads are primarily speakers. The battery is
connected to the combined boost converter, which is subsequently connected to the full-bridge class-D
amplifier. Finally, the full-bridge class-D amplifier is connected to the load.

Figure 1. Illustration of the studied audio amplifier architecture.
2. Converter Topology and Operation Principles

The proposed converter is used as an automotive battery-powered interface. The converter topology for the new combined boost converter contains two-phase circuits, as shown in Figure 2. One is the boost circuit, which involves inductor \( L_1 \), capacitor \( C_1 \), active switch \( S_1 \) and diode \( D_1 \). The other is the inverted boost circuit, which contains inductor \( L_2 \), capacitor \( C_2 \), active switch \( S_2 \), and diode \( D_2 \). The inductors \( L_1 \) and \( L_2 \) are amount to \( L \) and the capacitors \( C_1 \) and \( C_2 \) are amount to \( C \). \( C_o \) is the common output capacitor, \( V_i \) is the supply voltage, \( V_o \) is the output voltage, and \( R_o \) is the output load resistance.

![Proposed combined boost converter topology.](image)

Figure 2. Proposed combined boost converter topology.

The following four assumptions are made in analyzing the proposed combined boost converter. (1) For simplicity, it is assumed that all the components in Figure 2 are idealized; (2) All voltages and currents in the circuit are periodic in steady-state conditions; (3) For high boost conversion, the duty cycle of the major switch is exceed 50%, which is presented as \( D \); (4) The converter works in continuous conduction mode (CCM). In the combined boost converter, all working modes and their equivalent circuits corresponding to the ON/OFF status of the active switches have been illustrated in Figure 3. The steady-state waveforms of the combined boost converter are demonstrated in Figure 4. The working modes can be described clearly as follows.

1. Mode 1 \([t_0-t_1]\) and Mode 3 \([t_2-t_3]\): In these two modes, the active switches \( S_1 \) and \( S_2 \) are switched on while the diodes, \( D_1 \) and \( D_2 \) are reverse-bias. The current in the inductors, \( i_{L1} \) and \( i_{L2} \), increase to store energy in \( L_1 \) and \( L_2 \), respectively. The output power for the back-end amplifier is provided by capacitor \( C_o \). The total current \( i_{L} \) and inductor currents of \( L_1 \) and \( L_2 \) are expressed below.

\[
i_{L} = i_{L1} + i_{L2}
\]

\[
\frac{di_{L1}}{dt} = \frac{V_i}{L_1}
\]

\[
\frac{di_{L2}}{dt} = \frac{V_i}{L_2}
\]

2. Mode 2 \([t_1-t_2]\): The active switch \( S_1 \) remains conducting and \( S_2 \) is switched off. \( D_1 \) is reverse-bias and \( D_2 \) is forward-bias. While the current \( i_{L1} \) increase to store energy in \( L_1 \), the energy stored in inductor \( L_2 \) is now released through \( D_2 \), \( C_2 \), \( C_1 \), and \( C_o \) to the output. The total current \( i_{L} \) and inductor currents of \( L_1 \) and \( L_2 \) can be expressed as follows:

\[
i_{L} = i_{L1} + \frac{i_{L2}}{2}
\]

\[
\frac{di_{L1}}{dt} = \frac{V_i}{L_1}
\]
\[
\frac{di_{L2}}{dt} = \frac{V_i - V_{C2}}{L_2} = \frac{V_{C1} - V_o}{L_2}
\] (6)

(3) Mode 4 \([t_3-t_4]\): \(S_2\) is switched on and \(S_1\) is switched off. \(D_2\) is reverse-bias and \(D_1\) is forward-bias. The energy stored in \(L_1\) is released through \(D_1\) to charge capacitor \(C_1\) and \(C_o\). The total current \(i_{Lt}\) and inductor currents of \(L_1\) and \(L_2\) can be expressed as follows:

\[
i_{Lt} = i_{L2} + \frac{i_{L1}}{2}
\] (7)

\[
\frac{di_{L1}}{dt} = \frac{V_i - V_{C1}}{L_1} = \frac{V_{C2} - V_o}{L_1}
\] (8)

\[
\frac{di_{L2}}{dt} = \frac{V_i}{L_2}
\] (9)

**Figure 3.** Working modes and equivalent circuits of the combined boost converter. (a) Mode 1 and Mode 3, (b) Mode 2, and (c) Mode 4.
3. Analysis of Steady-State

In this section, the voltage gain, voltage stress on the switches, and inductor current ripple of the combined boost converter working in the steady state are analyzed.

3.1. Voltage Gain

Using Figures 3 and 4, the corresponding state equation for each mode can be obtained. These illustrations enable the observation that the weighting factors in the four working modes which are \((D-\frac{1}{2}), (1-D), (D-\frac{1}{2}),\) and \((1-D)\). The Equations (10) and (11) are obtained using the inductor voltage-second balance principle on \(L_1\) and \(L_2\) as follows:

\[
V_{\text{C1}} = \frac{V_i}{1-D} \tag{10}
\]
\[ V_{C2} = \frac{V_i}{1 - D} \]  

The \( C_1 \) and \( C_2 \) capacitors are connected in series with the supply voltage, and the equation of output voltage of the converter is expressed as:

\[ V_o = V_{C1} + V_{C2} - V_i \]  

By combining (10)–(12), the static voltage gain can be derived by:

\[ \frac{V_o}{V_i} = \frac{1 + D}{1 - D} \]  

The static voltage gain of the conventional boost converter is expressed as:

\[ \frac{V_o}{V_i} = \frac{1}{1 - D} \]  

Figure 5 shows a comparison of the voltage gains produced by the proposed combined boost converter, the interleaved boost converter with two-phase and the conventional boost converter. From Figure 5, we observe that the converter has a higher voltage gain than the two-phase interleaved converter and the conventional boost converter.

3.2. Voltage Stress of the Switches

The open circuit voltage stress on switches \( S_1 \) and \( S_2 \) can be obtained by the aforementioned analyses of operations. The relevant expression is written as (15).

\[ V_{S1,\text{max}} = V_{S2,\text{max}} = \frac{V_i}{1 - D} \]  

3.3. Inductor Current Ripples

Using Equations (1)–(9), the total current ripple in the proposed combined boost converter can be represented by:

\[ \Delta I_L = \frac{V_i T_s}{L} (2D - 1) \]
The current ripples of the inductors $L_1$ and $L_2$, in the proposed combined boost converter can thus be expressed as:

$$\Delta i_L = \Delta i_{L1} = \Delta i_{L2} = \frac{V_i T_s}{L} D$$  \hspace{1cm} (17)$$

The variation of the duty cycle of the total current ripple to inductor current ripple as a function of the duty cycle is displayed in Figure 6. The proposed converter has the same performance as the two-phase interleaved boost converter, and that is superior to the conventional boost converter.

![Figure 6. The ratio between the total current ripple and the inductor current ripple versus the duty cycle.](image)

3.4. The Mode for Boundary Conduction

The boundary normalized inductor time constant $\tau_{L,B}$ is expressed as:

$$\tau_{L,B} = \frac{L f_{sw}}{R} \hspace{1cm} (18)$$

where $f_{sw}$ is the switching frequency.

The output current during boundary conduction mode (BCM) is indicated by:

$$i_O = \frac{V_i T_s}{L} (1 + D) \hspace{1cm} (19)$$

Therefore, the boundary normalized time constant is represented by:

$$\tau_{L,B} = 1 - D \hspace{1cm} (20)$$

Figure 7 shows a plot of the boundary normalized inductor time constant curve. When $\tau_L$ is planned to be higher than the boundary curve of $\tau_{L,B}$, the converter operates in continuous conduction mode (CCM). Conversely, the proposed converter works in discontinuous conduction mode (DCM) when $\tau_{L_B}$ is chosen to be smaller than the boundary curve of $\tau_{L_B,B}$.
3.5. Component Stress and Loss

The equations for analyzing the component stress of the combined boost converter are summarized in Table 1. In addition, equations for loss analysis are shown in Table 2.

### Table 1. The results for stress analysis in steady-state.

<table>
<thead>
<tr>
<th>Items</th>
<th>State</th>
</tr>
</thead>
<tbody>
<tr>
<td>RMS current stress on $S_1$ ($i_{S1}$)</td>
<td>$I_{S1(RMS)} = I_{S2(RMS)} \sqrt{D}$</td>
</tr>
<tr>
<td>RMS current stress on $S_2$ ($i_{S2}$)</td>
<td>$I_{S2(RMS)} = I_{S1(RMS)} \sqrt{D}$</td>
</tr>
<tr>
<td>RMS current stress on $L_1$ ($i_{L1}$)</td>
<td>$I_{L1(RMS)} = \sqrt{\left(\frac{I_{L1}}{2 \sqrt{3}}\right)^2 + \left(\frac{\Delta I_{L1}}{2 \sqrt{3}}\right)^2}$</td>
</tr>
<tr>
<td>RMS current stress on $L_2$ ($i_{L2}$)</td>
<td>$I_{L2(RMS)} = \sqrt{\left(\frac{I_{L2}}{2 \sqrt{3}}\right)^2}$</td>
</tr>
<tr>
<td>RMS current stress on $L_4$ ($i_{L4}$)</td>
<td>$I_{L4(RMS)} = \sqrt{\left(\frac{I_{L1} + I_{L2}}{2 \sqrt{3}}\right)^2 + \left(\frac{\Delta I_{L2}}{4 \sqrt{3}}\right)^2}$</td>
</tr>
<tr>
<td>RMS current stress on $D_1$ ($i_{D1}$)</td>
<td>$I_{D1(RMS)} = I_{L2(RMS)} \sqrt{1 - \frac{2}{\sqrt{3}}}$</td>
</tr>
<tr>
<td>RMS current stress on $D_2$ ($i_{D2}$)</td>
<td>$I_{D2(RMS)} = I_{L1(RMS)} \sqrt{1 - \frac{2}{\sqrt{3}}}$</td>
</tr>
<tr>
<td>RMS current stress of $C_1$ ($i_{C1}$)</td>
<td>$I_{C1(RMS)} = I_o \sqrt{\frac{D + \frac{r^2}{1 - D}}{1 - D}}$, $r = \frac{\Delta I}{I_f}$, $I_f = \frac{I_o}{1 - D}$</td>
</tr>
<tr>
<td>RMS current stress of $C_2$ ($i_{C2}$)</td>
<td>$I_{C2(RMS)} = I_o \sqrt{\frac{D + \frac{r^2}{1 - D}}{1 - D}}$, $r = \frac{\Delta I}{I_f}$, $I_f = \frac{I_o}{1 - D}$</td>
</tr>
<tr>
<td>RMS current stress of $C_o$ ($i_{C_o}$)</td>
<td>$I_{C_o(RMS)} = I_o \sqrt{\frac{D}{1 + D}}$</td>
</tr>
</tbody>
</table>
Table 2. The equations of loss in steady-state.

<table>
<thead>
<tr>
<th>Items</th>
<th>State</th>
</tr>
</thead>
<tbody>
<tr>
<td>Total loss of $S_1$</td>
<td>$\frac{V_{S1(DS1)} \times I_{S1(D1)} \times T_{1} \times f_{sw}}{2} + \frac{V_{S1(DS2)} \times I_{S1(D2)} \times T_{1} \times f_{sw}}{2}$ + $\frac{R_{DS1(ON)} \times \left[I_{S1(RMS)}\right]^2}{V_{S2(DS1)} \times I_{S2(D1)} \times T_{2} \times f_{sw}} + \frac{Q_{S1} \times V_{GS1} \times f_{sw}}{2}$ + $\frac{R_{DS2(ON)} \times I_{S2(RMS)}^2}{V_{S2(DS2)} \times I_{S2(D2)} \times T_{2} \times f_{sw}} + \frac{Q_{S2} \times V_{GS2} \times f_{sw}}{2}$</td>
</tr>
<tr>
<td>Total loss of $S_2$</td>
<td></td>
</tr>
<tr>
<td>Conduction loss of $L_1$</td>
<td>$r_{L1} \times \left[I_{L1(RMS)}\right]^2$</td>
</tr>
<tr>
<td>Conduction loss of $L_2$</td>
<td>$r_{L2} \times \left[I_{L2(RMS)}\right]^2$</td>
</tr>
<tr>
<td>Total loss of $D_1$</td>
<td>$V_{F1} \times I_{o} \times K + 0.5 \times V_{R1} \times T_{RR1} \times f_{sw} \times I_{RR1}$</td>
</tr>
<tr>
<td>Total loss of $D_2$</td>
<td>$V_{F2} \times I_{o} \times K + 0.5 \times V_{R2} \times T_{RR2} \times f_{sw} \times I_{RR2}$</td>
</tr>
<tr>
<td>Conduction loss of $C_1$</td>
<td>$r_{C1} \times \left[I_{C1(RMS)}\right]^2$</td>
</tr>
<tr>
<td>Conduction loss of $C_2$</td>
<td>$r_{C2} \times \left[I_{C2(RMS)}\right]^2$</td>
</tr>
<tr>
<td>Conduction loss of $C_o$</td>
<td>$r_{C_o} \times \left[I_{C_o(RMS)}\right]^2$</td>
</tr>
</tbody>
</table>

* $Q_s$ represents the total charge on the gate of the metal-oxide-semiconductor field-effect transistor (MOSFET). The rise time $T_r$ is the time it takes to complete charging the gate of the MOSFET after the threshold voltage $V_{GS(th)}$ has been reached. The fall time, $T_f$, is the time it takes to reach the threshold voltage following the MOSFET’s switch-off delay time [34]. $V_G$ represents the forward voltage drop of the diode. $K$ is the time of the conduction period of the diode. $V_G$ represents the reverse voltage of the diode. $I_o$ is the reverse leakage current of the diode [35].

4. Converter Control Strategy

As described in the preceding paragraphs, the combined boost converter is dominated by the specific duty ratio of switches $S_1$ and $S_2$. By appropriately adjusting duty ratio, the output voltage can be flexible. The circuit model is established by PSIM® simulation software (Powersim Inc., Rockville, MD, USA) under the later suppositions to devise the closed-loop controller and reduce the mathematics for the converter. The suppositions includes (1) power switches and diodes are ideal; (2) equivalent series resistances (ESRs) of all the inductors and capacitors of the converter are thought to acquire a comparatively precise dynamic model; (3) the converter works in under CCM. The taken circuit parameters are $L_1 = L_2 = 250 \, \mu\text{H}$, $C_1 = C_2 = 10 \, \mu\text{F}$, $C_o = 1000 \, \mu\text{F}$, output resistance $R = 30 \, \Omega$, and ESRs $r_{L1} = r_{L2} = r_{C1} = r_{C2} = 100 \, \mu\text{m}$. 

Figure 8 illustrates the block diagram of the combined boost converter by measuring the output voltage feedback signal into the controller for control. Figure 8 illustrates the developed control system for the combined boost converter. It can be seen that the output voltage ($V_o$) is sensed and compared with the reference ($V_{o,ref}$). The output voltage controller produces those two inductor current reference ($i_{L1,ref}$, $i_{L2,ref}$) for the entire system, and the equal current sharing between the two interleaved phases can be also acquired. Furthermore, during the system startup, using a soft start system ($V_{on/off}$) is used to avoid the capacitor charge surge current causing damage to the converter components.

The Block diagram of the closed-loop control scheme is shown in Figure 9. In the inner current control loop, $F_M$ is the constant gain of the PWM generator; $G_{i1d}$ and $G_{i2d}$ is the transfer function from the duty ratio to the two different inductor current; $C_{i1}$ and $C_{i2}$ indicates the transfer function of current controllers; and $H_{i1}$ and $H_{i2}$ are the sensing gains of the current sensor. In the outer voltage control loop, $G_{o1}$ is the transfer function from the duty ratio to the output voltage; $C_o$ indicates the transfer function of output voltage controller; and $H_o$ indicates the sensing gain of the voltage sensor.
To supply a audio amplifier with a pure resistive load.

**Figure 8.** The developed control system for the combined boost converter.

**Figure 9.** Block diagram for the closed-loop control scheme.

From Figure 9, we can derive open the loop gain of the voltage and current loops of the proposed converter by the following equations.

\[
T_{11}(s) = F_m H_{11} G_{11 d}(s) C_{11}(s)
\]

\[
T_{12}(s) = F_m H_{12} G_{21 d}(s) C_{12}(s)
\]

(21)
\[ T_i(s) = H_i G_{vd}(s) C_i(s) \cdot \left( \frac{T_{i1}(s)}{1 + T_{i1}(s)} \cdot \frac{1}{H_{i1}} + \frac{T_{i2}(s)}{1 + T_{i2}(s)} \cdot \frac{1}{H_{i2}} \right) \]  

(22)

where, \( F_M = 1/100 \), \( H_{i1} = H_{i2} = H_i = 1 \).

The small-signal transfer from the duty ratio to those inductor current \( G_{i1d} \) and \( G_{i2d} \) and the duty ratio to output voltage \( G_{vd} \) can be shown below.

\[
G_{i1d}(s) = G_{i2d}(s) = \frac{2V_o}{(1 - D)^2 R} \frac{s^2 2DRC_1}{1 + D} + 1 \\
G_{vd}(s) = (1 - D)R \left[ \frac{1 - sL_1}{2R} \left( \frac{1 - D}{1 + D} \right) \right] \left( srC_o C_o + 1 \right)
\]

(23)

(24)

A uncomplicated type-II controller that comprise one-zero, one-pole, and another one-pole at the origin is employed for the current loop compensation to offer sufficient DC gain, bandwidth, gain/phase margins for the system. In addition, a proportional-integral (PI) controller that contain one-zero and one-pole at origin is applied for the voltage loop compensation.

The corresponding current/voltage controllers of the converter are selected as follows:

\[
\begin{align*}
C_{i1}(s) &= C_{i2}(s) = 21.29 \left( \frac{s + 6280}{s} \right) \\
C_v(s) &= 10 \left( \frac{s + 1570}{s} \right)
\end{align*}
\]

(25)

Figure 10a shows the frequency response of the loop gain for compensated current loop, under the full-load conditions. This work leads to a phase margin of 55 degrees and the crossover frequency is approximately 8 kHz. Figure 10b shows the frequency response of the loop gain for compensated voltage loop, under the full-load conditions. This work leads to a phase margin of 45 degrees and the crossover frequency is approximately 800 Hz.
5. Simulated and Experimented Results

In order to confirm the performance of the combined boost converter, simulations and experiments were conducted based on the test setup shown in Figure 11. Figure 12 shows a three-view photograph of the realized boost converter prototype. Figure 13 shows the realized test bench, which consists of an oscilloscope, a power source, an electronics load, a PWM generator, and the proposed combined boost converter prototype.

![Figure 11. Block diagram of the experimental test setup.](image)

![Figure 12. Realized combined boost converter prototype. (a) Top view; (b) Front view; (c) Side view.](image)

![Figure 13. Realized test bench system (the oscilloscope, power source, electronics load, pulse-width modulation (PWM) generator, and the proposed combined boost converter prototype are labeled).](image)
The specifications and parameters of the components taken in the converter prototype are provided in Tables 3 and 4, respectively.

Table 3. Specifications of Converter Prototype.

<table>
<thead>
<tr>
<th>Specification</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Input Voltage, $V_i$</td>
<td>12 V</td>
</tr>
<tr>
<td>Output Voltage, $V_o$</td>
<td>60 V</td>
</tr>
<tr>
<td>Duty Cycle, $D$</td>
<td>0.67</td>
</tr>
<tr>
<td>Switching Frequency, $f_{sw}$</td>
<td>40 kHz</td>
</tr>
<tr>
<td>Output power, $P_o$</td>
<td>120 W</td>
</tr>
</tbody>
</table>

Table 4. Parameters of Components.

<table>
<thead>
<tr>
<th>Specification</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>MOSFET IPP080N06NG</td>
<td></td>
</tr>
<tr>
<td>Diode STPS8H100</td>
<td></td>
</tr>
<tr>
<td>Load Resistance, $R$</td>
<td>30 Ω</td>
</tr>
<tr>
<td>Inductors, $L_1$ and $L_2$</td>
<td>250 µH</td>
</tr>
<tr>
<td>Filter Capacitors, $C_1$ and $C_2$</td>
<td>10 µF</td>
</tr>
<tr>
<td>Output Capacitor, $C_o$</td>
<td>1000 µF</td>
</tr>
</tbody>
</table>

For input voltage of 12V and duty cycle of 66.7%, output voltage of 60 V can be obtained using (13). The voltages on the capacitors of $C_1$ and $C_2$ are calculated using (10) and (11). The values across both $C_1$ and $C_2$ are calculated to be about 36 V (i.e., $V_{C1} = V_{C2} = 36$ V).

PSIM® simulation software (Powersim Inc., Rockville, MD, USA) is used to confirm the feasibility of the combined boost converter. Figures 14 and 15 indicate the simulated and experimented waveforms of the combined boost converter for gate driving signals $V_{GS1}$ and $V_{GS2}$ and two-phase inductor currents $i_{L1}$ and $i_{L2}$, respectively.

Figure 16 shows the simulated and experimented waveforms of the combined boost converter for the cross voltages across $S_1$ and $S_2$, respectively.

Figure 17 shows the simulated and experimented waveforms of the combined boost converter for the cross voltages across $D_1$ and $D_2$, respectively.

Figure 18 shows the simulated and experimented waveforms of the combined boost converter for the voltages across the $C_1$ and $C_2$ capacitors. The results verify the feasibility of the converter.

Figure 19 shows the transient response because of a step load current change between 120 W and 60 W for the combined boost converter prototype. As can be seen from Figure 19, the output voltage can be stably regulated to be 60 V under the load current variation between 1 A and 2 A.

Figure 20 shows the measured conversion efficiency of the combined boost converter, the interleaved boost converter with a two-phases and the conventional converter. The conversion efficiency is measured via precise digital power meter equipment, Yokogawa WT310 (Yokogawa Electric Corporation, Tokyo, Japan). Using the proposed combined boost converter, we obtain the maximum conversion efficiency is 98.7%, as well as the conversion efficiency with a full load is 89.2%. The proposed combined boost converter owns higher efficiency under full load conditions because the conduction loss can be cut down through applying the low-voltage-rated devices.

The calculated interleaved boost converter power loss distribution at the rated load condition, obtained using the equations in Table 2, is listed in Table 5 to expound the measured conversion efficiency. Furthermore, the resulting loss breakdown charts are depicted in Figure 21.
Figure 14. Waveforms of the combined boost converter for gate driving signals $V_{gs1}$ and $V_{gs2}$ and two-phase inductor current $i_{L1}$. (a) Simulated waveforms; (b) Experimented waveforms.

Figure 15. Waveforms of the combined boost converter for gate driving signals $V_{GS1}$ and $V_{GS2}$ and two-phase inductor current $i_{L2}$. (a) Simulated waveforms; (b) Experimented waveforms.
Figure 16. Waveforms of the combined boost converter for the cross voltages across $S_1$ and $S_2$. (a) Simulated waveforms; (b) Experimented waveforms.

Figure 17. Waveforms of the proposed combined boost converter for the cross voltages across $D_1$ and $D_2$. (a) Simulated waveforms; (b) Experimented waveforms.
Figure 18. Waveforms of the combined boost converter for the cross voltages across $C_1$ and $C_2$. (a) Simulated waveforms; (b) Experimented waveforms.

Figure 19. Waveforms of transient response in the load period steps from 120 W to 60 W and then back to 120 W. (a) Simulated waveforms; (b) Experimented waveforms.
Figure 20. The measured conversion efficiency for the proposed combined boost converter, the conventional boost converter, and the interleaved boost converter with two-phase.

Table 5. Parameters of Components.

<table>
<thead>
<tr>
<th>Items</th>
<th>Results (50% Load)</th>
<th>Results (100% Load)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Switching loss of $S_1$</td>
<td>0.049 W</td>
<td>0.059 W</td>
</tr>
<tr>
<td>Switching loss of $S_2$</td>
<td>0.049 W</td>
<td>0.059 W</td>
</tr>
<tr>
<td>Conduction loss of $L_1$ and $L_2$</td>
<td>0.64 W</td>
<td>3.2 W</td>
</tr>
<tr>
<td>Conduction loss of $D_1$ and $D_2$</td>
<td>0.0384 W</td>
<td>0.23 W</td>
</tr>
<tr>
<td>Conduction loss of $C_1$ and $C_2$</td>
<td>0.196 W</td>
<td>1.02 W</td>
</tr>
<tr>
<td>Conduction loss of $C_0$</td>
<td>0.035 W</td>
<td>0.075 W</td>
</tr>
<tr>
<td>Total losses</td>
<td>1.8828 W</td>
<td>9.134 W</td>
</tr>
<tr>
<td>Calculated Efficiency</td>
<td>98.5%</td>
<td>92.4%</td>
</tr>
<tr>
<td>Measured Efficiency</td>
<td>97.3%</td>
<td>89.1%</td>
</tr>
</tbody>
</table>

Figure 21. The losses breakdown charts. (a) half load and (b) rated load conditions.
For the sake of verifying the performance of the proposed combined boost converter, the other three converters published in [11,19,24] are used for comparison here, as shown in Table 6. It can be observed that the amounts of passive components in [19] exceed the requirement in the converter. It will lead to an increase in manufacturing costs.

The voltage gain of the former converter [11] is equal to the proposed one presented in this work. Although the former converter in [11] has the relatively low-cost components, the input current ripple is large because of the active switches being controlled simultaneously by using one control signal. The voltage gain of the previous converter in [24] is slightly larger than that of the proposed converter in this study; however, the input current ripple is large owing to the single-phase operation makes this converter not suitable for high current and low ripple applications.

From the point view of the cost-performance ratio, the proposed combined boost converter really carries out the higher conversion efficiency and also lower input current ripple under 120 W power rating than other existing works [11,19,24]. Based on its features, this converter can be as a suitable candidate for 12 V battery-powered front-end stage for supplying an automotive audio amplifier.

**Table 6. Performance comparisons among other existing converters.**

<table>
<thead>
<tr>
<th>Items</th>
<th>This Converter</th>
<th>[11]</th>
<th>[19]</th>
<th>[24]</th>
</tr>
</thead>
<tbody>
<tr>
<td>Switching control structure</td>
<td>two-phase</td>
<td>single-phase</td>
<td>three-phase</td>
<td>single-phase</td>
</tr>
<tr>
<td>Input current ripple</td>
<td>Low</td>
<td>High</td>
<td>Low</td>
<td>Medium</td>
</tr>
<tr>
<td>Voltage gain</td>
<td>$(1 + D)/(1 - D)$</td>
<td>$(1 + D)/(1 - D)$</td>
<td>$(3 + nD - D^2)/(1 - D)$</td>
<td>$1/(1 - D)^2$</td>
</tr>
<tr>
<td>High-side voltage</td>
<td>60 V</td>
<td>60 V</td>
<td>200 V</td>
<td>62.5 V</td>
</tr>
<tr>
<td>Low-side voltage</td>
<td>12 V</td>
<td>12 V</td>
<td>24 V</td>
<td>10 V</td>
</tr>
<tr>
<td>Number of main power devices</td>
<td>4</td>
<td>3</td>
<td>8</td>
<td>4</td>
</tr>
<tr>
<td>Number of storage components</td>
<td>5</td>
<td>4</td>
<td>8</td>
<td>5</td>
</tr>
<tr>
<td>Maximum efficiency</td>
<td>98.7%</td>
<td>92.1%</td>
<td>92.3%</td>
<td>92.5%</td>
</tr>
<tr>
<td>Realized prototype power rating</td>
<td>120 W</td>
<td>40 W</td>
<td>100 W</td>
<td>100 W</td>
</tr>
<tr>
<td>BOM Cost</td>
<td>Low</td>
<td>Low</td>
<td>High</td>
<td>Medium</td>
</tr>
</tbody>
</table>

Remark: $n$ represents the turns ratio for coupled inductor [19].

6. Conclusions

A modified interleaved boost converter with two-phase is presented as a battery-powered front-end interface for automotive audio amplifiers. The combined boost converter is created based on a two-phase structure by combining the conventional boost converter with its inverted type. As well as the existing characteristics that benefit from interleaved converters, the converter provides the more advantages in extending the duty cycle than the conventional boost and the interleaved boost converters. Furthermore, it also prevents working with a wide duty cycle. The operating principles, steady-state analyzes, as well as the closed-loop control designs of the converter are explored in this study.

Simulations and experiments are also performed using input voltage of 12 V for a 120 W circuit. A reasonable duty cycle of 0.67 is selected to reach output voltage of 60 V, which corresponds to static voltage gain of five. The converter achieves a maximum measured conversion efficiency of 98.7%. According to its characteristics, the combined boost converter is highly suitable for use as a front-end converter in powering automotive audio amplifiers.

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Yuan-Chih Lin substantially contributed to literature search, control strategy design, and production and analysis of the results.

**Conflicts of Interest:** The authors declare no conflict of interest.

**References**


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